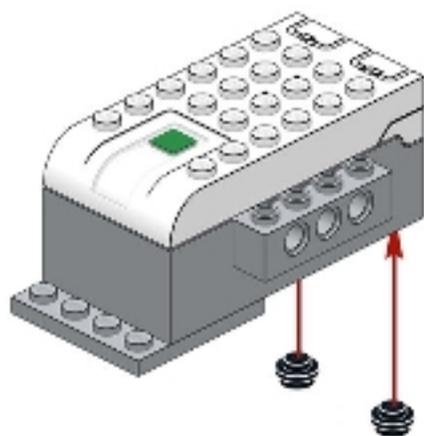


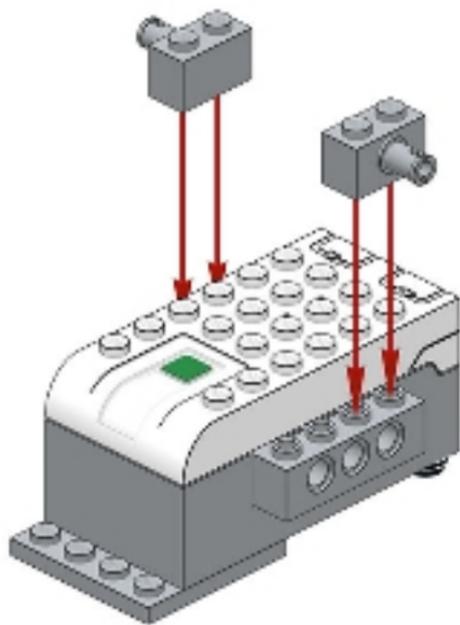
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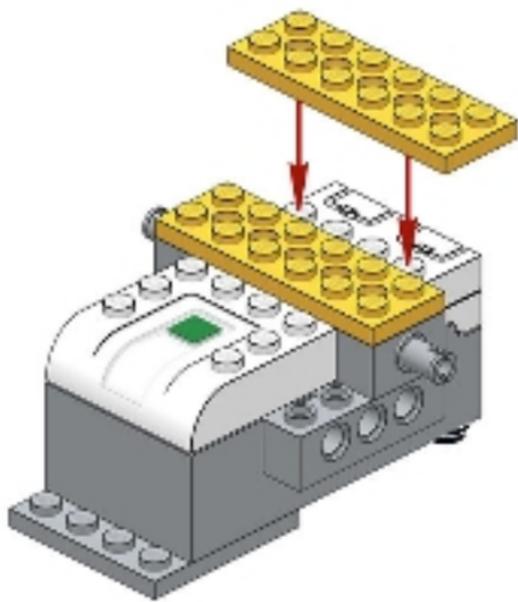
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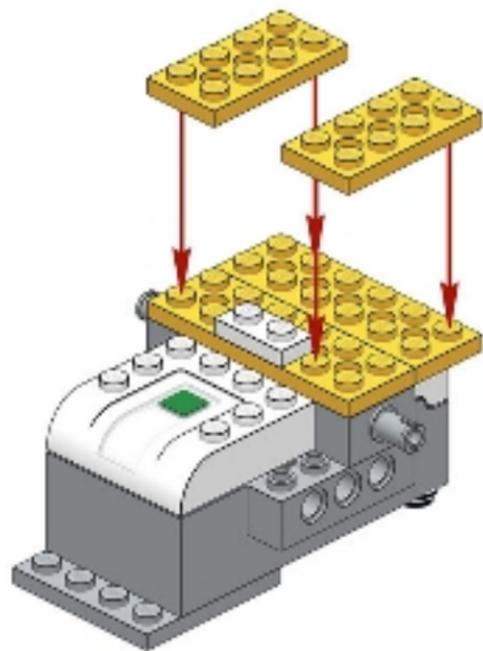


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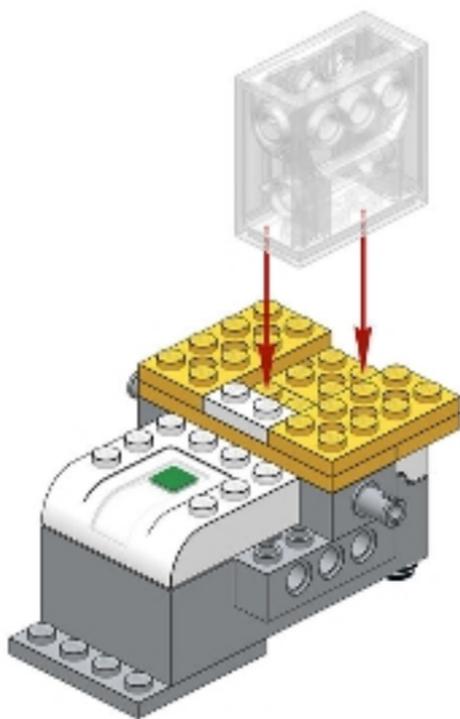
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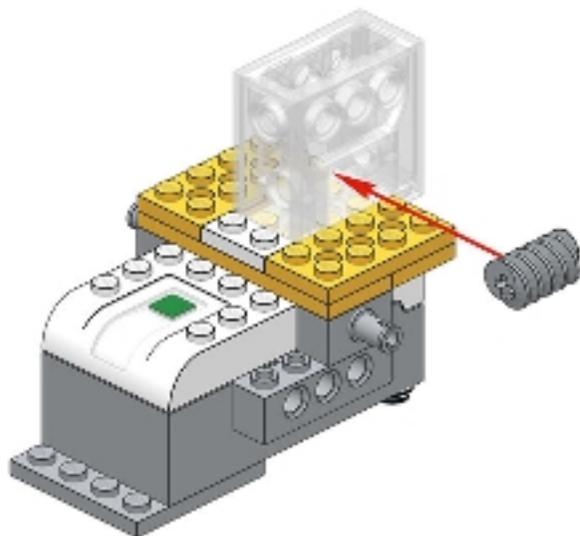
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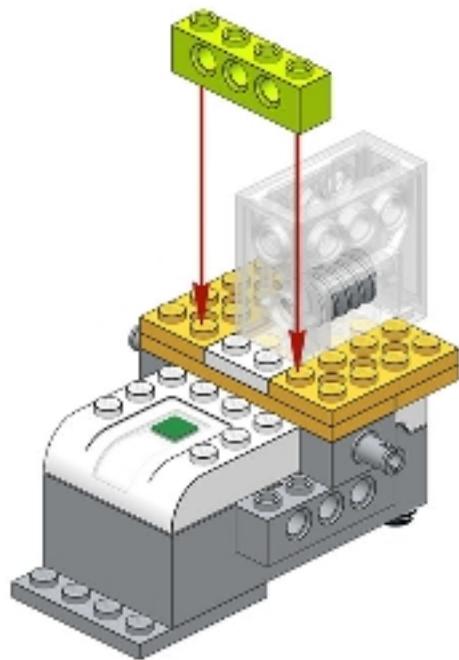
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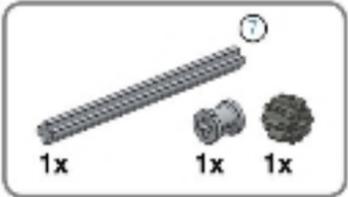




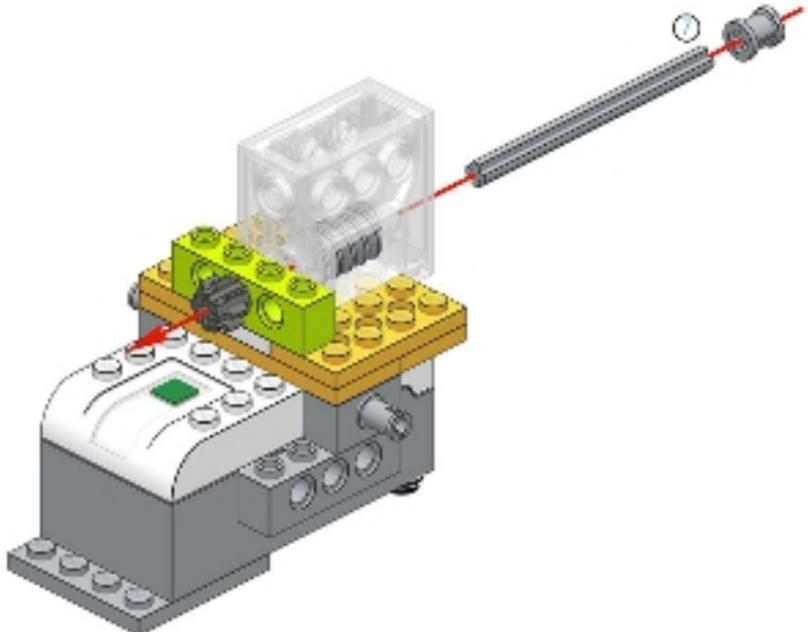
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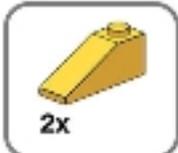
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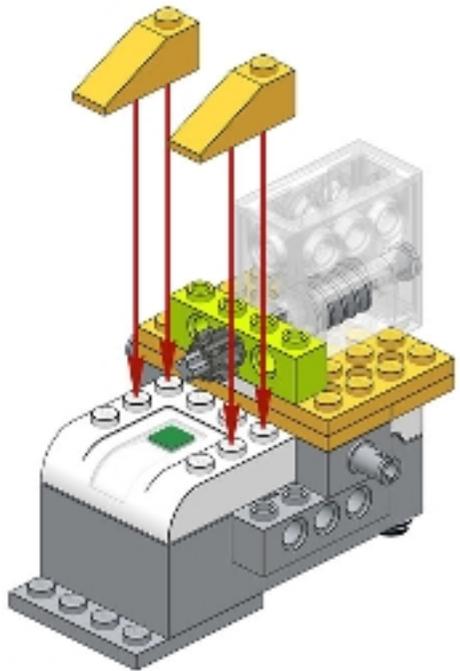


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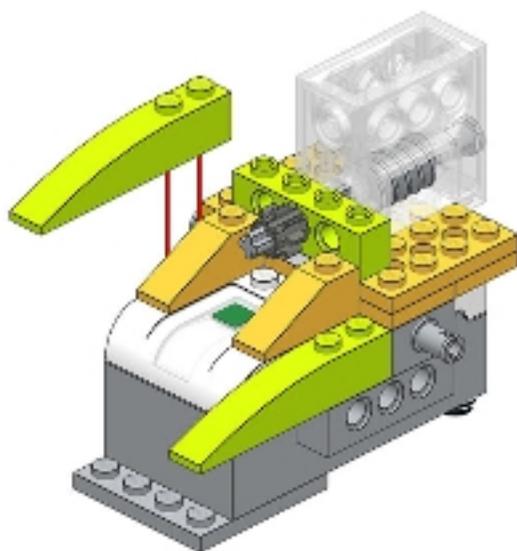
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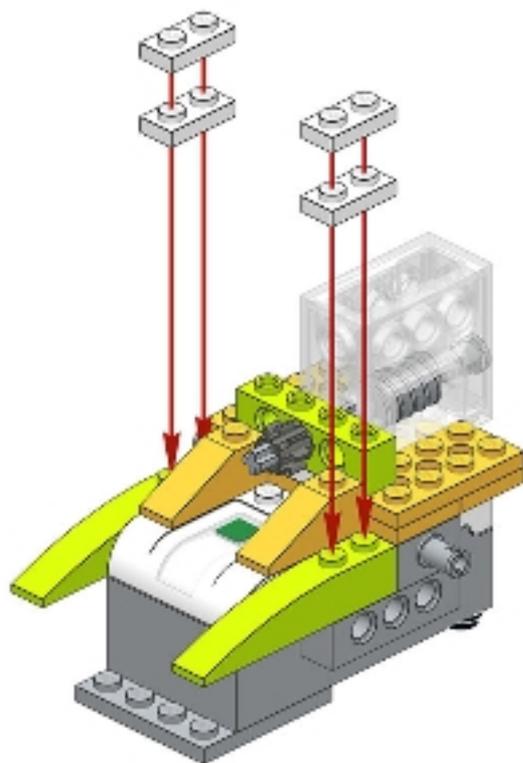
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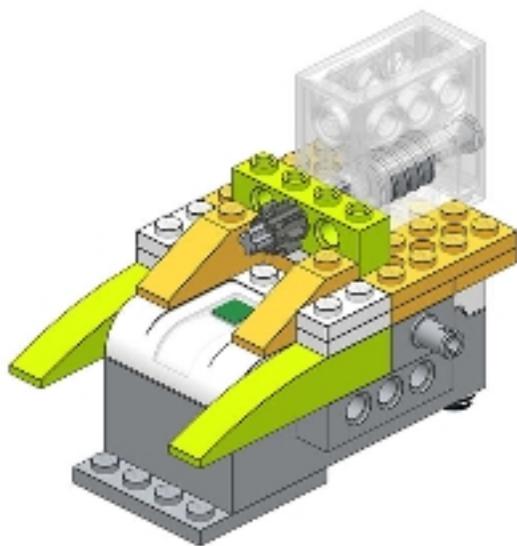


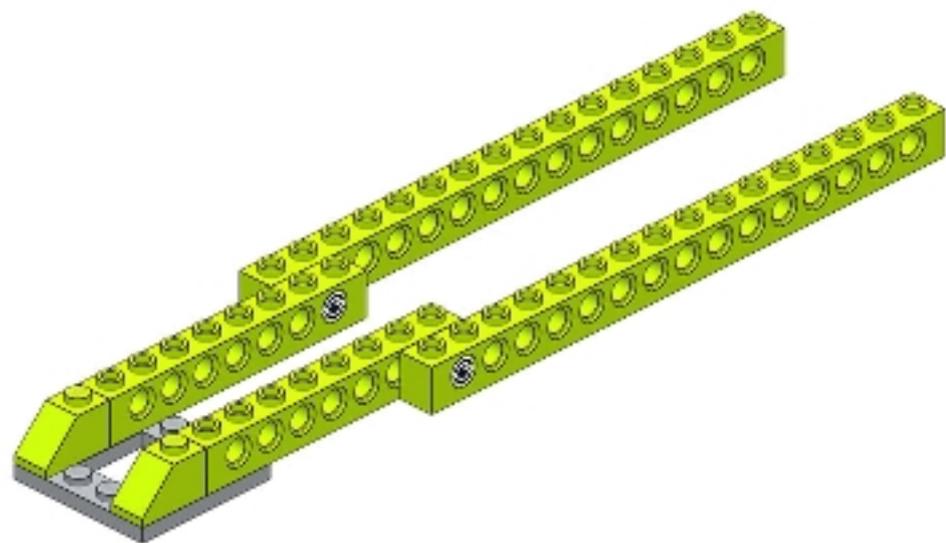
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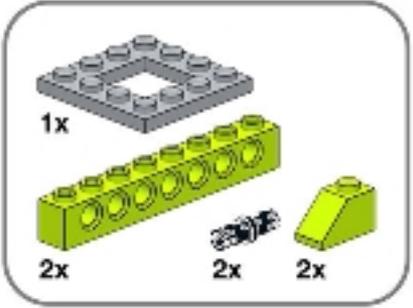
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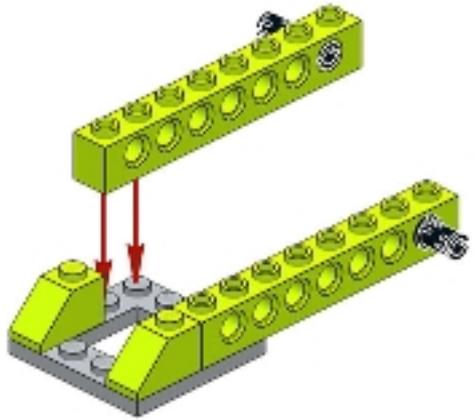
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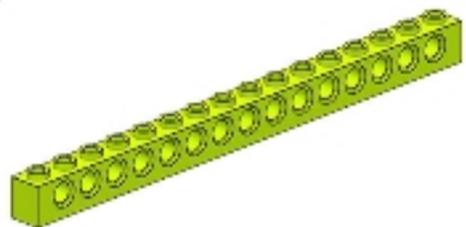






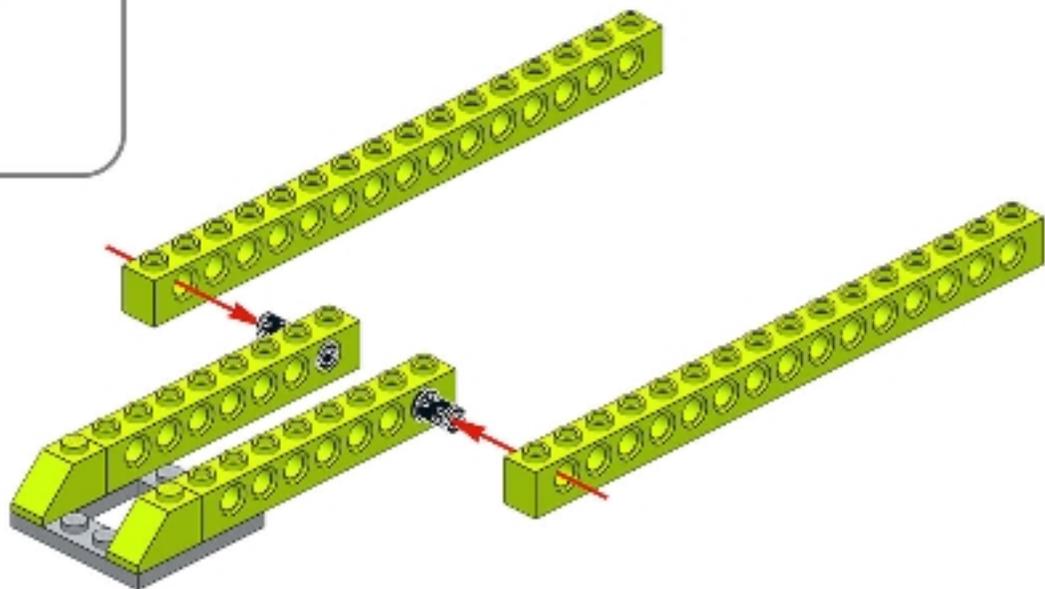
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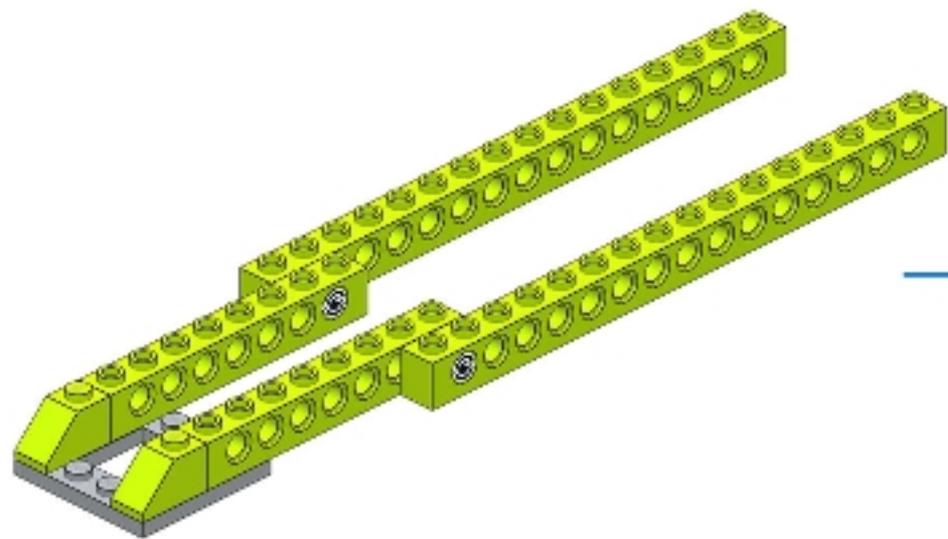


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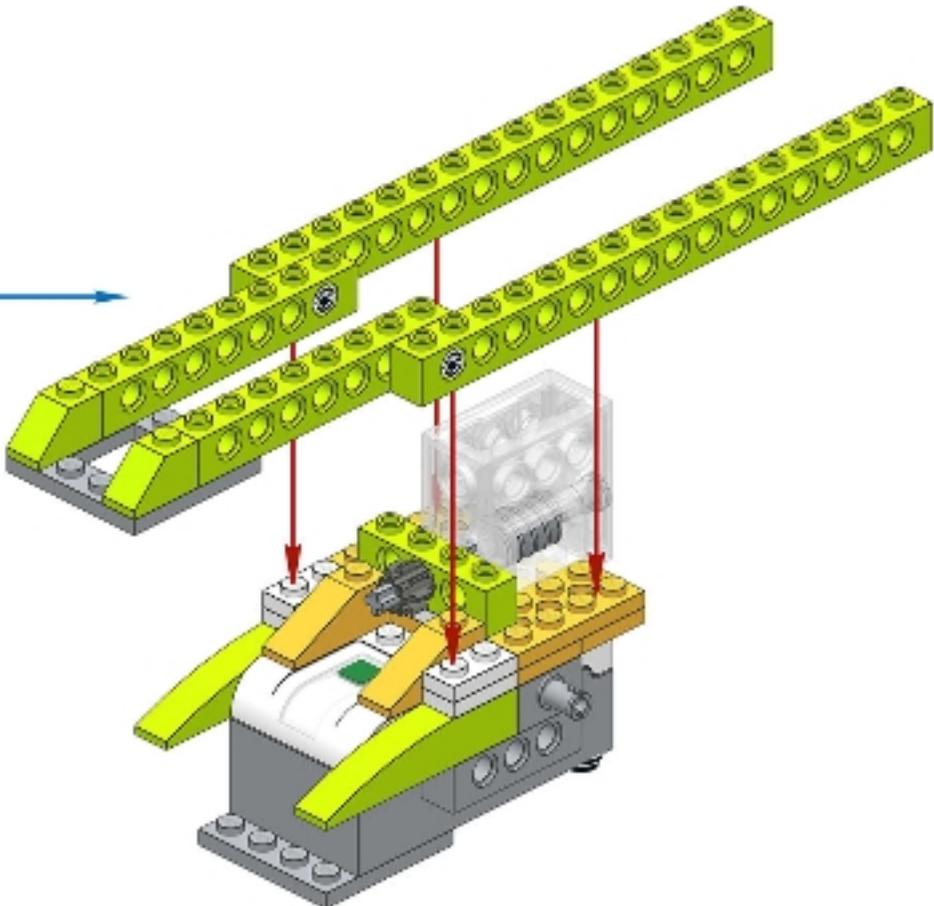
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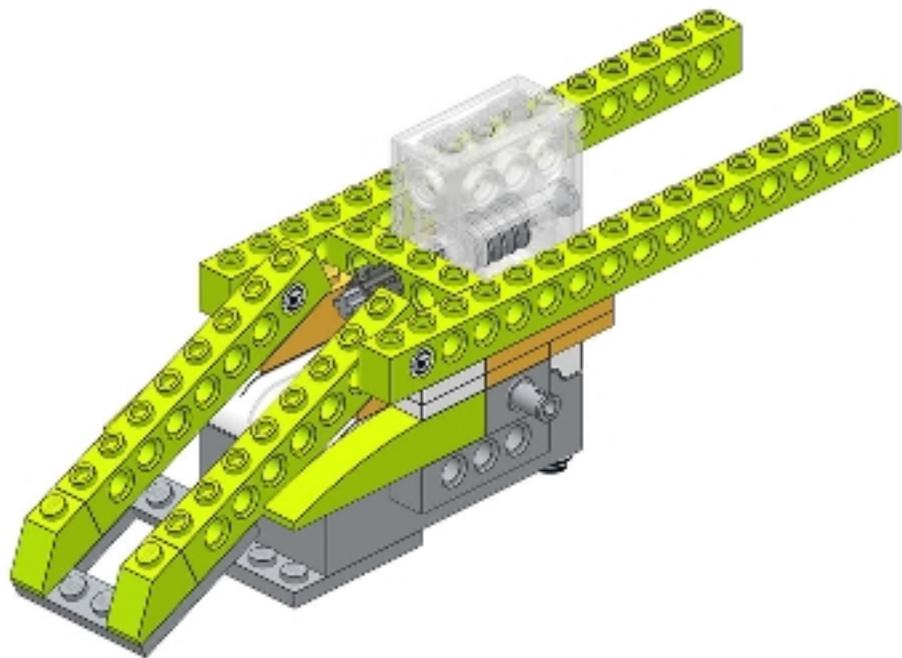
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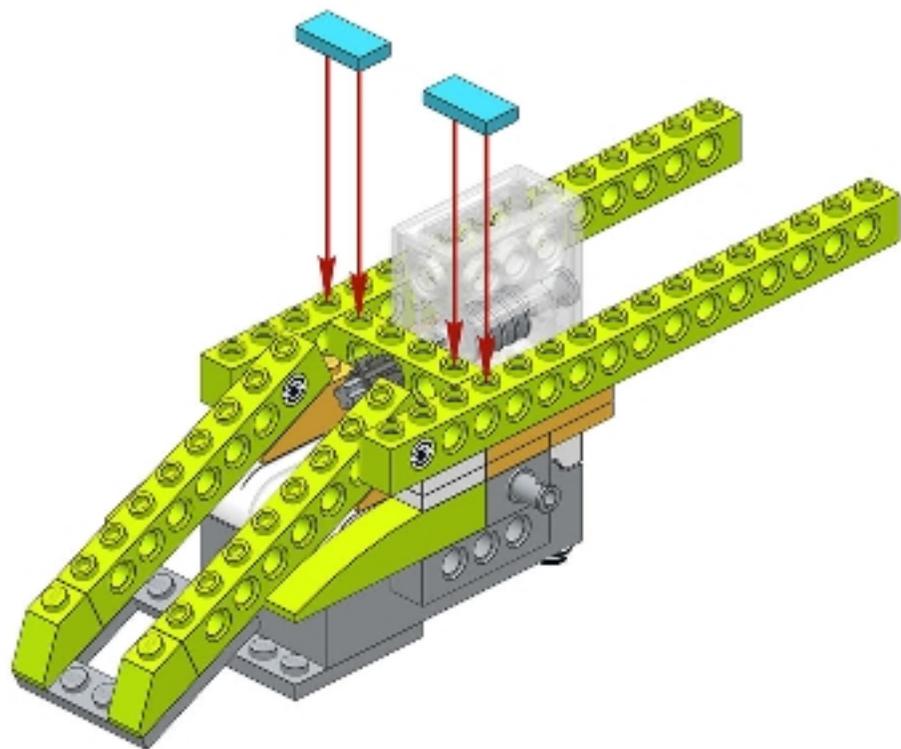
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2x

19





1x



3x



1x

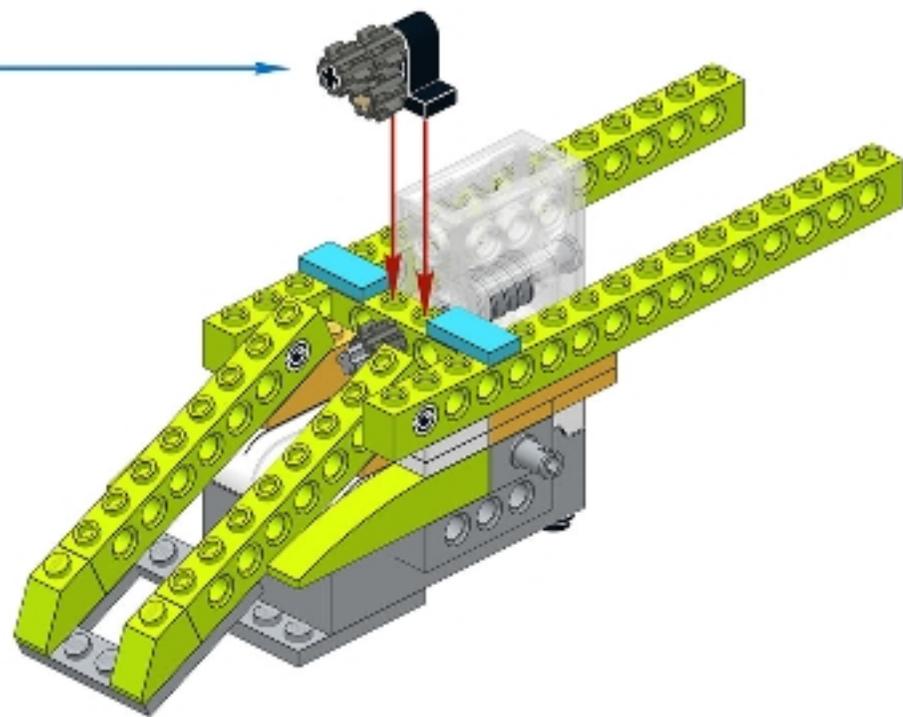


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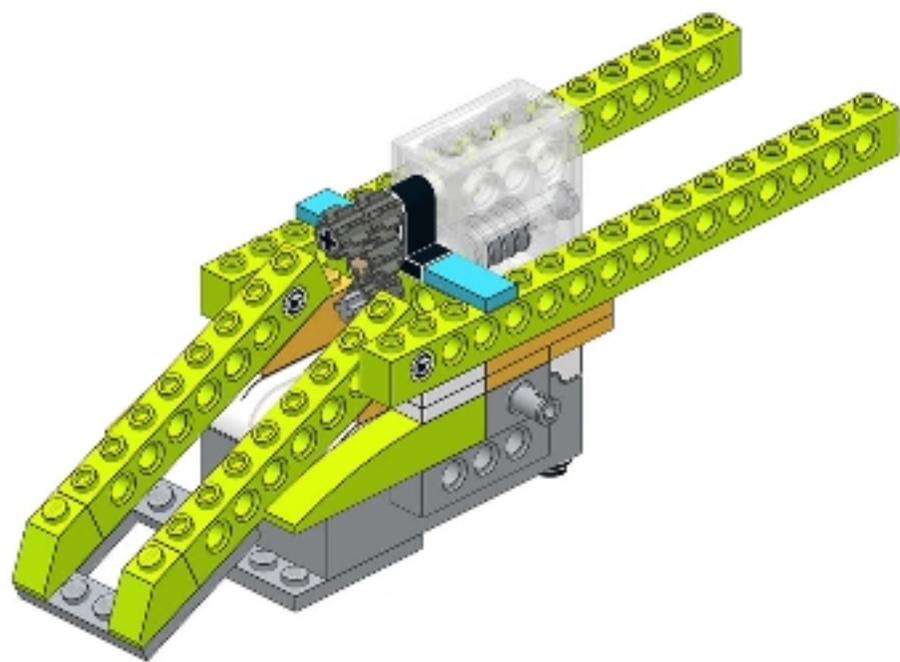
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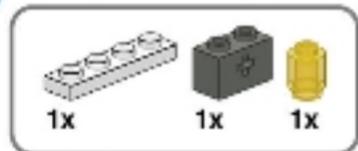
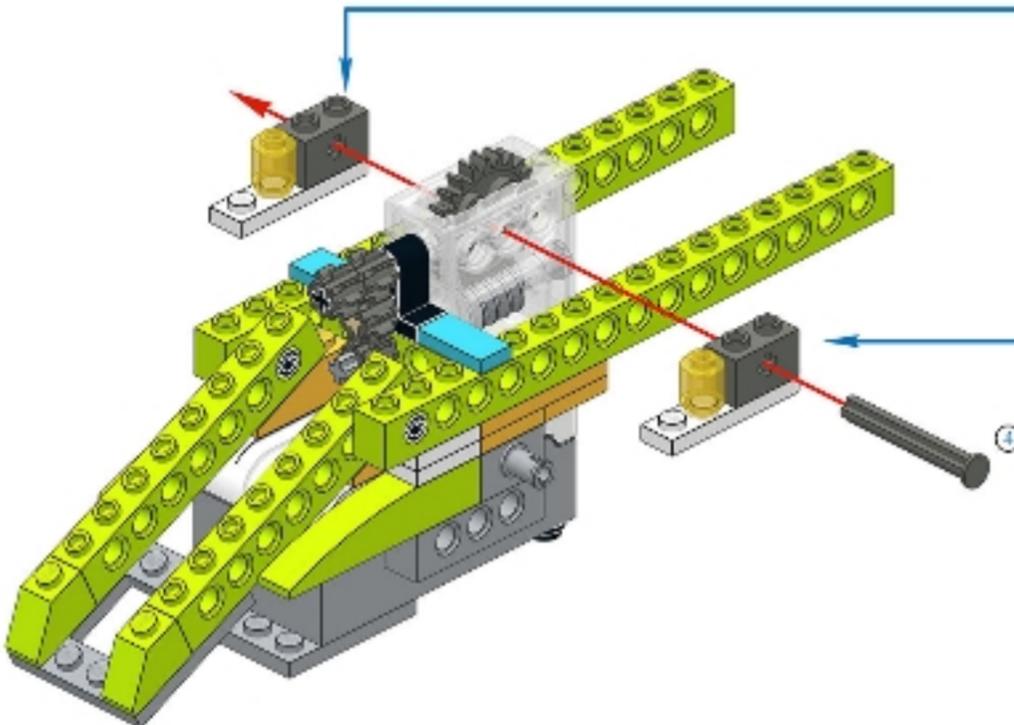


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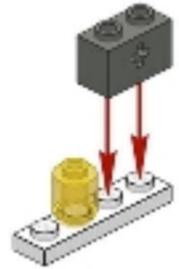




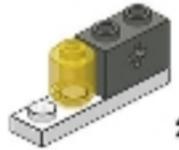
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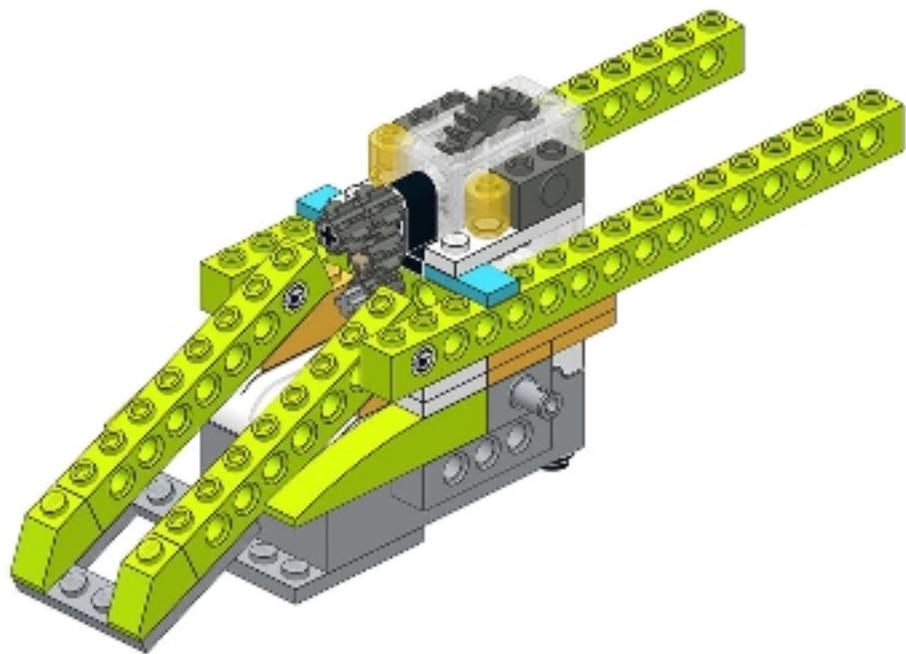
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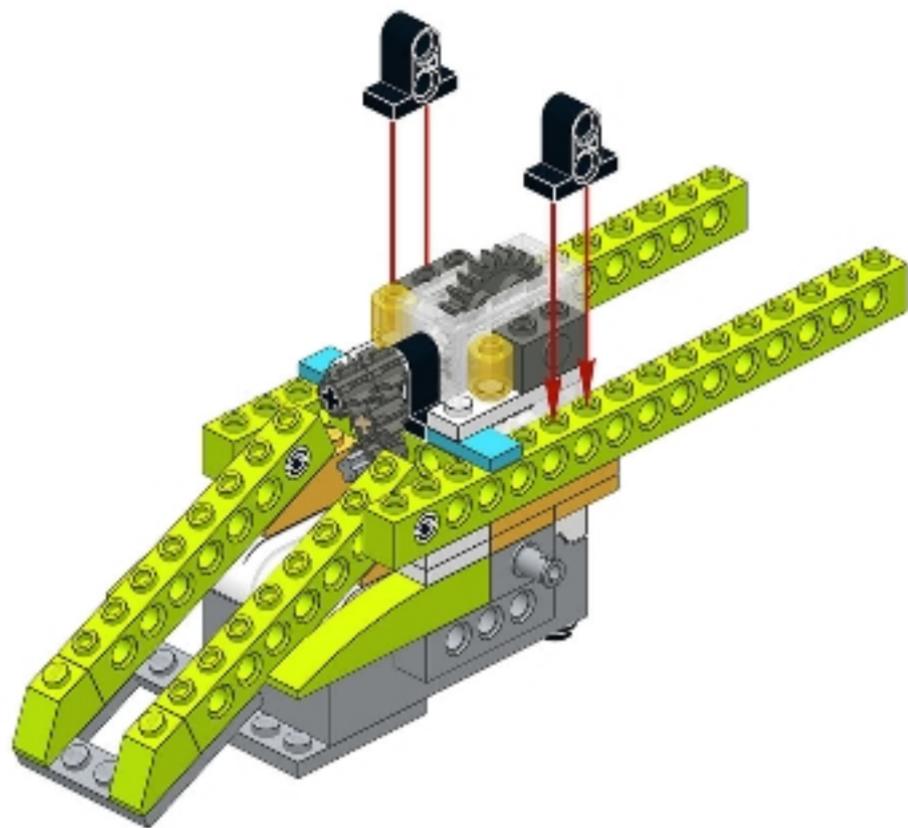
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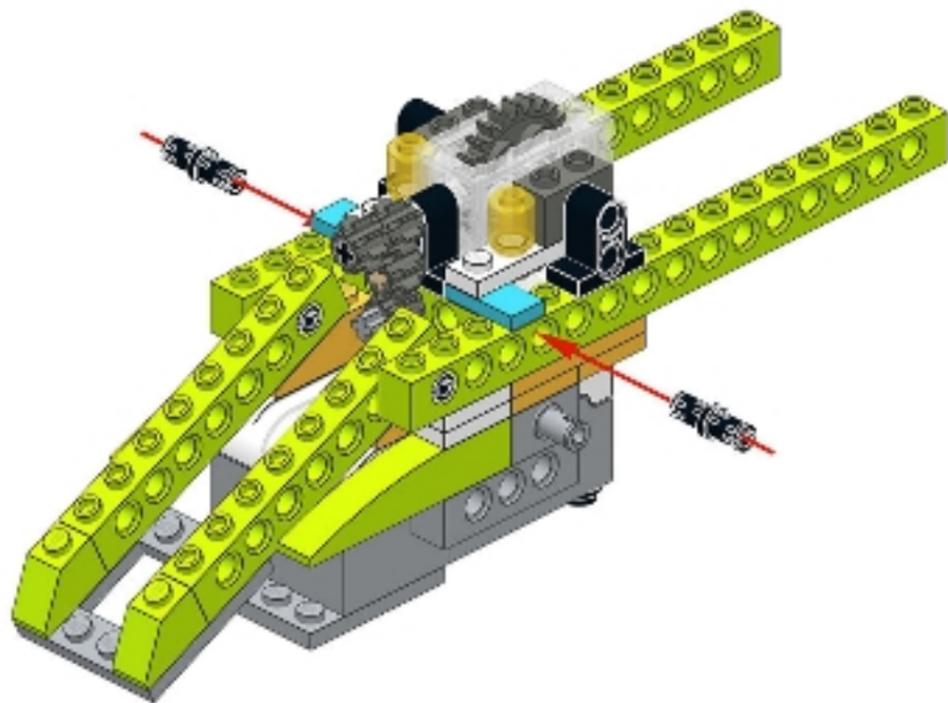
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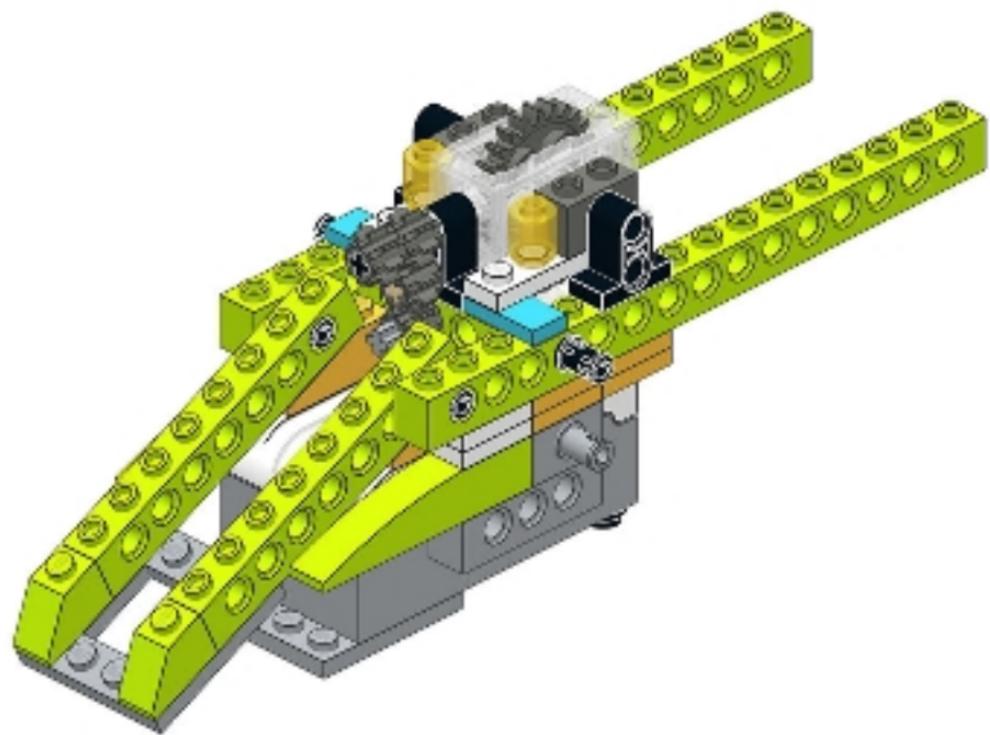


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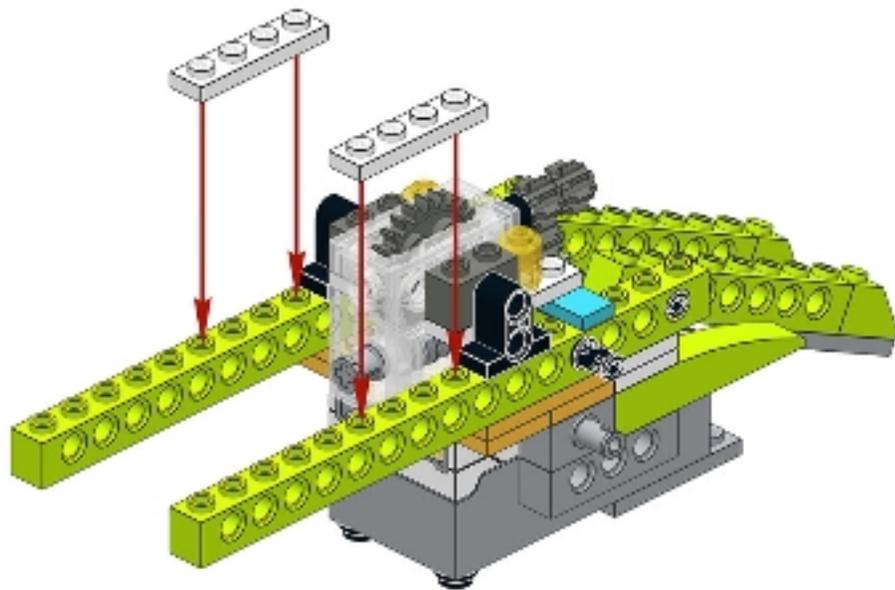


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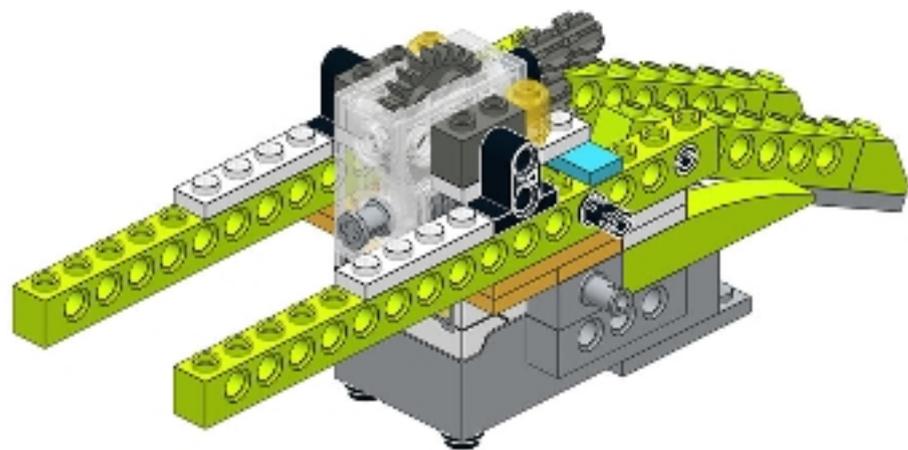




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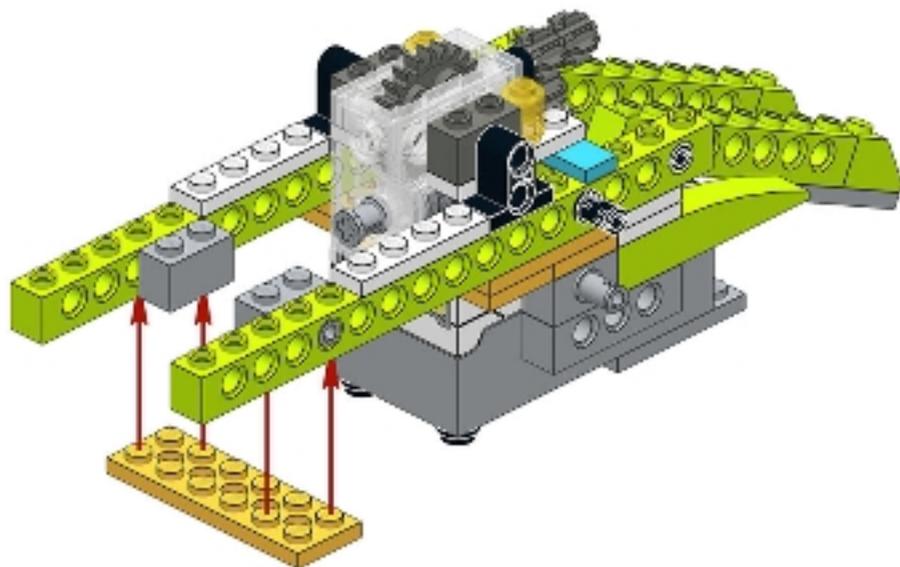


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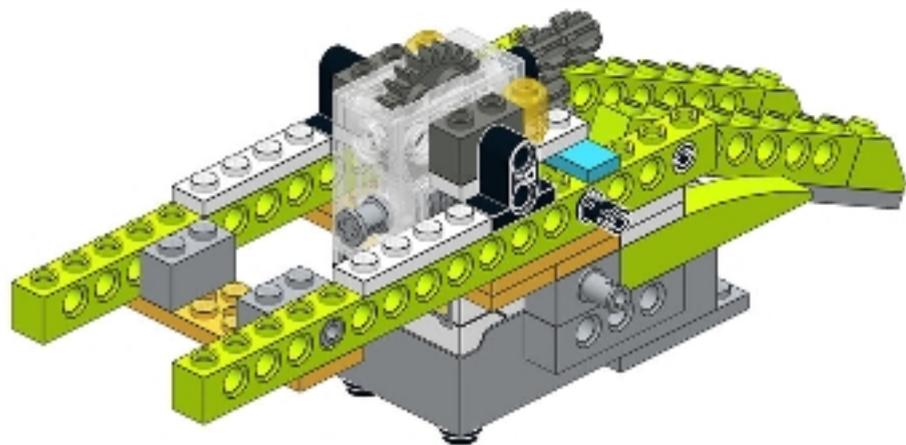


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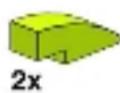
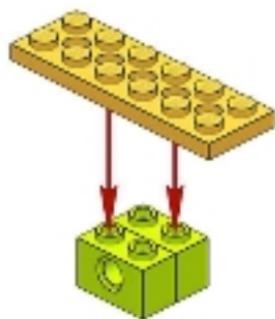


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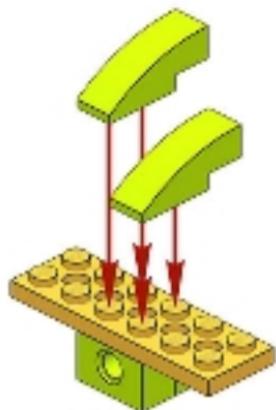




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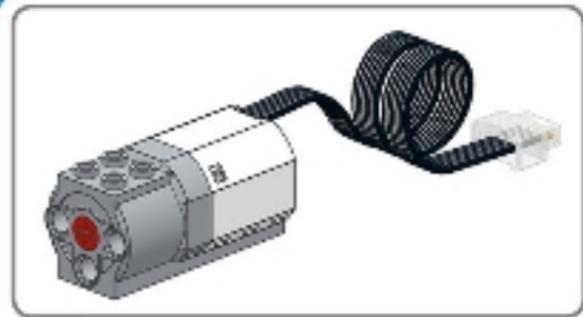


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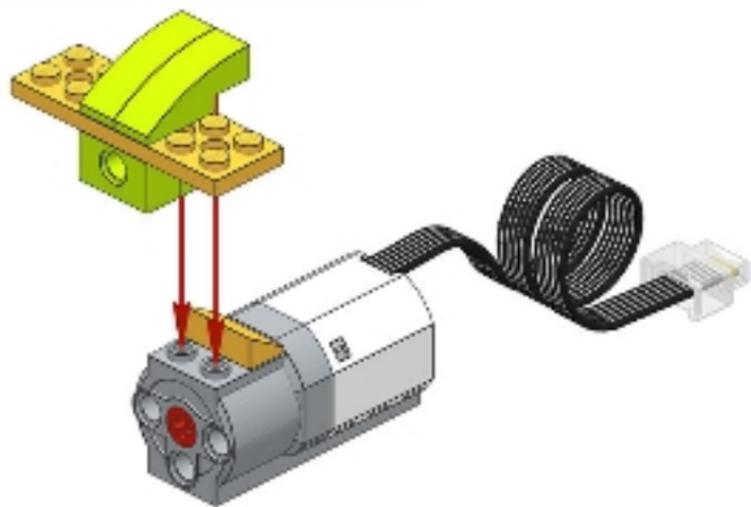


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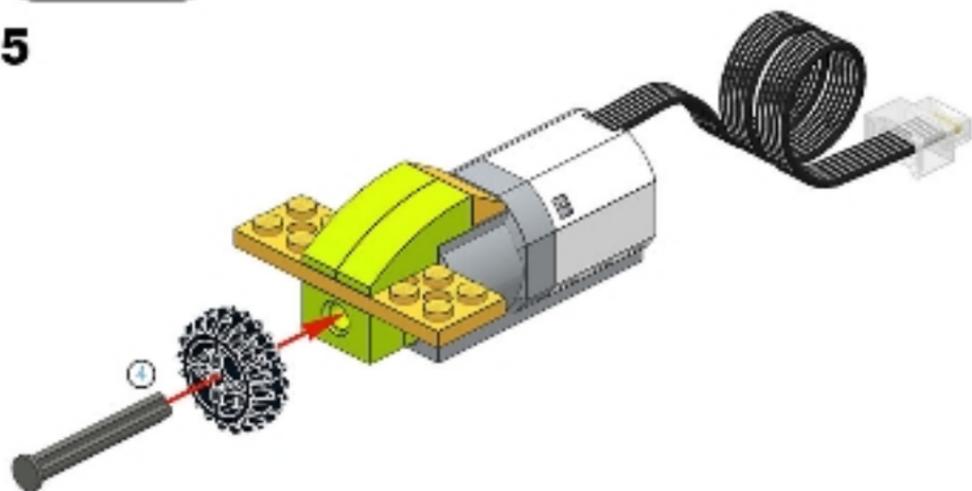




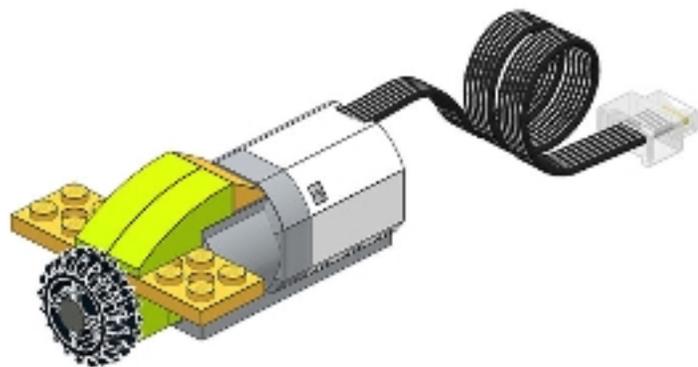
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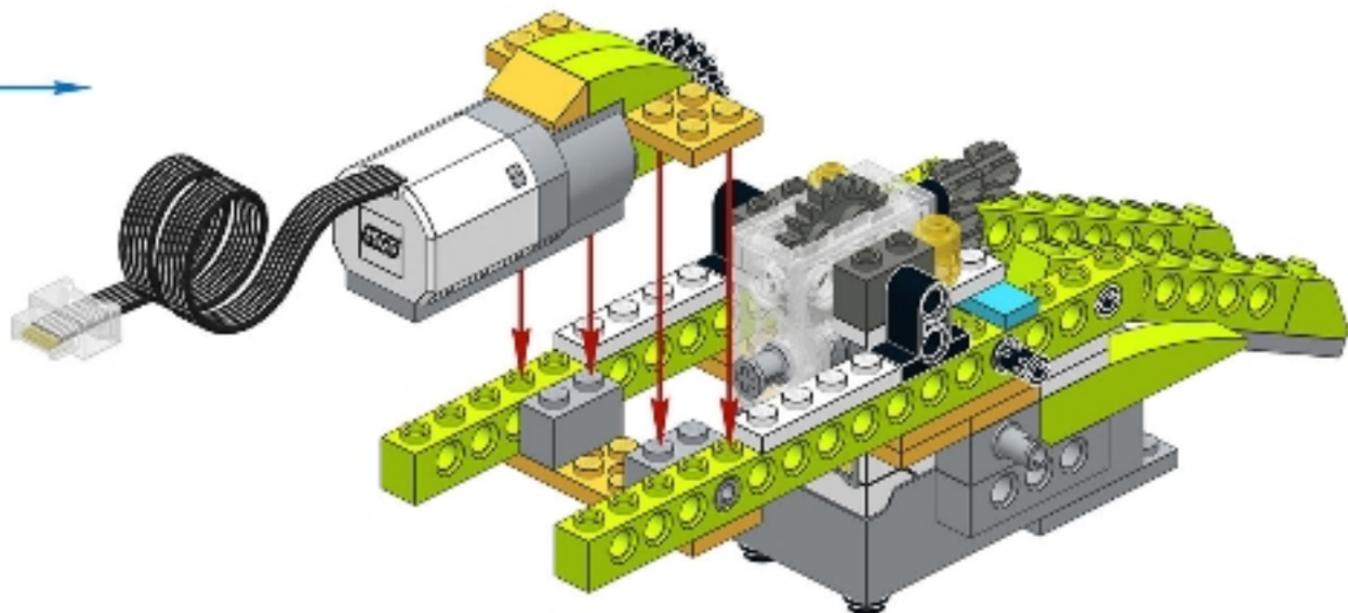
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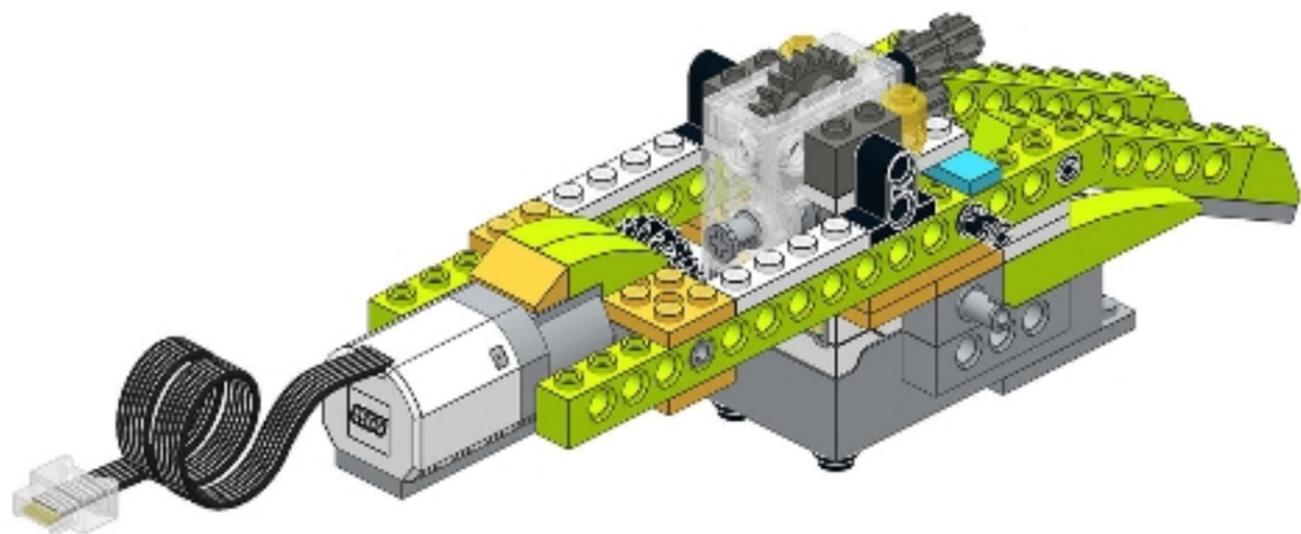
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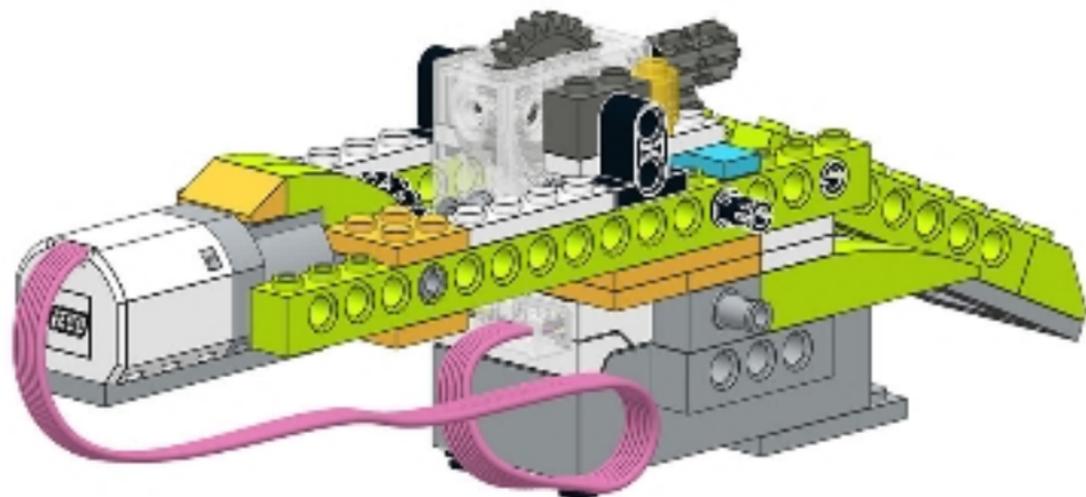
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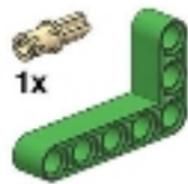


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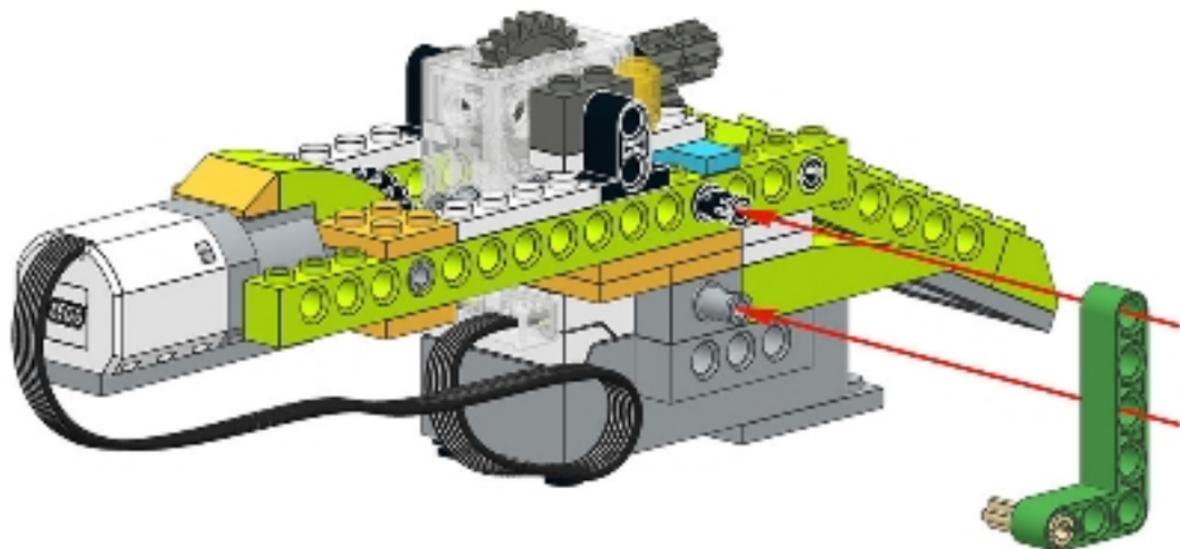


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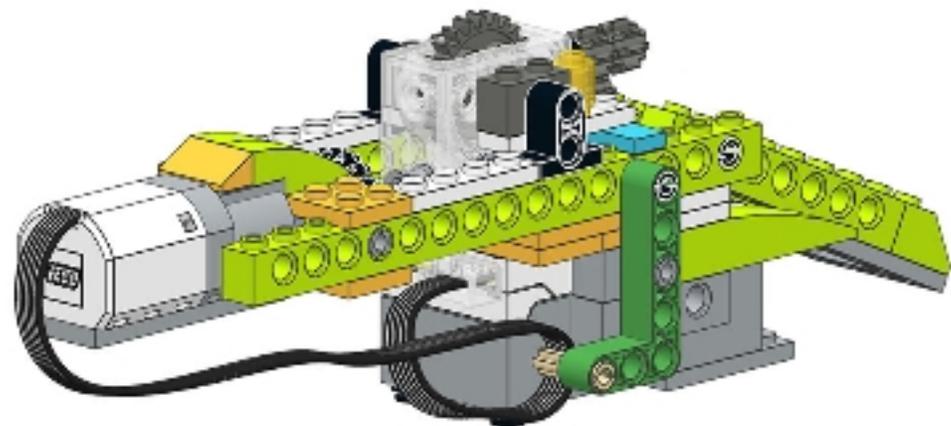


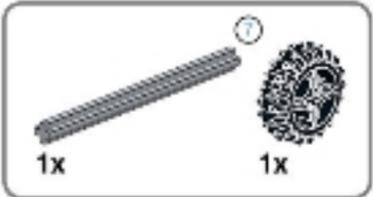
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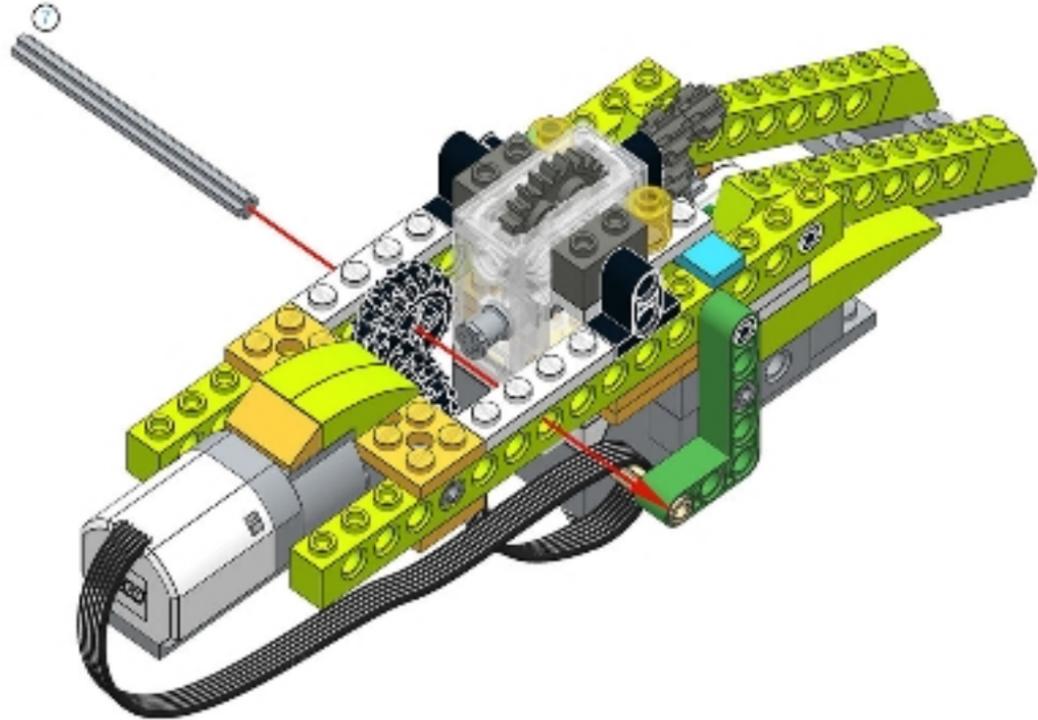


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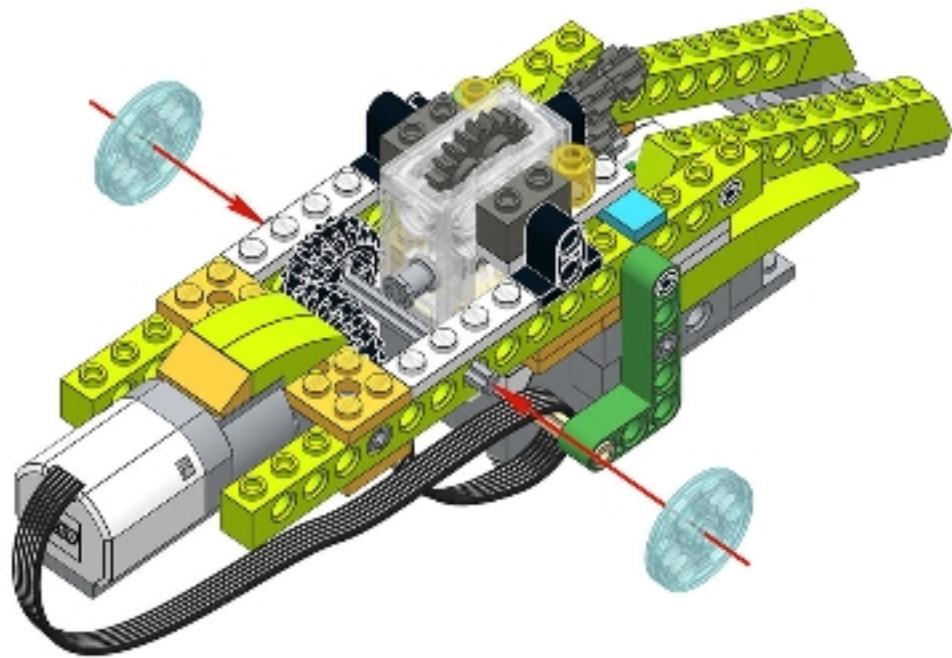
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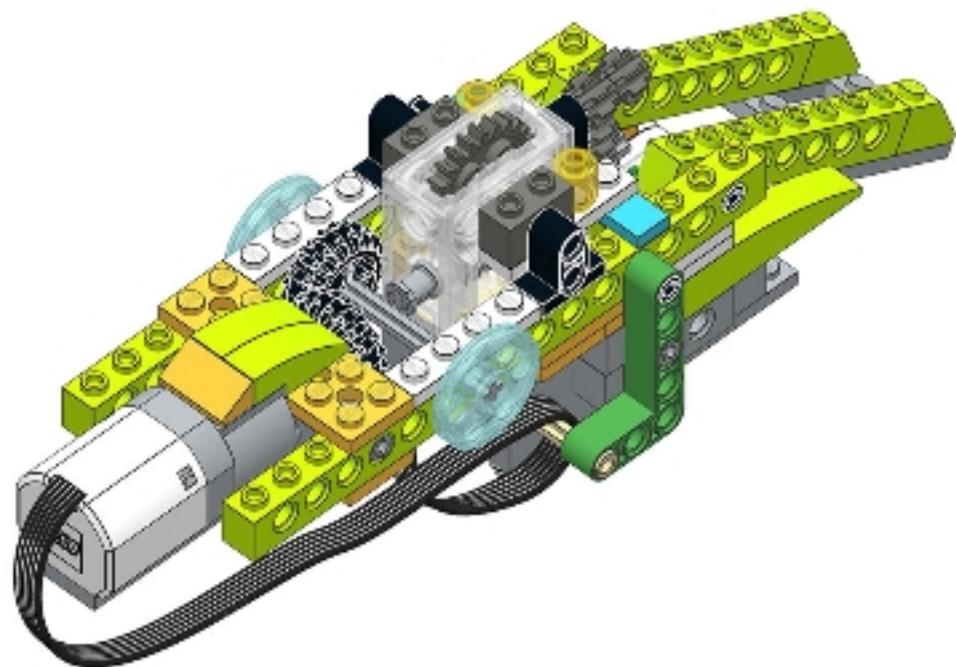


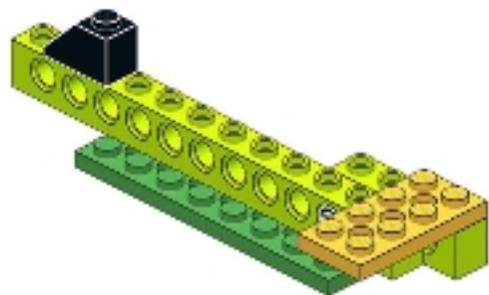
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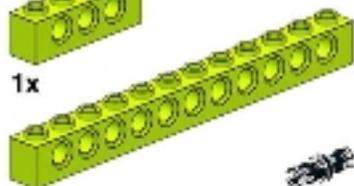


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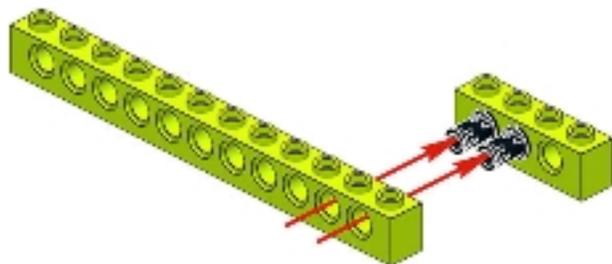


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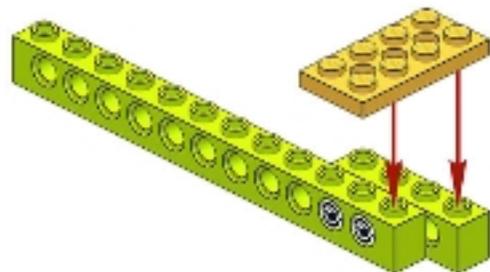
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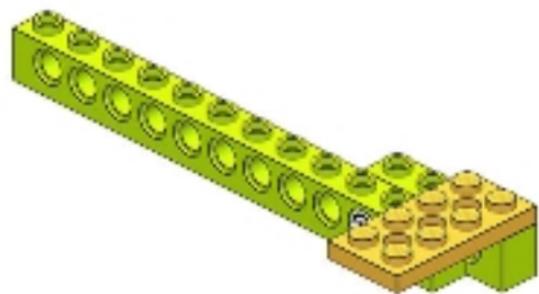


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44



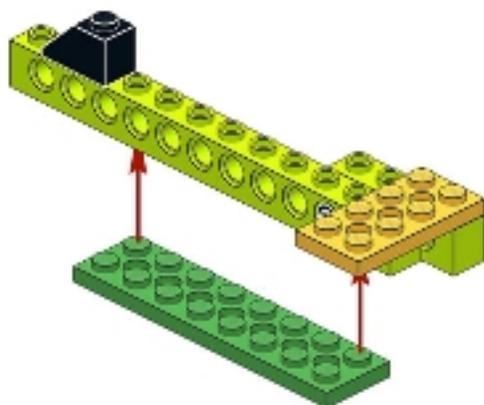


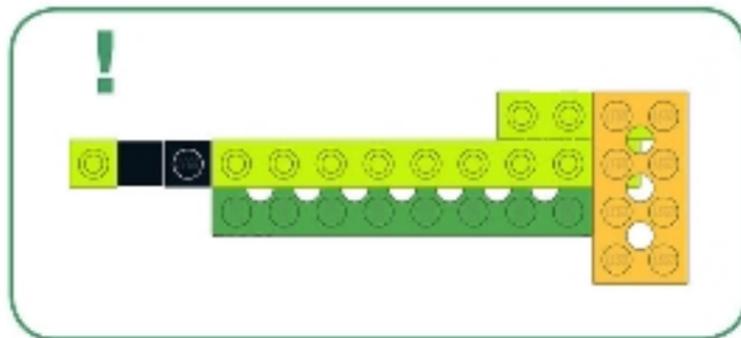
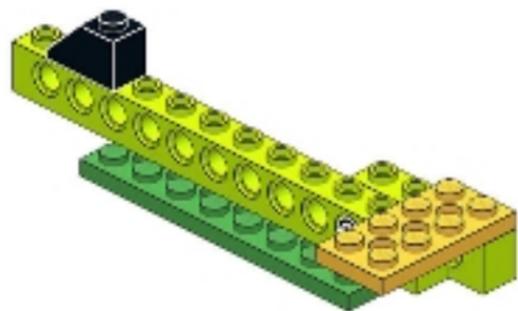
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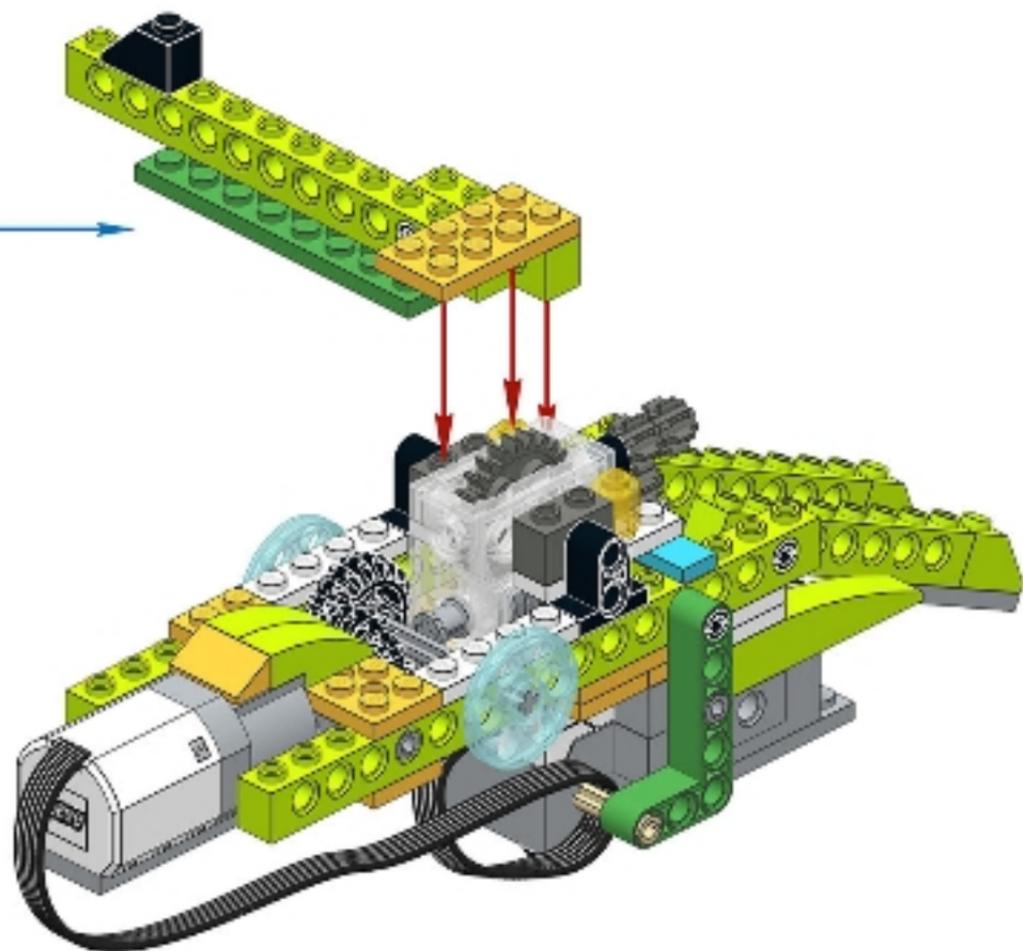
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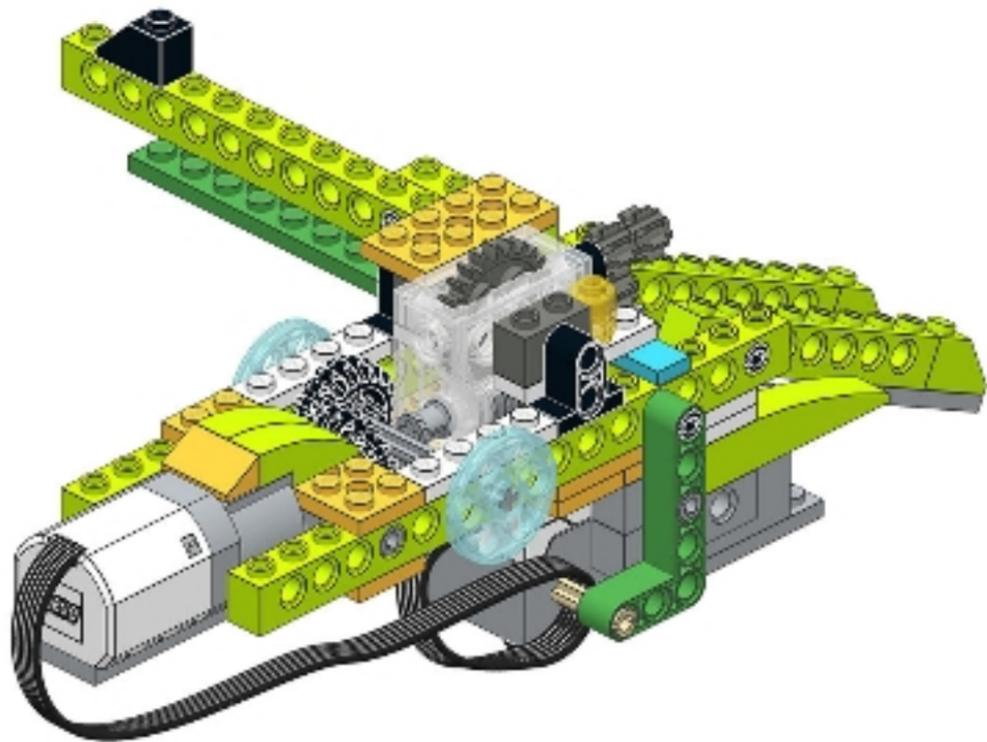


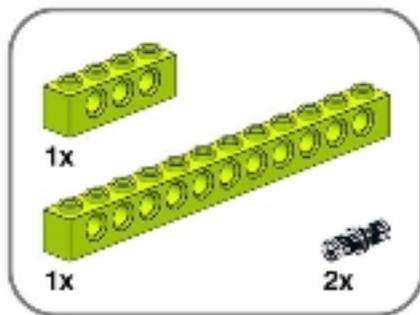
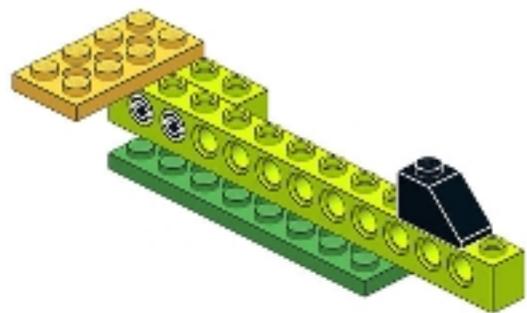


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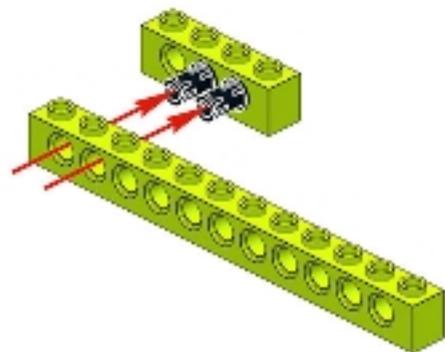


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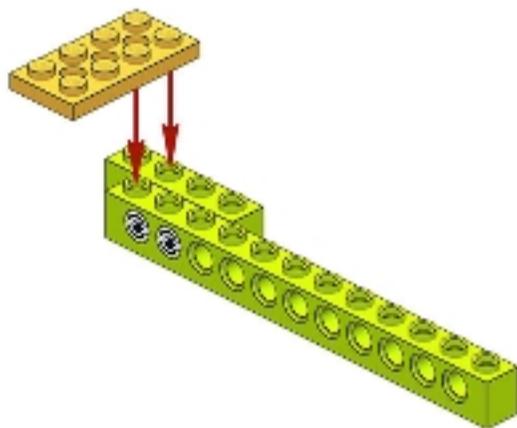
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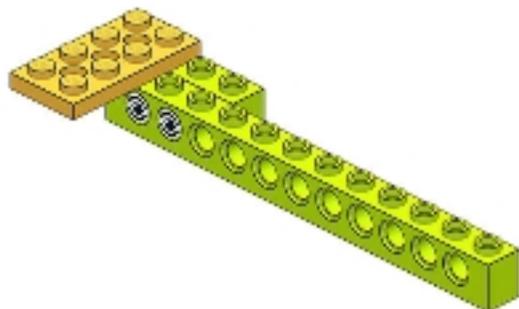


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50



51



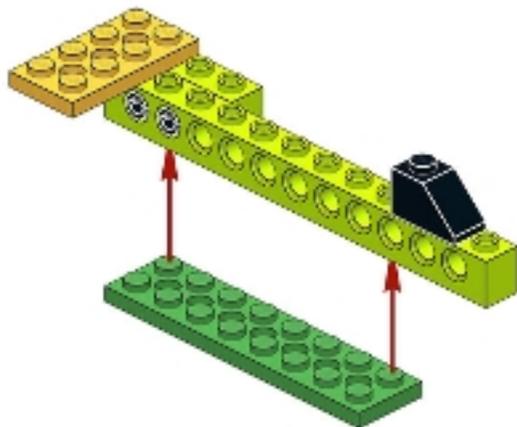


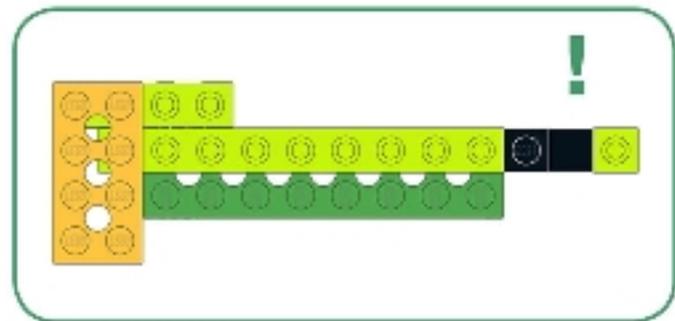
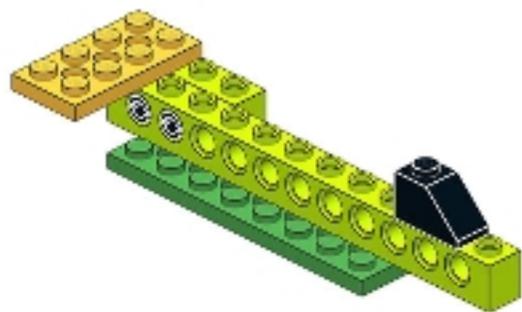
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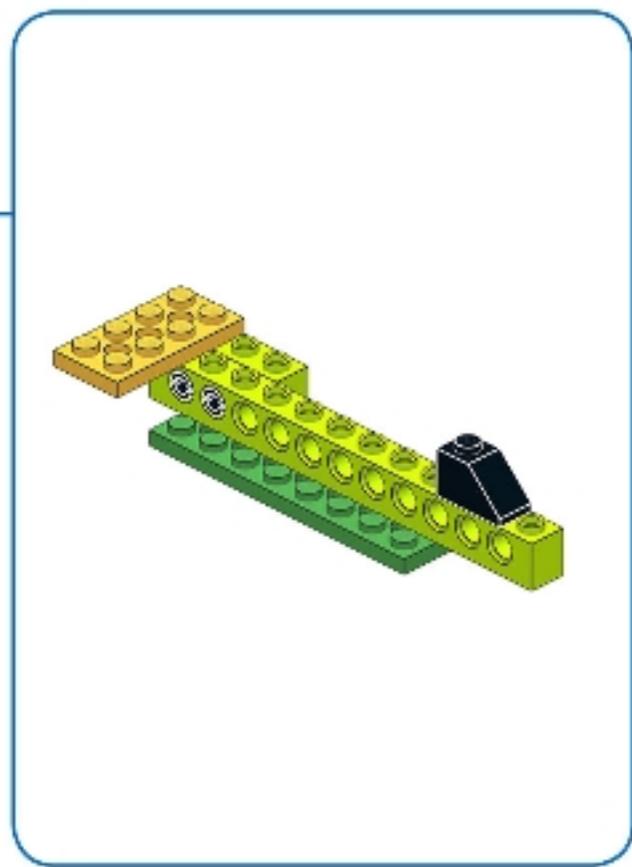
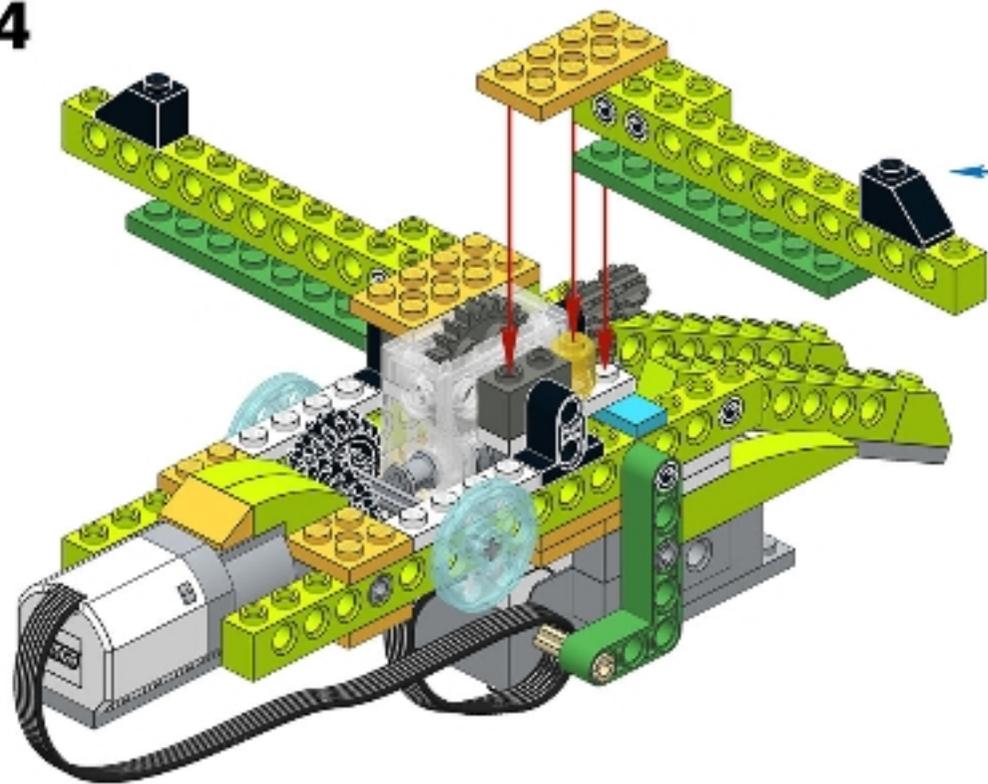
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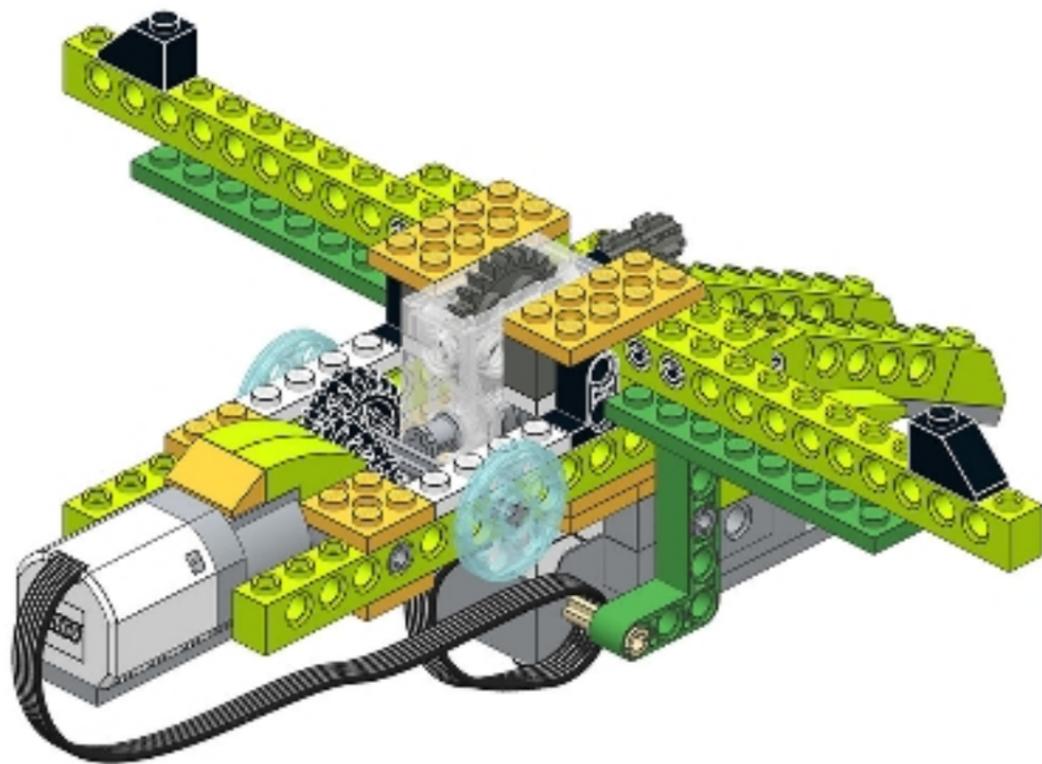




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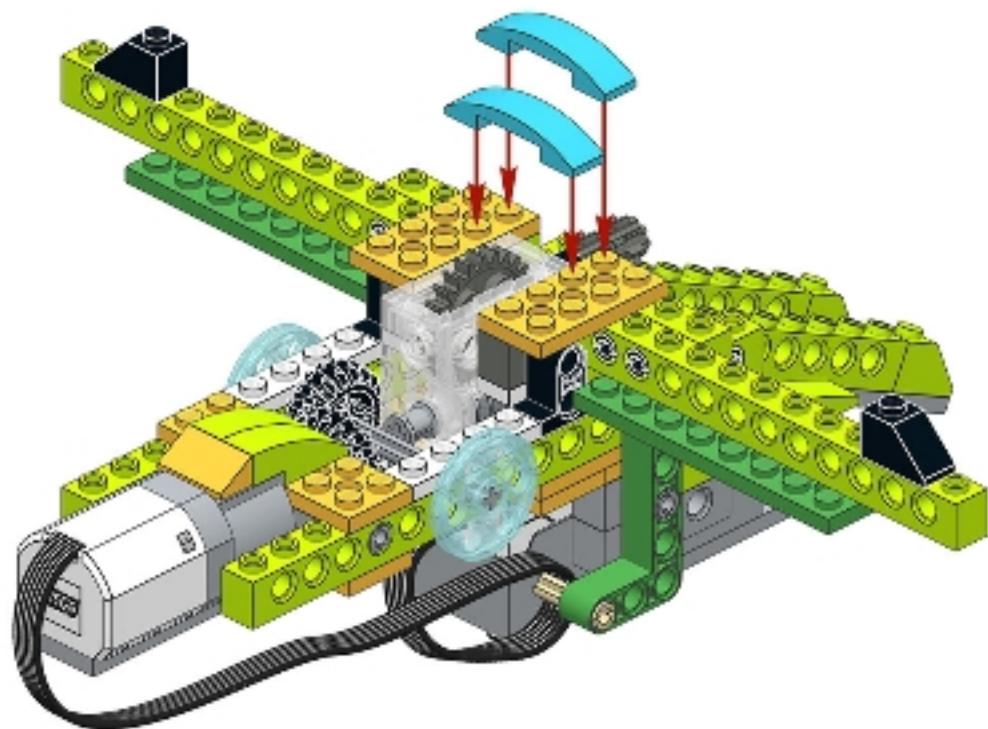
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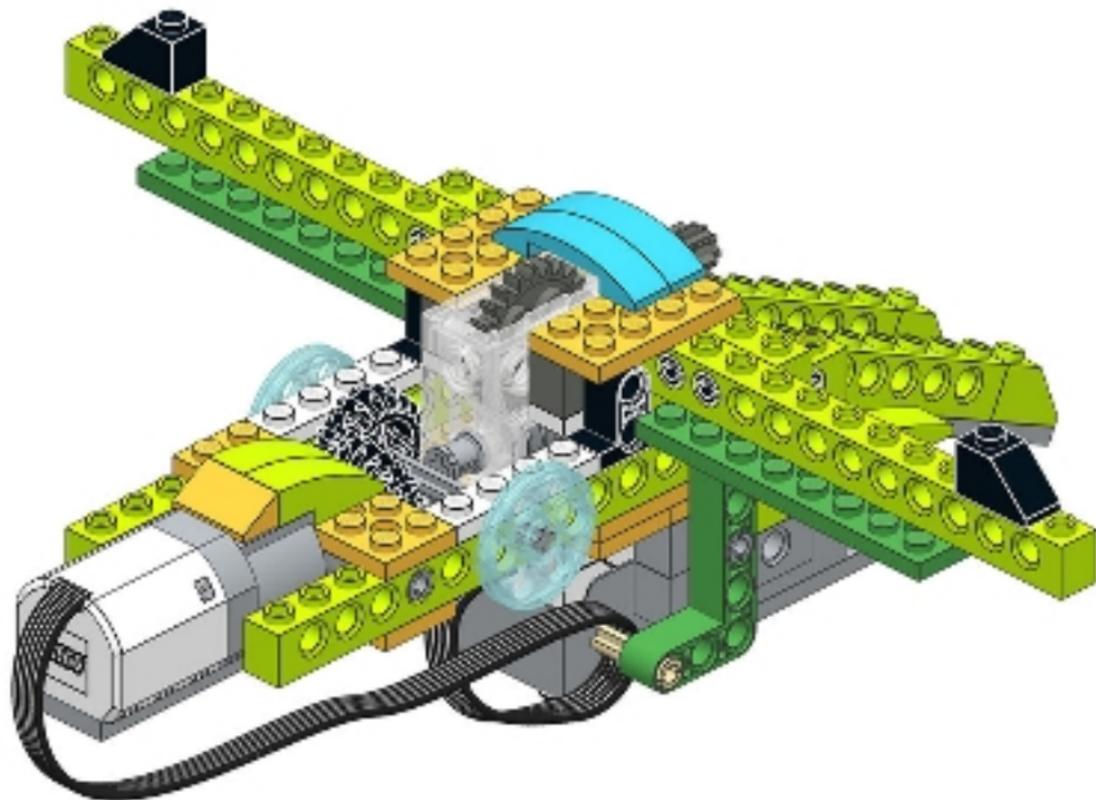


2x

56



57





1x



1x

1x



1x

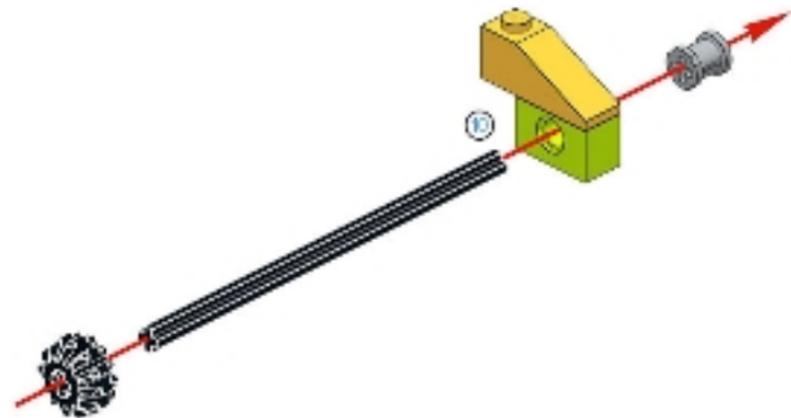


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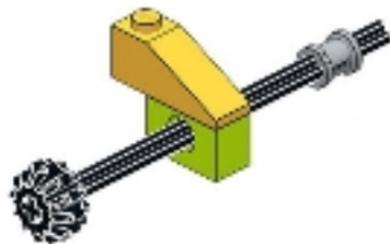


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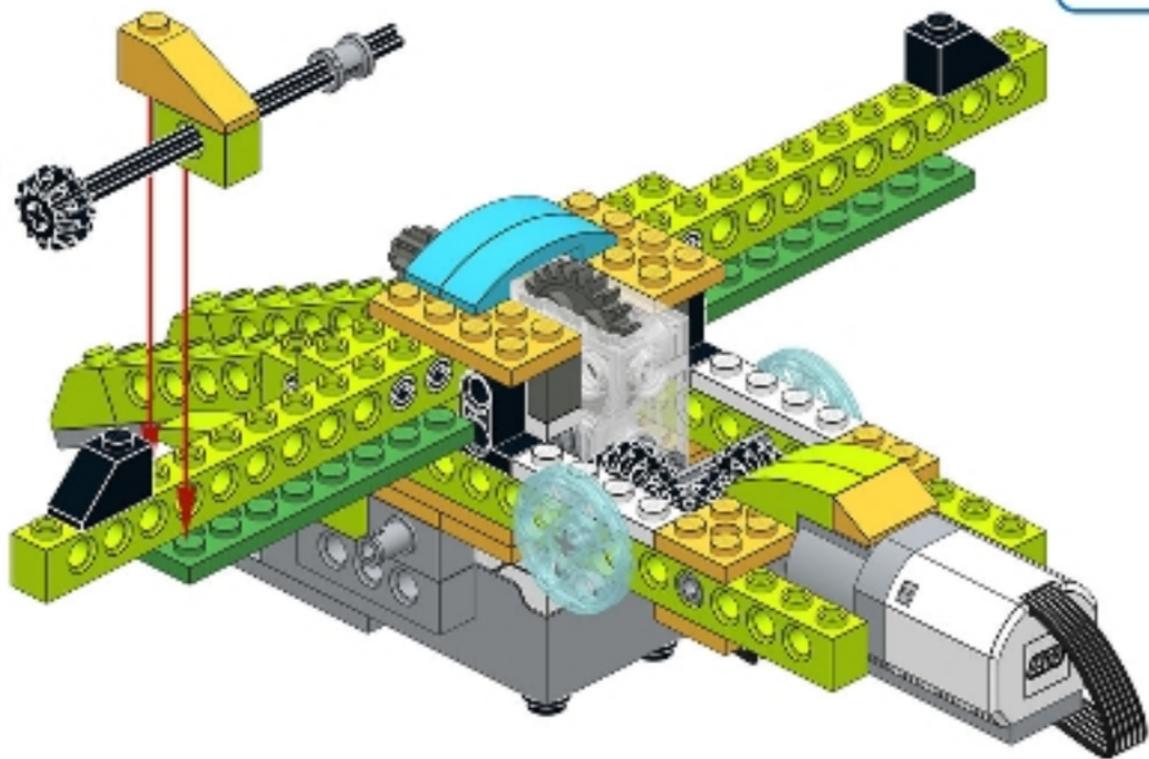
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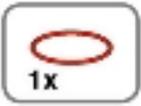


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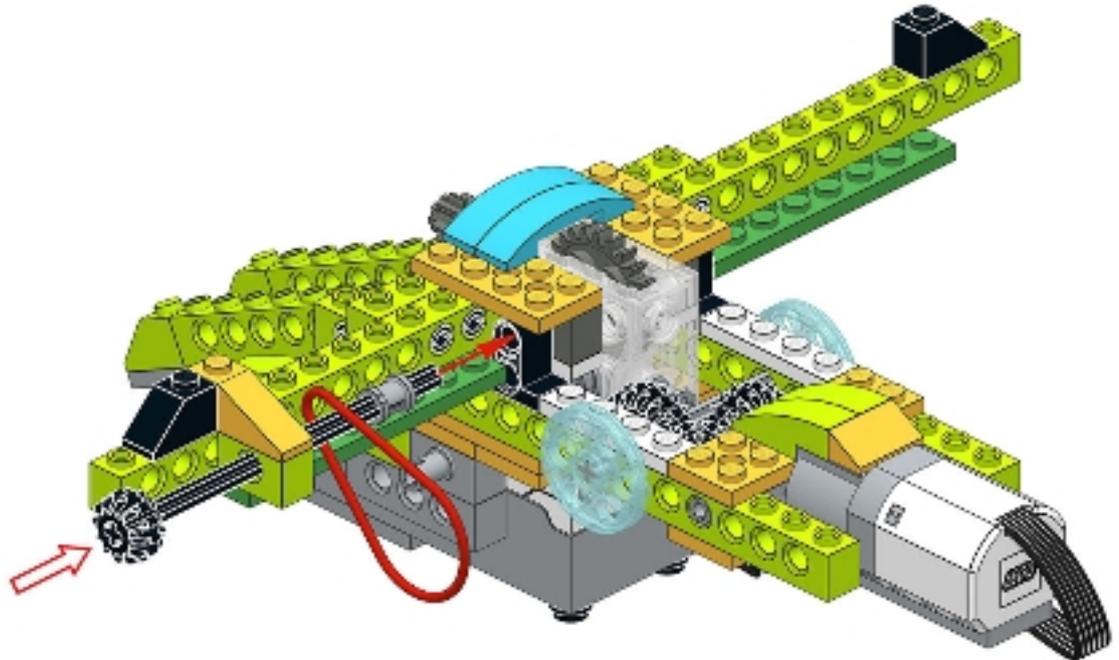


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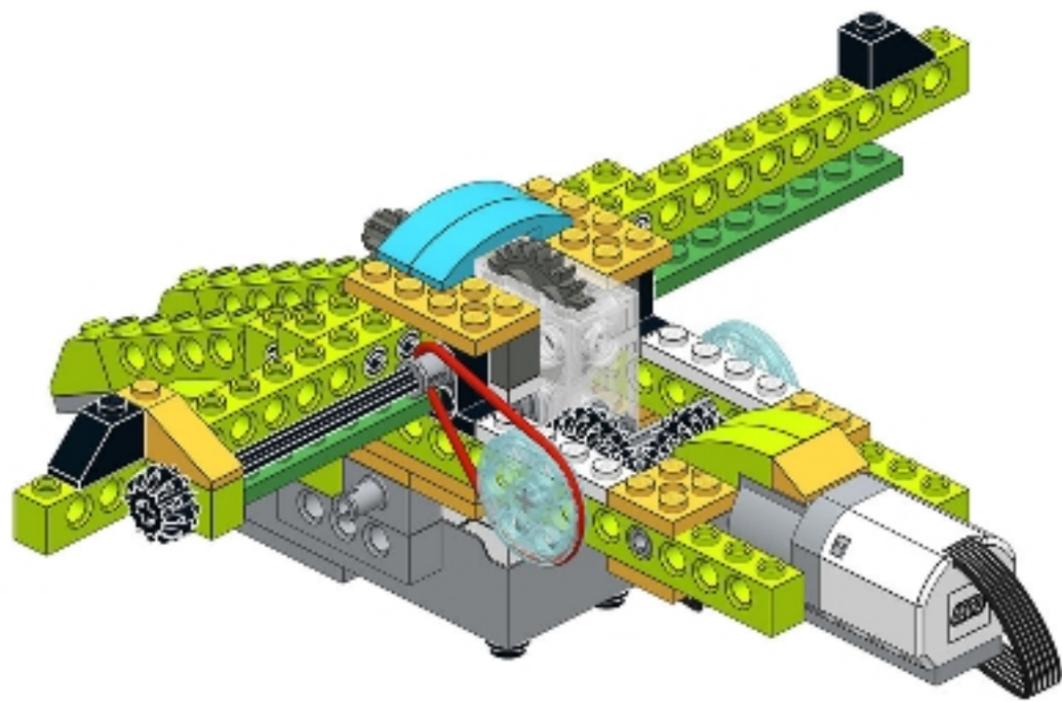


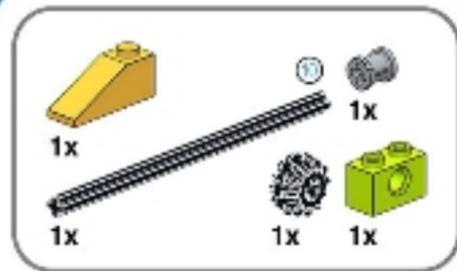


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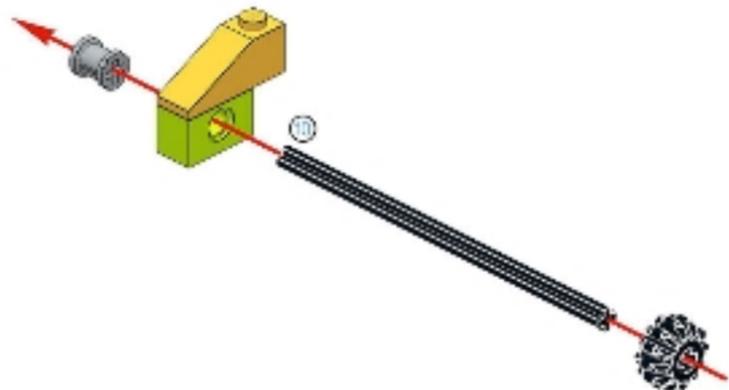


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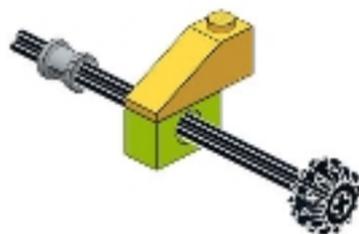




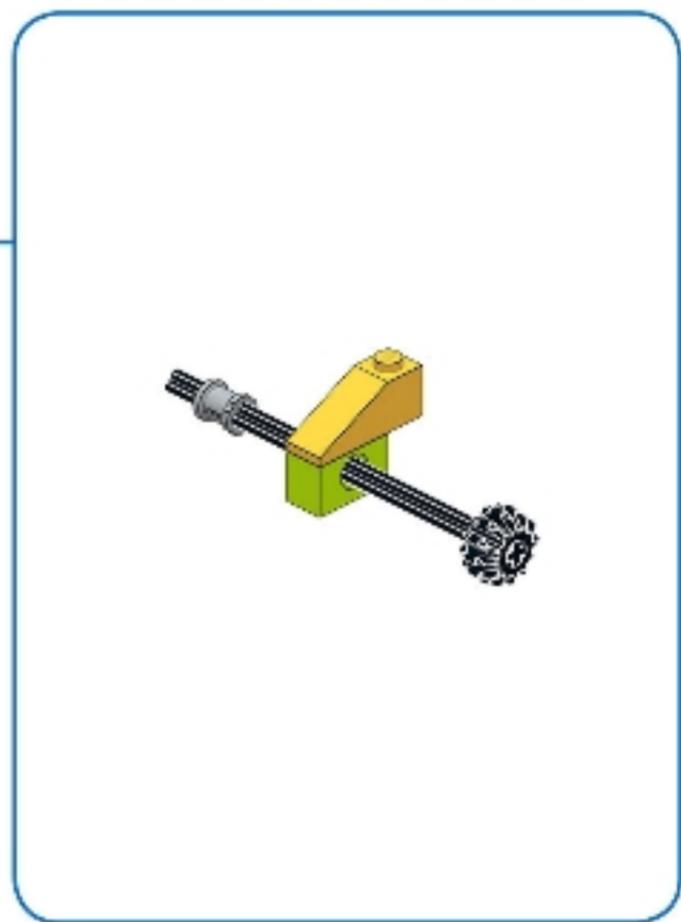
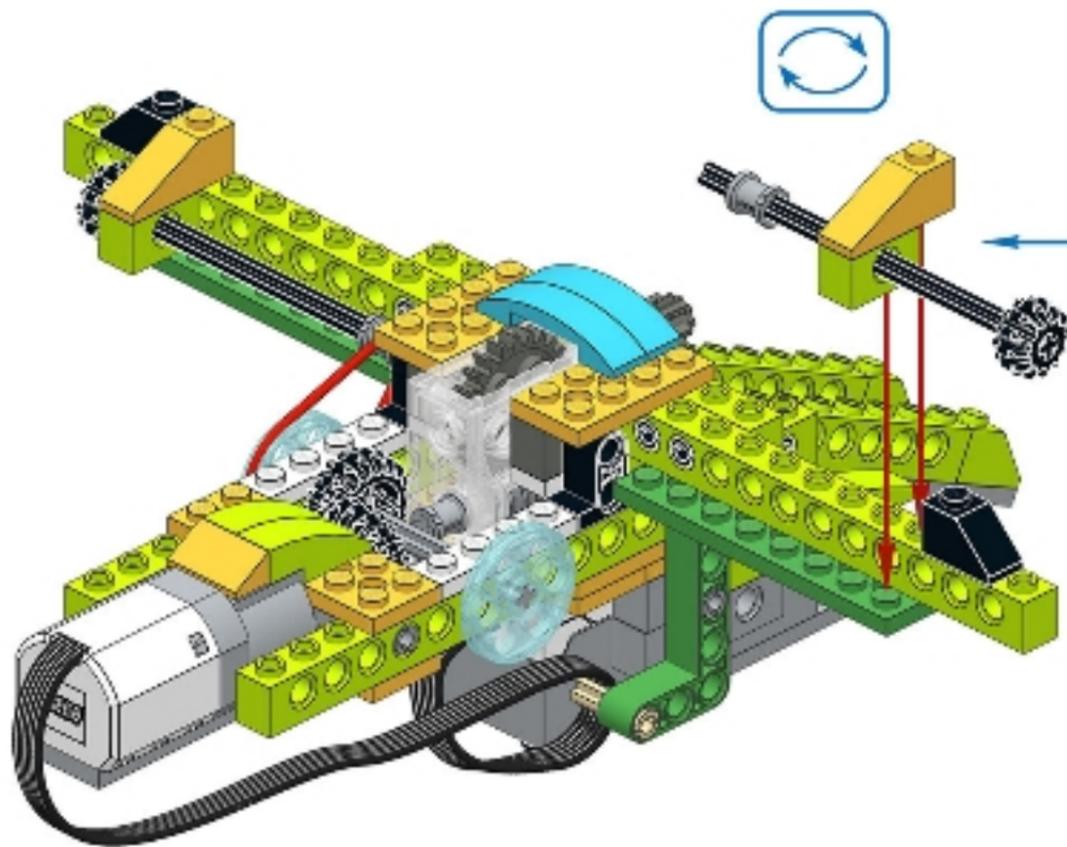
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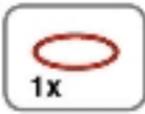


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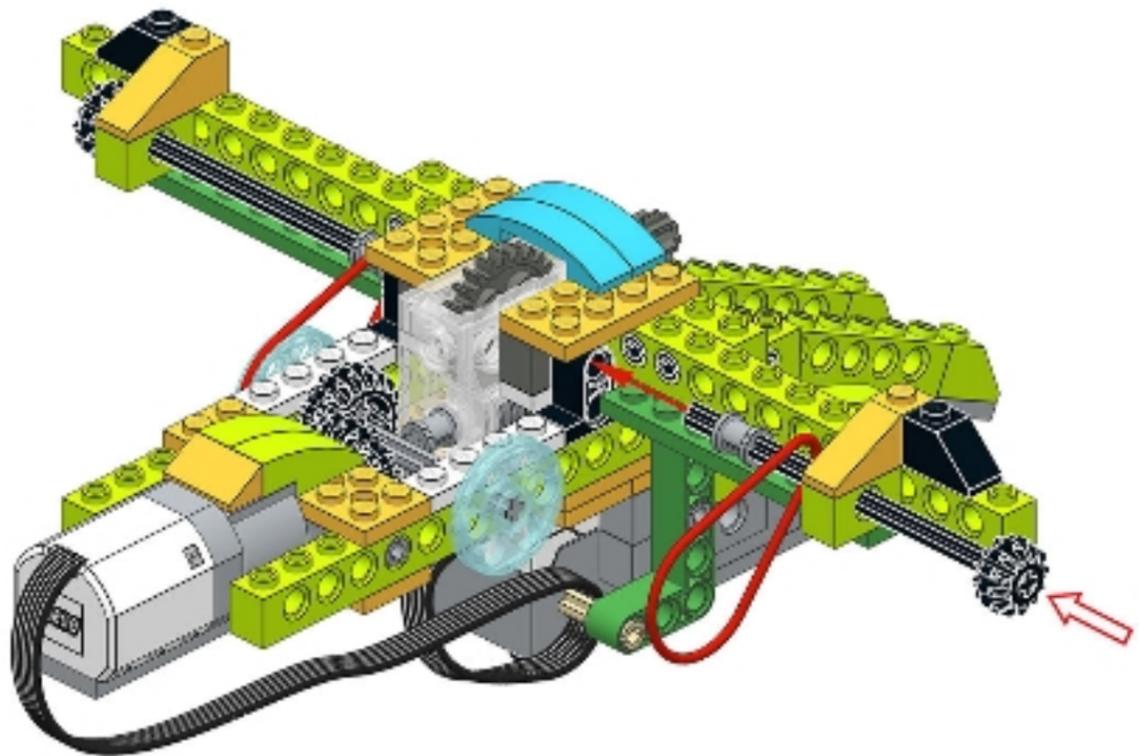


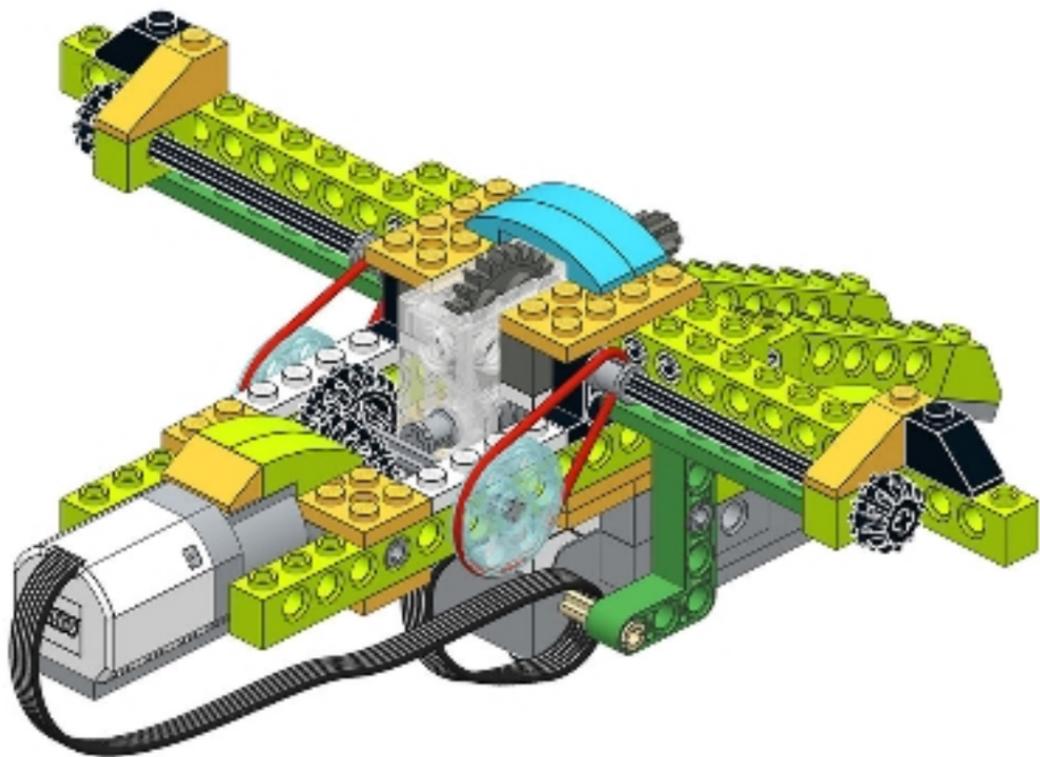
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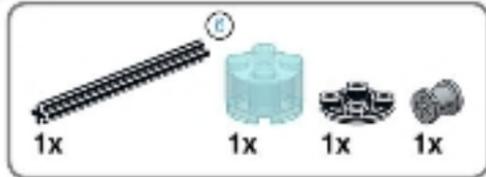




64







1



2

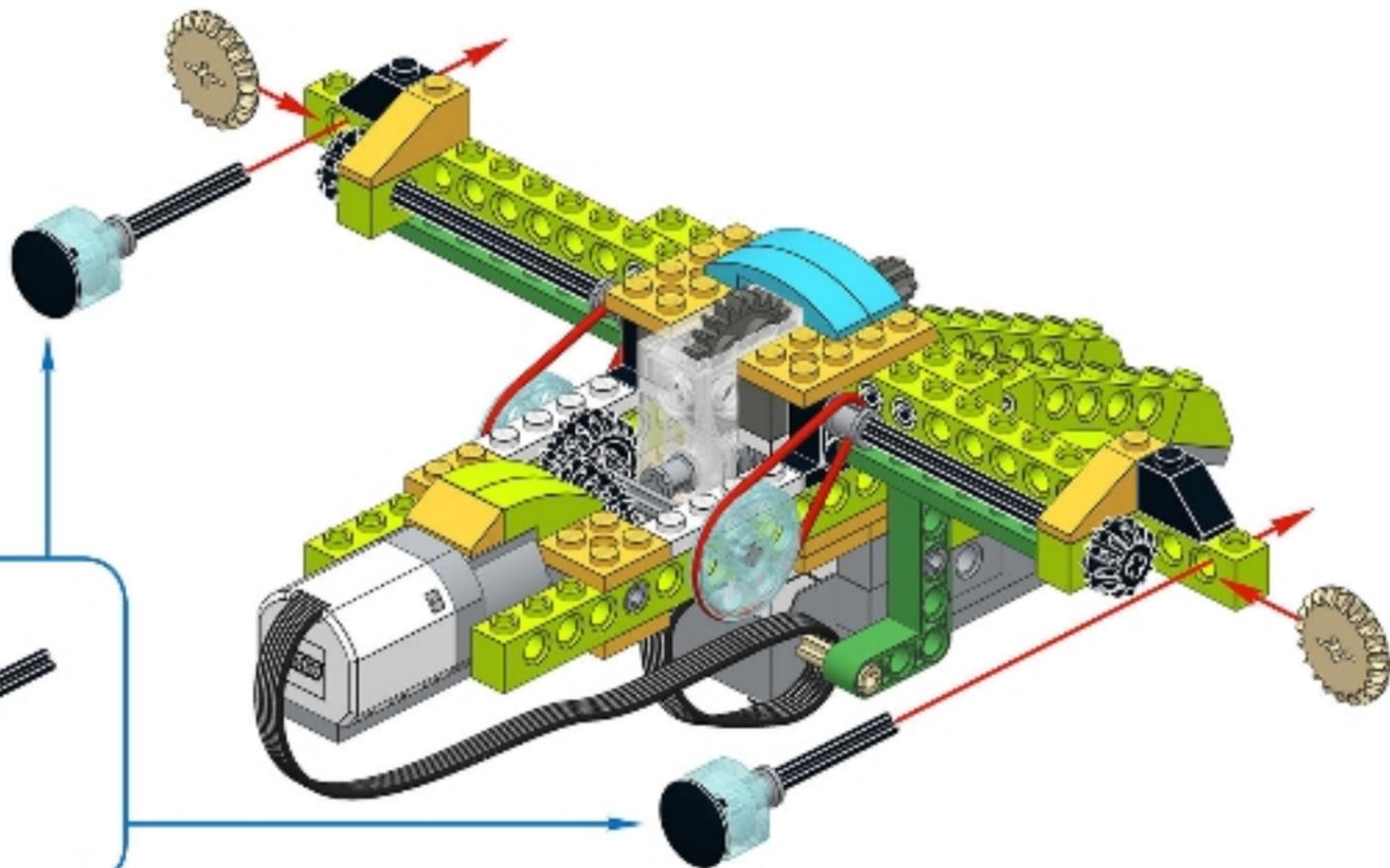


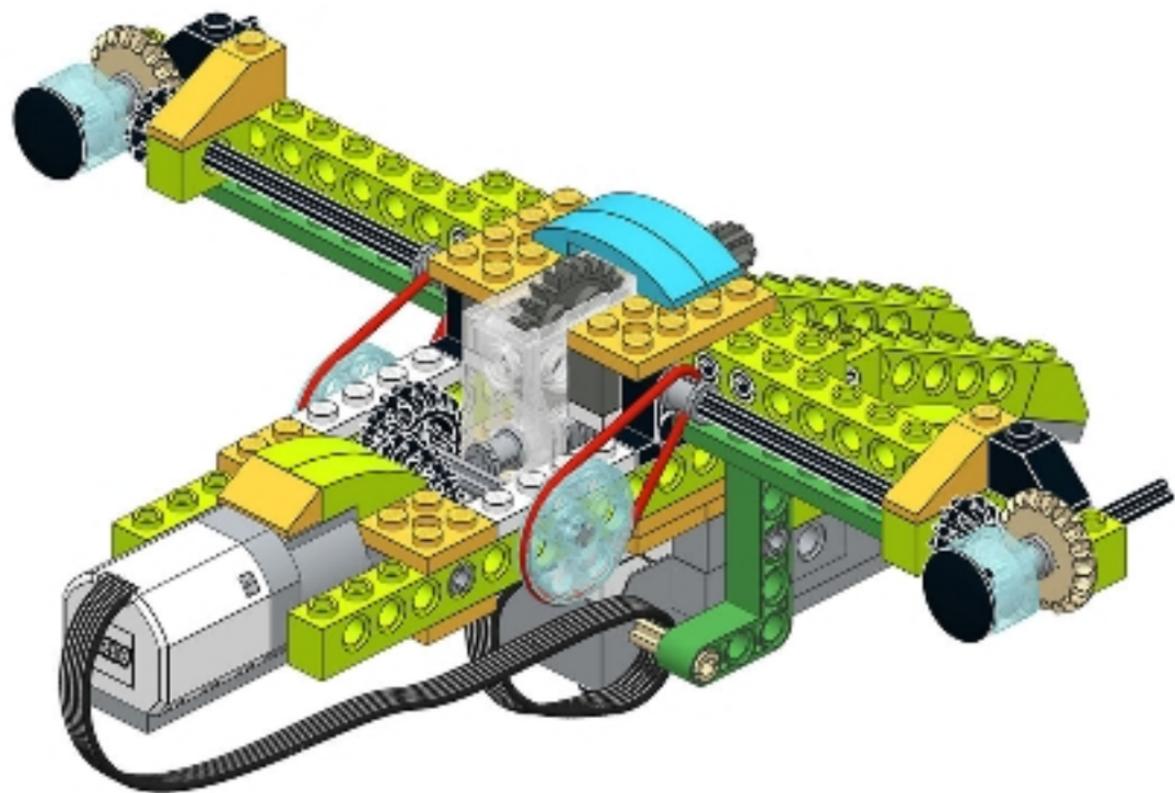
2x



2x

67



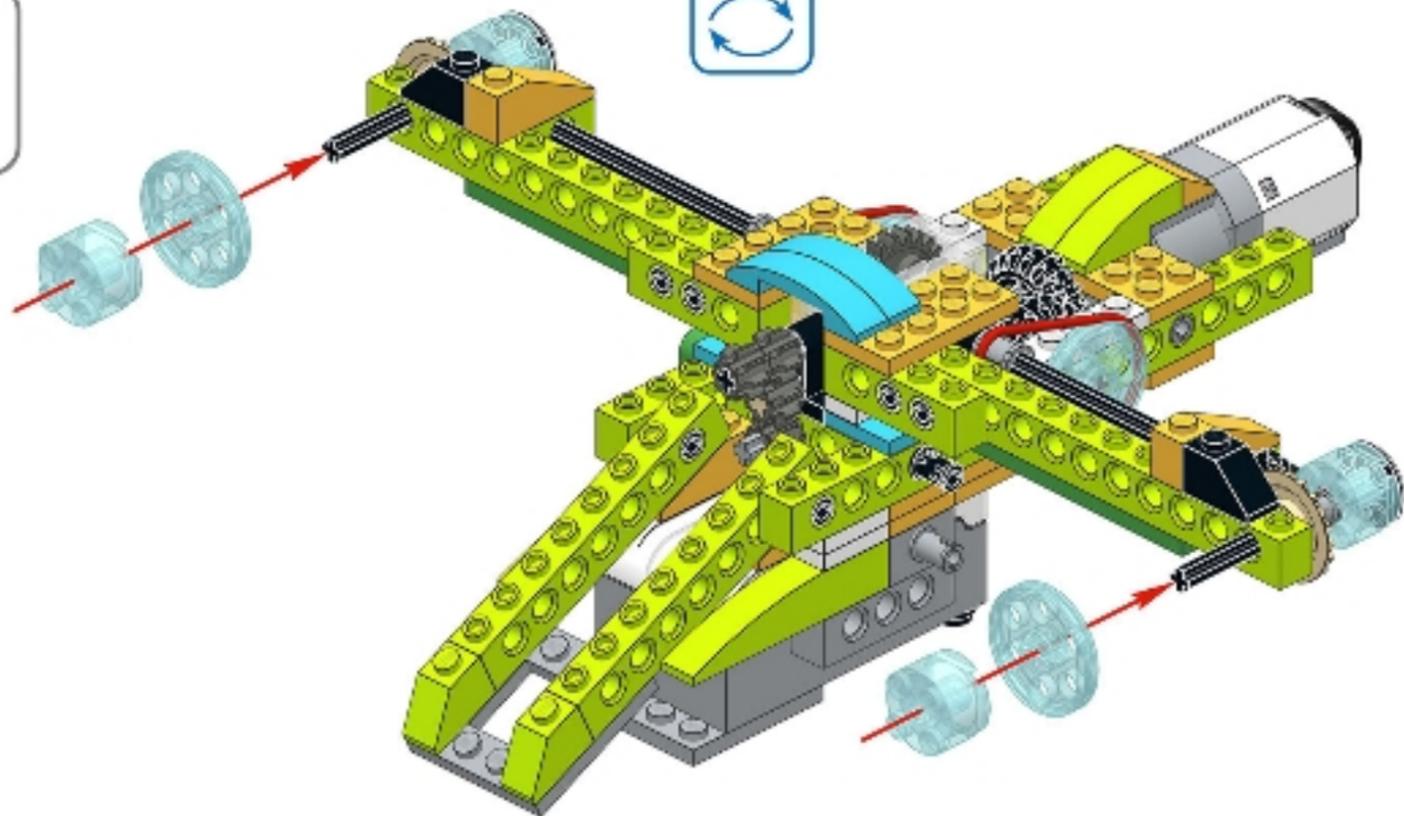




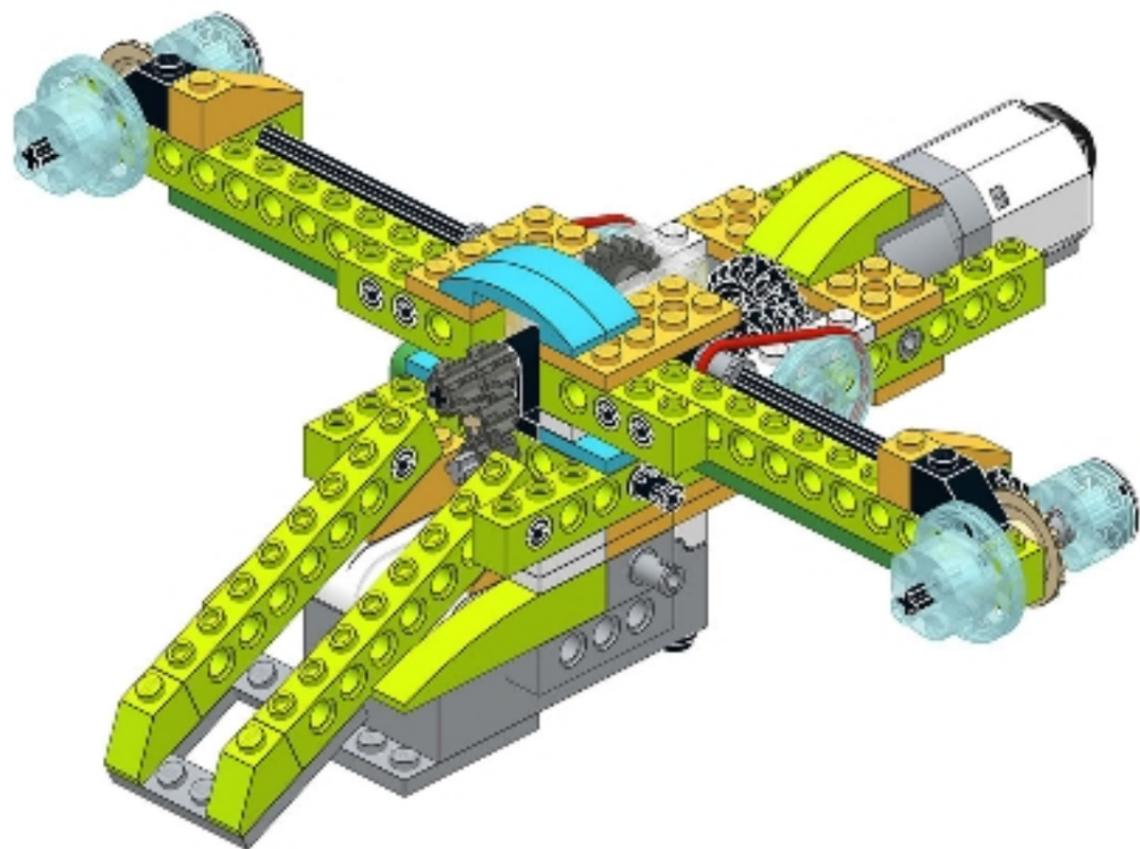
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2x

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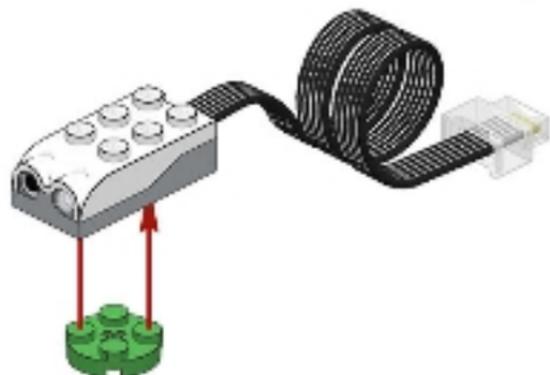
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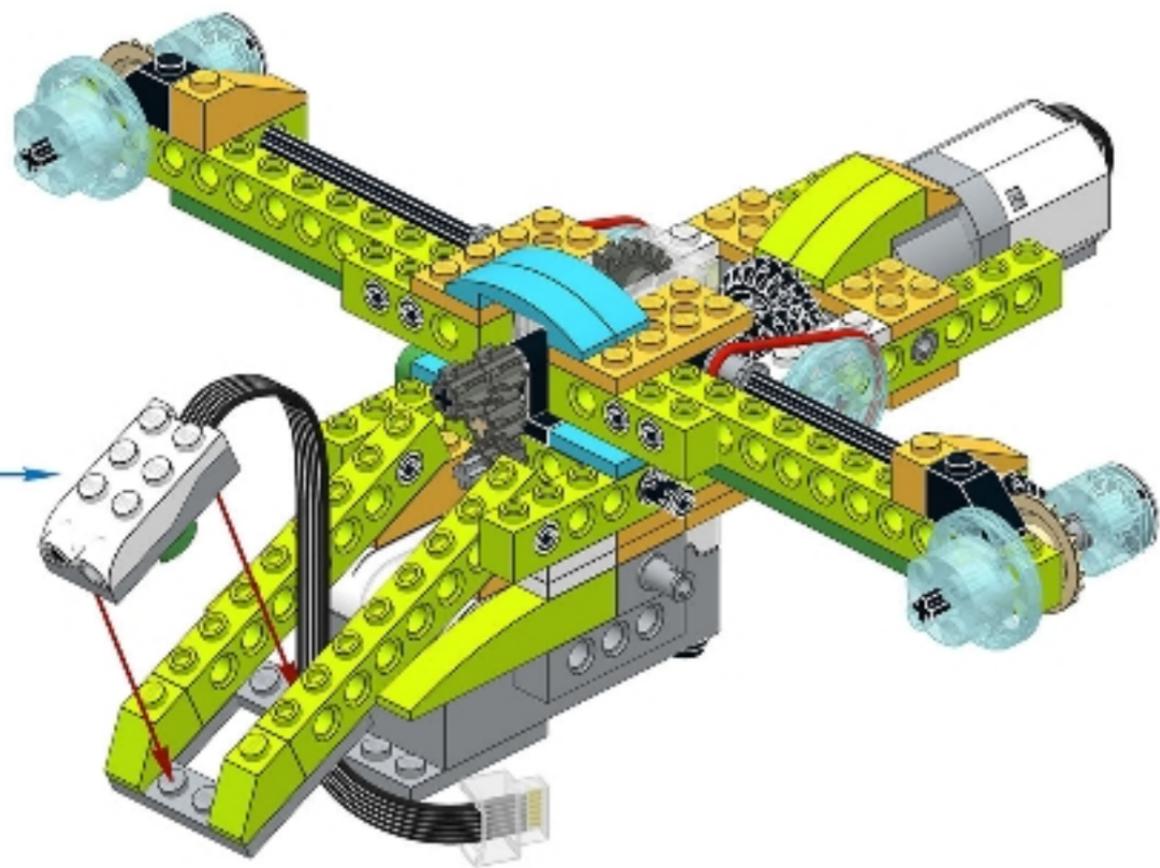
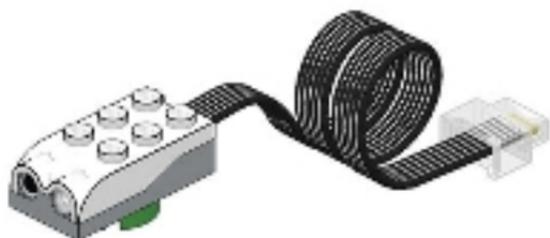


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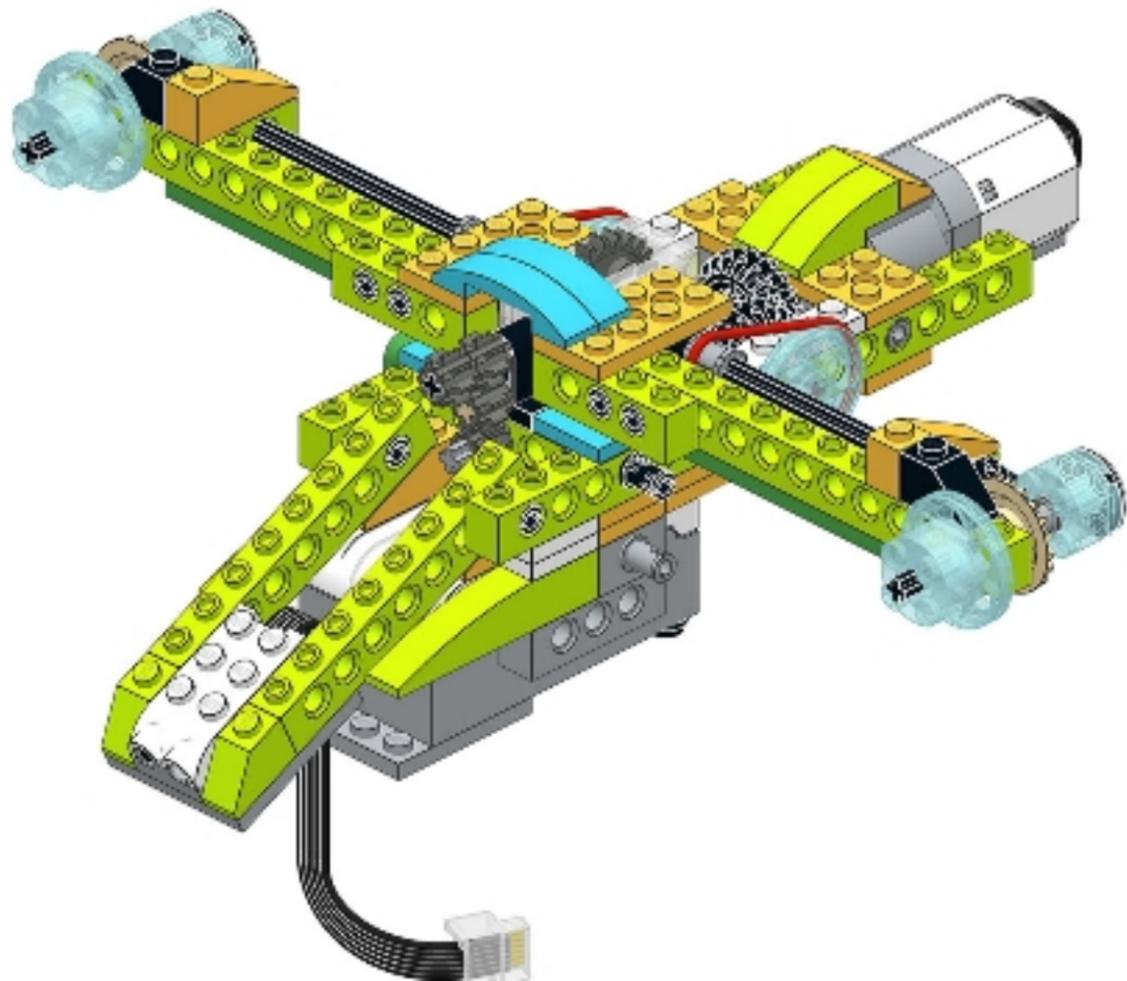
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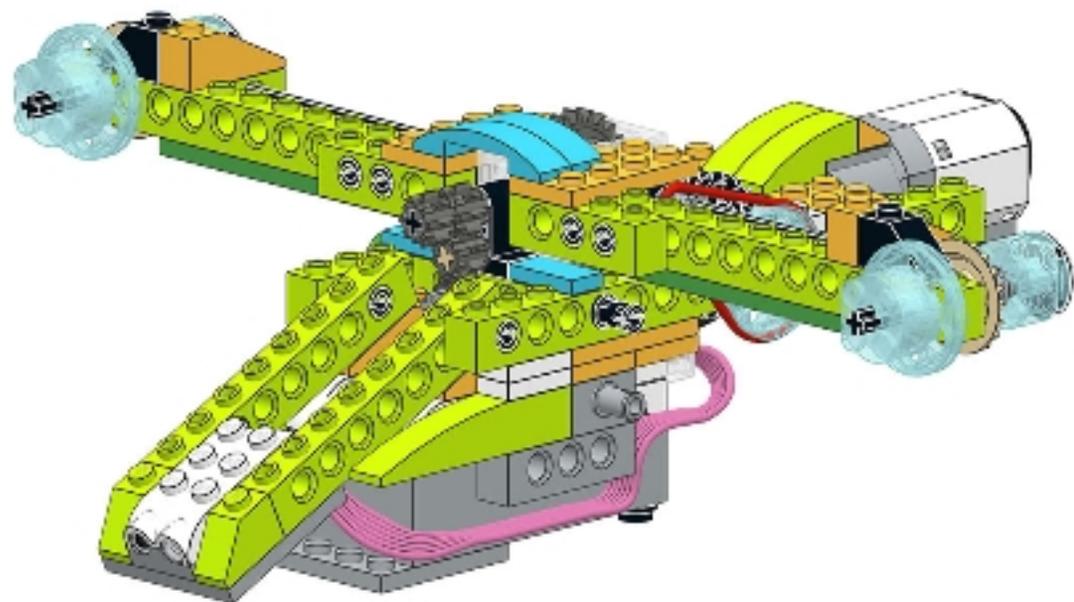
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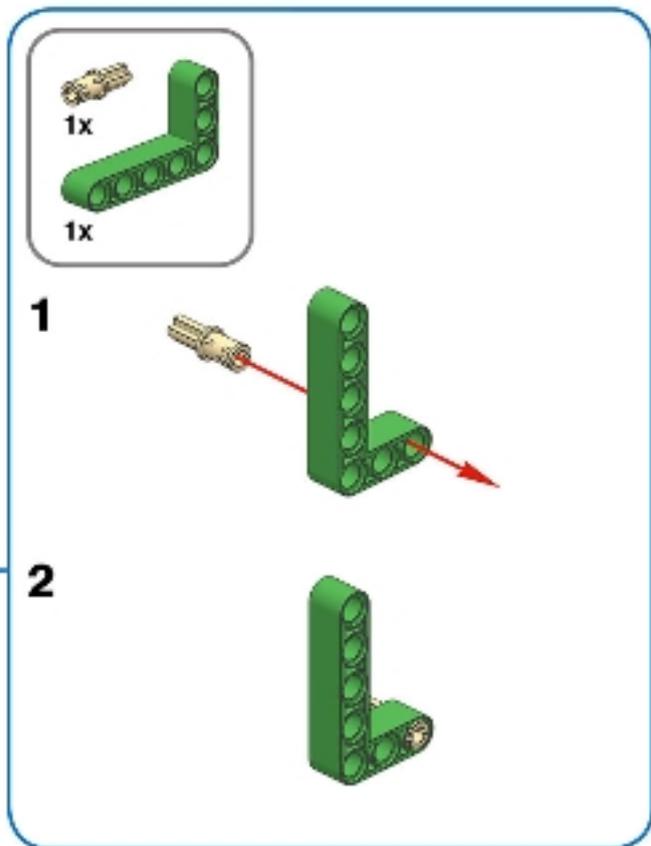
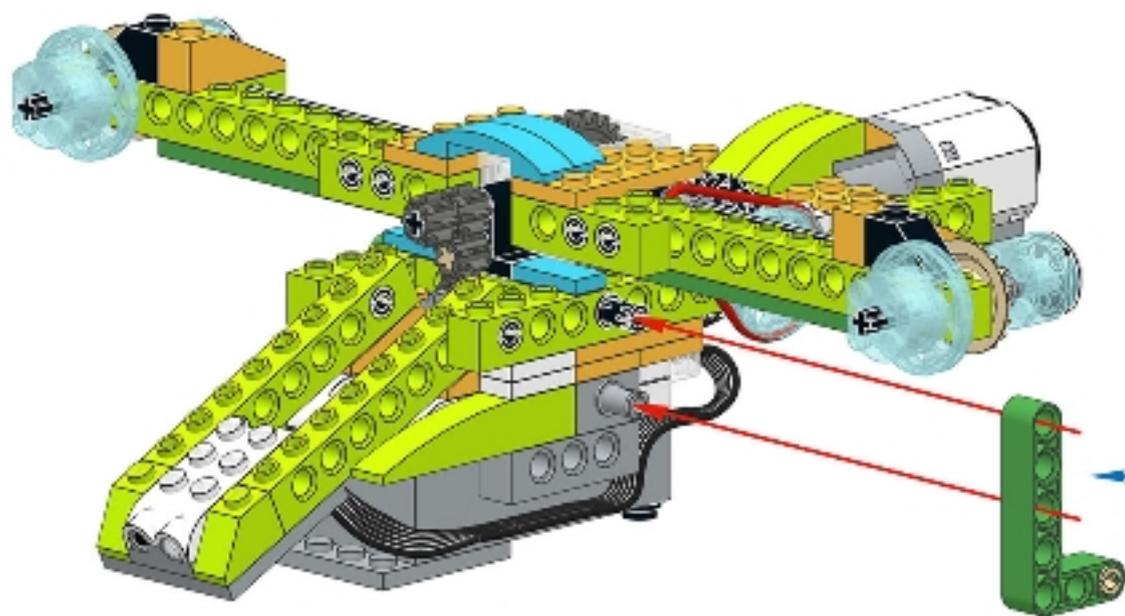
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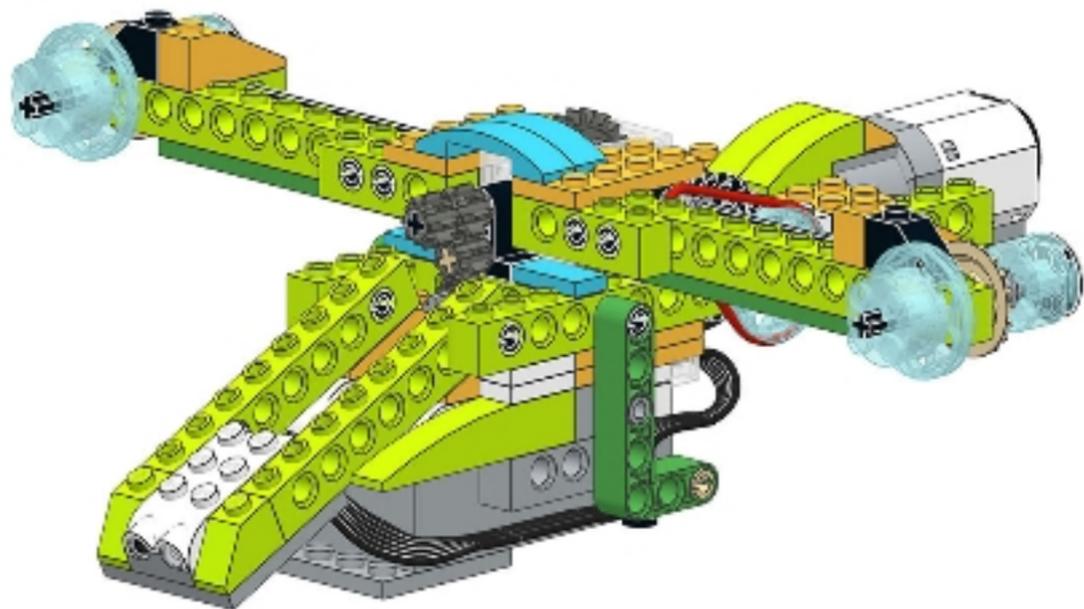
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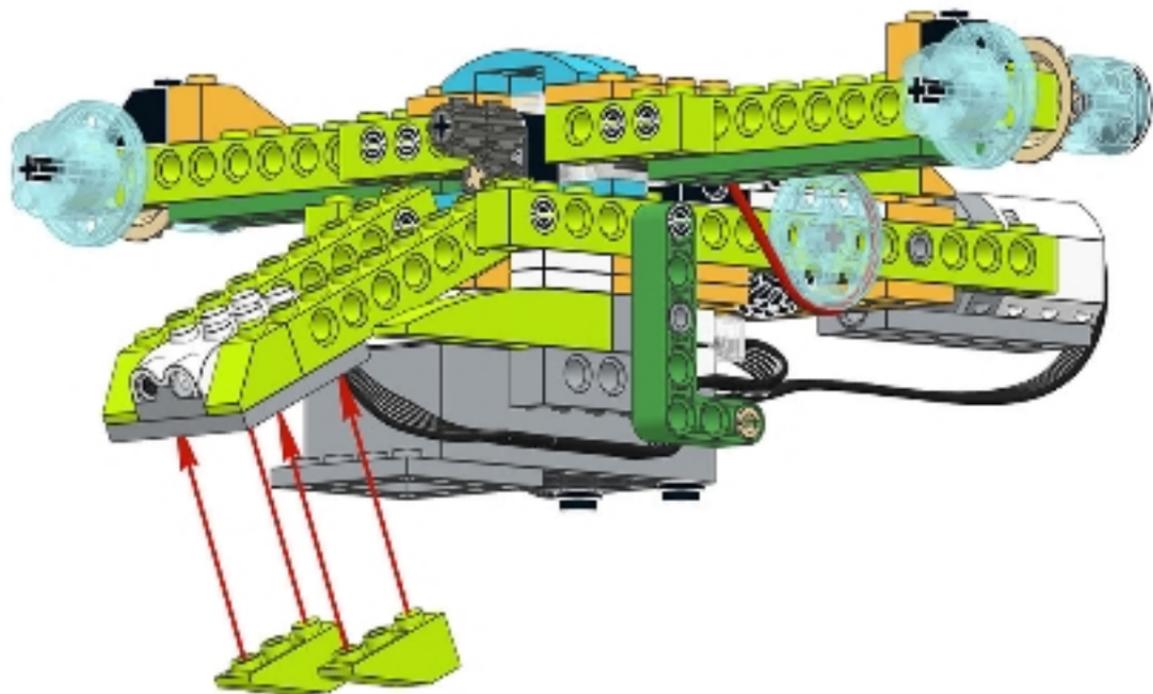
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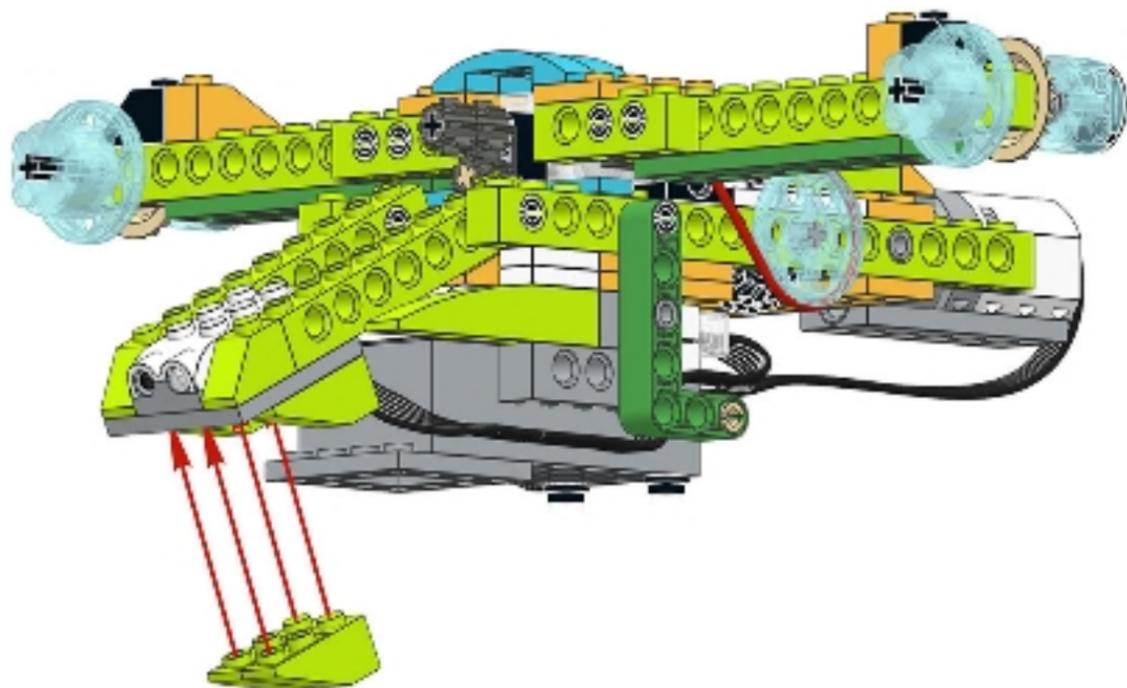
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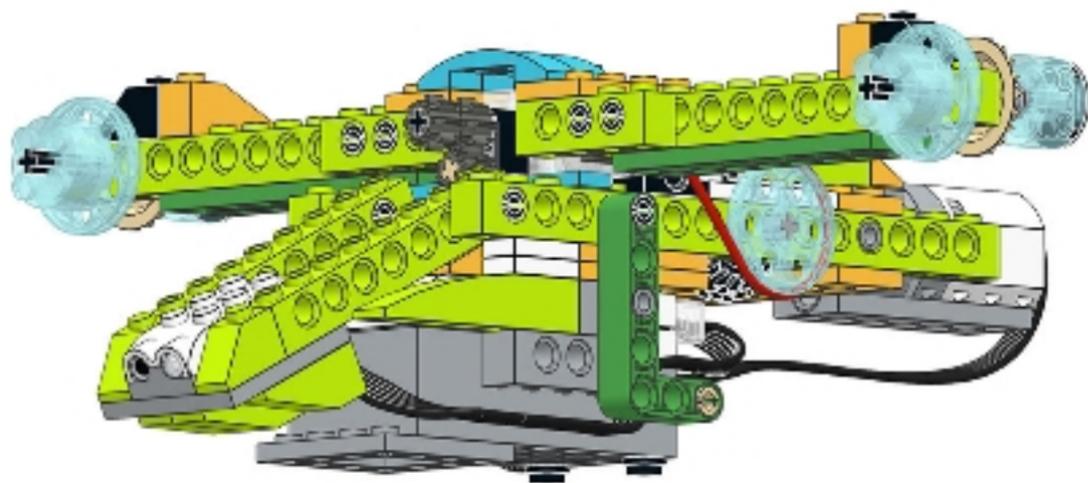


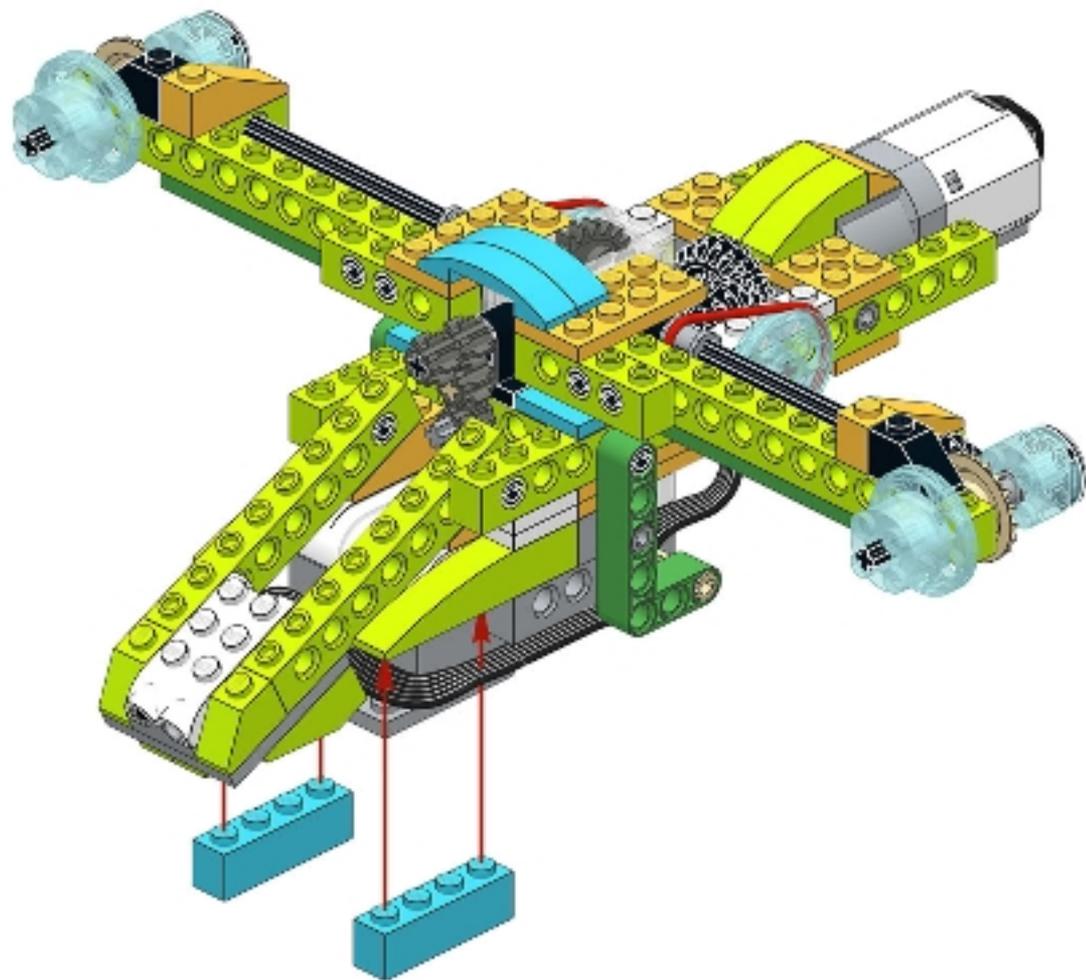


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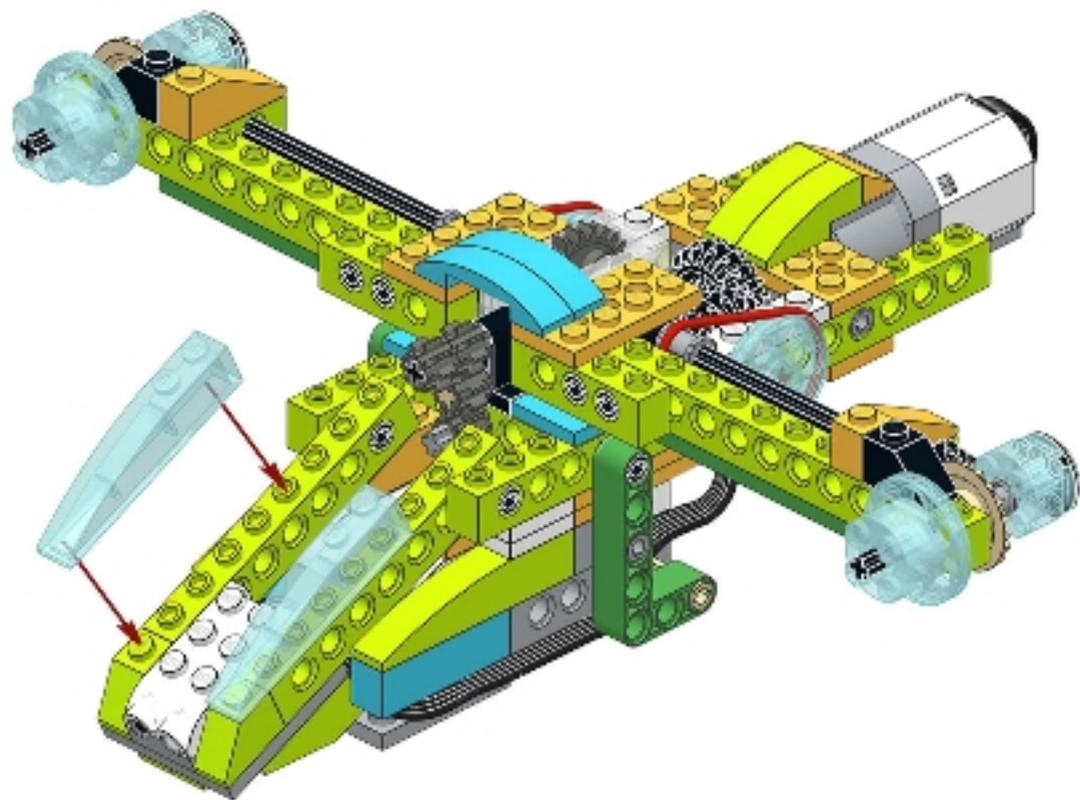
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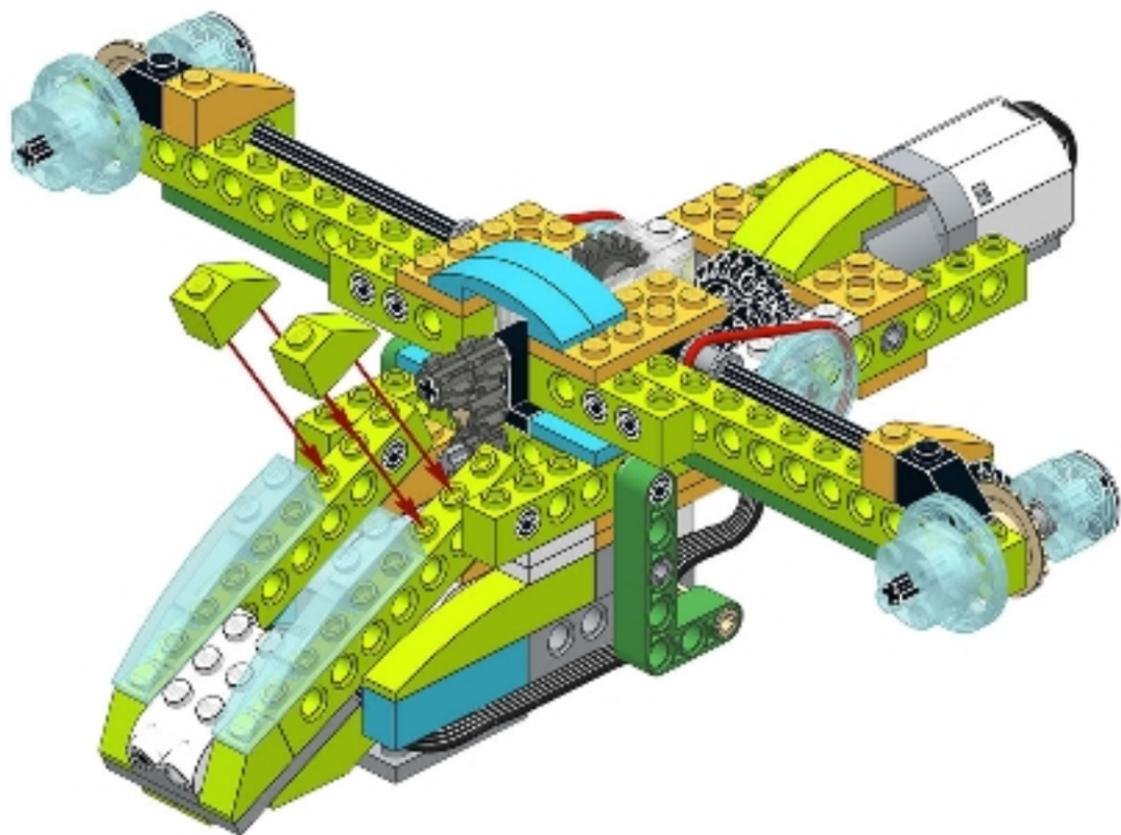
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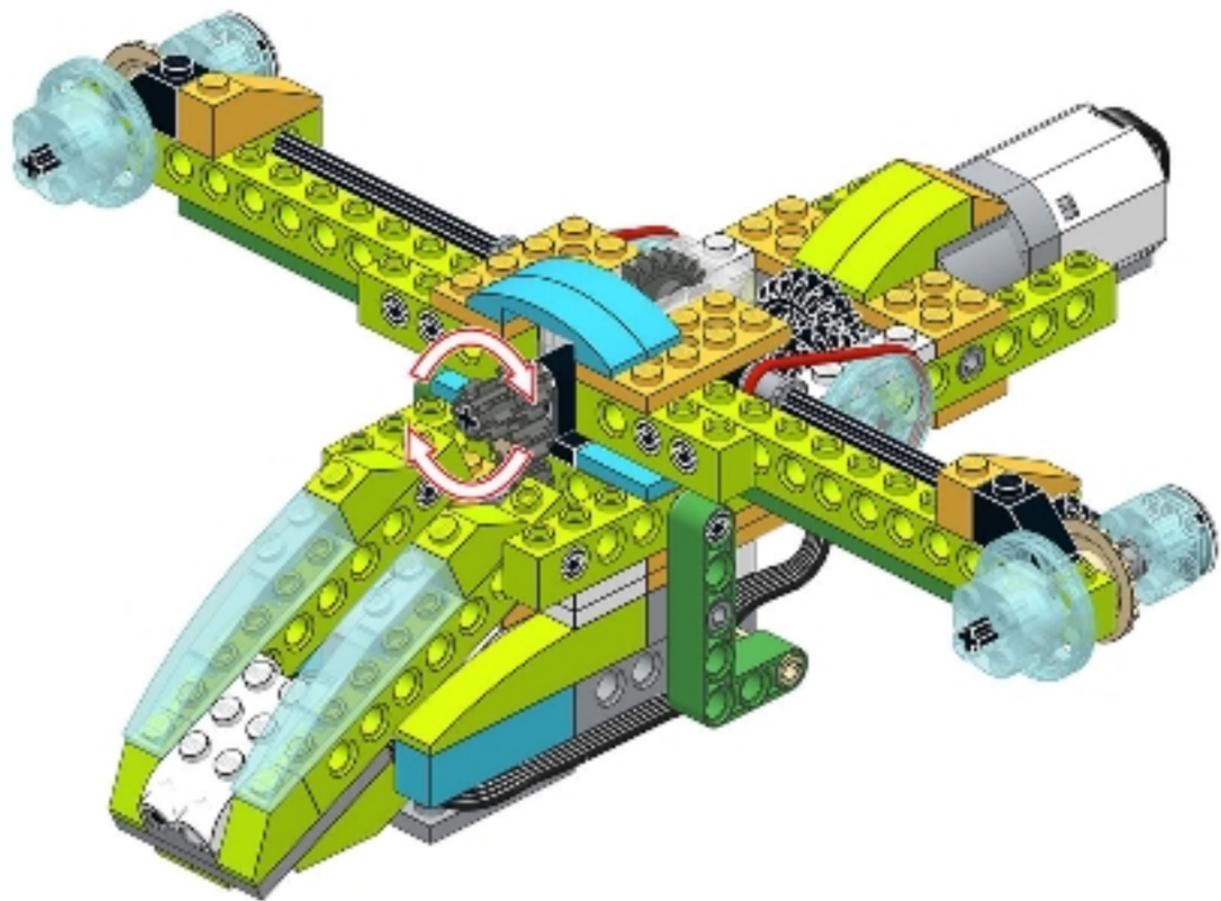


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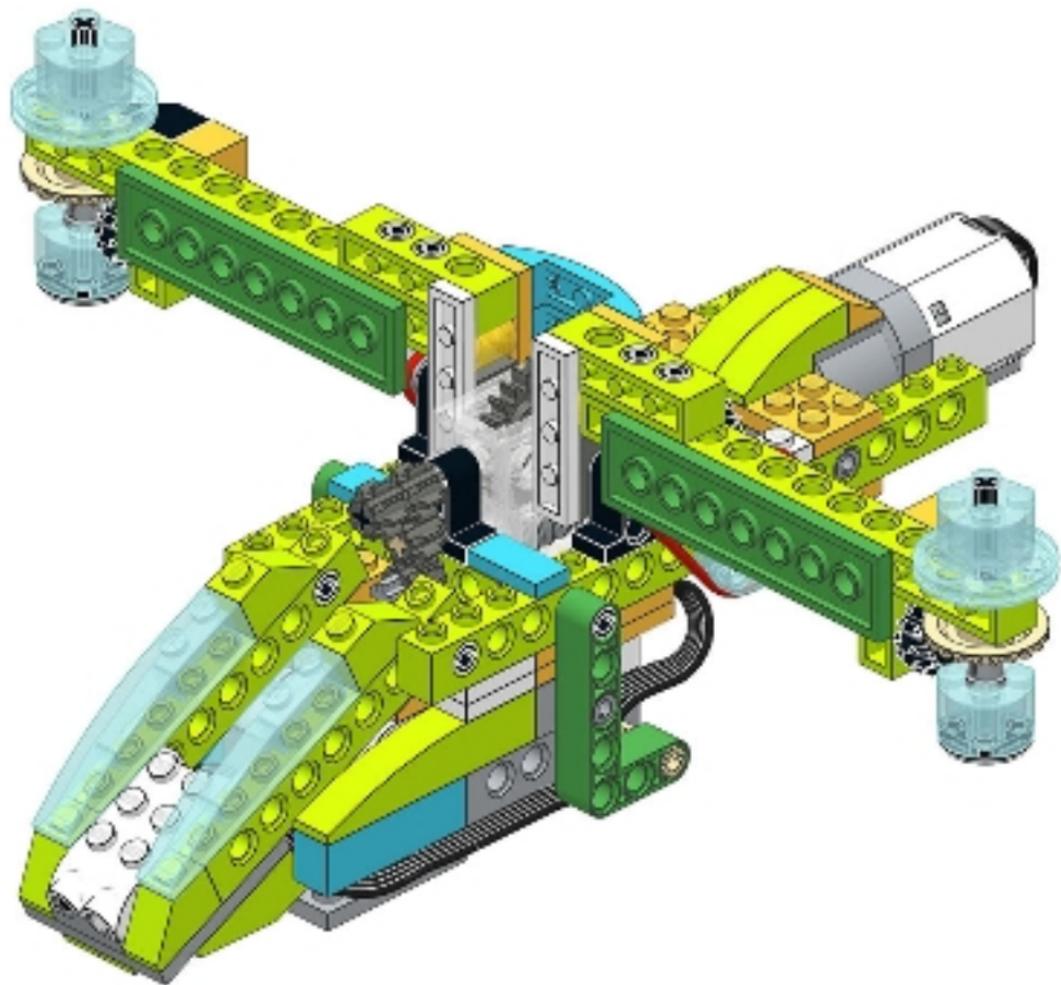
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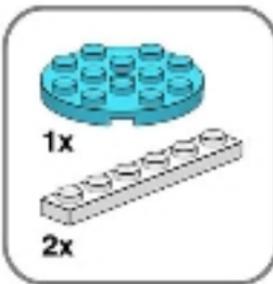
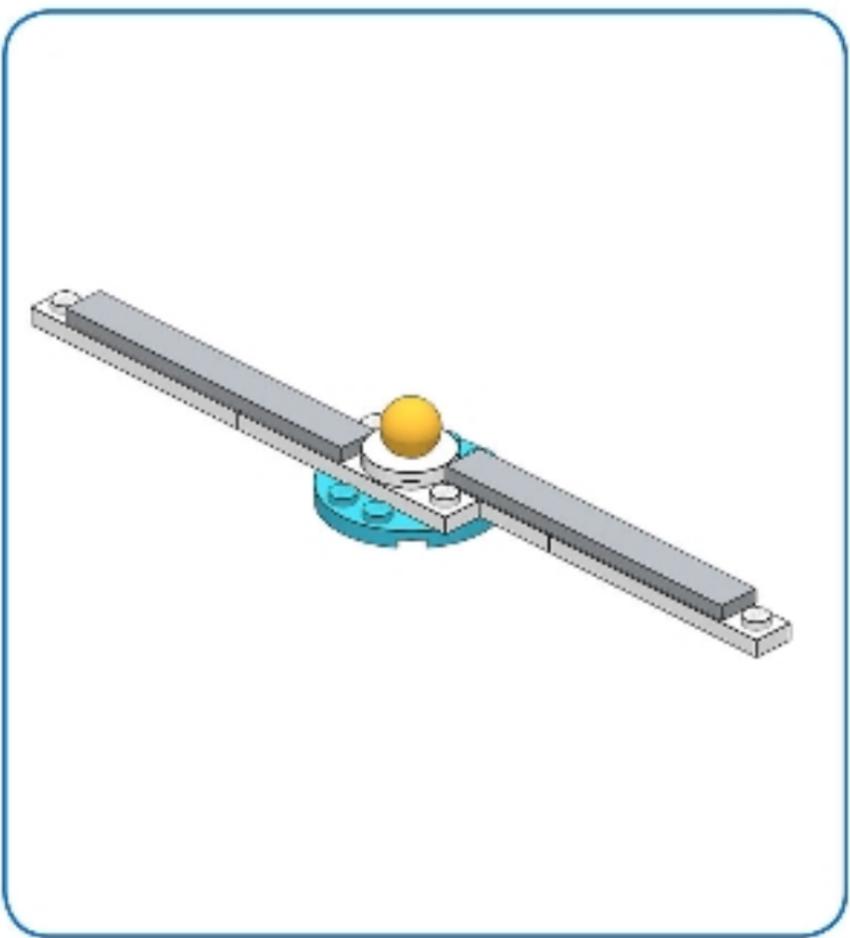


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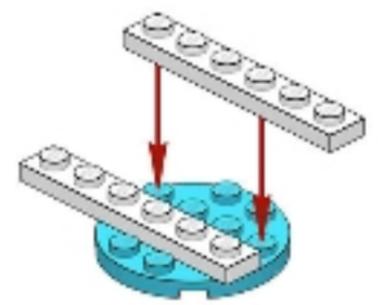


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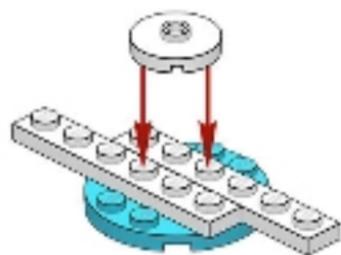
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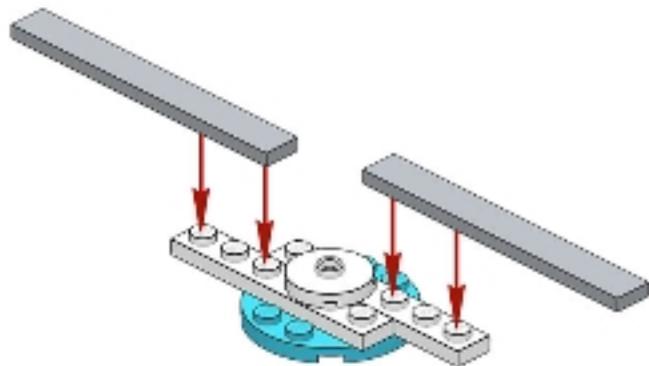
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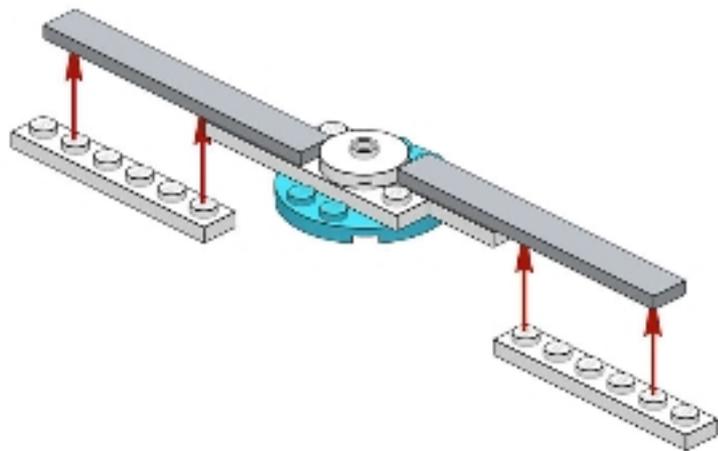
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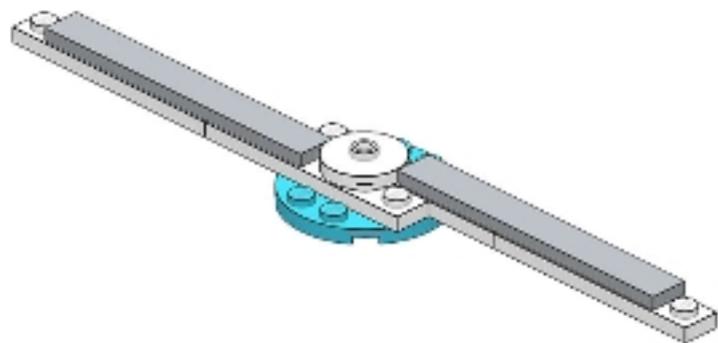




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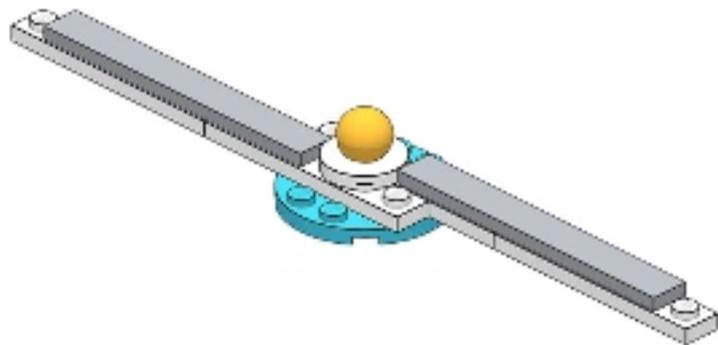




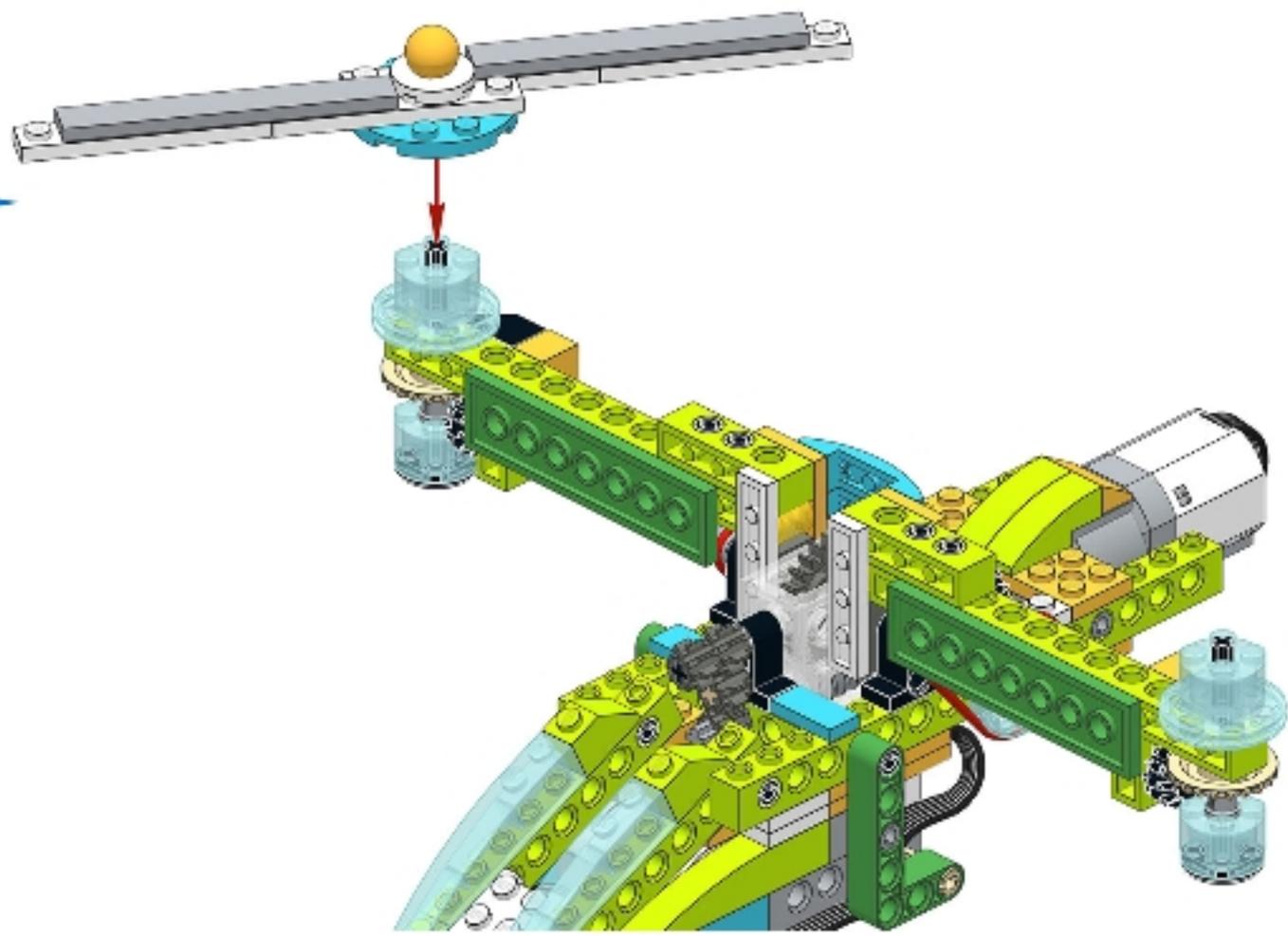


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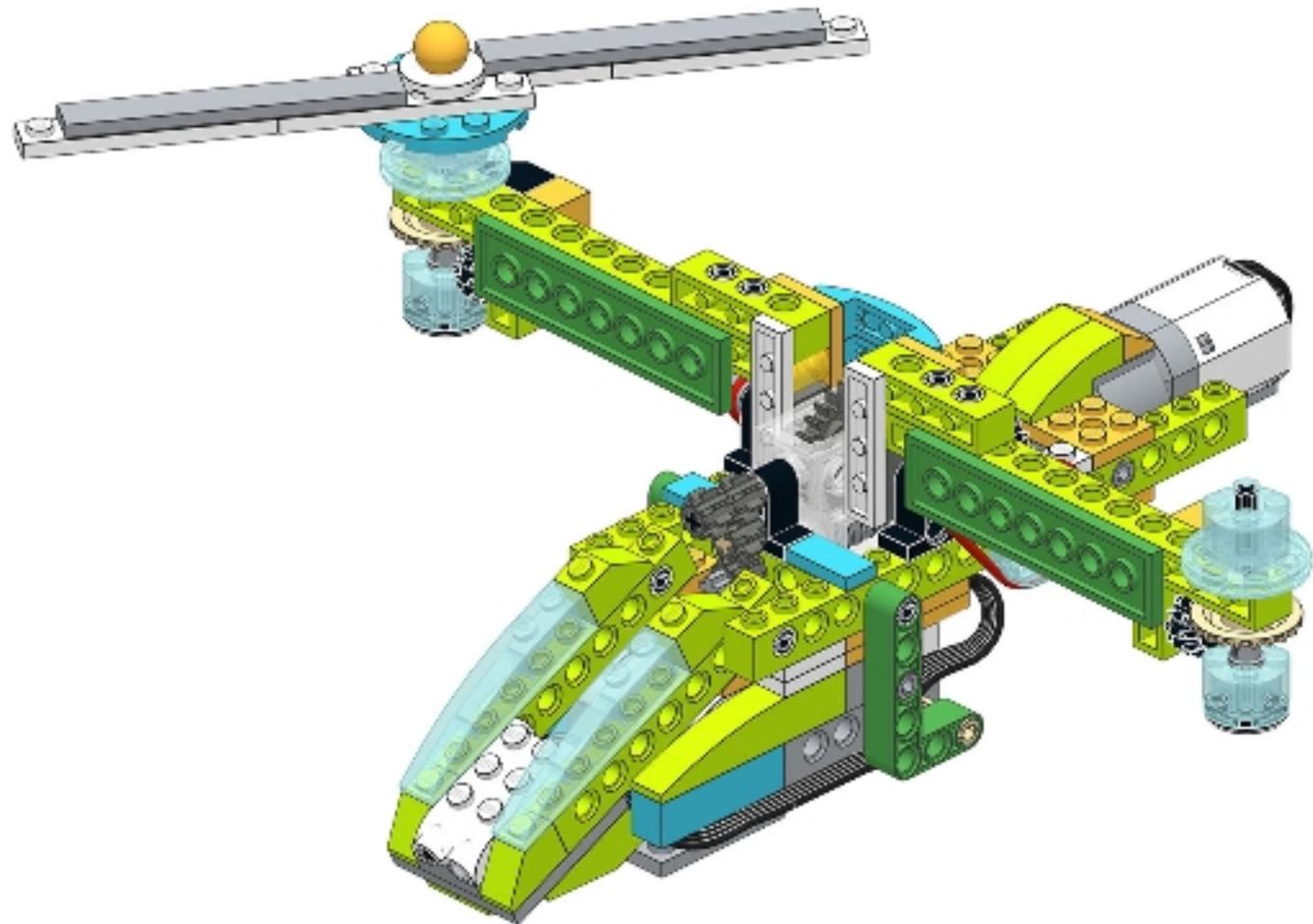


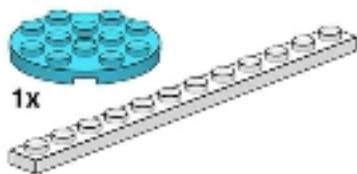
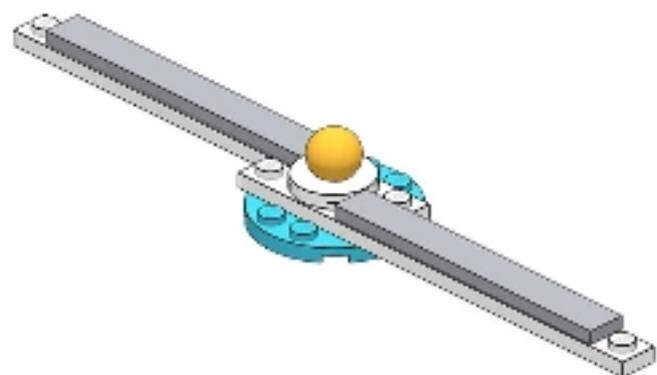
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90/98

91

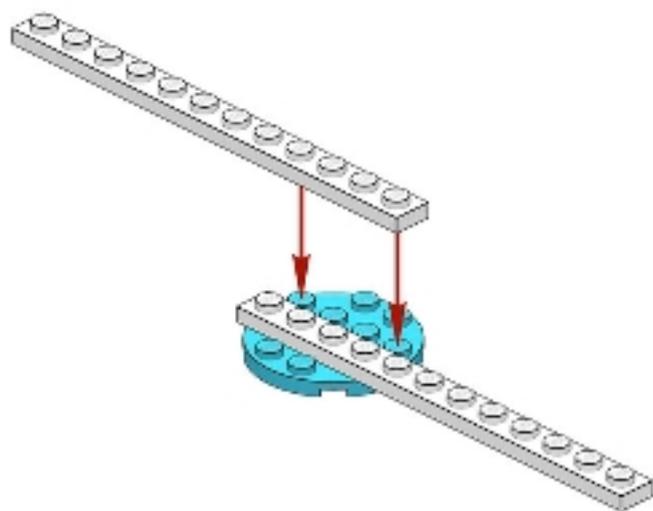




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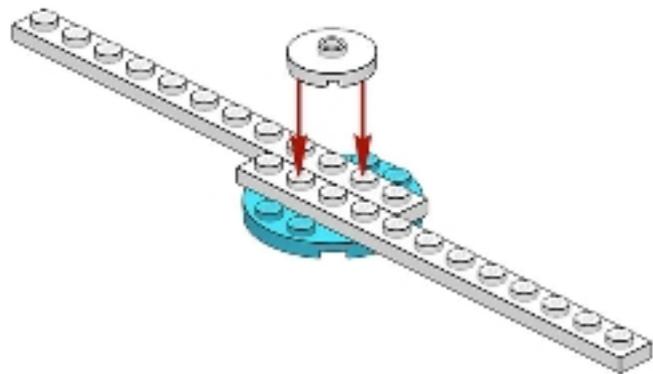
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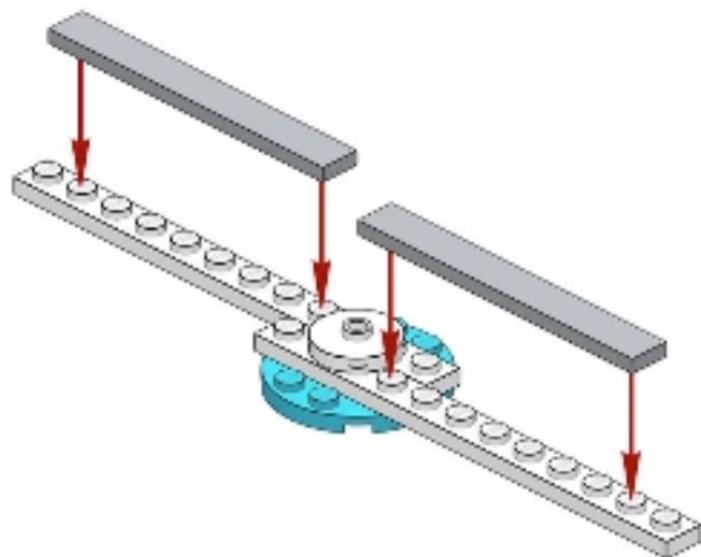
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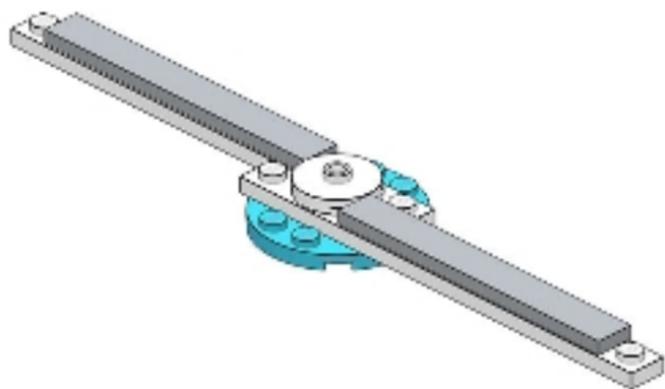


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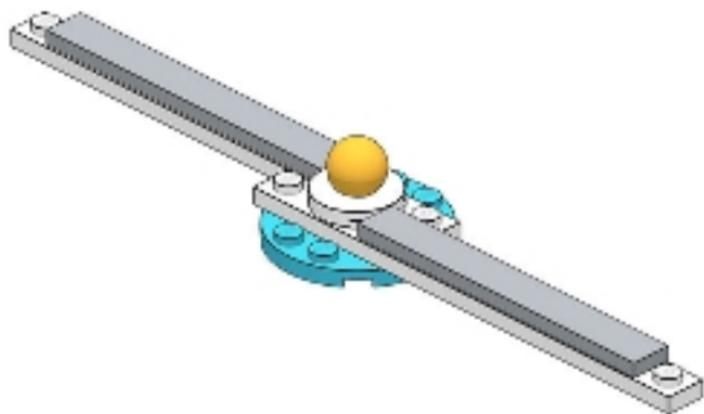
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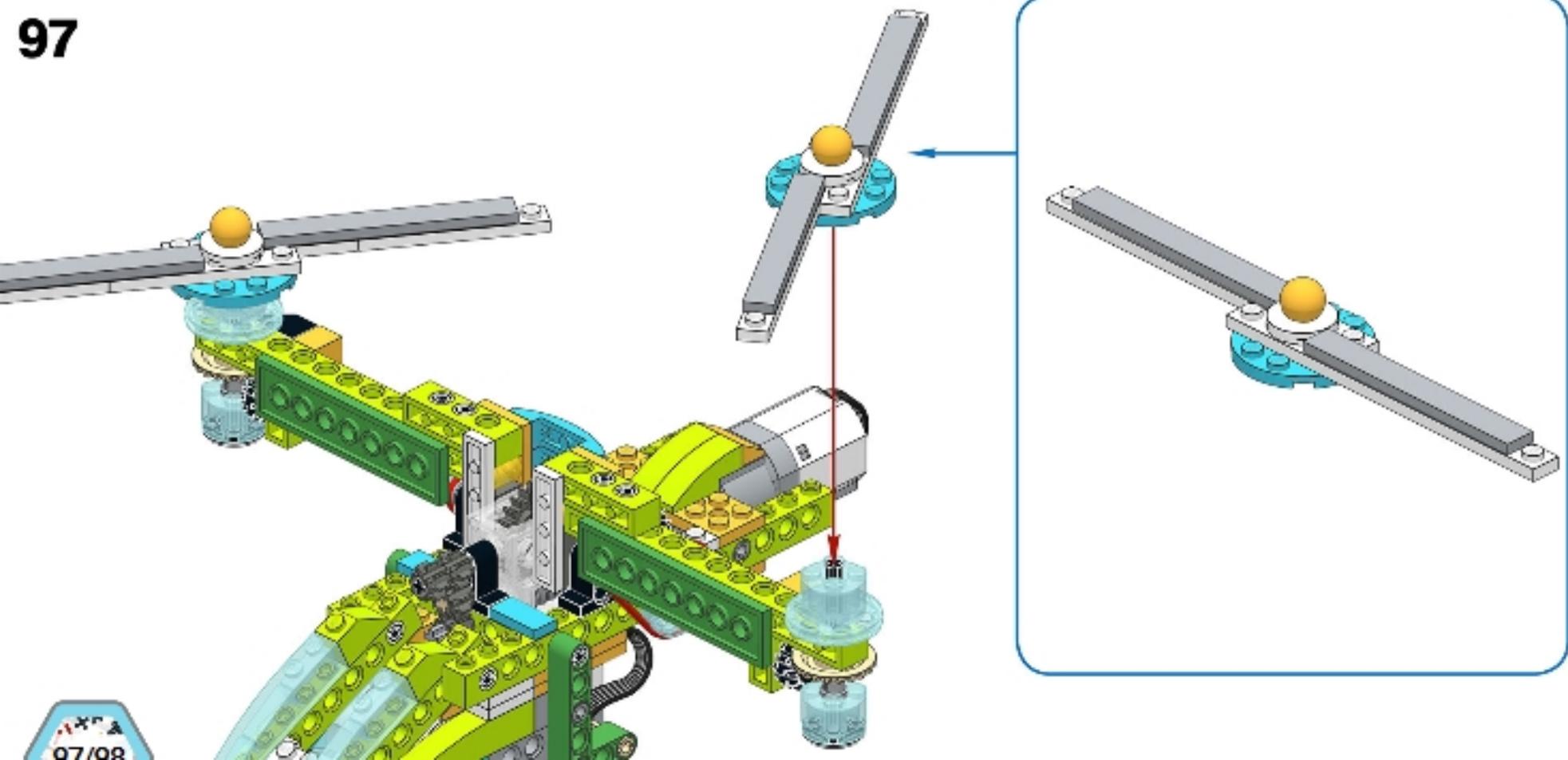


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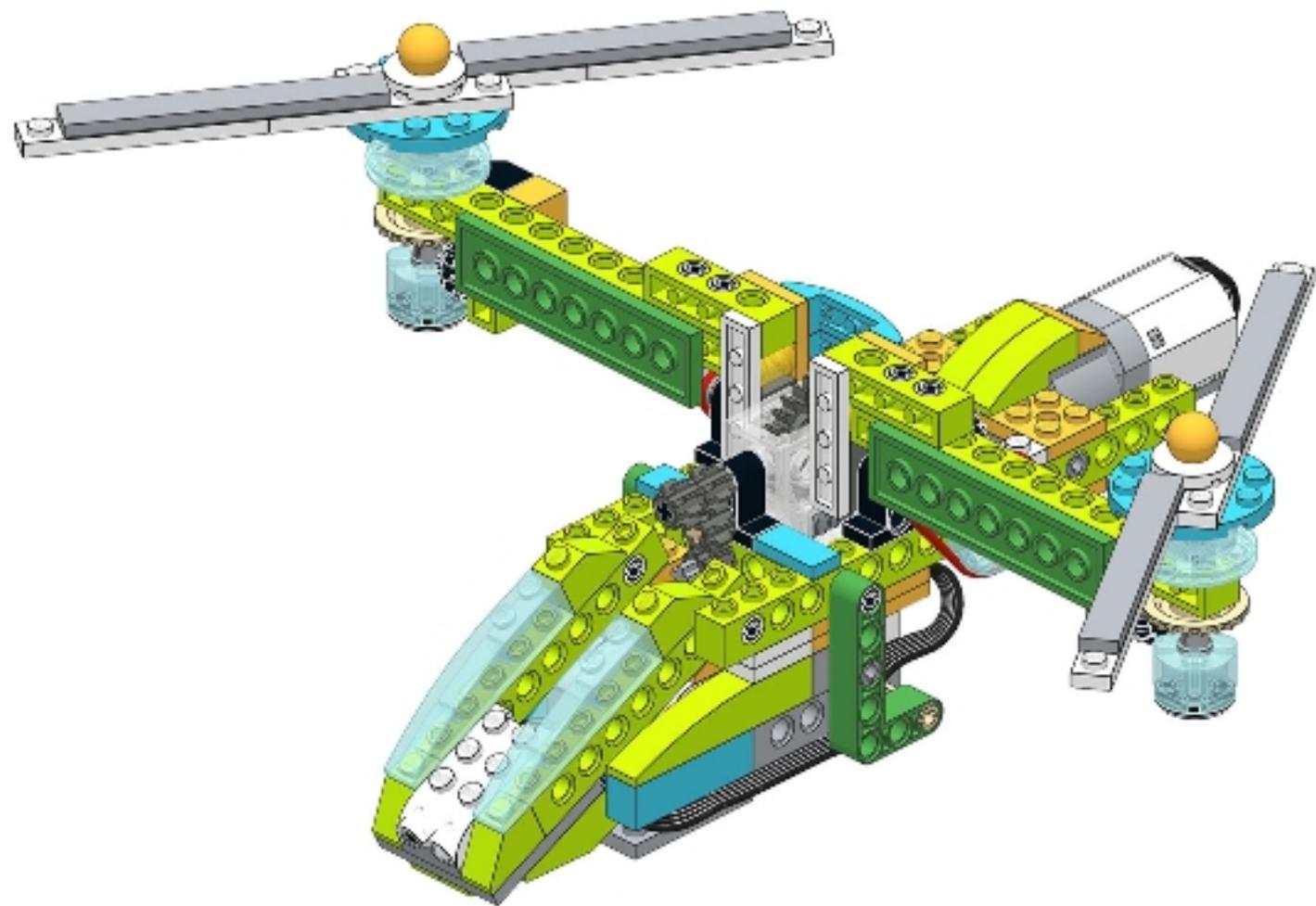
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97



98



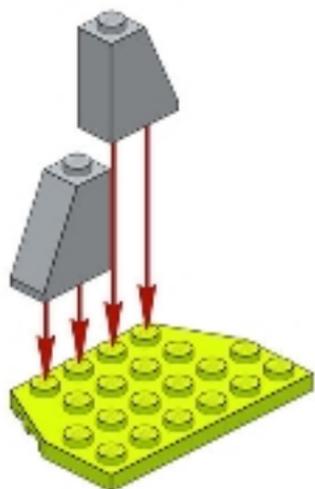


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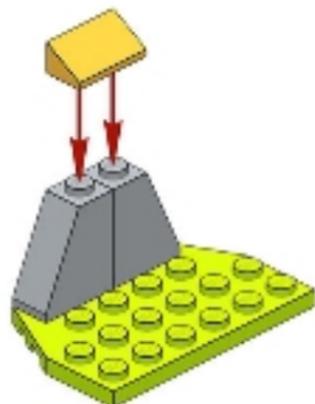
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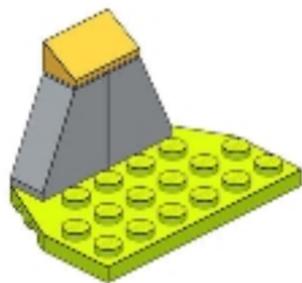


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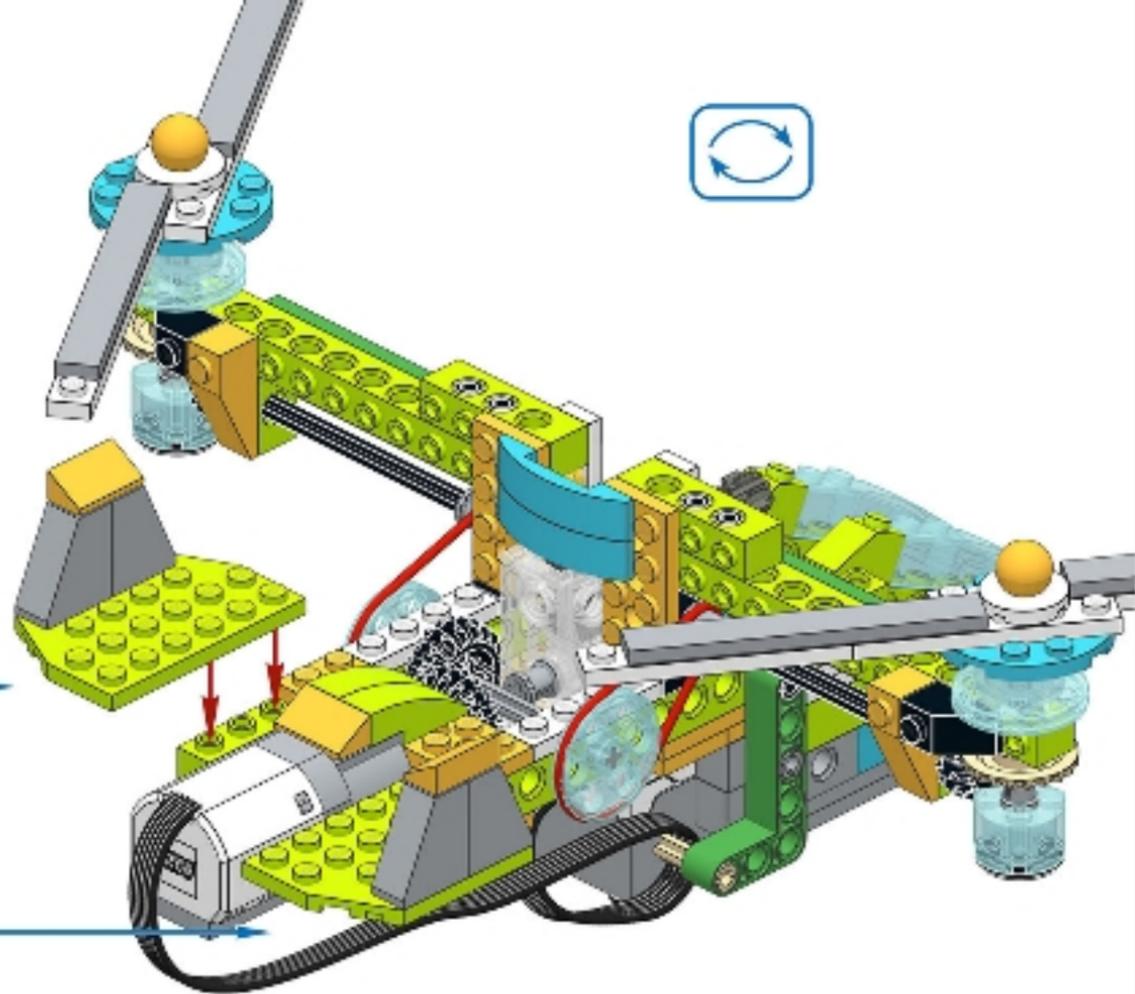
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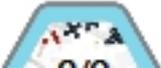
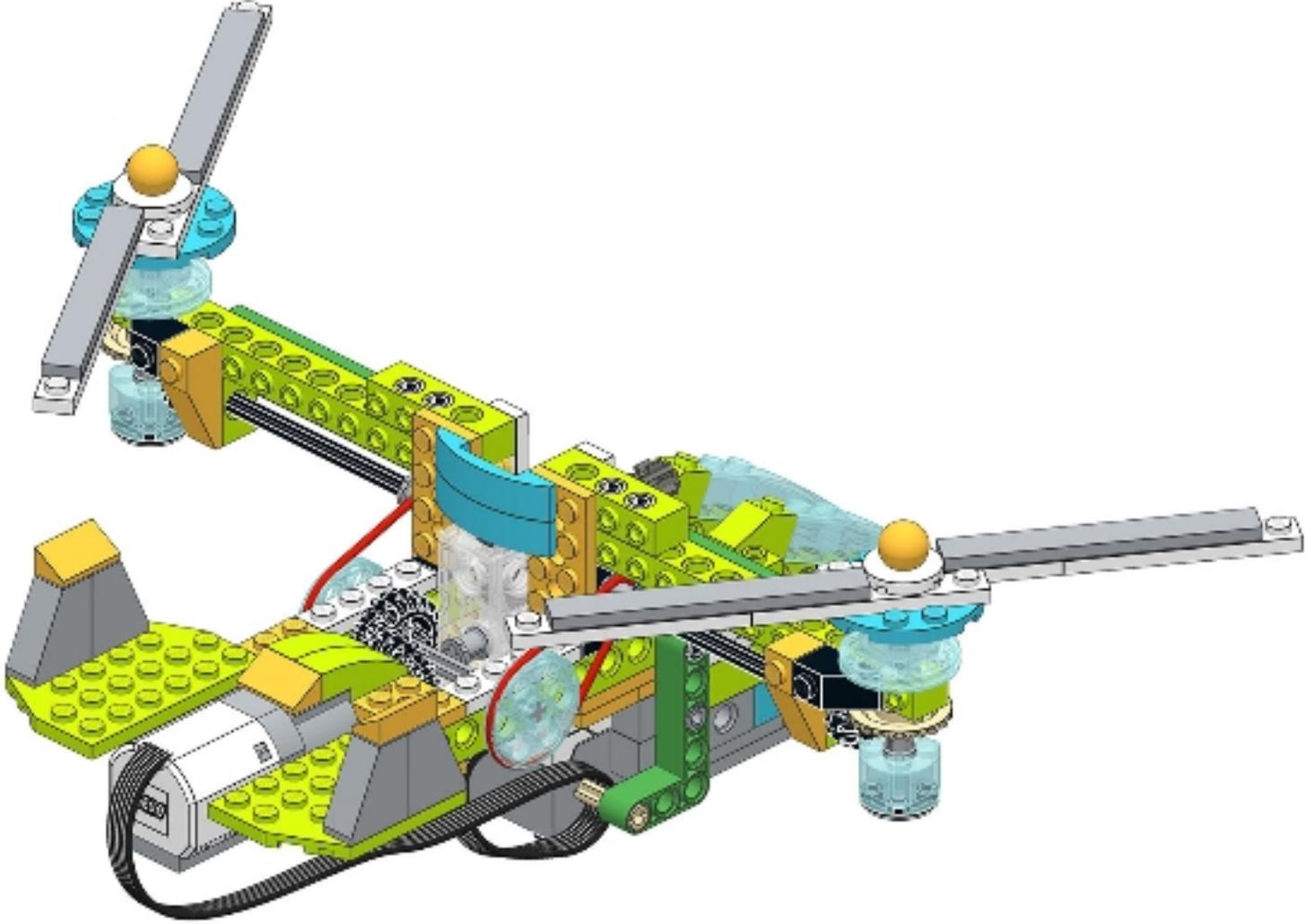
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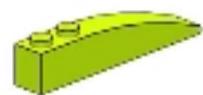


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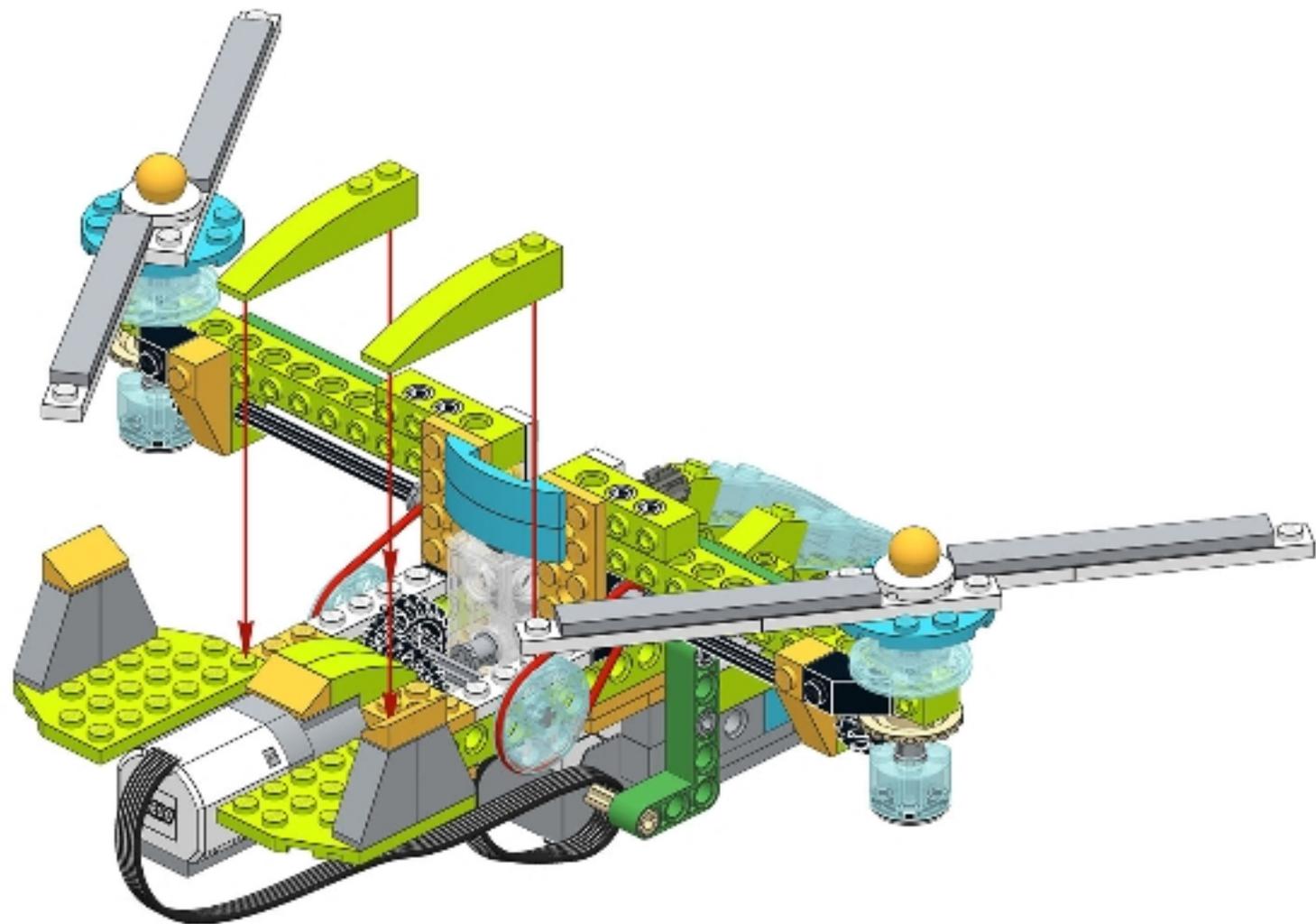
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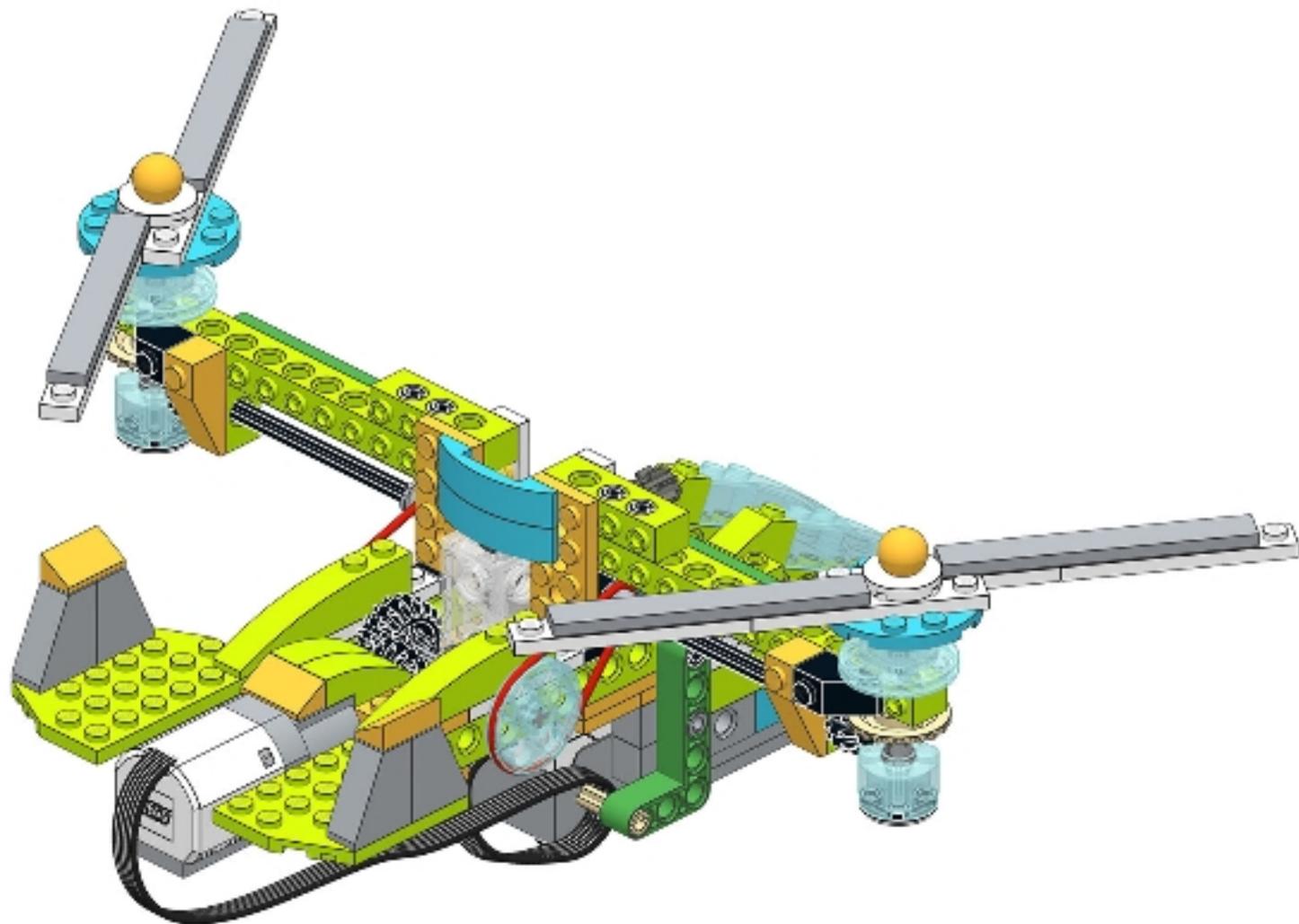


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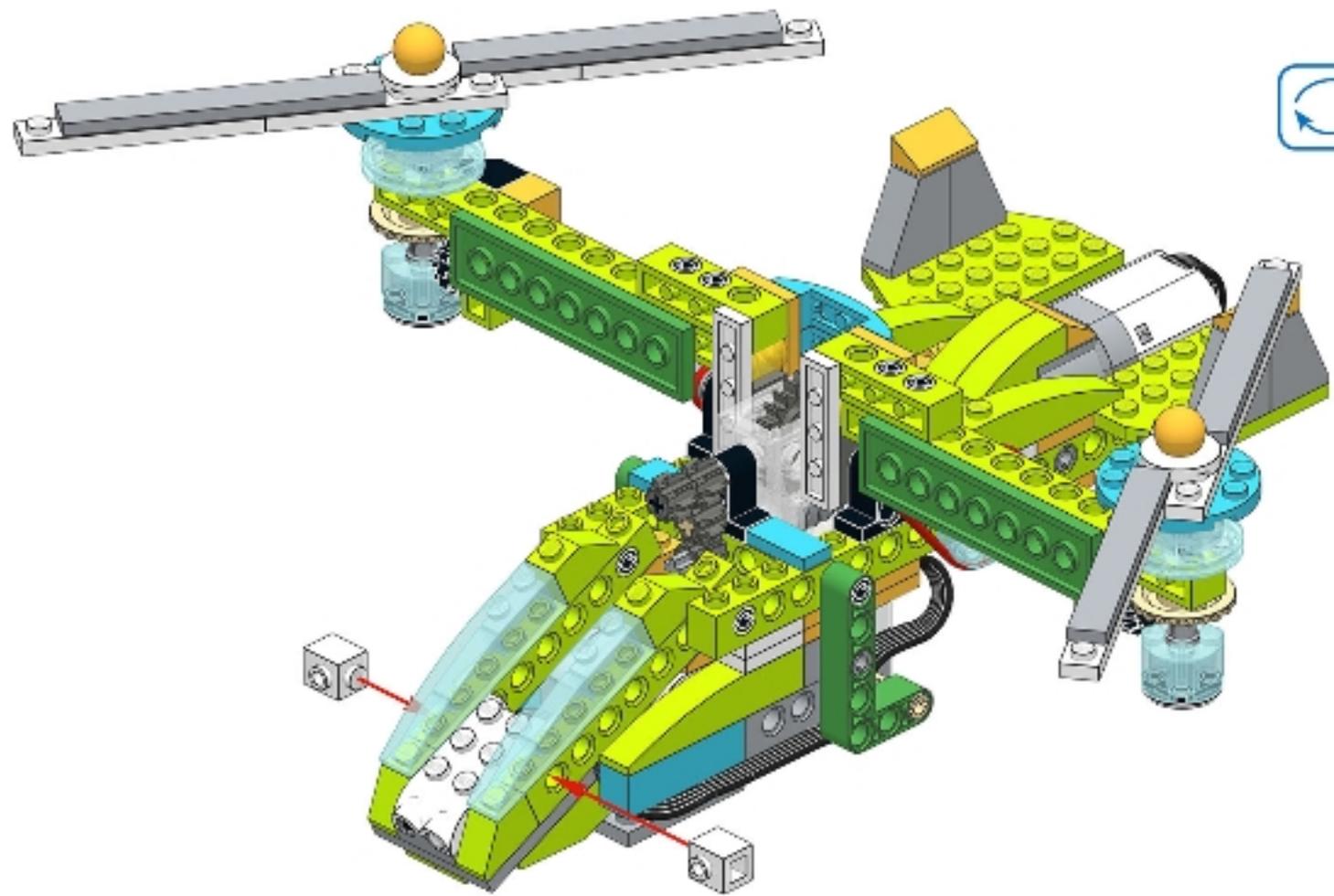


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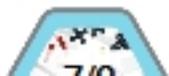
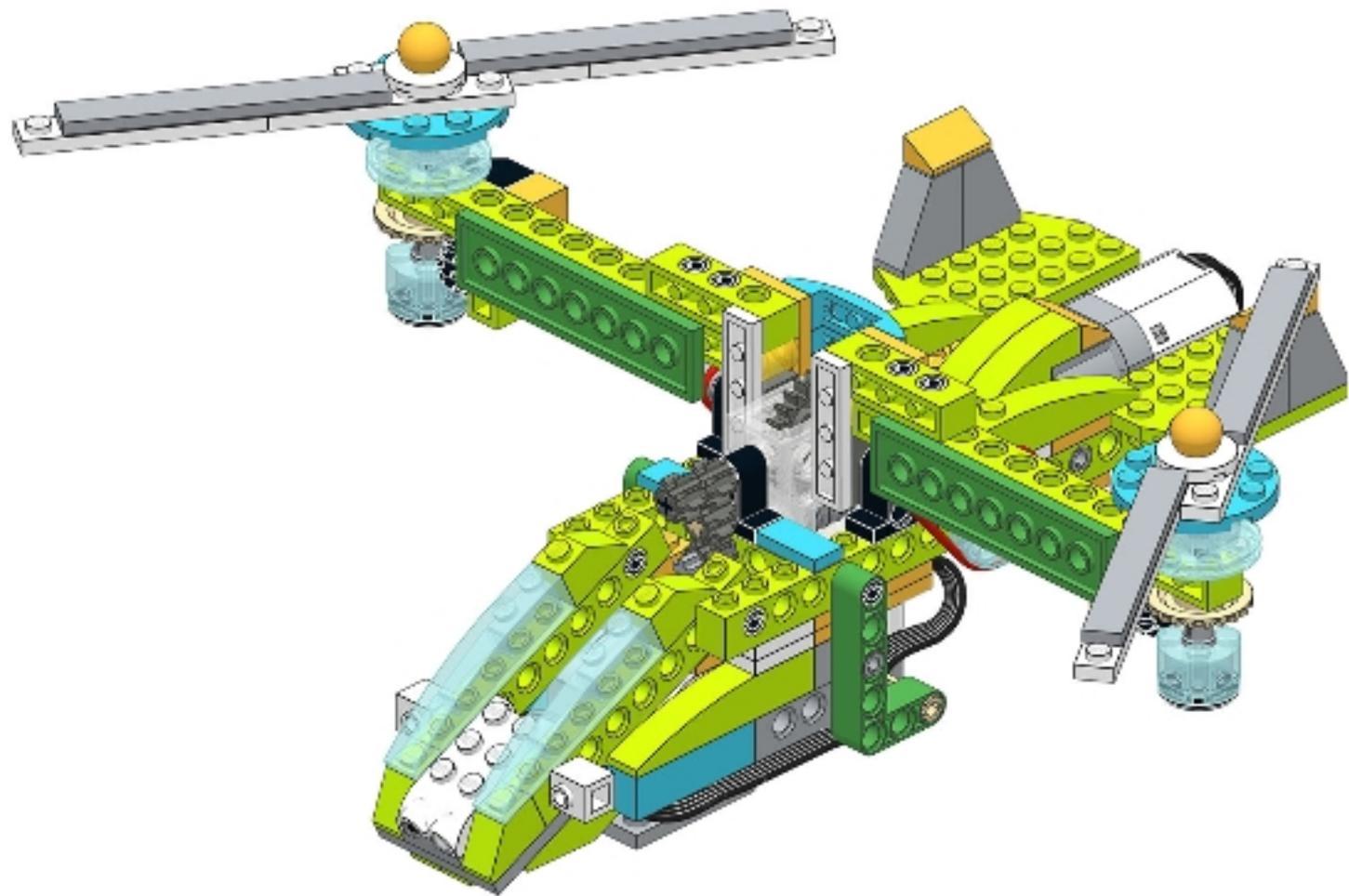


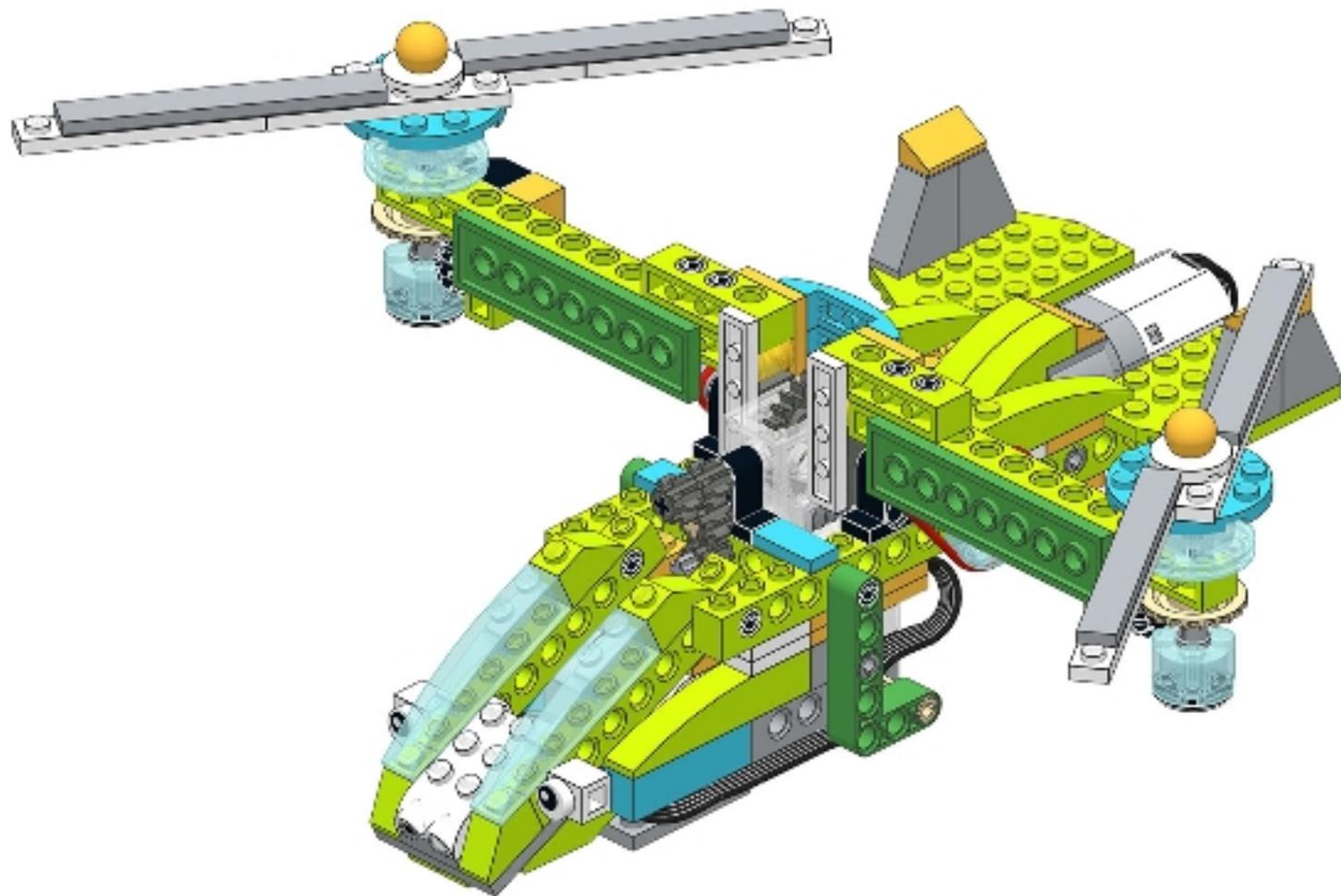


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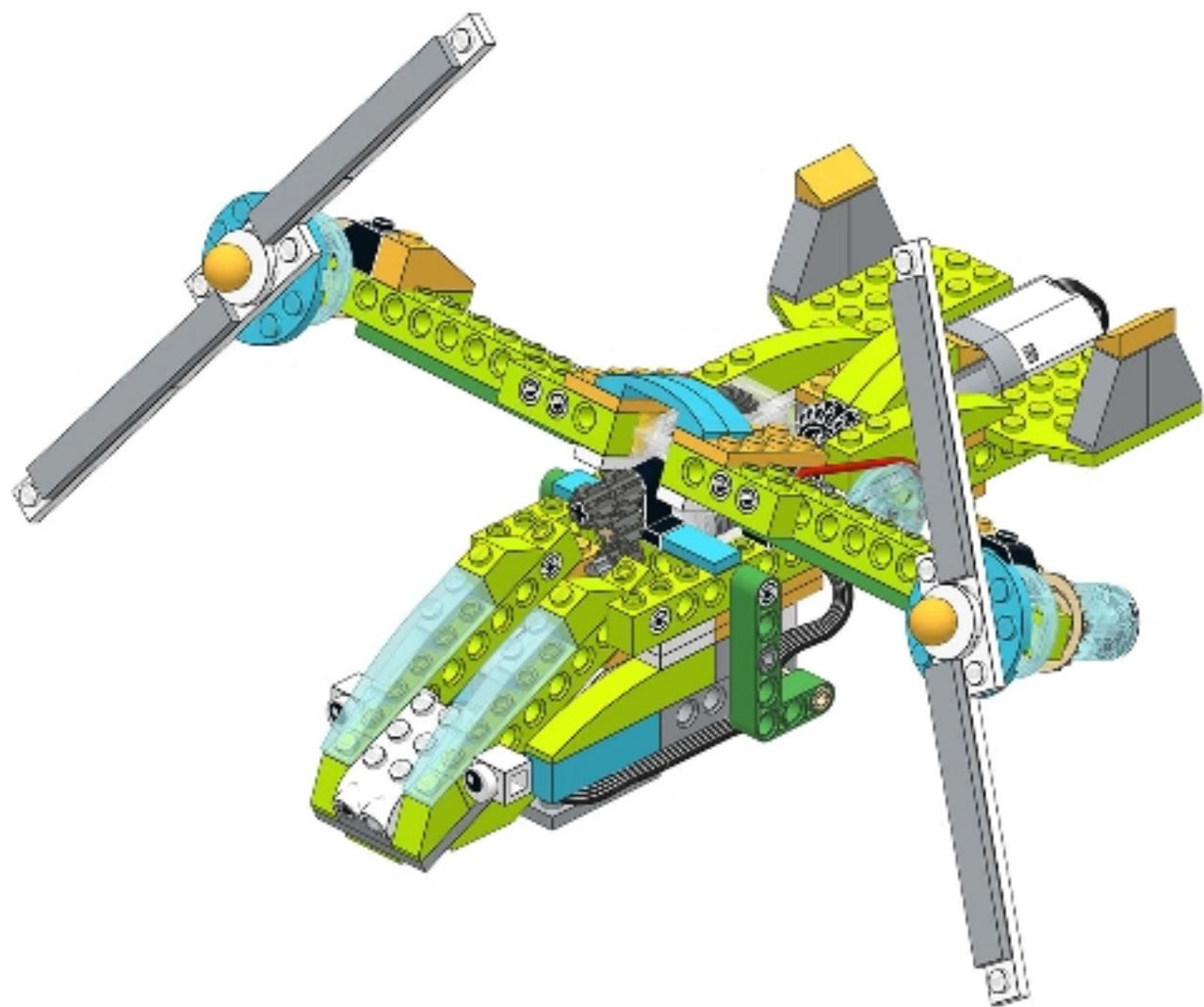


105




2x**106**

107





Task 1. Program

Write a program for robot for the example below.



Datas of the motion sensor immediately set the speed of the motor. Due to this when the distance to the surface increases and the speed of the rotors rotation increases too.



Task 2. Questions

Thanks to which program block is the speed setted more than once, and constantly specifies?





Task 3. Program 1

Modify the program you wrote as follows:



Immediately after take-off, the fuel program runs, in which the robot will count the amount of consumed fuel. And the speed of rotation of the motor axis will make equal to the counter on the



Task 4. Program 1

Modify the program you wrote as follows:



After the landing and emptying of the tank, the program "ground" is runned. After completion of refueling, the fuel program will be runned again. So you do not have to restart the program after each landing.