# Machine Learning for Networks: Regression (continued) and Classification 

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Regression (continued)

- Polynomial Regression
- Variance vs. Bias Trade-Off
- Regularization
- Scaling
- Feature Selection

Classification

- Logistic Regression
. Classification Performance
- Class imbalance


## Section 1

## Polynomial Regression and hyper-parameter tuning

## Univariate Polynomial Regressions

- A univariate polynomial regression of degree $p$ is

$$
h_{\theta}(x)=\theta_{0}+\theta_{1} \cdot x+\theta_{2} \cdot x^{2}+\ldots \theta_{p} \cdot x^{p}
$$

- $p=1$ : linear
$p=2$ : quadratic
$p=3$ : cubic
- Equivalent to linear regression with features

$$
x, x^{2}, \ldots, x^{p}
$$

- $p$ is a hyper-parameter: parameter of the learning algorithm.
- How to choose $p$ ?


## Multi-variate polynomial regression

- With $j=1 \ldots N$ features, all terms of degree 2 are included:

$$
\begin{aligned}
h_{\theta}(\mathbf{x}) & =\theta_{0}+\theta_{1} \cdot x_{1}+\cdots+\theta_{N} \cdot x_{N} \\
& +\theta_{N+1} \cdot x_{1}^{2}+\cdots+\theta_{N+N} \cdot x_{N}^{2} \\
& +\theta_{1,2} \cdot x_{1} x_{2}+\theta_{1,3} \cdot x_{1} x_{3}+\cdots+\theta_{1, N} \cdot x_{1} x_{N} \\
& +\theta_{2,3} \cdot x_{2} x_{3}+\theta_{2,4} \cdot x_{2} x_{4}+\ldots
\end{aligned}
$$

- A pol. regression of degree $p$ includes the following terms:
- Bias term

$$
\theta_{0}
$$

- Powers of features

$$
x_{j}^{k} \quad k=1, \ldots, p
$$

- Mixed terms of power 2:

$$
x_{j} \cdot x_{j^{\prime}} \quad j^{\prime}>j
$$

- Mixed terms of power 3

$$
x_{j} \cdot x_{j^{\prime}} \cdot x_{j^{\prime \prime}} \quad j^{\prime \prime}>j^{\prime}>j
$$

- Mixed terms of power $p$


## Hyper-parameter tuning

| BufferHealth | BufferProgress | BufferValid | label | label_num |
| :---: | :---: | :---: | :---: | :---: |
| 10.241165 | 0.015357 | true | q360p | 360 |
| 4.446780 | 0.007103 | true | q144p | 144 |
| 3.989780 | 0.006509 | true | q144p | 144 |
| 3.700462 | 0.005897 | true | q360p | 360 |
| 4.512780 | 0.007156 | true | q360p | 360 |
| 9.454706 | 0.016805 | true | q360p | 360 |
| 4.606780 | 0.008046 | true | q144p | 144 |
| 5.301853 | 0.007990 | true | q720p | 720 |
| 3.638107 | 0.005493 | true | q240p | 240 |
| 5.314732 | 0.009400 | true | q240p | 240 |
| 8.554780 | 0.011688 | true | q480p | 480 |
| 4.189780 | 0.007516 | true | q360p | 360 |
| 3.633641 | 0.005897 | true | q480p | 480 |
| 1.495841 | 0.002473 | true | q720p | 720 |
| 8.802211 | 0.014076 | true | q1080p | 1080 |
| 4.611142 | 0.009263 | true | q144p | 144 |
| 5.590378 | 0.009113 | true | q480p | 480 |
| 4.940168 | 0.008851 | true | q1080p | 1080 |
| 4.940168 | 0.008851 | true | q1080p | 1080 |
| 9.239532 | 0.016335 | true | q720p | 720 |

## Hyper-parameter tuning

| Buttertealth | ButterProgress | Butiervalid label | label_num |  |
| :---: | :---: | :---: | :---: | :---: |
| 10.241165 | 0.015357 | true a360p | 360 |  |
| 4.446780 | 0.007103 | true q144p | 144 |  |
| 3.989780 | 0.006509 | true al44p | 144 |  |
| 3.700462 | 0.005897 | true a360p | 360 |  |
| 4.512780 | 0.007156 | true a360p | 360 |  |
| 9.454706 | 0.016805 | true a360p | 360 |  |
| 4.606780 | 0.008046 | true al44p | 144 |  |
| 5.301853 | 0.007990 | true atzop | 720 | TRAINING |
| 3.638107 | 0.005493 | true q240p | 240 | $\}$ SET |
| 5.314732 | 0.009400 | true $\mathrm{q}^{240 \mathrm{p}}$ | 240 |  |
| 8.554780 | 0.011688 | true $\mathrm{a}^{4880}$ | 480 |  |
| 4.889780 | 0.007516 | tree a360p | 360 |  |
| 3.633641 | 0.005897 | tree a480p | 480 |  |
| 1.495841 | ${ }^{0.002473}$ | true a720p | 720 |  |
| 8.802211 | 0.014076 | true q9080p | 1080 |  |
| 4.611142 | ${ }^{0.009263}$ | tree $\mathrm{q}^{144 \mathrm{p}}$ | 144 |  |
| 5.590378 | 0.009113 | true a480p | 480 |  |
| 4.940168 | 0.008851 | true $\mathrm{q}^{10800}$ | 1080 |  |
| 4.940168 | 0.008851 | true q1080p | 1080 | TEST |
| 9.239532 | 0.016335 | true a720p | ${ }_{720}$ |  |

- Divide training and test sets


## Hyper-parameter tuning

| Butertealth | Butererrogress | Buttervalid label | label_num | TRAINING SET <br> TEST SET |
| :---: | :---: | :---: | :---: | :---: |
| 10.241165 | 0.015357 | true a360p | 360 |  |
| 4.446780 | 0.007103 | true q144p | 144 |  |
| 3.989780 | 0.006509 | true al44p | 144 |  |
| 3.70462 | 0.005897 | true a360p | 360 |  |
| 4.512780 | 0.007156 | true a360p | 360 |  |
| 9.454706 | 0.016805 | true a360p | 360 |  |
| 4.606780 | 0.008046 | true al44p | 144 |  |
| 5.301853 | 0.007990 | true a720p | 720 |  |
| 3.638107 | 0.005493 | true a420p | 240 |  |
| 5.144732 | 0.009400 | true q240p | 240 |  |
| 8.554780 | 0.011688 | true 9480 p | 480 |  |
| 4.189780 | 0.007516 | tree a360p | 360 |  |
| 3.633641 | 0.005897 | true a480p | 480 |  |
| 1.495841 | 0.002473 | true a720p | 720 |  |
| 8.802211 | 0.014076 | true q1080p | 1080 |  |
| 4.611142 | 0.009263 | true q144p | 144 |  |
| 5.500378 | 0.009113 |  | 480 |  |
| 4.940100 | $\underbrace{0.008851}$ | Uue almee | 1080 |  |
| 4.940168 | 0en | 1080 p | 1080 |  |

- Divide training and test sets
- Use only training set


## Hyper-parameter tuning



- Divide training and test sets
- Use only training set
- For all the hyper-parameter values
- Construct a model with such values
- Compute cross-validation error


## Hyper-parameter tuning



- Divide training and test sets
- Use only training set
- For all the hyper-parameter values
- Construct a model with such values
- Compute cross-validation error
- Select the model with the smallest cross-validation error


## Hyper-parameter tuning

| BufferHealth | BufferProgress | BufferValid | label | label_num |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 10.241165 | 0.015357 | true | q360p | 360 |  |
| 4.446780 | 0.007103 | true | q144p | 144 |  |
| 3.989780 | 0.006509 | true | q144p | 144 |  |
| 3.700462 | 0.005897 | true | q360p | 360 |  |
| 4.512780 | 0.007156 | true | q360p | 360 |  |
| 9.454706 | 0.016805 | true | q360p | 360 |  |
| 4.606780 | 0.008046 | true | q144p | 144 |  |
| 5.301853 | 0.007990 | true | q720p | 720 | TRAINING |
| 3.638107 | 0.005493 | true | q240p | 240 | SET |
| 5.314732 | 0.009400 | true | q240p | 240 |  |
| 8.554780 | 0.011688 | true | q480p | 480 |  |
| 4.189780 | 0.007516 | true | q360p | 360 |  |
| 3.633641 | 0.005897 | true | q480p | 480 |  |
| 1.495841 | 0.002473 | true | q720p | 720 |  |
| 8.802211 | 0.014076 | true | q1080p | 1080 |  |
| 4.611142 | 0.009263 | true | q144p | 144 |  |
| 5.590378 | 0.009113 | true | q480p | 480 |  |
| 4.940168 | 0.008851 | true | q1080p | 1080 |  |
| 4.940168 | 0.008851 | true | q1080p | 1080 | TEST |
| 9.239532 | 0.016335 | true | q720p | 720 | SEI |

- Divide training and test sets
- Use only training set
- For all the hyper-parameter values
- Construct a model with such values
- Compute cross-validation error
- Select the model with the smallest cross-validation error
- Train the selected model on the training set
- Test error on the test set


## Hyper-parameter tuning

|  |  | labe |  |  |
| :---: | :---: | :---: | :---: | :---: |
| 10.241165 | 0.015357 | ssop | 350 |  |
| 4446780 | 0.07703 | tve al4ap | 144 |  |
| ${ }^{3.899780}$ | 0.006509 | tree ${ }^{1 / 44 \mathrm{p}}$ | ${ }^{144}$ |  |
| 3.700462 | 0.005897 | tue asbop | 350 |  |
| 4512780 | 0.007156 | tue assop | 380 |  |
| 9.447706 | 0.006805 | tue a 9360 | 330 |  |
| 4.608780 | ${ }^{0.008046}$ | tue altap |  |  |
| ${ }_{5}$ 5301839 | 0.00790 | ar2op | 720 | TRAINING |
| 3.688107 | 0.005493 | ${ }^{2240}$ | 240 |  |
| 5314732 | 0.00930 | tve q2400 | 240 |  |
| 8.554780 | 0.011688 | tue at800 | 480 |  |
| 4.189780 | 0.007516 | a300 | ${ }^{360}$ |  |
| 23841 | 0.005897 | tue at800 | 480 |  |
| 1.495841 | 0.00273 | tue arope | 720 |  |
| ${ }^{8.802211}$ | 0.014476 | tue quoso | 1080 |  |
| 4.611142 | 0.00923 | tue alisp | 144 |  |
| 5.590378 | 0.009113 | at800 | 480 |  |
| 4.490168 | 0.008851 | Ive qutiosp | 1080 |  |
| 4940168 | 0.008851 | tre alosop | 1080 | TEST |
| 9239532 | 0.016355 | tue arzop | 720 |  |

- Divide training and test sets
- Use only training set
- For all the hyper-parameter values
- Construct a model with such values
- Compute cross-validation error
- Select the model with the smallest cross-validation error
- Train the selected model on the training set
- Test error on the test set

We have only used the training set to select the best parameter

## Let's code ...



Go to notebook
03.regression_contd-and-classification/a.polynomial-regression.ipynb

## Complexity and Variance

More complexity, More model variance


Example of polynomial regression with degree 1 (linear), and then higher degrees Image from [AWS].

## Complexity and Variance

Higher $p \Longrightarrow$ higher complexity $\Longrightarrow$ higher variance (the model adapts too flexibly to the training data)


## Bias-Variance trade-off

$$
8 \text { / } 42
$$

If you reduce bias (on the training set) you increase the variance. And vice-versa. This is a fundamental limit of Machine Learning [KW96].


## Section 2

## Regularization

## Regularization

- Force the model to be simple.

Cost function:

$$
J(\boldsymbol{\theta}, \mathbf{X}, \hat{\mathbf{y}})=\frac{1}{M} \sum_{i=1}^{M}\left(y^{(i)}-h_{\theta}\left(\mathbf{x}^{(i)}\right)\right)^{2}+\underbrace{+\alpha \sum_{j=1}^{N} \theta_{j}^{2}}_{\text {regularization term }}
$$

- Parameters forced to be small $\Longrightarrow$ less overfit
- Bias term $\theta_{0}$ not regularized. Why?
- Force the model to be simple.

Cost function:

$$
J(\boldsymbol{\theta}, \mathbf{X}, \hat{\mathbf{y}})=\frac{1}{M} \sum_{i=1}^{M}\left(y^{(i)}-h_{\boldsymbol{\theta}}\left(\mathbf{x}^{(i)}\right)\right)^{2} \underbrace{+\alpha \sum_{j=1}^{N} \theta_{j}^{2}}_{\text {regularization term }}
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- Parameters forced to be small $\Longrightarrow$ less overfit
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- It is just an offset. It does not add complexity.


## Regularization

- Force the model to be simple.

Cost function:

$$
J(\boldsymbol{\theta}, \mathbf{X}, \hat{\mathbf{y}})=\frac{1}{M} \sum_{i=1}^{M}\left(y^{(i)}-h_{\boldsymbol{\theta}}\left(\mathbf{x}^{(i)}\right)\right)^{2} \underbrace{+\alpha \sum_{j=1}^{N} \theta_{j}^{2}}_{\text {regularization term }}
$$

- Parameters forced to be small $\Longrightarrow$ less overfit
- Bias term $\theta_{0}$ not regularized. Why?
- It is just an offset. It does not add complexity.
- Should regularization term considered when evaluating test error?

$$
\begin{gathered}
J_{\text {train }}=\frac{1}{\left|\mathscr{D}^{\text {train }}\right|} \sum_{i \in \mathscr{D}^{\text {train }}}\left(y^{(i)}-h_{\theta}\left(\mathbf{x}^{(i)}\right)\right)^{2} \underbrace{+\alpha \sum_{j=1}^{N} \theta_{j}^{2}}_{\text {regularization term }} \\
J_{\text {test }}=\frac{1}{\left|\mathscr{D}^{\text {test }}\right|} \sum_{i \in \mathscr{D}^{\text {test }}}\left(y^{(i)}-h_{\theta}\left(\mathbf{x}^{(i)}\right)\right)^{2}
\end{gathered}
$$

## Effects of $\alpha$

$$
J_{\text {train }}=\frac{1}{\left|\mathscr{D}^{\text {train }}\right|} \sum_{i \in \mathscr{D}^{\text {train }}}\left(y^{(i)}-h_{\theta}\left(\mathbf{x}^{(i)}\right)\right)^{2}+\underbrace{+\alpha \sum_{j=1}^{N} \theta_{j}^{2}}_{\text {regularization term }}
$$

- What if $\alpha \rightarrow 0$ ? Linear regression
- And if $\alpha \rightarrow+\infty$ ?



## Effects of $\alpha$

$$
J_{\text {train }}=\frac{1}{\left|\mathscr{D}^{\text {train }}\right|} \sum_{i \in \mathscr{D}^{\text {train }}}\left(y^{(i)}-h_{\theta}\left(\mathbf{x}^{(i)}\right)\right)^{2}+\underbrace{+\alpha \sum_{j=1}^{N} \theta_{j}^{2}}_{\text {regularization term }}
$$



- What if $\alpha \rightarrow 0$ ?

Linear regression

- And if $\alpha \rightarrow+\infty$ ?

$$
\text { Only } \theta_{0}
$$

- Suppose
- you try different $\alpha$ and
- the best error is with $\alpha \rightarrow+\infty$.

What do you conclude?
In this case, the best model is the simple average of $y$.

Let's code ...
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## Section 3

## Scaling

## Regularization and scaling

Features may have different magnitudes


- Regularization squashes blindly all features uniformly.
- "Small" features would need instead larger
- Need to scale features before applying regularization.

$$
J(\boldsymbol{\theta}, \mathbf{X}, \mathbf{y})=\frac{1}{M} \sum_{i=1}^{M}\left(y^{(i)}-h_{\boldsymbol{\theta}}\left(\mathbf{x}^{(i)}\right)\right)^{2} \underbrace{+\alpha \sum_{j=1}^{N} \theta_{j}^{2}}_{\text {regularization term }}
$$

$$
\boldsymbol{\theta}^{*}=\arg \min _{\theta} J(\boldsymbol{\theta}, \mathbf{X}, \mathbf{y})
$$

## Standard scaler

- If $\mu_{j}$ is avg of $j$-feature and $\sigma_{j}$ the stdev:

Standard Scaler

$$
x_{j}^{(i)^{\prime}}=\frac{x_{j}^{(i)}-\mu_{j}}{\sigma_{j}}
$$

Which is the correct way of applying scaling?
vs.

- Divide

$$
(\mathbf{X}, \mathbf{y}) \rightarrow\left(\mathbf{X}_{\text {train }}, \mathbf{y}_{\text {train }}\right),\left(\mathbf{X}_{\text {test }}, \mathbf{y}_{\text {test }}\right)
$$

- $\mathbf{X}_{\text {train }}{ }^{\prime}=\operatorname{scale}\left(\mathbf{X}_{\text {train }}\right)$
- $\mathbf{X}_{\text {test }}{ }^{\prime}=\operatorname{scale}\left(\mathbf{X}_{\text {test }}\right)$
- Train the model using ( $\left.\mathbf{X}_{\text {train }}{ }^{\prime}, \mathbf{y}_{\text {train }}\right)$
- Test using $\left(\mathbf{X}_{\text {test }}{ }^{\prime}, \mathbf{y}_{\text {test }}\right)$ using $\mu_{j}, \sigma_{j}, \min _{j}$, max $_{j}$ found in training
- $\mathbf{X}^{\prime}=\operatorname{scale}(\mathbf{X})$
- Divide $\left(\mathbf{X}^{\prime}, \mathbf{y}\right) \rightarrow\left(\mathbf{X}_{\text {train }}{ }^{\prime}, \mathbf{y}_{\text {train }}\right),\left(\mathbf{X}_{\text {test }}{ }^{\prime}, \mathbf{y}_{\text {test }}\right)$
- Train the model using $\left(\mathbf{X}_{\text {train }}{ }^{\prime}, \mathbf{y}_{\text {train }}\right)$
- Test using ( $\left.\mathbf{X}_{\text {test }}, \mathbf{y}_{\text {test }}\right)$


## Standard scaler

- If $\mu_{j}$ is avg of $j$-feature and $\sigma_{j}$ the stdev:

Standard Scaler

$$
x_{j}^{(i)^{\prime}}=\frac{x_{j}^{(i)}-\mu_{j}}{\sigma_{j}}
$$

Which is the correct way of applying scaling?
vs.

- Divide

$$
(\mathbf{X}, \mathbf{y}) \rightarrow\left(\mathbf{X}_{\text {train }}, \mathbf{y}_{\text {train }}\right),\left(\mathbf{X}_{\text {test }}, \mathbf{y}_{\text {test }}\right)
$$

- $\mathbf{X}_{\text {train }}{ }^{\prime}=\operatorname{scale}\left(\mathbf{X}_{\text {train }}\right)$
- $\mathbf{X}_{\text {test }}{ }^{\prime}=\operatorname{scale}\left(\mathbf{X}_{\text {test }}\right)$
- Train the model using ( $\left.\mathbf{X}_{\text {train }}{ }^{\prime}, \mathbf{y}_{\text {train }}\right)$
- Test using $\left(\mathbf{X}_{\text {test }}{ }^{\prime}, \mathbf{y}_{\text {test }}\right)$ using $\mu_{j}, \sigma_{j}, \min _{j}, \max _{j}$ found in training


## Data Leakage (Ch. 8 of [Teo19])

In the 2 nd case we would calculate $\mu_{j}, \sigma_{j}, \min _{j}, \max _{j}$ using data from test cot

## Effect of scaling



## When is scaling important

Is scaling important in a linear regression?

## When is scaling important

Is scaling important in a linear regression?

- It does not affect the accuracy of the model
- Because coefficients can scale based on the feature magnitude.
- But it's good for interpretability, when features are standardized
- Since we impose the stddev of all features to be 1 , the value of the coefficient is an indication of feature importance
- (how much a variation of a feature impacts the target)

Is scaling important in a polynomial regression?

## Section 4

## Feature selection

## Feature selection

- We have already seen some methods:
- Check the Pearson's correlation
- Run a lin.regr. on the scaled dataset and check the magnitude of the coefficients.
- See if a model improves/deteriorates when removing a feature
- Another method: Recursive Feature Elimination (RFE)
- Standardize your features
- Train your model with all features
- Remove the feature with the smallest coeff
- Train the model again
- Remove the feature with the smallest coeff
- ...
- Repeat until you are left with $N$ features.
- Why do we need to standardize the features?

Otherwise the coefficient weights are not an indication of feature importance.

- RFE + Cross Validation (RFECV)
- Repeat the process for different $N$ and select the $N$ providing the smallest cross-validation error.


## Let's code ...

Go to notebook 03.regression_contd-and-classification/b.regularization

## Section 5

## Classification: Logistic Regression

## Classification

Supervised ML task where the labels are in a finite set.

- Ex.: Classify video resolution based on network information Labels are 144p, 360p, etc.


## Binomial Logistic Regression

- Classes $k=0$ (negative) and 1 (positive).
- We do not predict directly the class $k$ of sample $\mathbf{x}$
- We instead predict probabilities
- The predicted probability of being positive is

$$
\begin{aligned}
\hat{p}_{1}^{(i)} & =\mathbb{P}\left[\mathbf{x}^{(i)} \text { is of class 1 }\right] \\
& =h_{\boldsymbol{\Theta}}\left(\mathbf{x}^{(i)}\right)=\sigma\left(\boldsymbol{\theta}^{T} \cdot \mathbf{x}^{(i)}\right)
\end{aligned}
$$

- The predicted probability of being negative is

$$
\hat{p}_{0}^{(i)}=1-\hat{p}_{1}^{(i)}
$$

- If $y^{(i)}$ is the true class of sample $\mathbf{x}^{(i)}$, the predicted probability of being of the true class is

$$
\hat{p}_{y^{(i)}}^{(i)}
$$

- Sigmoid $\sigma(t)=\frac{1}{1+e^{-t}}$


Picture from [Gér17]

- The predicted label is:

$$
\hat{y}^{(i)}= \begin{cases}1 & \text { if } \hat{p}_{1}^{(i)} \geq 0.5 \\ 0 & \text { if } \hat{p}_{1}^{(i)}<0.5\end{cases}
$$

## Neural Network

Logistic regression is a NN with one neuron


## Log-Loss function



## Picture from stackexchange

- For any sample $\left(\mathbf{x}^{(i)}, y^{(i)}\right)$ :

$$
\begin{aligned}
J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right) & \triangleq-\ln \left(\hat{p}_{y^{(i)}}^{(i)}\right)= \begin{cases}-\ln \left(\hat{p}_{1}^{(i)}\right) & \text { if } y^{(i)}=1 \\
-\ln \left(\hat{p}_{0}^{(i)}\right) & \text { if } y^{(i)}=0\end{cases} \\
& = \begin{cases}-\ln \left(\sigma\left(\boldsymbol{\theta}^{T} \cdot \mathbf{x}^{(i)}\right)\right) & \text { if } y^{(i)}=1 \\
-\ln \left(1-\sigma\left(\boldsymbol{\theta}^{T} \cdot \mathbf{x}^{(i)}\right)\right) & \text { if } y^{(i)}=0\end{cases}
\end{aligned}
$$

- For the entire dataset $(\mathbf{X}, \mathbf{y})$ :

$$
\begin{equation*}
J(\boldsymbol{\theta}, \mathbf{X}, \mathbf{y}) \triangleq \frac{1}{M} \sum_{i=1}^{M} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right) \tag{1}
\end{equation*}
$$

## Log-Loss function



## Picture from stackexchange

- For any sample $\left(\mathbf{x}^{(i)}, y^{(i)}\right)$ :

$$
\begin{aligned}
J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right) & \triangleq-\ln \left(\hat{p}_{y^{(i)}}^{(i)}\right)= \begin{cases}-\ln \left(\hat{p}_{1}^{(i)}\right) & \text { if } y^{(i)}=1 \\
-\ln \left(\hat{p}_{0}^{(i)}\right) & \text { if } y^{(i)}=0\end{cases} \\
& = \begin{cases}-\ln \left(\sigma\left(\theta^{T} \cdot \mathbf{x}^{(i)}\right)\right) & \text { if } y^{(i)}=1 \\
-\ln \left(1-\sigma\left(\theta^{T} \cdot \mathbf{x}^{(i)}\right)\right) & \text { if } y^{(i)}=0\end{cases}
\end{aligned}
$$



- How can we find:

$$
\theta^{*}=\arg \min _{\theta} J(\boldsymbol{\theta}, \mathbf{X}, \mathbf{y}) ?
$$

- For any $\left(\mathbf{x}^{(i)}, y^{(i)}\right)$, the loss function is derivable and convex:

$$
\begin{aligned}
& \nabla J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right) \\
& = \begin{cases}\nabla\left[-\ln \left(\sigma\left(\boldsymbol{\theta}^{T} \cdot \mathbf{x}^{(i)}\right)\right)\right] & \text { if } y^{(i)}=1 \\
\nabla\left[-\ln \left(1-\sigma\left(\boldsymbol{\theta}^{T} \cdot \mathbf{x}^{(i)}\right)\right)\right] & \text { if } y^{(i)}=0\end{cases}
\end{aligned}
$$

- For the entire dataset $(\mathbf{X}, \mathbf{y})$ :

$$
\begin{equation*}
J(\boldsymbol{\theta}, \mathbf{X}, \mathbf{y}) \triangleq \frac{1}{M} \sum_{i=1}^{M} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right) \tag{1}
\end{equation*}
$$

## Gradient Descent

- At each iteration

$$
\theta:=\theta-\eta \cdot \nabla_{\theta} J(\theta, \mathbf{X}, \mathbf{y})
$$

where (see (1))

$$
\nabla_{\theta} J(\boldsymbol{\theta}, \mathbf{X}, \mathbf{y})=\frac{1}{M} \sum_{i=1}^{M} \nabla_{\theta} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right)=\frac{1}{M} \sum_{i=1}^{M}\left[\begin{array}{c}
\frac{\partial}{\partial \theta_{0}} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right) \\
\vdots \frac{\partial}{\partial \theta_{N}} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right)
\end{array}\right]
$$

- For any sample $i$ we can compute that ${ }^{1}$ (No need to learn it by heart):

$$
\frac{\partial}{\partial \theta_{j}} J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right)=(\underbrace{\underbrace{\sigma\left(\theta^{T} \cdot \mathbf{x}^{(i)}\right)}-y^{(i)}}) \cdot x_{j}^{(i)}
$$

## Gradient Descent

- At each iteration

$$
\theta:=\theta-\eta \cdot \nabla_{\theta} J(\theta, \mathbf{X}, \mathbf{y})
$$

where (see (1))

$$
\nabla_{\theta} J(\theta, \mathbf{X}, \mathbf{y})=\frac{1}{M} \sum_{i=1}^{M} \nabla_{\theta} J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right)=\frac{1}{M} \sum_{i=1}^{M}\left[\begin{array}{c}
\frac{\partial}{\partial \theta_{0}} J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right) \\
\vdots \frac{\partial}{\partial \theta_{N}} J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right)
\end{array}\right]
$$

- For any sample $i$ we can compute that ${ }^{1}$ (No need to learn it by heart):

$$
\frac{\partial}{\partial \theta_{j}} J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right)=(\underbrace{\underbrace{\sigma\left(\boldsymbol{\theta}^{T} \cdot \mathbf{x}^{(i)}\right)}-y^{(i)}}_{\hat{p}^{(i)}}) \cdot x_{j}^{(i)}
$$

## Gradient Descent

- At each iteration

$$
\theta:=\theta-\eta \cdot \nabla_{\theta} J(\theta, \mathbf{X}, \mathbf{y})
$$

where (see (1))

$$
\nabla_{\theta} J(\boldsymbol{\theta}, \mathbf{X}, \mathbf{y})=\frac{1}{M} \sum_{i=1}^{M} \nabla_{\theta} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right)=\frac{1}{M} \sum_{i=1}^{M}\left[\begin{array}{c}
\frac{\partial}{\partial \theta_{0}} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right) \\
\vdots \frac{\partial}{\partial \theta_{N}} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right)
\end{array}\right]
$$

- For any sample $i$ we can compute that ${ }^{1}$ (No need to learn it by heart):

$$
\frac{\partial}{\partial \theta_{j}} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right)=(\underbrace{\underbrace{\sigma\left(\boldsymbol{\theta}^{T} \cdot \mathbf{x}^{(i)}\right)}_{\hat{p}^{(i)}}-y^{(i)}}_{-\boldsymbol{\varepsilon}^{(i)}}) \cdot x_{j}^{(i)}
$$

## Gradient Descent

- At each iteration

$$
\theta:=\theta-\eta \cdot \nabla_{\theta} J(\theta, \mathbf{X}, \mathbf{y})
$$

where (see (1))

$$
\nabla_{\theta} J(\boldsymbol{\theta}, \mathbf{X}, \mathbf{y})=\frac{1}{M} \sum_{i=1}^{M} \nabla_{\theta} J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right)=\frac{1}{M} \sum_{i=1}^{M}\left[\begin{array}{c}
\frac{\partial}{\partial \theta_{0}} J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right) \\
\vdots \frac{\partial}{\partial \theta_{N}} J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right)
\end{array}\right]
$$

- For any sample $i$ we can compute that ${ }^{1}$ (No need to learn it by heart):

$$
\frac{\partial}{\partial \theta_{j}} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right)=(\underbrace{\underbrace{\sigma\left(\theta^{T} \cdot \mathbf{x}^{(i)}\right)}_{\hat{p}^{(i)}}-y^{(i)}}_{-\varepsilon^{(i)}}) \cdot x_{j}^{(i)}
$$

- Therefore

$$
\nabla_{\theta} J\left(\theta, \mathbf{x}^{(i)}, y^{(i)}\right)=-\varepsilon^{(i)} \cdot \mathbf{x}^{(i)}
$$

## Gradient Descent

At each iteration

$$
\theta:=\theta-\eta \cdot \nabla_{\theta} J(\theta, \mathbf{X}, \mathbf{y})
$$



## Training with Gradient Descent

1. Full Gradient Descent:

- Initialize a random $\theta$
- Compute $h_{\theta}\left(\mathbf{x}^{(i)}\right)$ for all $\left(\mathbf{x}^{(i)}, y^{(i)}\right) \in \mathscr{D}^{\text {train }}$
- Compute the residuals

$$
\varepsilon^{(i)}=h_{\boldsymbol{\theta}}(\mathbf{x})-y^{(i)}
$$

- Apply the update:

$$
\theta:=\theta-\eta \cdot \underbrace{\frac{1}{M} \sum_{i=1}^{M} \varepsilon^{(i)} \cdot \mathbf{x}^{(i)}}_{\nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}, \mathbf{x}, \mathbf{y})}
$$

- Repeat several epochs.

The more the error on a $\mathbf{x}^{(i)}$, the more its contribution to the update.
Problem: what happens if $\mathscr{D}^{\text {train }}$ is huge?
2. Stochastic gradient descent

- Randomly select one sample $\left(\mathbf{x}^{(i)}, y^{(i)}\right)$
- Directly update

$$
\theta:=\theta-\eta \cdot \underbrace{\varepsilon^{(i)} \cdot \mathbf{x}^{(i)} \nabla}_{\nabla_{\boldsymbol{\theta}} J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right)}
$$

- Why stochastic: we apply a quantity which on expectation is equal to the actual gradient

3. Batch gradient descent

- Partition $\mathscr{D}^{\text {train }}$ into batches
- For each batch
- Predict all the data


## Logistic Regression is a linear classifier

Decision boundary: Surface of $\mathbb{R}^{N+1}$ that divides the region in which the classifier predicts 1 and the region in which it predicts 0 .

## Theorem

The decision boundary of Logistic
Regression is a hyperplane
Logistic regression predicts 1 if

$$
\begin{aligned}
& \hat{p}_{1}^{(i)}=h_{\boldsymbol{\theta}}(\mathbf{x})=\sigma\left(\boldsymbol{\theta}^{T} \cdot \mathbf{x}^{(i)}\right) \geq 0.5 \\
& \Longleftrightarrow \\
& \boldsymbol{\theta}^{T} \cdot \mathbf{x}^{(i)} \geq 0
\end{aligned}
$$

Therefore, the boundary decision is the set of $\mathbf{x}$ such that

$$
\boldsymbol{\theta}^{T} \cdot \mathbf{x}=0
$$



Picture above from [Gér17]


This surface is described by a linear equation, and thus it is a hyperplane.

## Multinomial Logistic Regression

Extension to multiple classes.

- Each class has its weight parameter $\theta_{k} \in \mathbb{R}^{N+1}$, except the last
- Compute a score $s_{k}(\mathbf{x}) \triangleq \theta_{k}{ }^{T} \cdot \mathbf{x}$
- For any $\mathbf{x}$, we have the score of all classes

$$
s_{1}(\mathbf{x}), \ldots, s_{K}(\mathbf{x})
$$

- We define that:

$$
\begin{aligned}
\hat{p}_{k} & =\mathbb{P}[\mathbf{x} \in \operatorname{class} k]=\operatorname{softmax}\left(s_{k}(\mathbf{x})\right) \\
& \triangleq \frac{\exp s_{k}(\mathbf{x})}{\sum_{z=1}^{K} \exp s_{z}(\mathbf{x})}=\frac{\exp \left(\boldsymbol{\theta}_{k}^{T} \cdot \mathbf{x}\right)}{\sum_{z=1}^{K} \exp \left(\theta_{z}^{T} \cdot \mathbf{x}\right)}
\end{aligned}
$$



- Predicted Class:

$$
k^{*}=\arg \max _{k} \operatorname{softmax}\left(\boldsymbol{\theta}_{k}^{T} \cdot \mathbf{x}\right)=\arg \max _{k} \boldsymbol{\theta}_{k}^{T} \cdot \mathbf{x}
$$

## Multinomial Logistic Regression (2)

We to compute $K-1$ parameter vectors:

$$
\begin{aligned}
\hat{p}_{k}^{(i)} & =\frac{\exp \left(-\theta_{K}\right)}{\exp \left(-\theta_{K}\right)} \cdot \frac{\exp \left(\boldsymbol{\theta}_{k}^{T} \cdot \mathbf{x}\right)}{\sum_{z=1}^{K} \exp \left(\boldsymbol{\theta}_{z}^{T} \cdot \mathbf{x}\right)} \\
& =\frac{\exp \left(\left(\boldsymbol{\theta}_{k}-\boldsymbol{\theta}_{K}\right)^{T} \cdot \mathbf{x}\right)}{\sum_{z=1}^{K} \exp (\underbrace{\left(\theta_{z}-\theta_{K}\right)^{T} \cdot \mathbf{x}}_{\theta_{z}^{\prime}})} \\
& =\frac{\exp \left(\theta_{k}^{\prime T} \cdot \mathbf{x}\right)}{1+\sum_{z=1}^{K-1} \exp \left(\theta_{z}^{\prime T} \cdot \mathbf{x}\right)}
\end{aligned}
$$



## Cross-entropy

- The loss function for each sample is the cross-entropy

$$
J\left(\boldsymbol{\theta}, \mathbf{x}^{(i)}, y^{(i)}\right)=-\sum_{k} \ln \hat{p}_{y^{(i)}}^{(i)}
$$

where $y_{k}^{(i)}=1 \Longleftrightarrow \mathbf{x}^{(i)} \in$ class $k$

- We want $\hat{p}_{y^{(i)}}^{(i)}$ to be as high as possible.
- Softmax "amplifies" the most probable class.



## Homework

## Assignement

Show that the Multinomial Logistic Regression with $K=2$ is equivalent to Binary Logistic Regression.

In other words, show that

$$
\mathbb{P}[\mathbf{x} \in \text { class } 1]=\operatorname{softmax}\left(\boldsymbol{\theta}^{T} \cdot \mathbf{x}\right)
$$

is equivalent to the binomial case

$$
\mathbb{P}[\mathbf{x} \in \text { class } 1]=\sigma\left(\theta^{T} \cdot \mathbf{x}\right)
$$

Then show that the loss function is also equivalent.

## Let's code ...

Go to notebook 03.regression_contd-and-classification.ipynb

## Section 6

## Class imbalance and performance metrics

## Confusion Matrix



## Class imbalance

When there are classes with many samples and other with less samples.
How to cope with it:

- Synthetic Minority Over-Sampling TEchnique (SMOTE) [CBHK02]
- 10 K citations!
- Others (you can explore yourself, if you want)
- Under-sampling majority class
- Use different weights in the loss function
- Others: see this blog.


## Classification Report

|  |  |  |  |  | - Precision: 29\% of samples classified as 0 are actually 0 <br> - Recall: 75\% of class 0 samples are correctly classified |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | precision | recall | f1-score | support | - Accuracy: $61 \%$ of classifications are correct |
| ${ }^{0}$ | 0.29 0.55 | 0.75 0.66 | 0.41 0.57 | ${ }_{10}^{8}$ |  |
| ${ }^{2}$ | 0.89 | 0.59 | 0.71 | 41 | - Support: 8 samples in the test set are of class 0 |
| macro avg | 0.57 | 0.65 | 0.56 | 59 |  |
| weighted avg | 0.75 | 0.61 | 0.64 | 59 | - f1-score: A combination of precision and recall: |

$$
F_{1}=\frac{2}{\frac{1}{\text { precision }}+\frac{1}{\text { recall }}}
$$

$\uparrow$ precision,$\uparrow$ recall $\Longrightarrow \uparrow F_{1}$

Regression (continued)

- Polynomial Regression
- Variance vs. Bias Trade-Off
- Regularization
- Scaling
- Feature Selection

Classification

- Logistic Regression
. Classification Performance
- Class imbalance


## To know more

- Video about feature scaling.
- More on feature selection.
- Several loss functions for classification (Video) [Mic]
- Another way of looking at Logistic Regression, based on likelihood: Sec. 4.3 of [JWHT13].


## References I

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[Gér17] Aurélien Géron, Hands-on machine learning with scikit-learn and tensorflow, 2017.
[JWHT13] Gareth James, Daniela Witten, Trevor Hastie, and Robert Tibshirani, An introduction to Statistical Learning, vol. 7, 2013.
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