

Chapter 6.

(Linear) Momentum and Collisions

6.1. Momentum

6.2. Impulse

6.3. Conservation of Momentum

6.4. Collision

6.4.1. Perfectly inelastic collision

6.4.2. Elastic collision

6.4.3. 1-D Collisions

6.4.4. 2-D Collisions

6.1. (Linear) Momentum

- This is a new fundamental quantity, like force, energy. It is a vector quantity (points in same direction as velocity).
- The linear momentum $\vec{p}$ of an object of mass m moving with a velocity $\vec{v}$ is defined to be the product of the mass and velocity:

$$\vec{p} = m\vec{v}$$

- The terms momentum and linear momentum will be used interchangeably in the text.
 - Momentum depend on an object's mass and velocity
- ??? Momentum and Energy**

MCQ: Two objects with masses m_1 and m_2 have equal kinetic energy. How do the magnitudes of their momenta compare?

- (A) $p_1 < p_2$ (B) $p_1 = p_2$
(C) $p_1 > p_2$ (D) Not enough information is given

MCQ

??? Momentum and Energy

Two objects with masses m_1 and m_2 have equal kinetic energy. How do the magnitudes of their momenta compare?

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6.1. Linear Momentum, (cont'd)

- Linear momentum is a vector quantity:

$$\vec{p} = m\vec{v}$$

- Its direction is the same as the direction of the velocity
- The dimensions of momentum are **ML / T**
- The SI units of momentum are: **kg.m/s**
- Momentum can be expressed in component form:

$$p_x = mv_x$$

$$p_y = mv_y$$

$$p_z = mv_z$$

Newton's Law and Momentum

- Newton's Second Law can be used to relate the momentum of an object to the resultant force acting on it

$$\boxed{\vec{F}_{net} = m\vec{a} = m \frac{d\vec{v}}{dt} = \frac{d(m\vec{v})}{dt}} \quad (\text{because } m = \text{const})$$

- The change in an object's momentum divided by the elapsed time equals the constant net force acting on the object

$$\boxed{\frac{d\vec{p}}{dt} = \vec{F}_{net}}$$

the 1st law of (linear) momentum

Incase, F is changing: $\frac{\Delta \vec{p}}{\Delta t} = \frac{\text{change in momentum}}{\text{time interval}} = \vec{F}_{average}$

6.2. Impulse $\vec{I}$

- There is an **impulse** delivered to the object:

$$\vec{I} = \int_{t_1}^{t_2} \vec{F} dt$$

- ✓ is defined as the *impulse*
- ✓ vector quantity, the direction depends on the direction of the force.
- ✓ In case, $\vec{F} = \overrightarrow{\text{const}}$ (a single, constant force acts on the object) then $\vec{I} = \vec{F}\Delta t$. With direction is the same the direction of the force acting on the object.

Impulse-Momentum Theorem

- From relation (1st law): $\vec{F}_{net} = \frac{d\vec{p}}{dt}$

$$d\vec{p} = \vec{F}_{net} dt$$

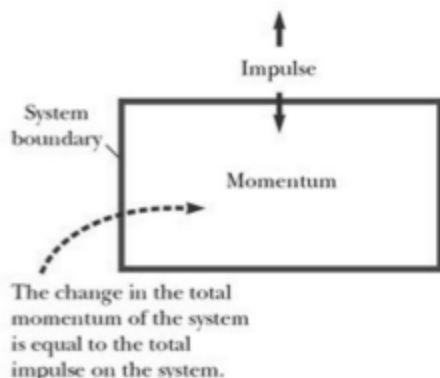
- The theorem states that the impulse acting on a system is equal to the change in momentum of the system

$$\Delta\vec{p} = \int_{\vec{p}_1}^{\vec{p}_2} \vec{p} dt = \int_{t_1}^{t_2} \vec{F}_{net} dt = \vec{I}$$

- Or: $\vec{I} = \Delta\vec{p} = m\vec{v}_f - m\vec{v}_i$

- Incase, F is changing

$$\Delta\vec{p} = \vec{F}_{net/average} \Delta t = \vec{I}$$



Example 1: Calculating the Change of Momentum

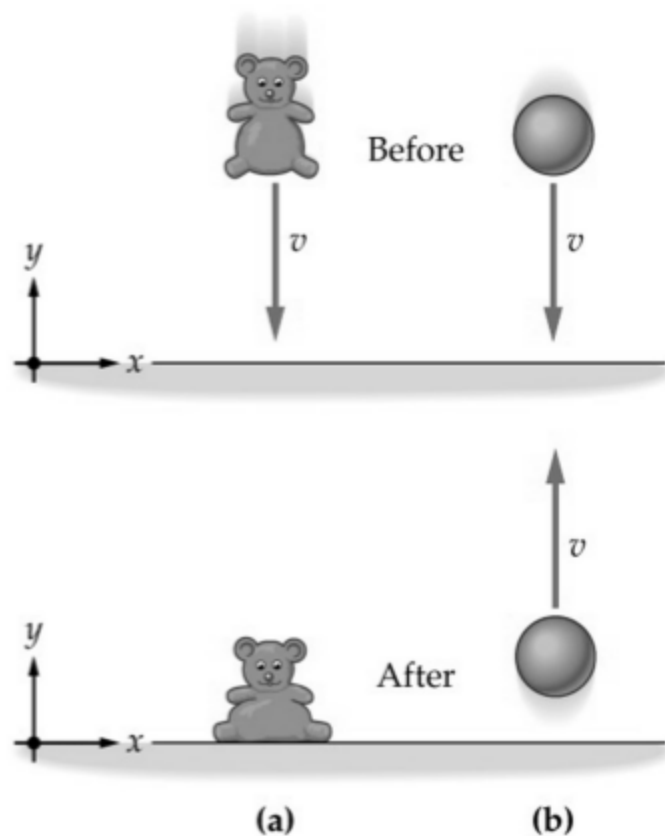
$$\begin{aligned}\Delta \vec{p} &= \vec{p}_{after} - \vec{p}_{before} \\ &= m\vec{v}_{after} - m\vec{v}_{before} \\ &= m(\vec{v}_{after} - \vec{v}_{before})\end{aligned}$$

For the teddy bear

$$\Delta p = m[0 - (-v)] = mv$$

For the bouncing ball

$$\Delta p = m[v - (-v)] = 2mv$$



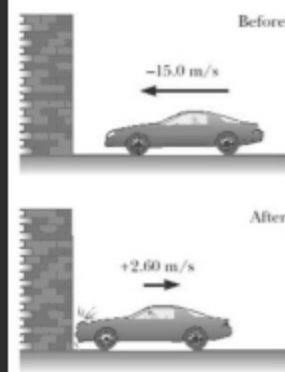
(a)

(b)

Example 2: How Good Are the Bumpers?

In a crash test, a car of mass $1.5 \times 10^3 \text{ kg}$ collides with a wall and rebounds as in figure. The initial and final velocities of the car are $v_i = -15 \text{ m/s}$ and $v_f = 2.6 \text{ m/s}$, respectively. If the collision lasts for 0.15 s , find

- the impulse delivered to the car due to the collision
- the size and direction of the average force exerted on the car



$$p_i = mv_i = (1.5 \times 10^3 \text{ kg})(-15 \text{ m/s}) = -2.25 \times 10^4 \text{ kg} \cdot \text{m/s}$$

$$p_f = mv_f = (1.5 \times 10^3 \text{ kg})(+2.6 \text{ m/s}) = +0.39 \times 10^4 \text{ kg} \cdot \text{m/s}$$

$$\begin{aligned} I &= p_f - p_i = mv_f - mv_i \\ &= (0.39 \times 10^4 \text{ kg} \cdot \text{m/s}) - (-2.25 \times 10^4 \text{ kg} \cdot \text{m/s}) \\ &= 2.64 \times 10^4 \text{ kg} \cdot \text{m/s} \end{aligned}$$

$$F_{av} = \frac{\Delta p}{\Delta t} = \frac{I}{\Delta t} = \frac{2.64 \times 10^4 \text{ kg} \cdot \text{m/s}}{0.15 \text{ s}} = 1.76 \times 10^5 \text{ N}$$

Example 3: Impulse-Momentum Theorem

- A child bounces a 100 g superball on the sidewalk. The velocity of the superball changes from 10 m/s downward to 10 m/s upward. If the contact time with the sidewalk is 0.1s, what is the magnitude of the impulse imparted to the superball?

- (A) 0
- (B) 2 kg.m/s
- (C) 20 kg.m/s
- (D) 200 kg.m/s
- (E) 2000 kg.m/s

$$\vec{I} = \Delta \vec{p} = m\vec{v}_f - m\vec{v}_i$$

- what is the magnitude of the force between the sidewalk and the superball?

- (A) 0
- (B) 2 N
- (C) 20 N
- (D) 200 N
- (E) 2000 N

$$\vec{F} = \frac{\vec{I}}{\Delta t} = \frac{\Delta \vec{p}}{\Delta t} = \frac{m\vec{v}_f - m\vec{v}_i}{\Delta t}$$

6.3. Conservation of Momentum

- In a system: Masses $m_1, m_2, \dots, m_N$ Velocities: $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_N$
$$\frac{d\vec{p}_i}{dt} = \vec{F}_{i-external} + \vec{F}_{i-internal}$$

- Using 3rd Newton's Law $\Rightarrow \sum_{i=1}^N \vec{F}_{i-internal} = 0$, so

$$\sum_{i=1}^N \frac{d\vec{p}_i}{dt} = \sum_{i=1}^N \vec{F}_{i-external}$$

- In case of isolated system: $\sum_{i=1}^N \vec{F}_{i-external} = 0$

$$\Rightarrow \sum_{i=1}^N \vec{p}_i = \text{const}$$

- the total momentum of the isolated system remains constant in time.
 - Isolated system: no external forces.
 - Closed system: no mass enters or leaves.
 - The linear momentum of each colliding body may change.
 - The total momentum $\vec{p}$ of the system cannot change.

6.4. Collision & Conservation of Momentum

- Start from impulse-momentum theorem

$$\vec{F}_{21}\Delta t = m_1\vec{v}_{1f} - m_1\vec{v}_{1i}$$

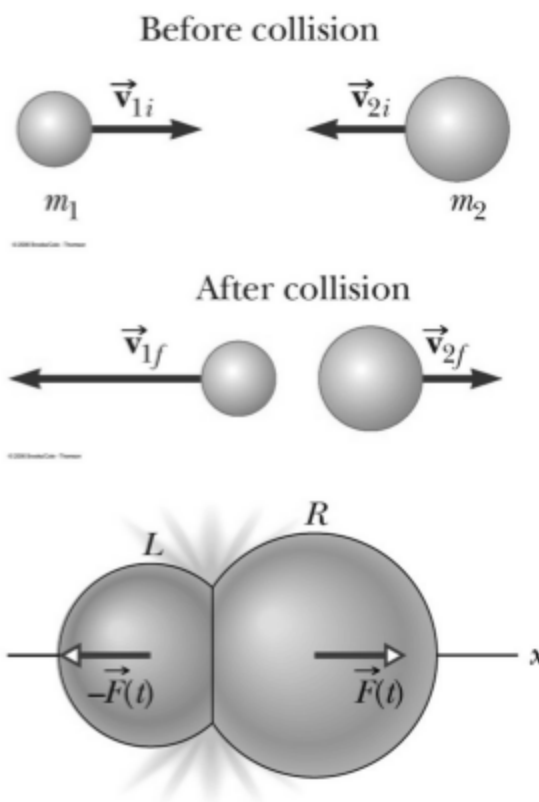
$$\vec{F}_{12}\Delta t = m_2\vec{v}_{2f} - m_2\vec{v}_{2i}$$

- Since: $\vec{F}_{21}\Delta t = -\vec{F}_{12}\Delta t$

- Then: $m_1\vec{v}_{1f} - m_1\vec{v}_{1i} = -(m_2\vec{v}_{2f} - m_2\vec{v}_{2i})$

- So:

$$m_1\vec{v}_{1i} + m_2\vec{v}_{2i} = m_1\vec{v}_{1f} + m_2\vec{v}_{2f}$$



Conservation of Momentum: two objects

- When no external forces act on a system consisting of two objects that collide with each other, the total momentum of the system remains constant in time

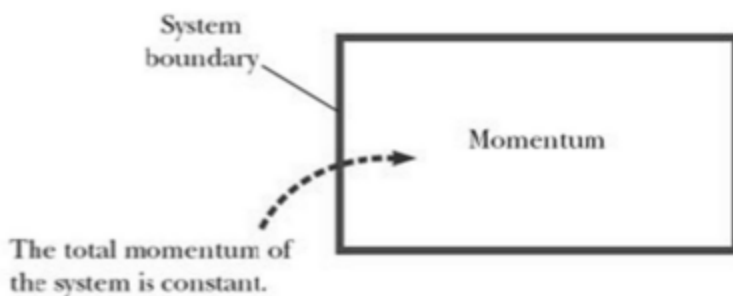
$$\vec{F}_{net}\Delta t = \Delta\vec{p} = \vec{p}_f - \vec{p}_i$$

- When $\vec{F}_{net} = 0$
then $\Delta\vec{p} = 0$
- For an isolated system

$$\vec{p}_f = \vec{p}_i$$

- Specifically, the total momentum before the collision will equal the total momentum after the collision:

$$m_1\vec{v}_{1i} + m_2\vec{v}_{2i} = m_1\vec{v}_{1f} + m_2\vec{v}_{2f}$$



Example 3: The Archer

An archer stands at rest on frictionless ice and fires a 0.5-kg arrow horizontally at 50.0 m/s. The combined mass of the archer and bow is 60.0 kg. With what velocity does the archer move across the ice after firing the arrow?

$$m_1 = 60.0\text{ kg}, m_2 = 0.5\text{ kg},$$

$$v_{1i} = v_{2i} = 0, v_{2f} = \frac{50\text{ m}}{\text{s}},$$

$$v_{1f} = ?$$

$$p_i = p_f$$

$$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1f} + m_2 v_{2f}$$

$$0 = m_1 v_{1f} + m_2 v_{2f}$$

$$v_{1f} = -\frac{m_2}{m_1} v_{2f} = -\frac{0.5\text{ kg}}{60.0\text{ kg}} (50.0\text{ m/s}) = -0.417\text{ m/s}$$



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MCQ: Conservation of Momentum

A 100 kg man and 50 kg woman on ice skates stand facing each other. If the woman pushes the man backwards so that his final speed is 1 m/s, at what speed does she recoil?

- (A) 0
- (B) 0.5 m/s
- (C) 1 m/s
- (D) 1.414 m/s
- (E) 2 m/s

6.4. Collision (cont's)

Types of Collisions

- Momentum is conserved in any collision
- **Inelastic collisions:** *rubber ball and hard ball*
 - Kinetic energy is not conserved
 - **Perfectly inelastic** collisions occur when the objects stick together
- **Elastic collisions:** *billiard ball*
 - both momentum and kinetic energy are conserved
- **Actual collisions**
 - Most collisions fall between elastic and perfectly inelastic collisions

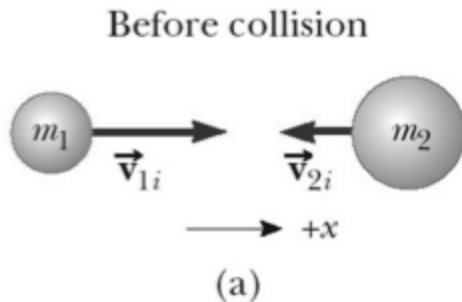
Collisions Summary

- In an elastic collision, both momentum and kinetic energy are conserved.
- In a non-perfect inelastic collision, momentum is conserved but kinetic energy is not. Moreover, the objects do not stick together.
- In a perfectly inelastic collision, momentum is conserved, kinetic energy is not, and the two objects stick together after the collision, so their final velocities are the same.
- Elastic and perfectly inelastic collisions are limiting cases, most actual collisions fall in between these two types .
- Momentum is conserved in almost all collisions.

6.4.1. Perfectly Inelastic Collisions

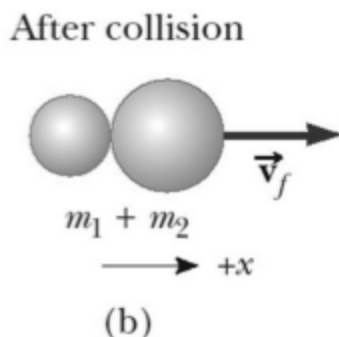
- When two objects stick together after the collision, they have undergone a perfectly inelastic collision
- Conservation of momentum

$$m_1 v_{1i} + m_2 v_{2i} = (m_1 + m_2) v_f$$



- Kinetic energy is NOT conserved

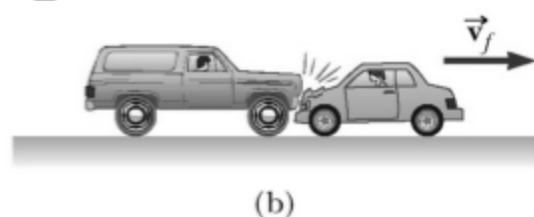
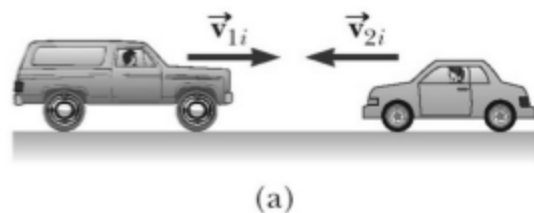
$$v_f = \frac{m_1 v_{1i} + m_2 v_{2i}}{m_1 + m_2}$$



An SUV Versus a Compact

- An SUV with mass 1.80×10^3 kg is travelling eastbound at $+15.0$ m/s, while a compact car with mass 9.0×10^2 kg is travelling westbound at -15.0 m/s. The cars collide head-on, becoming entangled.

- Find the speed of the entangled cars after the collision.
- Find the change in the velocity of each car.
- Find the change in the kinetic energy of the system consisting of both cars.



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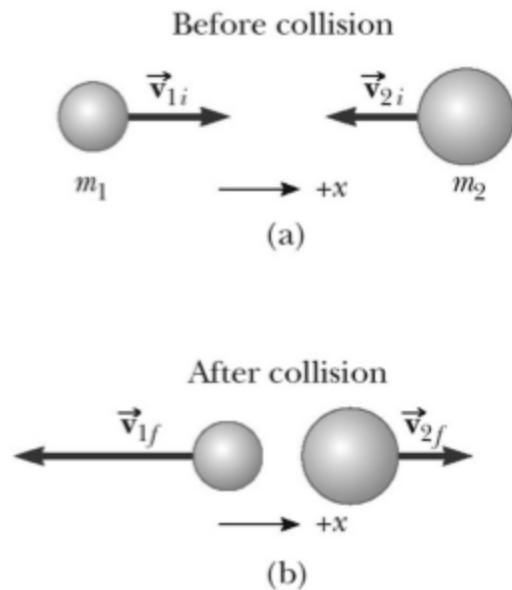
6.4.2. Elastic Collisions

- Both momentum and kinetic energy are conserved

$$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1f} + m_2 v_{2f}$$

$$\frac{1}{2} m_1 v_{1i}^2 + \frac{1}{2} m_2 v_{2i}^2 = \frac{1}{2} m_1 v_{1f}^2 + \frac{1}{2} m_2 v_{2f}^2$$

- Typically have two unknowns
- Momentum is a vector quantity
 - Direction is important
 - Be sure to have the correct signs
- Solve the equations simultaneously



Summary of Types of Collisions

- In an **elastic collision**, both momentum and kinetic energy are conserved

$$v_{1i} + v_{1f} = v_{2f} + v_{2i}$$

$$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1f} + m_2 v_{2f}$$

- In an **inelastic collision**, momentum is conserved but kinetic energy is not

$$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1f} + m_2 v_{2f}$$

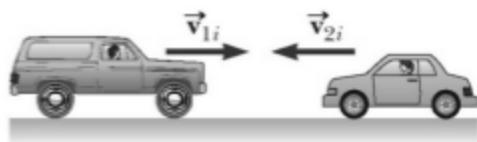
- In a **perfectly inelastic collision**, momentum is conserved, kinetic energy is not, and the two objects stick together after the collision, so their final velocities are the same

$$m_1 v_{1i} + m_2 v_{2i} = (m_1 + m_2) v_f$$

Example 5. Conservation of Momentum

- An object of mass m moves to the right with a speed v . It collides head-on with an object of mass $3m$ moving with speed $v/3$ in the opposite direction. If the two objects stick together, what is the speed of the combined object, of mass $4m$, after the collision?

- (A) 0
- (B) $v/2$
- (C) v
- (D) $2v$
- (E) $4v$



(a)

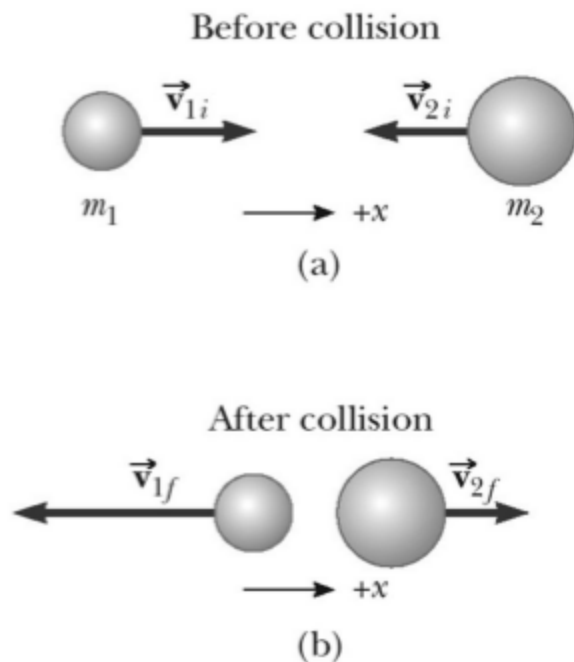


(b)

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Problem Solving for 1D Collisions, 1

- **Coordinates:** Set up a coordinate axis and define the velocities with respect to this axis
 - It is convenient to make your axis coincide with one of the initial velocities
- **Diagram:** In your sketch, draw all the velocity vectors and label the velocities and the masses

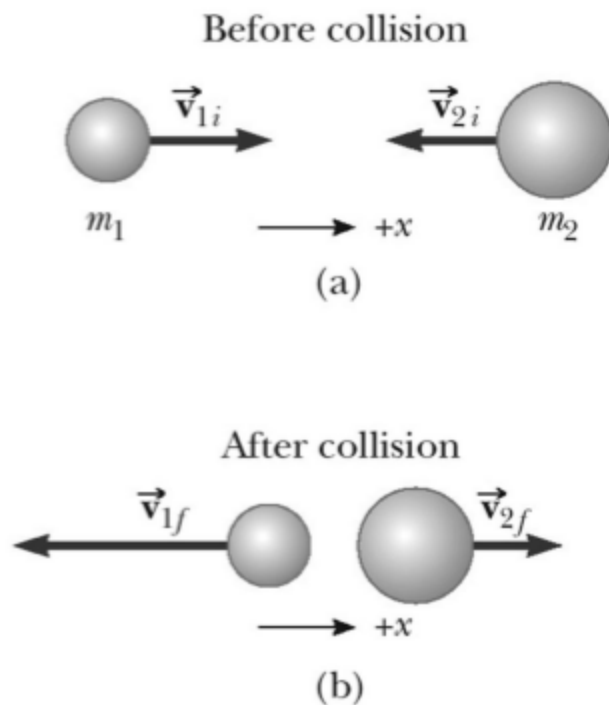


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Problem Solving for 1D Collisions, 2

- **Conservation of Momentum:**
Write a general expression for the total momentum of the system *before* and *after* the collision
 - Equate the two total momentum expressions
 - Fill in the known values

$$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1f} + m_2 v_{2f}$$



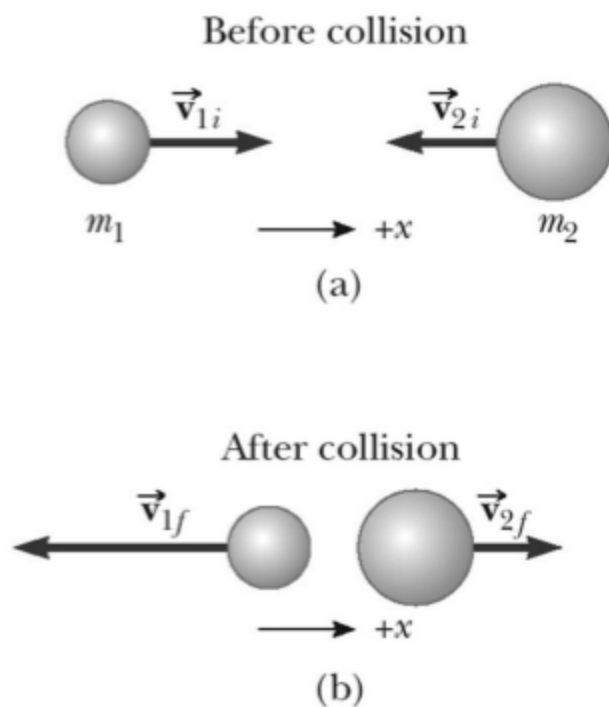
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Problem Solving for 1D Collisions, 3

- **Conservation of Energy:** If the collision is elastic, write a second equation for conservation of KE, or the alternative equation

$$v_{1i} + v_{1f} = v_{2f} + v_{2i}$$

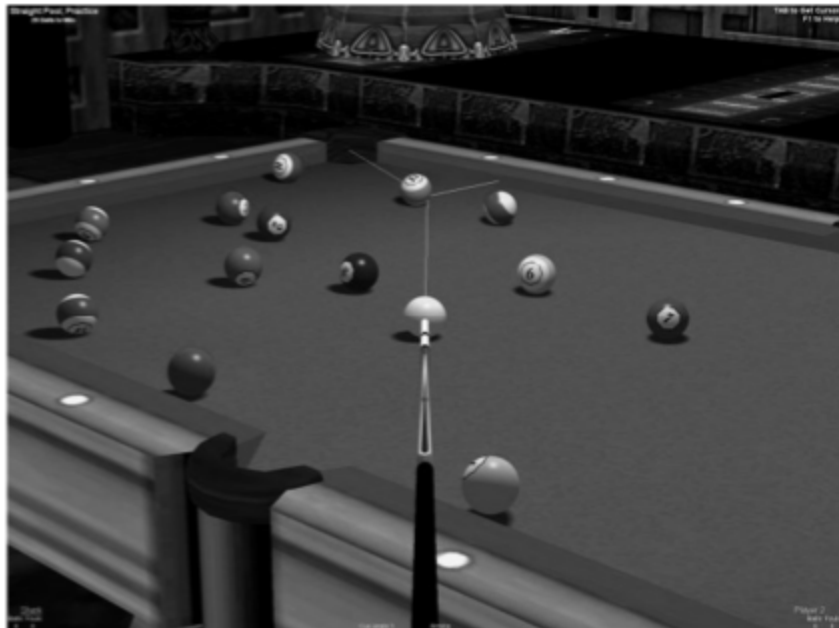
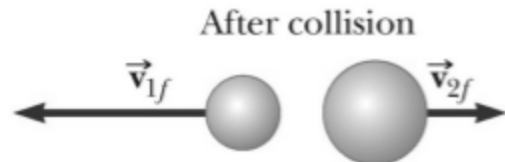
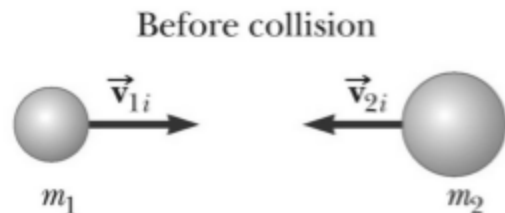
- This only applies to perfectly elastic collisions



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- **Solve:** the resulting equations

One-Dimension vs Two-Dimension

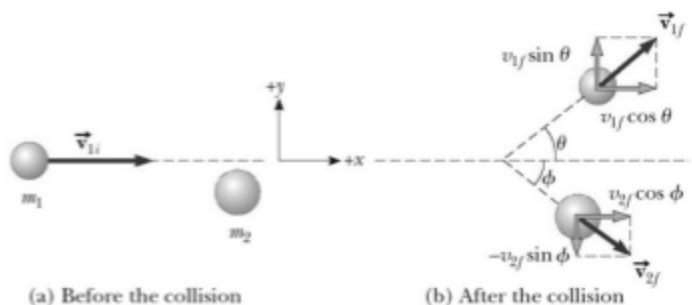


6.4.4. Two-Dimensional Collisions

- For a general collision of two objects in two-dimensional space, the conservation of momentum principle implies that the **total momentum of the system in each direction is conserved**

$$m_1 v_{1ix} + m_2 v_{2ix} = m_1 v_{1fx} + m_2 v_{2fx}$$

$$m_1 v_{1iy} + m_2 v_{2iy} = m_1 v_{1fy} + m_2 v_{2fy}$$



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6.4.4. Two-Dimensional Collisions

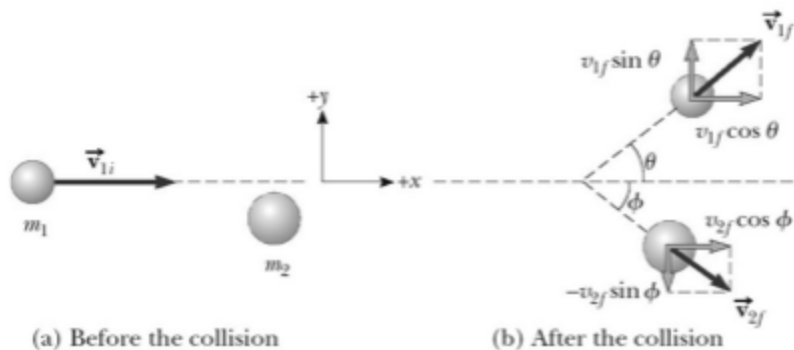
- The momentum is conserved in all directions
- Use subscripts for
 - Identifying the object
 - Indicating initial or final values
 - The velocity components
- If the collision is elastic, use conservation of kinetic energy as a second equation
 - Remember, the simpler equation can only be used for one-dimensional situations

$$\begin{aligned}m_1 v_{1ix} + m_2 v_{2ix} &= m_1 v_{1fx} + m_2 v_{2fx} \\ m_1 v_{1iy} + m_2 v_{2iy} &= m_1 v_{1fy} + m_2 v_{2fy}\end{aligned}$$

$$v_{1i} + v_{1f} = v_{2i} + v_{2f}$$

Glancing Collisions

- The “after” velocities have x and y components
- Momentum is conserved in the x direction and in the y direction
- Apply conservation of momentum separately to each direction



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$$\begin{aligned} m_1 v_{1ix} + m_2 v_{2ix} &= m_1 v_{1fx} + m_2 v_{2fx} \\ m_1 v_{1iy} + m_2 v_{2iy} &= m_1 v_{1fy} + m_2 v_{2fy} \end{aligned}$$

Example 6: 2-D Collision,

- Particle 1 is moving at velocity $\vec{v}_{1i}$ and particle 2 is at rest
- In the x -direction, the initial momentum is $m_1 v_{1i}$
- In the y -direction, the initial momentum is 0.
- After the collision, the momentum in the x -direction is $m_1 v_{1f} \cos \theta + m_2 v_{2f} \cos \phi$
- After the collision, the momentum in the y -direction is $m_1 v_{1f} \sin \theta + m_2 v_{2f} \sin \phi$

$$m_1 v_{1i} + 0 = m_1 v_{1f} \cos \theta + m_2 v_{2f} \cos \phi$$

$$0 + 0 = m_1 v_{1f} \sin \theta - m_2 v_{2f} \sin \phi$$

- If the collision is elastic, apply the kinetic energy equation

$$\frac{1}{2} m_1 v_{1i}^2 = \frac{1}{2} m_1 v_{1f}^2 + \frac{1}{2} m_2 v_{2f}^2$$