



MAKER WORKS TECHNOLOGY INC  
Technique support: [support@makeblock.cc](mailto:support@makeblock.cc)  
[www.makeblock.cc](http://www.makeblock.cc)



:@Makeblock



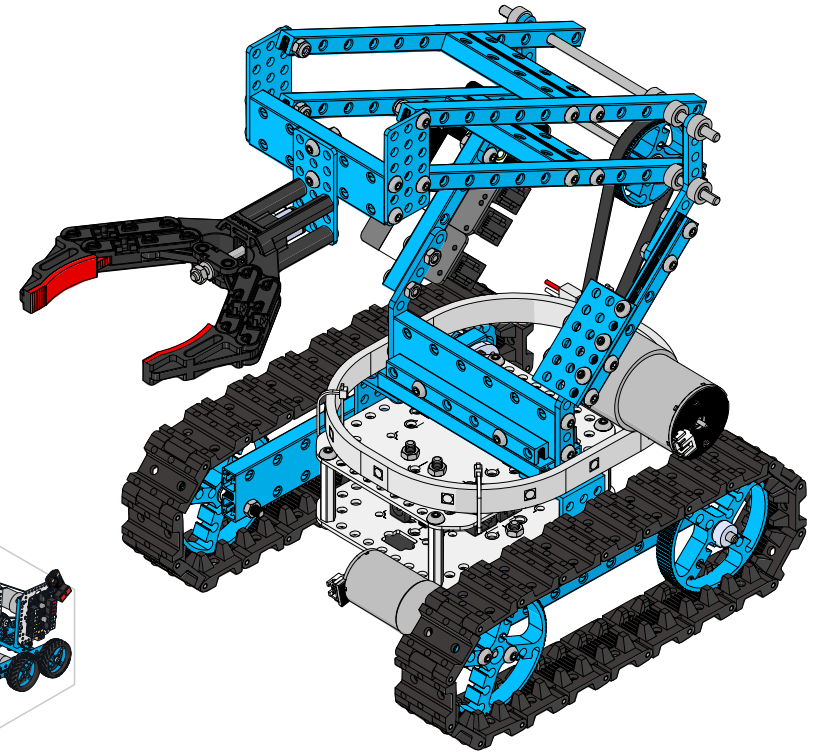
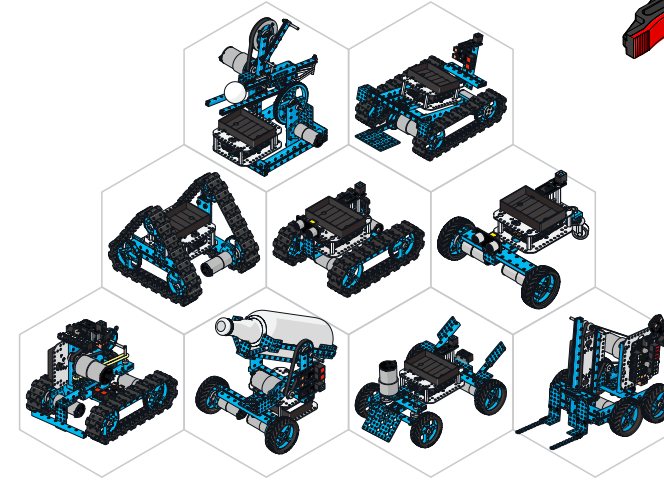
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# Ultimate Robot Kit



# Quick Guide

Warning: Keep this kit out of the reach of small children or animals. Small parts may cause choking or serious injury if swallowed.

Makeblock Ultimate Robot Kit can build as various styles, Robotic Arm Tank, Triangular Tank, Ball Launcher, Forklift etc. It is also a great tool to learn mBlock, Scratch and Arduino programming.



Please visit

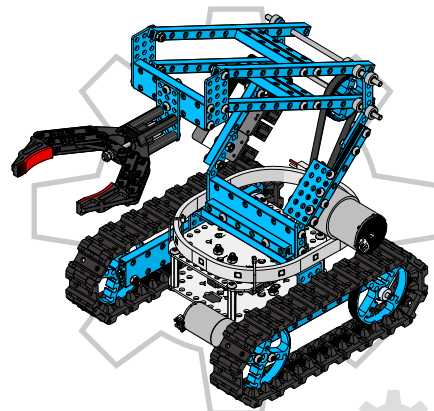
<http://learn.makeblock.cc/ultimate-robot-kit/>  
to view the build and programming guide.



Parts List



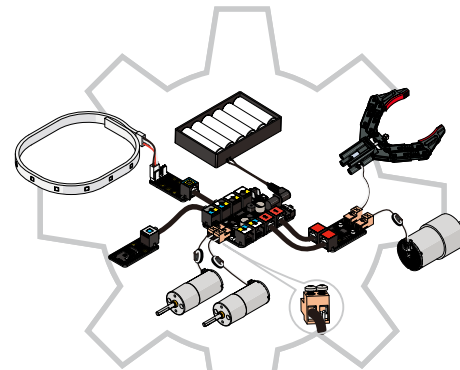
Check all components in parts list, please contact Makeblock or the distributor if any component lacked.



Build the Robotic Arm Tank



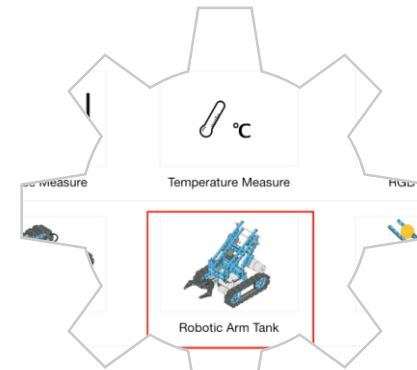
Follow our manual to build the Robotic Arm Tank.



Wiring



Do wiring. Install batteries for your robot .



Control with App



Turn on the power of your robot, control your robot with App. **Now it's time to play your robot!**



Robot Ideas--Further exploration



Try other styles:  
Follow our guideline on website to build the other 9 robot styles.















Programming Guide--Further exploration
















Advanced player can re-program to the robot by mBlock or Arduino to explore the wonderful robotic world.
















# Parts List















Pictures for reference only




- 2× Beam 0824-64 
- 2× Beam 0824-80 
- 3× Beam 0824-96 
- 2× Beam 0824-128 
- 2× Beam 0824-144 
- 4× Beam 0808-88 
- 4× Beam 0808-184 
- 4× Bracket 3×3 
- 1× Bracket 3×6 
- 4× Plate 3×6 
- 1× Plate 7×9 
- 8× Link Rod 

- 2× Bracket P3 
- 1× Caster Wheel 
- 4× Plate 45° 
- 1× Disc D72 
- 2× DC Motor-25 Bracket 
- 1× DC Motor-37 Bracket 
- 3× Shaft Connector 4mm 
- 1× Timing Pulley 18T 
- 2× Timing Pulley 62T 
- 4× Timing Pulley 90T 
- 2× Timing Pulley Slice 90T 
- 1× Gear 16 
- 1× Gear 80 

- 2× Timing Belt Connector 
- 4× Tire 68.5×22mm 
- 40× Track 
- 40× Track Axle 
- 1× Timing Belt 98MXL 
- 1× Timing Belt 240MXL 
- 6× Rubber Ring 
- 2× D Shaft 4×56mm 
- 2× D Shaft 4×128mm 
- 6× Threaded Shaft 4×39mm 
- 10× Shaft Collar 4mm 
- 8× Flange Bearing 4×8×3mm 
- 4× Nylon Pulley with Bearing 
- 8× Bearing 4×8×3mm 

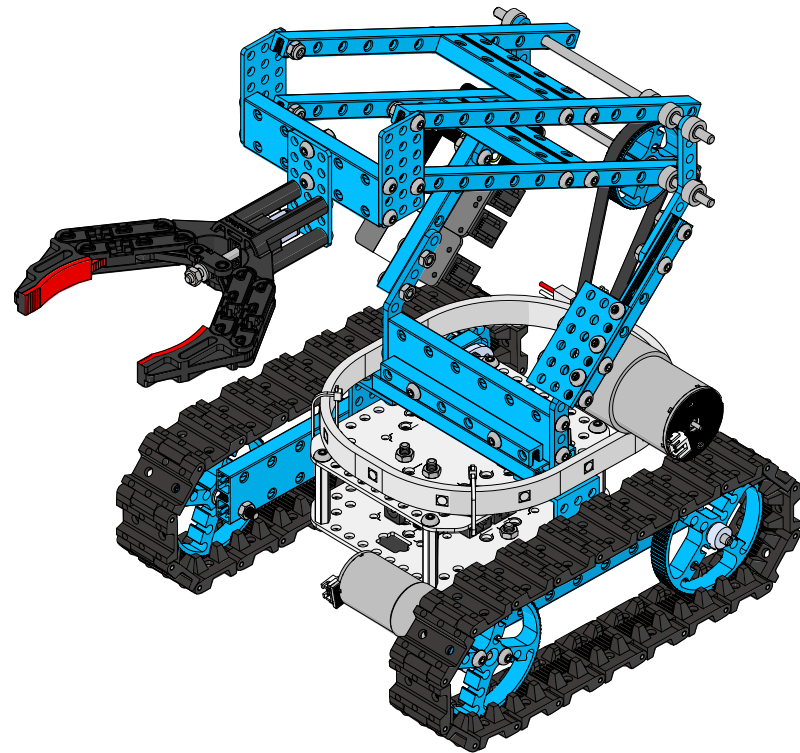
- 31× Screw M4×8 
- 42× Screw M4×14 
- 10× Screw M4×22 
- 10× Screw M4×30 
- 28× Nut M4 
- 2× Nut M8 
- 30× Nylon Lock Nut M4 
- 10× Screw M3×8 
- 16× Headless Set Screw M3×5 
- 6× Nylon Stud M4×30 
- 1× Hex Screwdriver 
- 1× Cross Screwdriver 
- 1× Wrench 
- 1× Hex Allen Key 2.5mm 
- 2× Hex Allen Key 1.5mm 

- 16× Plastic Rivet R4060 
- 12× Plastic Rivet R4120 
- 2× BaseBracket 
- 1× Battery Holder for (6) AA 
- 2× DC Motor-25 
- 1× DC Motor-37 
- 3× Terminal Block 
- 3× Motor Cable 
- 3× Ferrite Ring 
- 2× Micro Switch 
- 2× Micro Switch Cable 
- 4× Tapping Screws-2×10 
- 50× Plastic Ring 4×7×2mm 
- 1× Micro Switch Bracket 































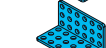


















- 1× Makeblock Orion 
- 1× Me Ultrasonic Sensor 
- 1× Me Dual Motor Driver 
- 1× Me Bluetooth Module 
- 1× Me Line Follower 
- 1× Me Sound Sensor 
- 1× Me RJ25 Adapter 
- 1× LED RGB Strip-Addressable 
- 3× RJ25 Cable-20cm 
- 3× RJ25 Cable-35cm 
- 1× Micro USB Cable 
- 1× Robot Gripper 



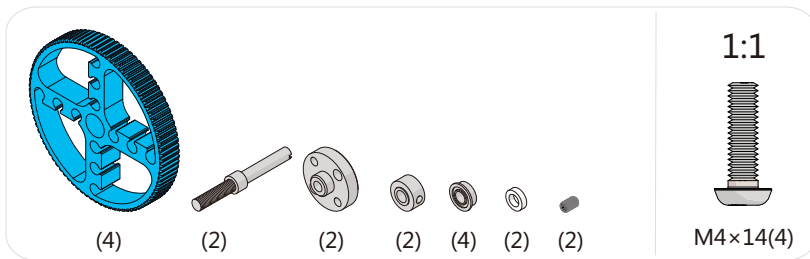
# Build the Robotic Arm Tank



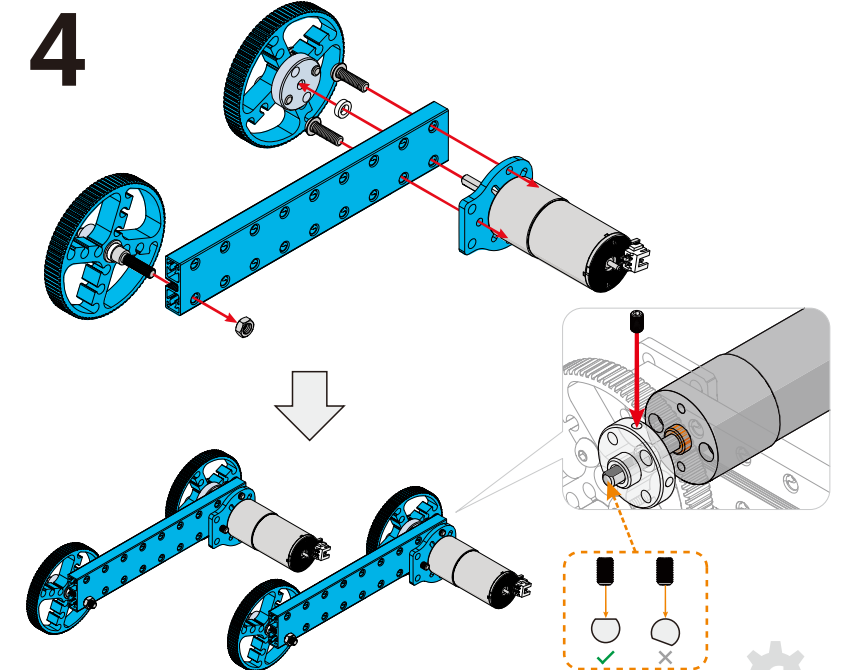
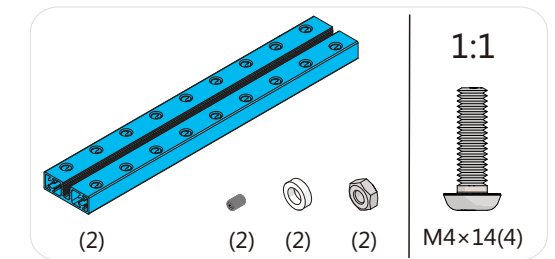
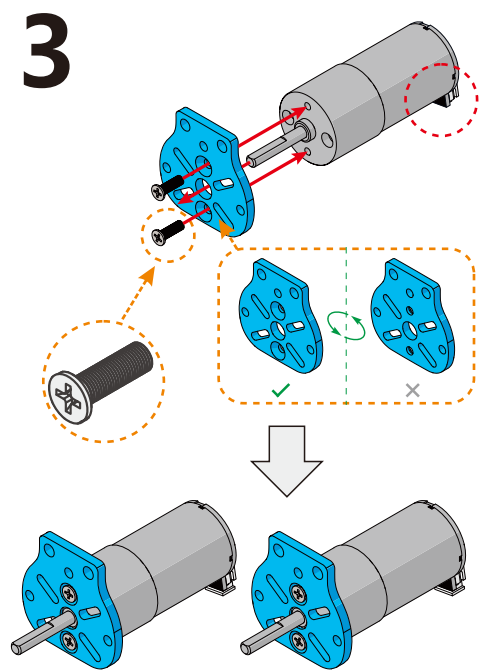
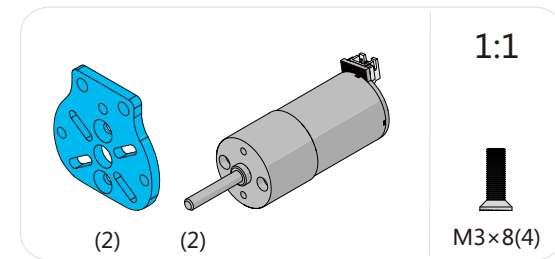
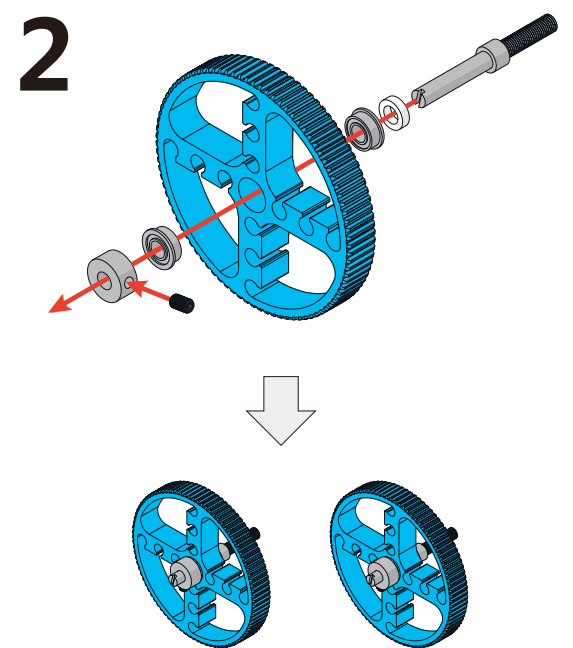
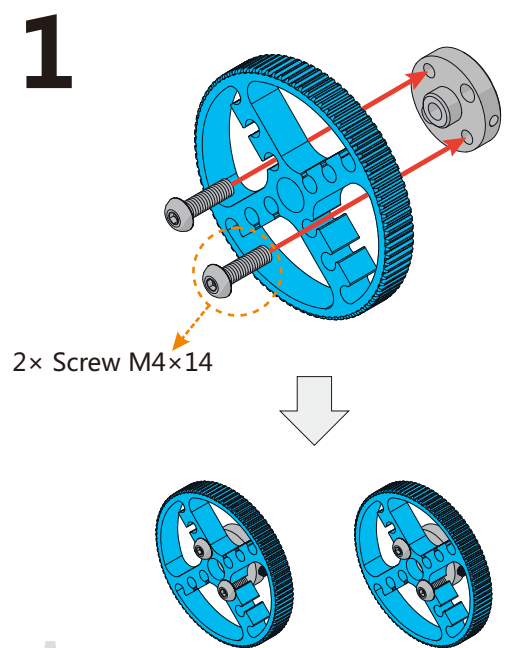
# Part List for the Robotic Arm Tank

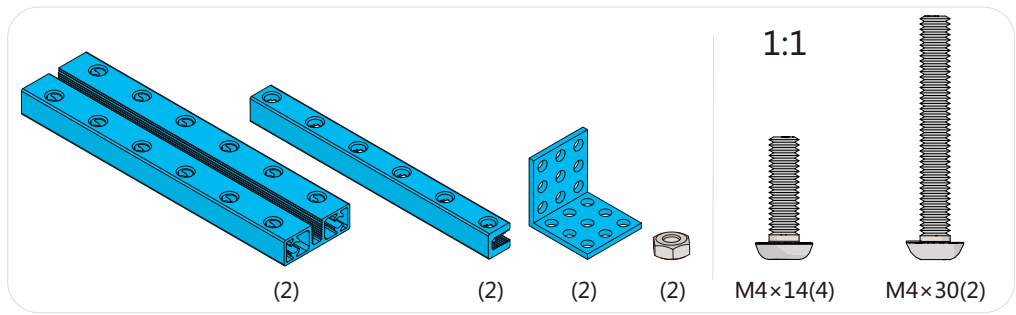
1× Timing Belt 98MXL		1× DC Motor-37 Bracket		1× Timing Pulley 62T	
4× Beam 0808-184		2× DC Motor-25 Bracket		4× Timing Pulley 90T	
4× Beam 0808-88		4× Plate 45°		4× Nylon Stud	
2× Beam 0824-64		6× Flange bearing 4×8×3mm		1× Battery Holder for (6)AA	
1× Beam 0824-80		21× Nut 4mm		2× BaseBracket	
2× Beam 0824-96		4× Nylon Lock Nut 4mm		1× Makeblock Orion	
2× Beam 0824-144		4× Plastic Ring 4×7×2		1× Me RJ25 Adapter	
3× Plate 3×6		13× HeadlessSetScrewM3x5		1× Me Dual Motor Driver	
2× Bracket 3×3		8× Screw M3×8		1× Me Bluetooth Module	
1× Bracket 3×6		31× Screw M4×8		1× LED RGB Strip-Addressable	
2× D Shaft 4×128mm		42× Screw M4×14		2× RJ25 Cable-20cm	
2× DC Motor-25		1× Screw M4×22		2× RJ25 Cable-35cm	
1× DC Motor-37		2× Screw M4×30		1× Micro USB Cable	
3× Terminal Block		2× Shaft Connector 4mm		1× Robot Gripper	
3× Motor Cable		10× Shaft Collar 4mm			
3× Ferrite Ring		2× Threaded Shaft 4×39			
		36× Track			
		36× Track Axle			
		1× Timing Pulley 18T			



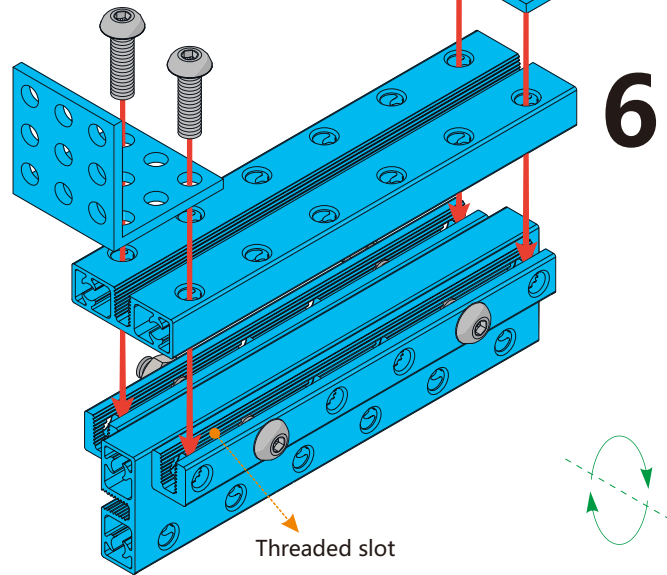
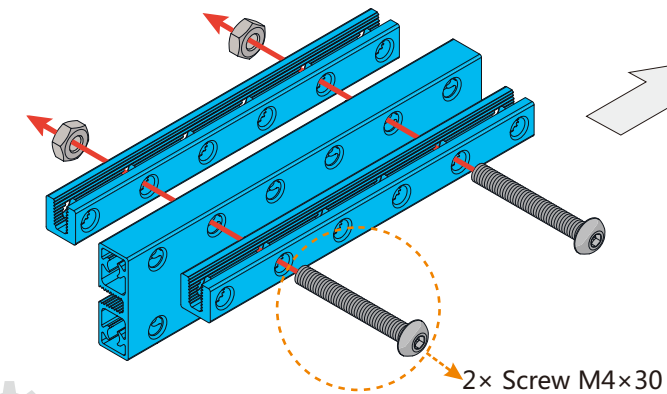


Tips: Identify the right mechanical parts from similar ones with different hole quantity included.

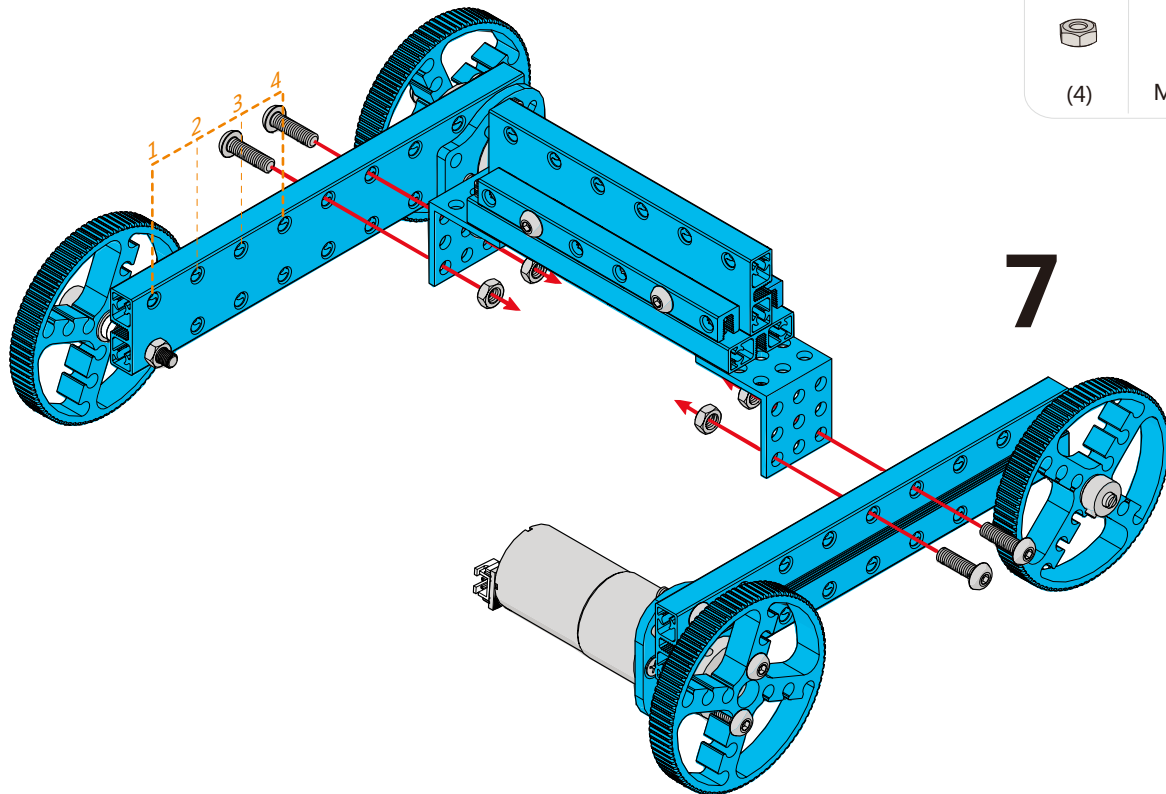
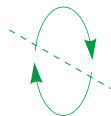




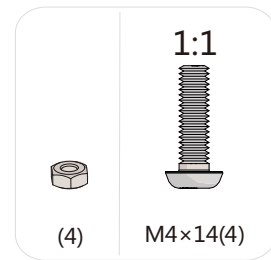
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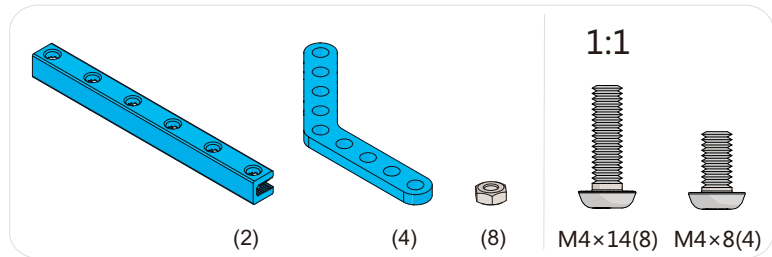


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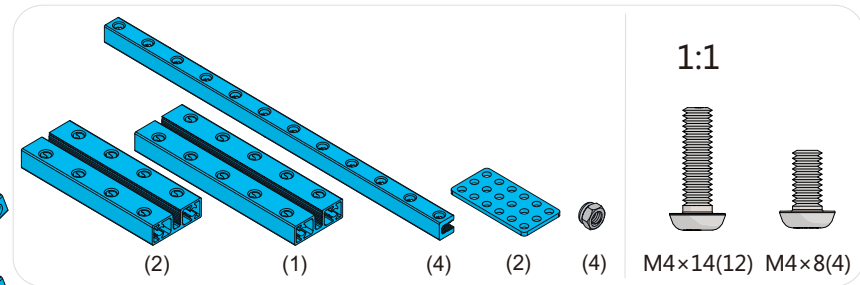
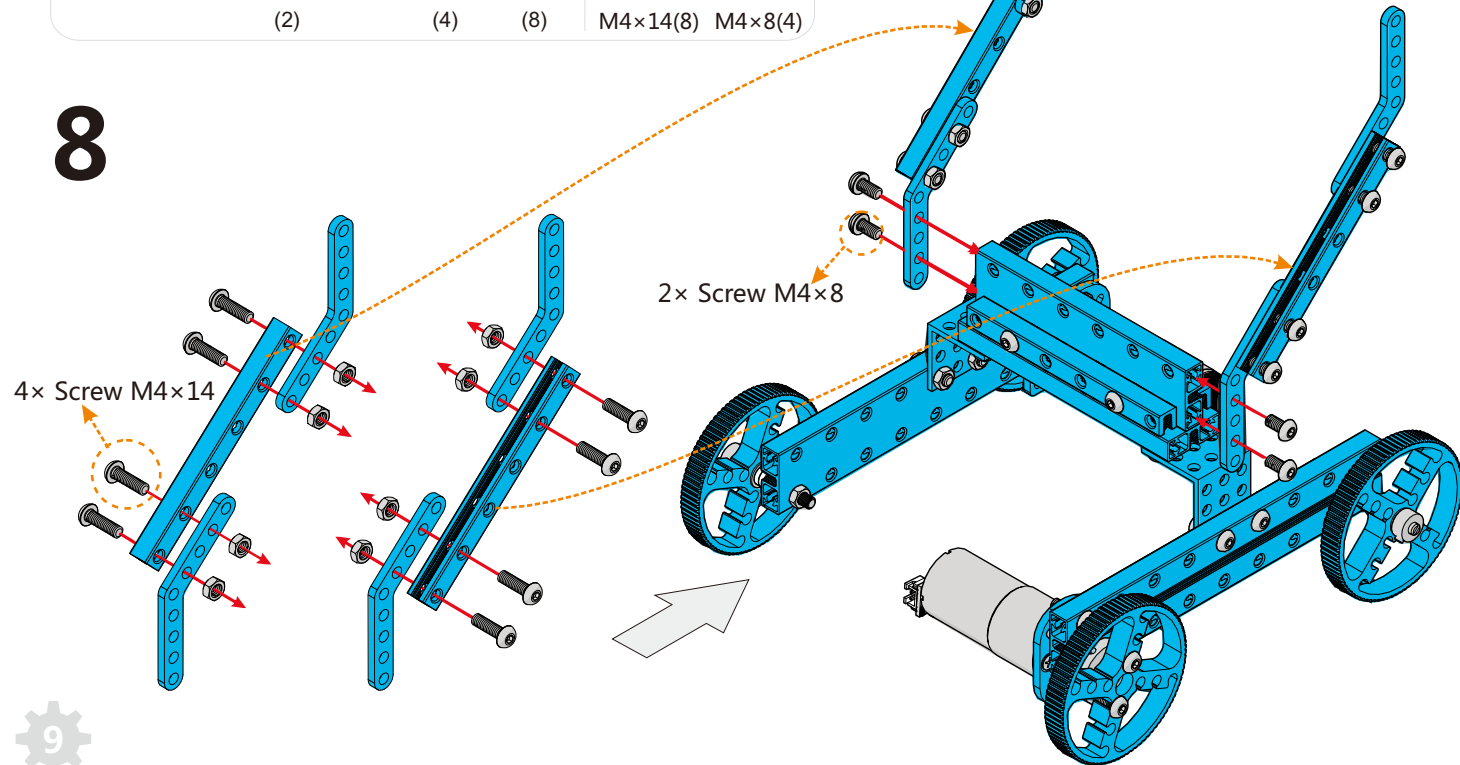


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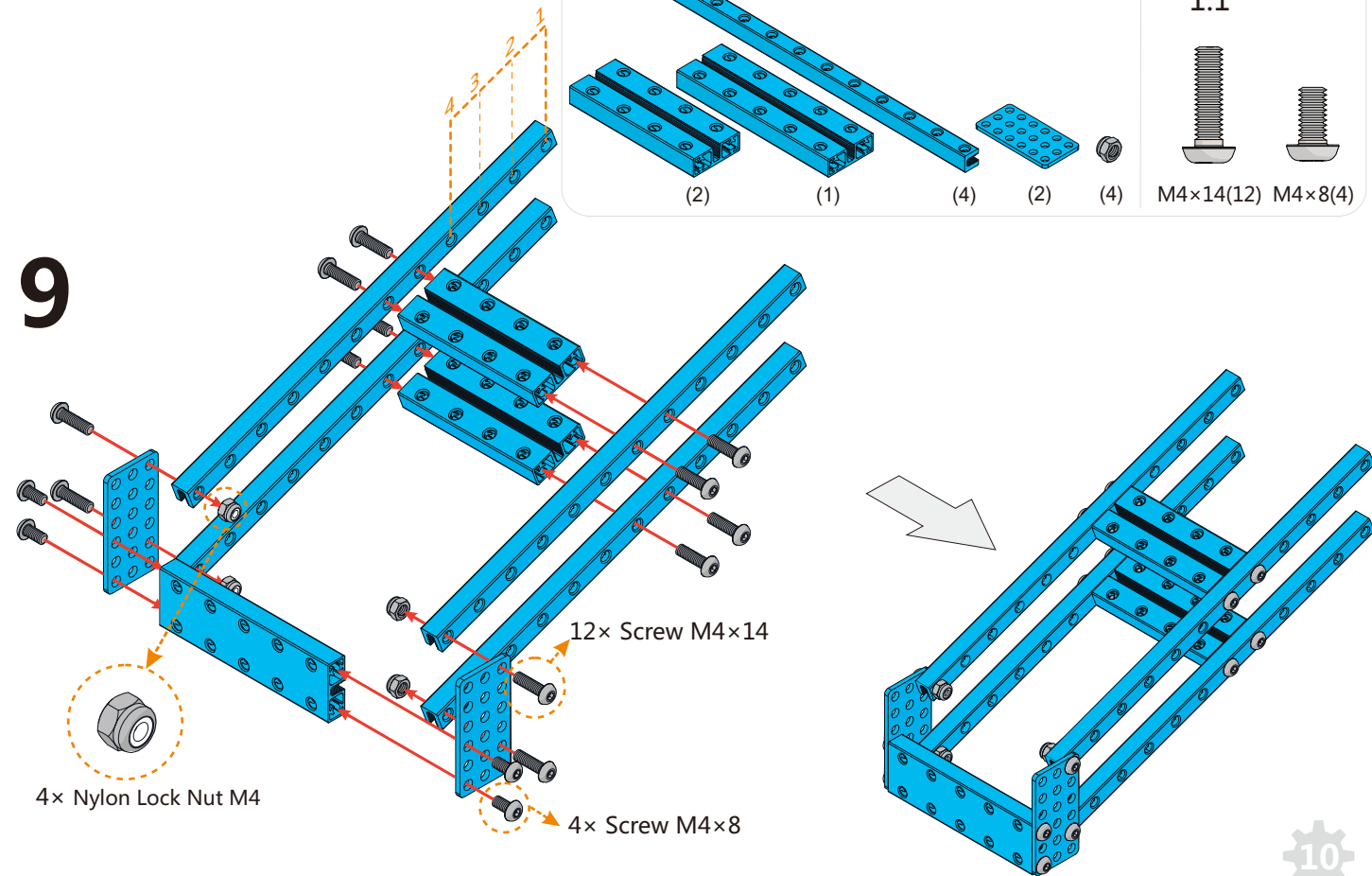


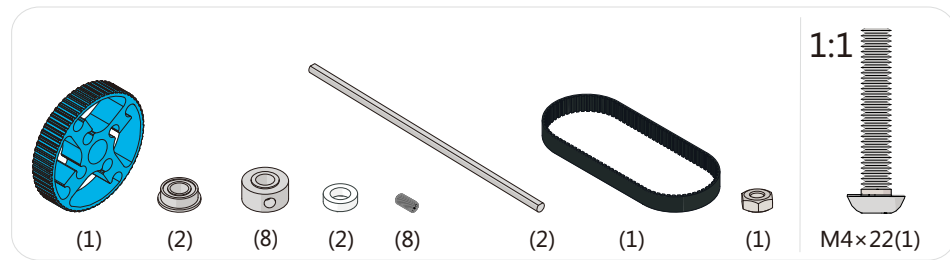


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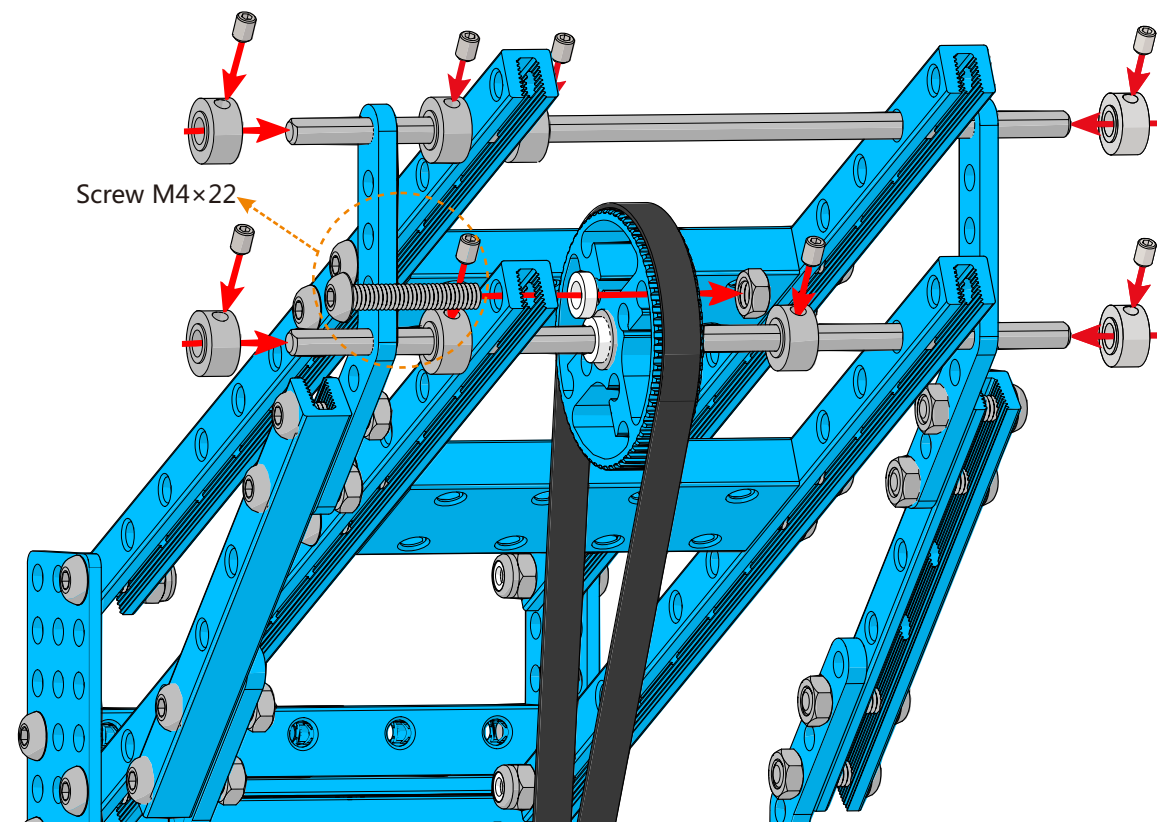
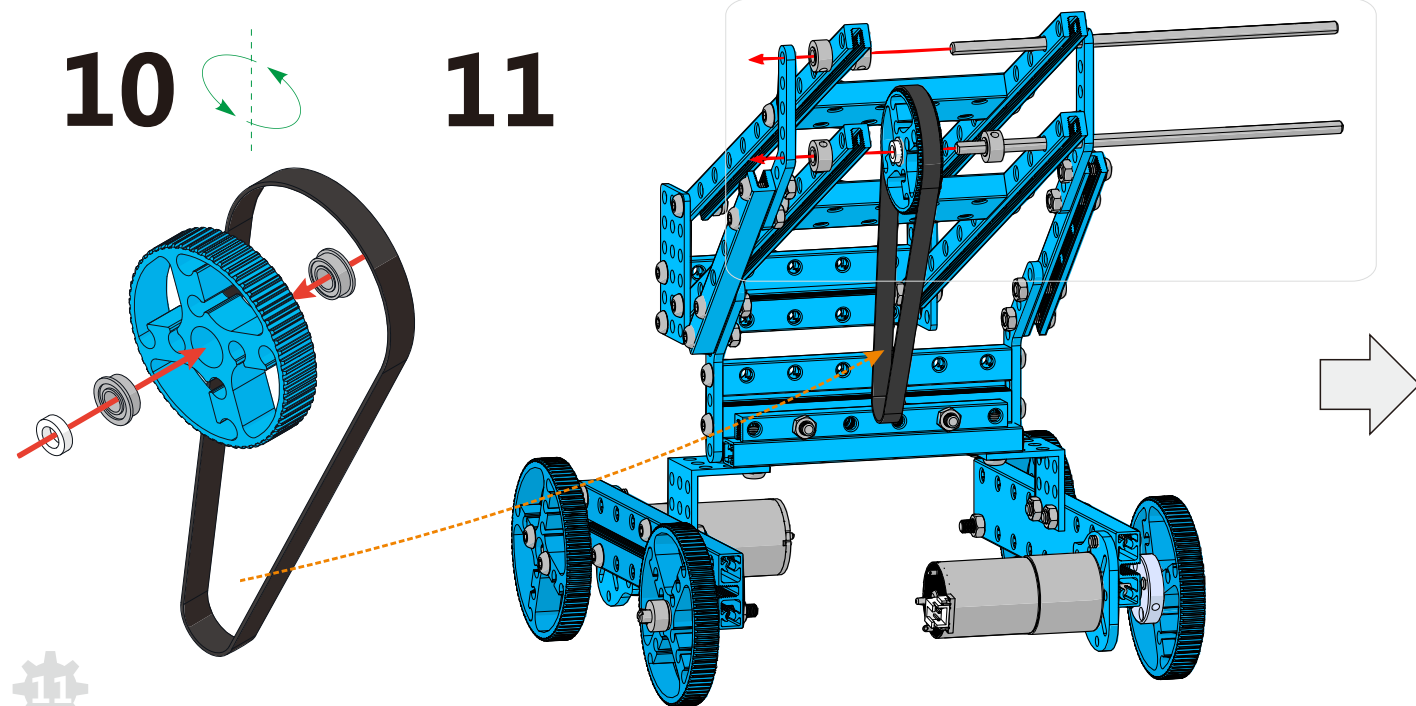
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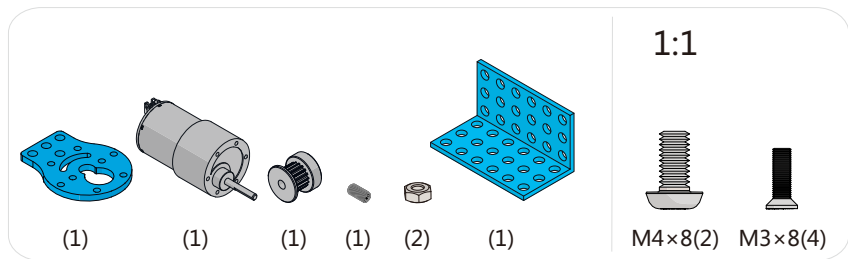
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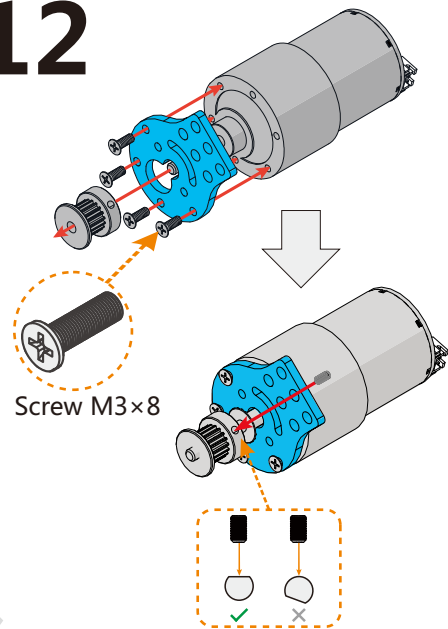
Screw M4x22



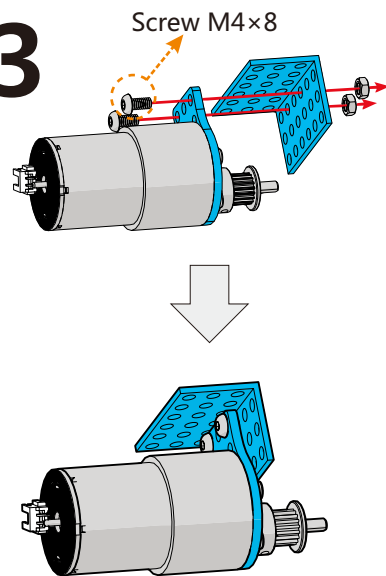




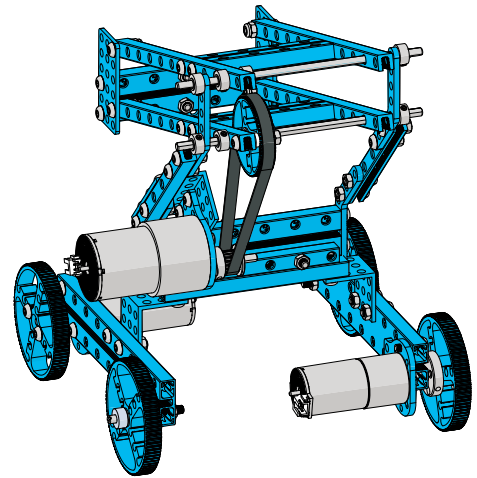
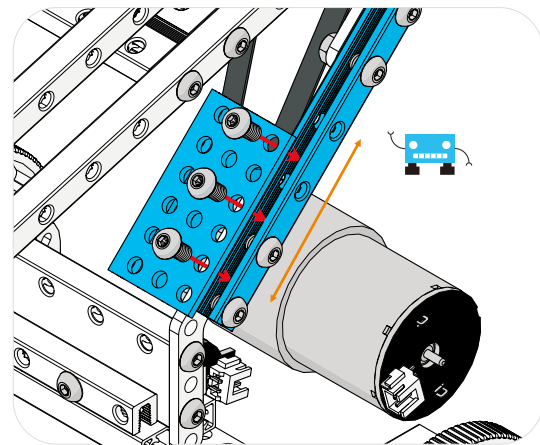
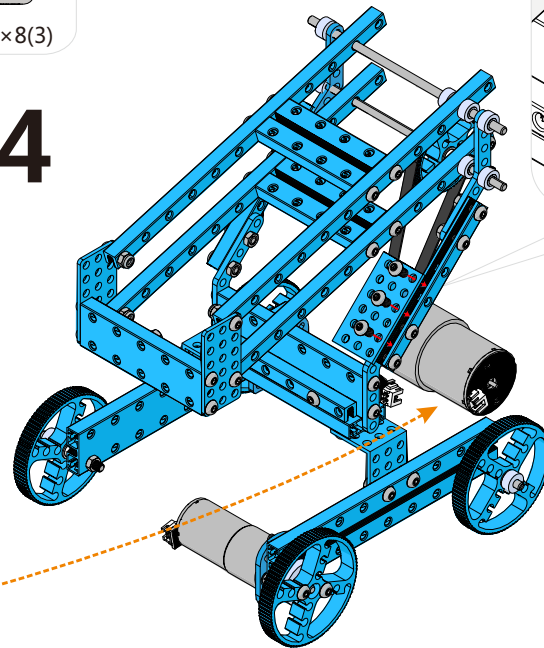
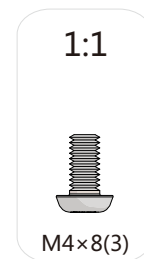
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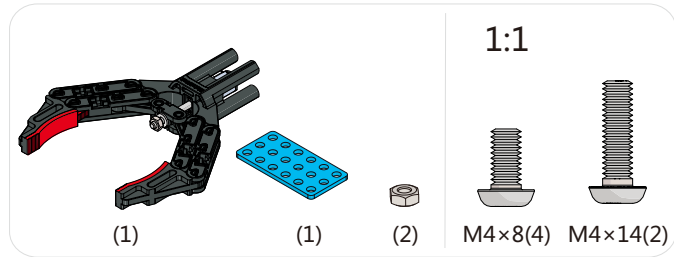
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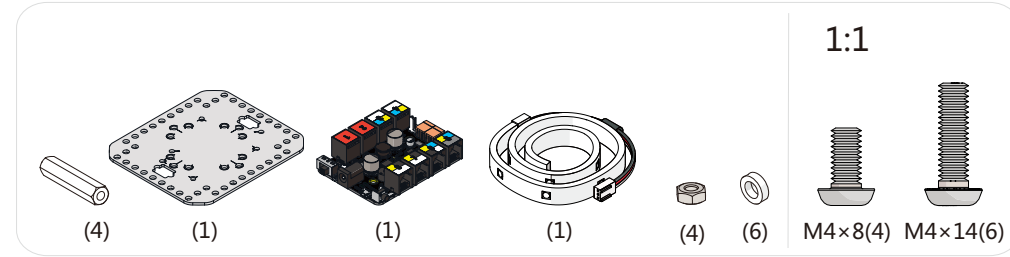
You may need to adjust the position of Bracket 3×6 to tension the timing belt.



15

2× Screw M4×14

4× Screw M4×8



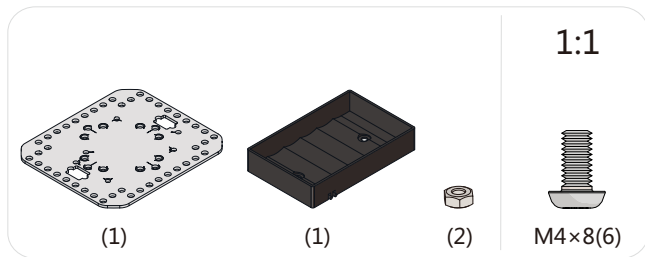
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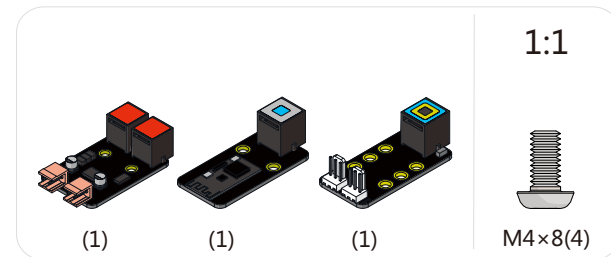
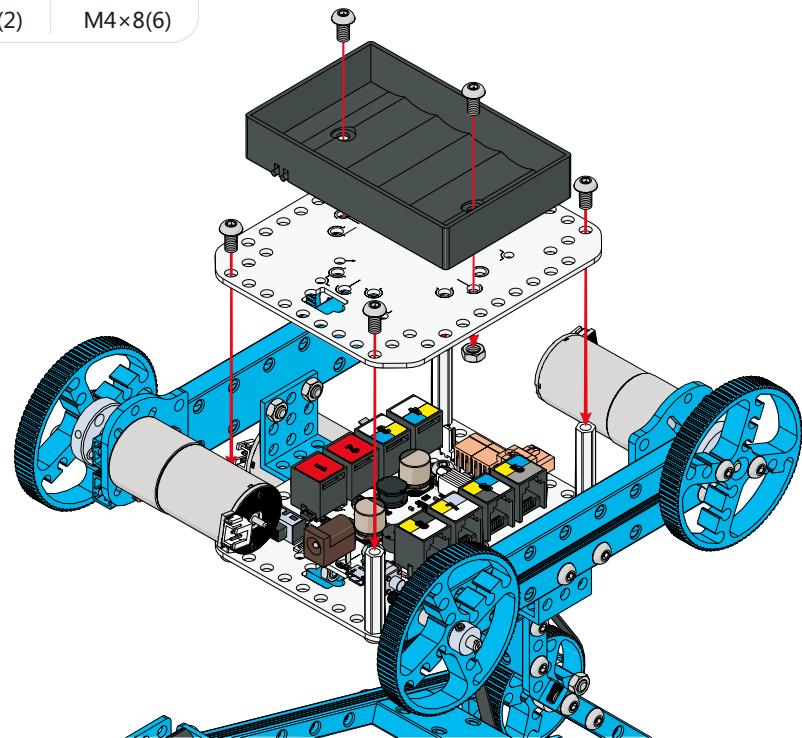
2× Screw M4×14

4× Screw M4×8

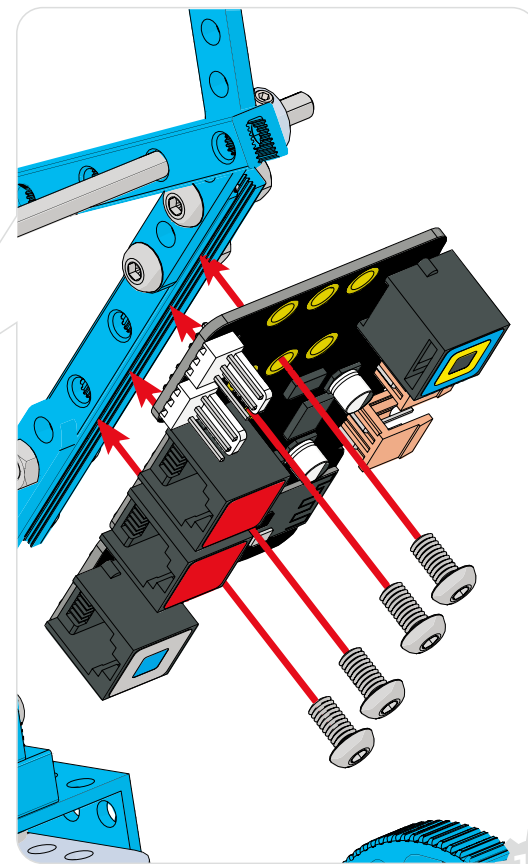
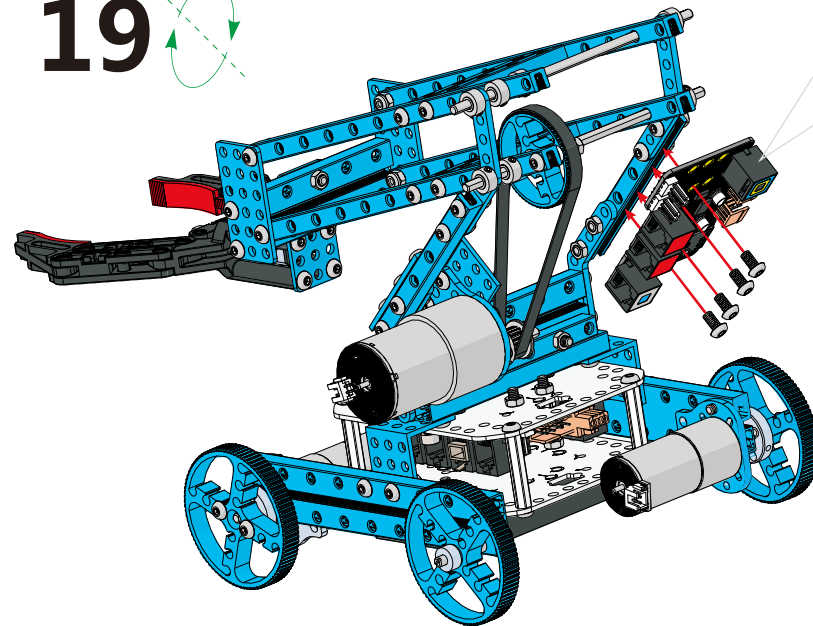
4× Screw M4×14

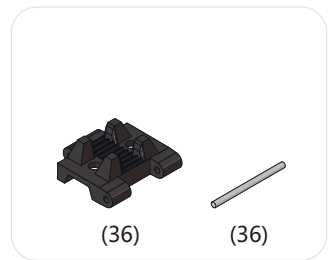


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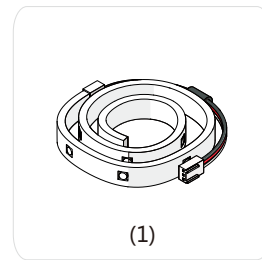
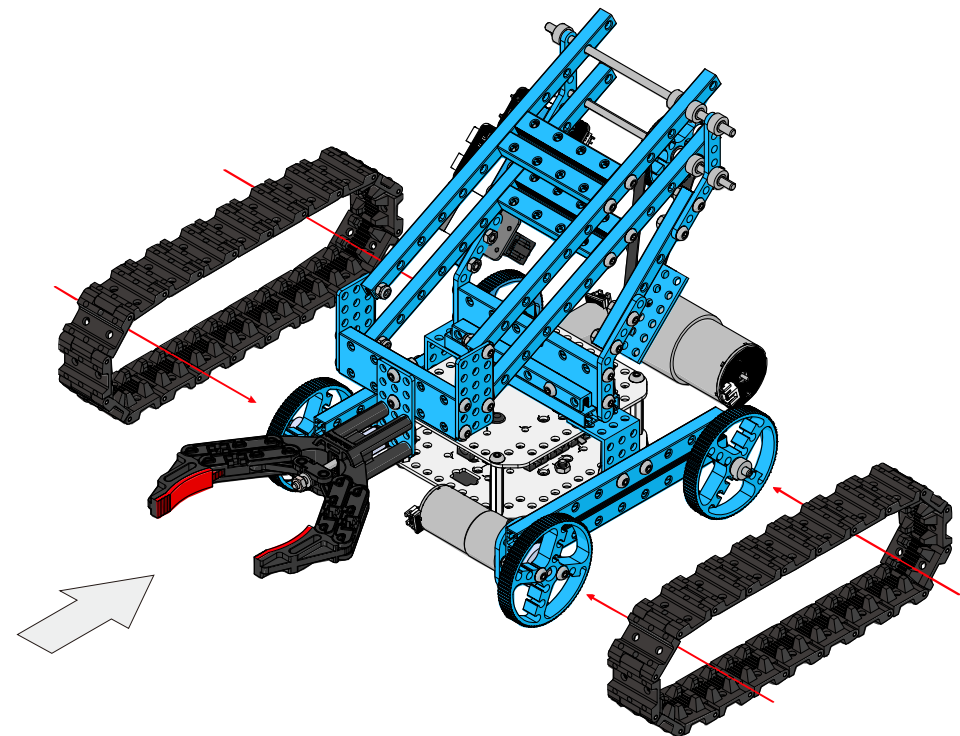
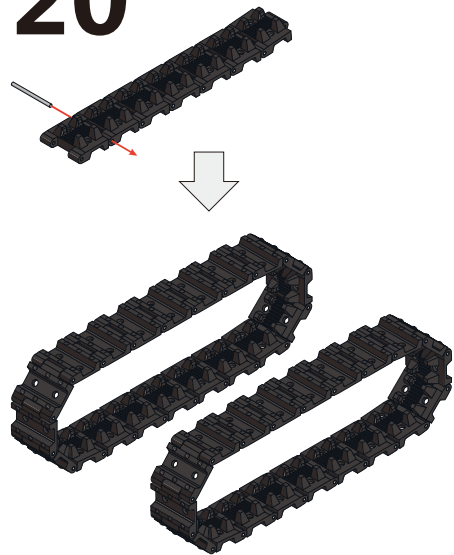


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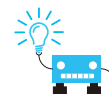
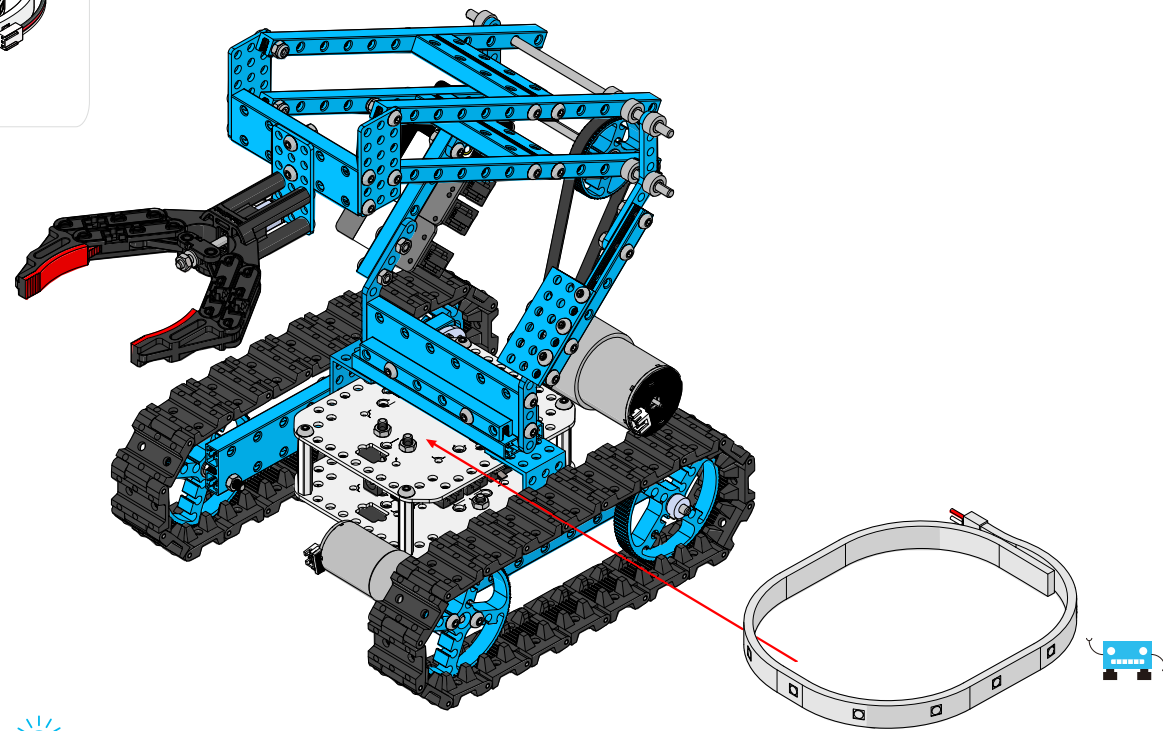




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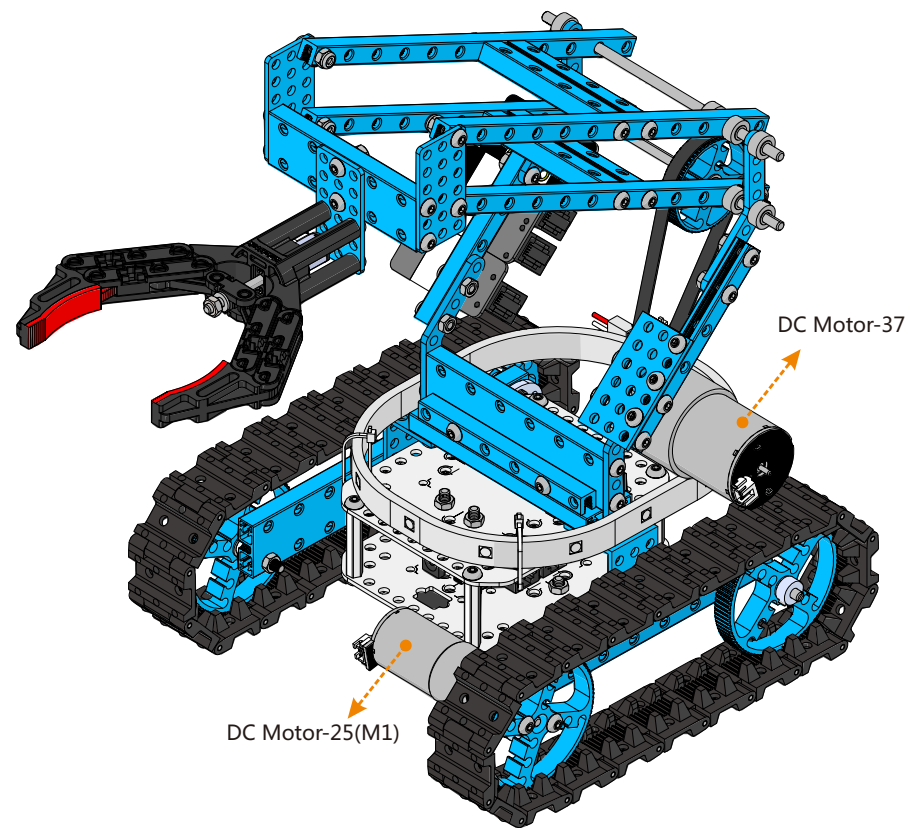


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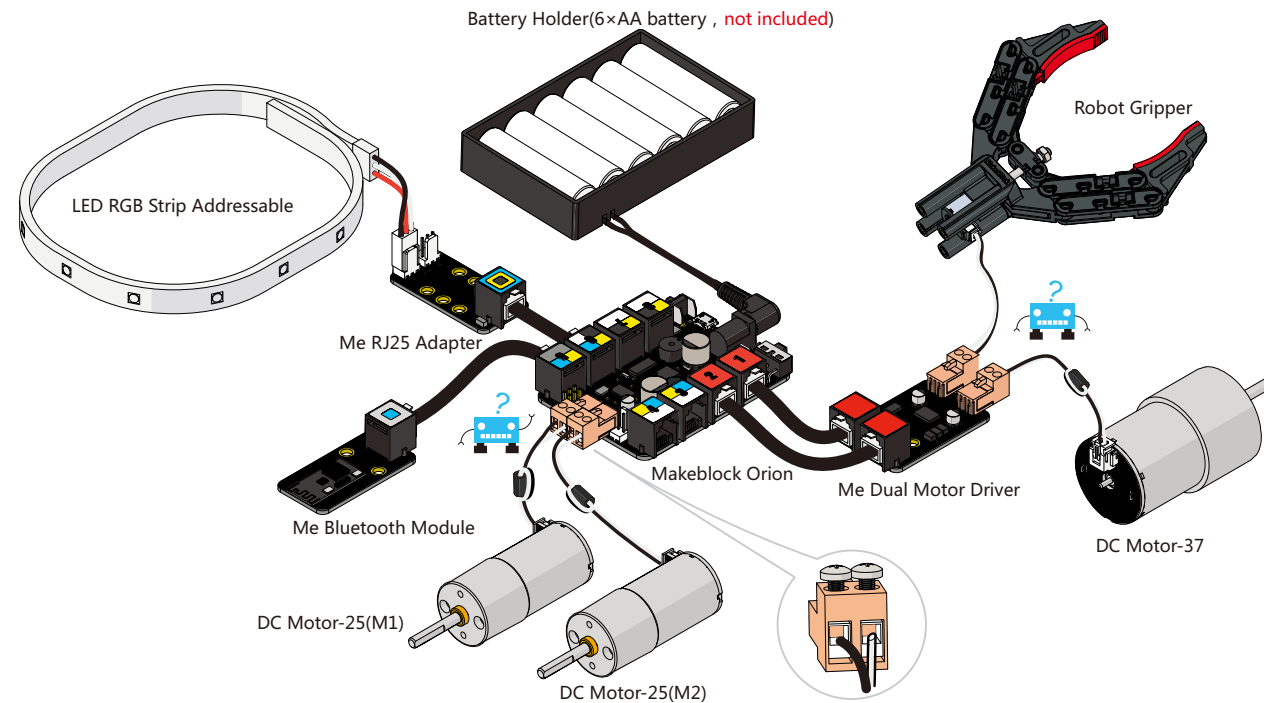
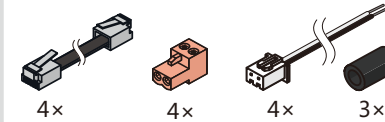
Use nylon cable ties when necessary.





## Wiring

To reduce the electromagnetic interference, please consider to add the ferrite ring to the wires which connected to motors.



# Control with App

- 1、Download and install Makeblock HD app **by either way below**.
  - A. Download Makeblock app at <http://app.makeblock.cc/>.
  - B. Scan QR code below to download Makeblock app.(Figure 1)
- 2、Check wiring, make sure everything is correct, and then turn on the power of your robot.
- 3、Turn on the Bluetooth of your smart device.
- 4、Run Makeblock app, select your robot from Examples.(Figure 2)

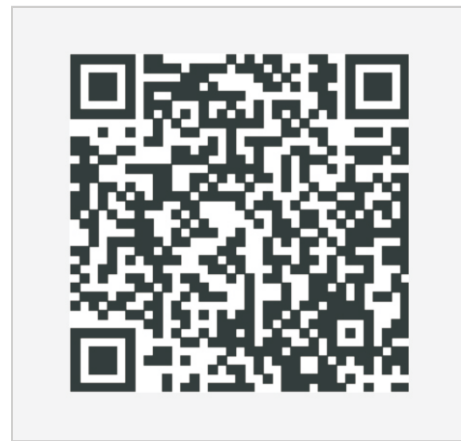


Figure 1

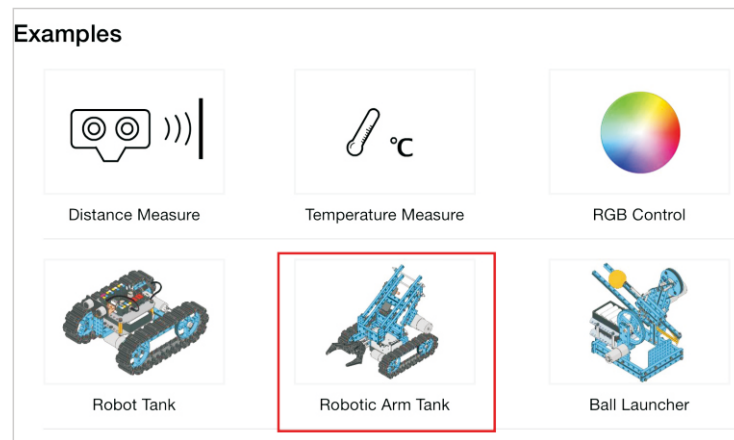


Figure 2

- 5、Put your smart device close to robot, touch the play button(Figure3)to find Bluetooth device,and then connect the robot to your smart device.(Figure 4)
- 6、Control your robot by the direction button(direction) and slider(speed).(Figure 5)

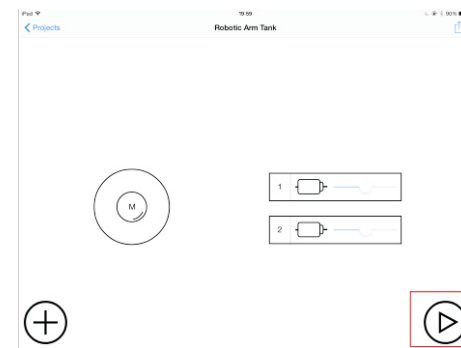


Figure 3

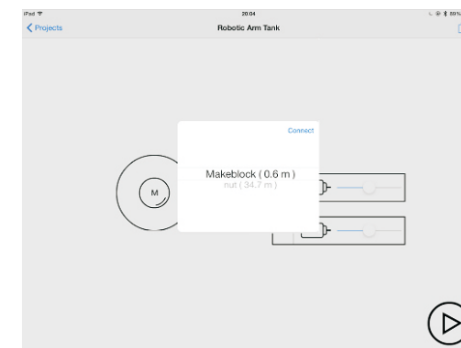


Figure 4

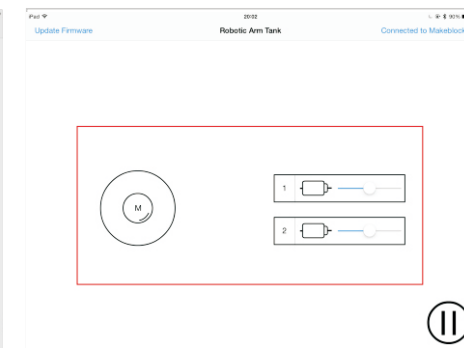
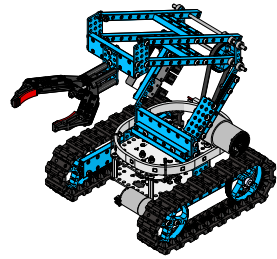


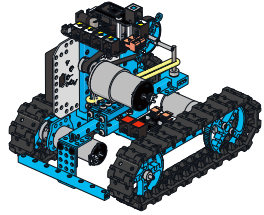
Figure 5

Now it's time to play your robot!

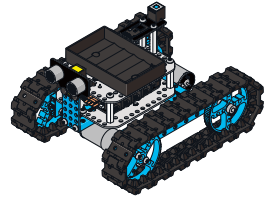
## Robot Ideas--Further exploration



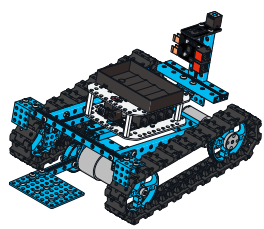
Robotic Arm Tank



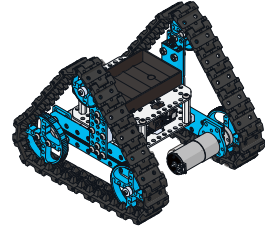
Attack Tank



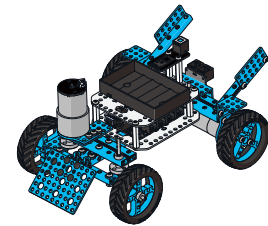
Robot Tank



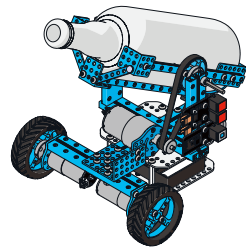
Sumo Tank



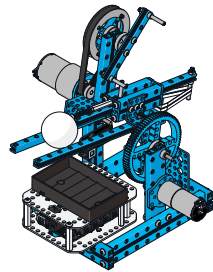
Triangular Tank



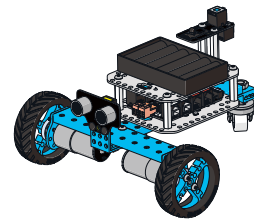
Skill Racing car



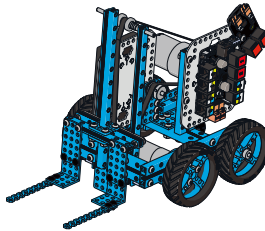
Drink Car



Ball Launcher



3-Wheeled Car



Forklift

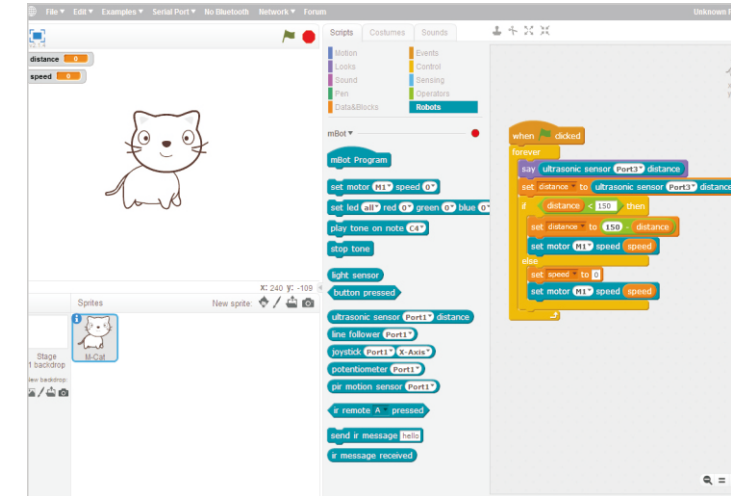


Please visit

<https://grabcad.com/makeblock-1/projects>  
to view 3D models.

## Programming--Further exploration

### Working with mBlock--Hack the Physical World



The Ultimate Robot Kit support mBlock perfectly which allow you re-programming your robot by simply drag and joint the blocks of mBlock. No more difficult coding.

mBlock is a free modified version of Scratch 2.0 developed by MIT Media Lab, mBlock add some hardware-related blocks in the original Scratch, with these blocks, users can read sensors, control motors and even a whole robot.

Besides blocks for the basic microcontroller functionalities, analog and digital writes and reads, PWM outputs. There are also blocks for each specific electronic modules, such as ultrasonic sensor, temperature sensor, light sensor, DC motor driver, stepper driver, etc. With these blocks, it's simple to interact with many kinds of electronic modules.


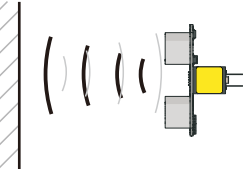
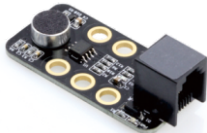


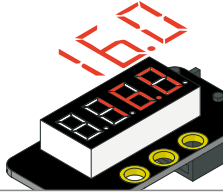

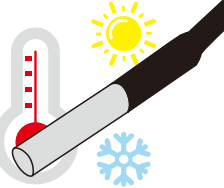
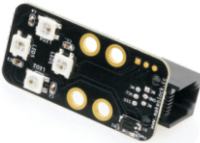




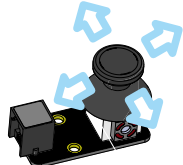
Visit the following URL for more details:  
<http://learn.makeblock.cc/learning-scratch>

### Working with Arduino IDE --Learn Programming the Fun Way

Arduino is an open-source electronics prototyping platform based on flexible , easy-to-use hardware and software.The Arduino software consists of a development environment (IDE) and the core libraries. The IDE is written in Java and based on the Processing development environment.

Visit the following URL for more details: <http://learn.makeblock.cc/learning-Arduino>  
Download the library zip package: <https://github.com/Makeblock-official/Makeblock-Library/archive/master.zip>

Electronic modules on makeblock--Further exploration

	<p>Ultrasonic module works for measuring distance from 3cm to 400cm.</p>			<p>Me Sound Sensor can measure the volume. It can be used in some sound interactive projects, such as a voice-operated switch.</p>	
	<p>Me 7-Segment Display is a display module with four digit tube which can show some data, such as speed, time, score etc.</p>			<p>Me Temperature Sensor is a stainless steel tube sensor which is used for measuring temperature.</p>	
	<p>Me RGB LED module contains four programmable RGB LEDs. Color of each LED can be set by editing components of red, green, and blue.</p>			<p>Me PIR Motion Sensor can detect infrared ray which derives from animals/humans in less than 6 meters.</p>	
	<p>Me Joystick is normally used to control the move direction of object.</p>		see more on makeblock platform		

Kits on Makeblock--Further exploration

