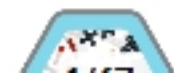
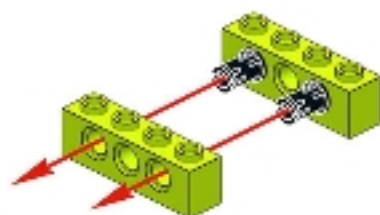


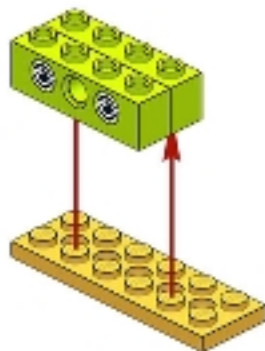
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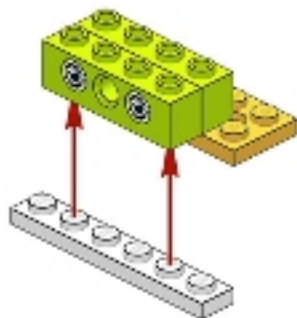
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1x

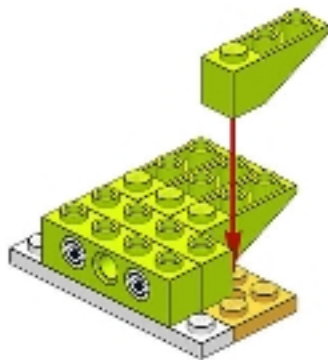
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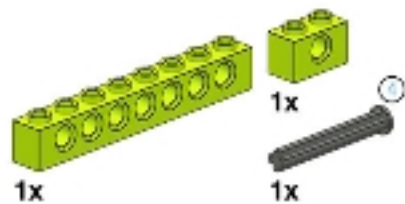




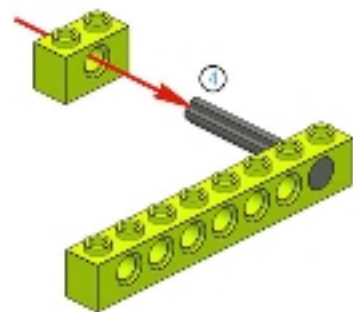
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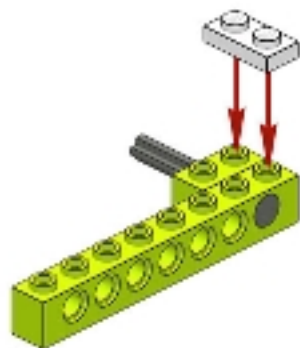


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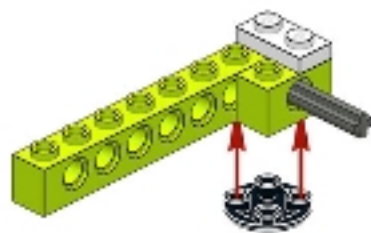
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2



1x

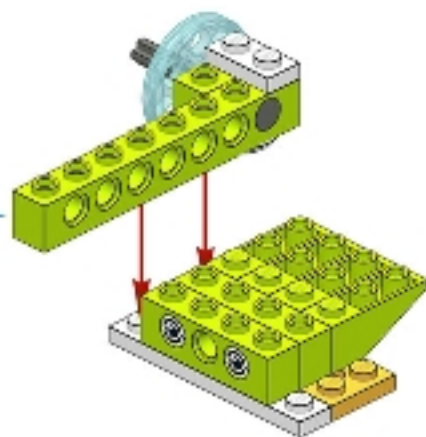
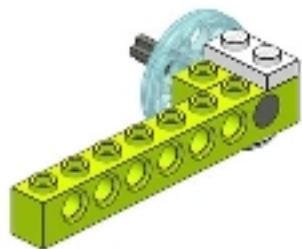
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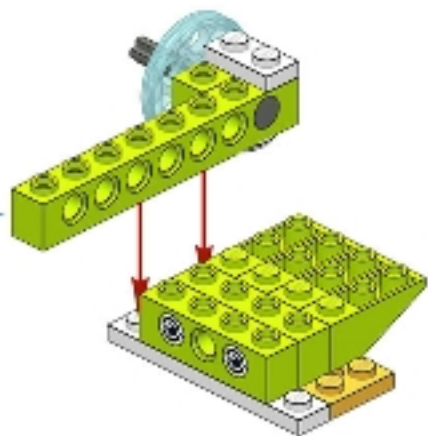
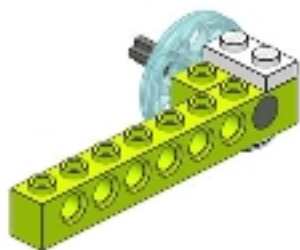
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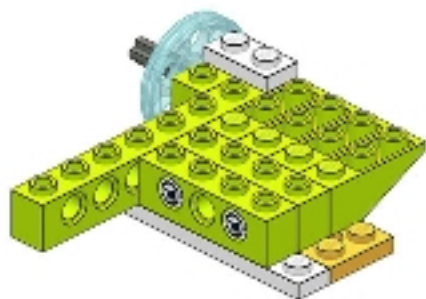


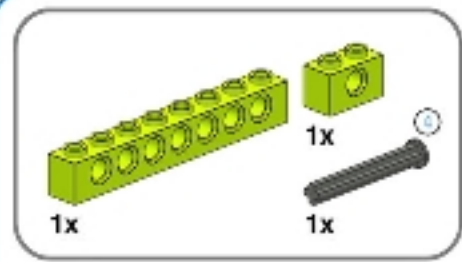
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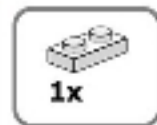
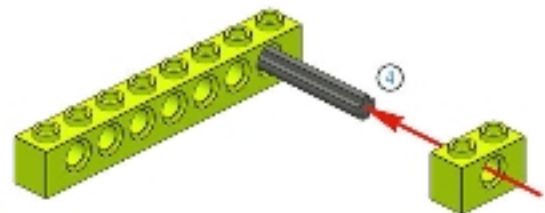


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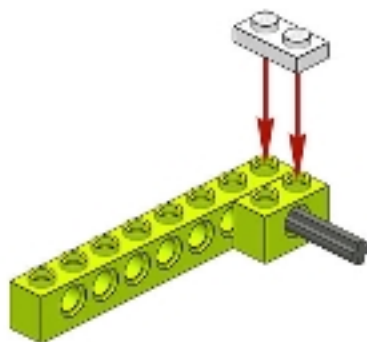




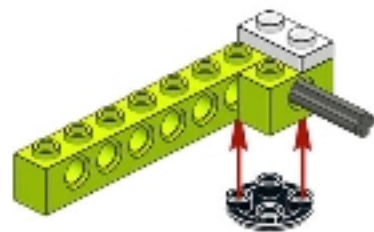
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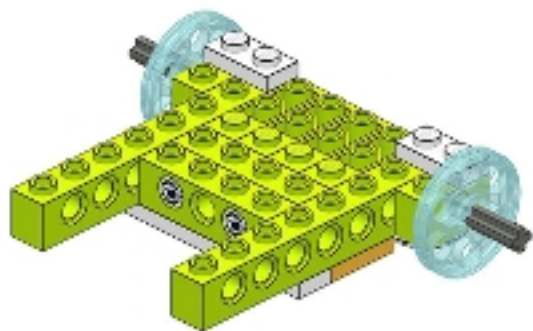
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3



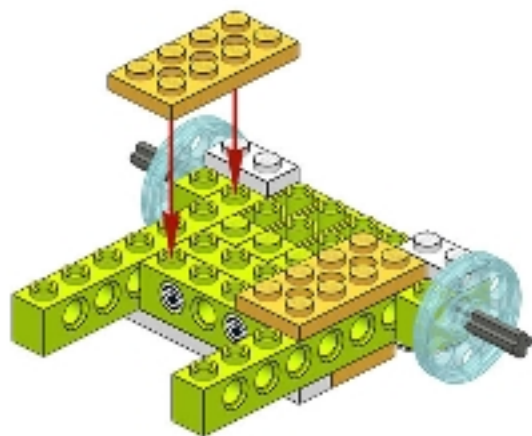
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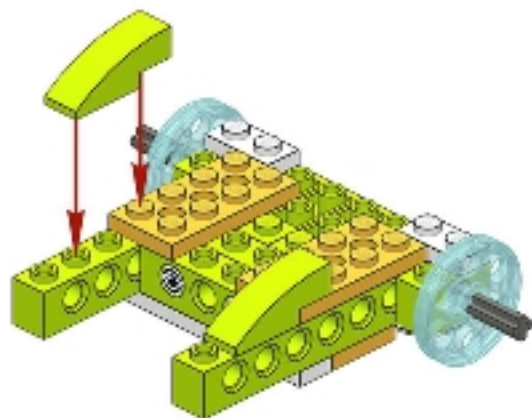
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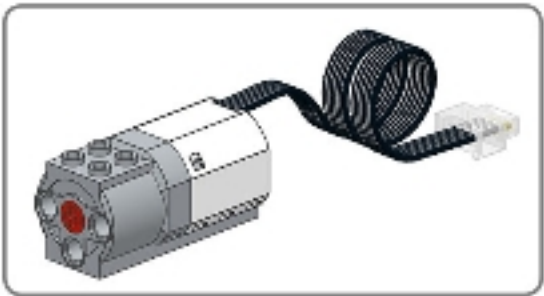




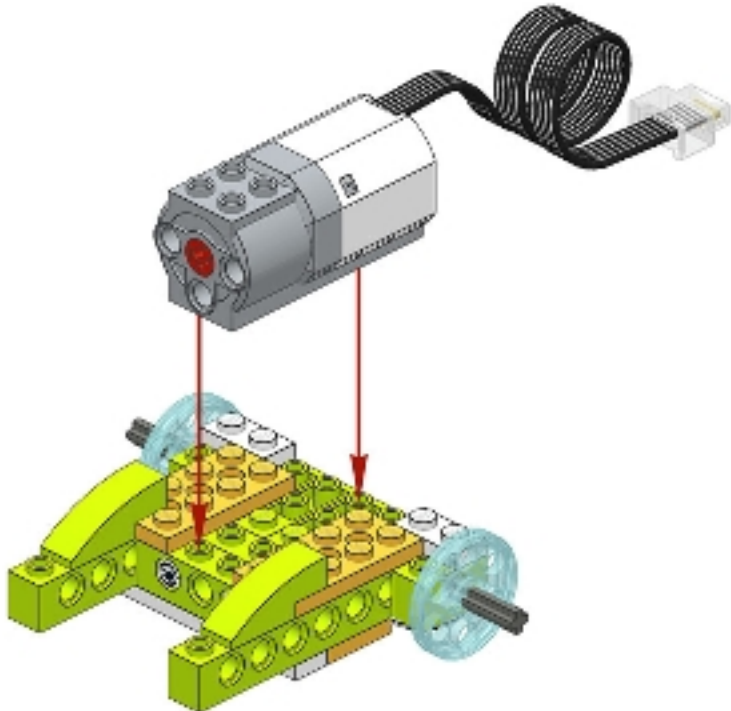
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12





13



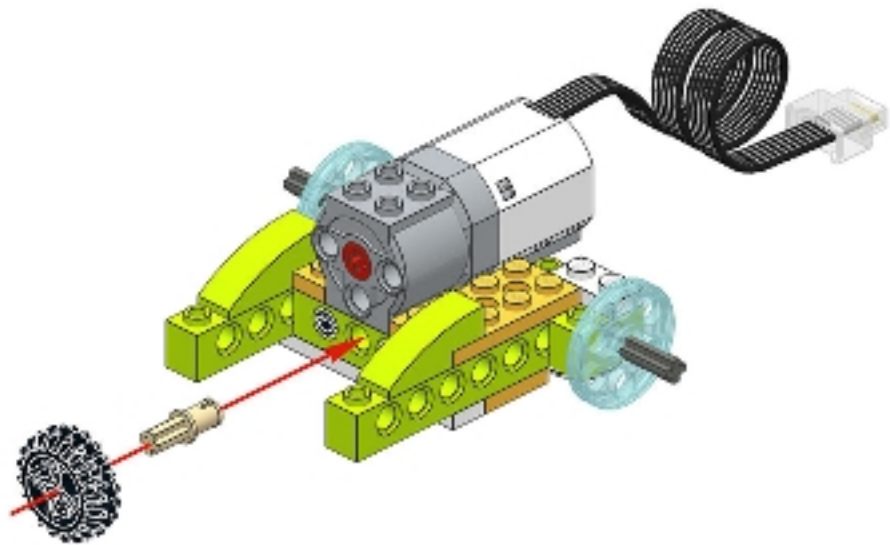


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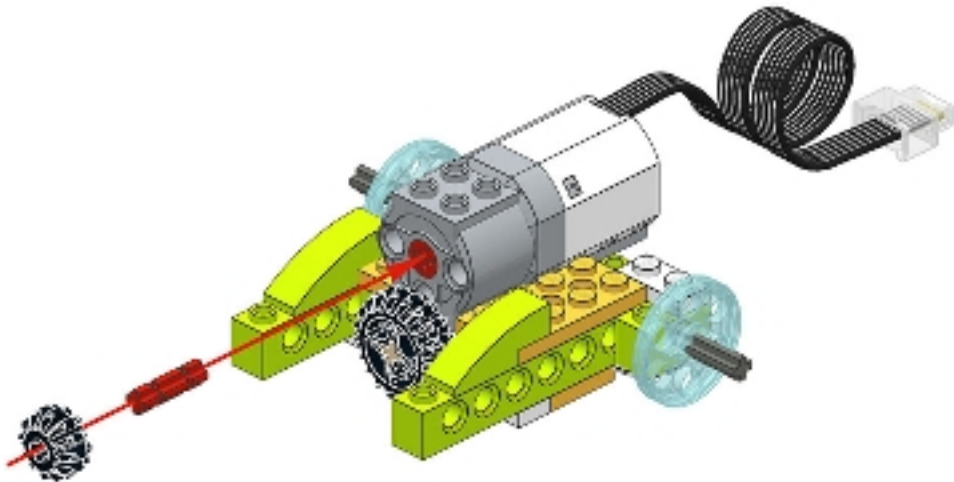
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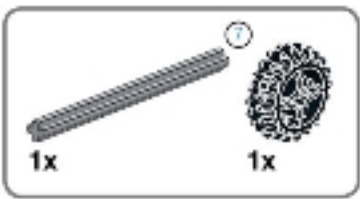
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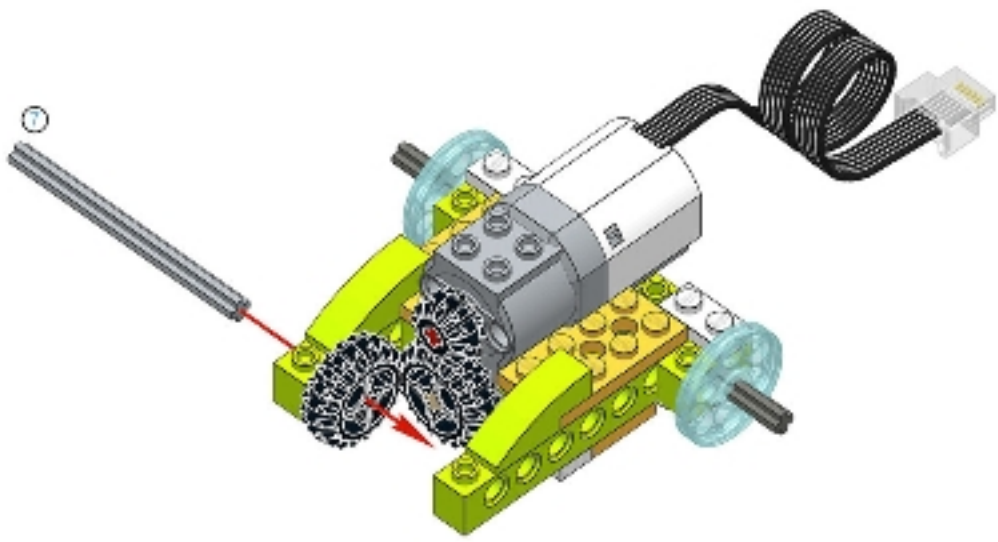


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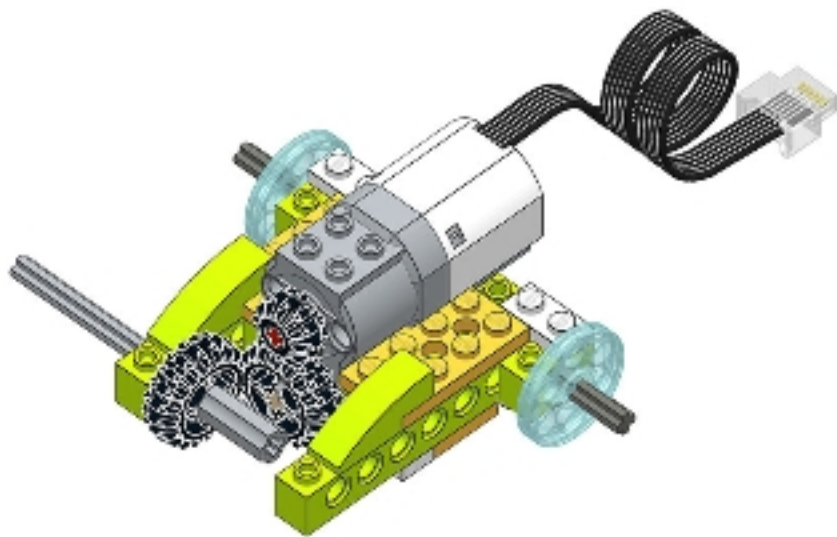
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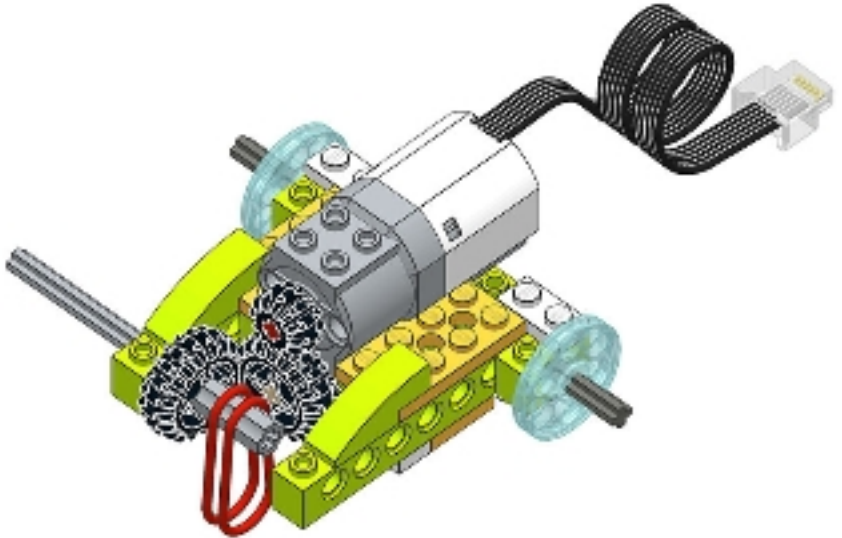
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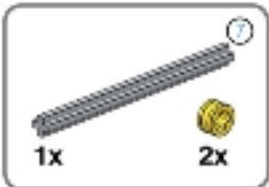
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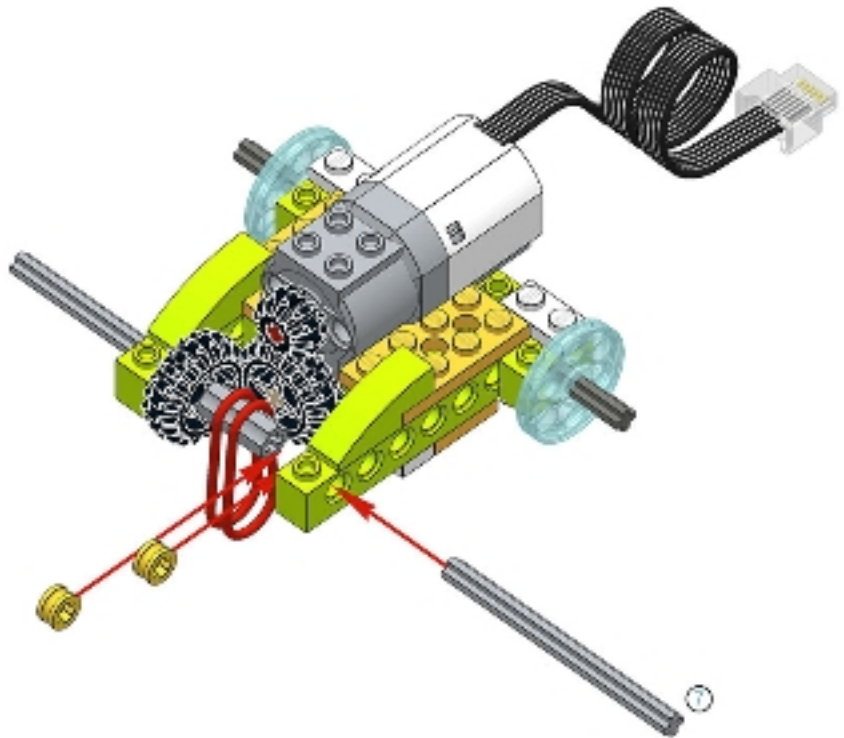


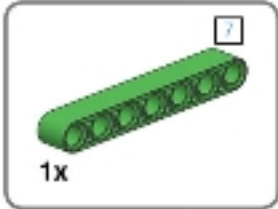
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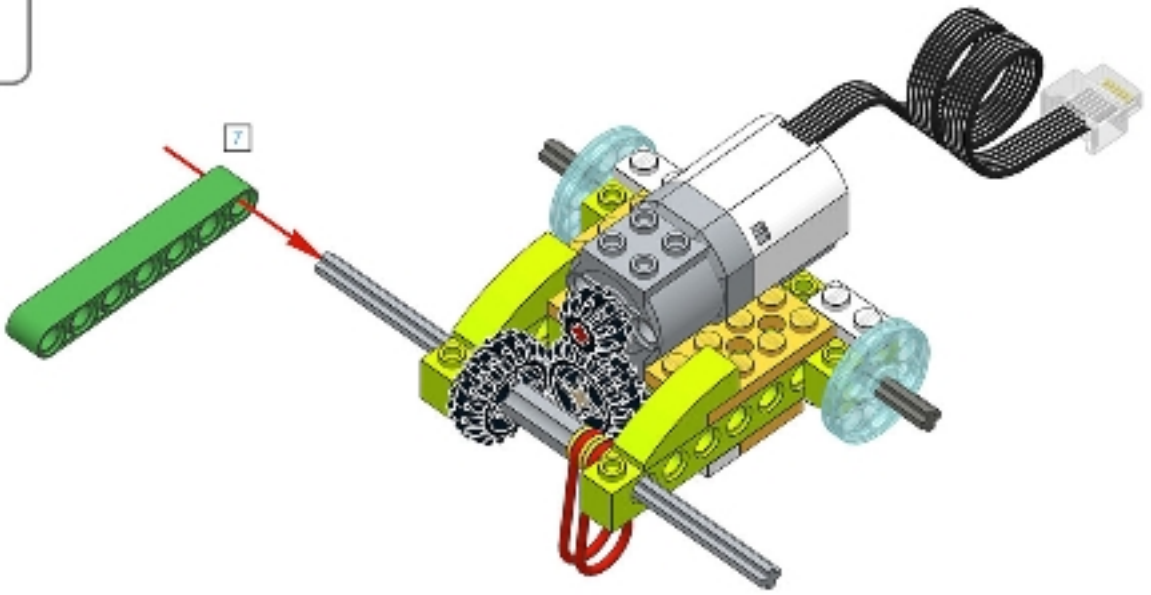
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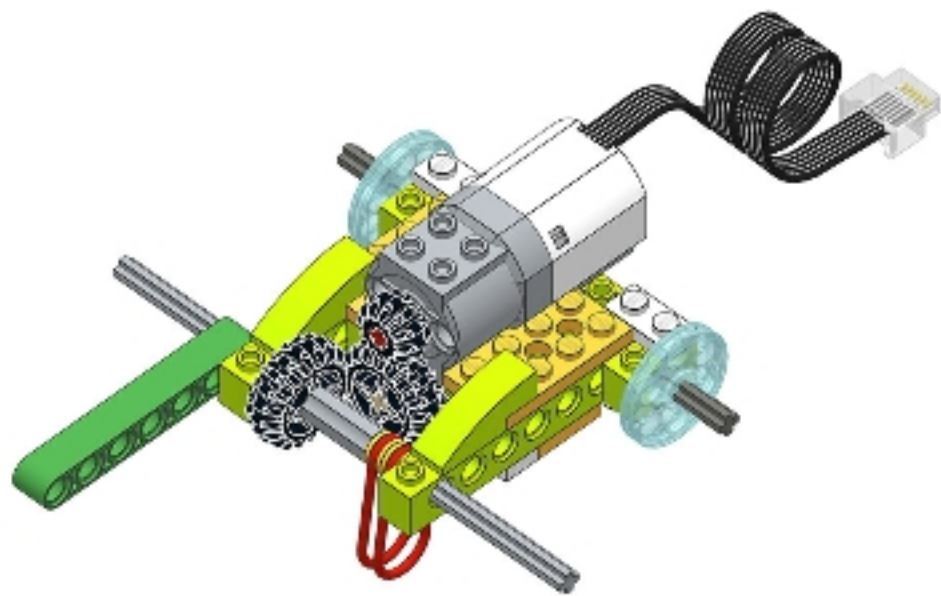


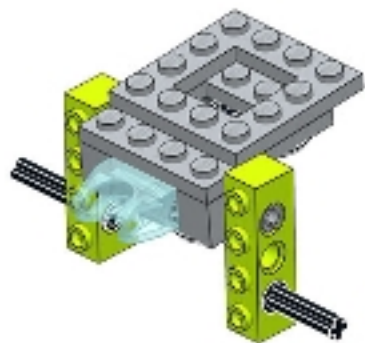
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21



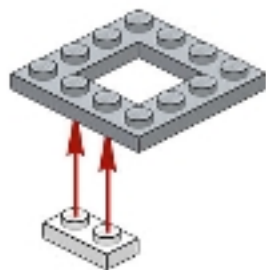


1x



1x

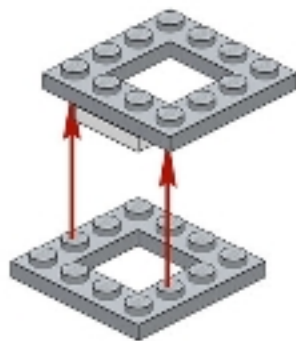
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23



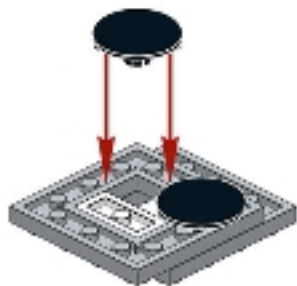
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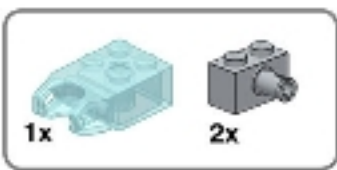




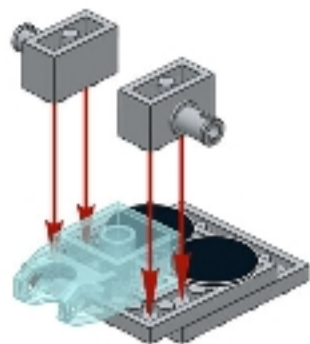
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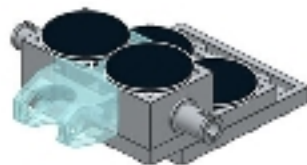
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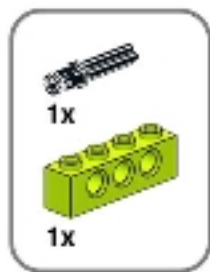




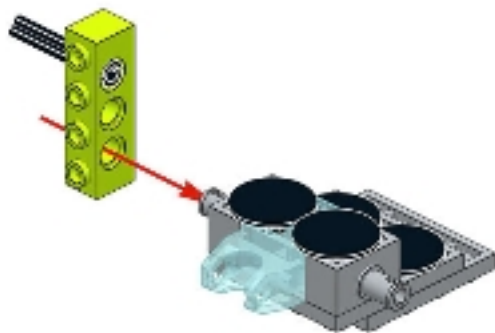
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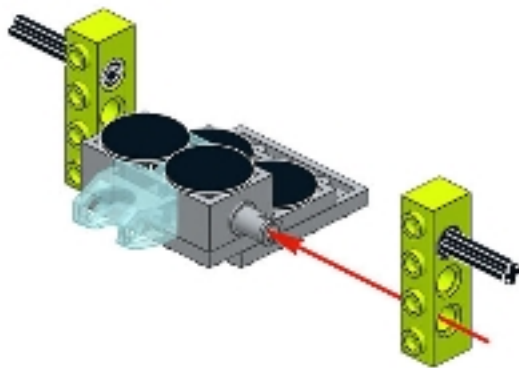




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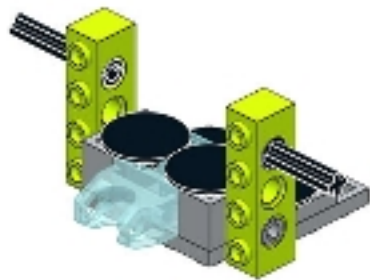


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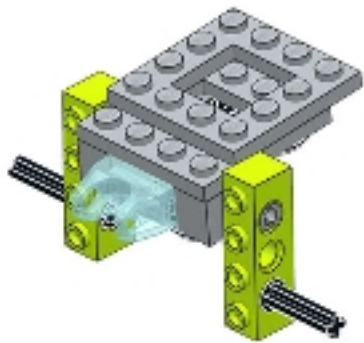


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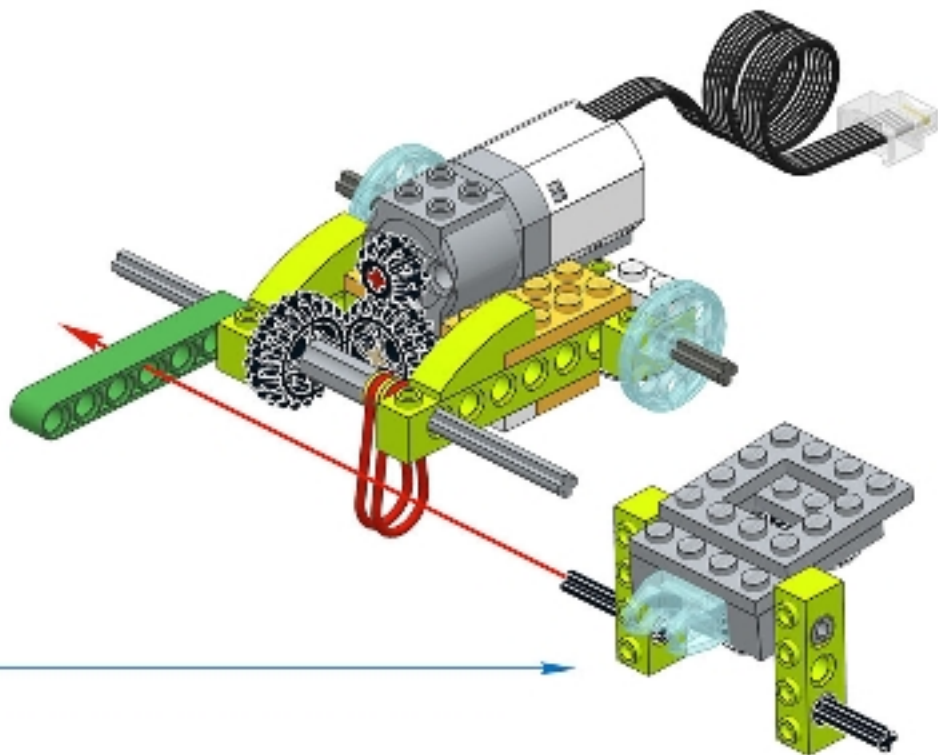
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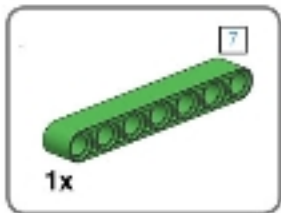


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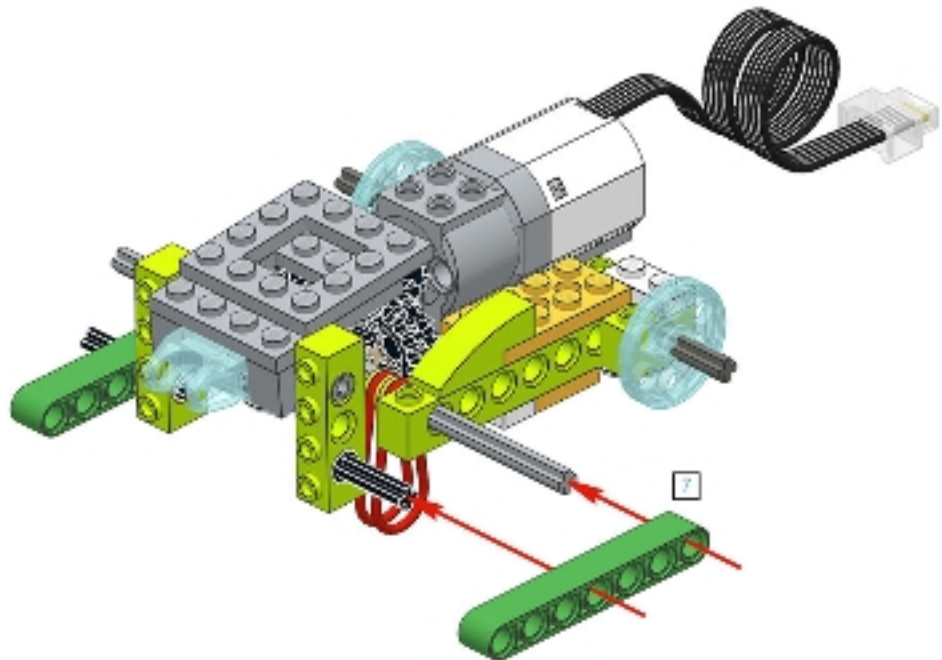


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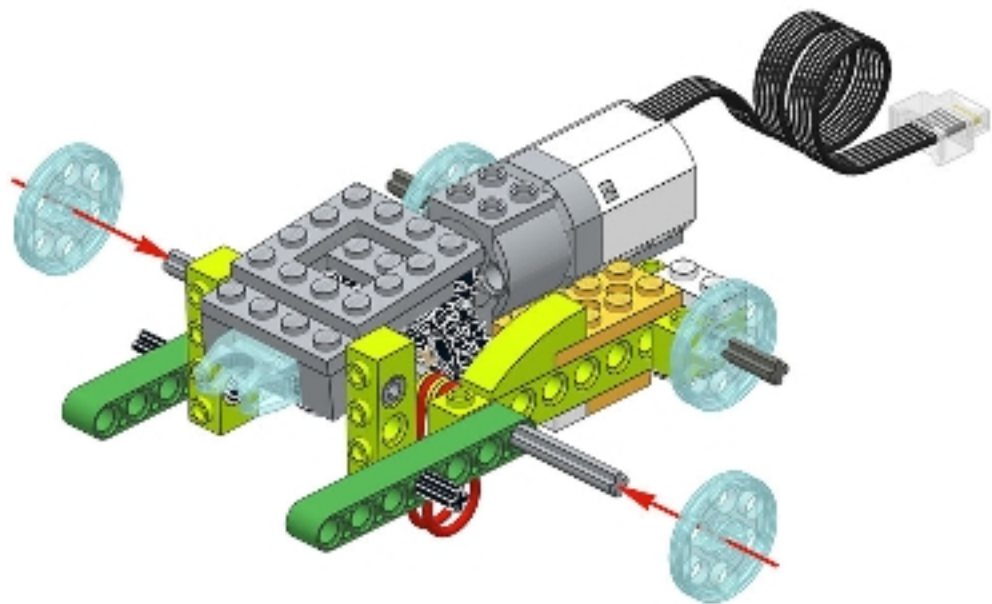
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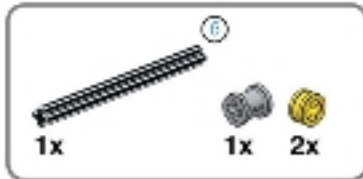




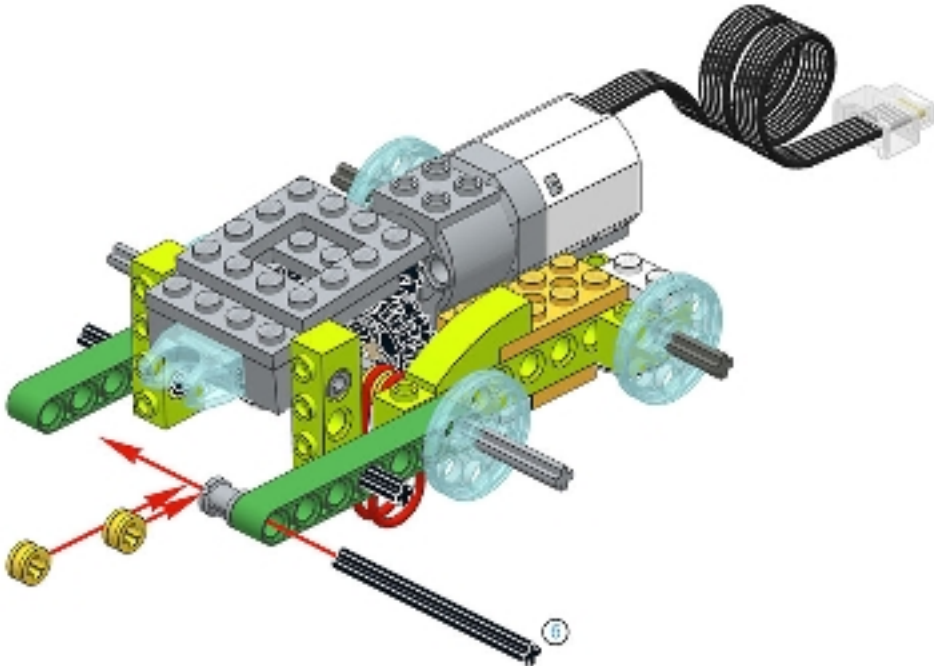
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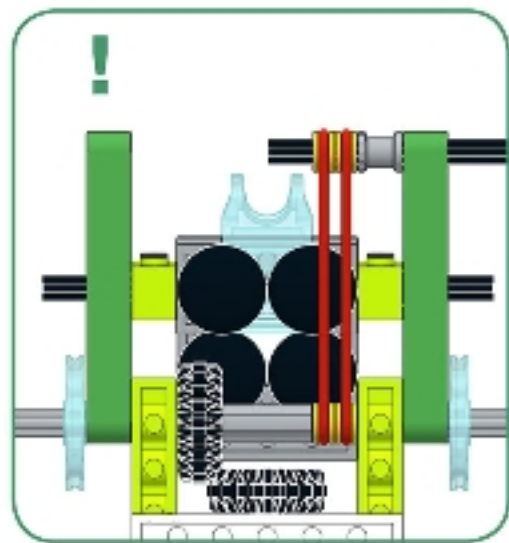
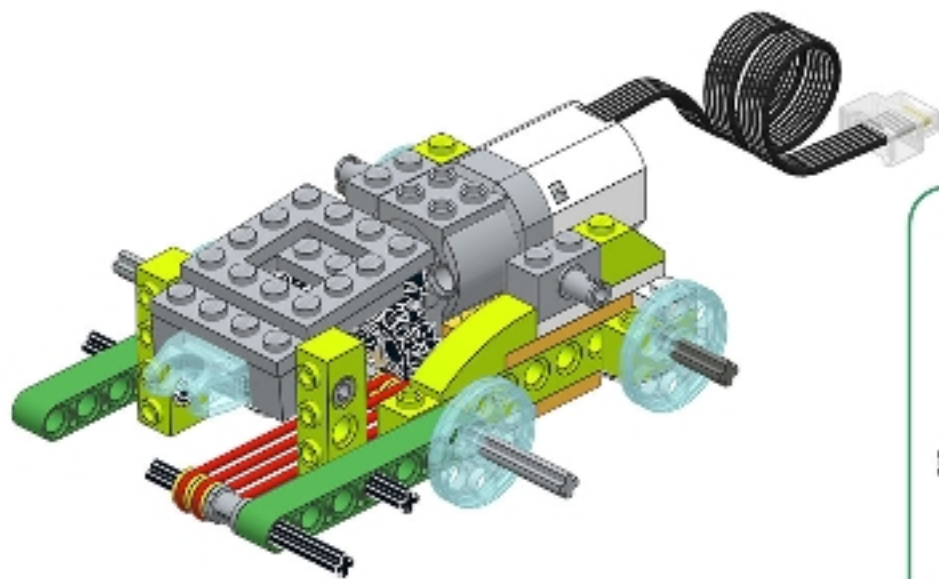
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35

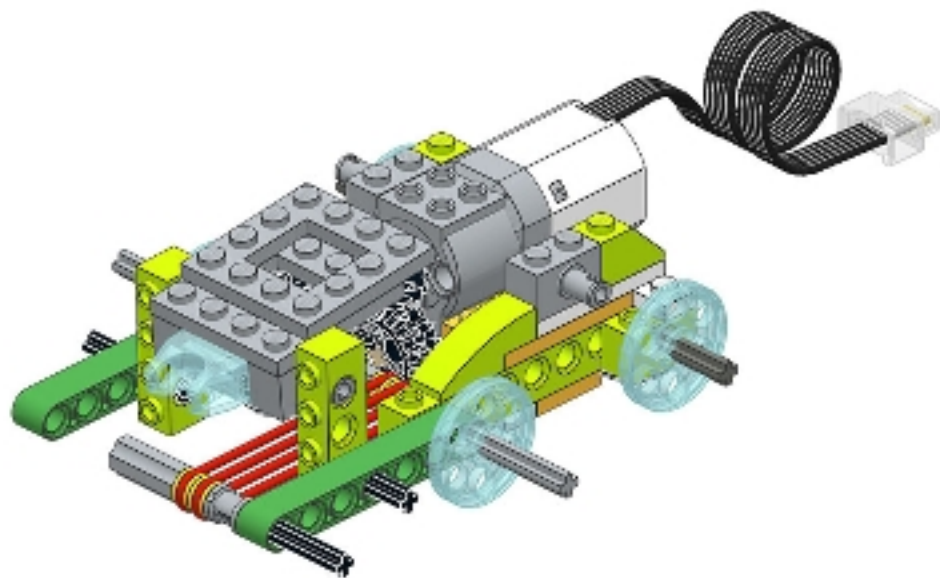






1x

37



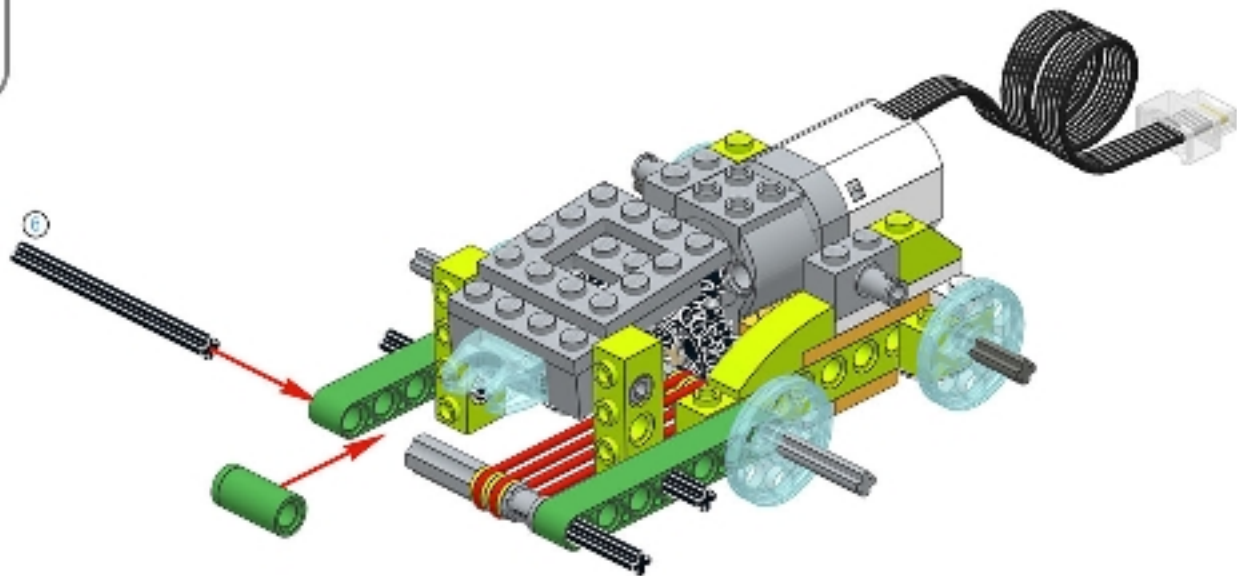


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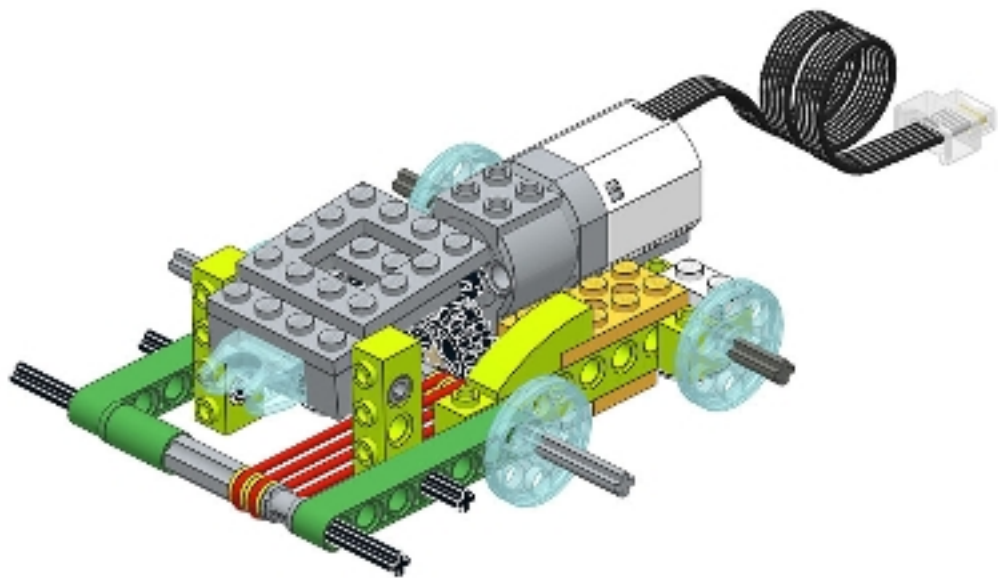


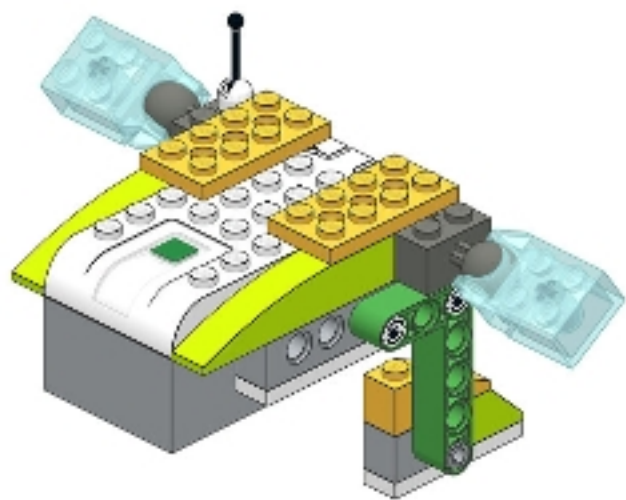
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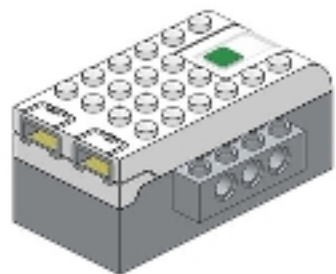
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39

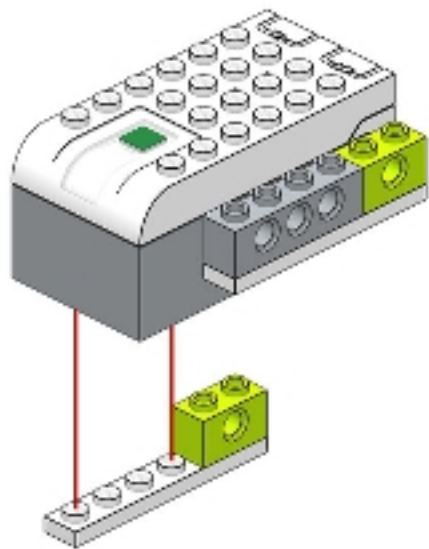




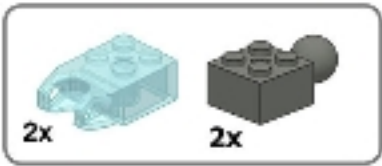


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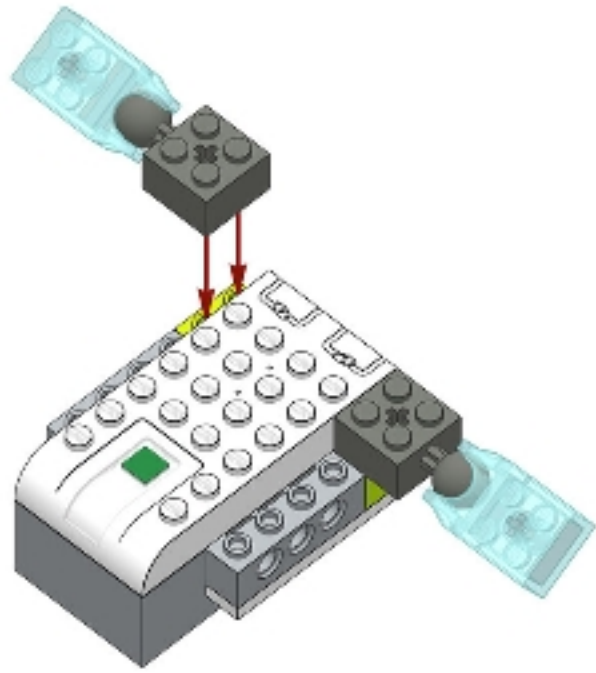
2x



41



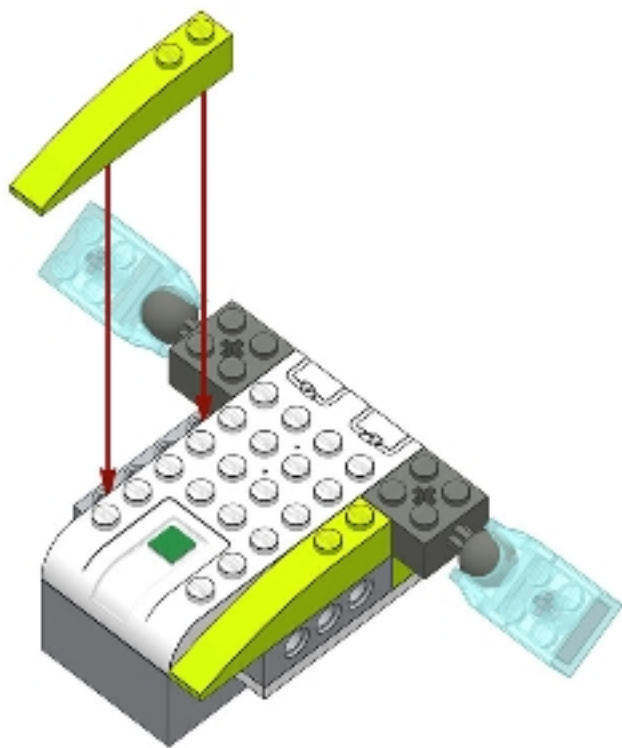
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2x

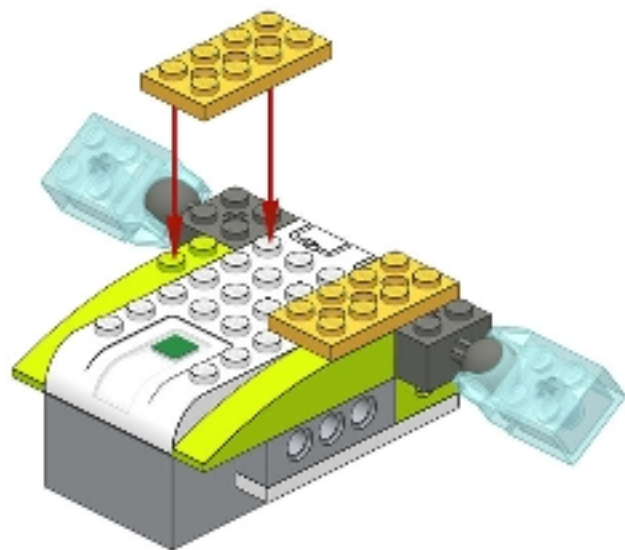
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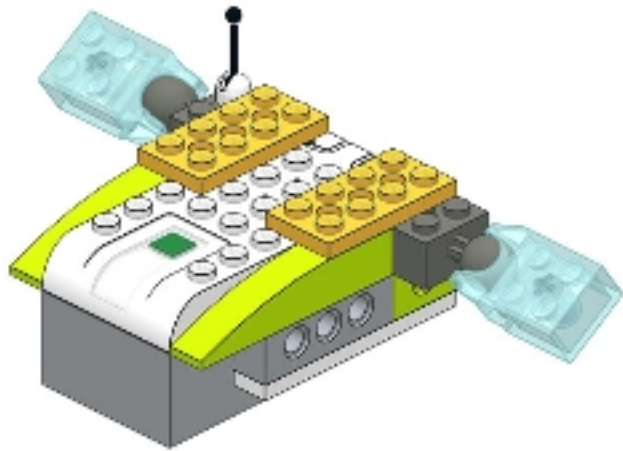
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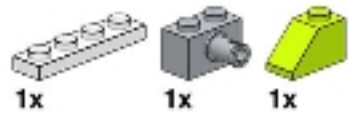
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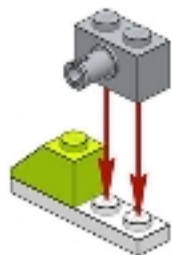


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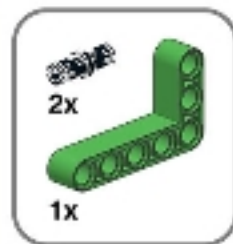
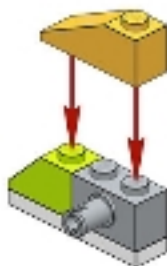




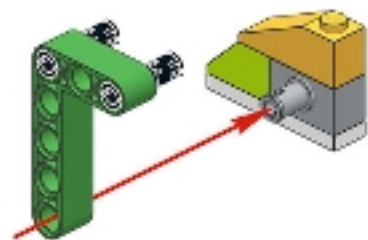
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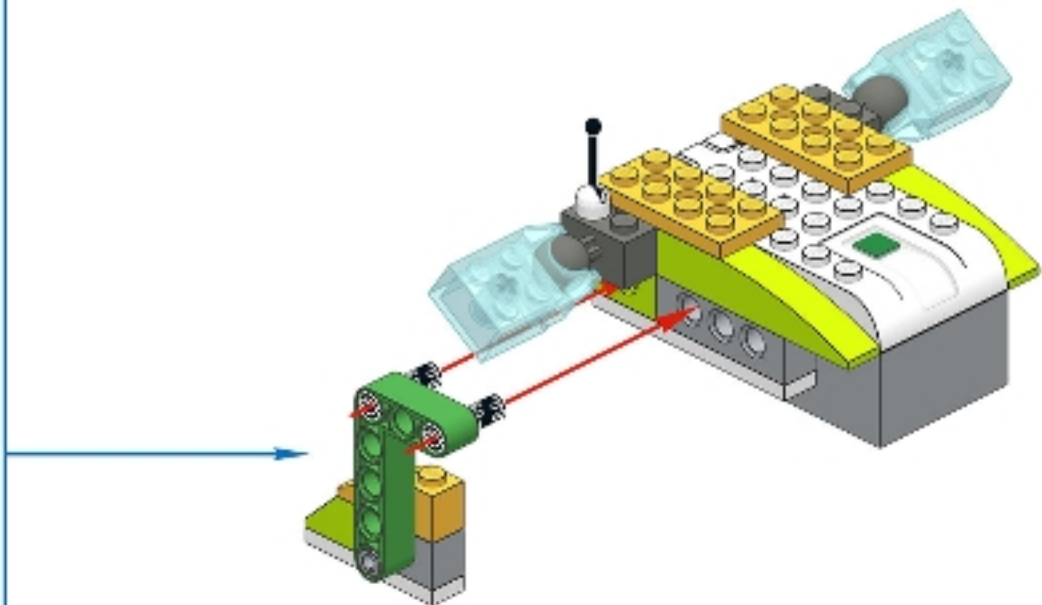
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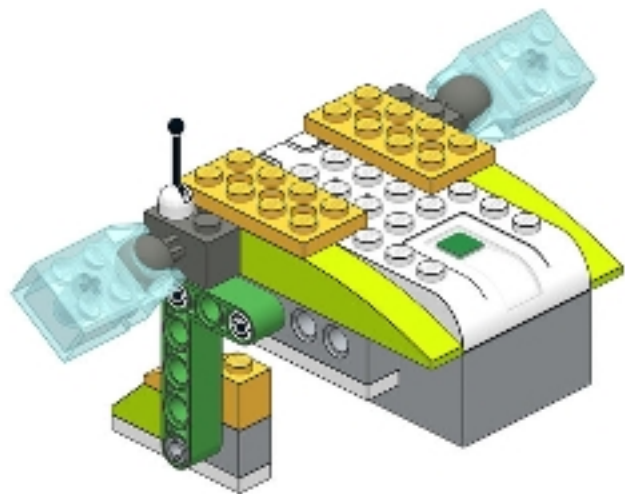
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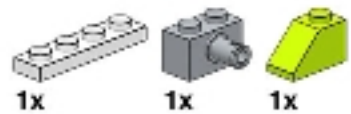


4



48



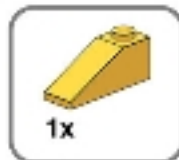
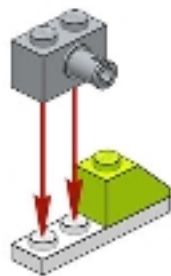


1x

1x

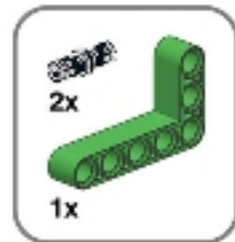
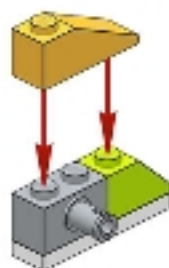
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1x

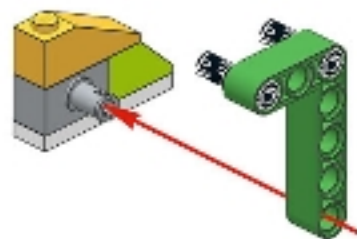
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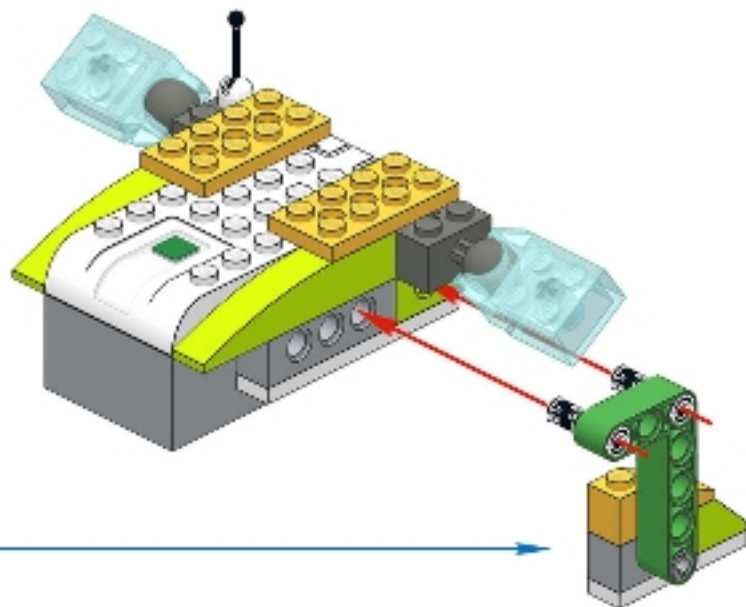
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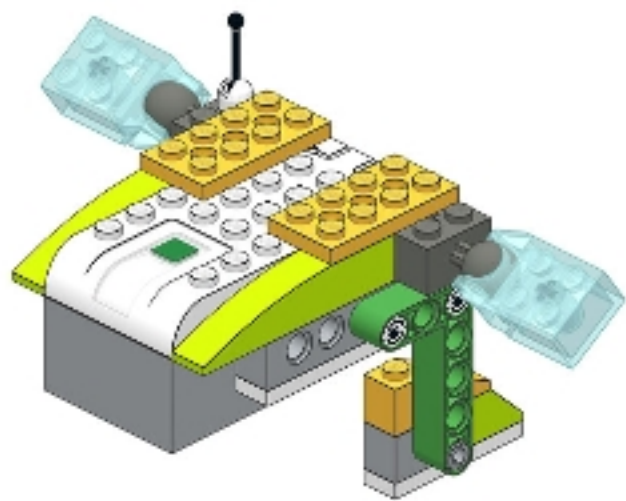
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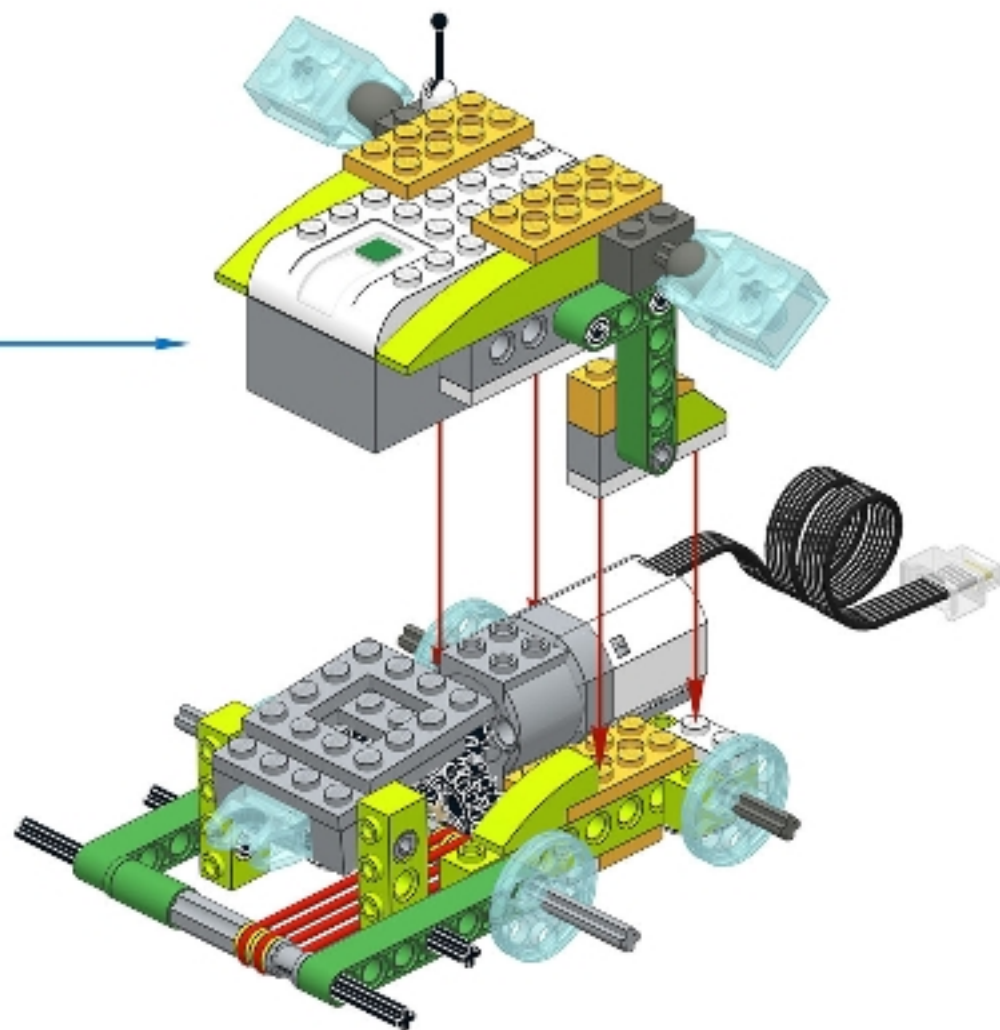
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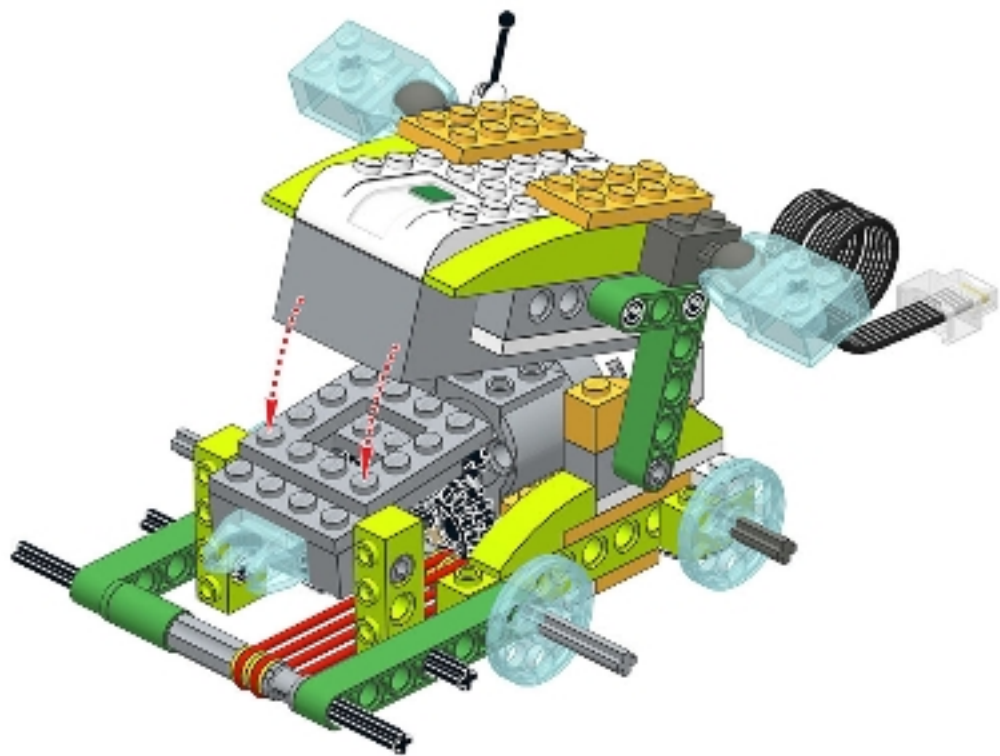


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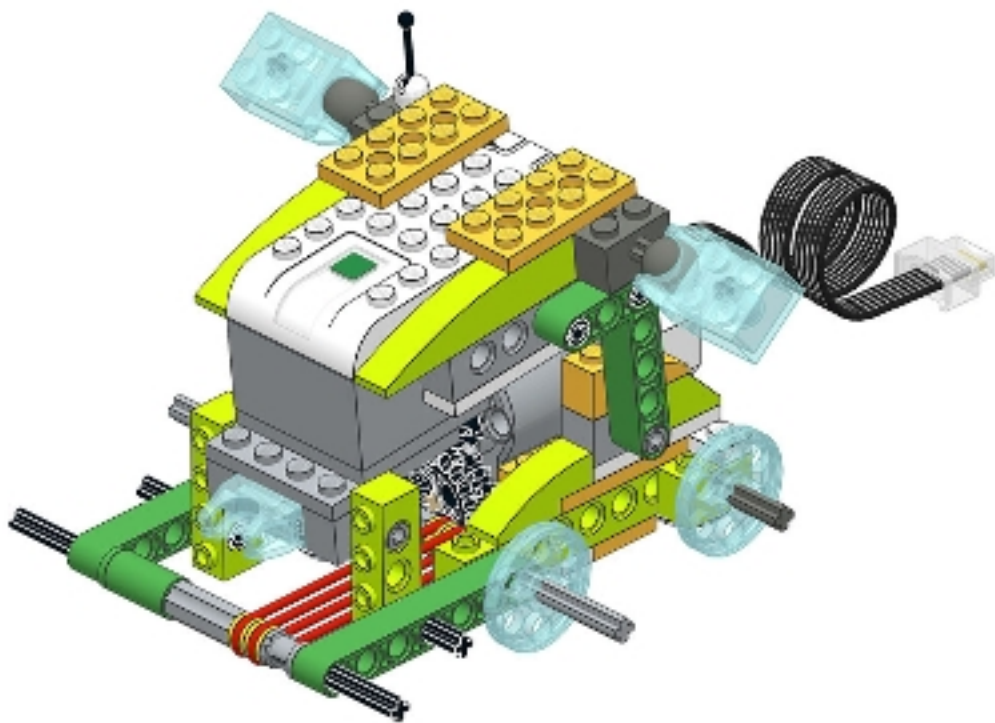


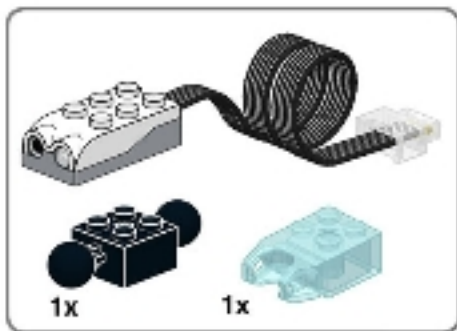
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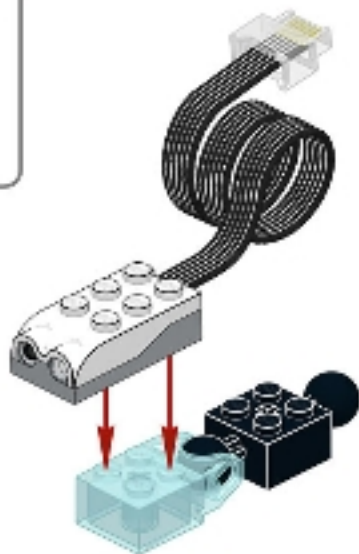


54





55



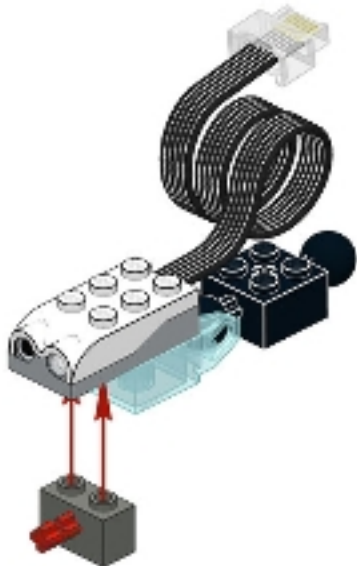


1x



1x

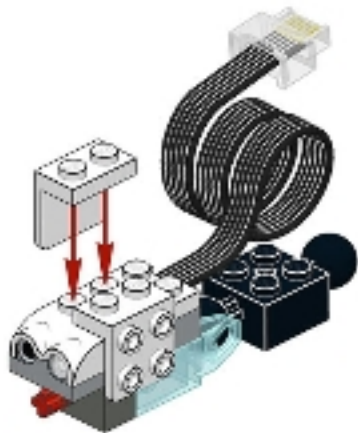
56





2x

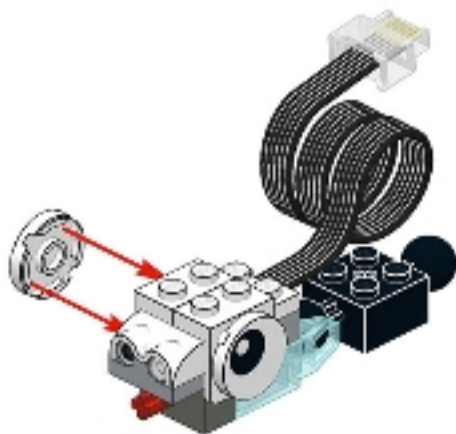
57





2x

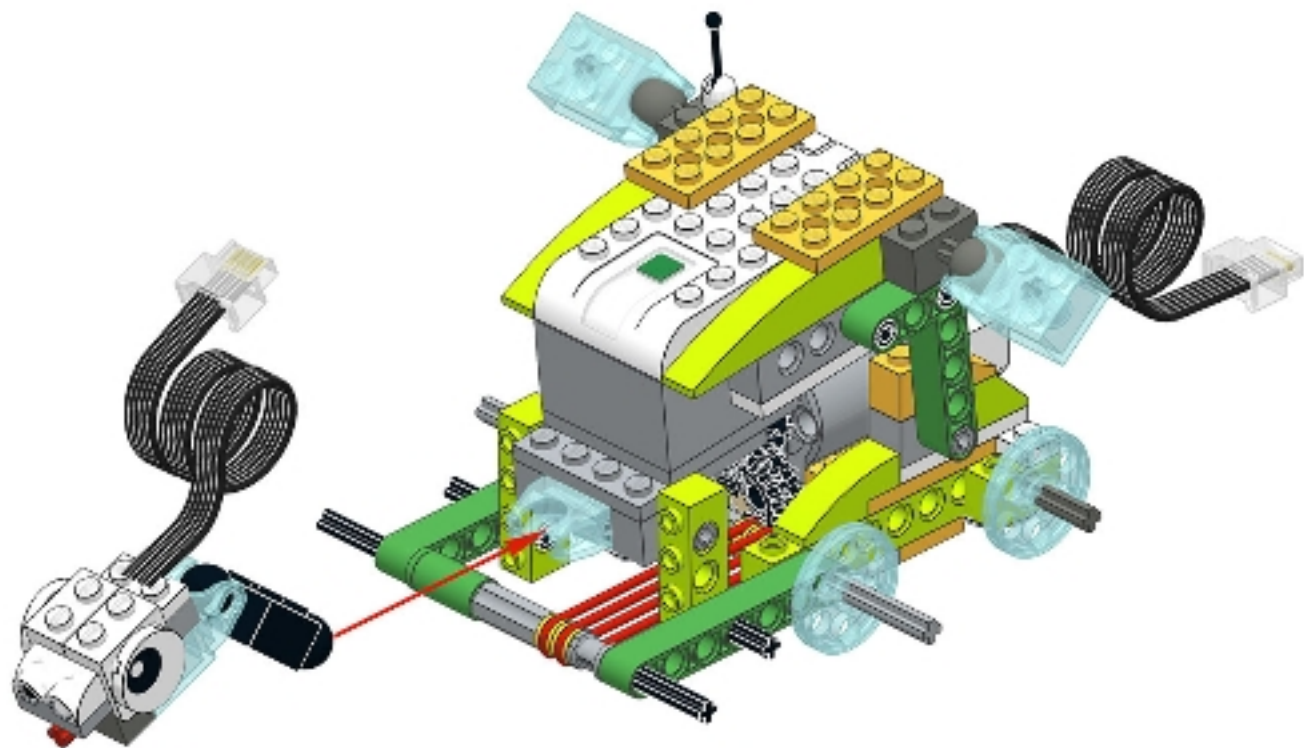
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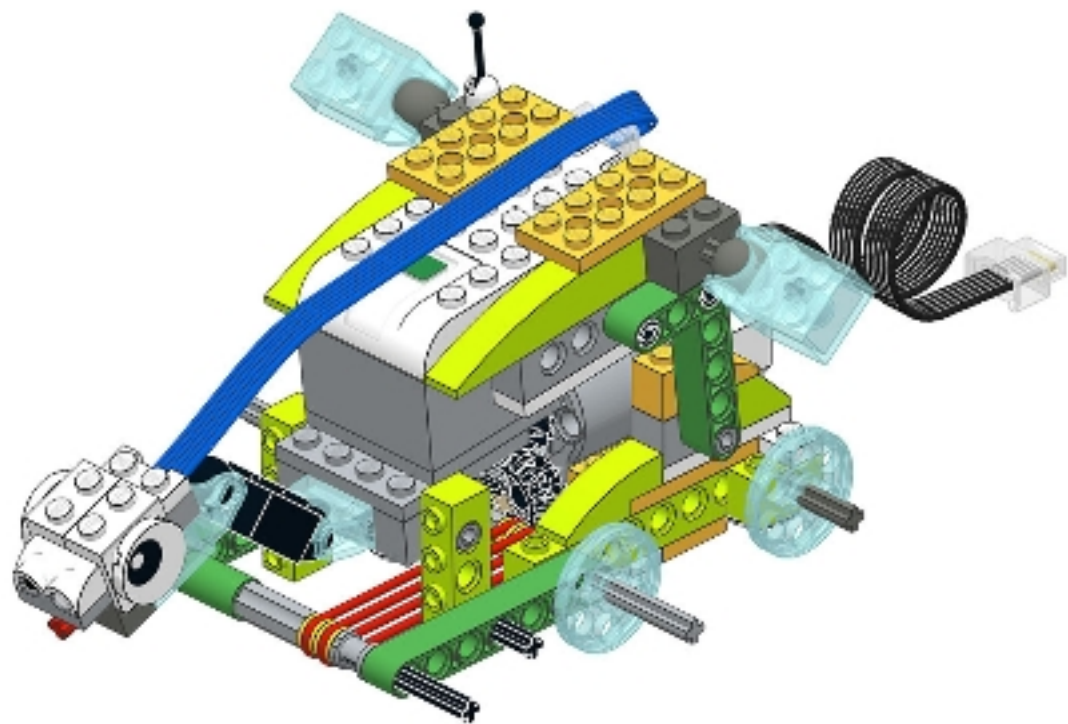
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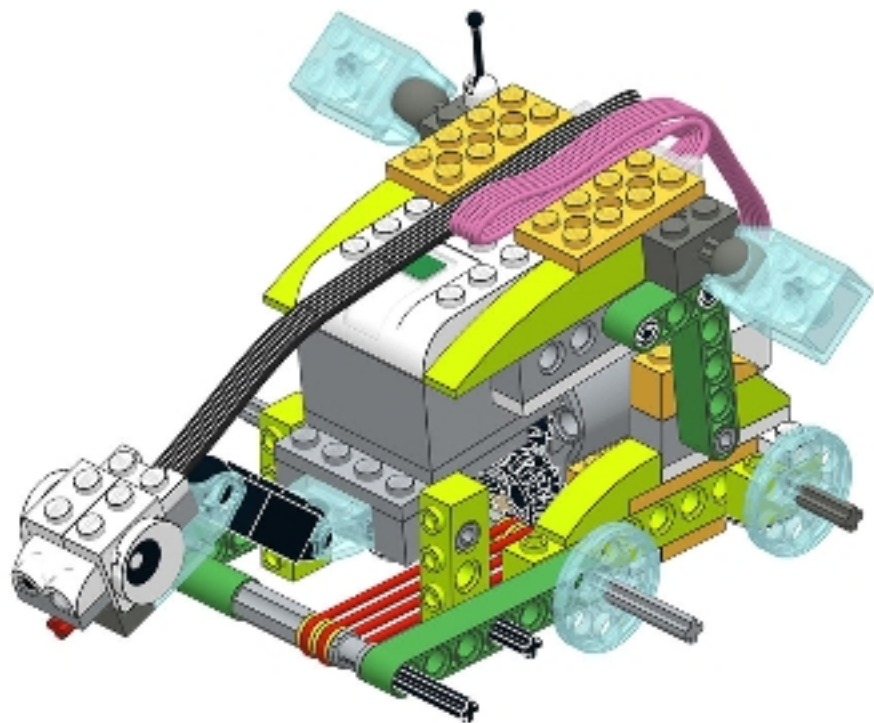


60



61

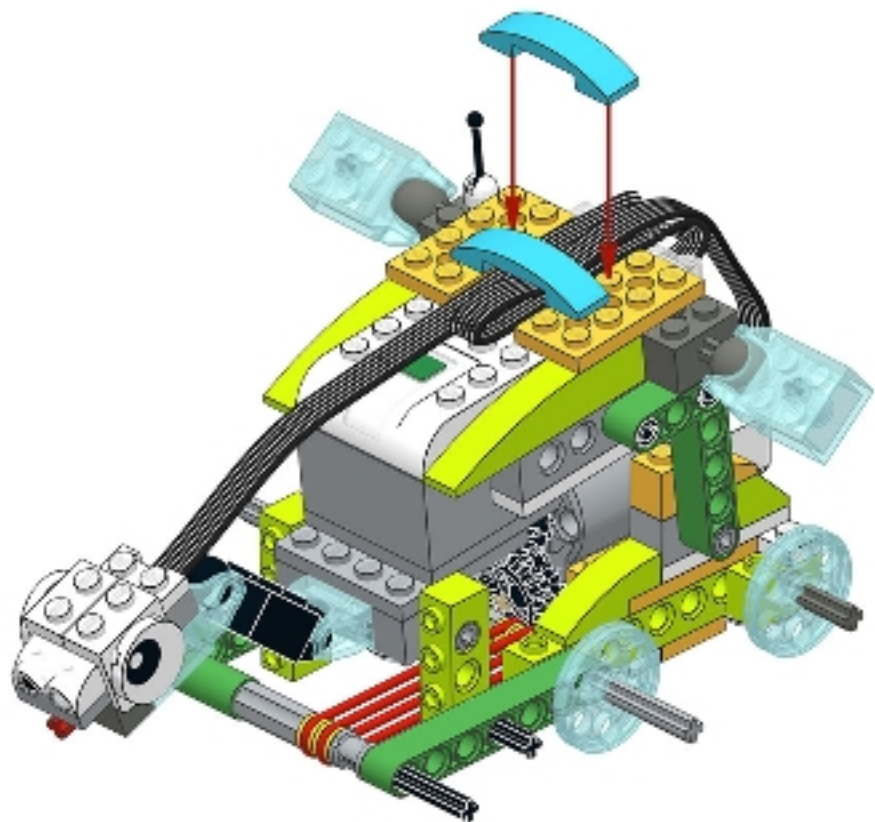




2x



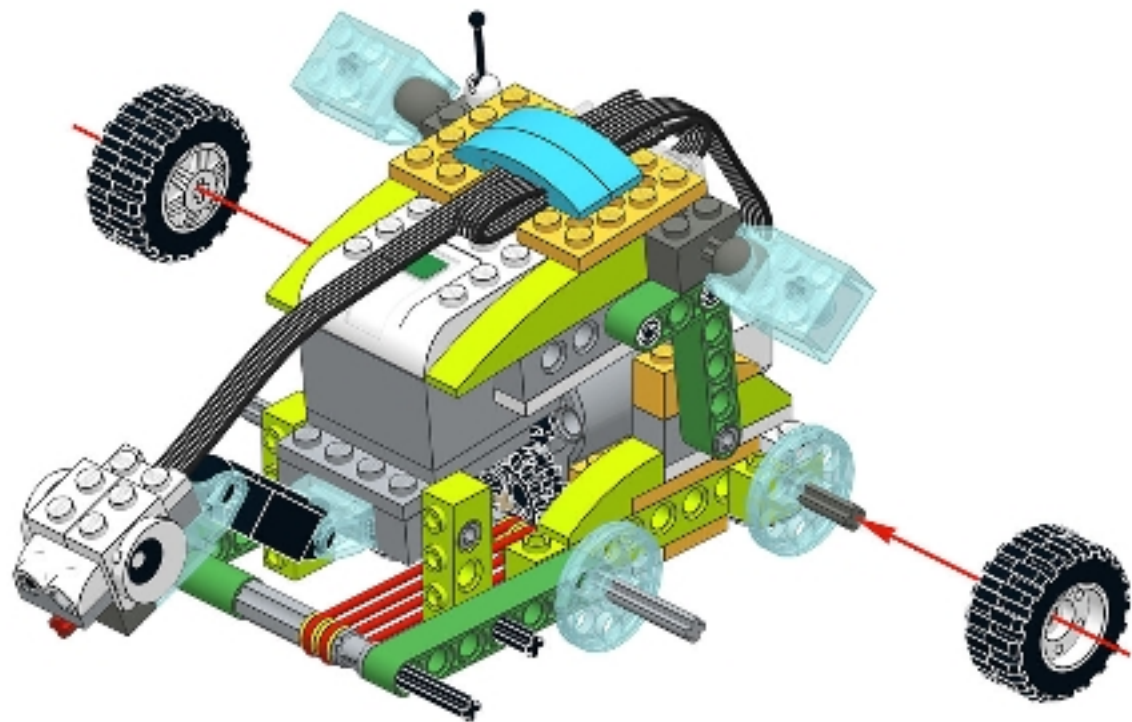
63





2x

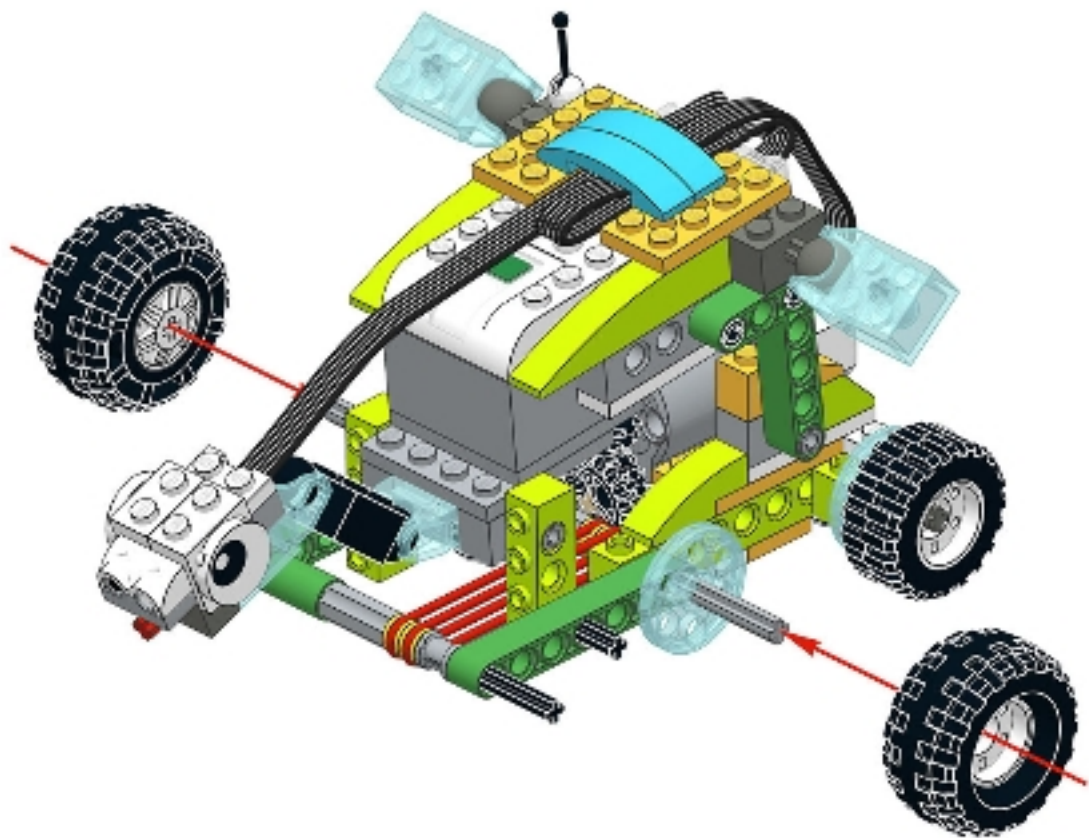
64





2x

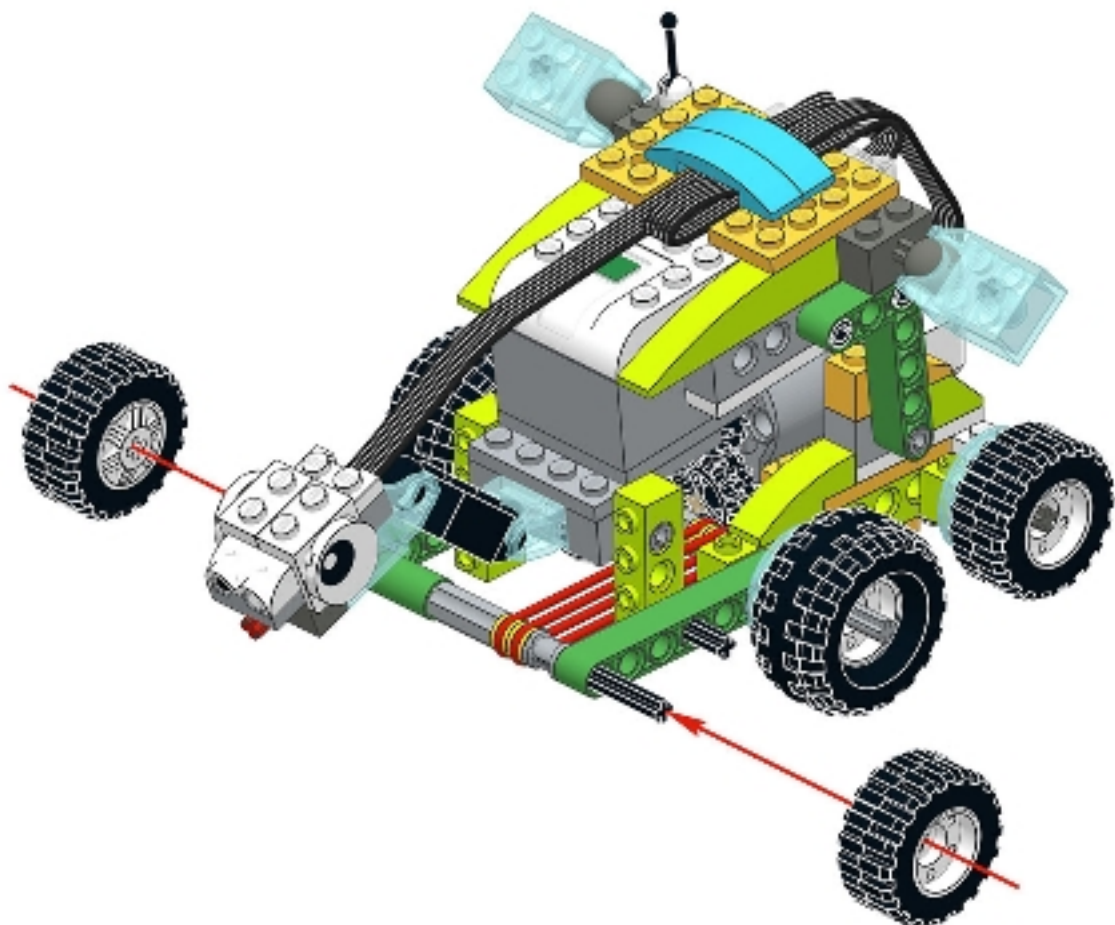
65





2x

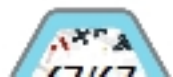
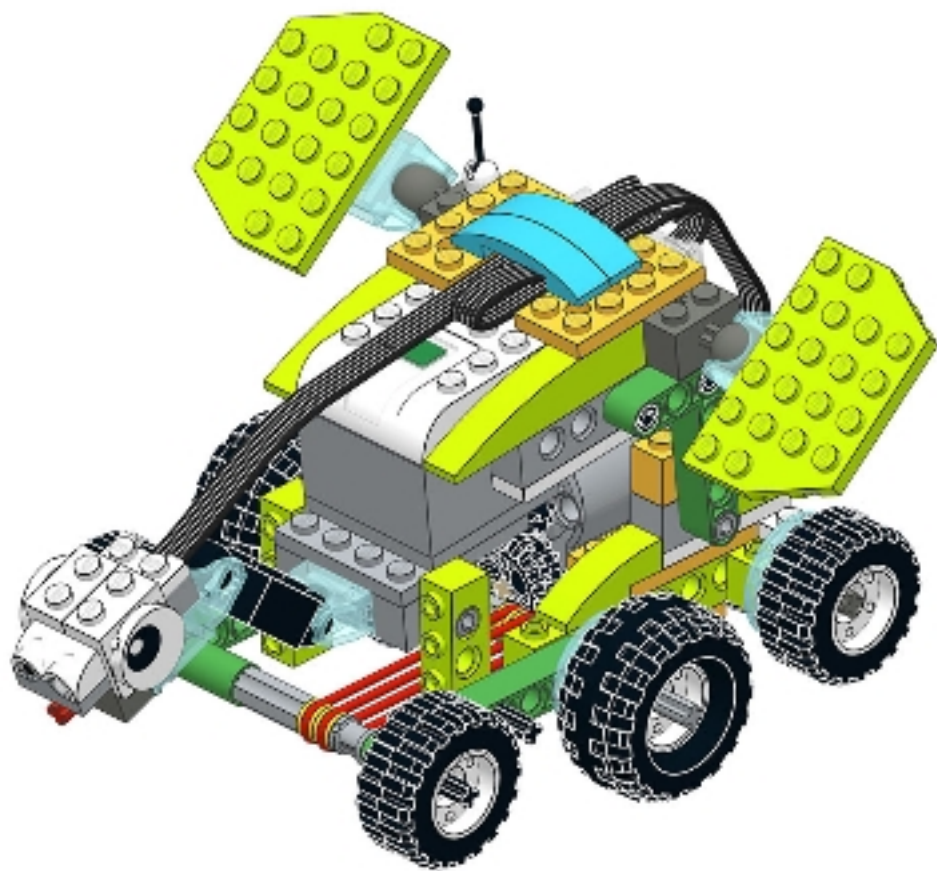
66

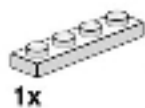




2x

67





1x

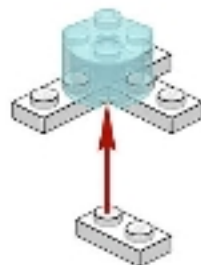


2x



1x

72



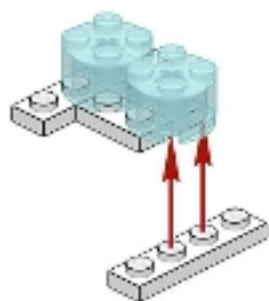


1x



1x

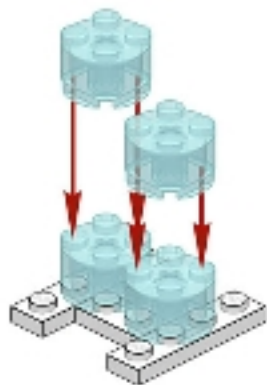
73

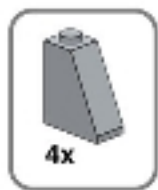




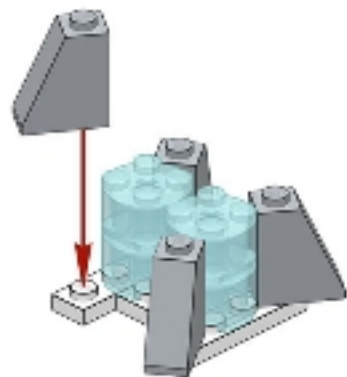
2x

74





75



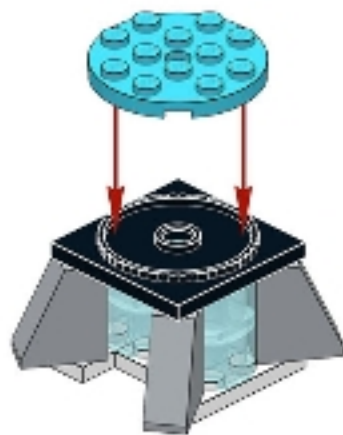


1x



1x

76





1x



1x

77

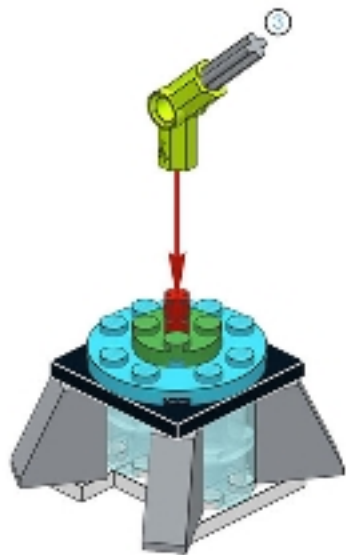




1x



1x



78

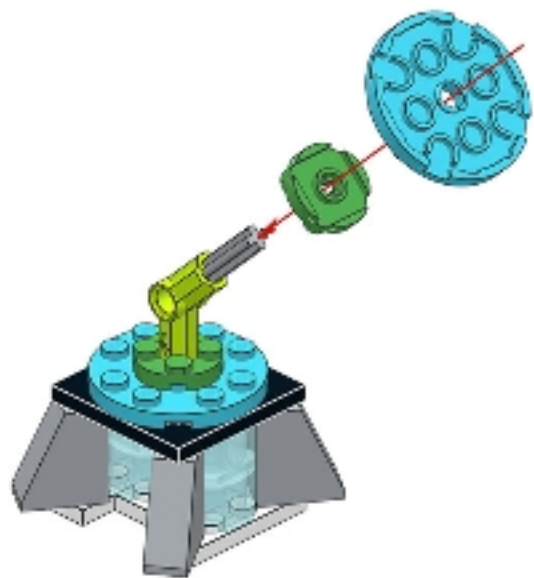


1x



1x

79





80





Task 1. Program

Write the program to move the robot forward by the example below.

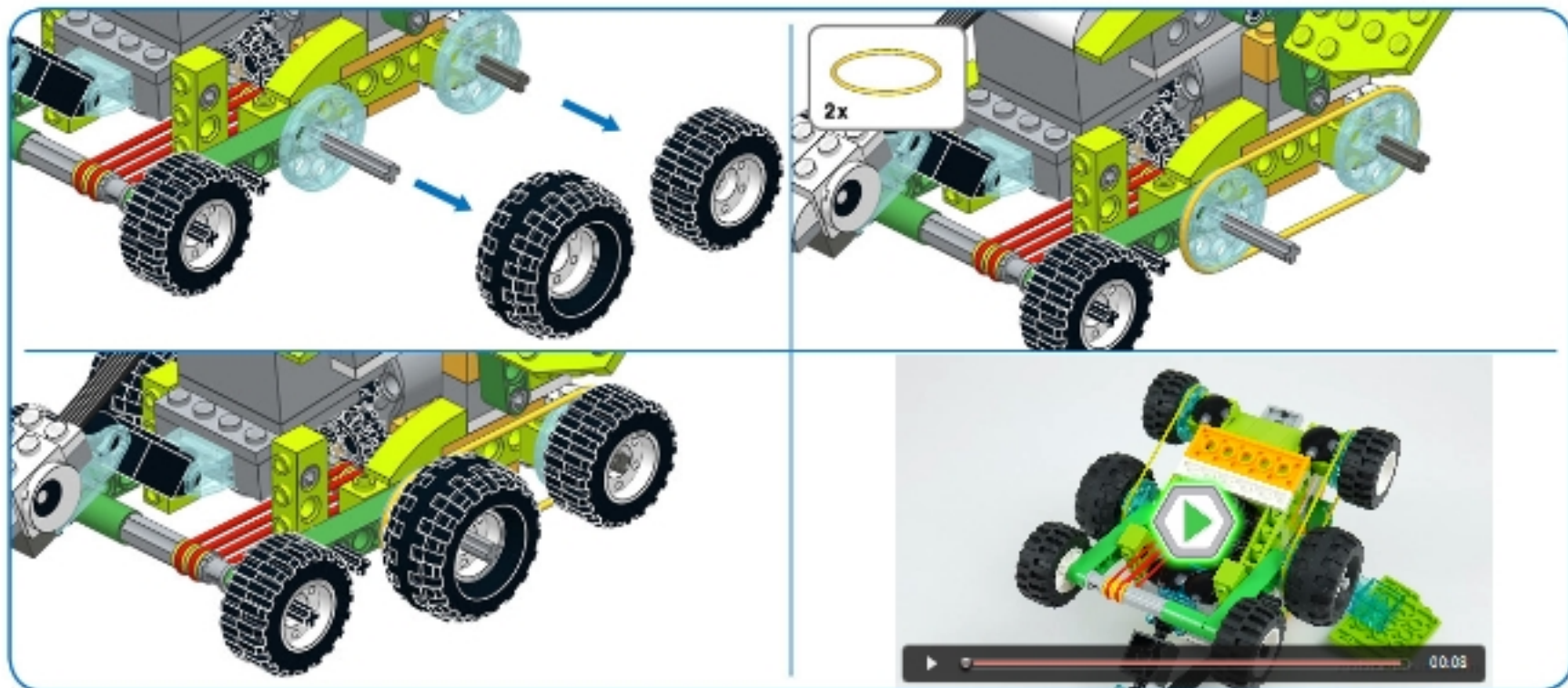


To test the passability you just need to run the motor.



Task 2

Connect the drive of the rear wheels of the robot.





Task 4. Program

Modify the program you wrote as follows:



When approaching the robot to the chasm, the sensor will detect a sharp increase in the distance to the object.



Task 5. Program

Modify the program you wrote as follows:



To change the sensor's operation mode simply click on its image!