

Efficient Rule Testing in Learning By Observation

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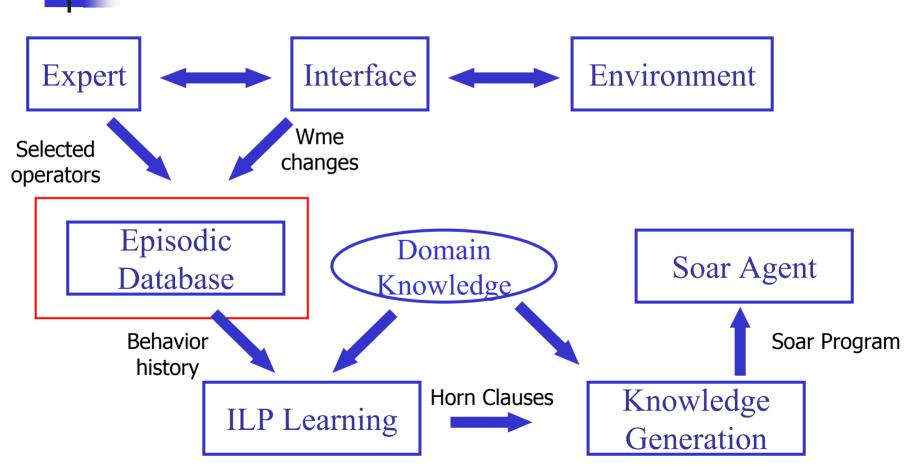


GOAL

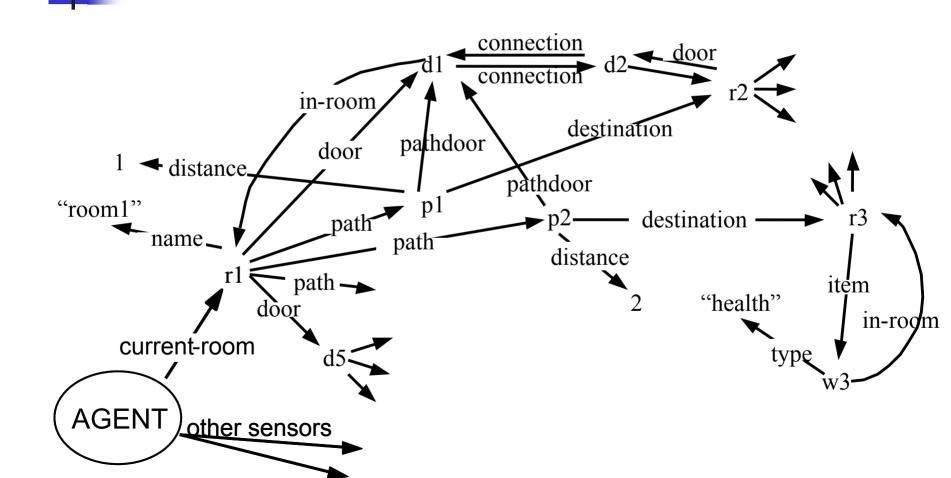
- Storing and accessing an agent's past experience efficiently
- Key component of our learning by observation system
- Examining the behavior history of a Soar agent (i.e. for debugging)



Learning By Observation







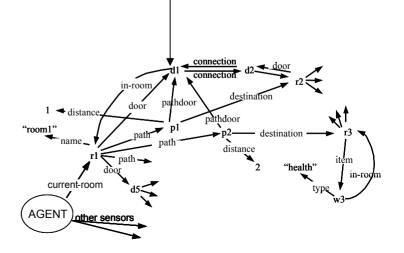


Snapshop of Working Memory

AGENT BEHAVIOR HISTORY: The Set of Situations

Situation:

a snapshot of the working memory at a time

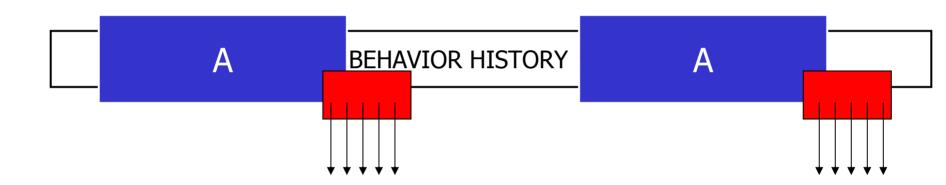






- Regions operator A is selected
- Positive examples of Termination Condition of A

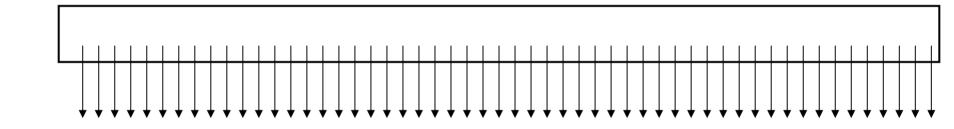




hypotheses are tested over each "positive situation"



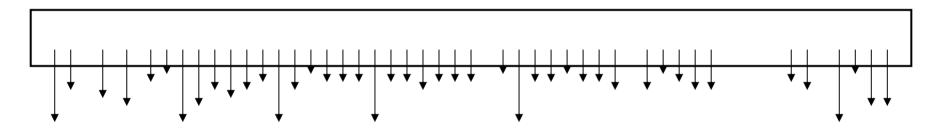
Storing Explicit Situations



- For each situation, store all WMEs
- Space inefficient



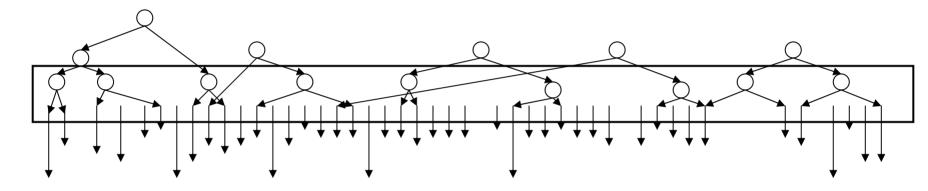
Storing Changes in Situations



- Store only the changes of WMEs
 - i.e. KnoMic (van Lent 2000)
- the database has to be traced forward starting from the initial situation.
 - Difficult to use with learning algorithms that deal with noise



Storing Indexed Changes



 Store the changes to WMEs and use index mechanism to efficiently access situations

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Rule Testing at a Situation

Given:

- R1 is a WME id representing a room
- S30 is a situation

Example Query:

(R1, ^contains-item, ?VALUE) at S30.

Output:

• Return all VALUE such that (R1 ^contains-item, VALUE) holds at S30.

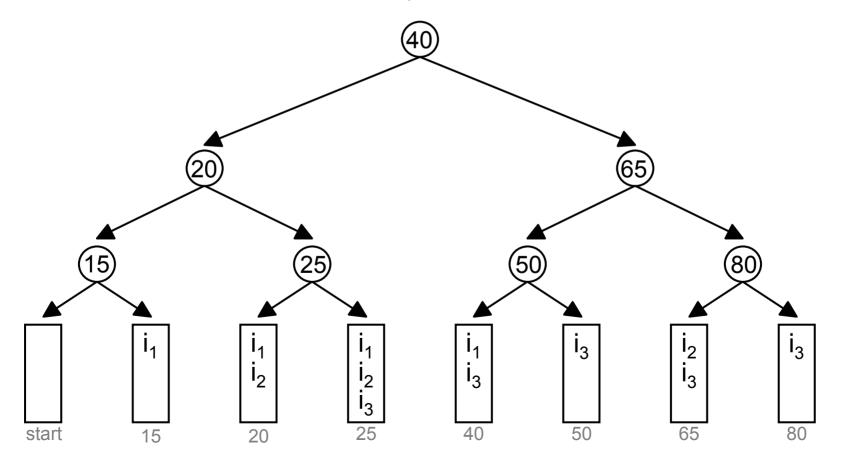


Storing Indexed Changes

- A binary search tree, for each (WME Id, Attribute)
- For each query:
 - Locate the corresponding search tree
 - Find values traversing the tree

Binary Search Tree Example

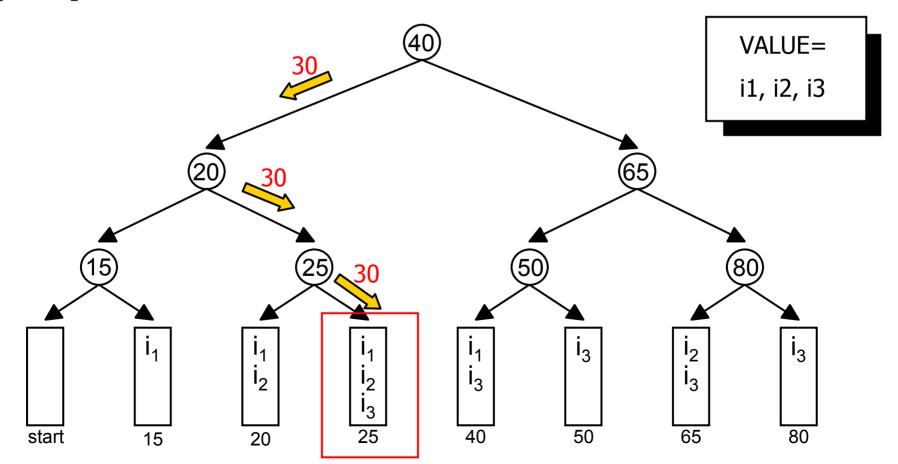
Search tree of (R1, contains-item)





Binary Search Tree Example

Query: (R1, ^contains-item, ?VALUE) at S30





Rule Testing at a Situation

- Using this scheme, a rule can be tested at any situation in the history of an agent.
- This provides space efficiency, while keeping the access times reasonable.

We want more than that !



Rule Testing over a Range of Situations

GOAL

test a rule over a range of situations at once.

MOTIVATION

In consecutive situations, similar conditions hold

RESULT

More efficient than testing a rule at each situation individually



Testing a Condition on Multiple States

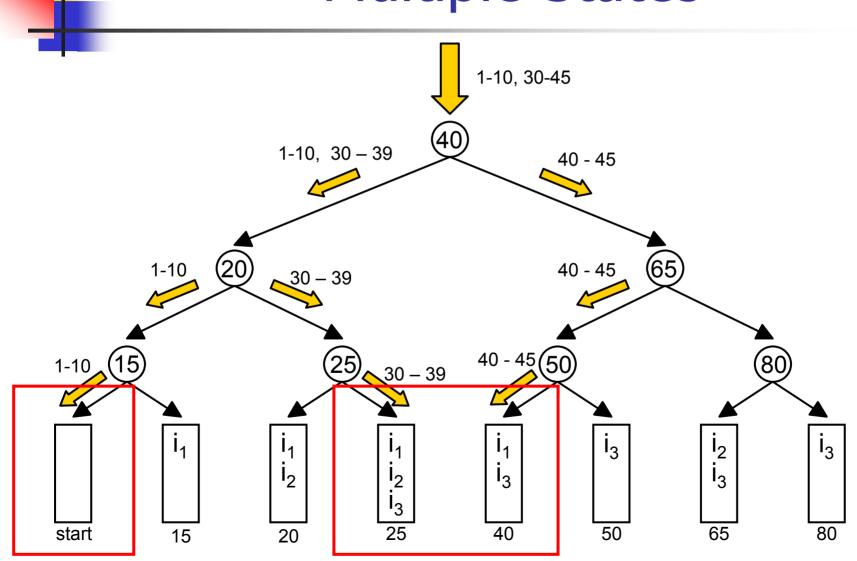
• Query:

(R1, contains-item, ?VALUE) at S1-S10, S30-S45

Output:

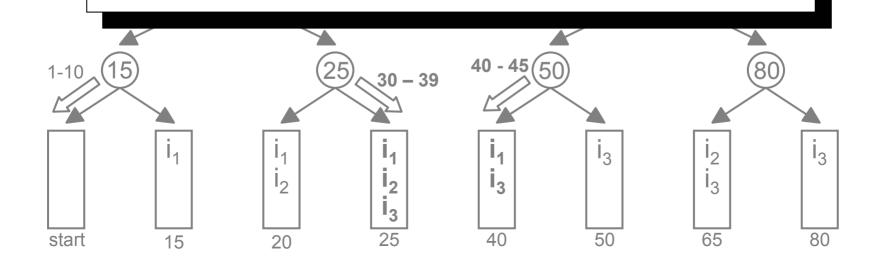
A Set of (VALUE, Situation-Range) pairs

Testing a Condition on Multiple States



Testing a Condition on Multiple States

- (R1 ^contains-item i₁) at 30-39, 40-45
- (R1 ^contains-item i₂) at 30-39
- (R1 ^contains-item i₃) at 30-39, 40-45





- A Rule contains multiple conditions
 - i.e. C1 **and** C2 ...
 - Each Condition Ci propagates:
 - the values
 - the set of situations
 - that satisfy Ci and previous conditions
- This idea can be also generalized for rules that contain "not" and "or"



Why is this useful?

- In Learning by Observation :
 - The rules are checked over continues ranges

A



Why is this useful?

- In Soar Programing:
 - It may help to understand the behavior of a Soar agent.
 - i.e. Show me all situations when a Tanksoar agent has perceived a threat but did not fire.



Nuggests

- Range Testing is efficient
 - Space complexity
 - Significantly better than explicit storage
 - Proportional to the number of changes (not situations)
 - Time Complexity:
 - Significantly better than testing at each situation using the index.
 - Can potentially perform better than storing situations explicitly



Coals

- Performance depends on the Environment Representation & Rules
 - Multivalued attributes that change value often cause space inefficiency
 - As the rules gets longer,
 the query mechanism time efficiency decrease
 - multivalued attributes and "or" connections decrease time efficiency.
- No direct connection to Soar in current implementation