Collaborative multi-agent IVUS image segmentation



Ernst Bovenkamp

Division of Image Processing, Department of Radiology Leiden University Medical Center, The Netherlands

E.G.P.Bovenkamp@lumc.nl

Outline



- System design
- Agent design
- Conflict resolution
- Examples and Results
- Future work.

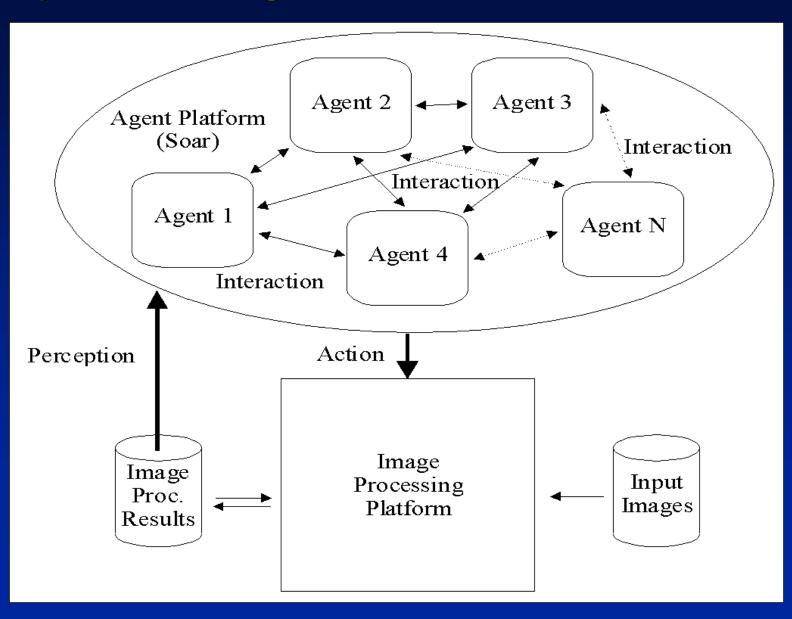


Multi-agent IVUS image interpretation

- Modular approach:
 One or more agents for each possible image object.
- Currently: lumen, vessel, shadow, calcified plaque, side-branch, and status agent.
- Agents establish interrelations through communication and exchange interests and capabilities.

System design





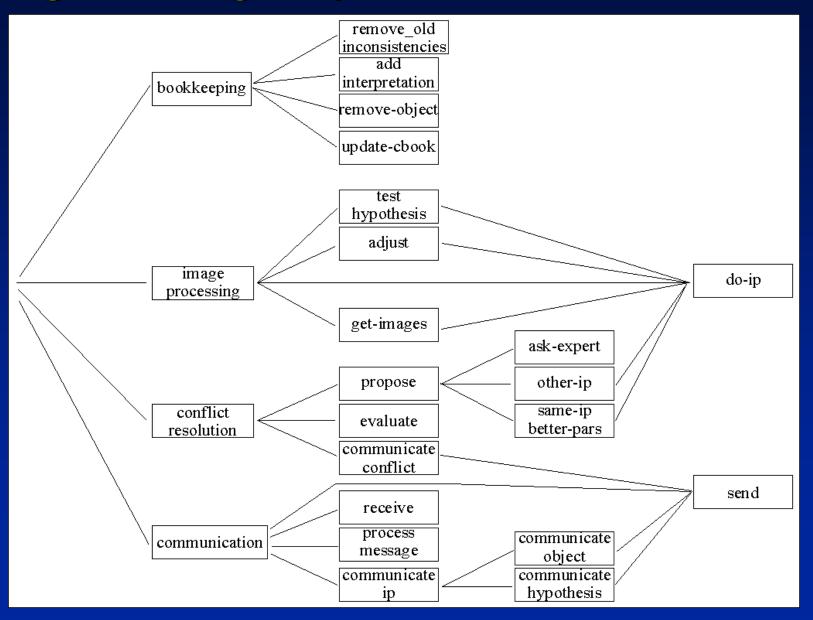
Agent design: productions

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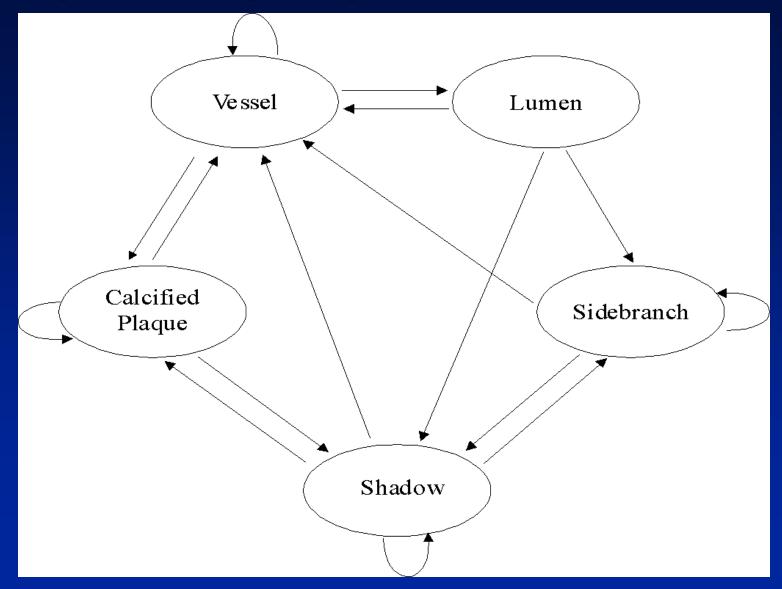
Typical agent model:
37 communication rules
189 image processing rules
112 conflict resolution rules
26 utilities and default rules
9 agent specific rules
373 productions

Agent design: operator relations





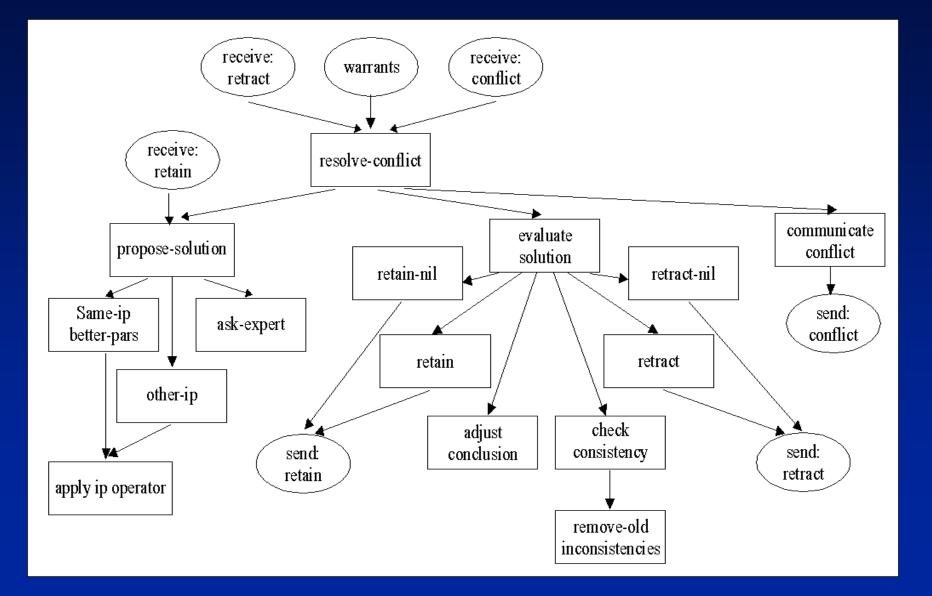
Agent design: agent relations





Conflict resolution: design



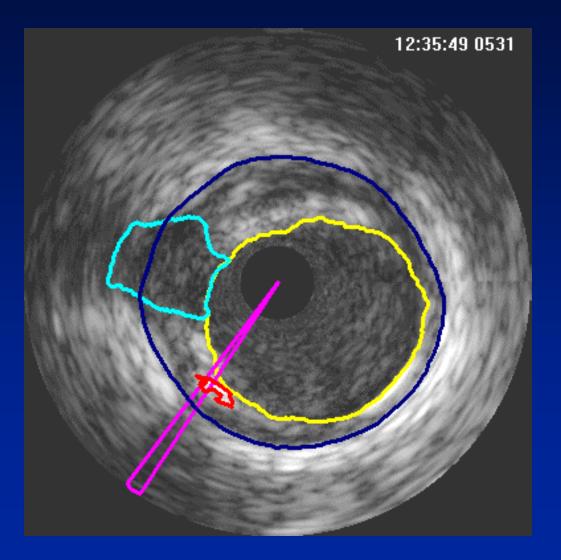


Conflict resolution: snapshot



| 💐 ivus-shadow-old 📃 🔲 🗵 | | | | | | |
|-------------------------|---|----------------|--|--|--|--|
| 100: | 0: 0135 (propose-solution) 101: ==>S: S27 (operator no-change) | Step | | | | |
| 102: | 0: 0138 (same-ip-better-pars) Improving selectivity. Adjusting mindist: 30> 31 | Stop | | | | |
| 103: | ==>S: S28 (operator no-change) | Run | | | | |
| 104: | 0: 0143 (send) 2875115: Sending message to <agent-status></agent-status> | Init | | | | |
| 105: | 0: 0141 (detect-shadow-old) Detecting shadow contours Sensitivity (mindist = 31, mu = 0.66, fuzzy-set = [20 25 29 35]) | Learn Watch | | | | |
| | Selectivity (mindist = 31, mu = 0.33, fuzzy-set = [29 35 99 100]) | Excise | | | | |
| 106: | 0: 0145 (evaluate-solution) 107: ==>S: S31 (operator no-change) | Productions | | | | |
| 108: | 0: 0148 (retain-object) 109: ==>S: S32 (operator no-change) | Save | | | | |
| | | | | | | |
| Comman | Print | | | | | |

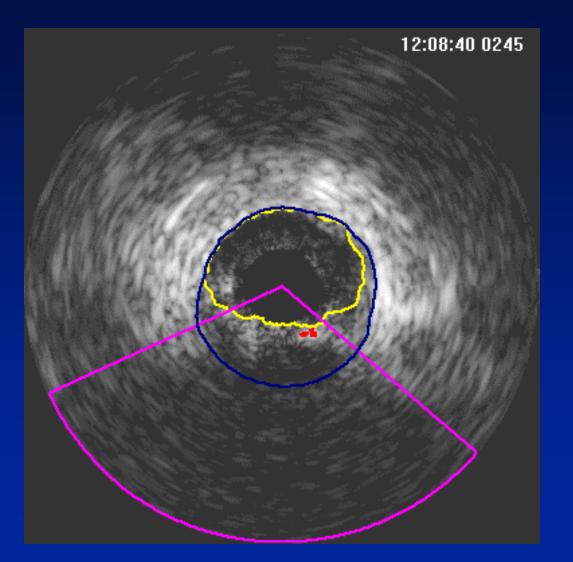
Conflict resolution: example





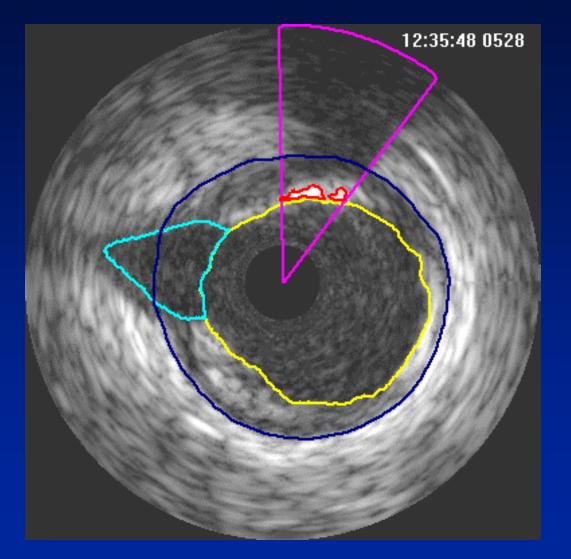
Test-hypothesis: example





Results: patient1





Standalone (sa) vs multi-agent (ma)

- All conflicts resolved.
- Considerable improvement of detectors.
- Still some room for improvement.

| Result | lumen | | vessel | | sidebranch | | shadow | |
|------------|-------|----|--------|----|------------|----|--------|----|
| | sa | ma | sa | ma | sa | ma | sa | ma |
| optimal | 30 | 30 | 18 | 27 | 26 | 32 | 12 | 12 |
| suboptimal | 2 | 2 | 2 | 5 | 0 | 0 | 1 | 1 |
| false | 0 | 0 | 12 | 0 | 6 | 0 | 10 | 0 |

Future work



- Validation of complete imageruns.
- Publication of results.
- Inclusion of new agents (CSG, stent).
- Learning image processing from the user.

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