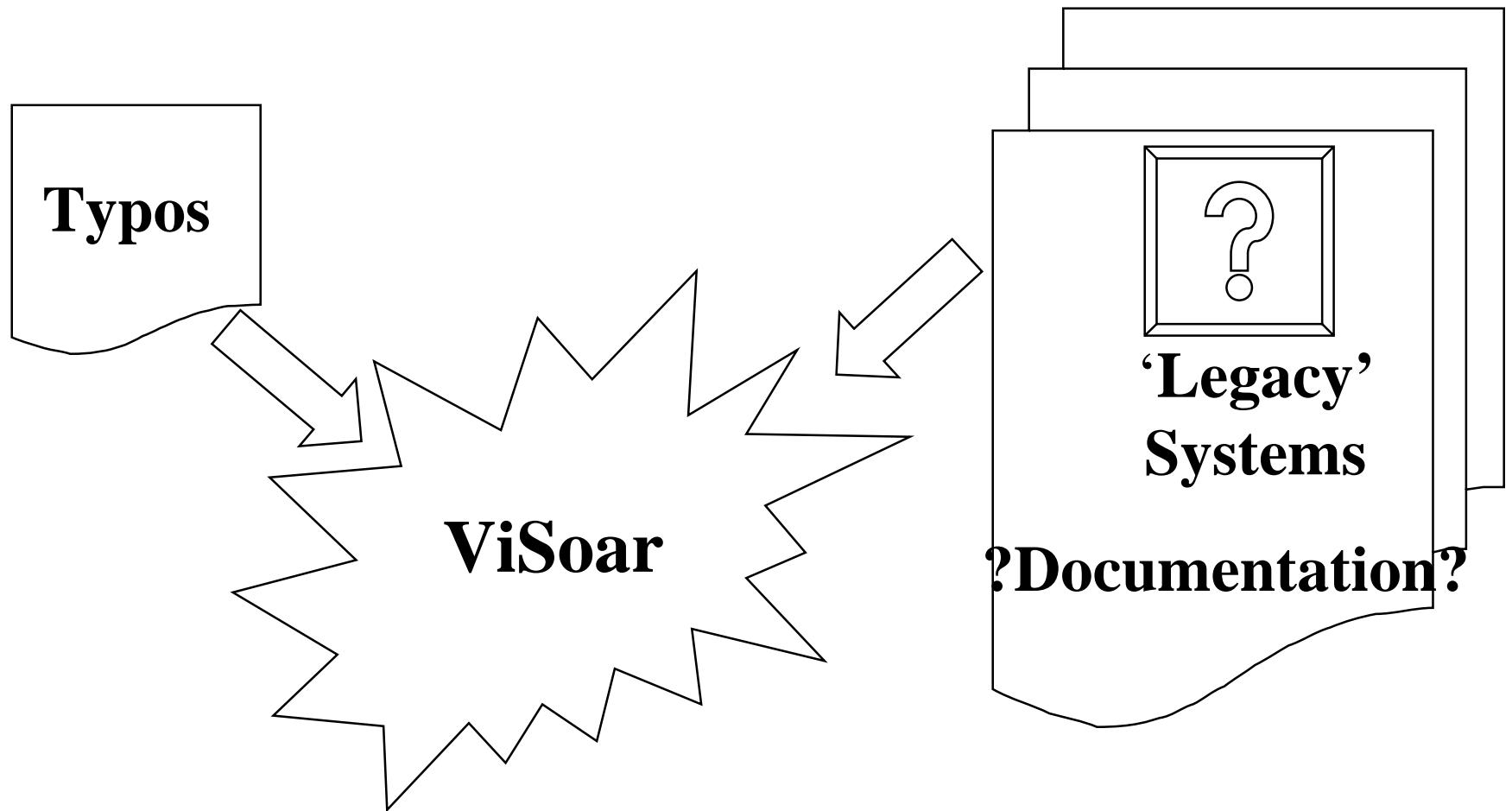


ViSoar

Intelligent Agents Group,
University of Portsmouth

<http://www.dcs.port.ac.uk/~hirsta/visoarx.htm>

ViSoar Genesis



Background to ViSoar

- Typos
- Whilst evaluating Milind's STEAM ruleset:
 - problems were encountered in setting up initial team states correctly
 - a large number of reusable components and attribute-value structures were identified
- This suggested the need for:
 - an automatic team generator
 - a ‘reusable code exploiter’

What is ViSoar?

- An integrated Visual Soar development environment.
- Currently comes in two parts:
 - ★ – code generation tools (*deViSoar*)
 - ★ – offline ‘reverse engineering’ tools (*reViSoar*)
 - automated debugger (*adViSoar*)
- Compatible with automatic high level knowledge representation language to Soar code translator package (*Soarceror*)

Philosophy

- Visual environment
- Written in Tcl/Tk
- Exploit Soar architecture at command rather than code level
- Facilitate the construction of typo free Soar code

deViSoar

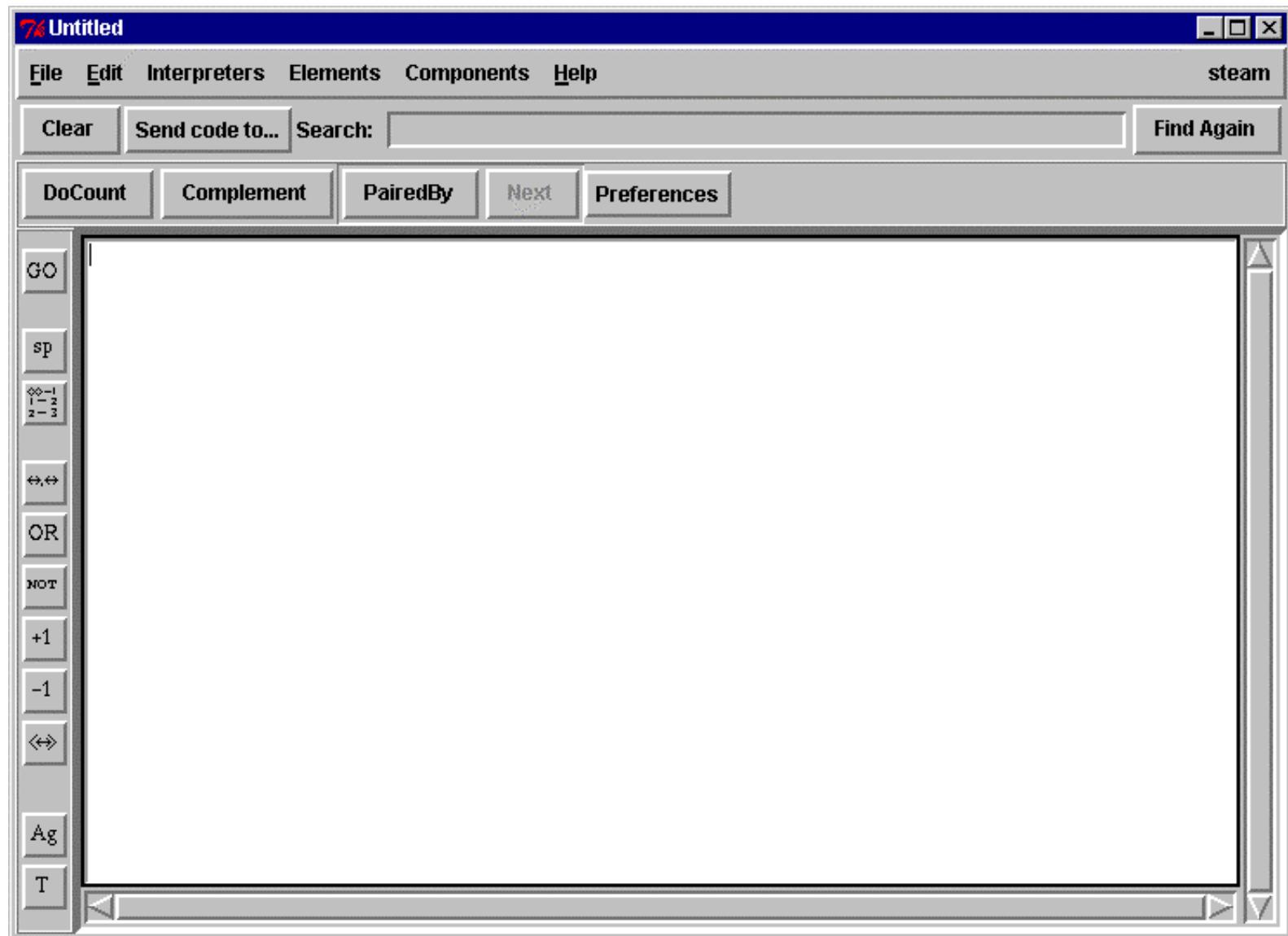
- Text editor
- ‘*avtree* ontology’ editor
- Automatically generated ‘skeleton’ productions
- Various Soar code manipulating tools
 - OR
 - NOT

reViSoar

- ‘Reverse engineering’ of legacy Soar agents
- Utilises an offline operator hierarchy analyser (*OpHelia*)
 - extracts implicit structure of rulesets
 - operator/problem space hierarchy
 - productions related to particular operators/problem spaces
- Generates *avtree* that may be passed to *deViSoar*

Additional Components

- Production viewer (*ProdView*)
 - allows straightforward inspection of (large numbers of) productions
 - available as standalone package with connector to TSI
 - *ViSoar* integrated version provides filtered searching of loaded productions



deViSoar Menubar



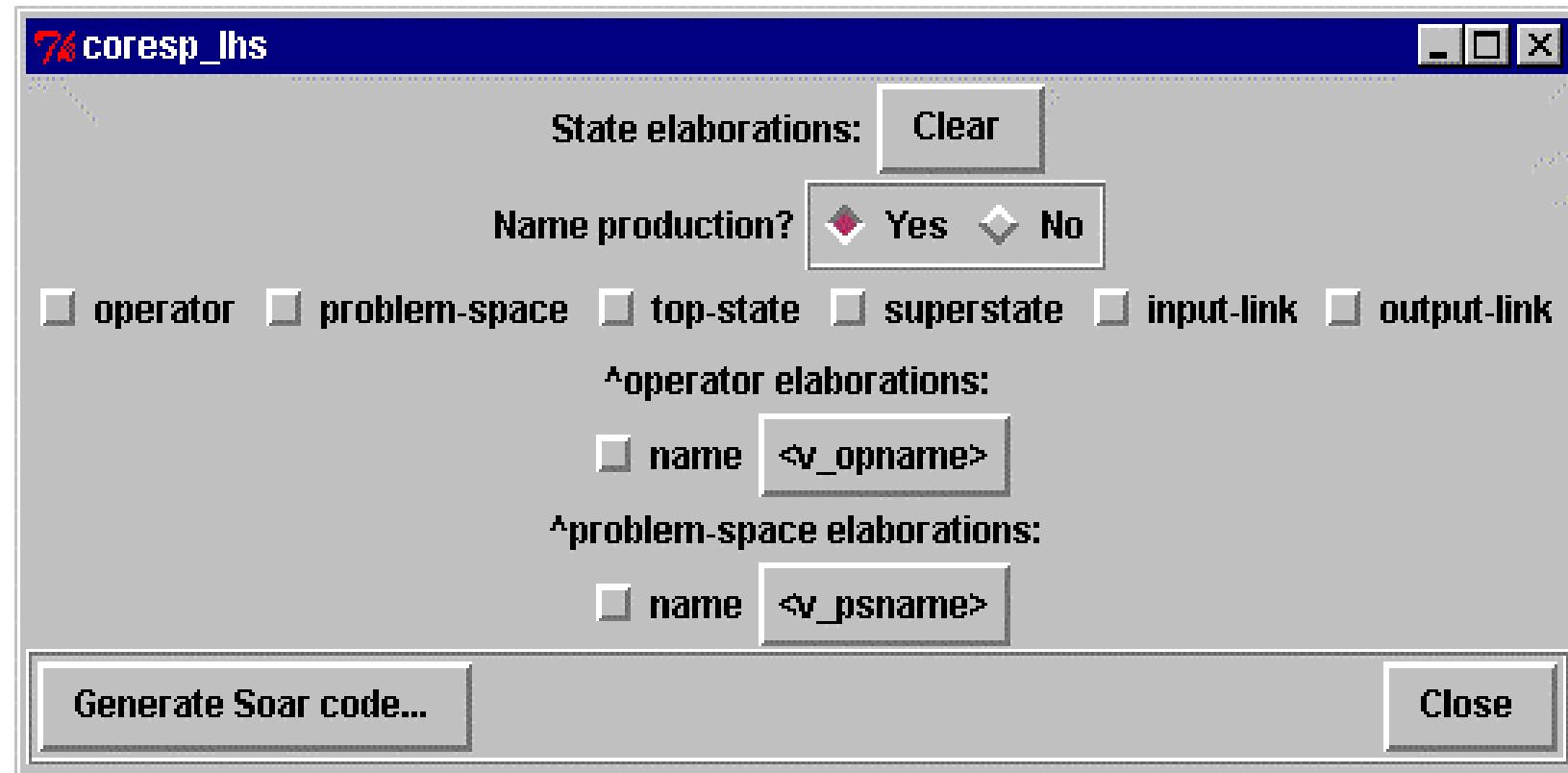
- Standard *File* options (*Load*, *Save*, etc.)
- Standard *Edit* options (*Cut*, *Copy*, etc.)
- *Interpreters* raises *reViSoar* window for selected (or newly *Created*) Soar interpreter
- *Elements* contains project dependent *avtrees* and operator hierarchies
- *Components* contains toolbar commands and raises *Skeleton* production dialogues

deViSoar Vertical Toolbar



- *GO* to relevant part of *avtree*
- Raise *core-lhs skeleton* dialogue
- Generate standard form list
- Toggle dot/expanded form
- Insert *or* construct
- Insert NEQ construct
- Increment indirector count
- Decrement indirector count
- Toggle indirector/constant

Core-lhs Skeleton (1)



Core-lhs Skeleton (2)

Automatically generated Soar code:

```
#*****  
sp {apply*wait  
  (state <s> ^operator <v_o> ^io <v_io>)  
  (<v_io> ^input-link <v_ip>)  
  (<v_o> ^name wait )  
  
-->  
}
```

The *Operator Proposal* Skeleton

```
#*****  
sp { *propose*operator*test_operator  
  (state <s> ^problem-space <v_ps> ^top-state <v_ts> ^superstate  
   <v_ss> ^io <v_io> ^io <v_io>)  
  (<v_io> ^input-link <v_ip>)  
  (<v_io> ^output-link <v_op>)  
  (<v_ps> ^name <v_psname> )  
  -->  
  (<s> ^operator <v_o> + &)  
  (<v_o> ^name test_operator + )  
 }
```

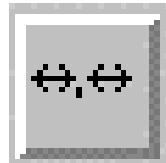
The *problem-space* Proposal

```
#*****  
sp { *create*problem-space*test_ps  
  (state <s> ^operator <v_o> ^top-state <v_ts> ^superstate <v_ss>  
   ^io <v_io> ^io <v_io>)  
  (<v_io> ^input-link <v_ip>)  
  (<v_io> ^output-link <v_op>)  
  (<v_o> ^name <v_opname> )  
  
-->  
  (<s> ^problem-space <v_ps> + & )  
  (<v_ps> ^name test_ps + )  
}
```

Exploiting dot notation

Expand

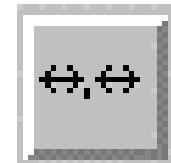
(<s> ^grandparent.parent.child
grandchild)



(<s> ^grandparent <vs6>)
(<vs6> ^parent.child grandchild)

Collapse

...^parent <ind>)
(<x> ^however many)
(<y> ^infill lines)
(<ind> ^child val...)



...^parent.child val...)
(<x> ^however many)
(<y> ^infill lines)

The *OR* Construct

(<s> ^choices <v_ch>)



either:

(<s> ^choices { << multiple none >> <v_ch> })

or:

(<s> ^choices { << >> <v_ch> })

depending on user-preference.

Inequalities

($<\!\!v_o\!\!> \wedge \text{name } \mathbf{wait}$)



($<\!\!v_o\!\!> \wedge \text{name } \{ \triangleleft \text{ wait } \})$

Alternatively:

($<\!\!v_{io}\!\!> \wedge \text{input-link } <\!\!v_{ip}\!\!>$)



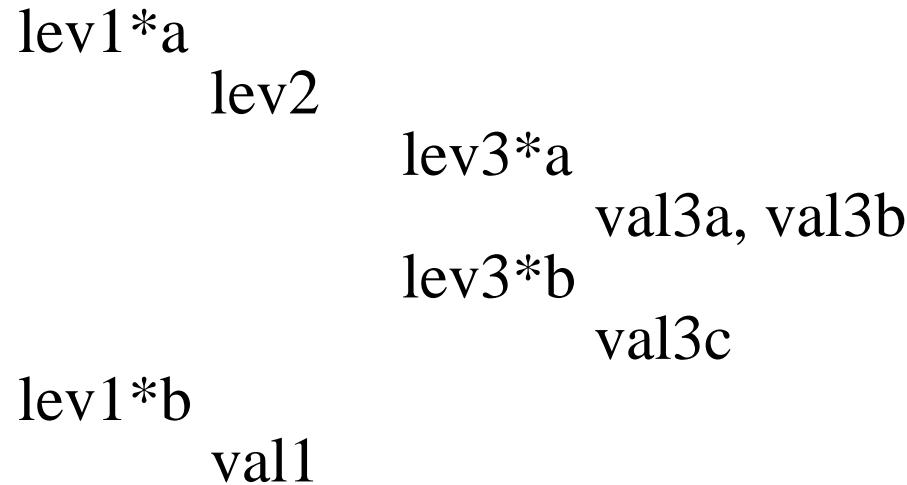
($<\!\!v_{io}\!\!> \wedge \text{input-link } \{ \triangleleft <\!\!v_{ip}\!\!> <\!\!v_{ip}^*\!\!> \})$

The *avtree* I - Implicit vs. Explicit Problem Spaces

- Explicit problem-spaces are identified with the \wedge *problem-space.name* attribute
- Implicitly defined problem-spaces reflect the state elements manipulated by productions acting within the ‘problem-space’
- The *avtree* for productions whose behaviour we associate with activity in a given problem-space defines the problem-space

The *avtree* II - Example

(state <s> ^lev1*a (<lev1*a> ^lev2 <lev2>) ^lev1*b val1)
(<lev2> ^lev3*a << val3a val3b >> -^lev3*b <x>)
-->
(<lev2> ^lev3*b val3c + &)



The *avtree* III - Element Types

- The *avtree* for a ruleset essentially provides a hierarchically structured ontology:
 - major attributes (have attributes as values)
 - minor attributes (have constant values)
 - values
 - single attributes
 - multi-attributes

Growing the *avtree*

- Attributes and values may be added to any *avtree* at any time from the *Elements* menu.
- *Add ^attr <ind>...* allows you to add a *major attribute* (an attribute that will have another attribute as its child)
- *Add ^attr const...* allows you to add a *minor attribute* (an attribute that takes a constant value), and will then prompt for its values
- *Add value...* allows you to a constant value
- Deleting *avtree* elements is currently unsupported.

avtree Summary

The *avtree*:

- represents an ontology for a given Soar agent
- may be used as an implicit problem space definition
- may be created/added to, saved and loaded within *deViSoar*
- may be extracted from a legacy ruleset within *reViSoar*, and saved for use in *deViSoar*
- may be used for sophisticated search routines

Add ^attr const...

Prompts for attributes:



followed by appropriate prompts for values:

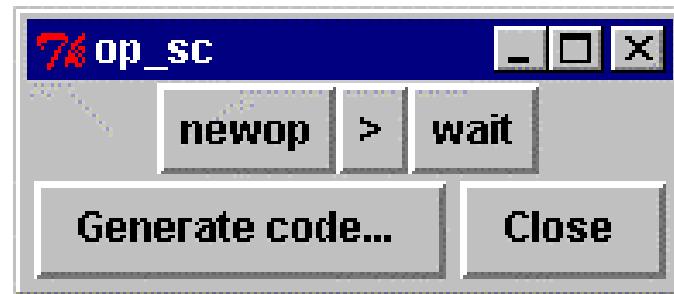


Value Adding Shortcuts

- HML provides: *high* *medium* *low*
- YN provides: *yes* *no*
- NEWS provides: *north* *south* *east* *west*
- UD provides: *up* *down*
- RL provides: *right* *left*

Adding new shortcuts is straightforward.

Operator Search Control



```
#*****  
sp { *search-control  
  (state <s> )  
    (<s> ^operator <op1> + <op2> + )  
    (<op1> ^name newop )  
    (<op2> ^name wait )  
  
    -->  
    (<s> ^operator <op1> > <op2> )  
}
```

Generating lists



will generate the list:

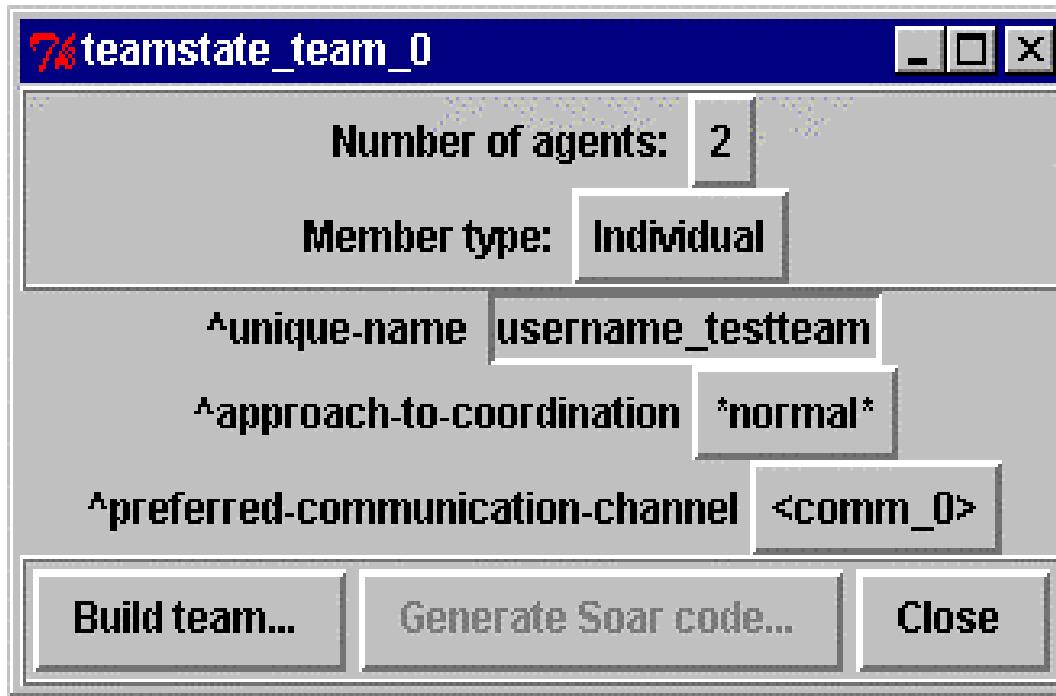
```
(<list*0> ^item one ^next <list*1> )
(<list*1> ^item two ^next <list*2> )
(<list*2> ^item three )
```

Add Ons for *deViSoar*

- deViSoar is intended to support the use of task specific skeletons
- Currently, several skeletons for use with Tambe's STEAM ruleset are provided
- Ideally, a user should be able to quickly and easily create new skeletons relevant to a given project

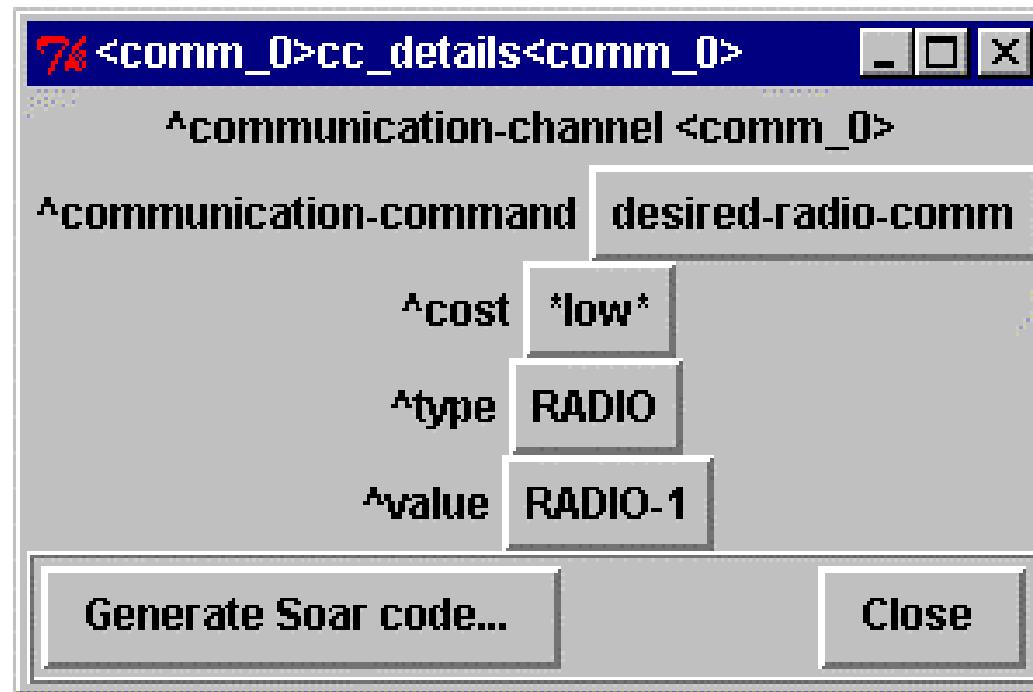
STEAM Add-Ons: Team Creation 1

- Using the  button raises:



STEAM Add-Ons: Team Creation 2

- Raising the ‘communication channel’ menu provides an option to change channel properties:



STEAM Add-Ons: Team Creation 3

- After ‘building’ the team, team definition code may be automatically generated (formatting sacrificed for clarity(!)):

```
sp {elaborate*teamstate*username_testteam
(state <s> ^name top-ps ^superstate nil )-->
(<s> ^command <c>) (<c> ^group <team_0> )
(<team_0> ^unique-name username_testteam ^communicated <comm> ^colocated *no* )
(<team_0> ^teamtype *yes* ^team-plan <tp> ^approach-to-coordination *normal*)
(<team_0> ^member-list <m> ^team-leader username_testteam_agent_1 )
(<m> ^leader <agent_1> ^member <agent_1> + & ^member <agent_2> + &)
(<agent_1> ^unique-name username_testteam_agent_1)
(<agent_2> ^unique-name username_testteam_agent_2)
(<team_0> ^speaking-order <so> )
(<so> ^username_testteam_agent_1 <so0> ^username_testteam_agent_2 <so1> )
(<so> ^member username_testteam_agent_1 ^next <so0> )
(<so0> ^member username_testteam_agent_1 ^next <so1> )
(<so1> ^member username_testteam_agent_2 ^next nil )
(<team_0> ^preferred-communication-channel <comm_0> ^communication-channel <comm_0> )
(<comm_0> ^communication-command desired-radio-comm ^cost *low* ^type RADIO ^value
RADIO-1)}
```

STEAM Add-Ons: Team Creation 4

- when team definition code is generated, an option is raised automatically that will generate and save code for each agent, if required, along the lines of:

```
sp {elaborate*teamstate*username_testteam_agent_1  
  (state <s> ^name top-ps ^superstate nil ^command <c> )  
  -->  
  (<s> ^self <agent_1> )  
  (<c> ^group <agent_1> )  
  (<agent_1> ^unique-name username_testteam_agent_1)  
  (<agent_1> ^approach-to-coordination *normal*)  
  (<agent_1> ^type individual)  
  (<s> ^trust username_testteam_agent_1 + &  
   ^trust username_testteam_agent_2 + &)}
```

STEAM Add-Ons: Agent Creation 1

- The  button raises the dialogue:



STEAM Add-Ons: Agent Creation 2

- If the agent type is ‘individual’, code will be generated of the form:

```
sp {elaborate*teamstate*username_agent_3
  (state <s> )
  (<s> ^name top-ps ^superstate nil )
  (<s> ^command <c> )
-->
  (<s> ^self <agent_3> )
  (<c> ^group <agent_3> )
  (<agent_3> ^unique-name username_agent_3)
  (<agent_3> ^approach-to-coordination *normal*)
  (<agent_3> ^type individual)
}
```

STEAM Add-Ons: Agent Creation 3

- If the agent is of type ‘team’:

```
sp {elaborate*teamstate*username_agent_3
  (state <s> ^name top-ps ^superstate nil ^command <c> )
  -->
  (<s> ^self <agent_3> )
  (<c> ^group <agent_3> )
  (<agent_3> ^unique-name username_agent_3 ^type team )
  (<agent_3> ^approach-to-coordination *normal*
    ^preferred-communication-channel <comm_0>)
  (<agent_3> ^member-list <agent_3_member>)
  (<agent_3_member> ^member <none> + &)
  (<agent_3_member> ^leader <none> ^speaking-order <so> )
  (<agent_3> ^communication-channel <comm_0> )
  (<comm_0> ^communication-command desired-radio-comm ^cost *low*)
  (<comm_0> ^type RADIO ^value RADIO-1)}
```

- Members may be added within the dialogue from a list of current agents (indls or teams) and suitable code will be generated

ViSoar availability

ViSoar is available on an AS IS basis from:
<http://www.dcs.port.ac.uk/~hirsta/tcltools.htm>

Also, e-mail for details of the latest version of the manual

Please register...