

# Affective Agent Architectures

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# Overview

- ◆ What are “affective agent architectures” and why should we care about them?
- ◆ The role of affect in “complex agents”
- ◆ Challenges for “affective AI”
- ◆ Some results from experiments with simple affective agents
- ◆ Concluding thoughts
- ◆ References

# Affective Agent Architectures

- ◆ *Affective agent architecture* := a control architecture of an agent that has *components*, which in connection with other *internal* and *external* (i.e., *environmental*) *states* can instantiate *affective states*
- ◆ *Affective state* :=<sub>appr.</sub> a *positively* or *negatively valenced, teleological* state that the agent does or does not desire to a varying degree
- ◆ NOTE: most (if not all) “affect concepts” are *cluster concepts* (and may thus, as a cluster, not have any feature in common; no necessary and sufficient cond.)

# Affect-why should we care?

- ◆ Because it may not be possible to design complex agents without affect
- ◆ Because it may be beneficial to integrate affect (e.g., “computationally cheaper” for certain tasks)
- ◆ Because complex agents may not be able to interact effectively with human otherwise
- ◆ Because there are no agents without affect in nature
- ◆ Because we want to know if we can do it
- ◆ Because the game industry wants them

# The Foundational Character of Affect

- ◆ Simple organisms have no deliberative capabilities, but they are “affective” (e.g., they have simple control states that give rise to attractive-aversive behavior, “fight-or-flight” behavior)
- ◆ Complex organisms have affective states at their base and on top a complex deliberative system (which often is used to control the affective system!)
- ◆ Affect seems to be used for internal and external control!

# Different Roles of Affect I

- ◆ Control function for *immediate actions* (e.g., fear triggers a run-away or freeze behavior)
- ◆ Control function for *change in short-term and long-term behavioral disposition* (e.g., anxiety leads to increased alertness, but possibly to depression and loss of interest long-term)
- ◆ Control function for change in *problem solving* (moods or “negative affect” can change between global and local processing, e.g., top-down vs. bottom up, Bless et al. 1996, Gasper & Clore 2002)

# Different Roles of Affect II

- ◆ Control function in *decision making*:
  - ◆ use *affective memory* (i.e., past affective appraisal of an object, agent or event) instead of longer, more complex cognitive re-evaluation (e.g., Kahneman 1997)
  - ◆ use *affective evaluation* as an implicit measure of the likelihood of the occurrence of a positive or negative future event (e.g., implicit knowledge about events may be represented as such and thus not be directly accessible to cognitive processes; see also, affective disorders, Damasio 1994)

# Different Roles of Affect III

- ◆ Control function for *social behavior*:
  - ◆ signalling behavioral dispositions is a beneficial mechanism to coordinate groups as it allows for the prediction of individual behavior (e.g., by indicating “pain”, “pleasure”, “fear”, “anger”, etc.)
  - ◆ affective approval or disapproval of own or other agents' actions (relative to norms) can trigger corrective response (e.g., “shame”, “guilt”, “pride”, “awe”, “contempt”, etc.)
  - ◆ cultural changes of innately aversive stimuli (e.g., “liking the burn of red chili peppers”, Rozin 1990)



# Possible Roles of Affect in Agent Architectures

- ◆ *Action selection and behavior arbitration* (e.g., pick the “affectively preferred” behavior)
- ◆ *Decision making* (e.g., for choices under time pressure, “tie breaker”, substitute for lack of knowledge)
- ◆ *Learning* (e.g., affective evaluations as Q values)
- ◆ *Integration* (e.g., control flow, resource management)
- ◆ *Goal processing* (e.g., arrangement and prioritization)
- ◆ *Coordinated behavior* (e.g., acting efficiently in unpredictable multi-agent environments)

# Challenges for “affective AI”

- ◆ *What kinds of affective states are useful and how can they be defined? (don't wait for psychologists!)*
- ◆ *How can they be integrated into agents architectures? (e.g., what are the architectural requirements)*
- ◆ *For what kinds of tasks are they beneficial, and are there tasks for which they are necessary?*
- ◆ *Do we need “embodied agents” for affect?*
- ◆ *Do we want “affective agents”? (e.g., McCarthy 1995)*
- ◆ *How do/can we know when we have them?*

# Experiments comparing Affective and Deliberative Agents

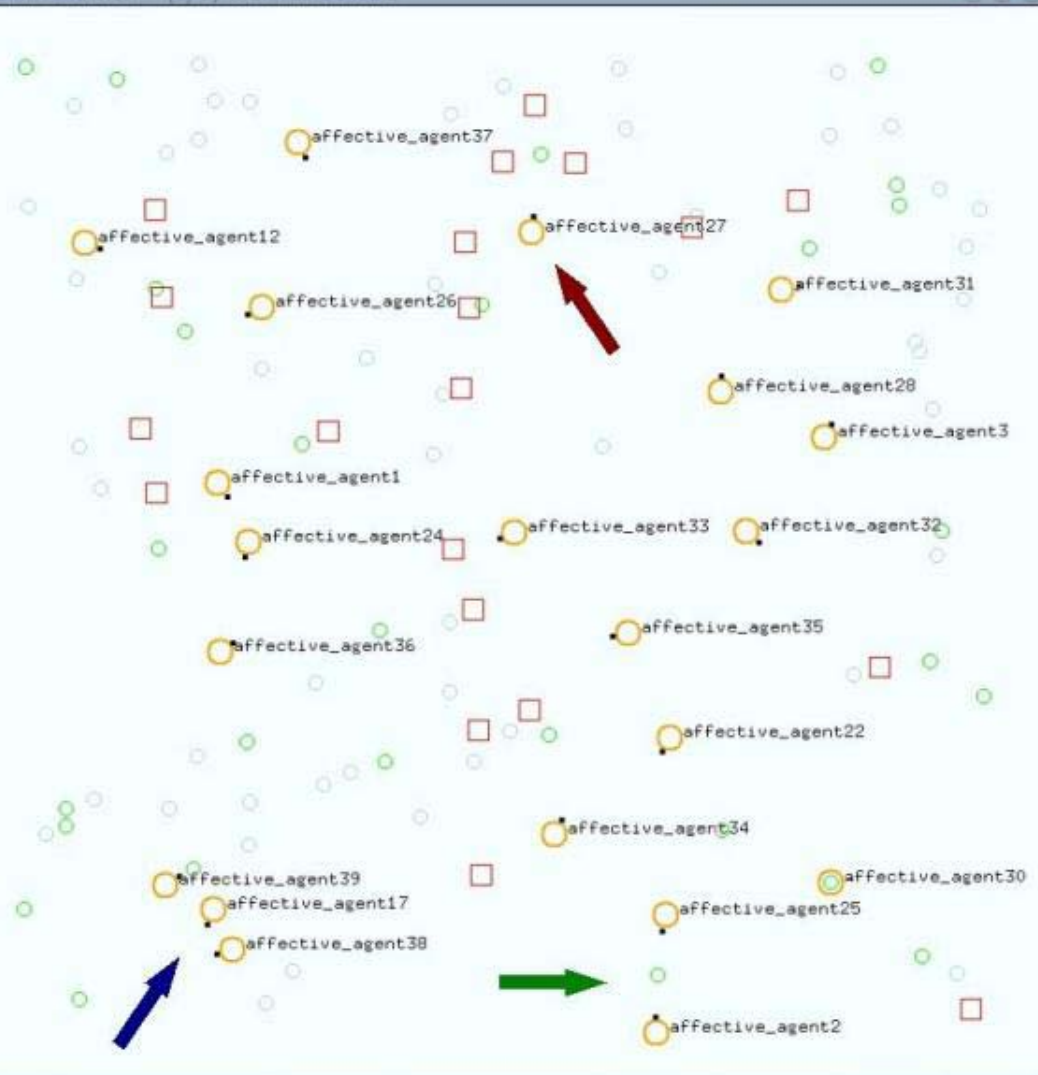
- ◆ *Idea of experimental comparison*: start simulation with different distributions of different kinds of agents in different environments
- ◆ The average number of surviving agents after a predetermined period is a *fitness measure* that can be used to assess *the relative advantage* of various architectural features of agents and their trade-offs
- ◆ *Caveat*: these kinds of experiments do not entail statements about architectural features *in general*
- ◆ (see Scheutz 2001, Scheutz and Schermerhorn 2002)

# Experimental Setup: a 2-Resource Foraging Task

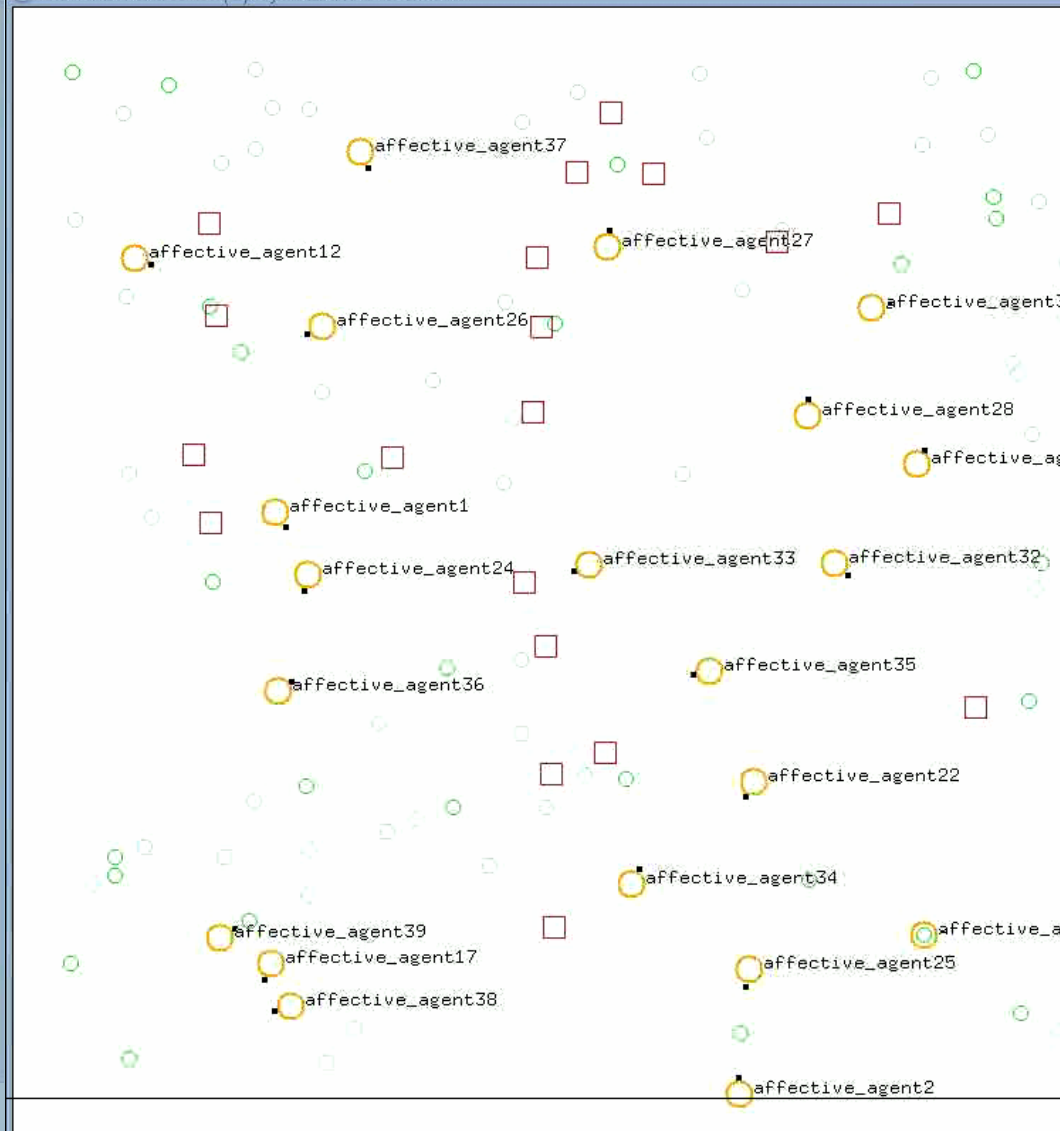
- ◆ Experiments conducted in SIMWORLD environment
- ◆ Each experiment consists of 20 runs of the simulation (for 10000 update cycles each)
- ◆ Obstacles are placed at random locations in the environment
- ◆ “Food and water rates” are fixed
- ◆ “Procreation age” is set to 250 update cycles
- ◆ Other parameters (e.g., food energy, ingestion time, movement energy, etc.) are also fixed in advance

# The SIMWOLRD Environment

SimWorld 3.3.1 -- (c) by Matthias Scheutz



SimWorld 3.3.1 -- (c) by Matthias Scheutz



# The Reactive and Affective Agents

- ◆ *Reactive* (as baseline): schema-based architecture (“greedy search”)
- ◆ *Affective*: reactive + “affective extension” (i.e., control components to implement emotional control, Scheutz 2001, Scheutz under review)
- ◆ Simple fear mechanism (“fear of obstacles” and “fear of other agents” which will temporarily change the behavioral dispositions of an affective agent)
- ◆ “Need-based” foraging (through “hunger” and “thirst” states)

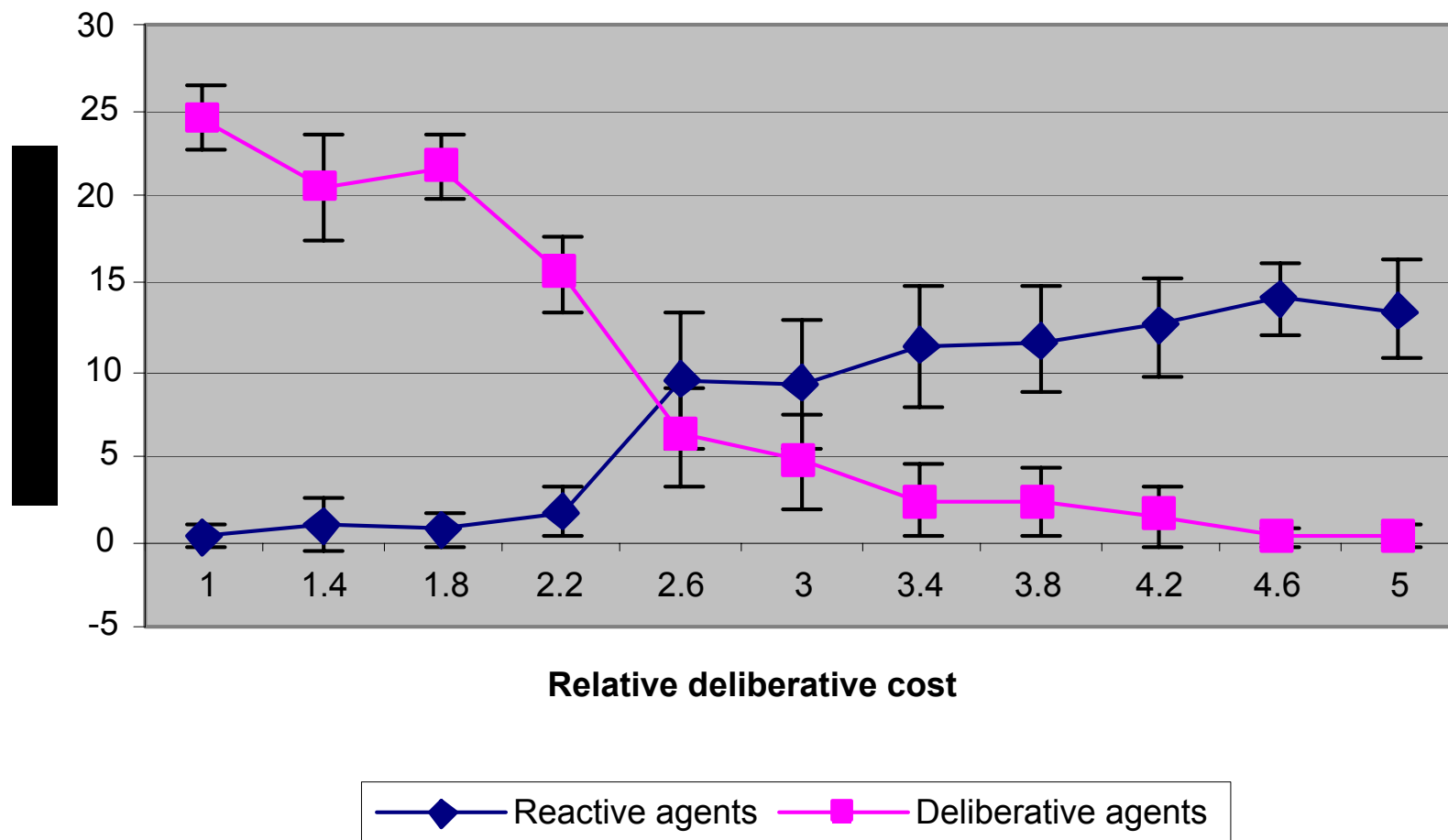
# The Deliberative Agents

- ◆ (Unlimited) memory component to store location of objects in the environment
- ◆ Update mechanism for relative positions of stored entities to adjust for movements
- ◆ A\* planner to compute optimal paths to resources
- ◆ Coherence mechanism to check whether locations of objects agree with perceived locations or whether goal item disappeared (which triggers re-planning)
- ◆ Replanning also triggered by closer goal item



# Results Experiment 1

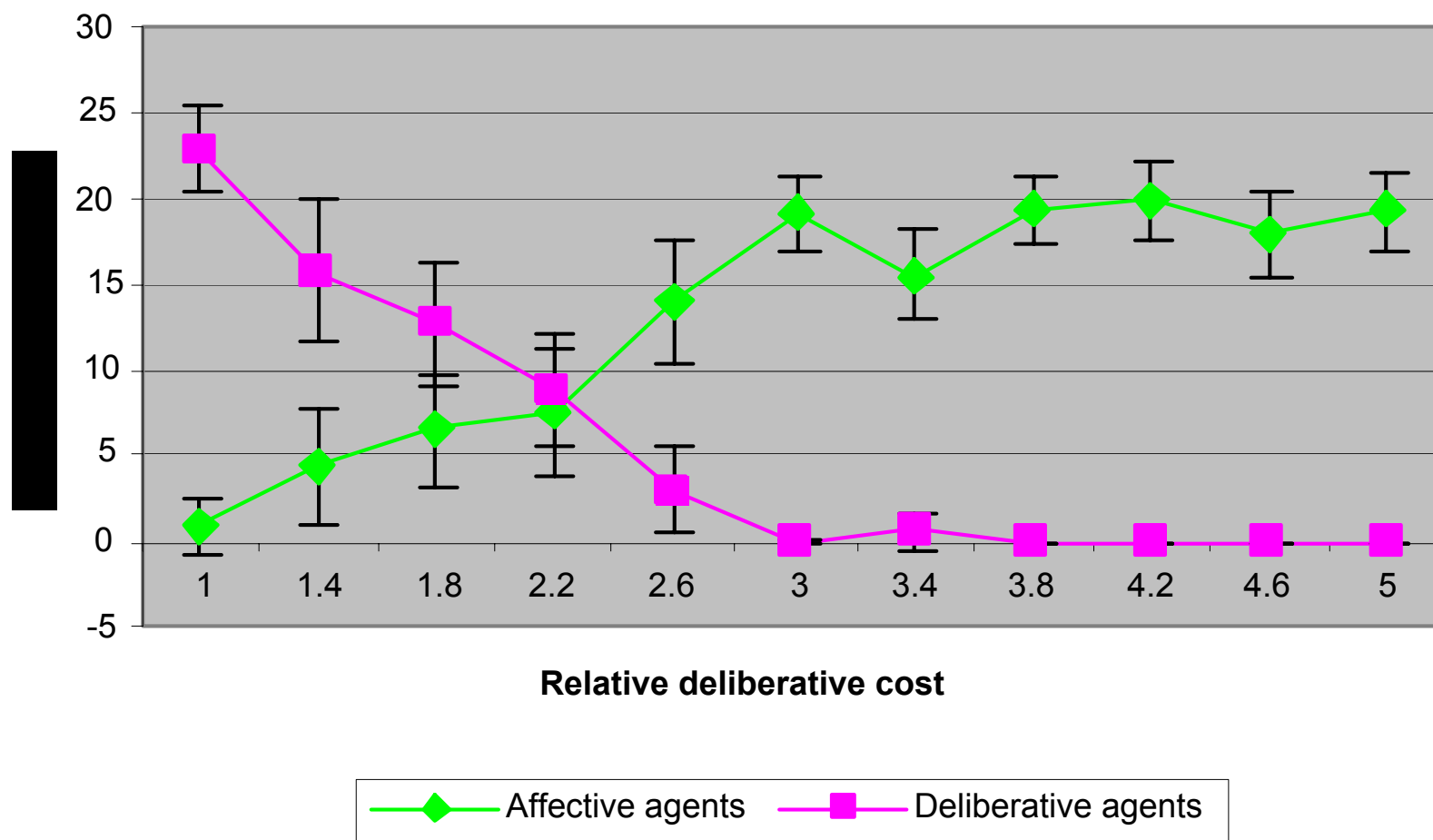
Reactive vs. Deliberative in 30 Obstacle Environments





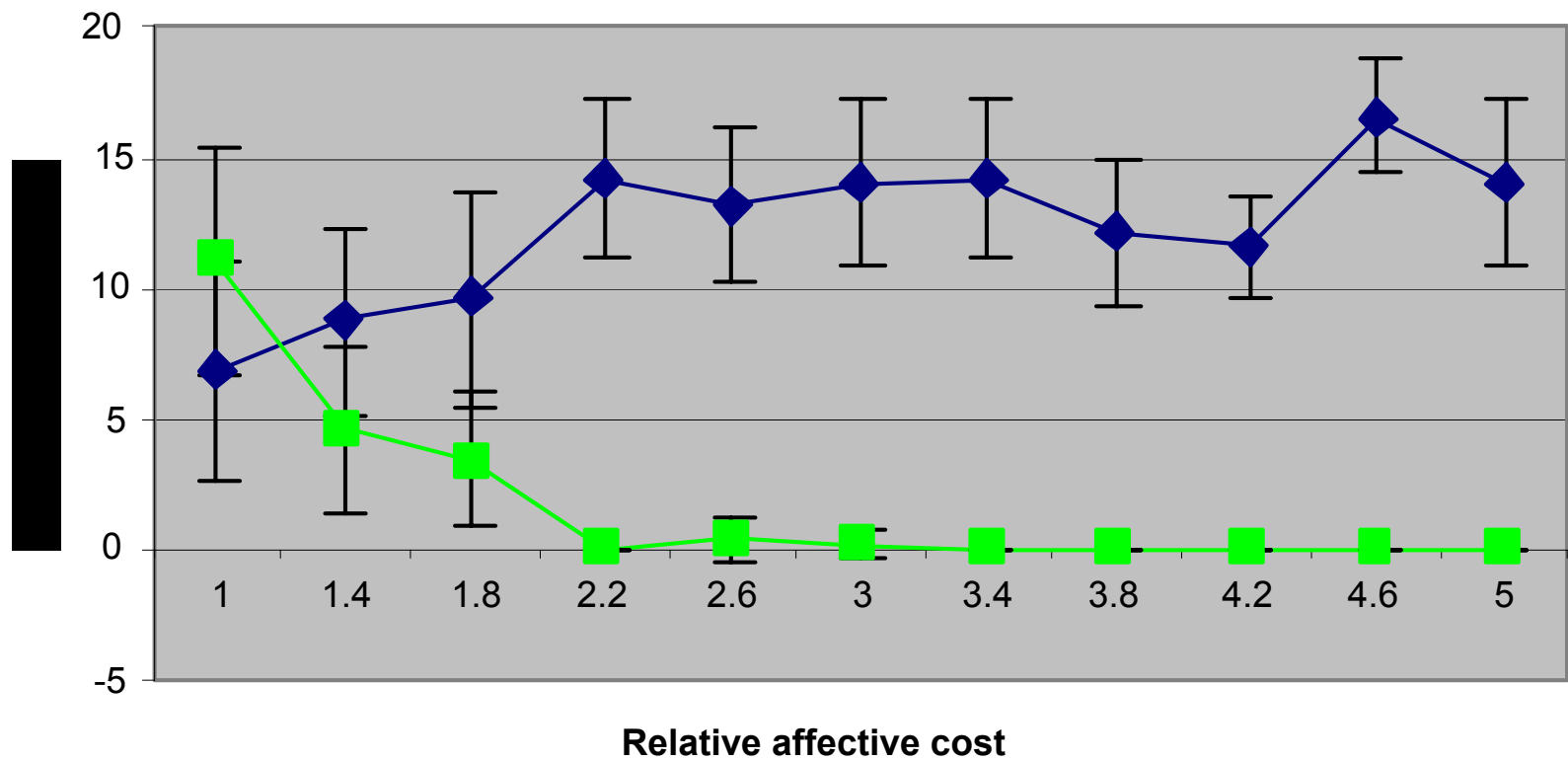
# Results Experiment 2

**Affective vs. Deliberative in 30 Obstacle Environments**



# Results Experiment 3

**Affective vs. Reactive in 30 Obstacle Environments**



◆ Reactive agents   
 ■ Affective agents

# Analysis of the Results

- ◆ Fitness ordering: deliberative  $>$  affective  $>$  reactive
- ◆ *Break-even points* in terms of relative cost:
  - ◆ deliberative = 3.4 \* reactive cost
  - ◆ deliberative = 2.5 \* affective cost
  - ◆ affective = 1.2 \* reactive cost
- ◆ *But:* reactive and affective computational cost is much lower than deliberative cost (at least by a factor of 100)
- ◆ *And:* additional affective cost  $<$ 20% of reactive

# Concluding thoughts

- ◆ Affective control seems to be efficient for simple agents-what about complex ones?
- ◆ How can affect be utilized to improve cognition?
- ◆ How can we categorize “affect” in a way that allows for integration into (existing) agent architectures (e.g., SOAR, ACT-R, and others)?
- ◆ How can we implement and test affective mechanisms in complex agents? (e.g., what sorts of tasks would be appropriate and challenging)

# Some References to our Work on Affective Agents

- ◆ Scheutz, Matthias (2002) “Agents With or Without Emotions?”. In *Proceedings of FLAIRS'02*, AAAI Press.
- ◆ Scheutz, M. and Schermerhorn, P. (2002) “Steps Towards a Systematic Investigation of Possible Evolutionary Trajectories from Reactive to Deliberative Control Systems”. In *Proceedings of Alife 8*, MIT Press.
- ◆ Scheutz, M. and Sloman, A. (2001) “Affect and Agent Control: Experiments with Simple Affective States”. In *Proceedings of IAT-01*, World Sci. Publisher.
- ◆ Scheutz, Matthias (2001) “The Evolution of Simple Affective States in Multi-Agent Environments”. In *Proceedings of AAAI Fall Symposium'01*, AAAI Press
- ◆ See also <http://www.nd.edu/~mscheutz/publications/>