

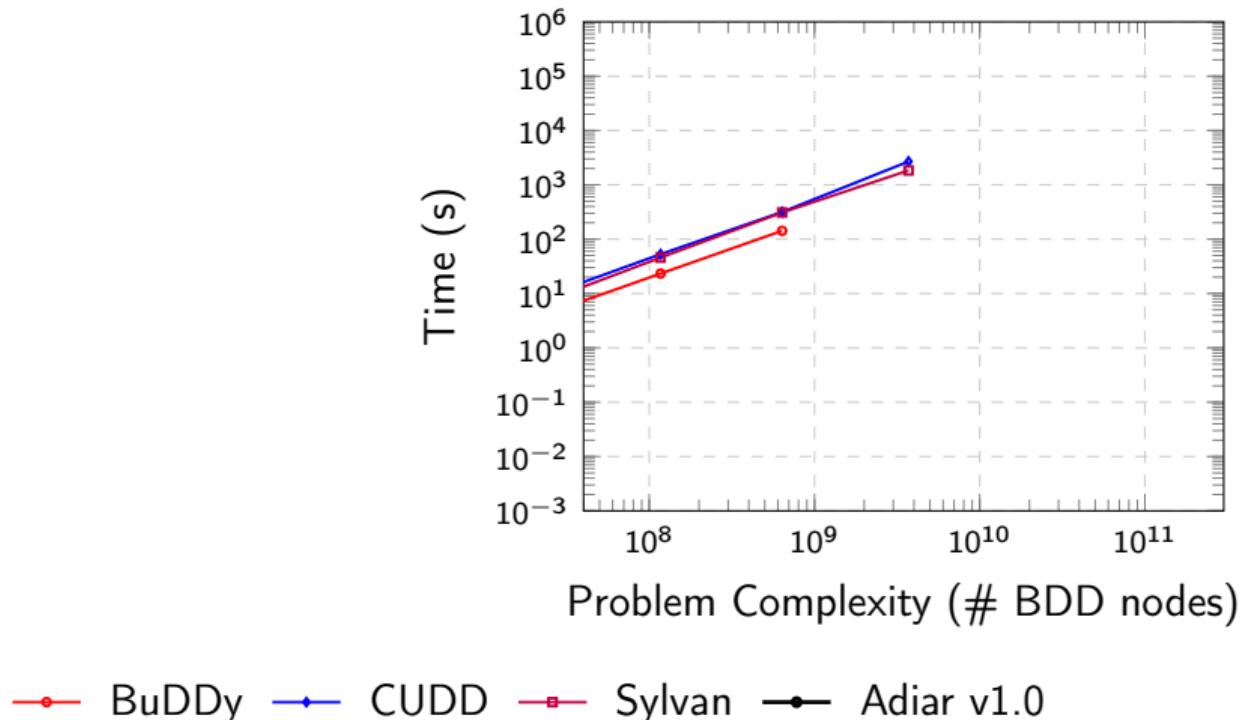
Predicting Memory Demands of BDD Operations using Maximum Graph Cuts

Steffan Christ Sølvsten and Jaco van de Pol

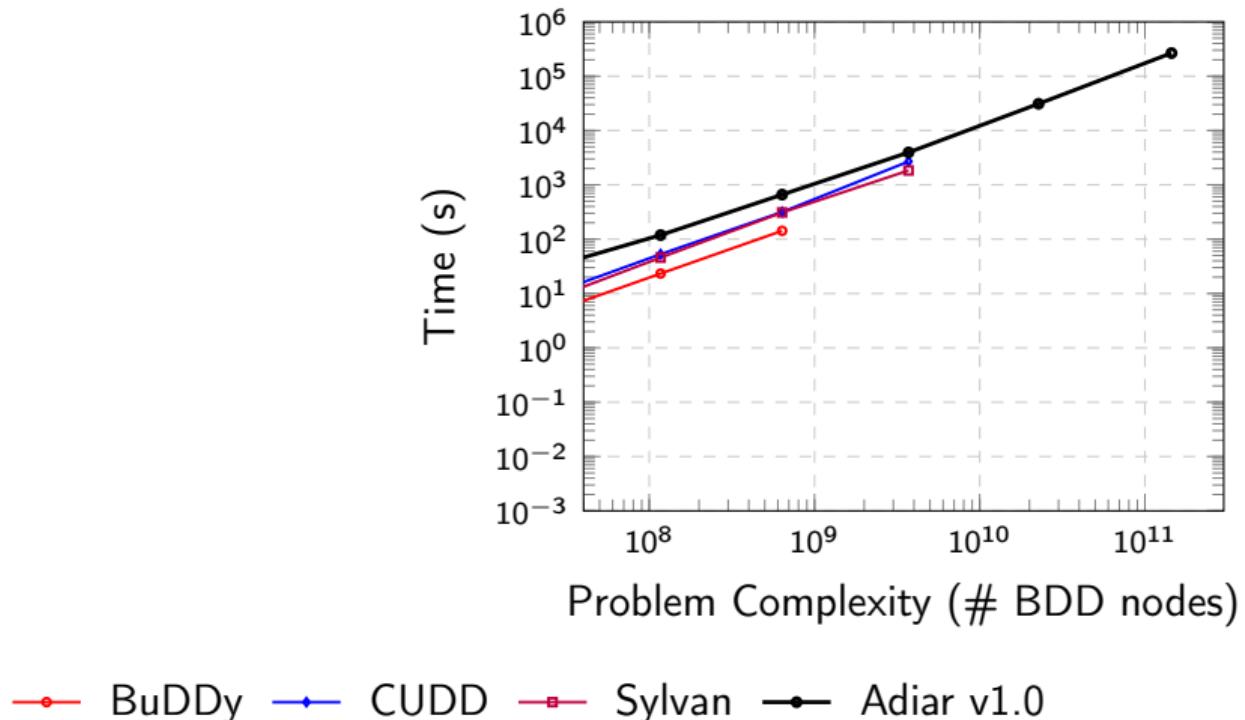
ATVA 2023



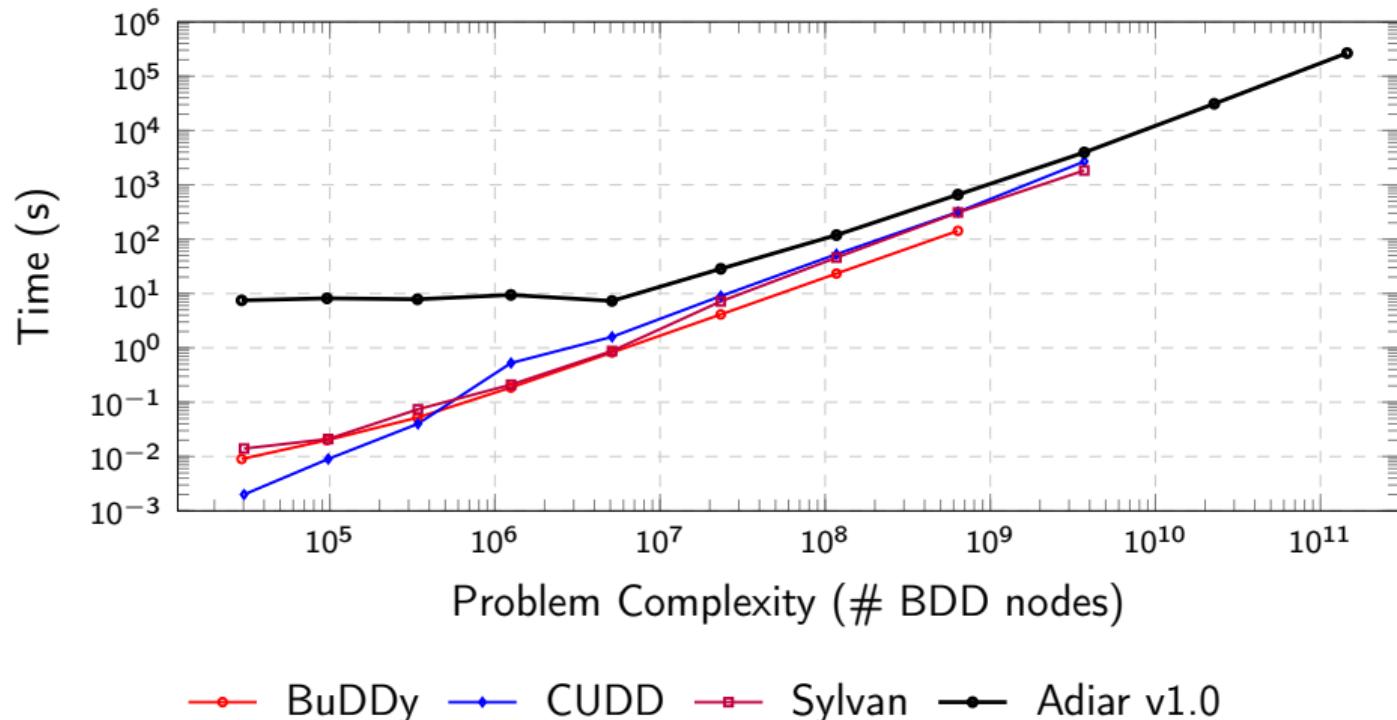
AARHUS
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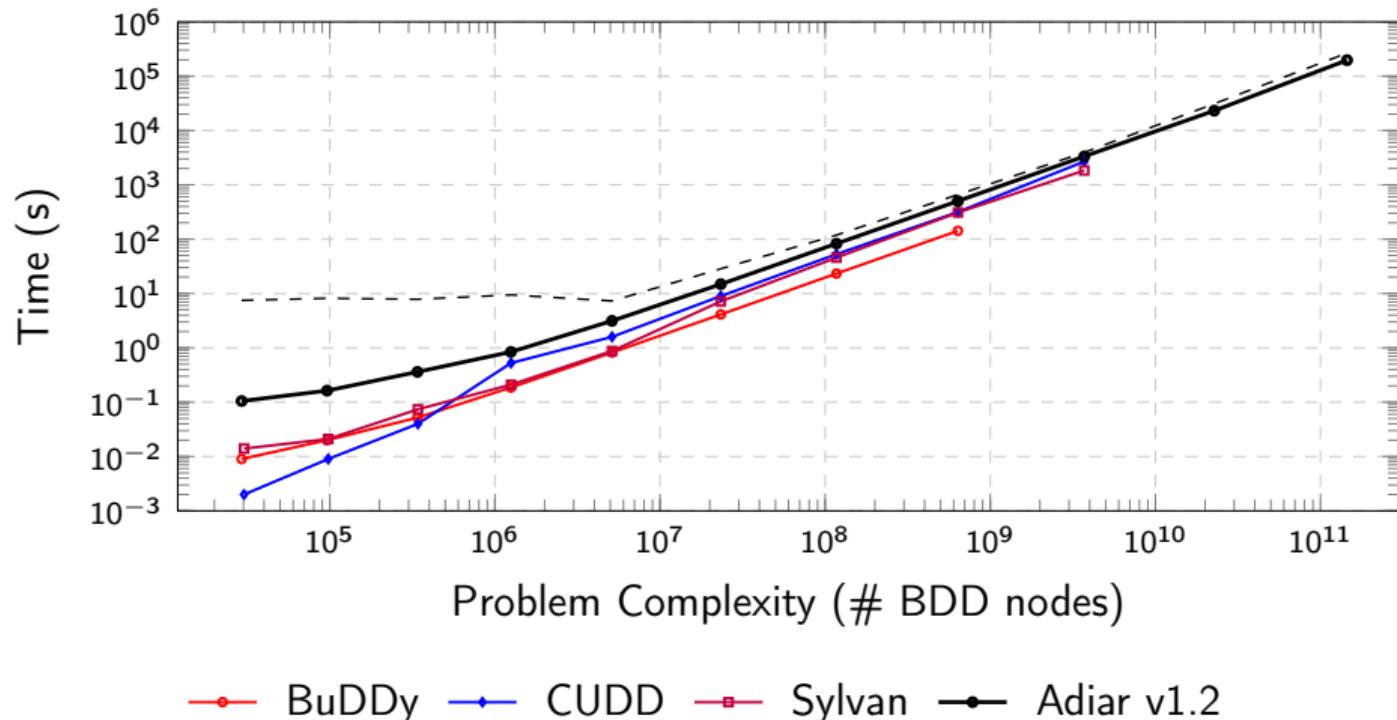
Running Time to solve N -Queens problems.



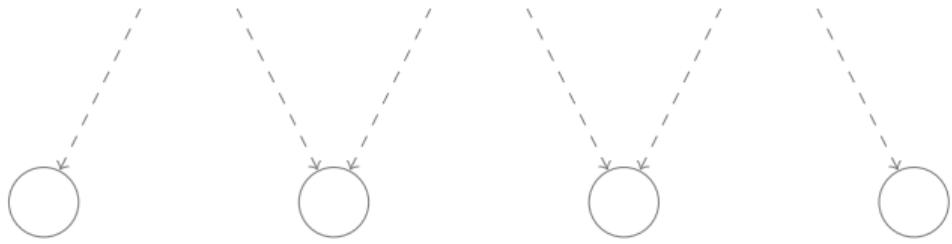
Running Time to solve *N*-Queens problems.



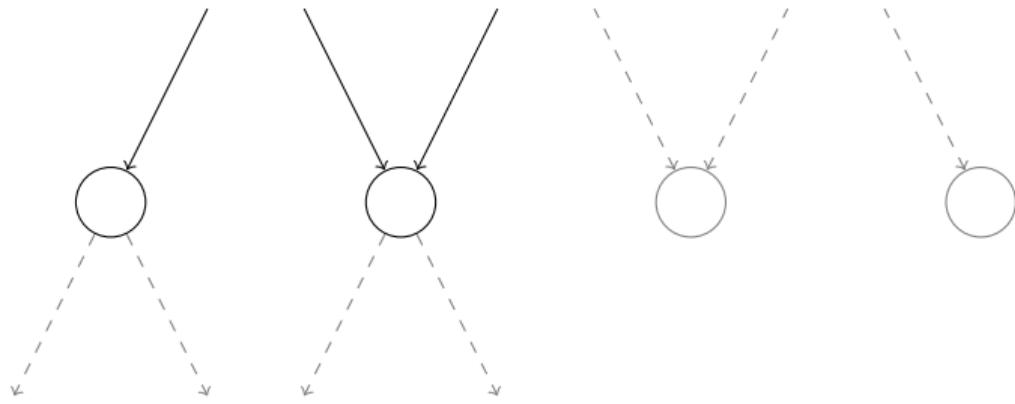
Running Time to solve N -Queens problems.

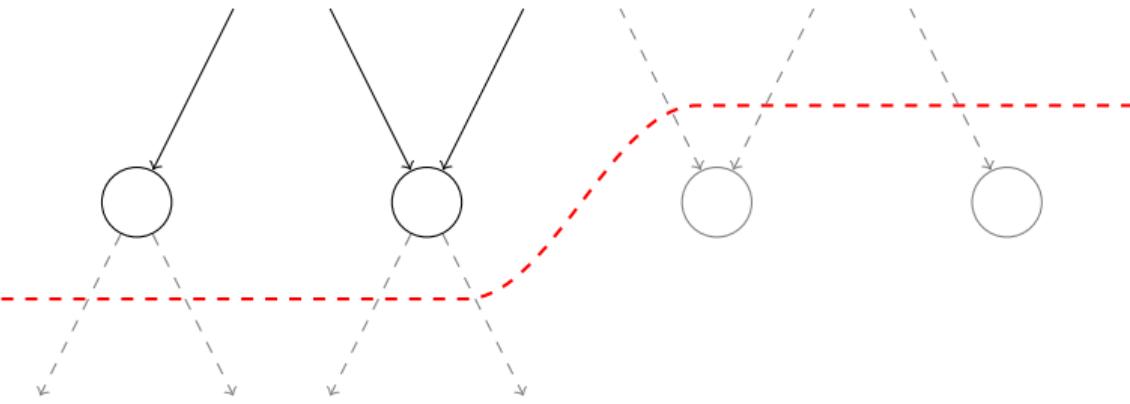


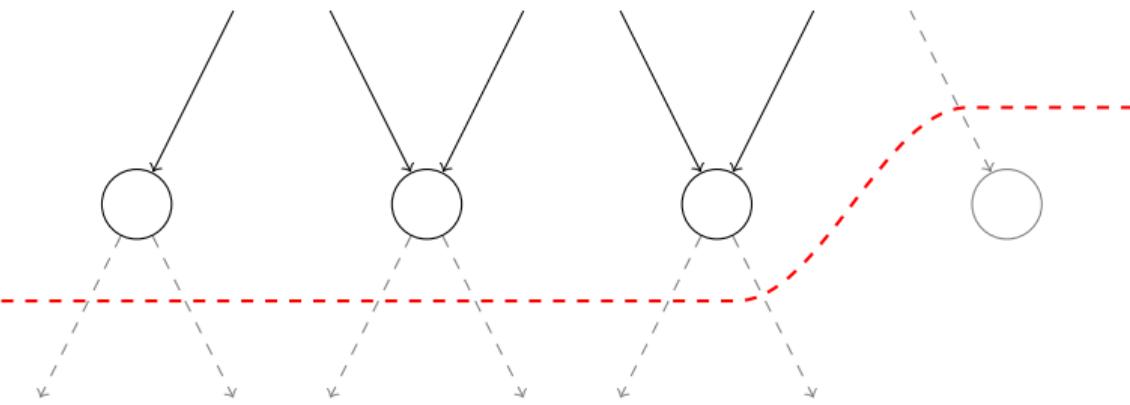
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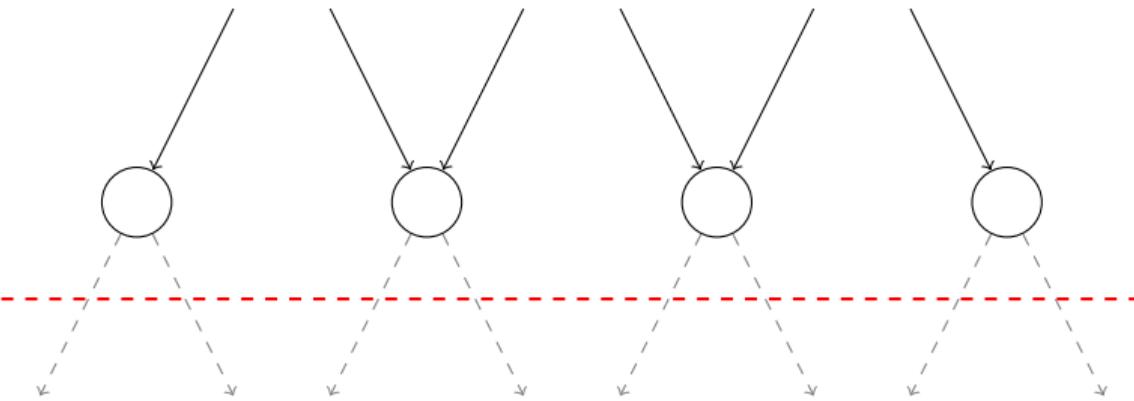




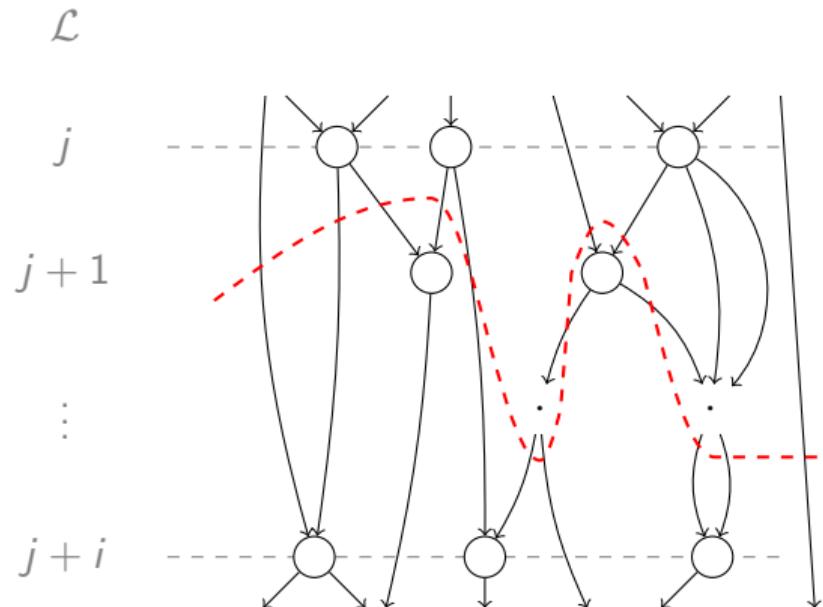




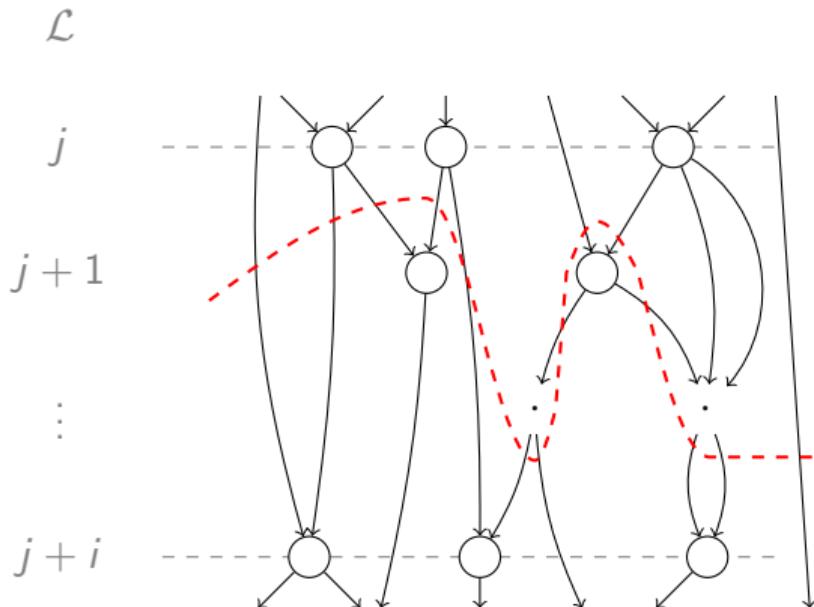




i -level cut



i -level cut



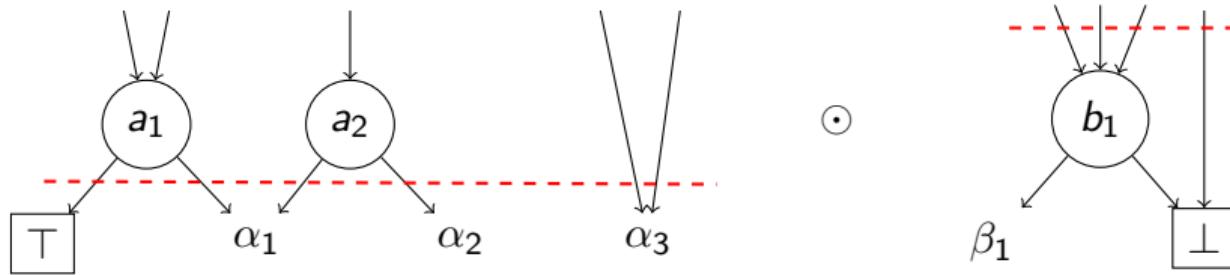
Lemma (Sølvsten, Van de Pol 2023)
The maximum i -level cut problem is in P for $i \in \{1, 2\}$.

Theorem (Lampis, Kaouri, Mitsou 2011)
The maximum i -level cut problem is NP-complete for $i \geq 4$.

Theorem (Sølvsten, Van de Pol 2023)

Given maximum 2-level cuts size C_f for f and C_g for g , the maximum 2-level cut for $f \odot g$ is less than or equal to $C_f \cdot C_g$.

Proof.

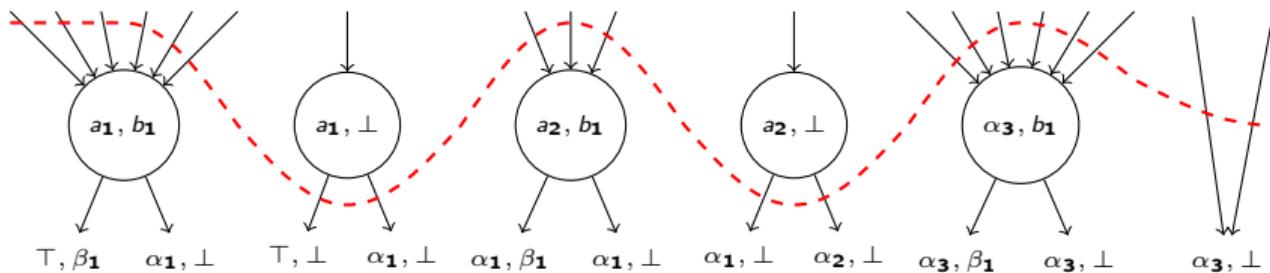


□

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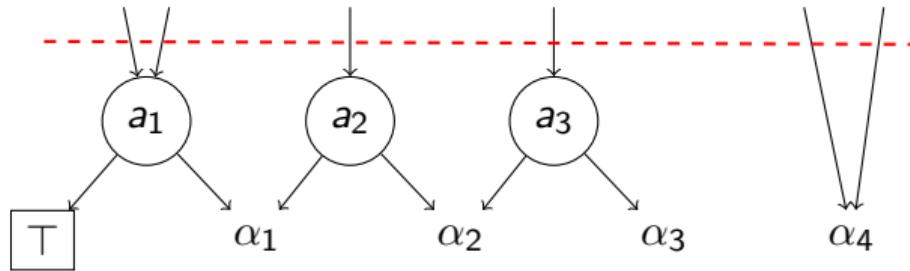


□

Lemma (Sølvsten, Van de Pol 2023)

The maximum 2-level cut for f is at most $\frac{3}{2}$ larger than its maximum 1-level cut.

Proof.

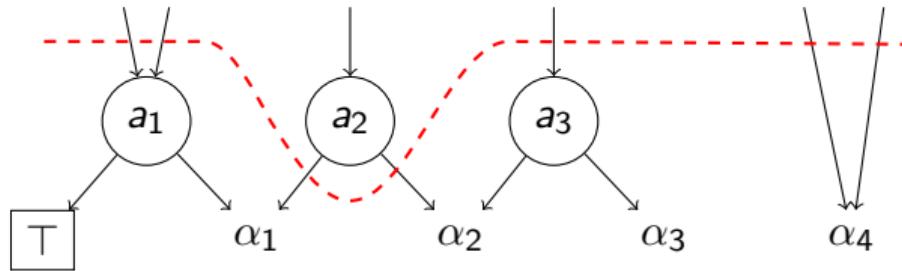


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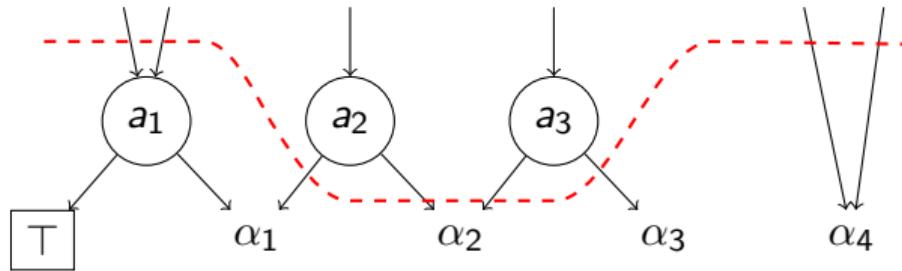


□

Lemma (Sølvsten, Van de Pol 2023)

The maximum 2-level cut for f is at most $\frac{3}{2}$ larger than its maximum 1-level cut.

Proof.



□



		Overhead	Precision
1-level cut	:	1.0%	69.2%
2-level cut	:	3.3%	86.3%

Possible to process a

1.1 GiB BDD

with only

128 MiB Memory



Running Time

Adiar v1.0 : 56.5 hours

Verification of the 15 smallest EPFL circuits.



Running Time

Adiar v1.0 : 56.5 hours

Adiar v1.2 : 4.0 hours (-93%)¹

Verification of the 15 smallest EPFL circuits.

¹ 52.1 of these hours were saved on just verifying the `sin` circuit alone.

Steffan Christ Sølvsten

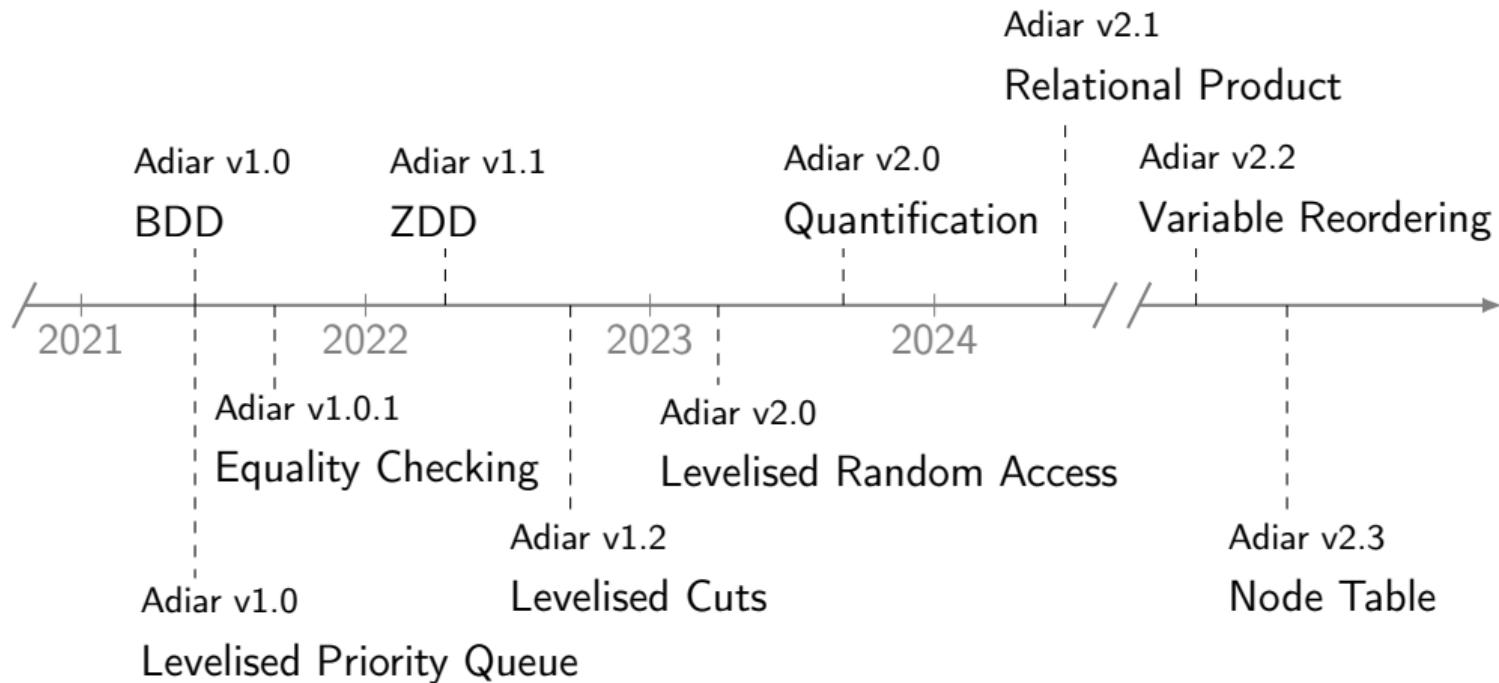
✉️ soelvsten@cs.au.dk

🌐 ssoelvsten.github.io

Adiar

🔗 github.com/ssoelvsten/adiar

💻 ssoelvsten.github.io/adiar



					Disk R/W	Transition Cost
	Sufficient?	Overhead	Memory ²			
DF ▶ Adiar (✗	3×	–	2×	–	–
DF Adiar (✓	–	3×	2×	–	–
DF → Adiar 1.0	✗ ¹	–	–	–	–	$\Omega(N \log N)$
State Pattern (✓ ⁴	~ 20% ³	2×	–	–	$\Omega(N)$
<i>i</i> -level cut (✓ ⁴	1%	–	–	–	–

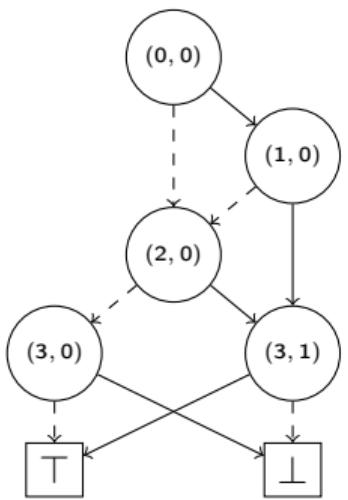
Comparison of possible solutions.

¹There can be a gap between when depth-first runs out of memory and Adiar 1.0 has no overhead.

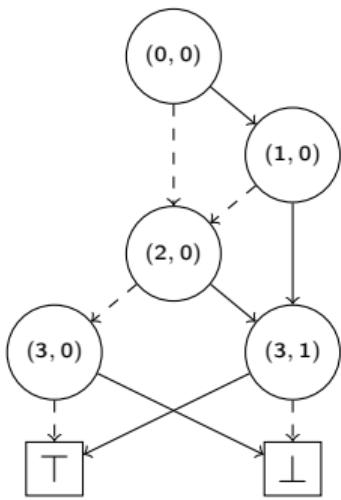
²Decreasing the memory dedicated to an external memory data structure impacts its performance.

³Runtime polymorphism adds a 20% to 30% overhead [Stroustrup].

⁴This solves the gap¹; a *non-trivial* integration with depth-first algorithms can cover tiny cases.



(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

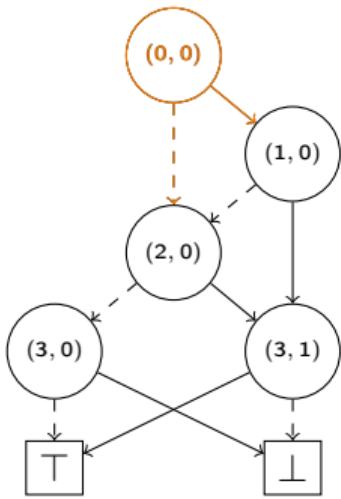


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Priority Queue: Q_{count} :

[

]

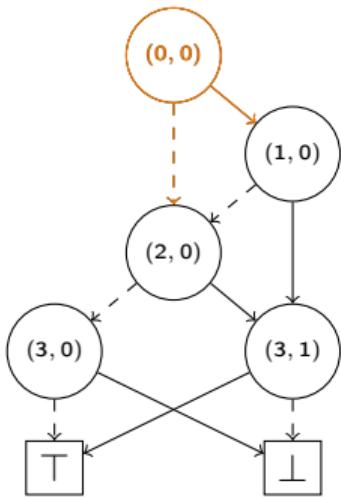


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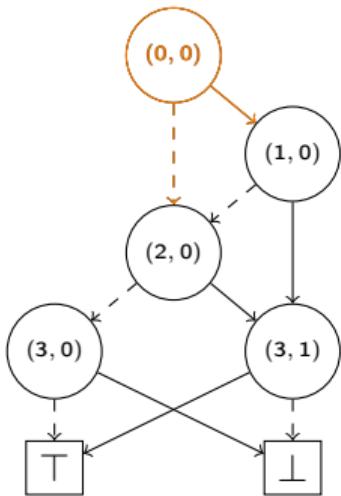


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Priority Queue: Q_{count} :

- [$((0, 0) \xrightarrow{\top} (1, 0), 1)$,
- $((0, 0) \xrightarrow{\perp} (2, 0), 1)$,

]

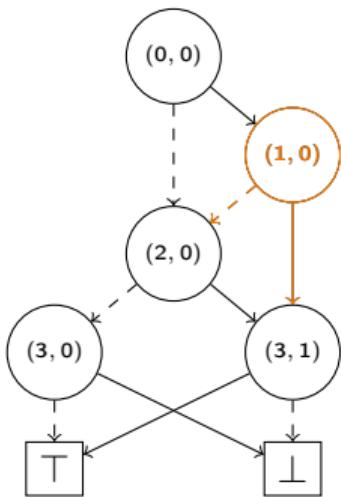


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(1, 0)	0	0

Priority Queue: Q_{count} :
 [$((0, 0) \xrightarrow{\top} (1, 0), 1)$,
 $((0, 0) \xrightarrow{\perp} (2, 0), 1)$,

]

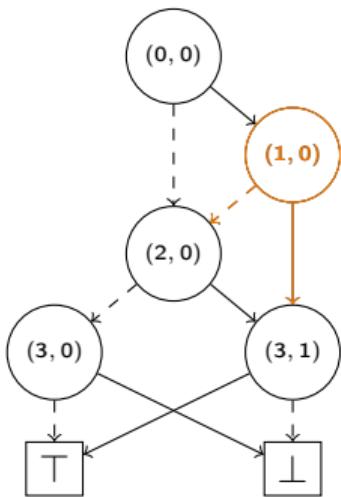


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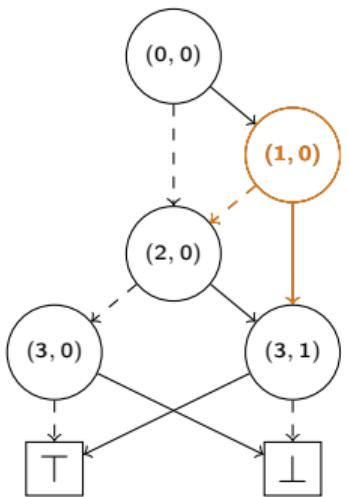


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
$(1, 0)$	1	0

Priority Queue: Q_{count} :
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 $((0, 0) \xrightarrow{\perp} (2, 0), 1)$,

]

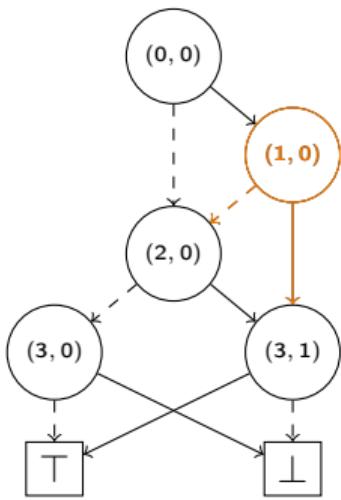


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(1, 0)	1	0

Priority Queue: Q_{count} :

[$((0, 0) \xrightarrow{\perp} (2, 0), 1)$,
	$((1, 0) \xrightarrow{\perp} (2, 0), 1)$,
	$((1, 0) \xrightarrow{\top} (3, 1), 1)$,
]		

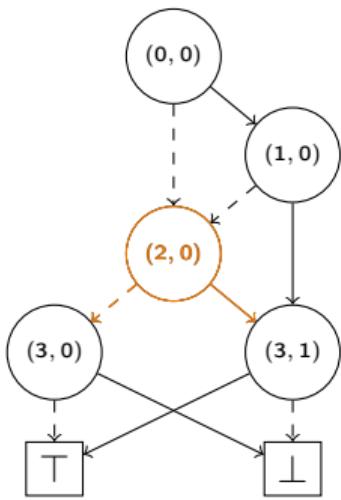


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(2, 0)	0	0

Priority Queue: Q_{count} :

[
 $((0, 0) \xrightarrow{\perp} (2, 0), 1)$,
 $((1, 0) \xrightarrow{\perp} (2, 0), 1)$,
 $((1, 0) \xrightarrow{\top} (3, 1), 1)$]

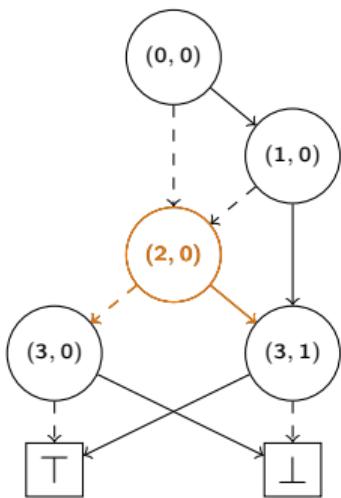


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Seek	Sum	Result
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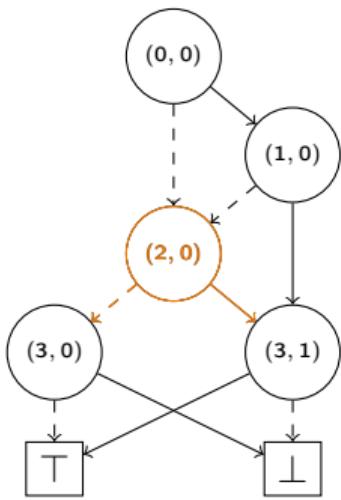


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(2, 0)	1	0

Priority Queue: Q_{count} :

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 $((1, 0) \xrightarrow{\perp} (2, 0), 1)$,
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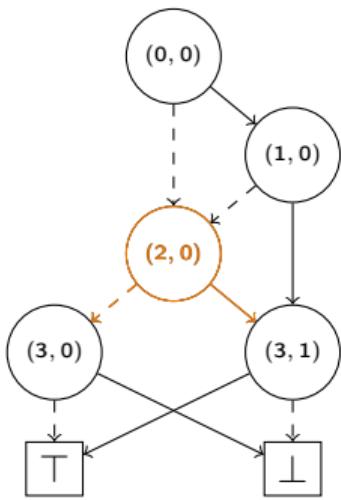


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(2, 0)	2	0

Priority Queue: Q_{count} :

[
 $((1, 0) \xrightarrow{T} (3, 1), 1)$,
]



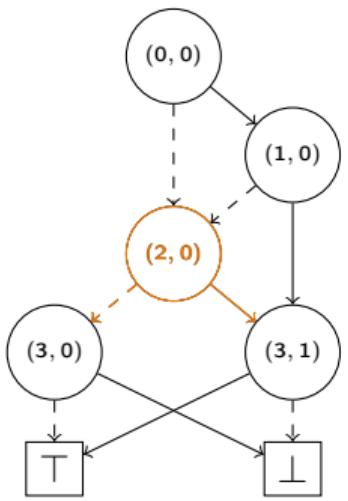
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(2, 0)	2	0

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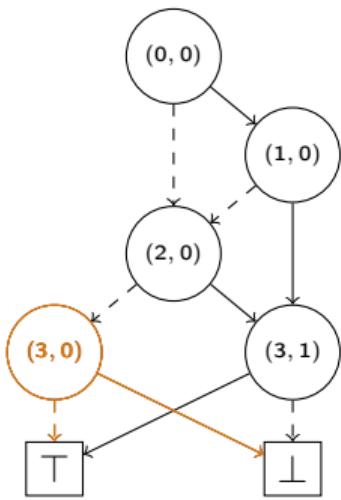
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Seek	Sum	Result
(3, 0)	0	0

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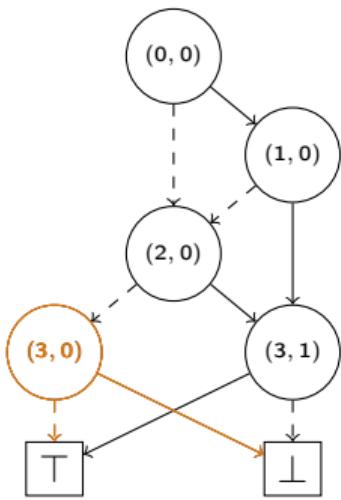
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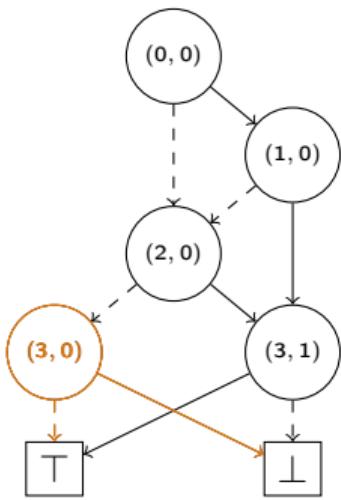
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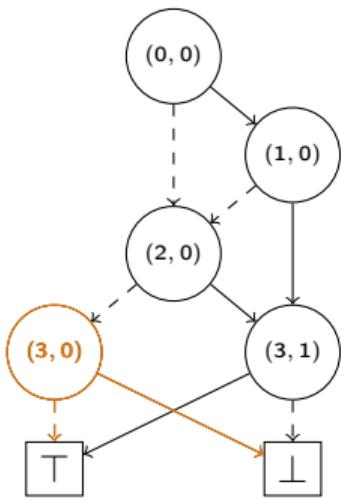
(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(3, 0)	2	2

Priority Queue: Q_{count} :

[

$((1, 0) \xrightarrow{\top} (3, 1), 1)$,
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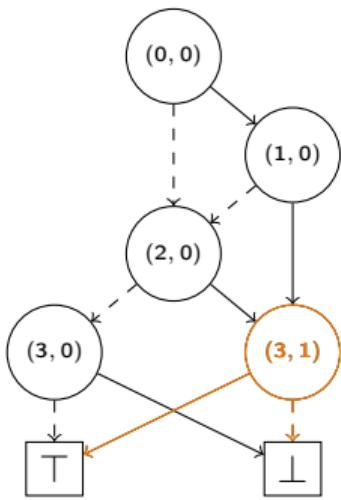
(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(3, 1)	0	2

Priority Queue: Q_{count} :

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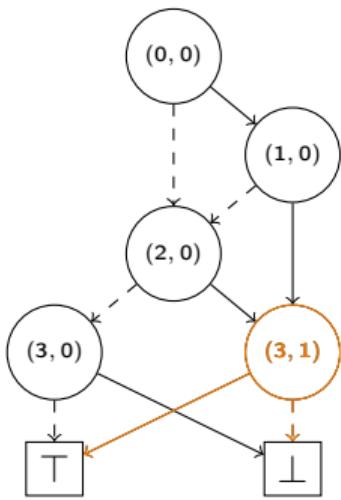
(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(3, 1)	0	2

Priority Queue: Q_{count} :

[

$((1, 0) \xrightarrow{\top} (3, 1), 1)$,
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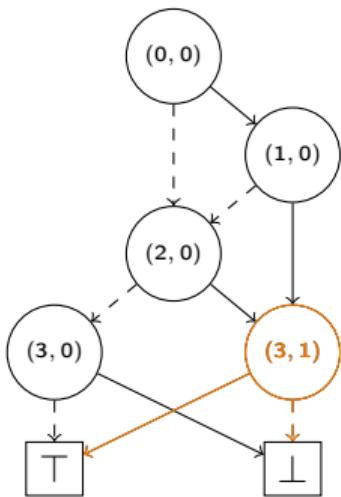
(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(3, 1)	1	2

Priority Queue: Q_{count} :

[

$((2, 0) \xrightarrow{\top} (3, 1), 2)]$

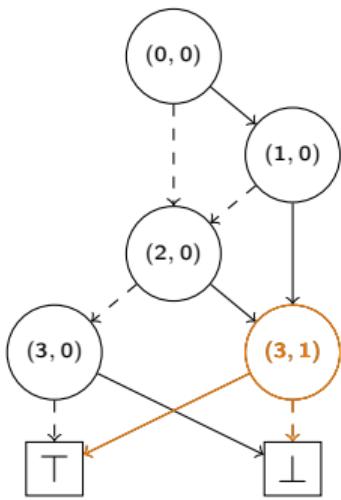


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(3, 1)	3	2

Priority Queue: Q_{count} :
[

]

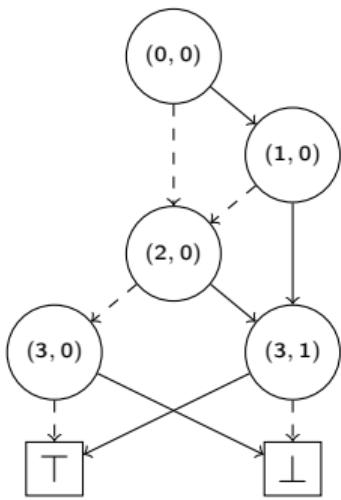


(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Seek	Sum	Result
(3, 1)	3	5

Priority Queue: Q_{count} :
[

]



(a) $(x_0 \wedge x_1 \wedge x_3) \vee (x_2 \oplus x_3)$

Result
5

Priority Queue: Q_{count} :

[

]

Steffan Christ Sølvsten

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Adiar

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