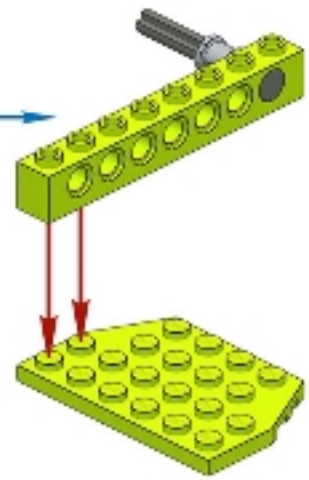
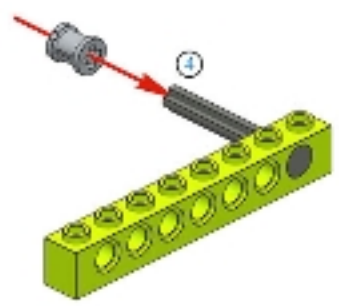
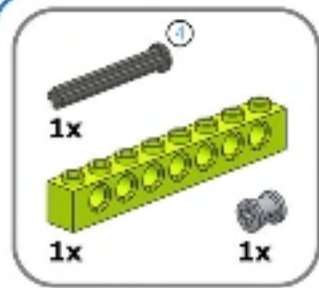
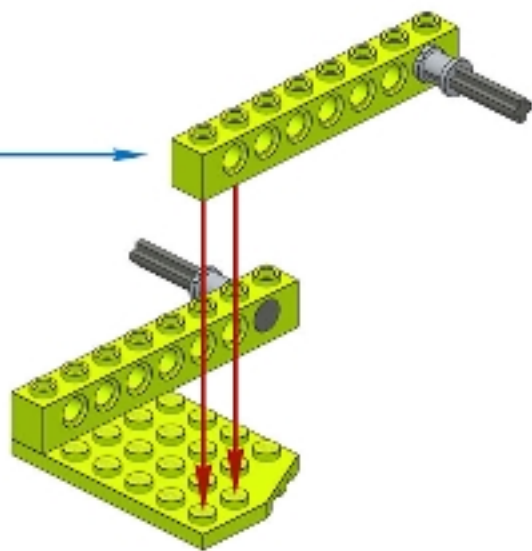
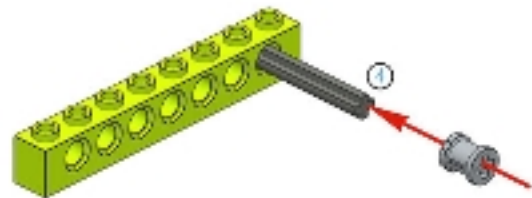


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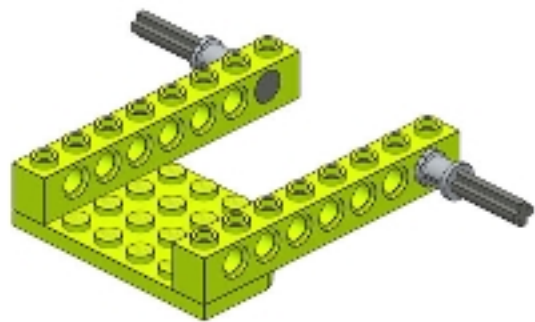


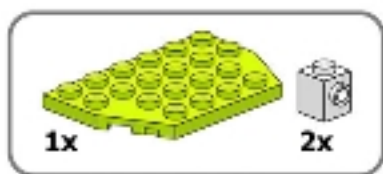


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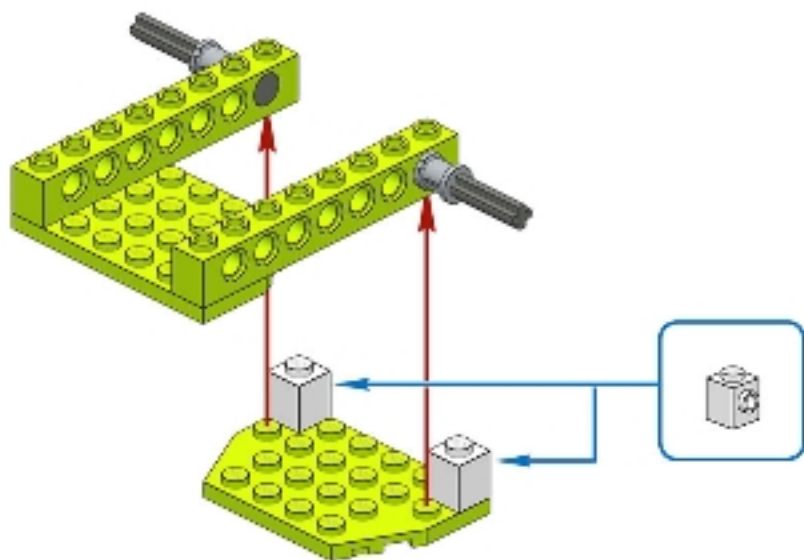


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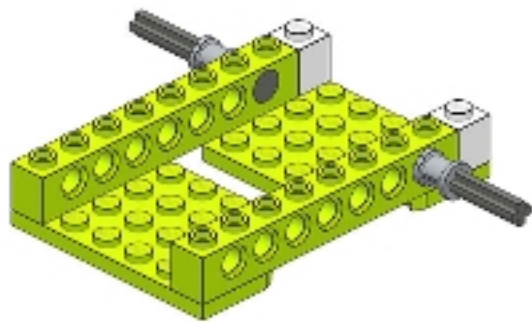




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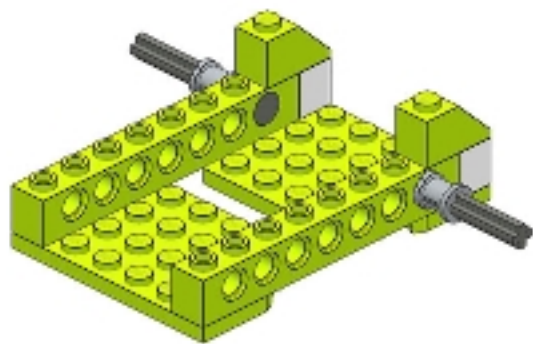
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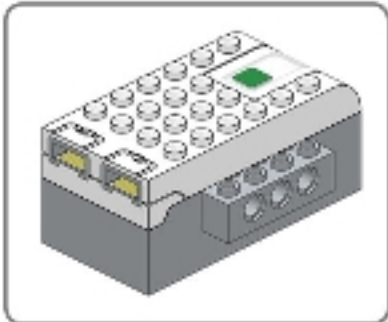




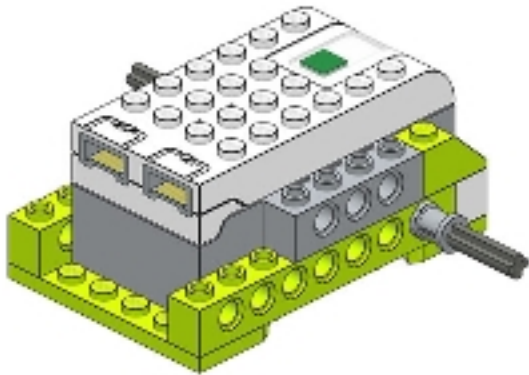
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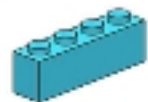
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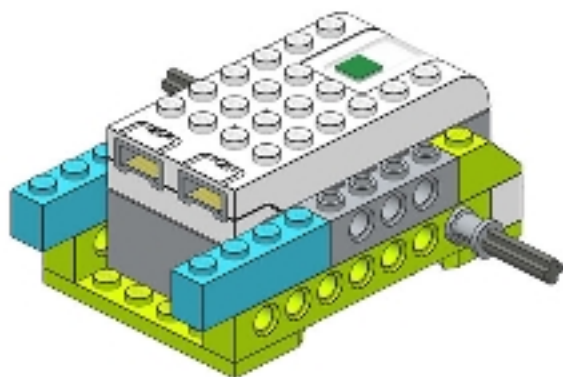
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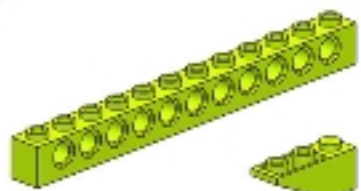




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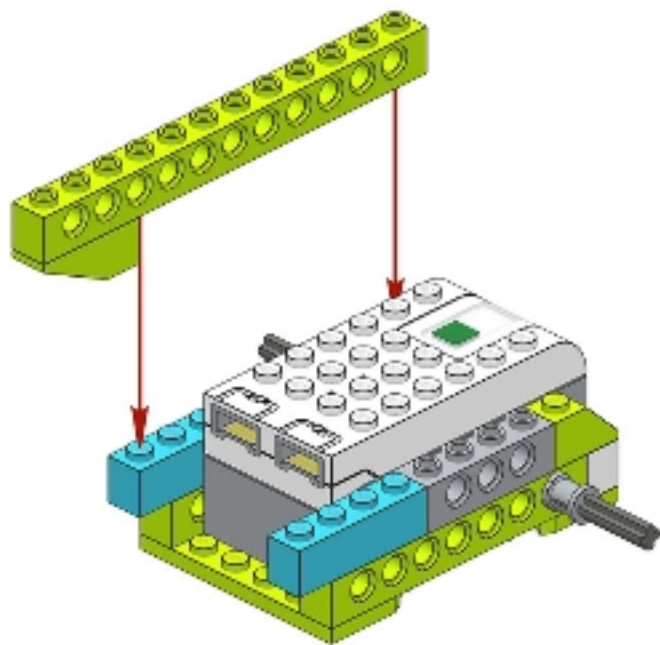




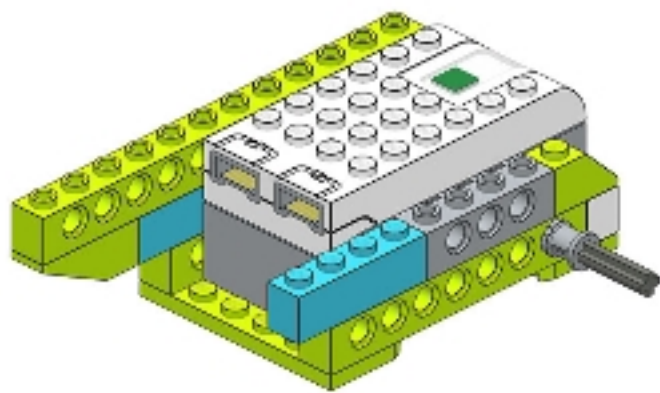
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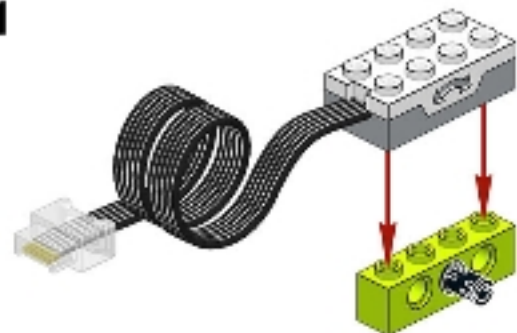
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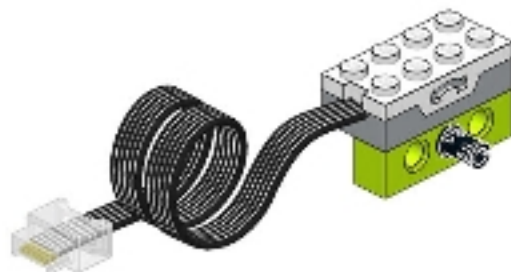


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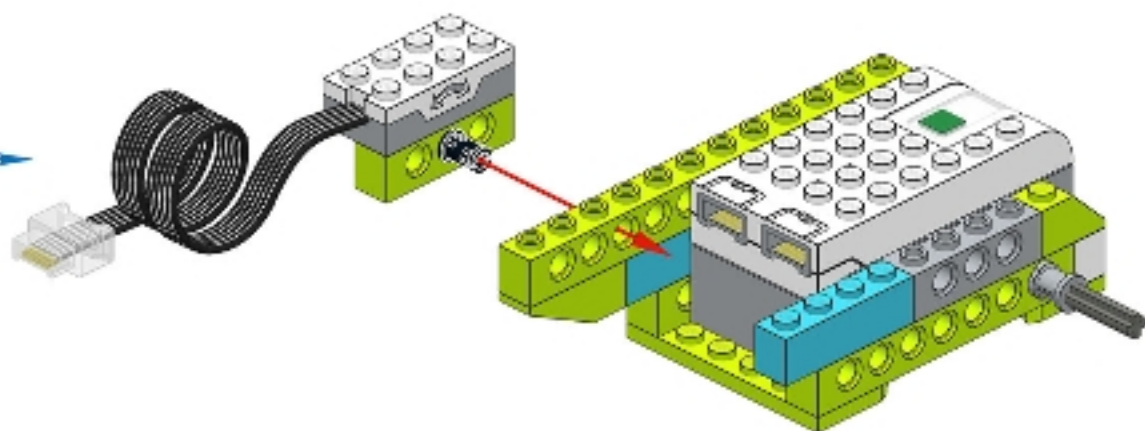
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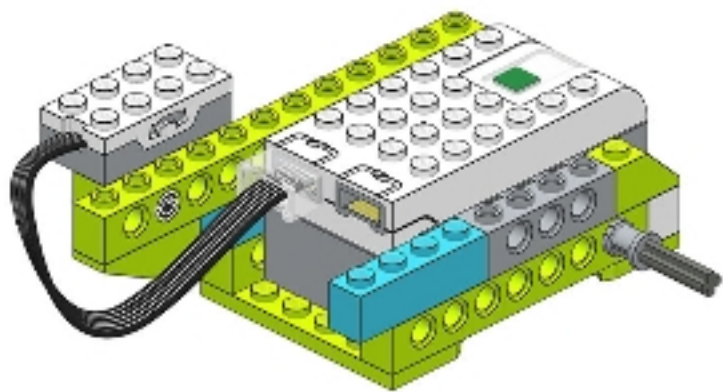
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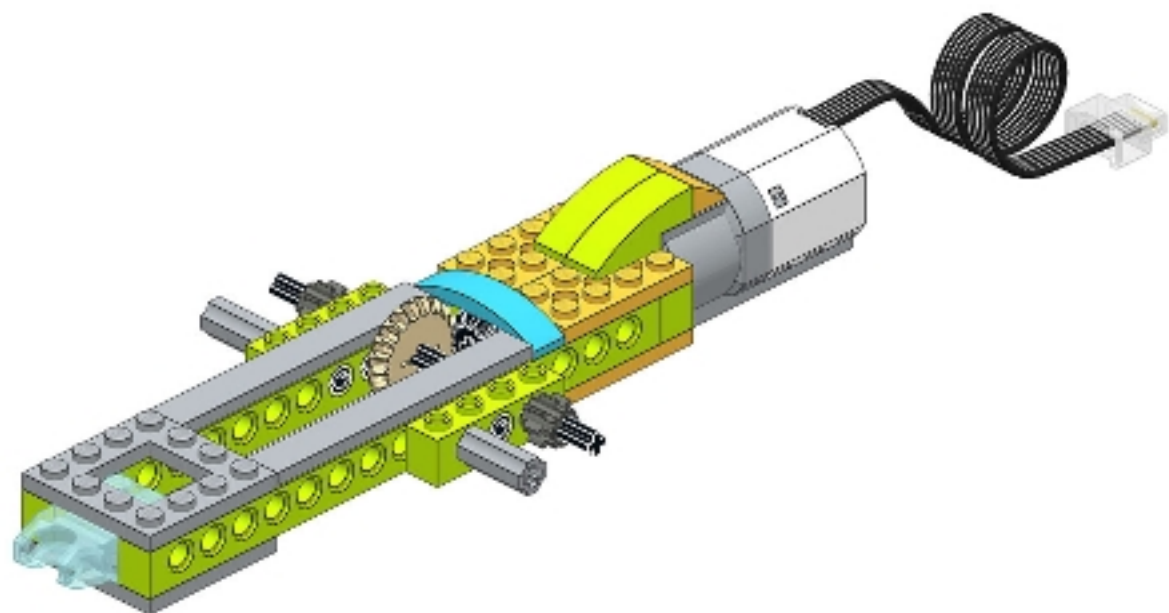


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13







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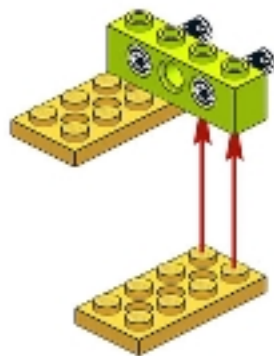


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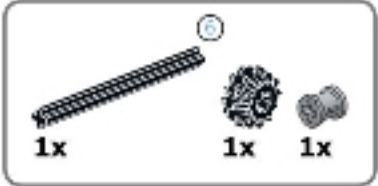




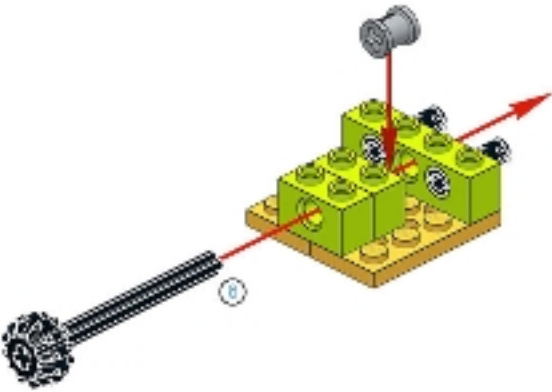
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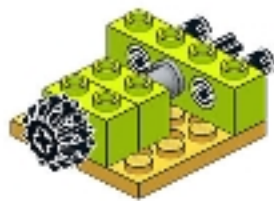


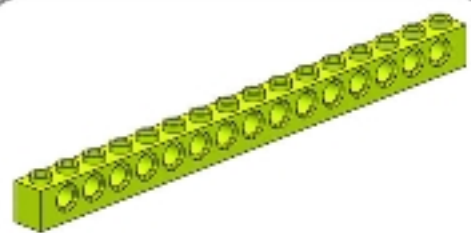


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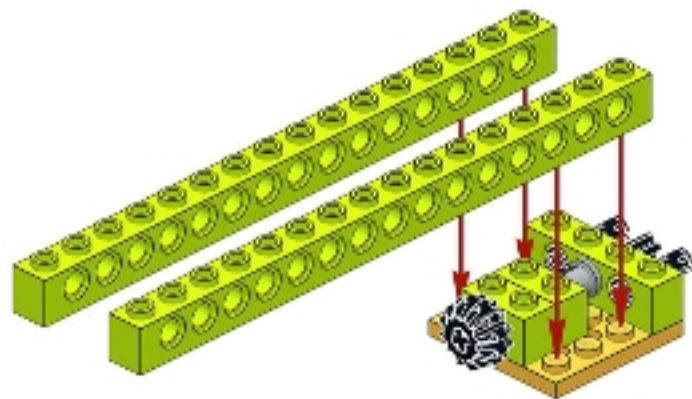
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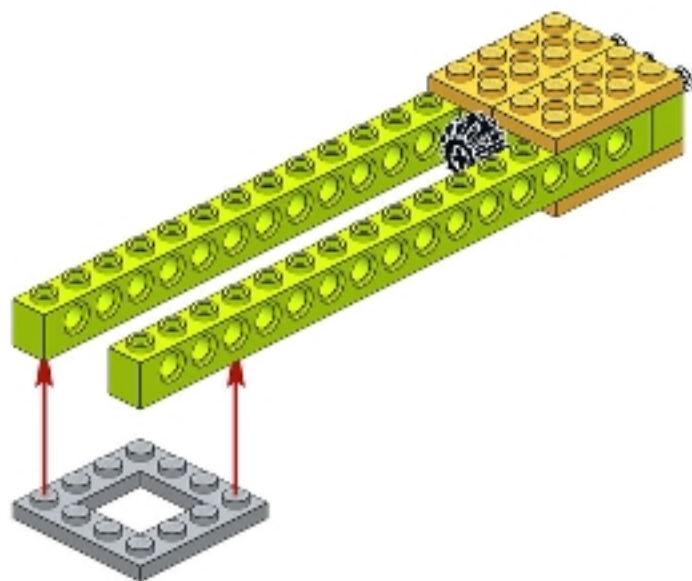
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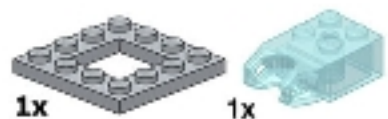




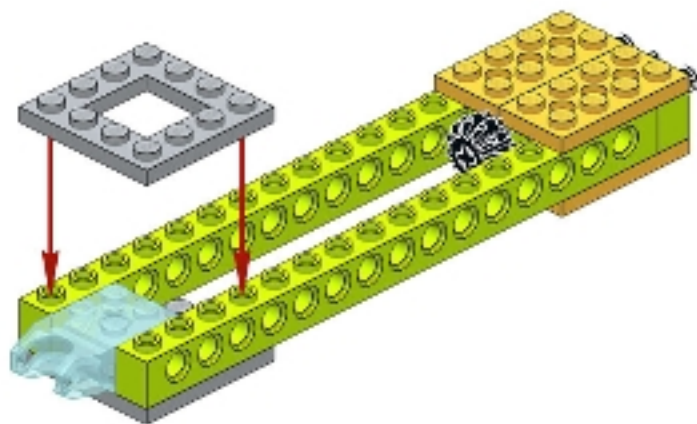
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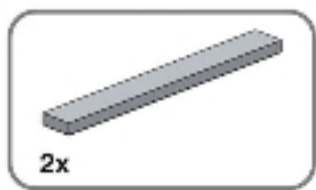
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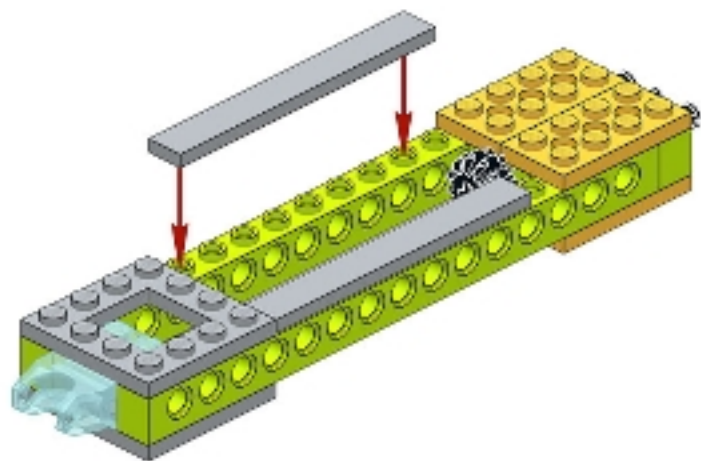


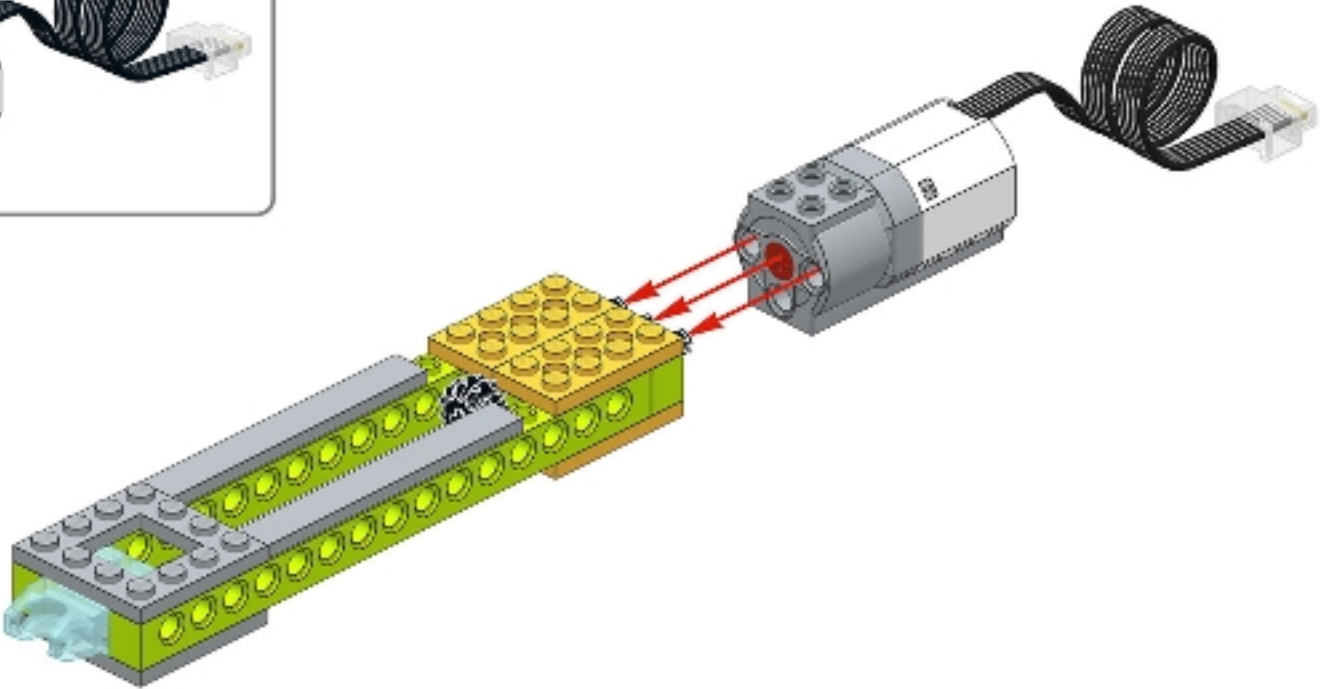
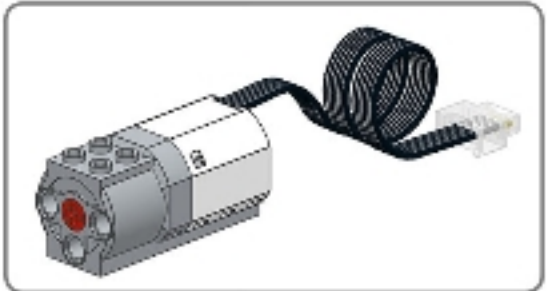
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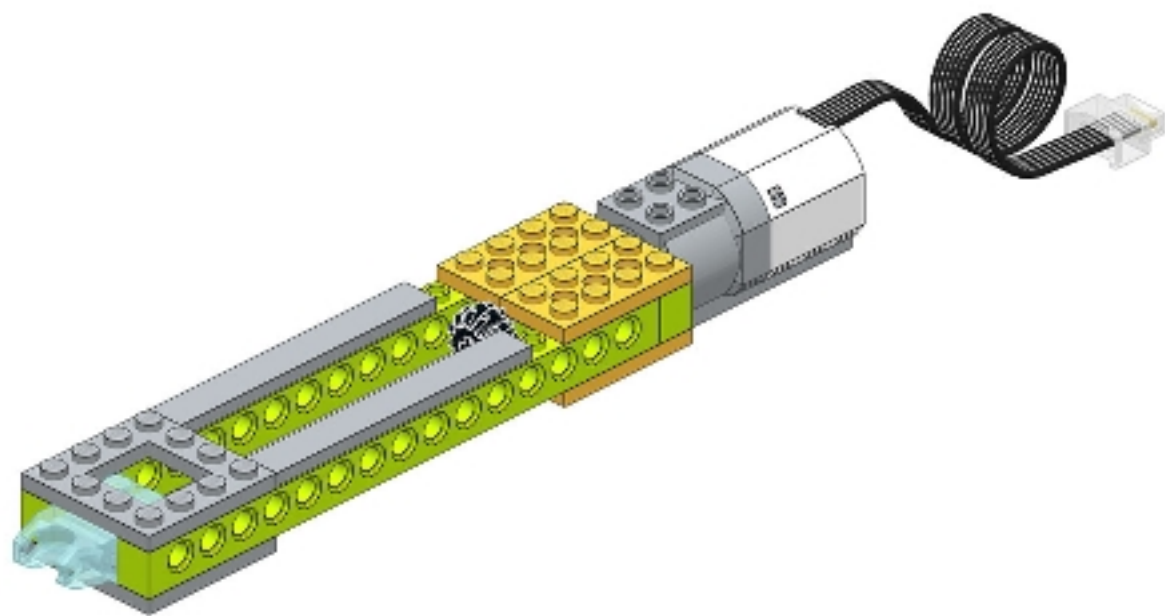
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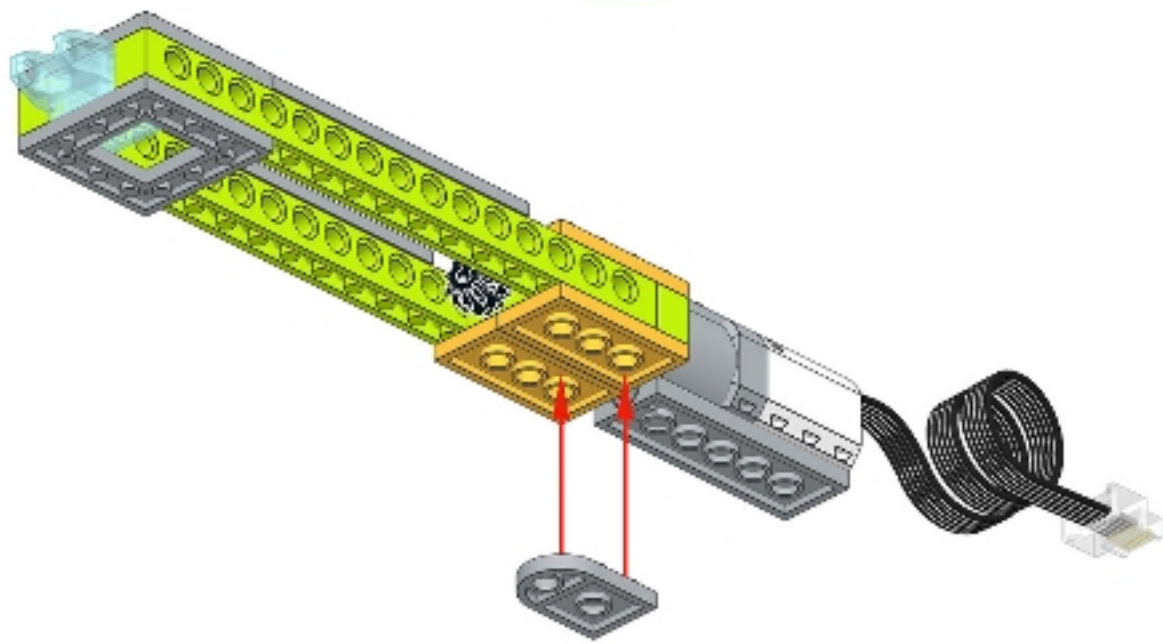




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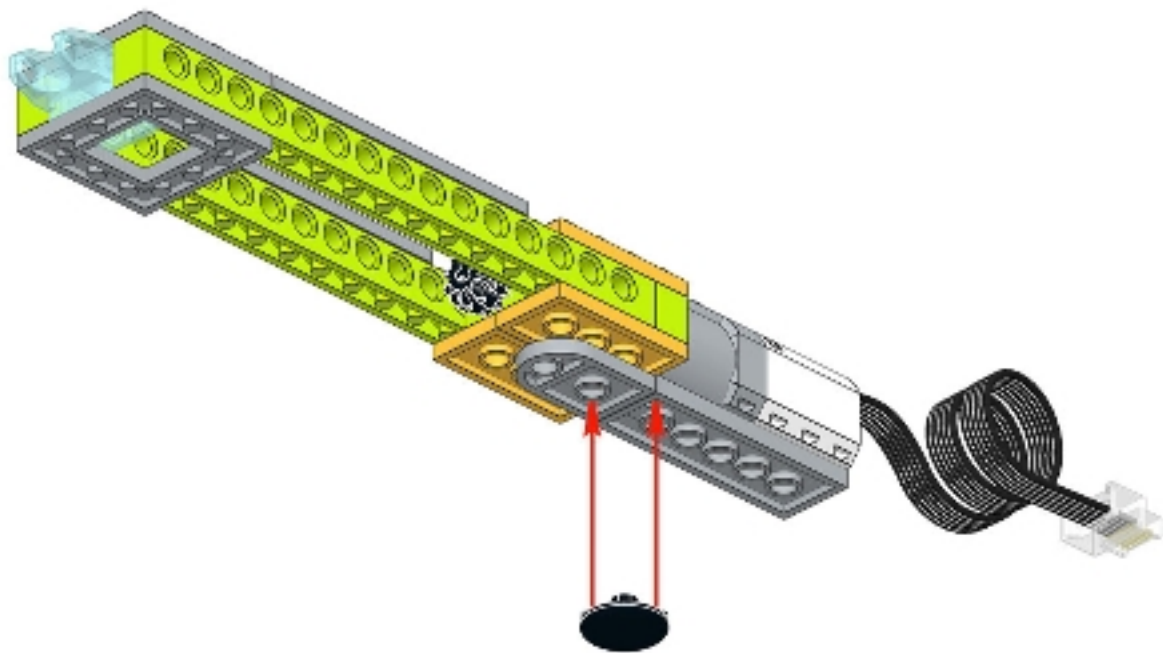
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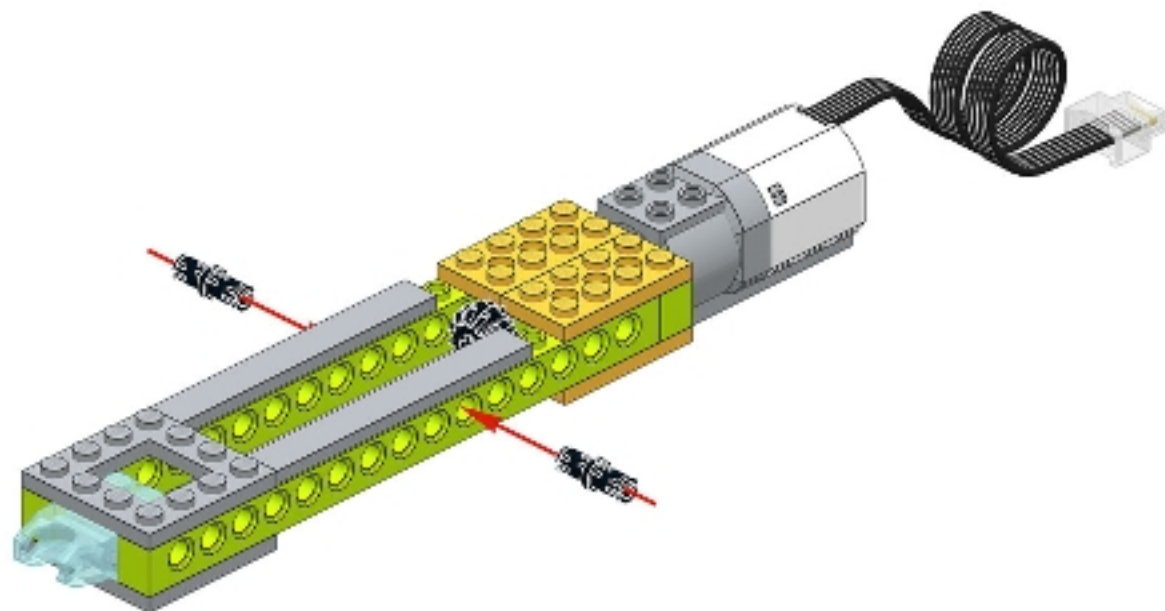




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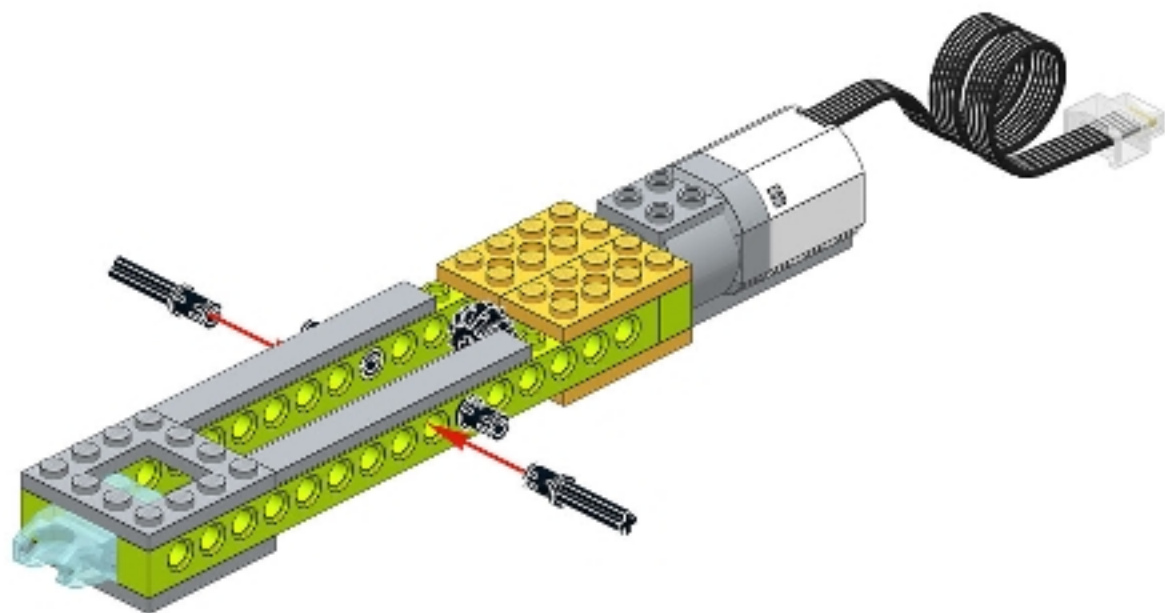
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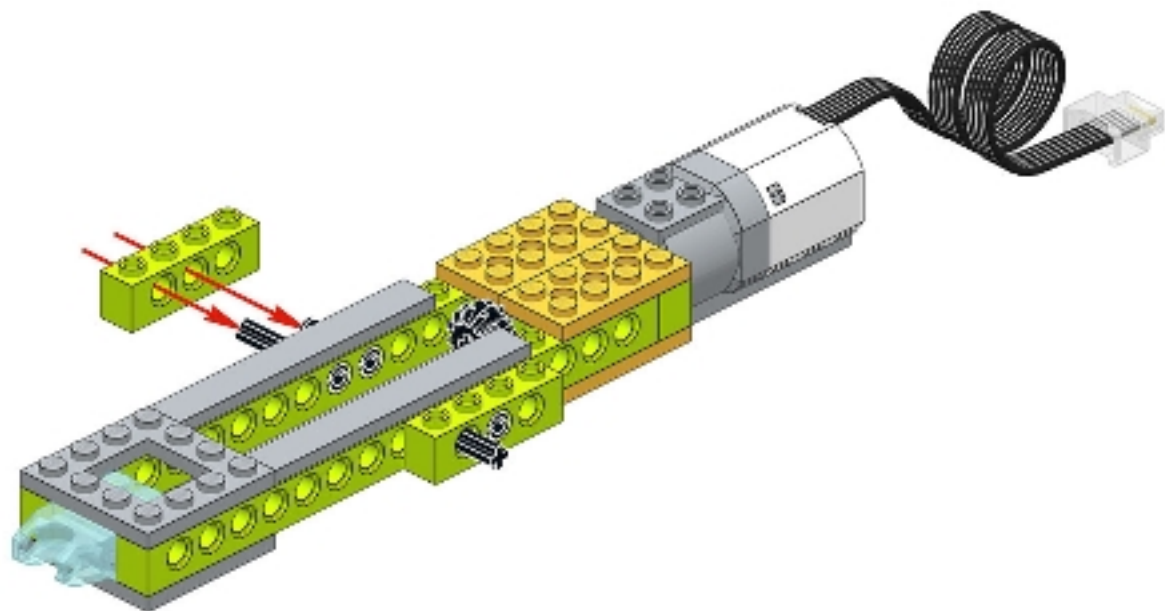
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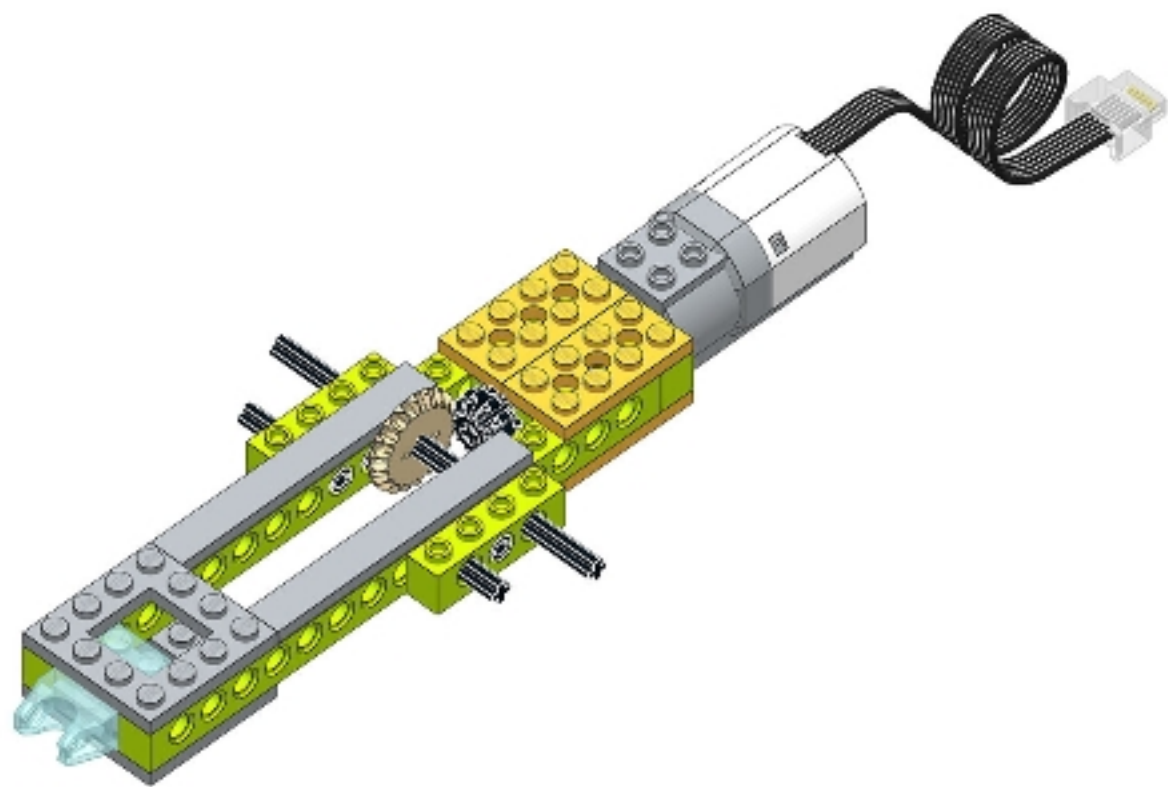


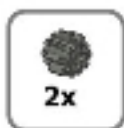
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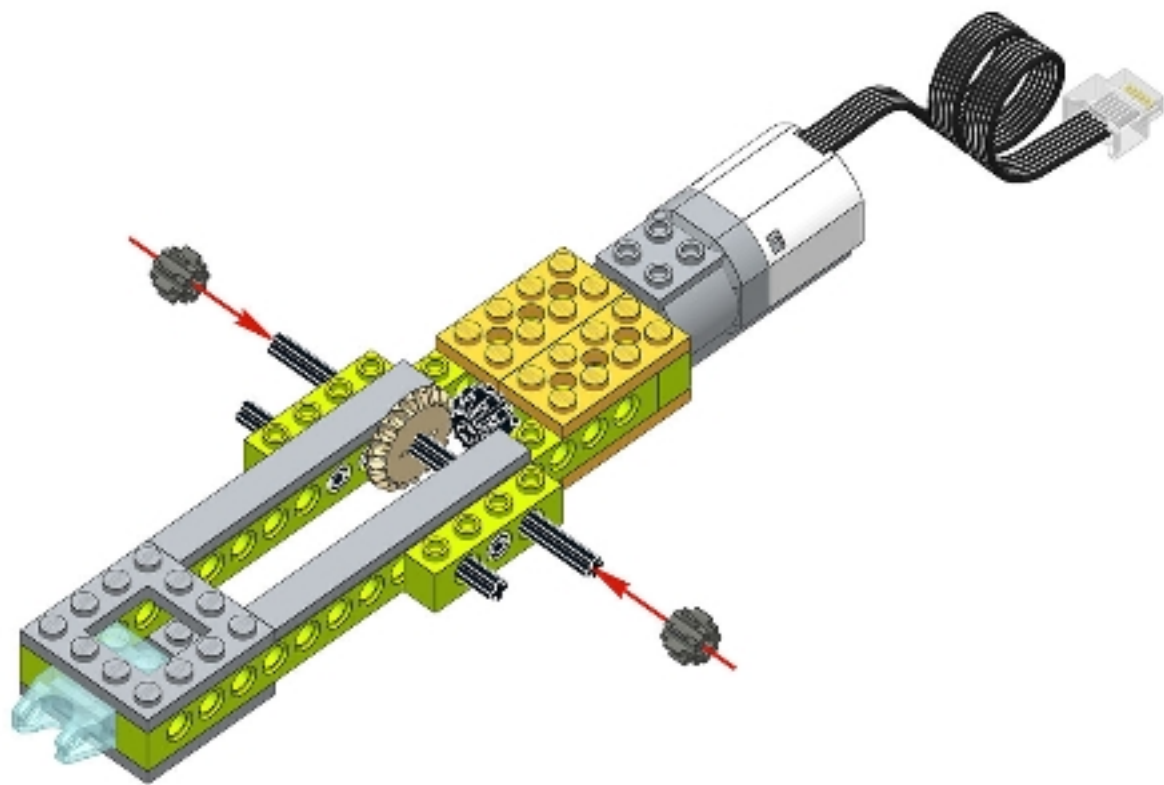


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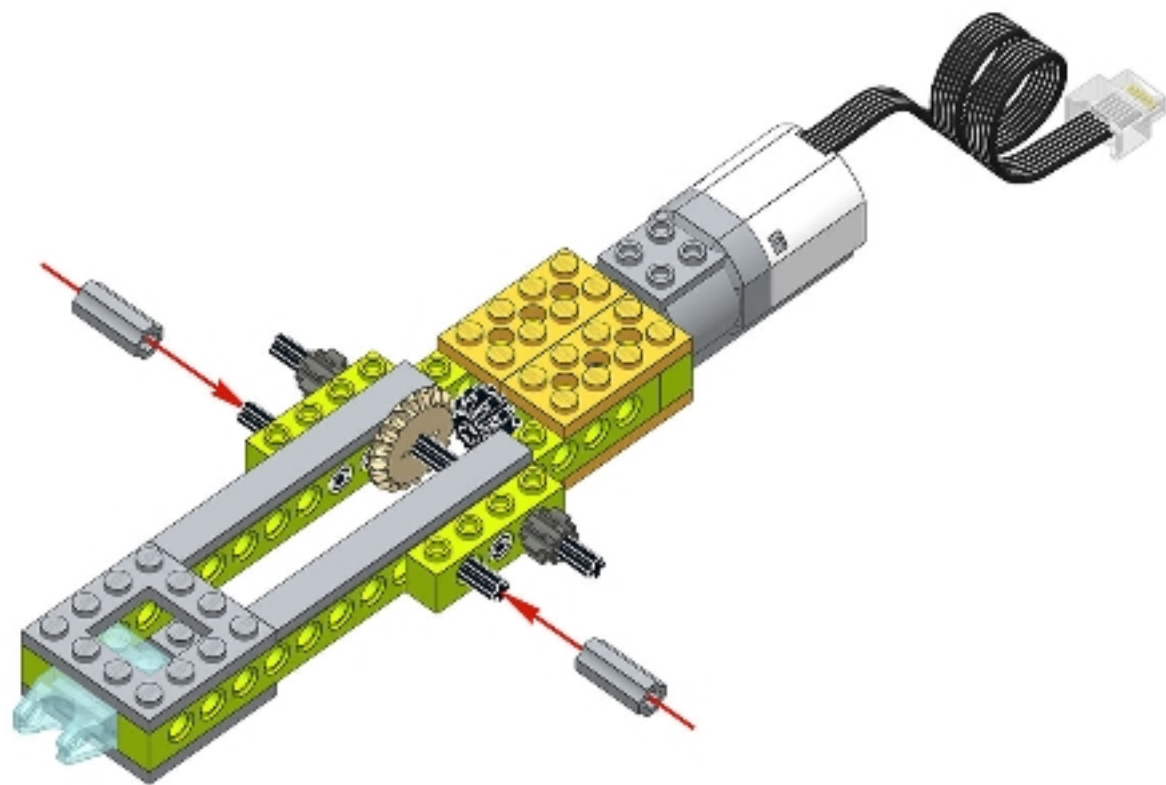
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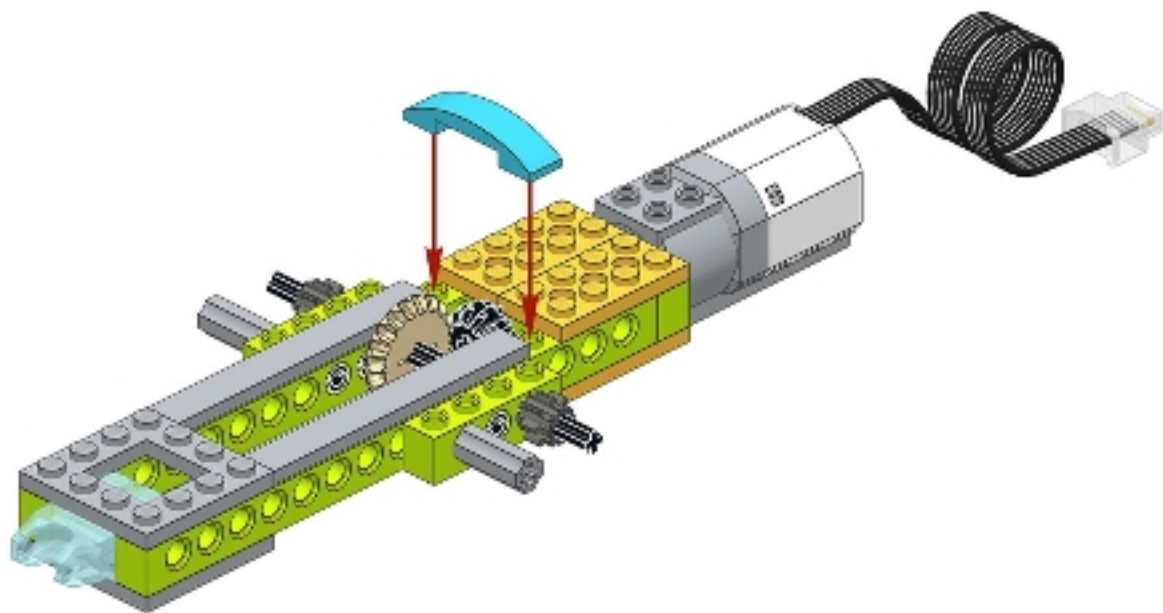
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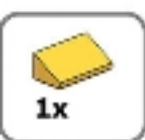




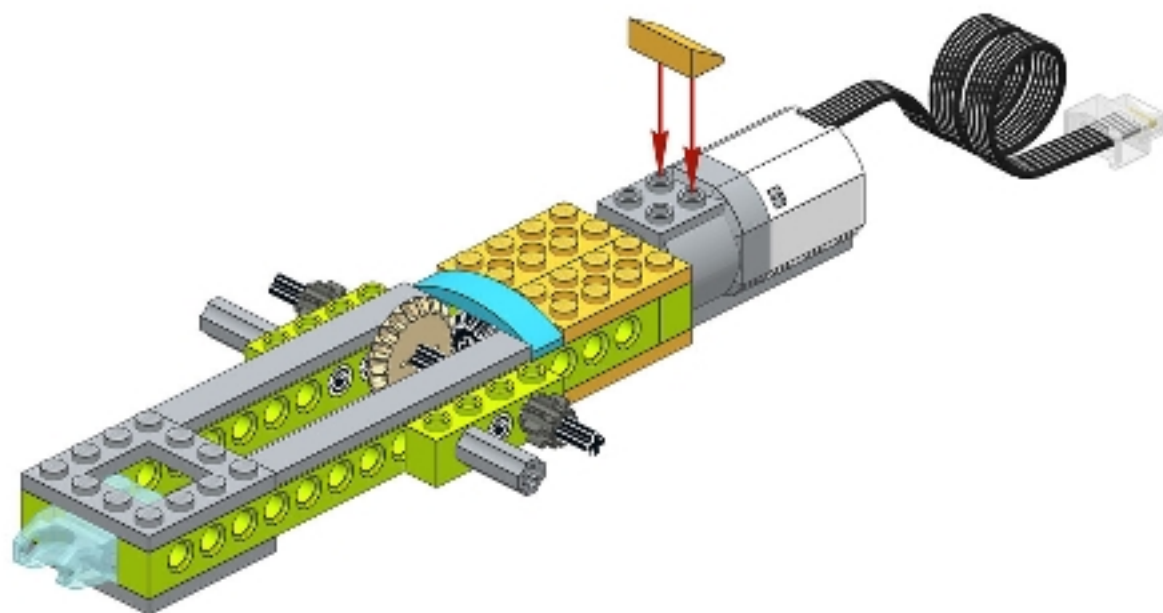
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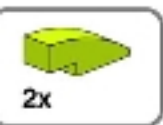
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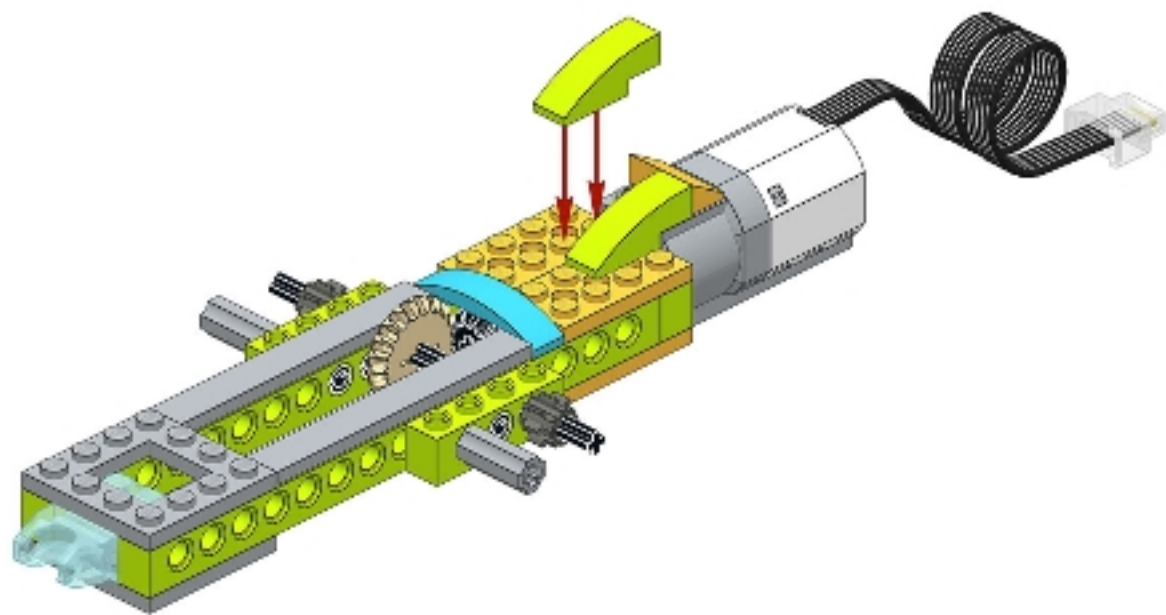


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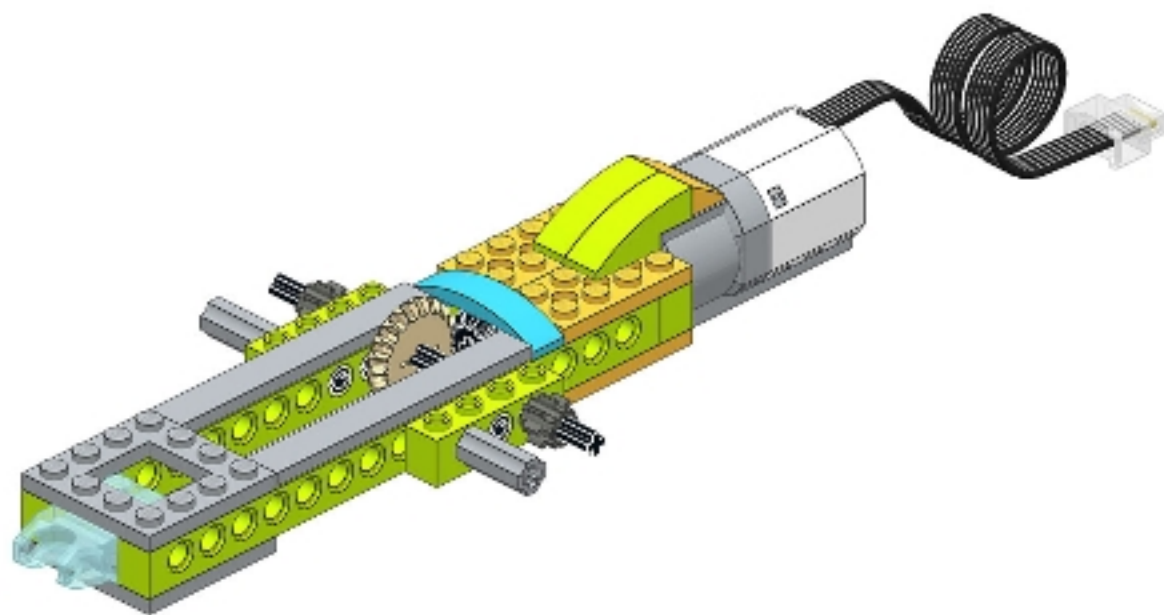




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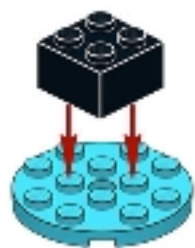




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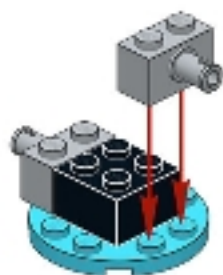
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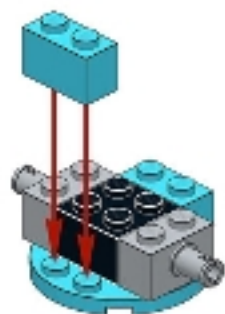
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2



2x

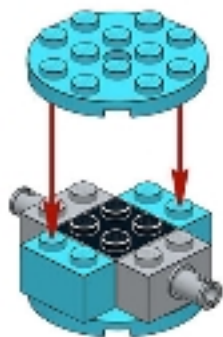
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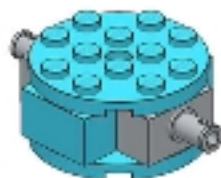


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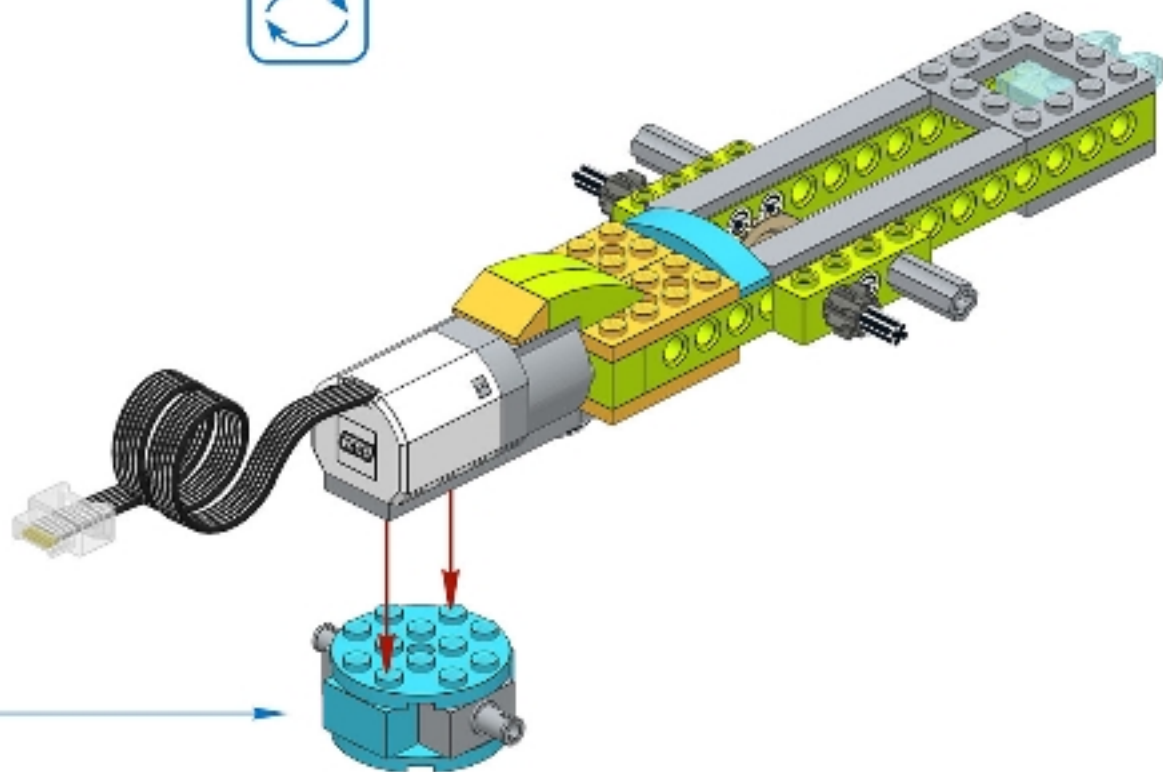
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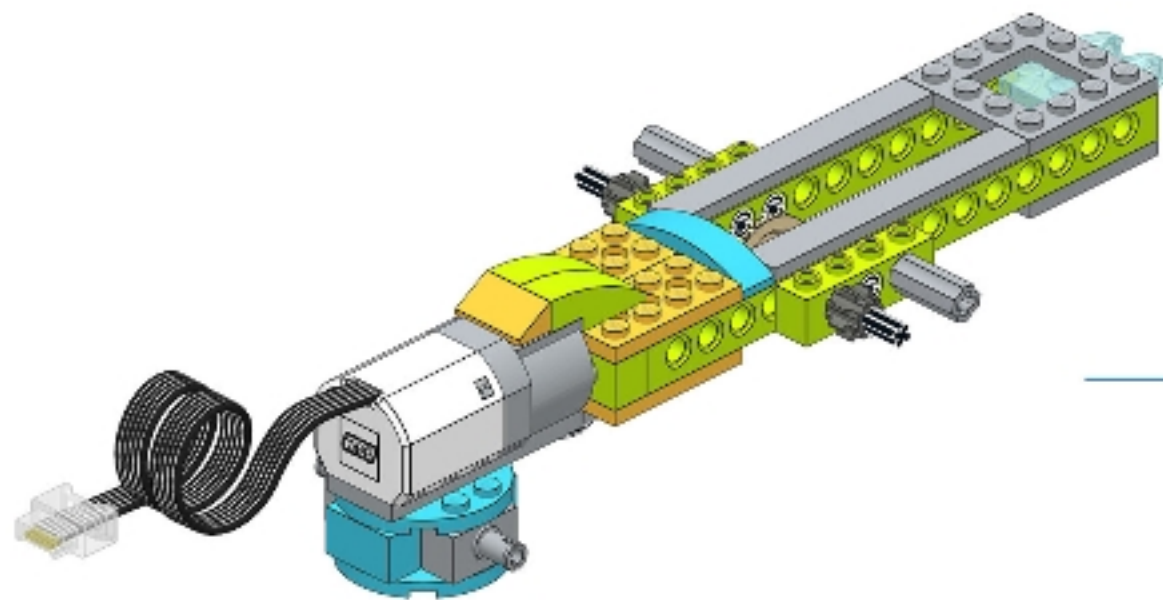
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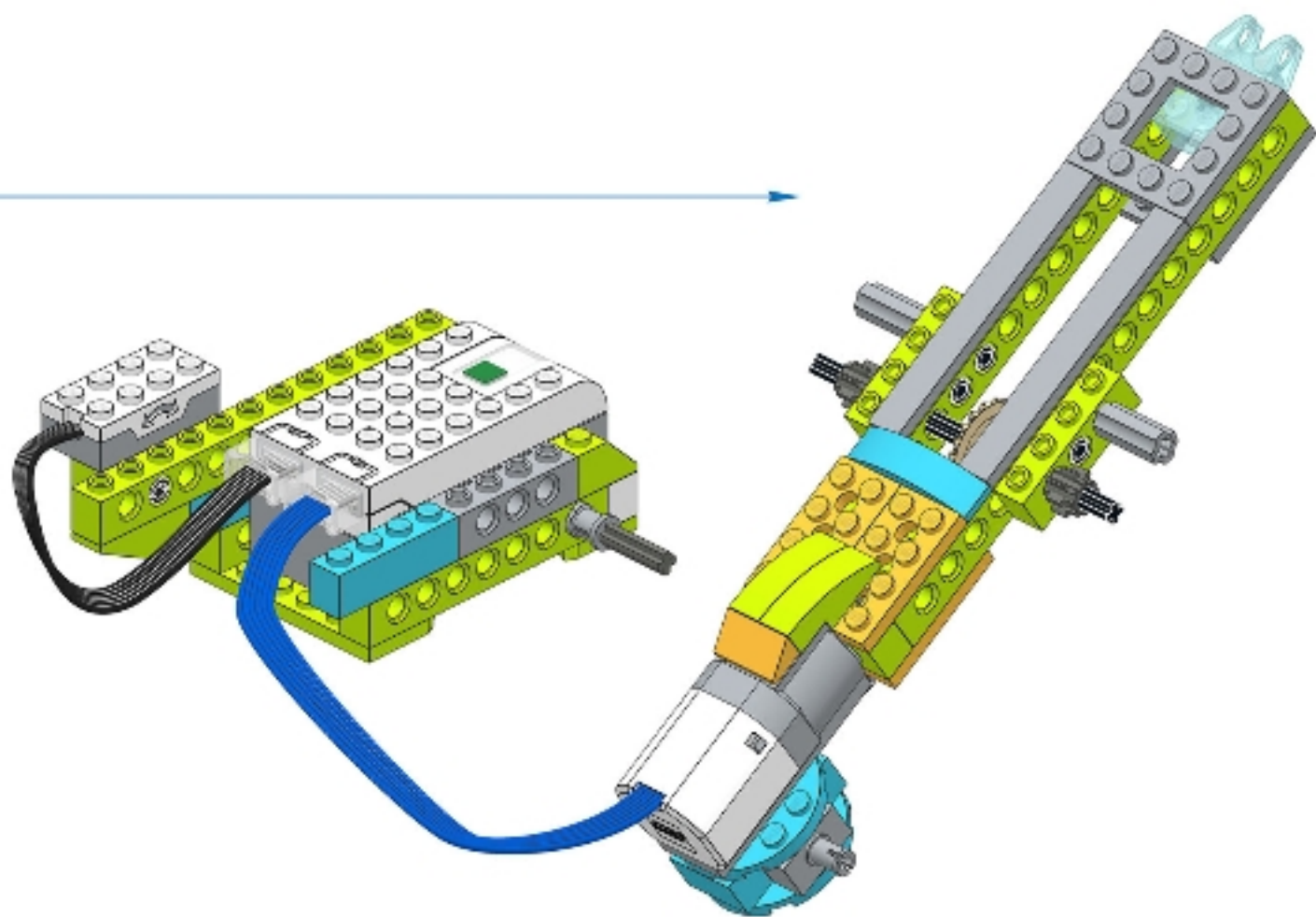
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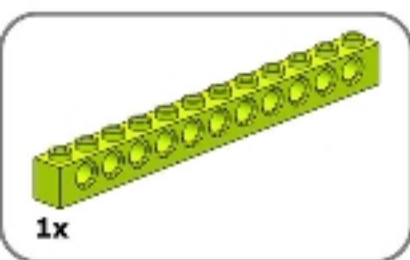


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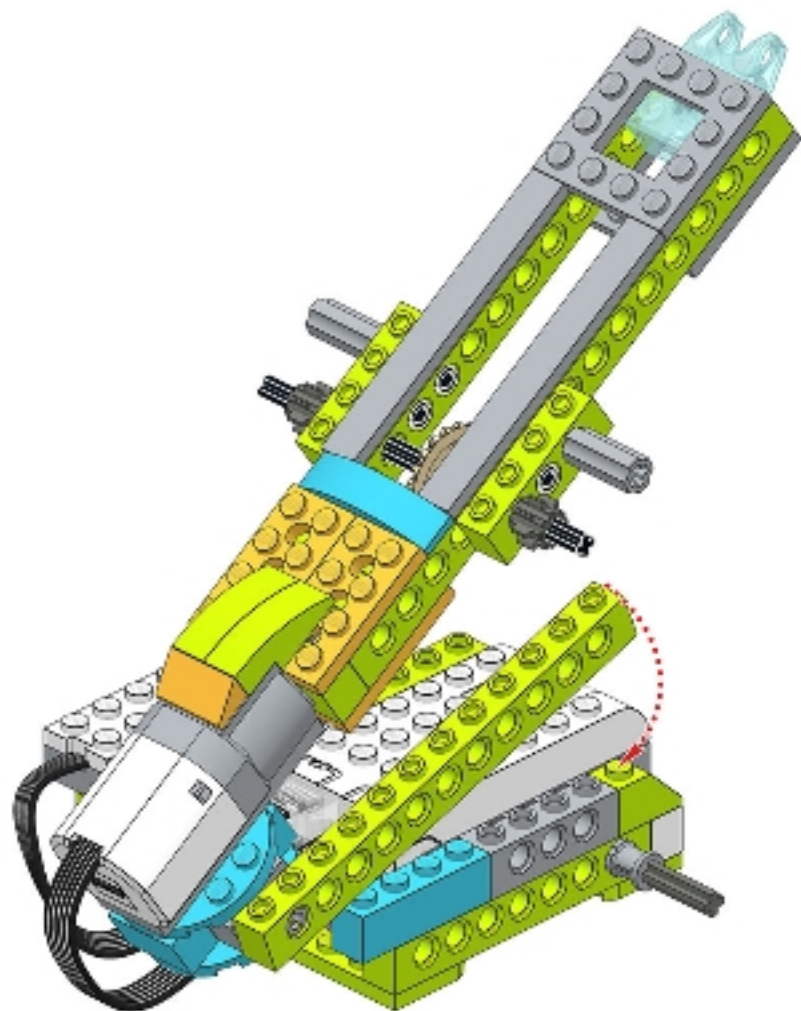


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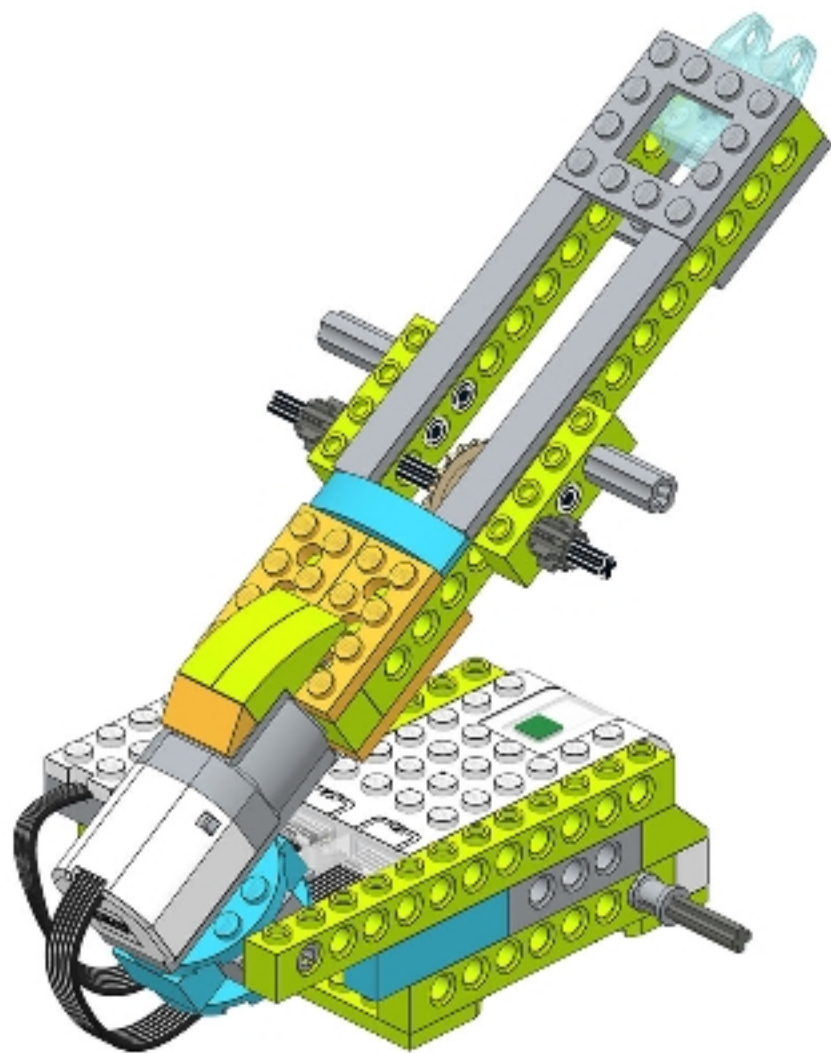


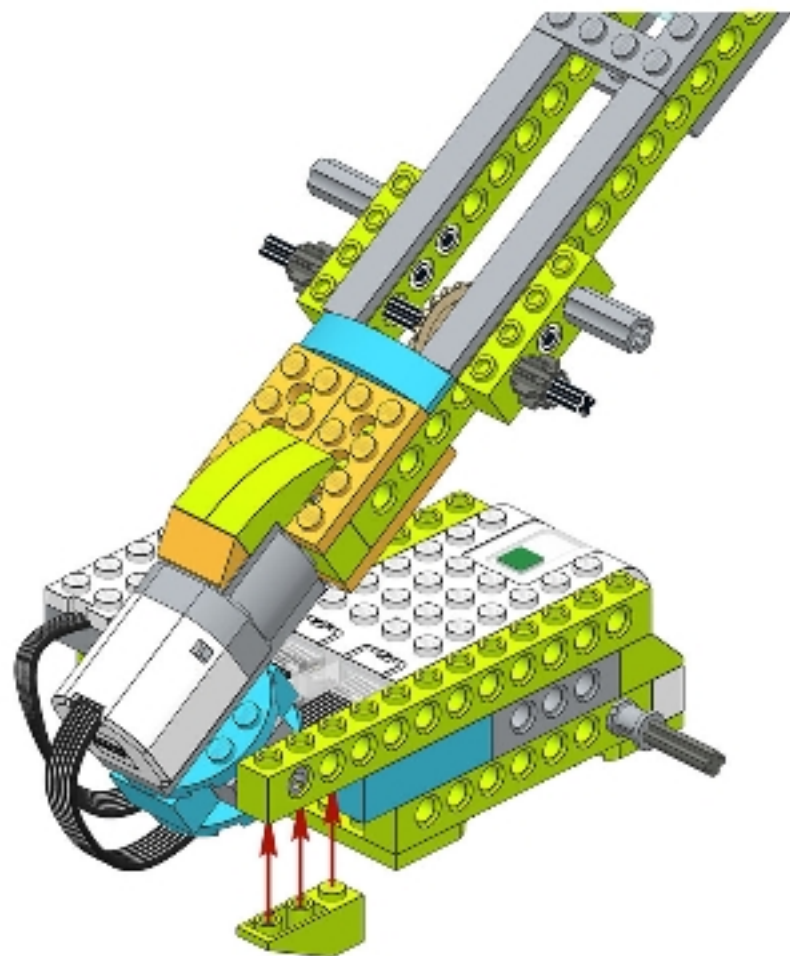


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49

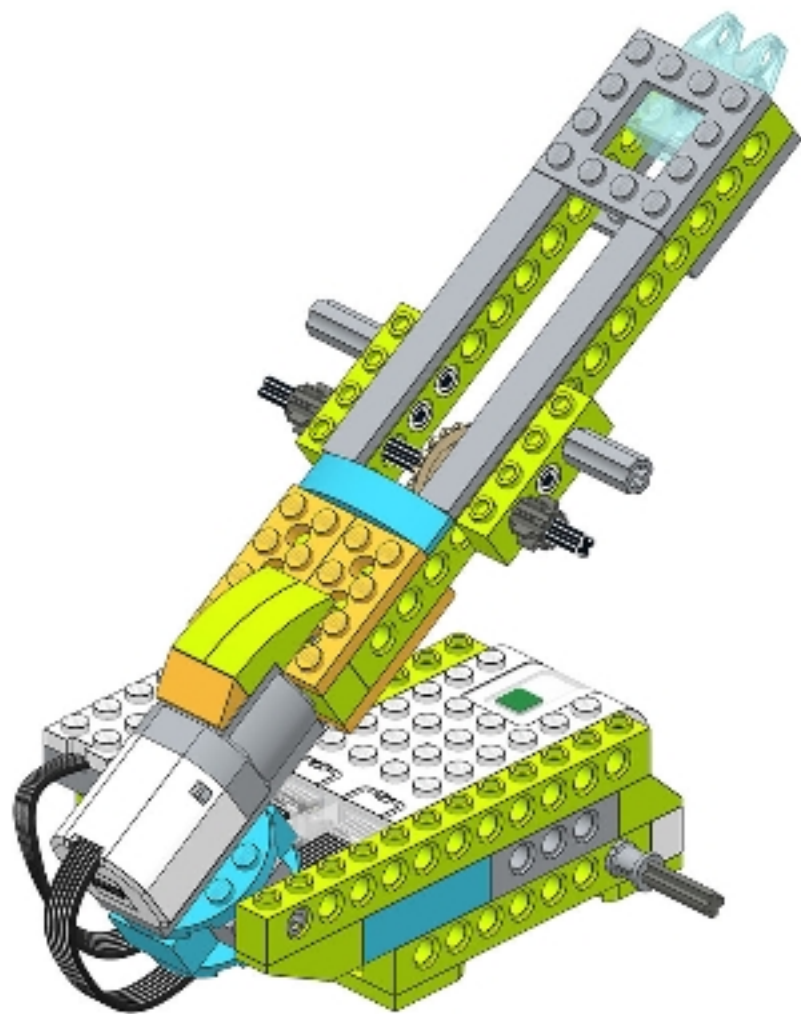




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50

51



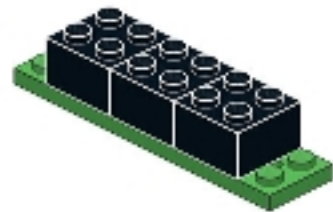


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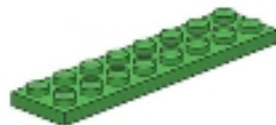
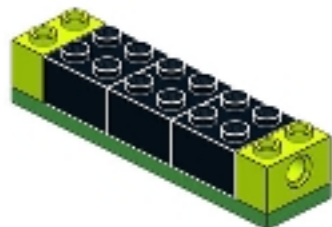
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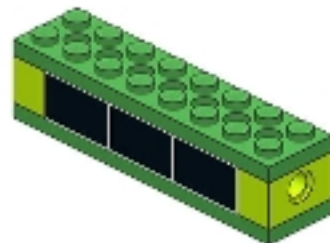
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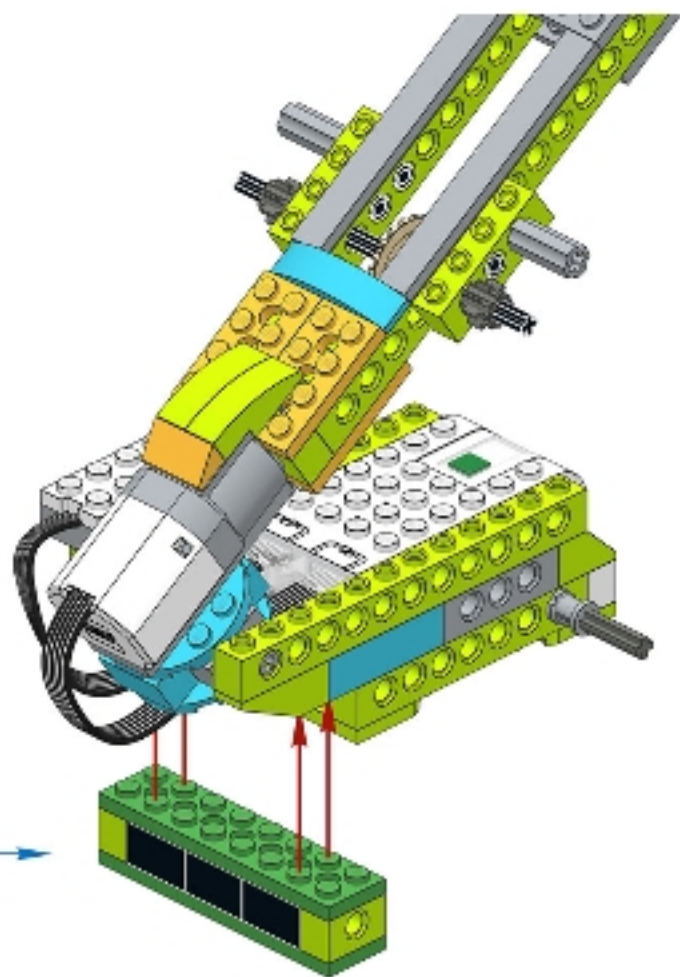


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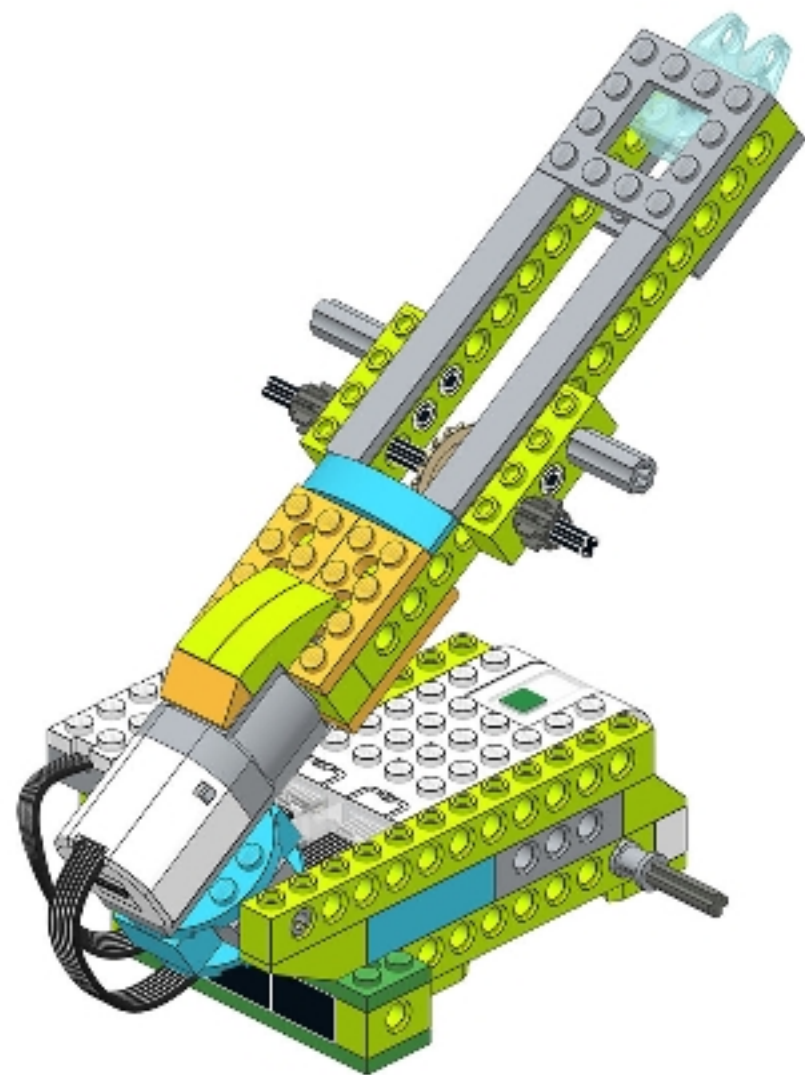
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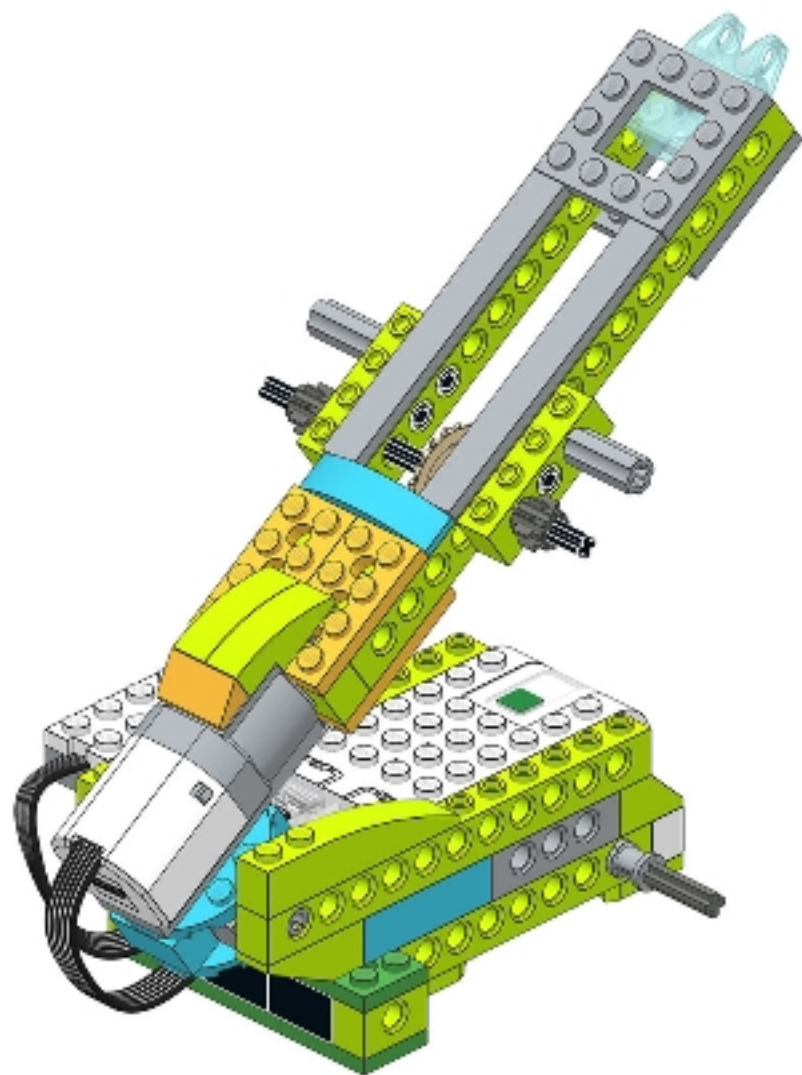
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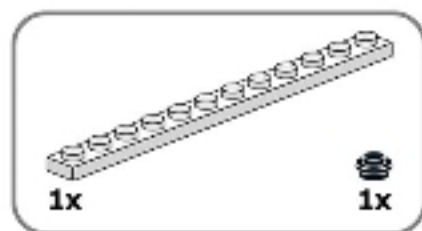
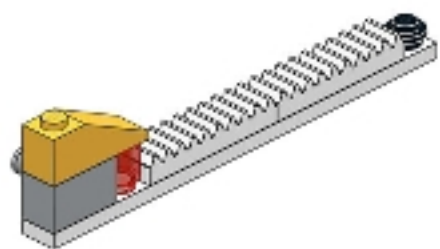


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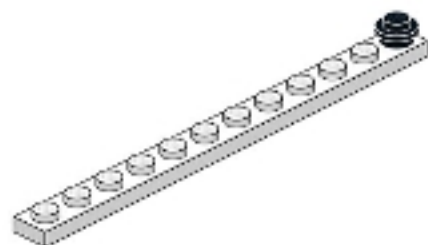


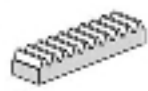
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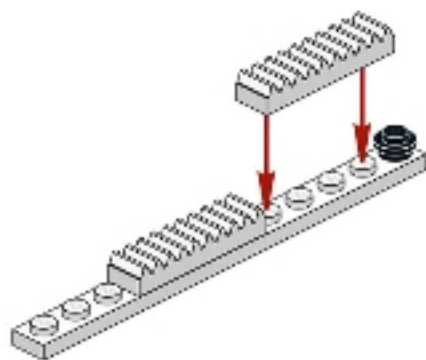
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2x

58



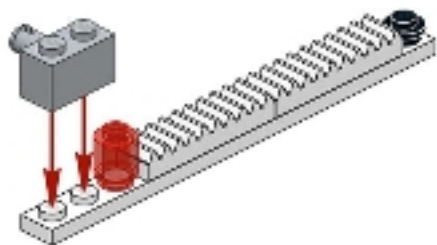


1x



1x

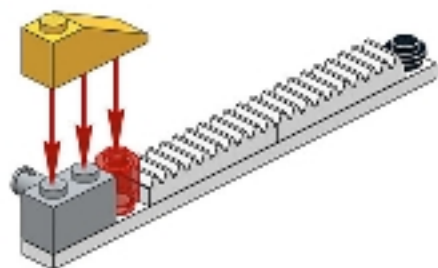
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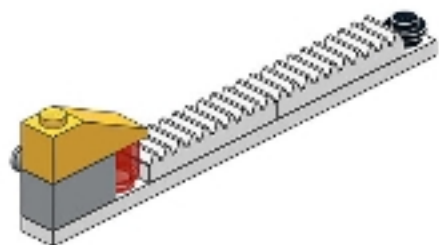


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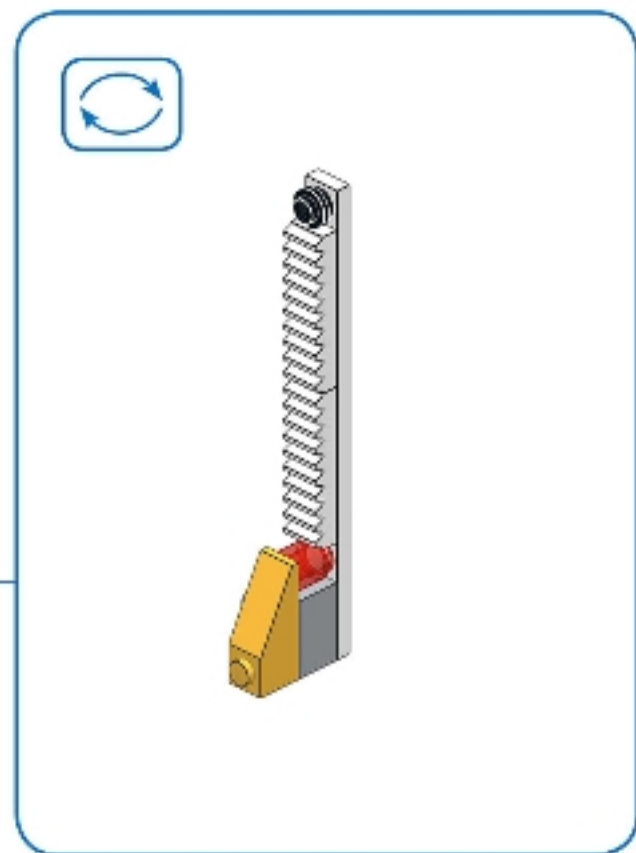
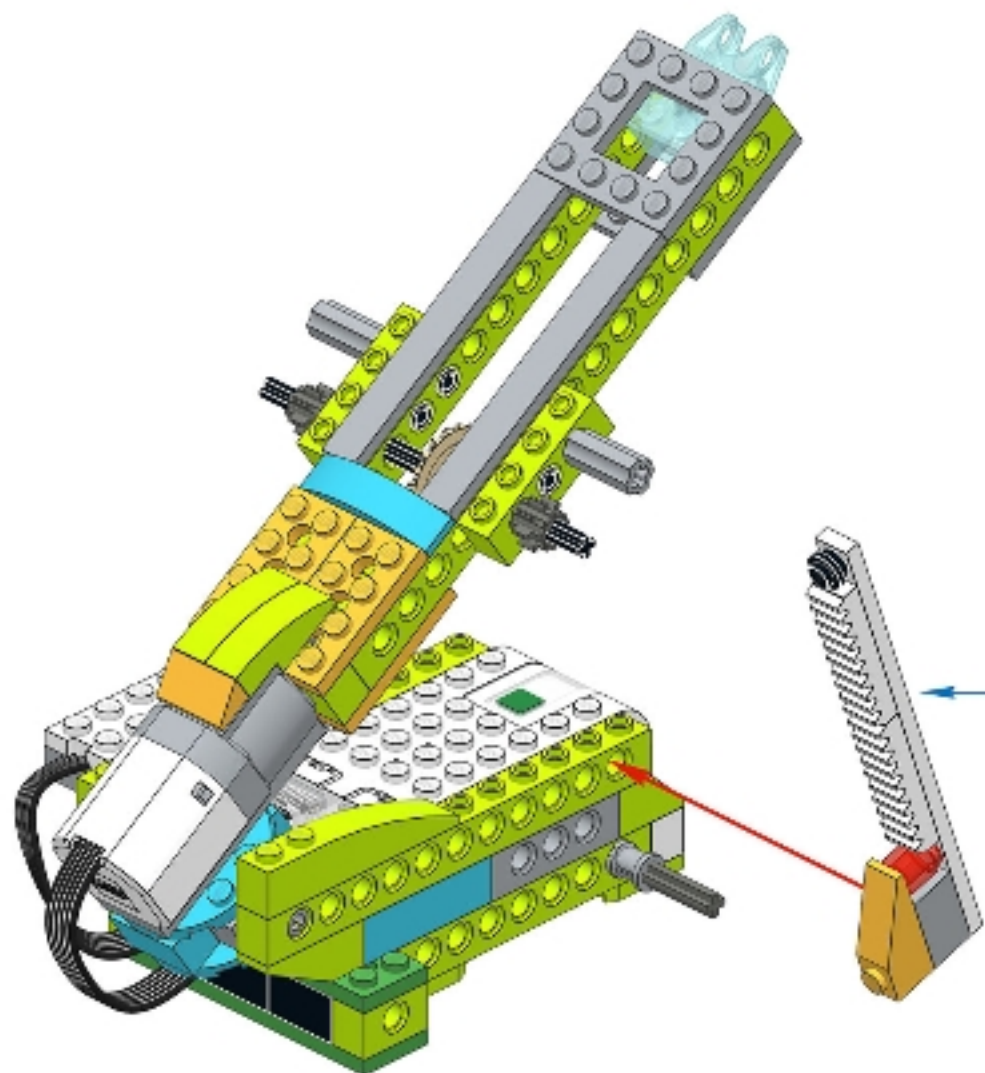
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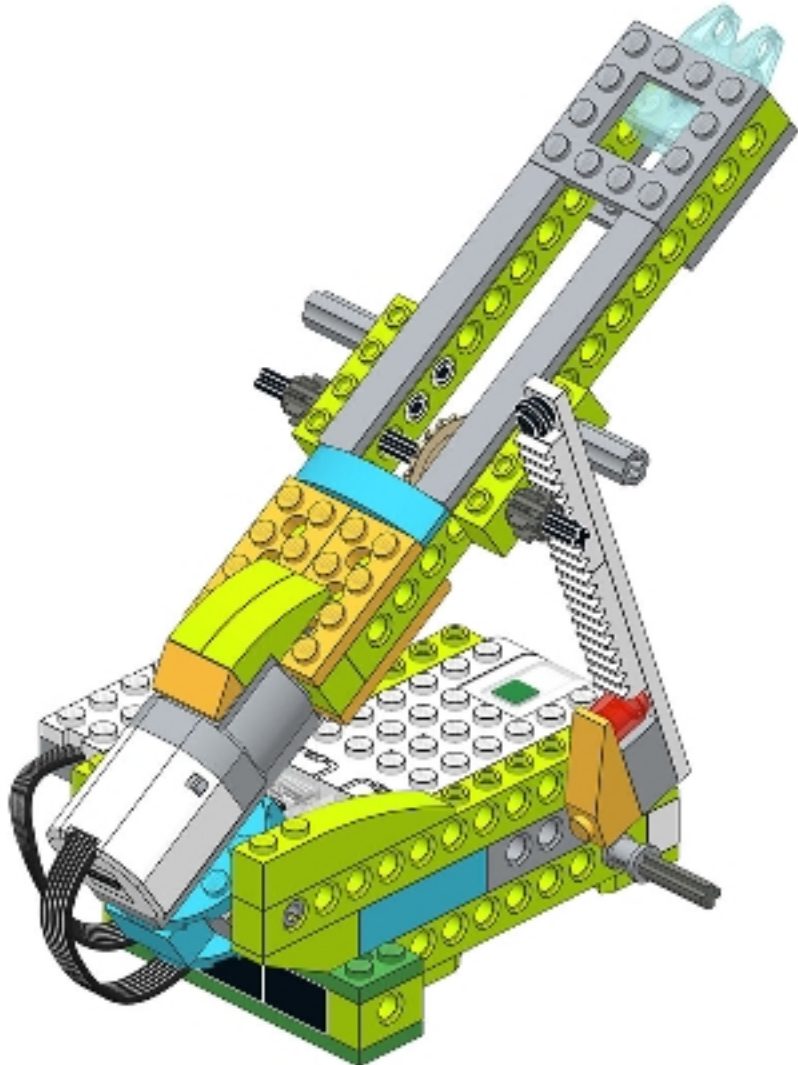


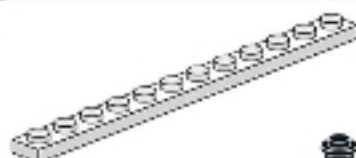
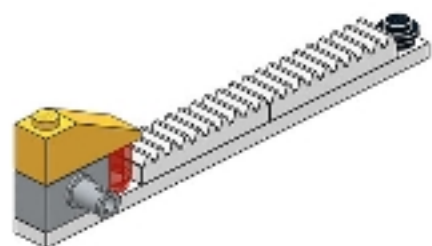
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62





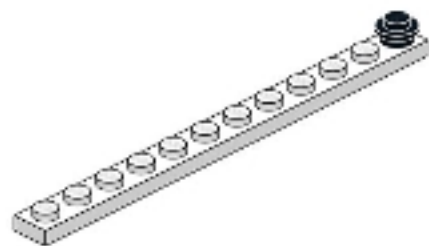


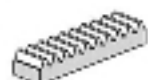
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1x

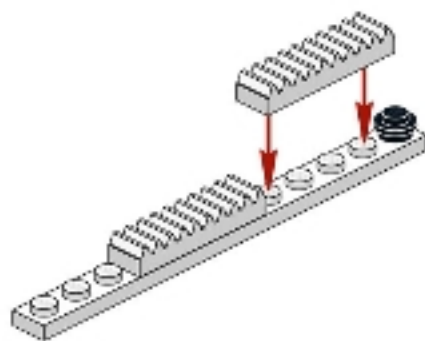
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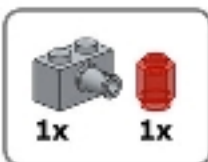




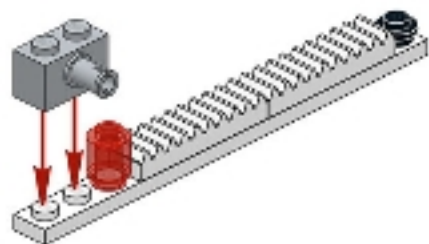
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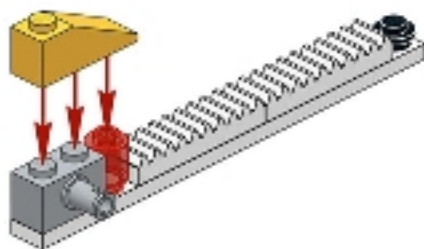
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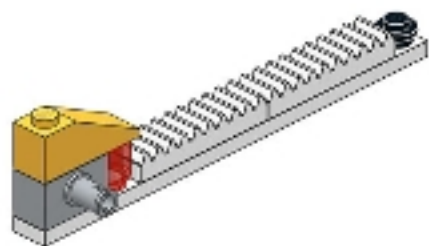


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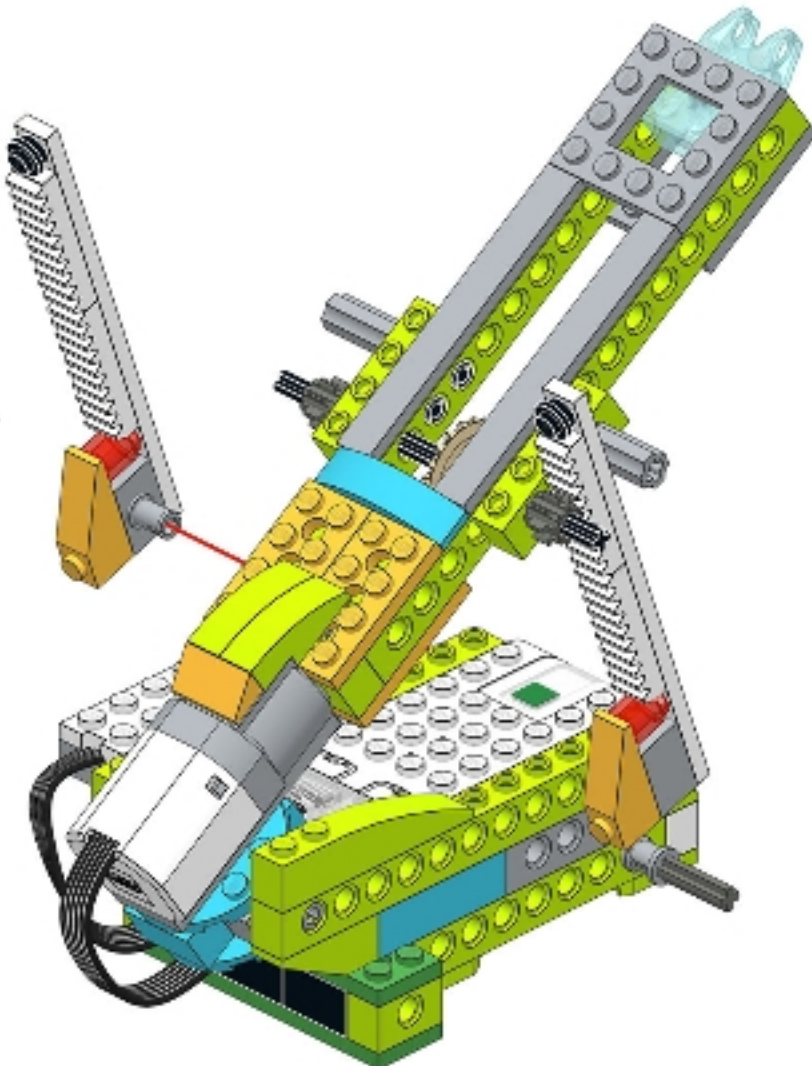
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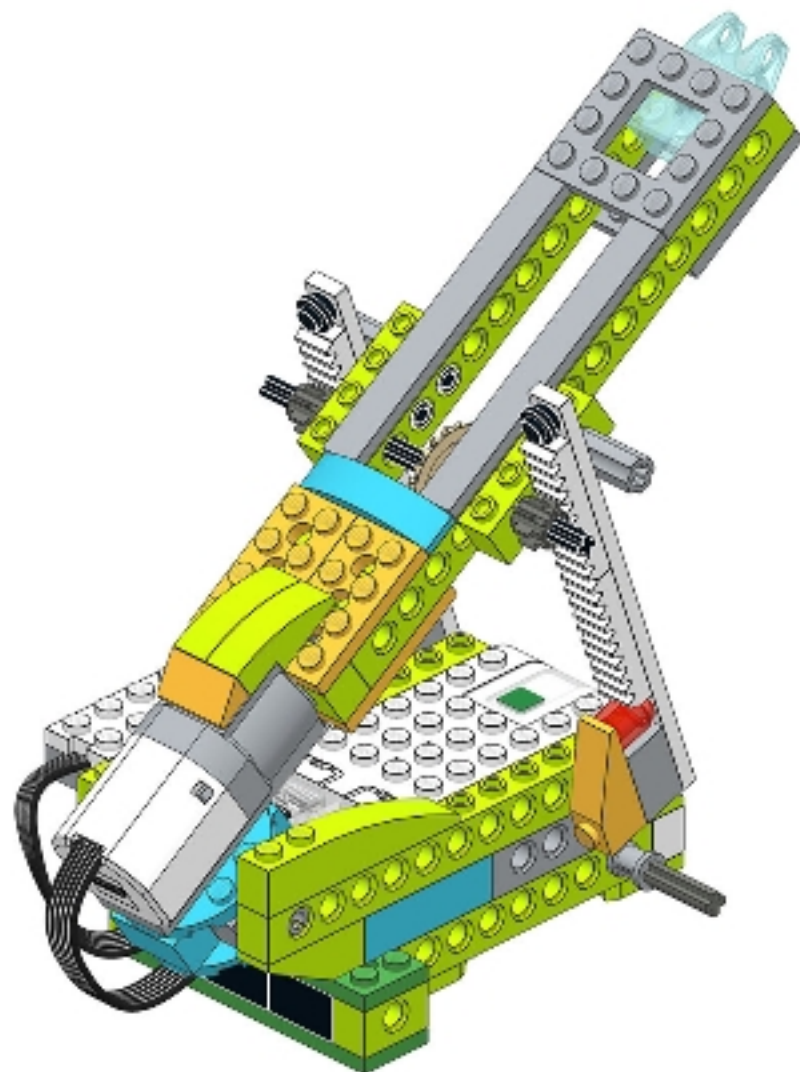
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69

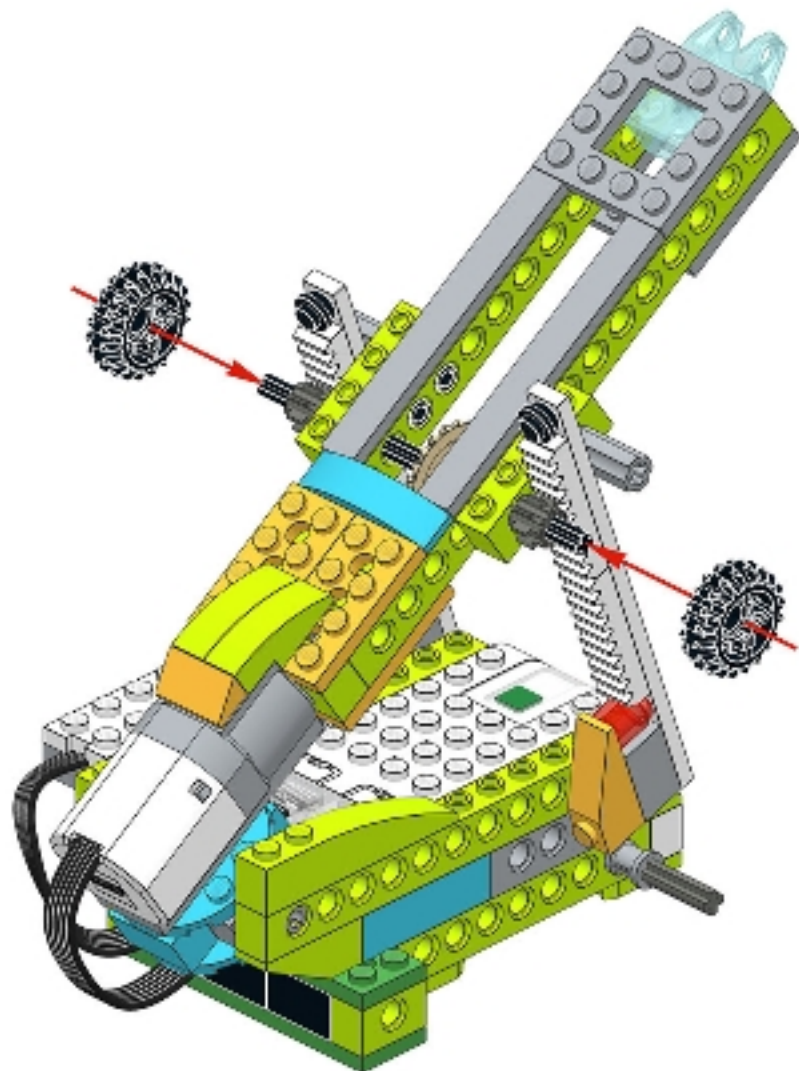


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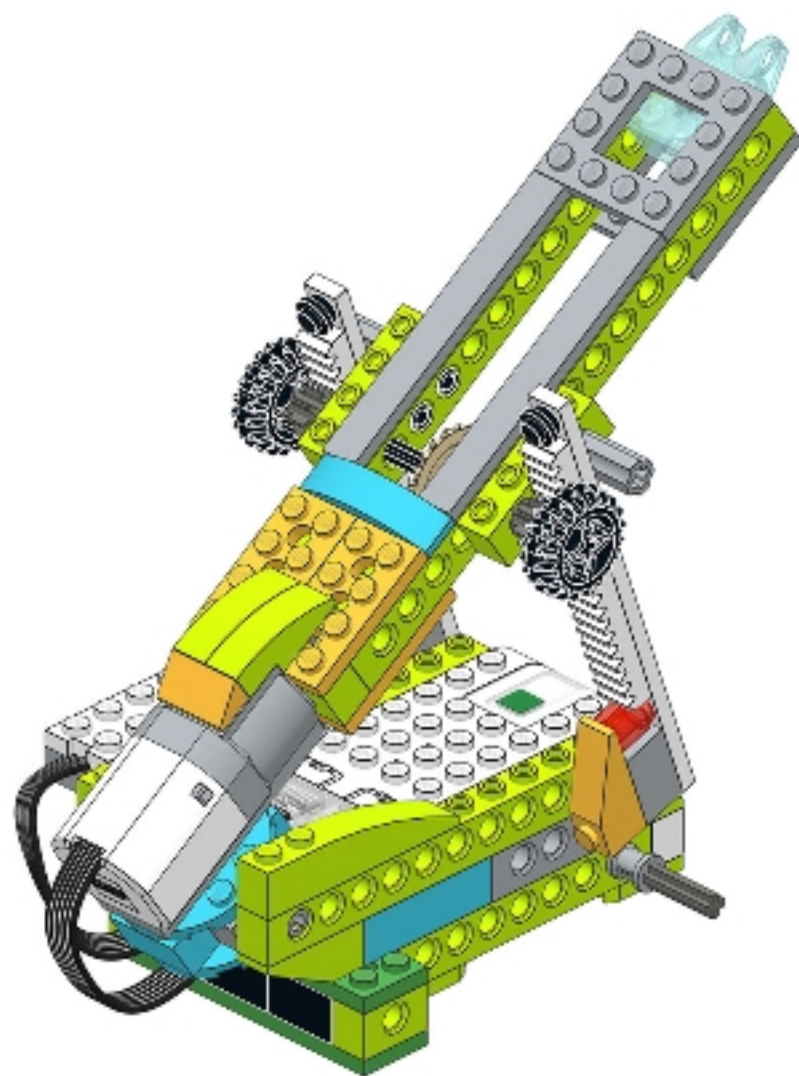


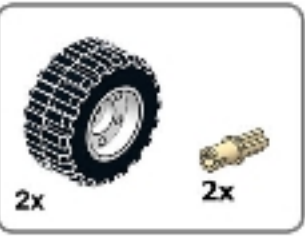


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72





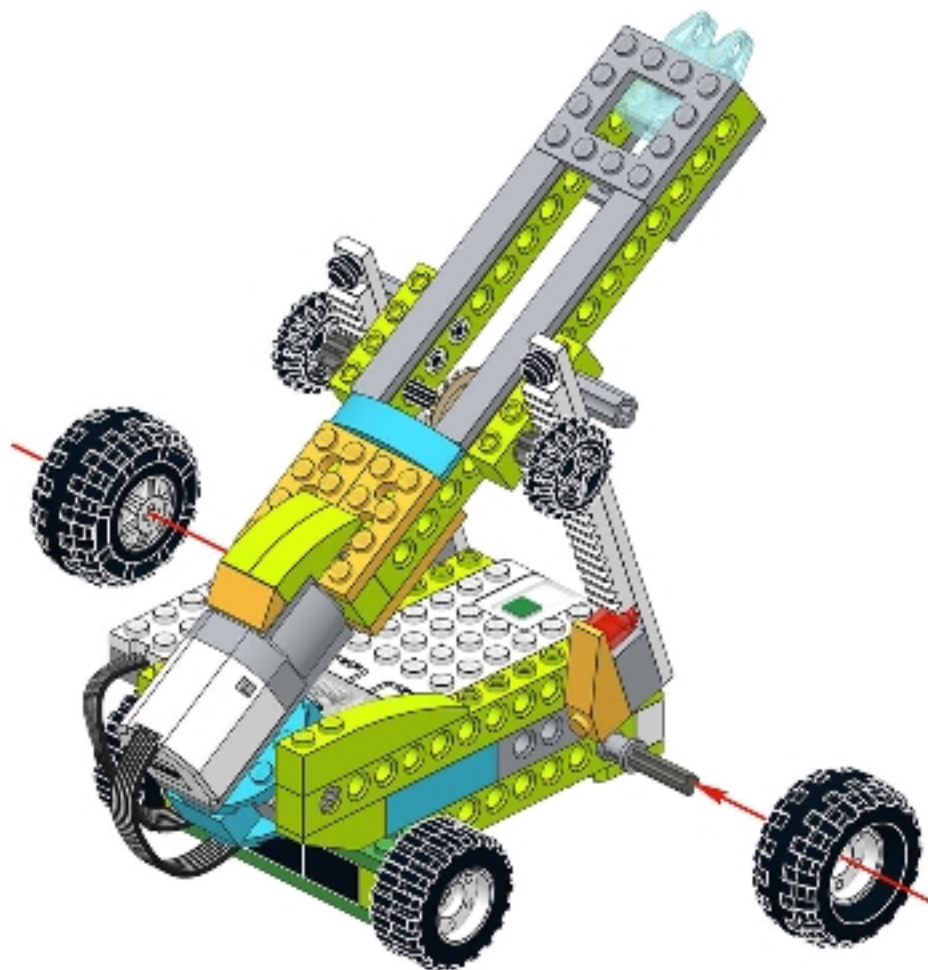
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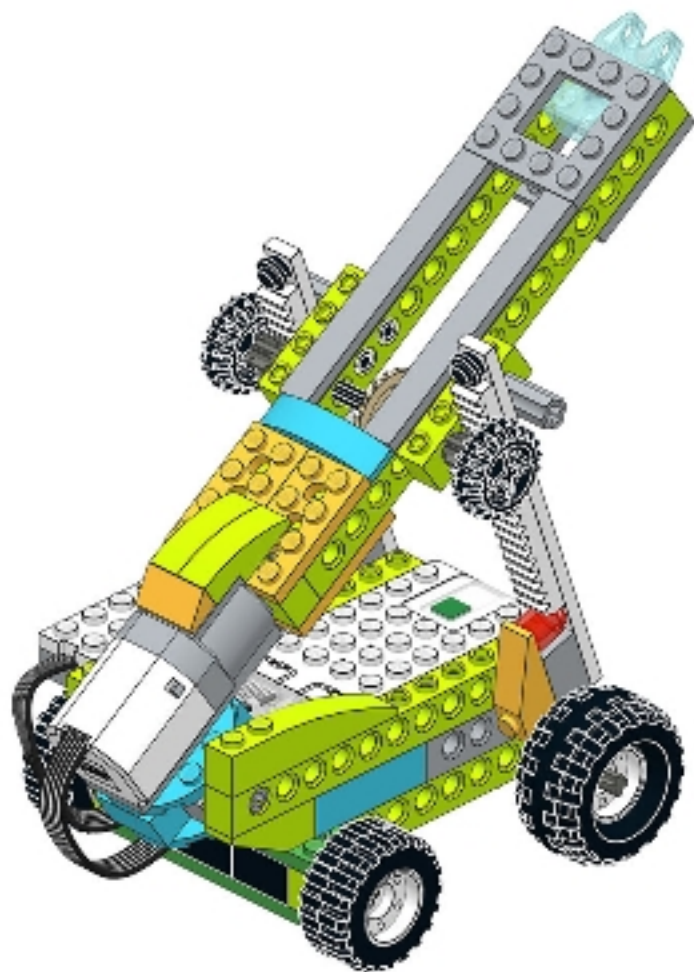


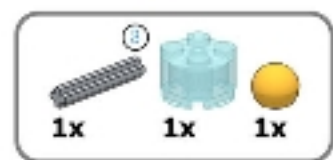
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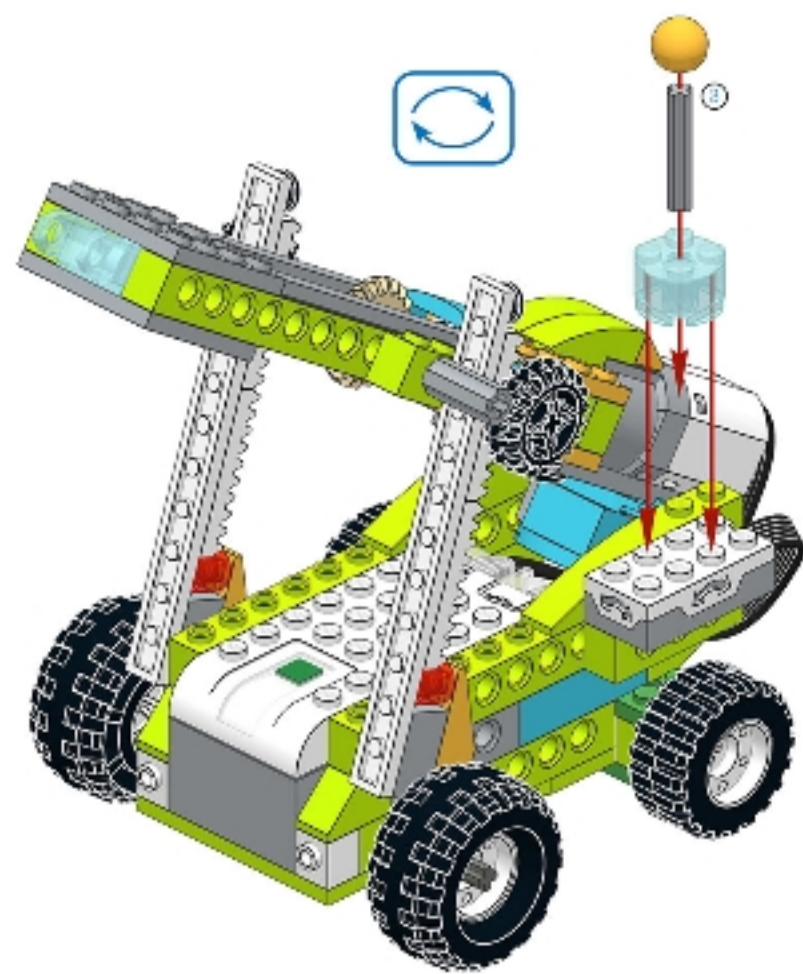


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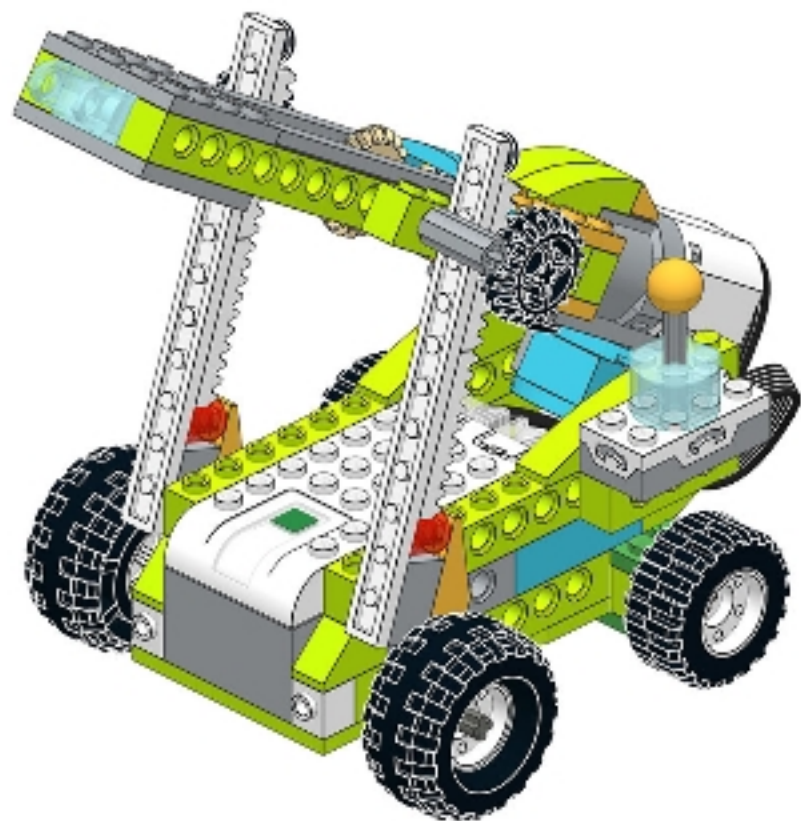


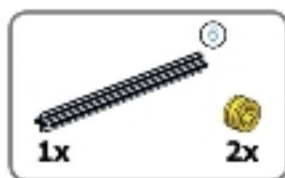


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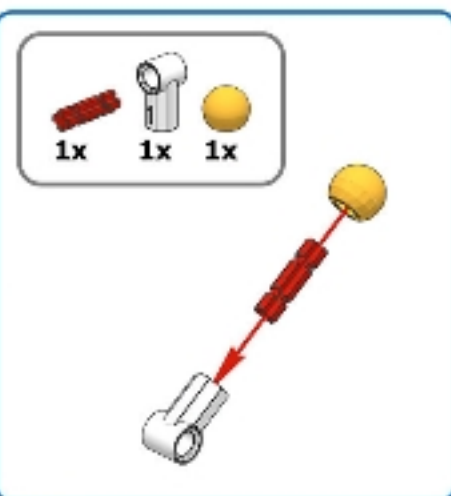
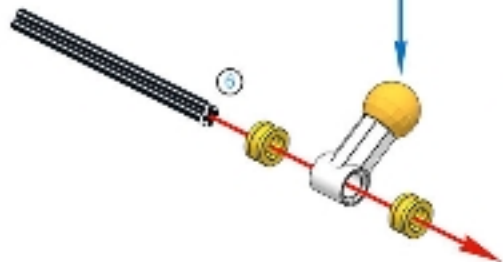


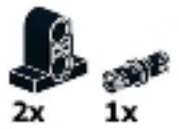
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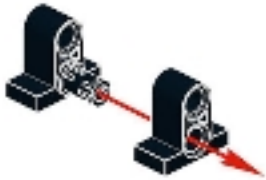


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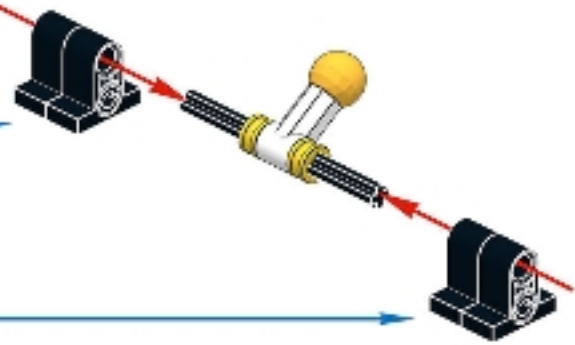




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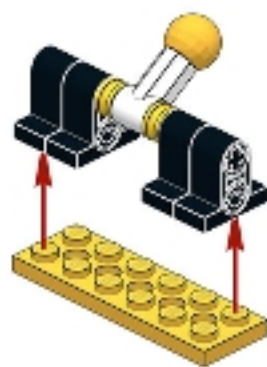
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1x

81





2x

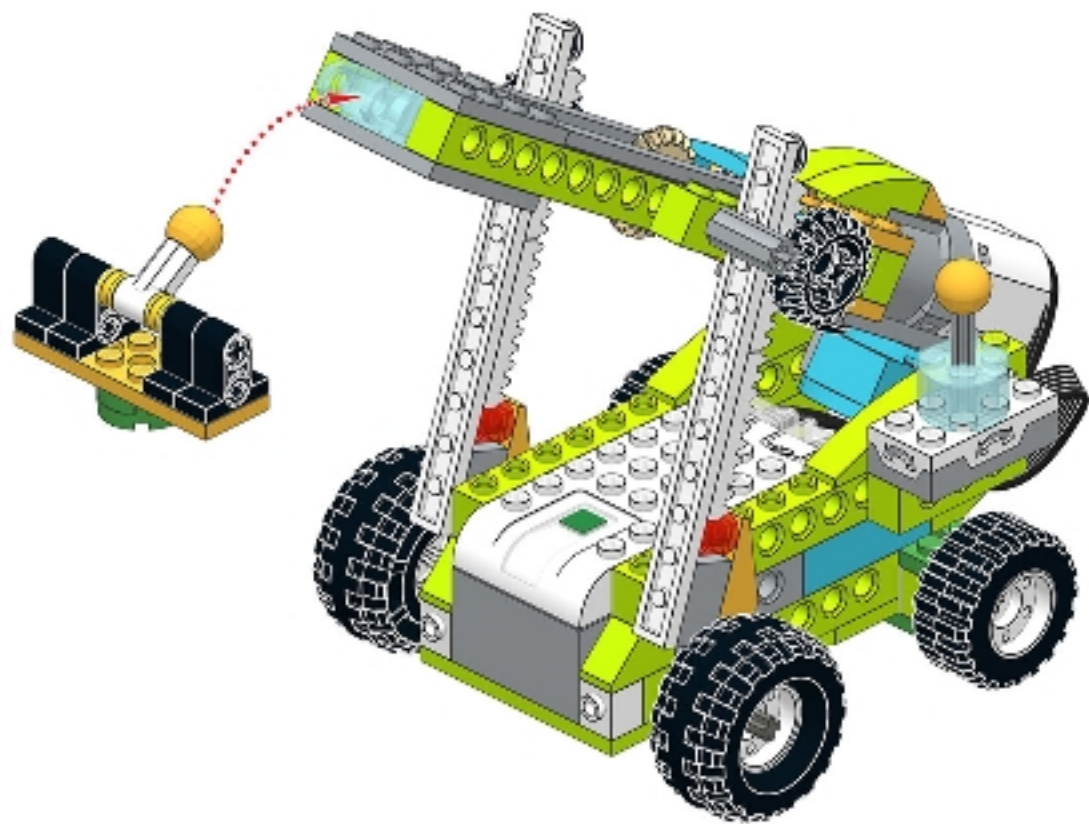
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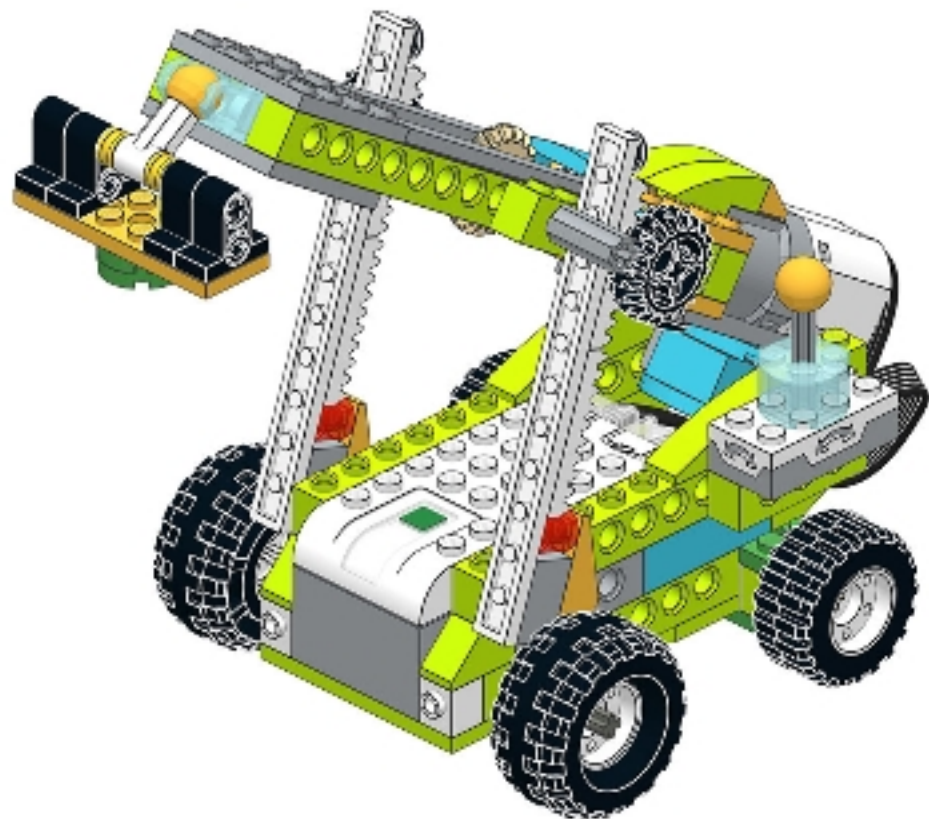
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84



85

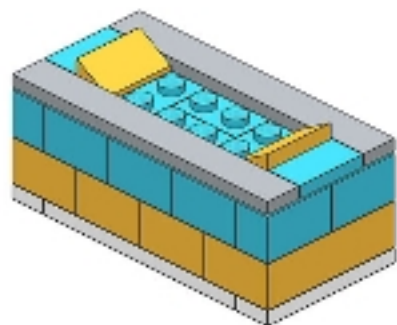




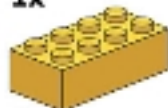
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86



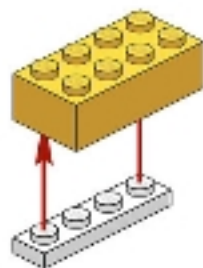


1x



1x

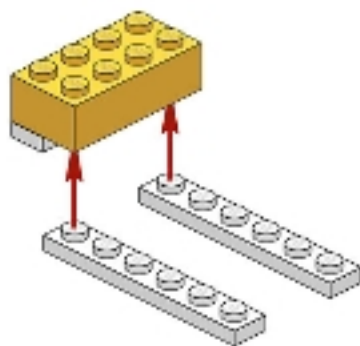
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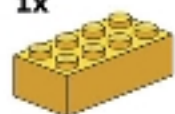
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88



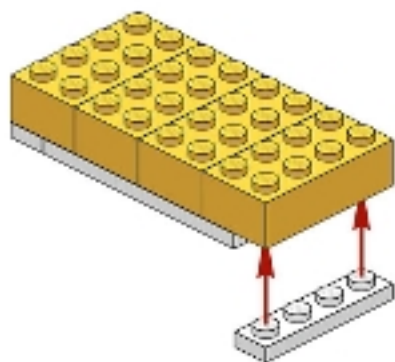


1x



3x

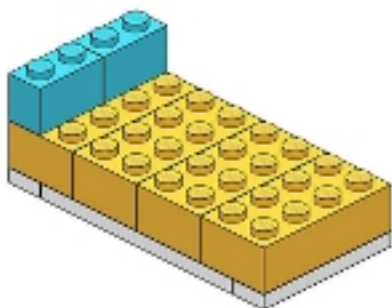
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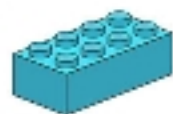




2x

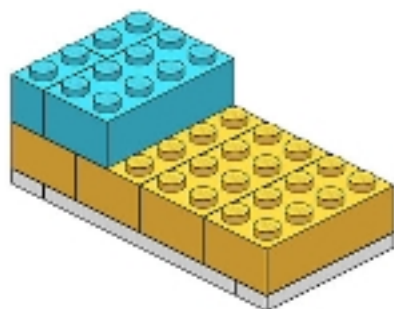
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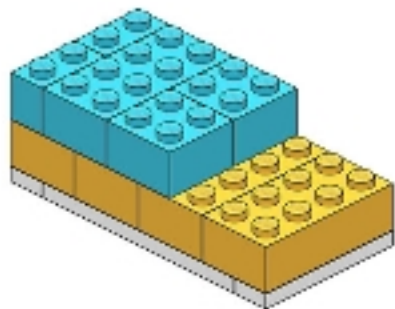
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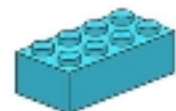




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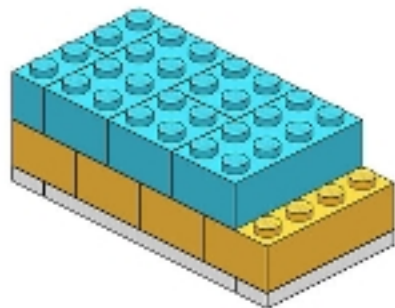
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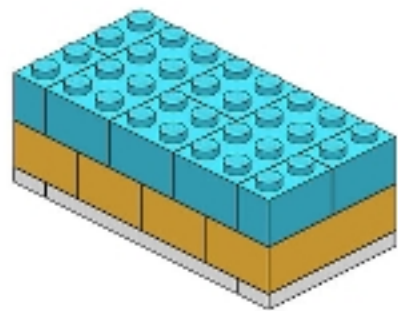
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2x

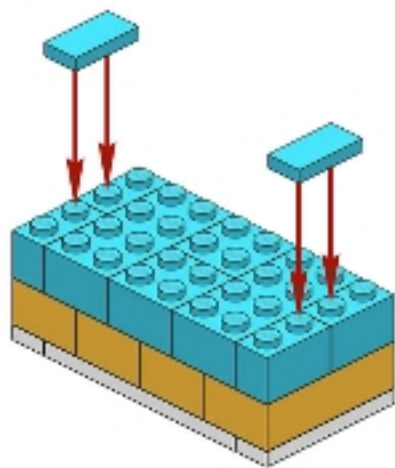
94





2x

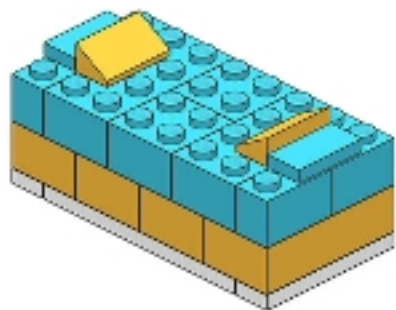
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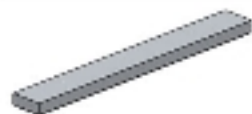




2x

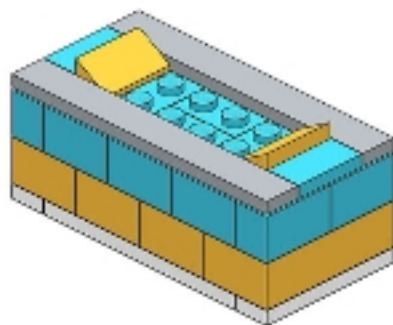
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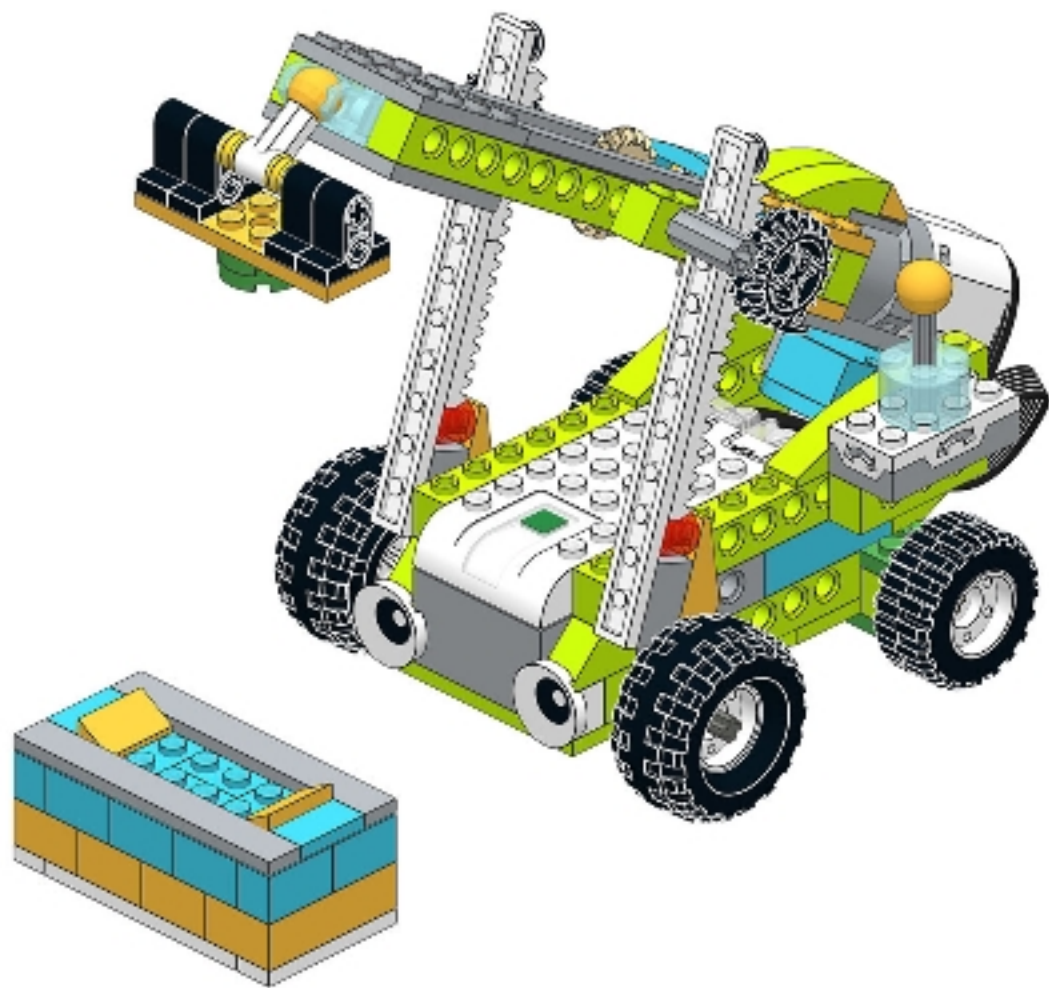


2x

97



98





Task 1. Program

Write the program for controlling the manipulator using the example below and test the robot.

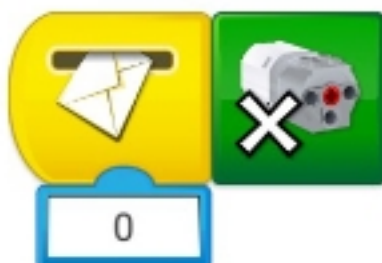


In order to control the manipulator more precisely, it is convenient to use a low speed. In our case - "1".



Task 2. Program

Modify your program and test your robot!



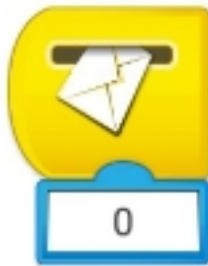
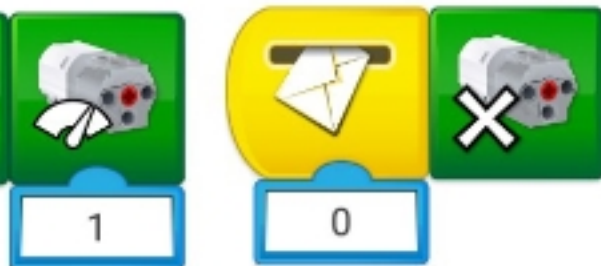
Run the program above will be a program that continuously transmit sensor readings:





Task 2. Questions

Which program block sends sensor data? Click on it.





Task 3. Questions

Which program block sets the direction of rotation of the motor axis?

