Quantitative Category Learning in Soar: Progress and Roadblocks

Robert Wray wray@soartech.com

Ron Chong rchong@gmu.edu

> Soar 22 June 2002



Agent-based Modeling & Behavioral Representation Program: Phase III

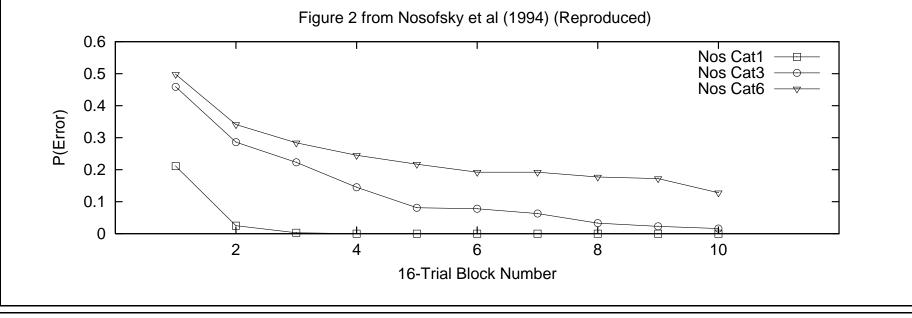
- Phase I/II: Enroute air-traffic control task (R. Chong) Interaction with real-time display (eye, text, mousing, etc.) Vary workload and compare to human data Integrated in DoD's "High Level Architecture" (HLA)
- Phase III: Air-traffic control task + Category Learning Interaction with real-time display (eye, text, mousing, etc.) +

Additional task: Learn when to allow/disallow "altitude change requests" (synthetic task, other activities pause) Maps to classic category learning results (3 attr, 2 values ea) altitude=20,000; size=L; turbulence=1 \rightarrow accept altitude=40,000; size=S; turbulence=3 \rightarrow reject

Rule-based Categorization

Given identical instances and identical probability distribution of categories, some category definitions are easier to learn than others (Shepard et al., 1961). Shepard et al results were duplicated with statistical confidences by (Nosofsky et al., 1994).

Category 1: One attribute determines classification (alt= $20 \rightarrow \text{accept}$) Category 3: Like Category 1 but some exceptions (alt= $20 \rightarrow \text{accept}$ except ...) Category 6: No pattern; must memorize instances



Quantitative Category Learning in Soar:Progress and Roadblocks

Symbolic Concept Acquisition

Soar model of concept acquisition developed by Craig Miller (Miller, 1993)

General-to-specific search over concept space

Backtracks, noise-tolerant

Qualitative fit to Nosofsky data

```
SCA Algorithm:

instance = input attributes and values

while (no matching prediction rule for instance)

abstract feature from instance

store most recently abstracted feature

restore most recently abstracted feature to instance

store new prediction rule for instance

Example:

Prediction rules:

alt=20 \rightarrow accept, (null) \rightarrow accept, (null) \rightarrow reject

New instance: size=S,turbulence=3,altitude=20

New Prediction Rule: alt=20, turb=3 \rightarrow accept
```

Current Effort: Quantitative Match to Nosofsky

Assumption: Learning curves for AMBR task should match Nosofsky results (preliminary data from BBN suggests this assumption holds)

Current Goal: Use SCA + knowledge to achieve reasonable qualitative fits to Nosofsky data

How close can we get without additional mechanisms? (avoid simulating subsymbolic mechanisms; eg, frequency effects)

What knowledge is necessary?

SCA: modify abstraction order

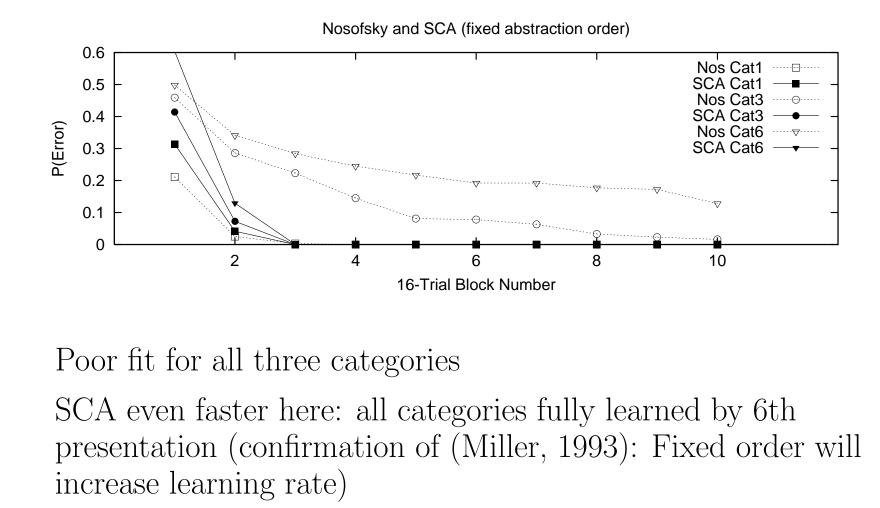
Process models of category learning

Future Work: Look at impact of subsymbolic mechanisms (EPIC-Soar)

Preliminary Results: SCA "out of the box" SCA with random feature abstraction order (slowest learning) Nosofsky and SCA (random order of feature abstraction) 0.6 Nos Cat1 0.5 SCA Cat1 Nos Cat3 0.4 SCA Cat3 P(Error) Nos Cat6 0.3 SCA Cat6 0.2 0.1 0 2 10 8 16-Trial Block Number Poor fit for all three categories SCA in worst case is too powerful: all categories fully learned by 8th presentation of each instance

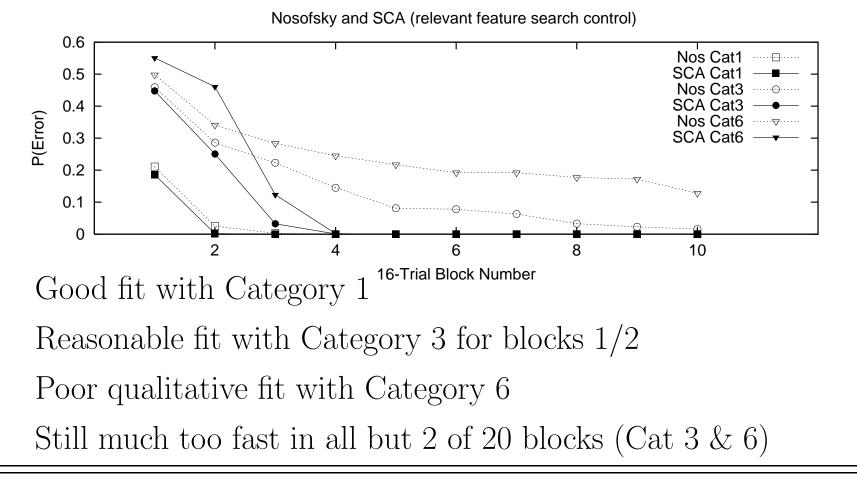
Preliminary Results: SCA + fixed abstraction order

Idea: These attributes have meaning (esp. altitude for an altitude change request)



Preliminary Results: SCA with simple search control

Simple, common sense knowledge: If an attribute made a difference in a previous prediction, then abstract it last (consider it the most relevant feature)



Quantitative Category Learning in Soar:Progress and Roadblocks

Improving the Fits

Soar

- ≻ Consider additional attributes Some subjects reported that they thought other issues could impact category
- \succ Consider other category learning models (existing process models?)
- ≻ Is it realistic to learn a new refinement every trial? Recall of prior instances is too powerful; perhaps use episodic memory to recall prior instances as in (Altmann and John, 1999)

EPIC-Soar

- \succ Impact of activation/decay memory model
- \succ Impact of chunk forgetting (possibly similar to episodic effects?)

Summary

Soar + SCA + simple knowledge seem unlikely to be able to account for much of the variance in the Nosofsky data

TBD

- Process model of concept learning?
- Impact of episodic memory?
- Explanatory power of subsymbolic mechanisms?
- Generalization of SCA concept (transfer task)?

Soar8 SCA code up on a webpage soon

References

Altmann, E. M. and John, B. E. (1999). Episodic indexing: A model of memory for attention events. Cognitive Science, 23(2):117–156.

Miller, C. S. (1993). Modeling Concept Acquisition in the Context of a Unified Theory of Cognition. PhD thesis, University of Michigan.

- Nosofsky, R. M., Gluck, M. A., Palmeri, T. J., McKinley, S., and Glauthuier, P. (1994). Comparing models of rule-based classification learning: A replication and extention of Shepard, Hovland, and Jenkins (1961). *Memory & Cognition*, 22(3):352–369.
- Shepard, R. N., Hovland, C. I., and Jenkins, H. M. (1961). Learning and memorization of classifications. *Psychological Monographs*, 75(13).