

Neur2BiLO: Neural Bilevel Optimization

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Introduction

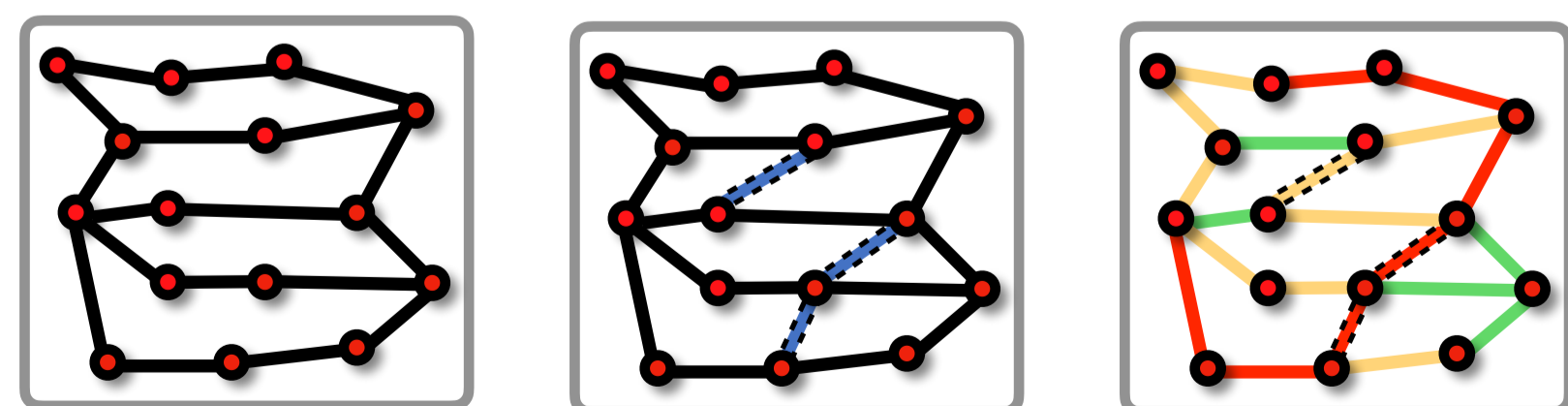
- **Summary:** A fast learning-based heuristic for *mixed integer (non-)linear bilevel optimization*
- **Objective:** Find the **leader / upper-level solution** (\mathbf{x}) that minimize the objective $F(\mathbf{x}, \mathbf{y})$ while considering the **follower / lower-level solution** (\mathbf{y}) will maximize their own objective $f(\mathbf{x}, \mathbf{y})$, subject to any constraints

$$\begin{aligned} \min_{\mathbf{x} \in \mathcal{X}, \mathbf{y}} \quad & F(\mathbf{x}, \mathbf{y}) \\ \text{s.t.} \quad & G(\mathbf{x}, \mathbf{y}) \geq \mathbf{0} \\ & \mathbf{y} \in \arg \max_{\mathbf{y}' \in \mathcal{Y}} \{f(\mathbf{x}, \mathbf{y}') : g(\mathbf{x}, \mathbf{y}') \geq \mathbf{0}\} \end{aligned}$$

- **Challenge:** Integer decisions variables make gradient and duality-based methods inapplicable
- **STOA:** Fast problem-specific heuristics for well-studied problems and less efficient general-purpose algorithms

Example

- **Discrete Network Design Problem:** A city planner wants to build a **subset of roads** (\mathbf{x}) to a road network to minimize **the total travel time in the network**, $F(\mathbf{x}, \mathbf{y})$. Based on the roads added, drivers will reach a **user equilibria**, $\mathbf{f}(\mathbf{x}, \mathbf{y})$, i.e., a **solution** (\mathbf{y}) in which no user can unilaterally reduce their travel time



- Intersection
- Existing Road
- Added Road
- Medium Traffic
- Low Traffic
- High Traffic

Methodology

- 1 Train a ML model to approximate the *value functions* of the leader and follower

Upper-Level Approximation (ULA)

$$NN_{\Theta}^u(\mathbf{x}) \approx F(\mathbf{x}, \mathbf{y}^*)$$

Lower-Level Approximation (LLA)

$$NN_{\Theta}^l(\mathbf{x}) \approx \max_{\mathbf{y} \in \mathcal{Y}} \{f(\mathbf{x}, \mathbf{y}) : g(\mathbf{x}, \mathbf{y}) \geq \mathbf{0}\}$$

- 2 Reformulate as a **single-level mixed integer program** by optimizing over predictive model

ULA

$$\min_{\mathbf{x} \in \mathcal{X}} \{NN_{\Theta}^u(\mathbf{x}) : G(\mathbf{x}) \geq \mathbf{0}\}$$

- Less variables (no \mathbf{y})
- Faster to optimize
- Does not model coupling constraints $G(\mathbf{x}, \mathbf{y})$
- May be infeasible

LLA

$$\min_{\mathbf{x} \in \mathcal{X}, \mathbf{y}} F(\mathbf{x}, \mathbf{y}) + \lambda s$$

$$\text{s.t. } G(\mathbf{x}, \mathbf{y}) \geq \mathbf{0}$$

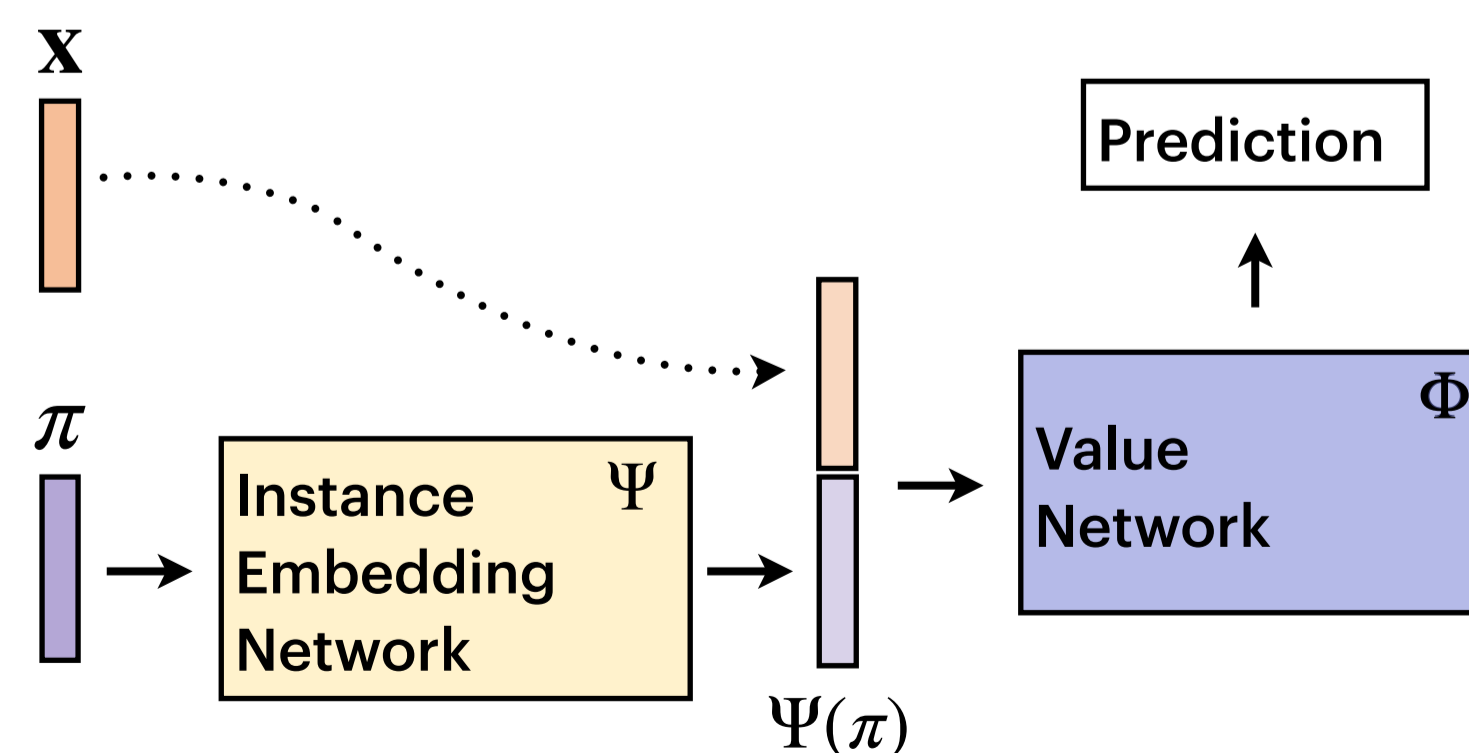
$$g(\mathbf{x}, \mathbf{y}) \geq \mathbf{0}$$

$$f(\mathbf{x}, \mathbf{y}) \geq NN_{\Theta}^l(\mathbf{x}) - s$$

- Requires lower-level variables (\mathbf{y}), a slack variable (s), and hyperparameter (λ)
- Always feasible
- Better for highly constrained problems

Architecture

- For **data-driven settings** where we want to train one model across variables instances ($\pi \in \Pi$)



- **Set / graph-based architectures** can be used to create models that handle invariance in **variable ordering** and allow generalization to varying **instances sizes**

Guarantees

- For min max problems, i.e., $F = f$, Neur2BiLO computes a solution with an optimality gap bounded by an additive function of the prediction error

ULA

If $|NN_{\Theta}^u(\mathbf{x}) - \Phi(\mathbf{x})| \leq \alpha, \forall \mathbf{x} \in \mathcal{X}$, then the upper-level approximation returns a solution $(\mathbf{x}^*, \mathbf{y}^*)$ that is bounded by $f(\mathbf{x}^*, \mathbf{y}^*) \leq \mathbf{opt} + 2\alpha$

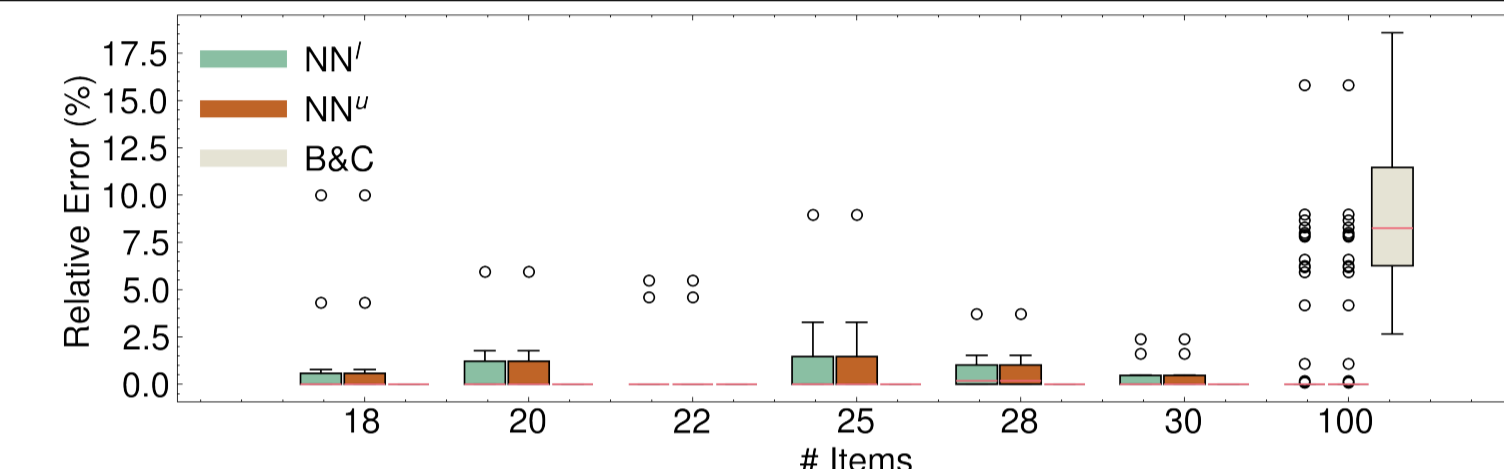
LLA

If $|NN_{\Theta}^l(\mathbf{x}) - \Phi(\mathbf{x})| \leq \alpha, \forall \mathbf{x} \in \mathcal{X}$, then the lower-level approximation returns a solution $(\mathbf{x}^*, \mathbf{y}^*)$ that is bounded by $f(\mathbf{x}^*, \mathbf{y}^*) \leq \mathbf{opt} + 3\alpha + \frac{2}{\lambda}\Delta$, where $\Delta = \max\{f(\mathbf{x}, \mathbf{y}) - f(\mathbf{x}, \mathbf{y}'), \forall \mathbf{x} \in \mathcal{X}, \mathbf{y}, \mathbf{y}' \in \mathcal{Y}\}$

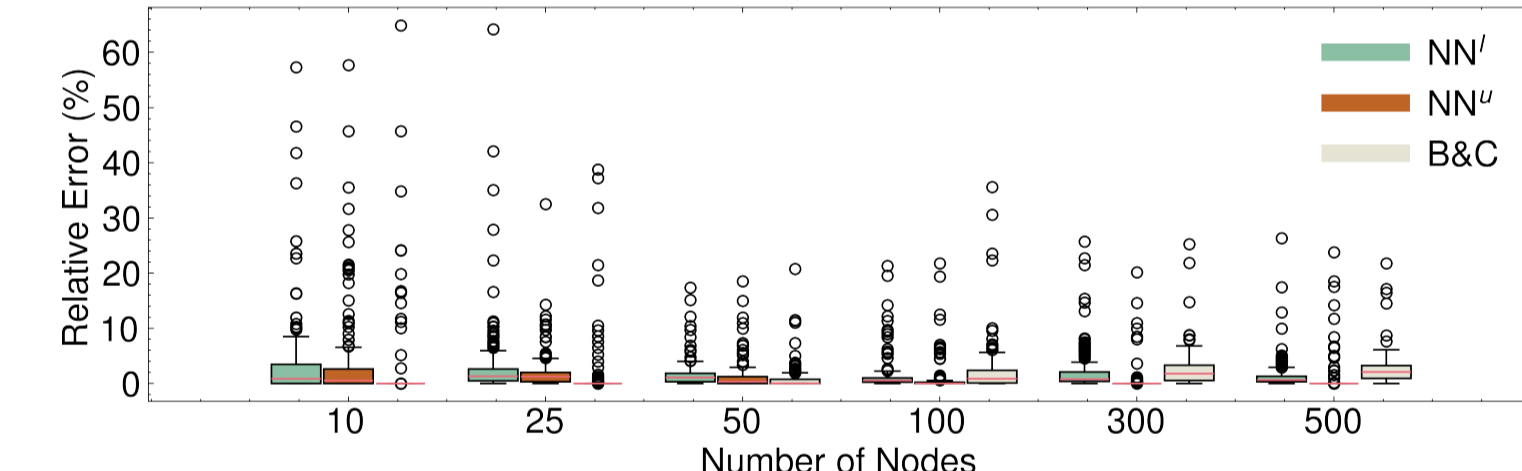
Computational Results

- **Efficiency:** Neur2BiLO finds solutions 100-1000x faster
- **Solution Quality:** Neur2BiLO finds STOA solutions on larger instances

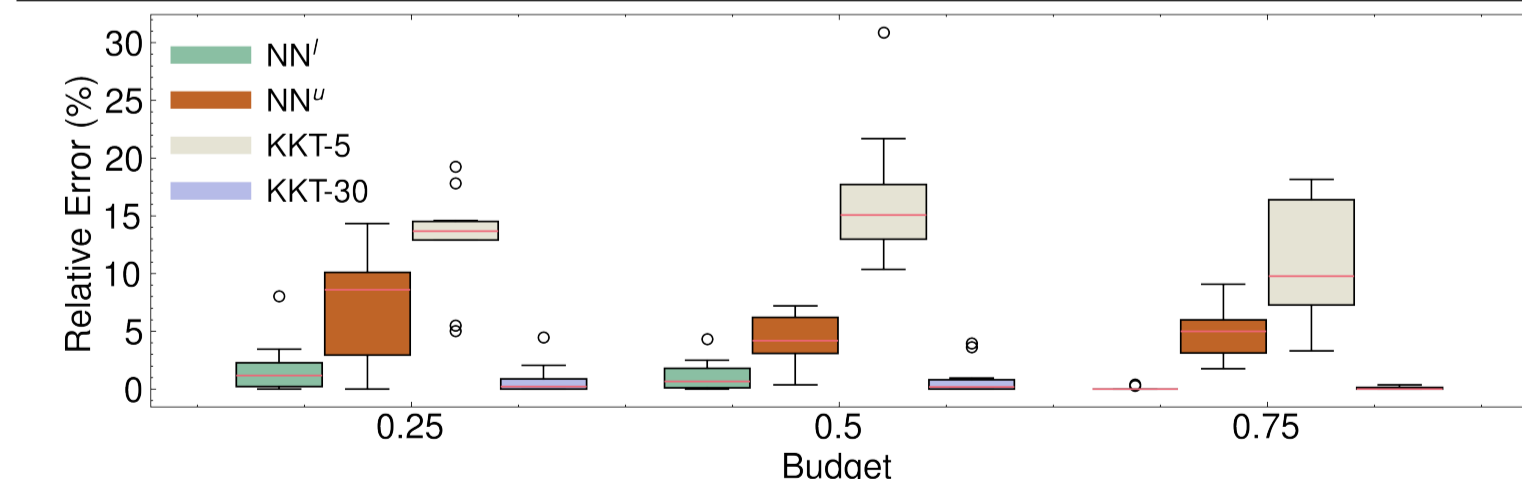
Knapsack Interdiction Problem (Combinatorial Interdiction)



Critical Node Problem (Security)



Discrete Network Design Problem (Transportation)



Donor Recipient Problem (Healthcare)

