

Perceptual Hierarchical Grouping in Soar Why Elaborations Rock!

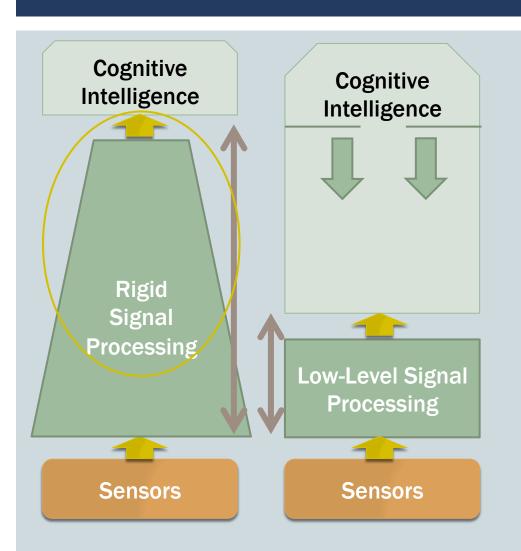
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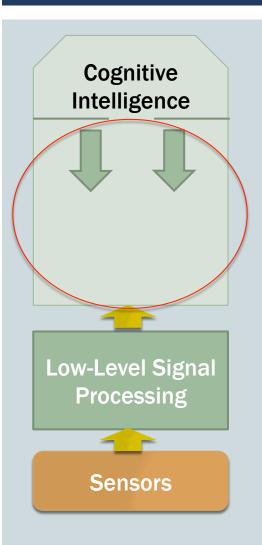


Big Picture



- Reduce gap between Cognitive Intelligence and Sensors
- Apply the concepts
 of Cognitive
 Intelligence to lower
 level perceptual
 tasks

Big Picture



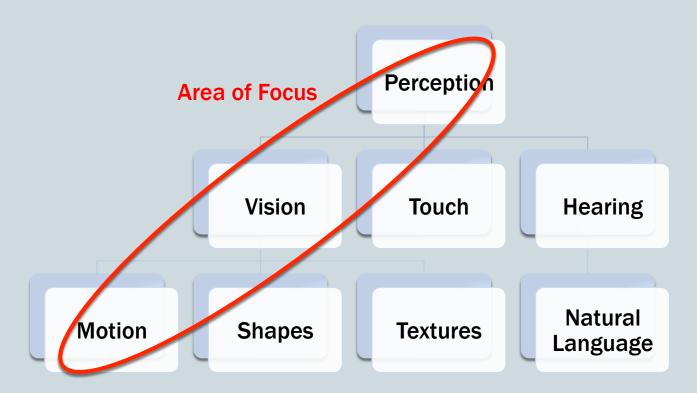
Concepts

- Reasoning what did we do last time?
- Learning What is important?
- Knowledge Representation
- Planning

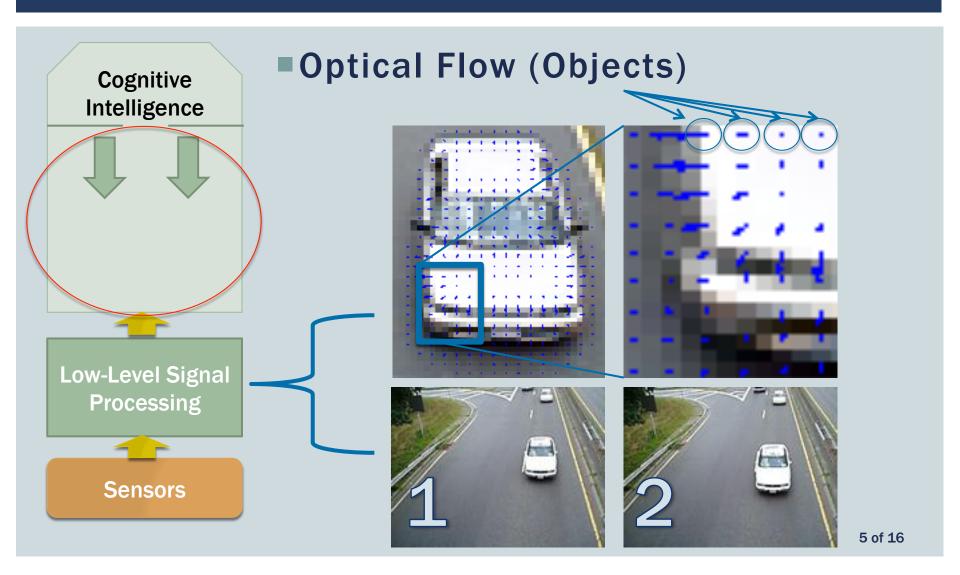
Can we avoid designing specific lower level reasoning system and learn how to perceive information?

Perception

Chosen to focus on Motion as a starting point.



Motion



Grouping

Create a Set of simple rules which can combine lower level information

Possible approaches include Gestalt Rules "perceptual organization" – sum of its parts

proximity	similarity	continuity

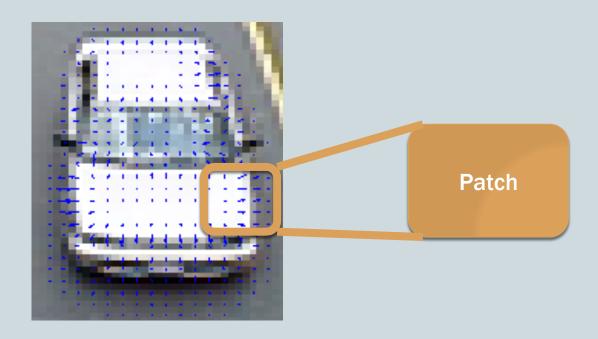
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Patch

Patch is a sub-region for which a proximity is defined



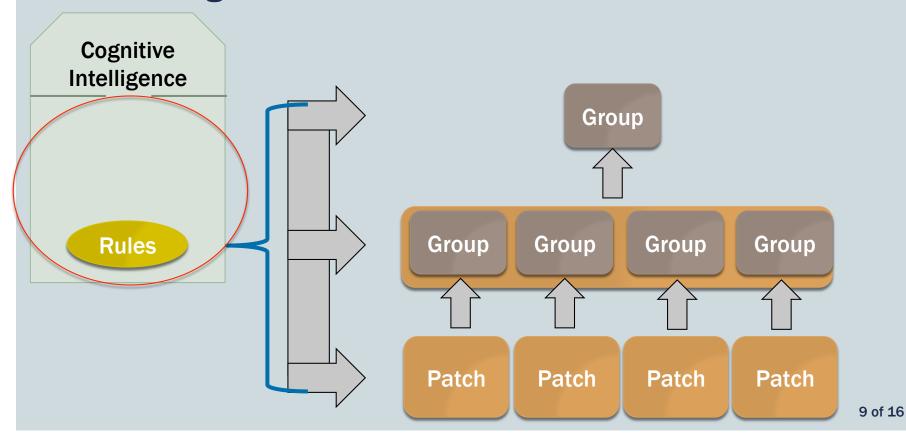
How do we Group a local Patch

- Simple set of Rules
 - What is "proximity"?
 - What is "similar"?
 - Angle
 - Magnitude



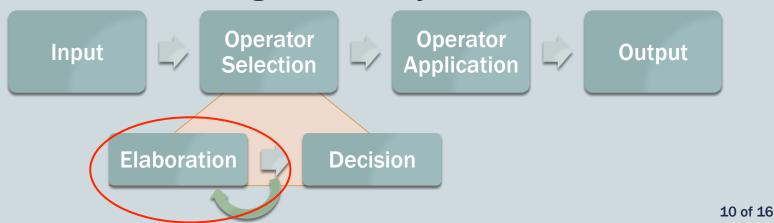
Hierarchical Grouping

Rules are the Same and apply at all levels allowing for multi-scale

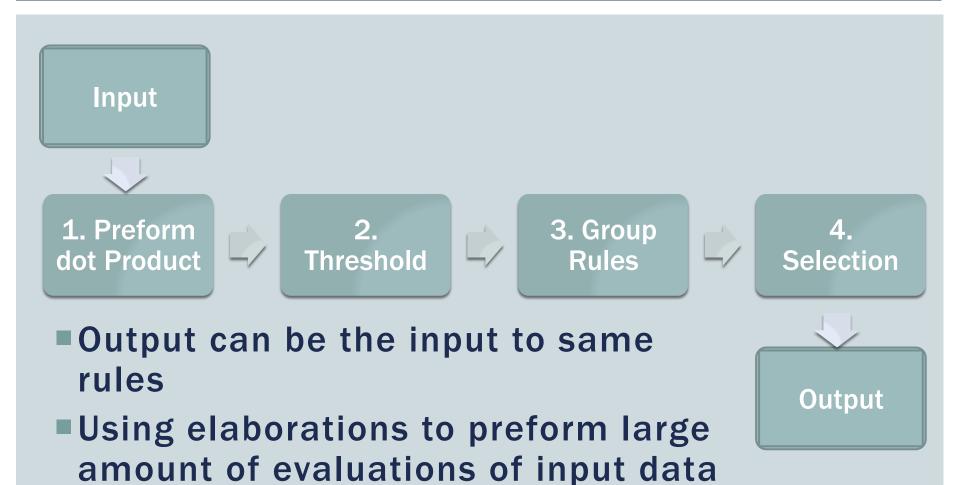


Why Soar?

- Production system allows for 'in theory' parallel execution
- Synergy with hardware implementation of Soar were working on
- Available Learning Capabilities
- Power of using Elaborations to generate parallel evaluation in a single Soar cycle



Power of Elaborations

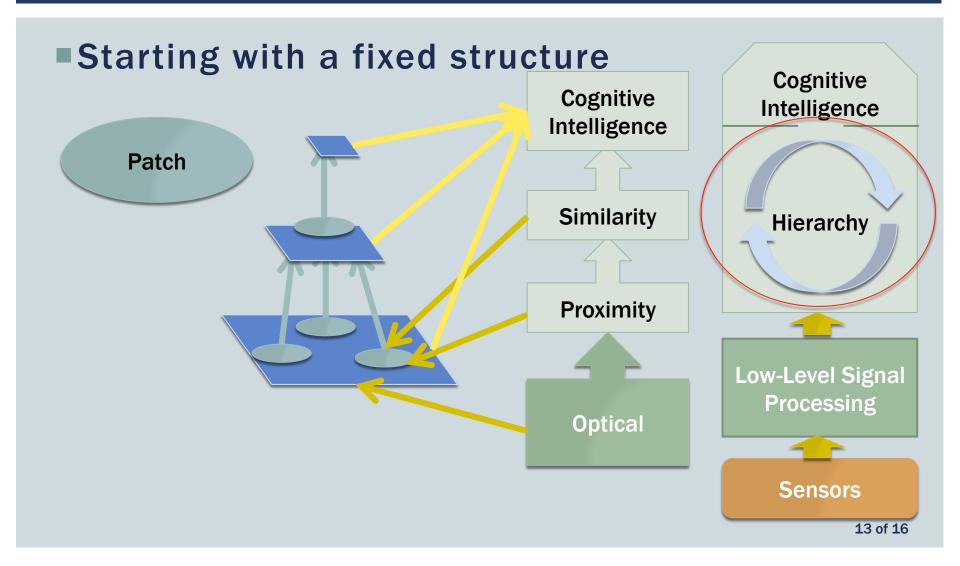


Grouping Rules

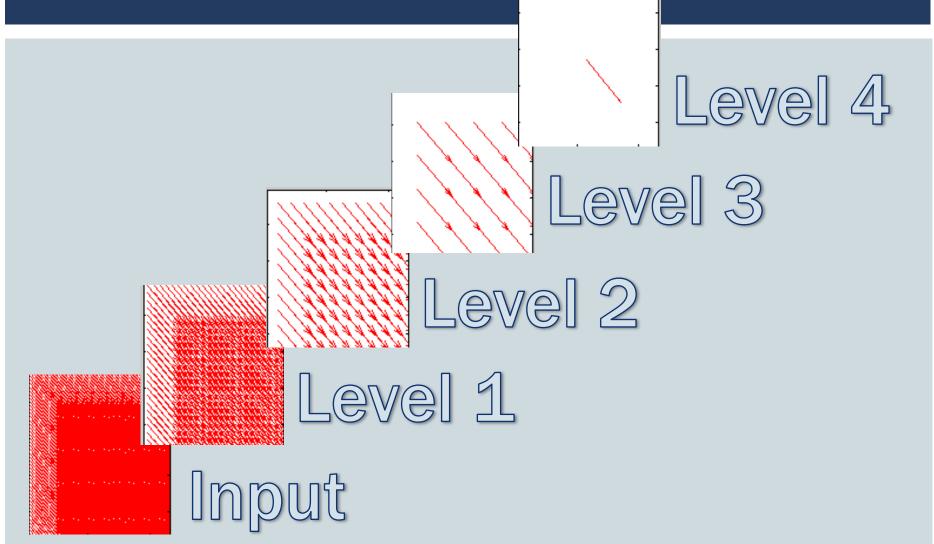
- What is defined as similar?
- What is good proximity?

- These change with time and are dynamic based on application
- Knowledge can be used to dynamically tune parameters

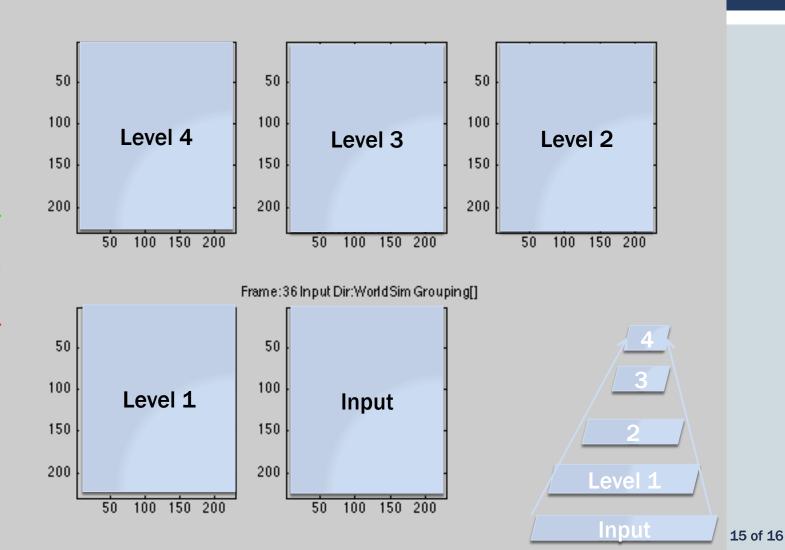
How do we implement it?



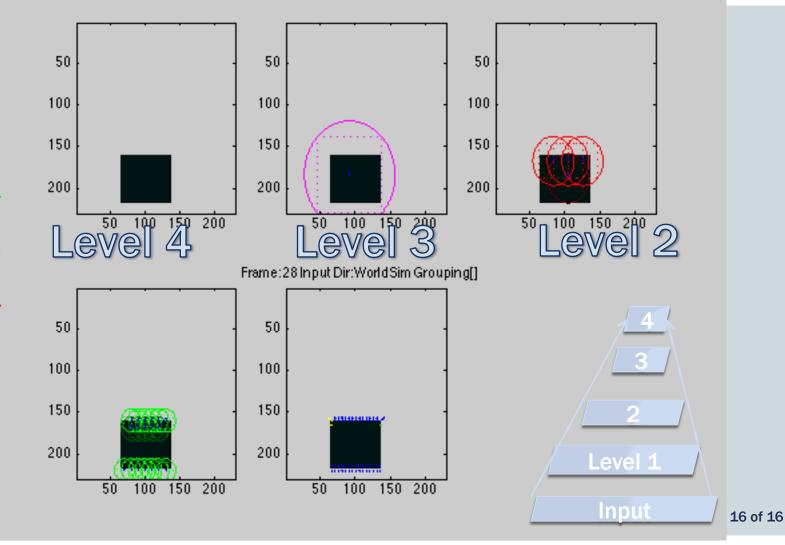
Optical Flow Example

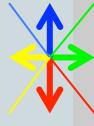


Example Layouts

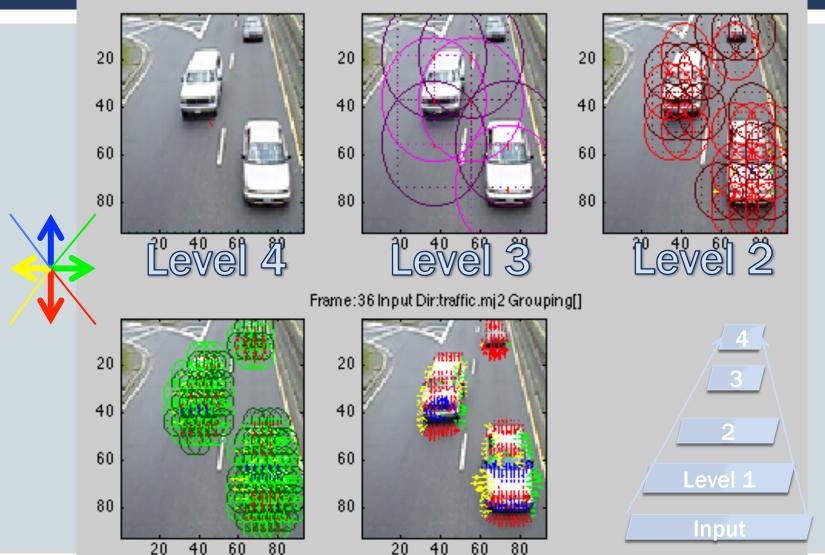


Simulated Example

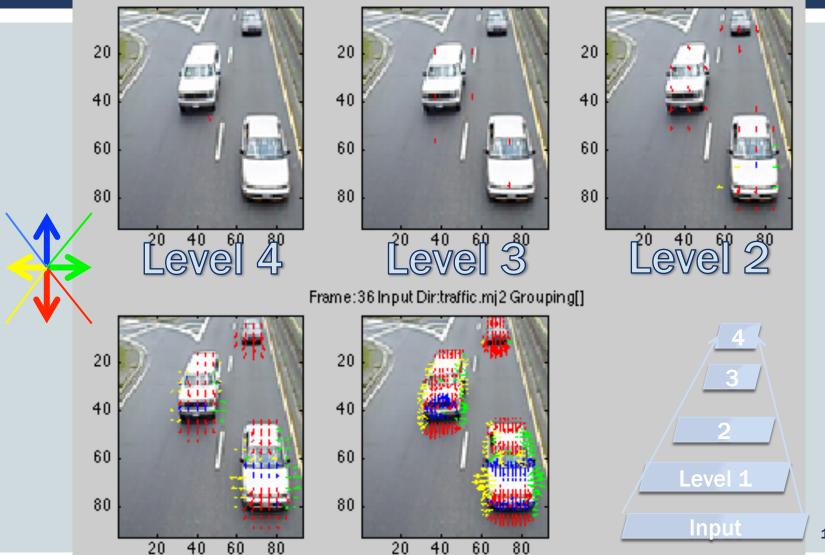




Real Example



Real Example



What's Next?

- Implementation in Soar
- Expansion to Multiple representations per patch
- Application of Soars Learning

Grouping over spatially distant groups (looking outside original patch proximity)

Soar Rules

```
Working Memory
(WM)
(S1 ^Group G1)
(G1 ^Flow F1)
(G1 ^Flow F2)
(F1 ^mag 1
      ^H 707
      ^V -707)
(F2 ^mag 1
      ^H 316
      ^V -949)
```

```
#Preform dot product in
productions
sp {elaborate*Dot*Product
  (state <s> ^name HierAgent
         ^Group <grp>
         ^GroupDot <grpDot>)
  (<grp> ^Flow <a1>
      ^Flow <a2>)
  (<a1> ^H <h1>
      ^{V} < v1>
  (<a2> ^H <h2>
      ^{V} < ^{2})
-->
  (<grpDot> ^Group <grp2>)
  (<grp2> ^element <a1>
      ^element <a2>
       ^dot (+ (* <h1> <h2>)
(* < v1 > < v2 >)))
```

Conclusion So Far

- Elaborations Rock
- Hardware realization can allow for exploiting parallelism to efficiently preform perceptual processing in Soar
- Hardware implementation could tip the balance between architectural vs knowledge based realization of cognitive capabilities
- What can you do with elaborations if they were truly parallel?