

3D visualization for the humanities

Alex Razoumov
alex.razoumov@westdri.ca



**Digital Research
Alliance** of Canada



SIMON FRASER
UNIVERSITY

- (1) copy of these slides and other files at <https://bit.ly/dhslides>
 - ▶ will download dh.zip (~ 12 MB)
 - ▶ uncompress it into your Downloads folder
 - ▶ find the slides dhsl.pdf inside
- (2) software installation described in slide 11

Bit of background

- Background in computational astrophysics
 - ▶ numerical simulations in galaxy formation, core-collapse supernovae, accretion disks, stellar hydrodynamics
 - ▶ designing numerical methods in computational fluid dynamics and radiative transfer
 - ▶ lots of parallel programming
- Day job: scientific visualization and teaching research computing across four Western provinces
 - ▶ 3D sci-vis of large computational models <https://ccvis.netlify.app>
 - ▶ basic and parallel programming: bash, Python, Julia, Chapel, C/C++, Fortran
- So ... teaching a 3D visualization workshop at DHSI
- My approach: apply scientific visualization tools to DH data
 - ▶ think of it as extension of interactive 2D plotting into the 3rd dimension using general-purpose, open-source, highly scalable tools
 - ▶ research scenario: already have a 3D dataset and want to visualize it
 - ▶ would love to hear back about humanities and social sciences problems for which we can apply today's tools

What we are not covering today

- Virtual tours, museums, reconstructions
 - ▶ game engines such as Unreal Engine, Unity, Godot (all open-source now)
 - ▶ 3D animation with Maya or Houdini (although these can be used for sci-vis)
 - ▶ special virtual environments such as Vsim (3D learning env. for DH), OpenSimulator (multi-user online env.)
 - ▶ don't confuse these with viewing visualizations with VR/AR headsets, which can be used for looking at pretty much everything we'll do today
- Architectural renderings
- 3D printing, modeling tools for design and prototyping – covered in another DHSI course?
- Photogrammetric processing of images – covered in DHSI course #52
 1. building 3D models from a set of images taken from various directions
 - many commercial offerings, rich area for VR and AR
 - for open-source <http://www.regard3d.org> ... good topic for a PhD thesis?
 2. building polynomial texture maps from a set of images taken with varying lighting direction
- Visualization of point cloud data – but we can do this with today's tools
- Artistic text visualizations

What we are covering today

- 3D multi-attribute scatter plots
 - ▶ semantic text analysis with multidimensional scaling to reduce distances to a 3D map
 - ▶ country ratings data from the Legatum 2015 Prosperity Index
- 3D graphs
 - ▶ NetworkX built-in graphs and layouts
 - ▶ custom layouts: encoding attribute(s) in the third dimension
 - ▶ scripting selections
 - ▶ graph statistics
- Continuous distributions
 - ▶ 2D function $f(x,y)$ extended into the third dimension
 - ▶ 3D function $f(x,y,z)$
 - ▶ using 3D filters to analyze data
- Creating animations
- Putting 3D visualizations on the web
 - ▶ briefly on the Smithsonian collection
 - ▶ vtk.js library on top of WebGL for client-side visualization
 - ▶ ParaView Glance
 - ▶ <http://3dhop.net>, an open-source software package for presenting interactive high-resolution 3D models online, aimed at the Cultural Heritage field

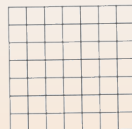
General-purpose 3D visualization tools

What is VTK?

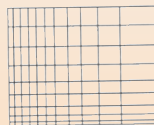
- **3D Visualization Toolkit** software system for 3D computer graphics, image processing, and visualization
- Open-source and cross-platform (Windows, Mac, Linux, other Unix variants)
- Supports OpenGL hardware acceleration
- Originally a C++ class library, now with interpreted interface layers for Python, Java, Tcl/Tk, JavaScript
- Supports wide variety of visualization and processing algorithms for polygon rendering, ray tracing, mesh smoothing, cutting, contouring, Delaunay triangulation, etc.
- Supports many data types: scalar, vector, tensor, texture, arrays of arrays
- Supports many 2D/3D spatial discretizations: structured and unstructured meshes, particles, polygons, etc. – see next slide
- Includes a suite of 3D interaction widgets, integrates nicely with several popular cross-platform GUI toolkits (Qt, Tk)
- Supports parallel processing and parallel I/O
- Base layer of many excellent 3D visualization packages (ParaView, VisIt, MayaVi, and several others)

VTK 2D/3D data: 6 major discretizations (mesh types)

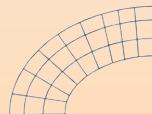
- **Image Data/Structured Points:** *.vti, points on a regular rectangular lattice, scalars or vectors at each point
- **Rectilinear Grid:** *.vtr, same as Image Data, but spacing between points may vary, need to provide steps along the coordinate axes, not coordinates of each point
- **Structured Grid:** *.vts, regular topology and irregular geometry, need to indicate coordinates of each point



(a) Image Data



(b) Rectilinear Grid



(c) Structured Grid

VTK 2D/3D data: 6 major discretizations (mesh types)

- **Particles/Unstructured Points:** *.particles
- **Polygonal Data:** *.vtp, unstructured topology and geometry, point coordinates, 2D cells only (i.e. no polyhedra), suited for maps
- **Unstructured Grid:** *.vtu, irregular in both topology and geometry, point coordinates, 2D/3D cells, suited for finite element analysis, structural design



(d) Unstructured Points



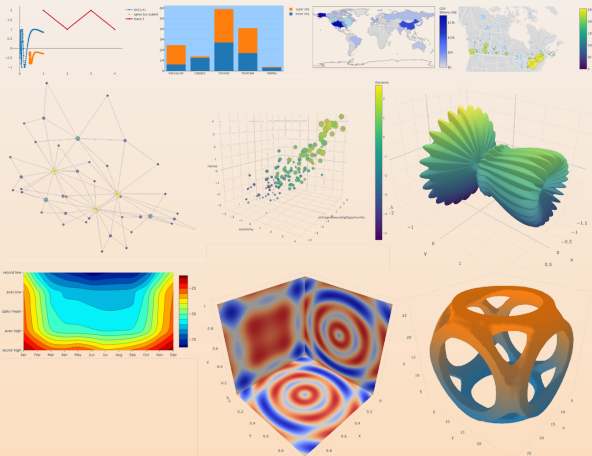
(e) Polygonal Data



(f) Unstructured Grid


Alternative tool: Plotly Python library

- Open-source project from Plot.ly <https://plot.ly/python>
- Produces dynamic html5 visualizations for the web
- APIs for Python (with/without Jupyter), R, JavaScript, MATLAB
- Can work offline (free) or by sending your data to your account on plot.ly (public plotting is free, paid unlimited private plotting and extra tools)



Software installation

- Today's only software requirement: <https://www.paraview.org/download>
 - ParaView comes with its own Python shell and VTK, but it is somewhat tricky to install libraries there
- To run Python scripts today, we will use <https://jupyter.dhssi.c3.ca>
 - now I will distribute the usernames and passwords
 - option 1: run a Python 3 notebook (not today: would need to compile VTK from source for 3.11)
 - option 2: run Python 3.10 scripts from the command line, all libraries already installed there
- Optional local installation:

1. for your OS install Python 3.10 or 3.11  there are many ways, e.g. via Miniconda
<http://conda.pydata.org/miniconda.html>, or a binary Python installer, or (MacOS only)
<https://brew.sh>

```
$ brew install python # installs into /opt/homebrew/bin/python3
$ export PATH="$ (brew --prefix) /opt/python@3/libexec/bin:$PATH" # add this to your ~/.bashrc
```

2. start the command shell (Terminal in MacOS/Linux, Anaconda or some other Prompt in Windows) and then install the required Python packages:

```
$ pip install virtualenv
$ virtualenv --no-download dhssi-env # install Python tools in the current directory
$ source dhssi-env/bin/activate # (every time) load the environment
$ pip install --upgrade pip
$ pip install pip_search # optional
$ pip_search vtk
$ pip install numpy networkx vtk gensim scikit-learn plotly pandas
...
$ deactivate # (every time) unload the environment
```

3. start Python and test your Miniconda installation:

```
>>> import vtk, networkx as nx
```

Download data to the remote machine

1. Open `https://jupyter.dhisi.c3.ca` in your browser, log in with your unique username and password, leave the OTP field blank
2. Start a server using the settings on the right
3. Launch a terminal by clicking on a button, also can do this via **File | New Launcher | Terminal**
4. Download and unpack the scripts and data

```
mkdir ~/tmp
cd ~/tmp
wget --no-check-certificate http://bit.ly/dhslides -O dhfiles.zip
# cp /project/def-sponsor00/shared/dhfiles.zip . # if wget does not work
unzip dhfiles.zip
rm dhfiles.zip
ls
```

5. Load our Python environment

```
source /project/def-sponsor00/shared/dhisi-env/bin/activate
```

Server Options

Reservation

None

Account

def-sponsor00

Time (hours)

4

Number of cores

1

Memory (MB)

3712

☒ Enable core oversubscription? Recommended for interactive usage

GPU configuration

None

User interface

JupyterLab

Python function to write points and graphs as VTK

- Function `writeObjects()` in `writeNodesEdges.py`
- Stores points or graphs as `vtkPolyData` or `vtkUnstructuredGrid`

```
def writeObjects(nodeCoords,
                 edges = [],
                 scalar = [], name = '', power = 1,
                 scalar2 = [], name2 = '', power2 = 1,
                 nodeLabel = [],
                 method = 'vtkPolyData',
                 fileout = 'test'):
```

```
"""
```

Store points and/or graphs as vtkPolyData or vtkUnstructuredGrid.

Required argument:

- nodeCoords is a list of node coordinates in the format [x,y,z]

Optional arguments:

- edges is a list of edges in the format [nodeID1,nodeID2]

- scalar/scalar2 is the list of scalars for each node

- name/name2 is the scalar's name

- power/power2 = 1 for r~scalars, 0.333 for V~scalars

- nodeLabel is a list of node labels

- method = 'vtkPolyData' or 'vtkUnstructuredGrid'

- fileout is the output file name (will be given .vtp or .vtu extension)

```
"""
```

Making 3D scatter plots

Semantic mapping

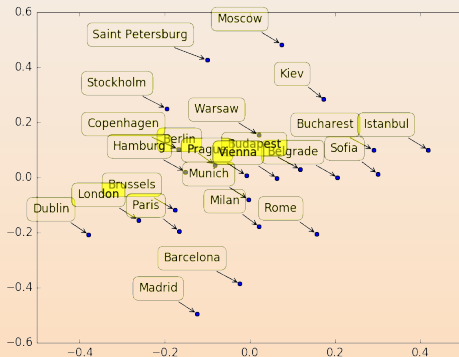
Idea inspired by [this blog post from 2009](#)

- Analyzed a corpus of 5,733,721 articles from 2,231 research journals (mostly science, technology and medical fields)
- Mapped the position of each journal in the 512-dimensional “semantic space” (more on this later)
- Calculated a 2231×2231 distance matrix in 512D
- Used multidimensional scaling to convert this matrix to 2D positions of 2231 points
- Coloured the points by 23 human-created journal categories
- Found excellent correspondence with human-created journal categories



Multidimensional scaling

Challenge: given a 24×24 table of pairwise distances between 24 cities, reconstruct their relative positions in 2D.



Semantic analysis of five public-domain texts

- (1) THE TIME MACHINE, by Herbert Wells
 - (2) OLIVER TWIST, by Charles Dickens
 - (3) ADVENTURES OF HUCKLEBERRY FINN, by Mark Twain
 - (4) THE WAR OF THE WORLDS, by Herbert Wells
 - (5) GALILIEAN-INVARIANT COSMOLOGICAL HYDRODYNAMICAL SIMULATIONS ON A MOVING MESH, by Volker Springel
- We'll analyze dictionaries and relative word frequencies and visualize a distance-based map of these texts in 3D

Algorithm

- (1) From each text pick up 30 longest paragraphs, $\times 5$ texts \Rightarrow 150 paragraphs
- (2) Convert line breaks and dashes to spaces, remove punctuation
- (3) Remove common words (prepositions, articles, etc)
- (4) Count words across all paragraphs and remove words that appear only once across all texts
- (5) Build a **global dictionary** (one for all five texts) of words, with N_{words} words
- (6) **Vectorize each paragraph** in the N_{words} -dimensional space, positioning it according to its word count; for details see <http://radimrehurek.com/gensim/tut1.html>
- (7) Normalize each vector to the number of words in its paragraph, to count relative word frequencies
- (8) **Calculate pairwise distances** between all paragraphs in the N_{words} -dimensional space \Rightarrow 150×150 matrix of numbers
- (9) Use multidimensional scaling to convert the distance matrix to paragraph positions in 3D, store them as VTK points
- (10) Visualize these points in 3D with ParaView, colouring by the author and sizing by the text per author (two texts for Herbert Wells)

Algorithm

- (1) From each text pick up 30 longest paragraphs, $\times 5$ texts \Rightarrow 150 paragraphs
- (2) Convert line breaks and dashes to spaces, remove punctuation
- (3) Remove common words (prepositions, articles, etc)
- (4) Count words across all paragraphs and remove words that appear only once across all texts
- (5) Build a **global dictionary** (one for all five texts) of words, with N_{words} words
- (6) **Vectorize each paragraph** in the N_{words} -dimensional space, positioning it according to its word count; for details see <http://radimrehurek.com/gensim/tut1.html>
- (7) Normalize each vector to the number of words in its paragraph, to count relative word frequencies
- (8) Calculate pairwise distances between all paragraphs in the N_{words} -dimensional space \Rightarrow 150×150 matrix of numbers
- (9) Use multidimensional scaling to convert the distance matrix to paragraph positions in 3D, store them as VTK points
- (10) Visualize these points in 3D with ParaView, colouring by the author and sizing by the text per author (two texts for Herbert Wells)

Algorithm

- (1) From each text pick up 30 longest paragraphs, $\times 5$ texts \Rightarrow 150 paragraphs
- (2) Convert line breaks and dashes to spaces, remove punctuation
- (3) Remove common words (prepositions, articles, etc)
- (4) Count words across all paragraphs and remove words that appear only once across all texts
- (5) Build a **global dictionary** (one for all five texts) of words, with N_{words} words
- (6) Vectorize each paragraph in the N_{words} -dimensional space, positioning it according to its word count; for details see <http://radimrehurek.com/gensim/tut1.html>
- (7) Normalize each vector to the number of words in its paragraph, to count relative word frequencies
- (8) Calculate pairwise distances between all paragraphs in the N_{words} -dimensional space \Rightarrow 150×150 matrix of numbers
- (9) Use multidimensional scaling to convert the distance matrix to paragraph positions in 3D, store them as VTK points
- (10) Visualize these points in 3D with ParaView, colouring by the author and sizing by the text per author (two texts for Herbert Wells)

Algorithm

- (1) From each text pick up 30 longest paragraphs, $\times 5$ texts \Rightarrow 150 paragraphs
- (2) Convert line breaks and dashes to spaces, remove punctuation
- (3) Remove common words (prepositions, articles, etc)
- (4) Count words across all paragraphs and remove words that appear only once across all texts
- (5) Build a **global dictionary** (one for all five texts) of words, with N_{words} words
- (6) **Vectorize each paragraph** in the N_{words} -dimensional space, positioning it according to its word count; for details see <http://radimrehurek.com/gensim/tut1.html>
- (7) Normalize each vector to the number of words in its paragraph, to count relative word frequencies
- (8) Calculate pairwise distances between all paragraphs in the N_{words} -dimensional space \Rightarrow 150×150 matrix of numbers
- (9) Use multidimensional scaling to convert the distance matrix to paragraph positions in 3D, store them as VTK points
- (10) Visualize these points in 3D with ParaView, colouring by the author and sizing by the text per author (two texts for Herbert Wells)

Algorithm

- (1) From each text pick up 30 longest paragraphs, $\times 5$ texts \Rightarrow 150 paragraphs
- (2) Convert line breaks and dashes to spaces, remove punctuation
- (3) Remove common words (prepositions, articles, etc)
- (4) Count words across all paragraphs and remove words that appear only once across all texts
- (5) Build a **global dictionary** (one for all five texts) of words, with N_{words} words
- (6) **Vectorize each paragraph** in the N_{words} -dimensional space, positioning it according to its word count; for details see <http://radimrehurek.com/gensim/tut1.html>
- (7) Normalize each vector to the number of words in its paragraph, to count relative word frequencies
- (8) Calculate pairwise distances between all paragraphs in the N_{words} -dimensional space \Rightarrow 150×150 matrix of numbers
- (9) Use multidimensional scaling to convert the distance matrix to paragraph positions in 3D, store them as VTK points
- (10) Visualize these points in 3D with ParaView, colouring by the author and sizing by the text per author (two texts for Herbert Wells)

Algorithm

- (1) From each text pick up 30 longest paragraphs, $\times 5$ texts \Rightarrow 150 paragraphs
- (2) Convert line breaks and dashes to spaces, remove punctuation
- (3) Remove common words (prepositions, articles, etc)
- (4) Count words across all paragraphs and remove words that appear only once across all texts
- (5) Build a **global dictionary** (one for all five texts) of words, with N_{words} words
- (6) **Vectorize each paragraph** in the N_{words} -dimensional space, positioning it according to its word count; for details see <http://radimrehurek.com/gensim/tut1.html>
- (7) Normalize each vector to the number of words in its paragraph, to count relative word frequencies
- (8) **Calculate pairwise distances** between all paragraphs in the N_{words} -dimensional space \Rightarrow 150×150 matrix of numbers
- (9) Use multidimensional scaling to convert the distance matrix to paragraph positions in 3D, store them as VTK points
- (10) Visualize these points in 3D with ParaView, colouring by the author and sizing by the text per author (two texts for Herbert Wells)

Algorithm

- (1) From each text pick up 30 longest paragraphs, $\times 5$ texts \Rightarrow 150 paragraphs
- (2) Convert line breaks and dashes to spaces, remove punctuation
- (3) Remove common words (prepositions, articles, etc)
- (4) Count words across all paragraphs and remove words that appear only once across all texts
- (5) Build a **global dictionary** (one for all five texts) of words, with N_{words} words
- (6) **Vectorize each paragraph** in the N_{words} -dimensional space, positioning it according to its word count; for details see <http://radimrehurek.com/gensim/tut1.html>
- (7) Normalize each vector to the number of words in its paragraph, to count relative word frequencies
- (8) **Calculate pairwise distances** between all paragraphs in the N_{words} -dimensional space \Rightarrow 150×150 matrix of numbers
- (9) Use **multidimensional scaling** to convert the distance matrix to paragraph positions in 3D, store them as VTK points
- (10) Visualize these points in 3D with ParaView, colouring by the author and sizing by the text per author (two texts for Herbert Wells)

Algorithm

- (1) From each text pick up 30 longest paragraphs, $\times 5$ texts \Rightarrow 150 paragraphs
- (2) Convert line breaks and dashes to spaces, remove punctuation
- (3) Remove common words (prepositions, articles, etc)
- (4) Count words across all paragraphs and remove words that appear only once across all texts
- (5) Build a **global dictionary** (one for all five texts) of words, with N_{words} words
- (6) **Vectorize each paragraph** in the N_{words} -dimensional space, positioning it according to its word count; for details see <http://radimrehurek.com/gensim/tut1.html>
- (7) Normalize each vector to the number of words in its paragraph, to count relative word frequencies
- (8) **Calculate pairwise distances** between all paragraphs in the N_{words} -dimensional space \Rightarrow 150×150 matrix of numbers
- (9) Use **multidimensional scaling** to convert the distance matrix to paragraph positions in 3D, store them as VTK points
- (10) Visualize these points in 3D with ParaView, colouring by the author and sizing by the text per author (two texts for Herbert Wells)

Hands-on: running the script

1. The entire algorithm is implemented in `semanticMapping.py`

🔍 let's take a look at it

▶ if working inside a Jupyter notebook, load the code into the current cell with:

```
%load semanticMapping.py    # fills the current cell with code from the script
```

and then run it

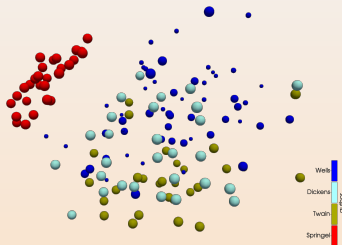
▶ if working in the terminal, use the commands:

```
pwd          # should be in /home/userXX/tmp
cat semanticMapping.py
python semanticMapping.py
```

2. Locate and download `texts.vtu` to your computer

Hands-on: viewing results in ParaView

- Load `texts.vtu` into ParaView and follow my instructions
 - ▶ colour glyphs by “author”
 - ▶ switch from continuous to categorical colours and annotate them, e.g.
 - blue, author=1, Herbert Wells
 - pale blue, author=2, Charles Dickens
 - beige, author=3, Mark Twain
 - red, author=4, Volker Springel
 - ▶ size glyphs by “novel per author” (large: The Time Machine, small: The War of the Worlds)



- Save the state to file `fourAuthors.pvsm`
- On Unix-like systems can reload from the GUI or from the command line with something like

```
/path/to/paraview --state=fourAuthors.pvsm
```

- Alternatively could map to 2D, using the third dimension to visualize another attribute, e.g. the year of publication, or the text size, or the number of protagonists, etc.

Hands-on: viewing results with plotly

```
$ diff semanticMapping.py directMapping.py
< print(coords)
98,99c98,116
< writeObjects(coords, scalar=author, name='author', fileout='texts',
<             scalar2=novelPerAuthor, name2='novel_per_author', method = 'vtkUnstructuredGrid')
---
> x = [point[0] for point in coords]
> y = [point[1] for point in coords]
> z = [point[2] for point in coords]
>
> import plotly.offline as py
> py.init_notebook_mode(connected=True)
> import plotly.graph_objs as go
> spheres = go.Scatter3d(x=x, y=y, z=z, mode='markers',
>                       marker=dict(
>                           sizemode = 'diameter', sizeref = 0.2, size = novelPerAuthor,
>                           color = author, colorscale = 'Viridis',
>                           colorbar = dict(title = 'author'),
>                           line = dict(color='rgb(140,140,170)')))) # sphere edge
> layout = go.Layout(title='Each sphere is a paragraph coloured by author'+
>                    'and sized by novelPerAuthor')
> fig = go.Figure(data=[spheres], layout=layout)
> py.iplot(fig)
```

- There are two code versions: (1) for running/rendering inside a Jupyter notebook, and (2) for running in a terminal and saving into an HTML file
 - 🔖 make sure to run the correct one

Speculative semantic analysis of the four gospels ▸

- `gospels.py` is a copy of `semanticMapping.py` doing the same analysis on the four gospels (Matthew, Mark, Luke and John) in Greek
- Run it inside Jupyter
- Download `testament.vtu` and load it into ParaView
- Continuous colouring with the default colour map shows **Matthew in blue**, **Mark in pale blue**, **Luke in beige**, and **John in red**
- Switch to categorical colouring, assign similar colours and annotate them

Speculative semantic analysis of the four gospels ▷▷

- **John** (red) is the most independent
- **Luke** (beige) ← **Matthew** (blue) + **Mark** (pale blue)
 - ▶ **Luke** has a lot of overlap with **Matthew** and **Mark**, so likely a composition from both **Matthew** and **Mark**
 - ▶ not the other way around (**Matthew** or **Mark** being a composition from **Luke**), as **Matthew** and **Mark** are sufficiently different
- Drop **Luke** (author=3) from the analysis: apply a Threshold filter 2.5 – 3.5 acting on the output of the Glyph filter, and invert

Speculative semantic analysis of the four gospels ▷▷▷

- **Matthew** ← **John** + **Mark**
 - ▶ **Matthew** may have pulled a bit from **John** and **Mark** (sitting in the middle between the two)
 - ▶ this leaves us with **John** and **Mark** as primaries
- Drop **Matthew** (author=1) from the analysis: add a second Threshold filter 1.5 – 4

Speculative semantic analysis of the four gospels ▷▷▷▷

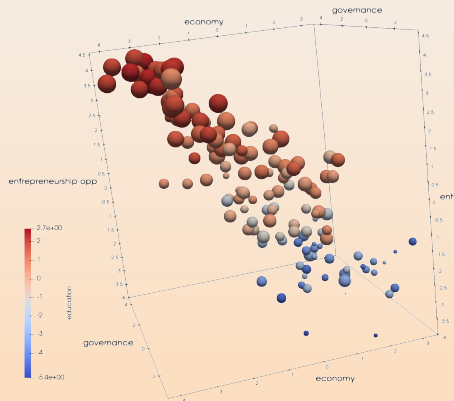
- **Mark** and **John** have good separation, but there is an open region between them left by **Matthew** and **Luke**
- Supports (does not rule out?) the idea that there could have been another (now lost) primary that would have filled this region that both **Matthew** and **Luke** pulled from
- This leaves us with **John**, **Mark**, and a lost source as our primaries
- Couple of extreme outliers: written by entirely different authors, possibly in a different time period?

Exercises: pick the one you like

- (1) Apply `semanticMapping.py` to several other texts, visualize the results, and do your own analysis. Do the results make sense?
 - ▶ need to be in plain text (any language), not in a proprietary binary format
 - ▶ could be your own texts
- (2) Combine the five texts in English and the four gospels in Greek into a single analysis
- (3) More challenging: use multidimensional scaling to reduce distances to 2D, and then plot the paragraphs in 3D using the third dimension to visualize some interesting attribute
- (4) Repeat the “four gospels” visualization in Plotly

Prosperity index: 3D scatter plot, 5 attributes

- Data from the Legatum 2015 Prosperity Index
<http://www.prosperity.com/#!/ranking>
(click on Scores, best to copy/paste from Firefox)
- Take a look at the data in `legatum2015.csv`: 8 rankings for each country
- Run the code `countries.py` (writes five attributes into `countries.vtp`)
- Apply Glyph filter with Glyph Mode = All Points
- 3D position by (economy, entrepreneurship opportunity, governance)
- Colour by education
- Size by safetySecurity
- Save the state to `countries.pvsm`
- Optionally turn on labels for countries – see the next slide



Labeling nodes

- (1) Press V to bring up Find Data dialogue
- (2) Find=Points from=countries.vtp with $ID \geq 0$ (will labels all points) and press Find Data
- (3) Make sure countries.vtp is visible in the pipeline browser
- (4) Check Point Labels -> tag to display the label (and not another variable)
- (5) Click on the gear icon (Edit Label Properties) and set opacity=0 and adjust the Point Label Font size
- (6) Now try labeling a single country (unfortunately, "tag is countryName" syntax does not work), but can look up the country in `legatum2015.csv`, check the line number, subtract 2, and use that as ID
- (7) Now label all those with poor security: `safetySecurity ≤ 3`
- (8) Now label all those with good education: `education ≥ 1.5`

Labeling nodes

- (1) Press V to bring up Find Data dialogue
- (2) Find=Points from=countries.vtp with $ID \geq 0$ (will labels all points) and press Find Data
- (3) Make sure countries.vtp is visible in the pipeline browser
- (4) Check Point Labels -> tag to display the label (and not another variable)
- (5) Click on the gear icon (Edit Label Properties) and set opacity=0 and adjust the Point Label Font size
- (6) Now try labeling a single country (unfortunately, "tag is countryName" syntax does not work), but can look up the country in `legatum2015.csv`, check the line number, subtract 2, and use that as ID
- (7) Now label all those with poor security: `safetySecurity \leq 3`
- (8) Now label all those with good education: `education \geq 1.5`

Labeling nodes

- (1) Press V to bring up Find Data dialogue
- (2) Find=Points from=countries.vtp with $ID \geq 0$ (will labels all points) and press Find Data
- (3) Make sure countries.vtp is visible in the pipeline browser
- (4) Check Point Labels -> tag to display the label (and not another variable)
- (5) Click on the gear icon (Edit Label Properties) and set opacity=0 and adjust the Point Label Font size
- (6) Now try labeling a single country (unfortunately, "tag is countryName" syntax does not work), but can look up the country in `legatum2015.csv`, check the line number, subtract 2, and use that as ID
- (7) Now label all those with poor security: $safetySecurity \leq 3$
- (8) Now label all those with good education: $education \geq 1.5$

Labeling nodes

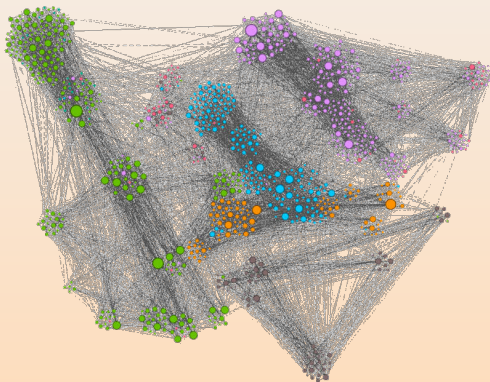
- (1) Press V to bring up Find Data dialogue
- (2) Find=Points from=countries.vtp with $ID \geq 0$ (will labels all points) and press Find Data
- (3) Make sure countries.vtp is visible in the pipeline browser
- (4) Check Point Labels -> tag to display the label (and not another variable)
- (5) Click on the gear icon (Edit Label Properties) and set opacity=0 and adjust the Point Label Font size
- (6) Now try labeling a single country (unfortunately, "tag is countryName" syntax does not work), but can look up the country in `legatum2015.csv`, check the line number, subtract 2, and use that as ID
- (7) Now label all those with poor security: $safetySecurity \leq 3$
- (8) Now label all those with good education: $education \geq 1.5$

29 / 82

Visualizing 3D graphs

Dedicated 2D graph tools

- Many dedicated 2D tools, most popular ones are Gephi, Cytoscape (both open source)



- How can we extend this to 3D? And do we really want to?

Dedicated 3D graph tools (circa 2016)

- Force Atlas 3D plugin for Gephi <http://bit.ly/1QcLuLK> gives a 2D projection with nodes as spheres at (x,y,z) and the proper perspective and lighting, but **can't interact with the graph in 3D**
- Functional brain network visualization tools, e.g. Connectome Viewer <http://cmtk.org/viewer>
- GraphInsight was a fantastic tool, free academic license, embedded Python shell – went to the dark side in the fall 2013 (**purchased by a bank, no longer exists**, can still find demo versions and youtube videos) <http://www.graphinsight.com> is down ... <https://twitter.com/GraphInsight>
- Walrus <http://www.caida.org/tools/visualization/walrus> was a research project, **latest update in 2005**, old source still available but people seem to have trouble compiling and running it now
- Network3D from Microsoft seems to be a **short-lived research project, Windows only**
- BioLayout Express 3D <http://www.bioblayout.org/download> is Ok, written in Java, development stopped in 2014 but still works, **only the commercial tool maintained** (\$500)
- ORA NetScenes from Carnegie Mellon for “networked text visualization”, not bad, **Windows only, not open-source, licensing not clear** (more of a demo license, they reserve the right to make it paid)
- Number of other research projects, in my view **not targeting end users**, e.g. <http://www.opengraphiti.com> (pain to compile: tends to pick /usr/bin/python, only Mac/Linux), or WebGL projects <https://youtu.be/qHkjSxbnzAU> that really require programming knowledge
 - <https://markwolff.shinyapps.io/QMtripplot17C/> is a nice WebGL example in R + Shiny
 - 3D Force-Directed Graph web component <https://github.com/vasturiano/3d-force-graph> implemented with ThreeJS and WebGL for 3D rendering and d3-force-3d for the layout (force) engine, **not bad overall**, but **very CPU/GPU-heavy on the client**

Is there any good, open-source, cross-platform,
currently maintained, user-friendly dedicated 3D
graph visualization tool?

... or we could use a general-purpose visualization tool

NetworkX + VTK + ParaView

- Our first solution: NetworkX + VTK + ParaView
 - ▶ advantages: (1) using general-purpose visualization tool; (2) everything is scriptable; (3) can scale directly to $10^{\sim 5.5}$ nodes, with a little extra care to $10^{\sim 9.5}$ nodes
 - ▶ disadvantages: graphs are static 3D objects, can't click on a node, highlight connections, move nodes, etc. (but we can script all these interactions!)
 - ▶ note: in the current implementation edges are displayed as straight lines; possible to use `vtkArcSource` or `vtkPolyLine` to create arcs and store them as `vtkPolyData`
- (1) We'll use NetworkX + VTK to create a graph, position nodes, optionally compute graph statistics, and write everything to a VTK file; we'll do this in Python 3.8
- (2) Load that file into ParaView
 - On presenter's laptop see *mutOnCtOrbits.mp4* for a more complex graph (6×10^5 edges) created with this workflow

NetworkX + Plotly

- Our second solution: NetworkX + Plotly
 - ▶ no intermediate steps: graph created directly in Python, opens automatically in a web browser
 - ▶ everything is scriptable
 - ▶ limited scaling
 - ▶ similarly to ParaView, no proper “graph controls” in 3D

NetworkX graphs

- NetworkX is a Python package for the creation, manipulation, and analysis of complex networks
- Documentation at <http://networkx.github.io>

```
import networkx as nx
```

```
# return all names (attributes and methods) inside nx
dir(nx)
```

```
# generate a list (of 139) built-in graph types
# with Python's ``list comprehension``
[x for x in dir(nx) if "_graph" in x]
```

NetworkX layouts ▸

```
# generate a (much shorter) list of built-in graph layouts
[x for x in dir(nx) if "_layout" in x]
# will print ['arf_layout', 'bipartite_layout', 'circular_layout',
# 'fruchterman_reingold_layout', 'kamada_kawai_layout', 'multipartite_layout',
# 'planar_layout', 'random_layout', 'rescale_layout', 'rescale_layout_dict',
# 'shell_layout', 'spectral_layout', 'spiral_layout', 'spring_layout']

# can always look at the help pages
help(nx.circular_layout)
```

- spring_ and fruchterman_reingold_ are the same, so really 13 built-in layouts
- can use 3rd-party layouts
- circular_, random_, shell_ are fixed layouts
- spring_ and spectral_ are force-directed layouts: **linked nodes attract each other**, **non-linked nodes are pushed apart**

NetworkX layouts ▸▸

- Layouts typically return a dictionary, with each element being a 2D/3D coordinate array indexed by the node's number (or name)

```
# generate a random graph with 10 nodes and 50 edges
H = nx.gnm_random_graph(10,50)
```

```
# the layout is a dictionary of 2D coordinates of all 10 nodes
nx.shell_layout(H,dim=2)      # in this layout only dim=2 supported
```

```
# each value of these is an (x,y,z) coordinate of a node
nx.circular_layout(H,dim=3)
nx.spring_layout(H,dim=3)
nx.random_layout(H,dim=3)
nx.spectral_layout(H,dim=3)
```

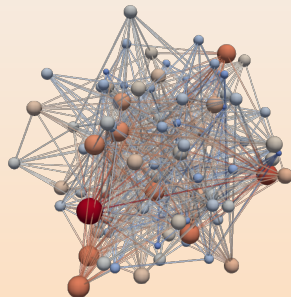

Our first graph (randomGraph.py)

```
import networkx as nx
from writeNodesEdges import writeObjects

numberNodes, numberEdges = 100, 500
H = nx.gnm_random_graph(numberNodes, numberEdges)
print('nodes:', H.nodes())
print('edges:', H.edges())

# return a dictionary of positions keyed by node
pos = nx.random_layout(H, dim=3)
# convert to list of positions (each is a list)
xyz = [list(pos[i]) for i in pos]

degree = [d for i, d in H.degree()]
writeObjects(xyz, edges=H.edges(), scalar=degree,
             name='degree', fileout='network')
```



Load this graph into ParaView

- After you run `randomGraph.py` from the command line, to reproduce the previous slide, you have three options:
 - (1) load the file `network.vtp`, apply Glyph filter, apply Tube filter, edit their properties, or
 - (2) in ParaView's menu navigate to **File | Load State** and select `drawGraph.pvsm`, or
 - **important: adjust the data file location!**

```
$ grep Users drawGraph.pvsm
<Element index="0" value="/Users/razoumov/teaching/humanities/network.vtp"/>
<Element index="0" value="/Users/razoumov/teaching/humanities/network.vtp"/>
```

- (3) on a Unix-based system start ParaView and load the state with one command:

```
/path/to/paraview --state=drawGraph.pvsm
```

- For subsequent plots, you can reload data without rebuilding the plot
File | Reload Files

Labeling graph nodes

- (1) Press V to bring up Find Data dialogue
- (2) Find Points with $ID \geq 0$ (or other selection)
- (3) Make points visible in the pipeline browser
- (4) Check Point Labels -> ID (can also do this operation from View -> Selection Display Inspector)
- (5) Adjust the label font size
- (6) Set original data opacity to 0

Also we can label only few selected points, e.g. those with degree ≥ 10

Switch to spring layout

- Let's apply a force-directed layout

```
$ diff randomGraph.py randomGraph2.py
10c10,11
< pos = nx.random_layout(H,dim=3)
---
> pos = nx.spring_layout(H,dim=3,k=1)
```

- Run “python randomGraph2.py” from the command line
- Press Disconnect to clear everything from the pipeline browser
- Reload the state file drawGraph.pvsm

Few more graphs: complete bipartite graph

Composed of two partitions with N nodes in the first and M nodes in the second. Each node in the first set is connected to each node in the second.

```
$ diff randomGraph2.py completeBipartite.py
5,7c5,6
< H = nx.gnm_random_graph(numberNodes,numberEdges)
< print('nodes:', H.nodes())
< print('edges:', H.edges())
---
> H = nx.complete_bipartite_graph(10,5)
> print(nx.number_of_nodes(H), 'nodes_and', nx.number_of_edges(H), 'edges')
15a15
> print('degree_=', degree)
```

- Run “python completeBipartite.py” from the command line
- Press Disconnect to clear everything from the pipeline browser
- Reload the state file drawGraph.pvsm

Your own graphs

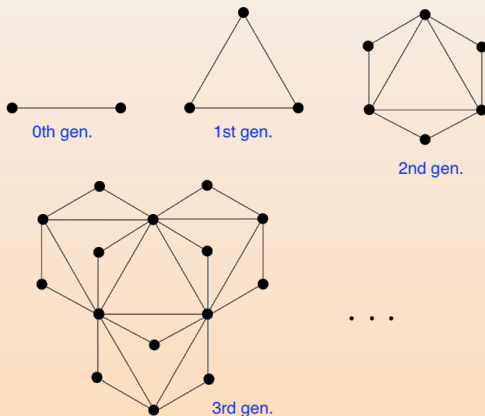
We are not limited to NetworkX's built-in graphs.
Can build our own graphs with:

```
H = nx.Graph()
H.add_node(1) # add a single node
H.add_nodes_from([2,3]) # add a list of nodes
H.add_edge(2,3) # add a single edge
H.add_edges_from([(1,2), (1,3)]) # add a list of edges
...
```

Dorogovtsev-Goltsev-Mendes graph

Dorogovtsev-Goltsev-Mendes graph is a fractal network from <http://arxiv.org/pdf/cond-mat/0112143.pdf>; in each subsequent generation:

1. every edge from the previous generation yields a new node, and
2. the new graph can be made by connecting together three previous-generation graphs



Dorogovtsev-Goltsev-Mendes graph (dgm.py)

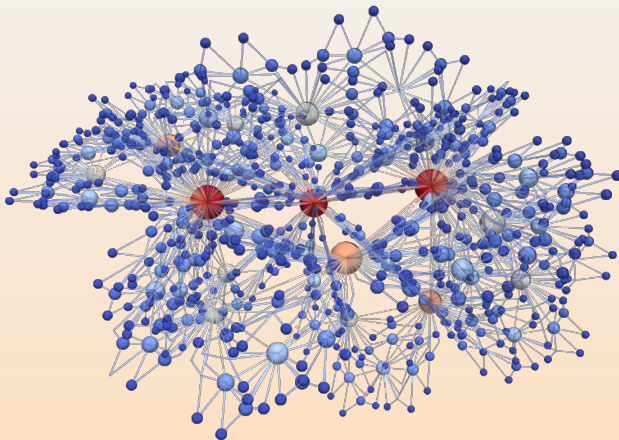
```
import networkx as nx
# from forceatlas import forceatlas2_layout
from writeNodesEdges import writeObjects
import sys
generation = int(sys.argv[1])
H = nx.dorogovtsev_goltsev_mendes_graph(generation)

# Force Atlas 2 from https://github.com/tpoisot/nxfa2.git
# pos = forceatlas2_layout(H, iterations=100, kr=0.001, dim=3)
pos = nx.spring_layout(H, dim=3)

# convert to list of positions (each is a list)
xyz = [list(pos[i]) for i in pos]

print(nx.number_of_nodes(H), 'nodes_and', nx.number_of_edges(H), 'edges')
degree = [d for i,d in H.degree(H.nodes())]
writeObjects(xyz, edges=H.edges(), scalar=degree,
            name='degree', power=0.333,
            fileout='network')
```


Dorogovtsev-Goltsev-Mendes graph (7th generation)



From the command line run

```
python dgm.py 1
```

...

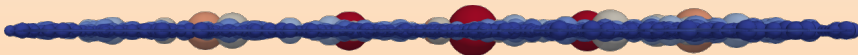
```
python dgm.py 7    # takes ~3s on my laptop
```

Custom layouts ▸

Let's first make a flat graph:

```
9,10c9,10
< pos = nx.spring_layout(H, dim=3)
---
> pos = nx.spring_layout(H, dim=2)
13c13
< xyz = [list(pos[i]) for i in pos]
---
> xyz = [[pos[i][0], pos[i][1], 0] for i in pos]
```

Run this with `python dgmFlat.py 7`, reload the state file
`drawGraph.pvsm`, adjust glyph radii

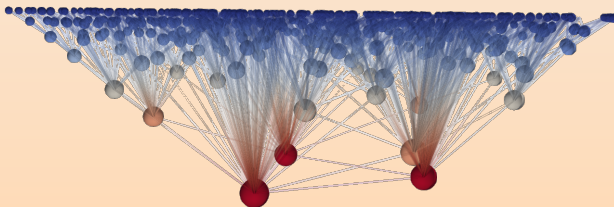


Custom layouts ▸▸

Now let's offset each node in the z-direction by a function of its degree:

```
$ diff dgmFlat.py dgmOffset.py
12,13d11
< xyz = [[pos[i][0], pos[i][1], 0] for i in pos]
15a14,15
> xyz = [[pos[i][0], pos[i][1], (degree[i])**0.5/15.] for i in pos]
```

Run this with “python dgmOffset.py 7” and colour edges by degree



Social network (florentineFamilies.py)

Let's visualize `nx.florentine_families_graph()`. It returns a list of edges with the nodes indexed by the family name. The function `writeObjects()` expects integer ID indices instead – hence the loop below: (when plotting, don't forget to turn on the labels!)

```
import networkx as nx
from writeNodesEdges import writeObjects
H = nx.florentine_families_graph()
nodes = list(H.nodes())

# index edges by their node IDs
edges = []
for edge in H.edges():
    edges.append([nodes.index(edge[0]), nodes.index(edge[1])])

pos = nx.spring_layout(H, dim=3, k=1) # return a dictionary of positions keyed by node
xyz = [list(pos[i]) for i in pos] # convert to list of positions (each is a list)

degree = [d for i, d in H.degree(H.nodes())]
writeObjects(xyz, edges=edges, scalar=degree, name='degree',
            fileout='network', nodeLabel=nodes, power=0.333)
```

Highlighting individual nodes (and edges)

Let's highlight nodes 'Strozzi', 'Tornabuoni', 'Albizzi' with colour.

```
$ diff florentineFamilies.py florentineFamilies2.py
14c14,17
< degree = [d for i,d in H.degree(H.nodes())]
---
> degree = [1]*len(nodes)
> selection = ['Strozzi', 'Tornabuoni', 'Albizzi']
> for i in selection:
>     degree[nodes.index(i)] = 3
```

How about highlighting the selection and their edges?
That's very easy: simply colour the edges by node degree.

Eigenvector centrality (dgmCentrality.py)

Let's compute and visualize eigenvector centrality in the 5th-deneration Dorogovtsev-Goltsev-Mendes graph with our custom 3D layout.

```
import networkx as nx
# from forceatlas import forceatlas2_layout
from writeNodesEdges import writeObjects
H = nx.dorogovtsev_goltsev_mendes_graph(5)
# pos = forceatlas2_layout(H, iterations=100, kr=0.001, dim=2)
pos = nx.spring_layout(H, dim=3)
print(nx.number_of_nodes(H), 'nodes_and', nx.number_of_edges(H), 'edges')
degree = [d for i,d in H.degree(H.nodes())]
xyz = [[pos[i][0], pos[i][1], (degree[i])**0.5/5.7] for i in pos]

# compute and print eigenvector centrality
ec = nx.eigenvector_centrality(H) # dictionary of nodes with EC as the value
ecList = [ec[i] for i in ec]
print('degree_', degree)
print('eigenvector_centrality_', ecList)
print('min/max_', min(ecList), max(ecList))

writeObjects(xyz, edges=H.edges(), scalar=degree, name='degree', power=0.333,
             scalar2=ecList, name2='eigenvector_centrality', power2=0.333, fileout='network')
```

- Run python dgmCentrality.py and load into ParaView by hand
- Colour by degree, size by eigenvector centrality

Other statistics in NetworkX

- Various centrality measures: degree, closeness, betweenness, current-flow closeness, current-flow betweenness, eigenvector, communicability, load, dispersion <https://networkx.github.io/documentation/stable/reference/algorithms/centrality.html>
- Several hundred built-in algorithms for various calculations <https://networkx.github.io/documentation/stable/reference/algorithms>

Graphs in Plotly (dgmDirect.py)

Last tested in 2019. Since then many functions have been redefined or moved around ...

```
import plotly.offline as py, plotly.graph_objs as go, networkx as nx, sys
py.init_notebook_mode(connected=True)
gen = int(sys.argv[1])
H = nx.dorogovtsev_goltsev_mendes_graph(gen)
print(H.number_of_nodes(), 'nodes and', H.number_of_edges(), 'edges')
pos = nx.spring_layout(H, dim=3)
Xn = [pos[i][0] for i in pos]; Yn = [pos[i][1] for i in pos]    # node coordinates
Zn = [pos[i][2] for i in pos]; Xe, Ye, Ze = [], [], []
for edge in H.edges():
    Xe += [pos[edge[0]][0], pos[edge[1]][0], None]    # edge ends' coordinates
    Ye += [pos[edge[0]][1], pos[edge[1]][1], None]
    Ze += [pos[edge[0]][2], pos[edge[1]][2], None]
degree = [deg[1] for deg in H.degree()]    # list of degrees of all nodes
labels = [str(i) for i in range(H.number_of_nodes())]
edges = go.Scatter3d(x=Xe, y=Ye, z=Ze, mode='lines',
    line=go.Line(color='rgb(160,160,160)', width=2), hoverinfo='none')
nodes = go.Scatter3d(x=Xn, y=Yn, z=Zn, mode='markers',
    marker=go.Marker(sizemode='area', sizeref=0.01, size=degree,
        color=degree, colorscale='Viridis',
        line=go.Line(color='rgb(50,50,50)', width=0.5)),
    text=labels, hoverinfo='text')
axis = dict(showbackground=False, showline=False, zeroline=False, showgrid=False,
    showticklabels=False, title='')
layout = go.Layout(title = str(gen) + "-gen Dorogovtsev-Goltsev-Mendes graph",
    showlegend=False, scene=go.Scene(xaxis=go.XAxis(axis), yaxis=go.YAxis(axis),
        zaxis=go.ZAxis(axis)), margin=go.Margin(t=100))
fig = go.Figure(data=[edges,nodes], layout=layout)
py.iplot(fig)
```


Visualizing continuous distributions in 3D

Mockup 2D continuous function

2D function defined inside a unit square ($x, y \in [0, 1]$)

$$f(x, y) = (1 - y) \sin(\pi x) + y \sin^2(2\pi x)$$

discretized on a 30^2 Cartesian grid and stored in `2d000.vtk`

- Load the data into ParaView
- Display $f(x, y)$ in 2D
- Apply the WarpByScalar filter to display it in 3D

Mockup 3D continuous function

3D “sine envelope wave” function defined inside a unit cube ($x_i \in [0, 1]$)

$$f(x_1, x_2, x_3) = \sum_{i=1}^2 \left[\frac{\sin^2 \left(\sqrt{\xi_i^2 + \xi_{i+1}^2} \right) - 0.5}{[0.001(\xi_i^2 + \xi_{i+1}^2) + 1]^2} + 0.5 \right], \text{ where } \xi_i \equiv 30(x_i - 0.5)$$

discretized on a 100^3 Cartesian grid and stored in `sineEnvelope.nc`

1. Load the data into ParaView as “NetCDF generic”
2. Surface view
3. Clip filter
4. Slice filter
5. Contour filter at $f(x, y, z) = 0.3$ and 0.115 (we’ll use the former in the last section)
6. Volume view
7. On presenter’s laptop see *growth.mp4*

Creating animations in ParaView

Animation methods

1. Use ParaView's built-in animation of any property of any pipeline object

- ▶ easily create snazzy animations, somewhat limited in what you can do
- ▶ in Animation View: select object, select property, create a new track with "+", double-click the track to edit it, press "Forward"

2. Use ParaView's ability to recognize a sequence of similar files

- ▶ time animation only, very convenient
- ▶ try loading `data/2d*.vtk` sequence and animating it (visualize one frame and then press "Forward")

3. Script your animation in Python (not covered in this workshop)

- ▶ steep learning curve, very powerful, can do anything you can do in the GUI
- ▶ typical usage scenario: generate one frame per input file
- ▶ a simpler exercise without input files: see next slide

Animation methods

1. Use ParaView's built-in animation of any property of any pipeline object
 - ▶ easily create snazzy animations, somewhat limited in what you can do
 - ▶ in Animation View: select object, select property, create a new track with "+", double-click the track to edit it, press "Forward"
2. Use ParaView's ability to recognize a sequence of similar files
 - ▶ time animation only, very convenient
 - ▶ try loading `data/2d*.vtk` sequence and animating it (visualize one frame and then press "Forward")
3. Script your animation in Python (not covered in this workshop)
 - ▶ steep learning curve, very powerful, can do anything you can do in the GUI
 - ▶ typical usage scenario: generate one frame per input file
 - ▶ a simpler exercise without input files: see next slide

Animation methods

1. Use ParaView's built-in animation of any property of any pipeline object
 - ▶ easily create snazzy animations, somewhat limited in what you can do
 - ▶ in Animation View: select object, select property, create a new track with "+", double-click the track to edit it, press "Forward"
2. Use ParaView's ability to recognize a sequence of similar files
 - ▶ time animation only, very convenient
 - ▶ try loading `data/2d*.vtk` sequence and animating it (visualize one frame and then press "Forward")
3. Script your animation in Python (not covered in this workshop)
 - ▶ steep learning curve, very powerful, can do anything you can do in the GUI
 - ▶ typical usage scenario: generate one frame per input file
 - ▶ a simpler exercise without input files: see next slide

Exercise: animating function growth ▷▷

To visualize a single frame of the movie:

1. load `data/sineEnvelope.nc` (discretized on a 100^3 grid)
2. apply `Threshold` keeping only data from 1.2 to 2
3. apply `Clip`: origin $O = (49.5, 15, 49.5)$, normal $N = (0, -1, 0)$
4. colour by the right quantity

Two possible solutions:

1. bring up **Animation View** to animate `Clip`'s O_2 from 0 to 99, for best results save animation as a sequence of PNG files
2. not covered in this workshop) Start/Stop Trace to record the workflow, save the corresponding **Python script**, enclose parts of it into a loop changing O_2 from 0 to 99 and writing a series of PNG screenshots, run it inside ParaView to produce 100 frames

in either case, merge PNGs using a 3rd-party tool, e.g.

```
ffmpeg -r 30 -i frame%04d.png -c:v libx264 -pix_fmt yuv420p \
-vf "scale=trunc(iw/2)*2:trunc(ih/2)*2" movie.mp4
```

Camera animation in the GUI

Good introductory resource https://www.paraview.org/Wiki/Advanced_Animations

1. Start with any static visualization
2. Click on 'Adjust Camera' icon (one of the left-side icons on top of the visualization window)
 - ▶ adjust / write down Camera Focal Point
3. Bring up Animation View (or erase all previous timelines)

(3a) In Animation View:

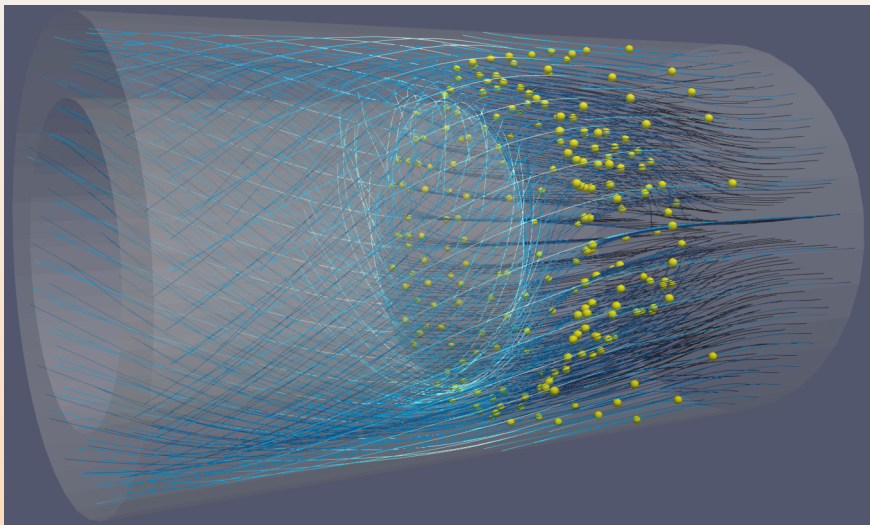
- select Camera - Orbit
- click "+" to create a new timeline
- set Center = Camera Focal Point, for the rest accept default settings
- adjust the number of frames

(3b) In Animation View:

- select Camera - Follow Path
- click “+” to create a new timeline
- double-click on the white timeline
- double-click on Path... in the right column
- click on Camera Position
 - ▶ a yellow path with spheres will appear
 - ▶ drag the spheres around
- also can change Camera Focus and Up Direction

4. Click "Forward"

Animating a stationary flow: time contours ▸



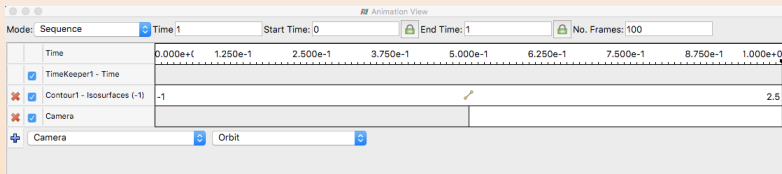
<https://vimeo.com/248509153> or *timeContours.mp4* on presenter's laptop

Animating a stationary flow: time contours ▷▷

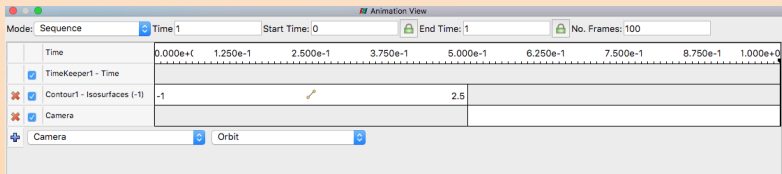
- Start with the streamtracer lines, however drawn
- Apply a Countour filter to the output of Streamtracer
 - ▶ contour by Integration Time
 - ▶ probe the range of values that works best
- Apply Glyph filter to the output of Countour
- Animation View: animate Contour - Isosurfaces
- This video was recorded with 2000 frames at 60 fps
 - ▶ such high resolution only for the final production video
 - ▶ debugging animation with 100 frames is perfectly Ok

Combining many timelines in one animation ▸

- Start with the previous integration-time-contour animation
- Add the second timeline to the animation: Camera - Orbit from $t = 0.5$ to $t = 1$ (while the first animation is still playing for its second half)

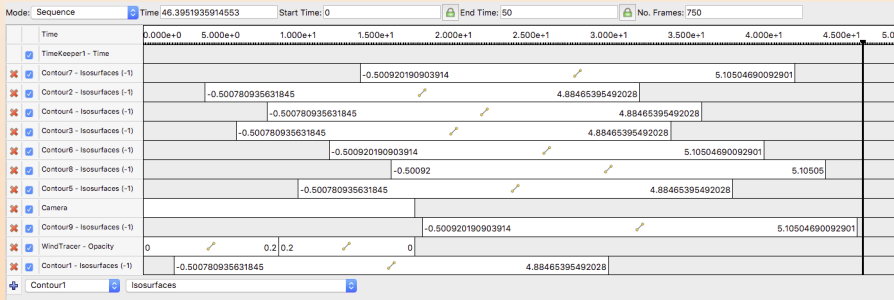


- Now complete integration-time-contour animation before rotation



Combining many timelines in one animation ▷▷

- In principle, can add as many timelines (with their individual time intervals and variables!) to the animation as you want
- Here is an example from WestGrid's 2017 *Visualize This* competition submission by Nadya Moisseeva (UBC) <https://scivis2021.netlify.app/2017>



- Here are couple more animation examples <https://ccvis.netlify.app/gallery/photorealistic-rendering>

Putting 3D visualizations on the web

- E.g. historical artifacts, digital prototypes, 3D buildings or terrains, point cloud (lidar) maps
- Would like a visitor to your page to be able to
 - ▶ rotate the object in 3D, zoom in/out
 - ▶ perhaps click on some predefined hotspots to launch additional actions

Example: Smithsonian 3D digitization

The Smithsonian museum has a collection of 3D textured models

<https://3d.si.edu>

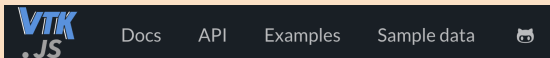
- Implemented their own Smithsonian X 3D Explorer viewer, a JavaScript/WebGL application talking to a proprietary server
- Navigate objects in 3D or 2.5D (six preset viewpoints) on low bandwidth
 - ▶ **setup toolbox** to compare different objects side-by-side in split mode
 - ▶ **material toolbox** to adjust colours, opacity, reflection, occlusion shadows, etc.
 - ▶ **lighting toolbox** to adjust the direction, colour and intensity of up to 3 light sources
 - ▶ **environment toolbox** to change background colours and the background grid
 - ▶ **tools toolbox** to measure and dissect models, plot various profiles along lines
- Also hosts Chandra X-ray Observatory 3D models
<https://3d.si.edu/collections/Chandra>
- Some models accompanied by an interactive guided tour
- Some models available for downloading
 - ▶ OBJ, STL (Stereo Lithography) - understood natively by ParaView
 - ▶ GLB = requires a plugin in ParaView
 - ▶ USDZ = open-source Universal Scene Description (with ZIP) from Apple/Pixar, can be read via ParaView Connector plugin

Recall VTK = Visualization Toolkit

- Software for 3D computer graphics, image processing, volume rendering, and scientific visualization
- In development since the early 1990s
- **Open-source, multi-platform**: Linux, Windows, Mac, the Web and mobile devices
- Core functionality written in **C++**, wrapped into other language bindings: Tcl, **Python**, Java
- Sits on top of a graphics library (typically OpenGL)
- Distributed-memory parallel processing via **MPI**
- Many-core and GPU architecture support via **VTK-m** (separate code base)

VTK.js

- Open-source JavaScript library for sci-vis on the web
 - ▶ not all VTK classes implemented
 - ▶ more complex applications: vtk.js ES6 code can be integrated into a web application in Node.js environment, typically requires a web server for local testing and for deployment
 - ▶ simpler usage: can be directly imported as a script tag inside live HTML pages from a global CDN (content delivery network) such as <https://unpkg.com>
- Uses WebGL (check your browser compatibility <https://get.webgl.org>)
 - ▶ WebGL2 for best performance <https://get.webgl.org/webgl2> (Chrome, Firefox)
- Variety of visualization algorithms
- Main resource <https://kitware.github.io/vtk-js>



- ▶ docs and tutorials assume JavaScript knowledge and familiarity with browser devtools
- ▶ check code examples under both API and Examples ⇒ can run simpler examples inside live HTML pages

Basic example: render a cone (glyphs.html)

Drop this file into your browser

```
<html>
<body>
  <script type="text/javascript" src="https://unpkg.com/vtk.js"></script>
  <script type="text/javascript">
    // create a basic cone object
    var cone = vtk.Filters.Sources.vtkConeSource.newInstance();
    cone.setRadius(0.3);
    cone.setResolution(50);
    var glyph = vtk.Filters.Sources.vtkSphereSource.newInstance();
    glyph.setRadius(0.015);
    glyph.setThetaResolution(30);
    glyph.setPhiResolution(30);
    // map polygonal data into renderable geometry
    var coneMapper = vtk.Rendering.Core.vtkMapper.newInstance();
    coneMapper.setInputConnection(cone.getOutputPort());
    var glyphMapper = vtk.Rendering.Core.vtkGlyph3DMapper.newInstance(); // special mapper with 2 connections
    glyphMapper.setInputConnection(cone.getOutputPort(), 0); // cone output goes to input port 0
    glyphMapper.setInputConnection(glyph.getOutputPort(), 1); // glyph output goes to input port 1
    // create an OpenGL object
    var coneActor = vtk.Rendering.Core.vtkActor.newInstance();
    coneActor.setMapper(coneMapper);
    coneActor.getProperty().setEdgeVisibility(true);
    var glyphActor = vtk.Rendering.Core.vtkActor.newInstance();
    glyphActor.setMapper(glyphMapper);
    // create a full-webpage renderer
    var fullScreenRenderer = vtk.Rendering.Misc.vtkFullScreenRenderWindow.newInstance();
    // from which you create a renderer itself
    var renderer = fullScreenRenderer.getRenderer();
    renderer.addActor(coneActor);  renderer.addActor(glyphActor);
    renderer.resetCamera();
    // and a render window
    var renderWindow = fullScreenRenderer.getRenderWindow();
    renderWindow.render();
  </script>
</body>
</html>
```

ParaView Glance

<https://kitware.github.io/paraview-glance>

PV Glance is an open-source **standalone** web app for **in-browser 3D sci-vis**

- very easy to use, ideal for sharing pre-built 3D scenes via the web
- no server \Rightarrow up to medium-size data (server support planned in future versions)
- interactive manipulation of pre-computed polygons
 - volumetric images, molecular structures, geometric objects, point clouds
- written in JavaScript and vtk.js + can be further customized with vtk.js and ParaViewWeb for custom web and desktop apps
- source and installation instructions

<https://github.com/kitware/paraview-glance>

-
1. Create a visualization with several layers, make **all layers visible in the pipeline**
 2. Many options in **File | Export Scene...** \Rightarrow save as VTKJS to your laptop
 3. Open <https://kitware.github.io/paraview-glance/app>
 4. Drag the newly saved file to the dropzone on the website
 5. Interact with individual layers in 3D: **rotate and zoom, change visibility, representation, variable, colourmap, opacity**

Automatically load a visualisation into Glance

<https://discourse.paraview.org/t/customise-pv-glance/2831>

- Use the query syntax `GLANCEAPPURL?name=FILENAME&url=FILEURL` to pass `name` and `url` to the web server
- E.g. using ParaView Glance website
`https://kitware.github.io/paraview-glance/app?name=sineEnvelope.vtkjs&url=https://raw.githubusercontent.com/razoumov/publish/master/data/sineEnvelope.vtkjs`
 ▶ shortened to `https://bit.ly/2KtPWNf`
- You can parse long strings with JavaScript (next slide)

Popular 3D model hubs

- <https://sketchfab.com> is probably the world's most popular commercial hub for 3D model hosting and sharing
 - ▶ free limited hosting
 - ▶ can upload polygonal data files
 - ▶ can publish directly to <https://sketchfab.com> from some applications and libraries, e.g. from <https://yt-project.org>
- USDZ sharing platform <https://usdzshare.com>

3DHOP = 3D Heritage Online Presenter

Caution: source code <https://github.com/cnr-isti-vclab/3DHOP> last updated in June 2020

- <http://3dhop.net> is an open-source package for presenting 3D high-resolution models online
 - ▶ from the **Visual Computing Lab** of the Istituto di Scienza e Tecnologie dell'Informazione, oriented toward the Cultural Heritage field
 - ▶ written in HTML and JavaScript
 - ▶ well-documented <http://3dhop.net/howto.php> + check their online demos!
- Can handle the following file formats:
 - (1) single-resolution PLY (polygon file format)
 - ▢ ParaView can export scenes in PLY format
 - alternatively can use the 3D unstructured triangular mesh editor MeshLab <http://meshlab.sourceforge.net> to convert other formats to PLY
 - per-vertex colour is supported, texture at the moment is not supported
 - vertex normals have to be included in the file
 - (2) NXS (batched multi-resolution mesh format) with $10^6 - 10^8$ triangles
 - Nexus package <http://vcg.isti.cnr.it/nexus> (developed in the same lab) can convert to NXS
 - Nexus uses 3DHOP for visualization on the web
 - (3) point clouds with $10^6 - 10^8$ points

Import 3D polygon file into 3DHOP ▸

- (1) In your local ParaView build a “sine envelope” isosurface at $f(x, y, z) = 0.3$
- (2) **File | Save Data** as PLY into `sineEnvelope.ply`, making sure to check **Enable Coloring** and **Enable Alpha**

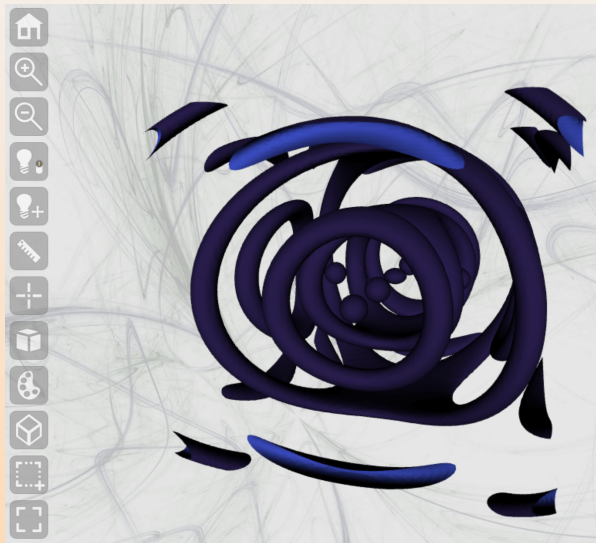
- Serve it locally or remotely with 3DHOP:

```
git clone https://github.com/cnr-isti-vclab/3DHOP.git 3dhop-src
cd 3dhop-src/minimal
mkdir -p models/singleres/
cp /path/to/your/download/sineEnvelope.ply models/singleres/
cp 3DHOP_all_tools.html index.html # page with all tools in a sidebar
sed -i "" -e "s|models/gargo.nxz|models/singleres/sineEnvelope.ply|" index.html
sudo python -m http.server 80 # Python 3
```

- **local demo:** point your web browser at `http://localhost`

- You can also find `3dhop/index.html` inside the ZIP download

Import 3D polygon file into 3DHOP >>



Creating interactive hotspots in a 3DHOP scene ▸

- I created a couple of hotspot meshes `ring.ply` and `top.ply`
 - ▶ loaded the original model into ParaView
 - ▶ twice applied Clip filter (result: Unstructured Grid), followed by Extract Edges (result: Polygonal Mesh)
 - ▶ for both **File | Save Data** as PLY into `top.ply` and `ring.ply`, making sure to check Enable Coloring and Enable Alpha
- Using `index.html` as template, I created a new file `hotSpots.html` in which we
 - (1) defined `mesh1`, `mesh2`, `mesh3`,
 - (2) set up `ringSpot` and `topSpot` objects,
 - (3) defined “Hide Hotspots” and “Show Hotspots” buttons and added them to function `actionsToolbar()`,
 - (4) defined actions in function `onPickedSpot()`
- You can see the changes with

```
diff index.html hotSpots.html
```

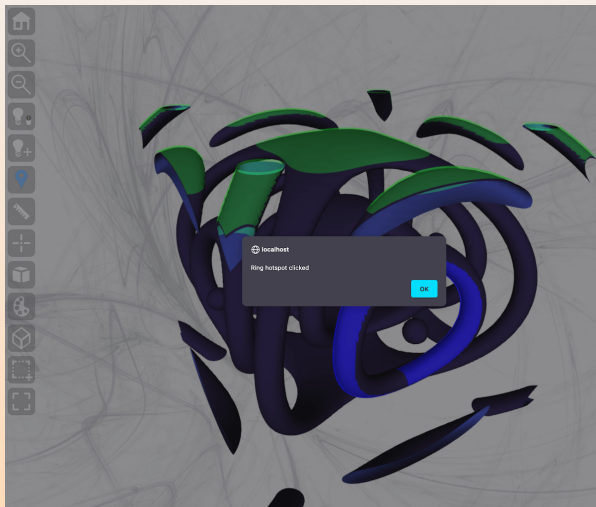
Creating interactive hotspots in a 3DHOP scene ▷▷

- Copy the hotspot meshes and a modified html into the corresponding directories and serve it locally or remotely with 3DHOP:

```
cd /path/to/3dhop-src/minimal
cp /path/to/your/download/{ring,top}.ply models/singleres
cp /path/to/your/download/3dhop/hotSpots.html .
sudo python -m http.server 80 # Python 3
```

- ▶ **local demo:** point your web browser at `http://localhost/hotSpots.html`
 - ▶ now there is a button “Show/Hide Hotspots”
 - ▶ clicking on the top hotspot opens DHSI homepage in a new window
 - ▶ clicking on the ring hotspot opens an alert window
- You can find `3dhop/hotSpots.html` inside the ZIP download

Creating interactive hotspots in a 3DHOP scene ▶▶▶



- Today we concentrated heavily on VTK and general-purpose scientific visualization tools
 - ▶ 3D multi-attribute scatter plots
 - ▶ 3D graphs
 - ▶ continuous distributions
 - ▶ animations
 - ▶ putting 3D visualizations on the web

Questions?

- Email me at alex.razoumov@westdri.ca
- Submit a problem ticket at support@tech.alliancecan.ca
- Our visualization showcase and support <https://ccvis.netlify.app>
- Alliance | Western Canada visualization resources <http://bit.ly/vispages>