# HARDWARE HACKING EXPERIMENTS

Extracting Firmware from Embedded Device

Jérémy Brun-Nouvion - 2020

### The Target

- Device: Netgear N300 Wireless Router
- Model No: WNR2000v4

#### **NETGEAR**<sup>®</sup>

Google play Mac & PC

NETGEAR

genie 🖤

Over 2 Million

Downloads

Available on the App Store

#### N300 Wireless Router

Model No. WNR200

N300 WiFi speed – Faster downloads & Internet gaming

> WiFi range for medium-sized homes

Parental Controls keep your Internet experience safe

NETGEAR<sup>®</sup> genie<sup>®</sup> App – Home networking simplified



C A

#### **Technical Specifications**

- Wi-Fi transmitters/receivers
   (Tx/Rx) 2x2 (2.4 GHz)
- Supports Wireless Multimedia (WMM) based QoS
- IPv6 Support (Internet Protocol Version 6)

#### Security

- Wi-Fi Protected Access\*
   (WPA/WPA2 PSK) and WEP
- Double firewall protection
   (SPI and NAT firewall)
- Denial-of-service (DoS) attack prevention
- DMZ for secure gaming

#### Standards

- IEEE 802.11 b/g/n 2.4 GHz
- Five (5) 10/100 (1 WAN and 4 LAN) Ethernet ports with auto-sensing technology

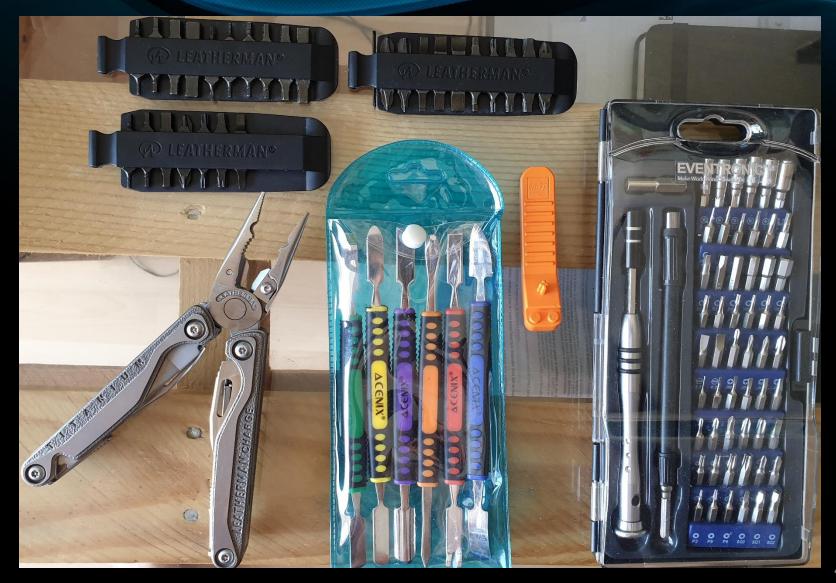
#### System Requirements

- Broadband (cable, DSL) Internet service and modem with Ethernet connection
- 802.11 b/g/n 2.4 GHz wireless adapter or Ethernet adapter and cable for each computer
- Microsoft<sup>®</sup> Windows<sup>®</sup> 7, 8, Vista<sup>®</sup>, XP, 2000, Mac<sup>®</sup> OS, UNIX<sup>®</sup>, or Linux<sup>®</sup>
- Microsoft<sup>®</sup> Internet Explorer<sup>®</sup> 5.0, Firefox<sup>®</sup> 2.0 or Safari<sup>®</sup> 1.4 or higher
- Use with an N300 Wireless USB Adapter (WNA3100) for maximum performance

2

0> TOOLBOX

# **Tools to open devices**



#### **Multimeter - PicoScope**



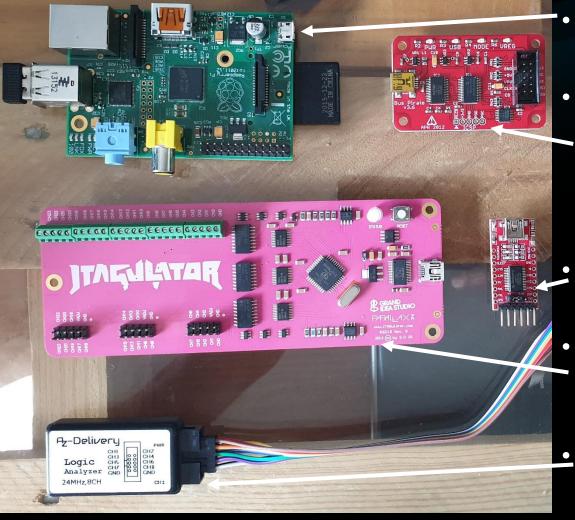
- Multimeter:
  - Very useful feature: Continuity test with beep (detect GND & Vcc pins easily)
  - Measure Voltage:
    - High constant (around 3.3V or 5V) may indicate Vcc
    - Voltage fluctuation may indicate data transmission
  - PicoScope =
    - USB PC Oscilloscope
    - Can be used to find points on PCB that are emitting data (eg. Tx pin of UART)

## **Physical connection tools**



- Soldering iron
- Pin headers (to solder to PCB pads)
- Jump wires (m/m, f/m, f/f)
- Chip clips (for 8-pin & 16pin Flash/EEPROM)

### Hardware



#### Raspberry Pi

- Bus Pirate (v3.6): Universal bus interface compatible with multiple protocols (I<sup>2</sup>C, SPI, JTAG, UART...)
- UART to USB adapter
- JTAGulator: Useful to identify JTAG pins
- Logic Analyzer

### Softwares

- Terminal emulator: screen/minicom/putty
- PicoScope software <u>https://www.picotech.com/downloads</u>
- Salae Logic Analyzer <a href="https://www.saleae.com/downloads/">https://www.saleae.com/downloads/</a>
- OpenOCD (used to interact with device via JTAG) <a href="http://openocd.org/">http://openocd.org/</a>
- Flashrom (identify, read, write flash memory chips) <u>https://www.flashrom.org/</u>
- Binwalk (firmware analysis tool) <u>https://github.com/ReFirmLabs/binwalk</u>

# **1> RECON**

# Manual / Online Public Information

₩ Mettre en surbril

ds.netgear.com/files/GDC/WNR2000V4/WNR2000v4\_UM\_14Mar2014.pdf

N300 Wireless Router WNR2000v4

- +  $\bigcirc$   $\square$   $A^{\flat}$  Lire à haute voix  $\lor$   $\forall$  Dessiner

#### Table 4. WNR2000v4 router factory default settings (continued)

Feature		Default behavior
Wireless	20/40 MHz coexistence	Enabled
(continued)	Data rate	Best
	Output power	Full

#### **Technical Specifications**

#### Table 5. WNR2000v4 router specifications

Feature	Description
Data and routing protocols	TCP/IP, RIP-1, RIP-2, DHCP, PPPoE, PPTP, Bigpond, Dynamic DNS, UPnP, and SMB
Power adapter	North America: 120V, 60 Hz, Input     UK, Australia: 240V, 50 Hz, input     Europe: 230V, 50 Hz, input     All regions (output): 12V DC @ 1A, output or 12V DC @ 0.5A, output
Dimensions	178 x 130 x 54 mm (7 x 5.1 x 2.1 in.)
Weight	0.28 kg (0.62 lb)
Operating temperature	0° to 40°C (32° to 104°F)
Operating humidity	90% maximum relative humidity, noncondensing
Electromagnetic Emissions	FCC Part 15 Class B VCCI Class B EN 55 022 (CISPR 22), Class B C-Tick N10947
LAN	10BASE-T or 100BASE-Tx, RJ-45
WAN	10BASE-T or 100BASE-Tx, RJ-45
Wireless	Maximum wireless signal rate complies with the IEEE 802.11 standard. See the footnote for the previous table.
Radio data rates	Auto Rate Sensing
Data encoding standards	IEEE 802.11n version 2.0 IEEE 802.11n, IEEE 802.11g, IEEE 802.11b 2.4 GHz
Maximum computers per wireless network	Limited by the amount of wireless network traffic generated by each node (typically 50–70 nodes).
Operating frequency range	2.412-2.462 GHz (US) 2.412-2.472 GHz (Japan) 2.412-2.472 GHz (Europe ETSI)
802.11 security	WEP, WPA-PSK, WPA2-PSK, WPA-PSK + WPA2-PSK mixed mode, WPA/WPA2 Enterprise

Vendor's documentation

- Google
- Previous research already available
- Similar products

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Wireles	S Freedom			Recent Charges 1	Media Manager Silemap
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Learn about OpenWrt  • Supported devices					
Packages     Operation     Documentation	Netgear WNR2000		D for future use with OpenWrt due to low flashfram. RLA SE/ JEME (Role I you intend to Sash an up-to-	- Netge - Netge - 100	of Contents - par WNR2000 sported Versions enhane Highdights
Cuikk start guide     User guide     Developer guide     Security		1) This device does not have suffic secure and reliable operation.	(05 or later) onto III See 4/32 warning for details. Ient resources (flash and/or RAM) to provide ord or changing simple network settings might not be		rtallation Flashing modified s-boot and pre- built Operative Backfirst on WhiRi2000v1
Generative     FAQ     Forum     Contributing		<ul> <li>possible any more, rendering the devices what you can do now.</li> <li>2) OpenWirt support for this device</li> </ul>	to effectively useless. See OpenWitt on 402 will end after 2019.		Installing Sunk LEDE on WHR2000H1 Installing OpenWIT onto a RAMdek on WHR2500H1
Contributing patches     Reporting bugs     Contributing to wild		19.07 will be the last official build for will be built for 4/32 devices. See Op-	US2 devices. After 19 07, no further OpenWit images mWit on 4/32 devices what you can do now		Installing OpenWit on WNR2000v3 Installing OpenWit on WNR2000 v4 (or WN2000RPTv3)
Controlling to weat     Project					
About OpenWit     Rules	The slock firmware for the v3 device runs O 1. Soldered aluminium antenna 2. On the main PCB				opported Versions where Highlights CPU (WNR2500v3)
Infrastructure     Website     Trademark policy	2. On the main PCB 3. PCB antenna daughter board 4. PCB antenna daughter board				ardware will Covening the case Secul
+ Contacts	( <u> </u>				OFIO JTAG Ibricking Jalom u-boot Hite
	Supported Versions				
	Brand Model   Current Version Release				Technical Data
	Netgear WNR2000 v1 19.07.4				Men/Edit dela
	Nelgear WNR2000 v2 18.05.4				Vew/Edit data
	Netgear         WNR2000         v3         19.07.4           Netgear         WNR2000         v4         17.01.7			wre 100%2 was 100%2 yn wrait 12/2 wynd 24e wraittofri 2003000 18.46 9 growded wrage too big to sawe arwetay 18.161/72?s-kroanae, wrwiel orgyfwerigas, phyffar 50478	View/Edit data
	Hardware Highlights				
	WNR2000 v1 Atheros AR9130		32, Atheros AR9103 bigin - 5		
	WNR2000 v3 Alberos AR7240 WNR2000 v4 Alberos AR9341		os AR7240 bigm - 5 os AR9341 bigm - 5		
	WNR2000 V4 Atheros Arcista	533 4 32 Alber	os AR9341 bigm - 5		
	Installation				

# **FCCID Lookup**



1 https://fccid.io/PY312300212



#### https://fccid.io/PY312300212

	https:/	/1ccid.io/		

FCC ID.io Blog Search

#### FCC ID PY312300212

PY3-12300212, PY3 12300212, PY312300212, PY312300212, PY312300212 Netgear Incorporated 11n Wireless Router **12300212** 

FCC ID > / Netgear Incorporated > / 12300212

An FCC ID is the product ID assigned by the FCC to identify wireless products in the market. The FCC chooses 3 or 5 character "Grantee" codes to identify the business that created the product. For example, the grantee code for FCC ID: PY31230021 s PY3. The remaining characters of the FCC ID, 12300212, are often associated with the product model, but they can be random. These letters are chosen by the applicant. In addition to the application, the FCC also publishes *Internal images, external images, user manuals, and test results* for wireless devices. They can be under the "exhibit" tab below.

Purchase on Amazon: 11n Wireless Router

Application: 11n Wireless Router

Equipment Class: DTS - Digital Transmission System

Alternate Sources: FCC.gov | FCC.report

Registered By: Netgear Incorporated - PY3 (United States) you@youremail.com Subscribe

you@youremail.com

App # Purpose

1 Original Equipment

Operating Frequencies				
Frequency Range	Power Output	Rule Parts	Grant Notes	Line Entry
2.412-2.462 GHz 🐠	745 mW	15C	МО	1

Unique ID

KwAY5bnasonz7/f7sCO60Ozz

Date

2012-12-10

Attestation Statements Adobe Acrobat PDF (96 kB)
Cover Letter(s) Adobe Acrobat PDF (159 kB)
Cover Letter(s) Adobe Acrobat PDF (116 kB)
Cover Letter(s) Adobe Acrobat PDF (125 kB)
RF Exposure Info Adobe Acrobat PDF (49 kB)
Users Manual Adobe Acrobat PDF (3496 kB)
Test Setup Photos Adobe Acrobat PDF (144 kB)
Test Report Adobe Acrobat PDF (800 kB)
Operational Description Adobe Acrobat PDF (40 kB)
Internal Photos Adobe Acrobat PDF (2973 kB)

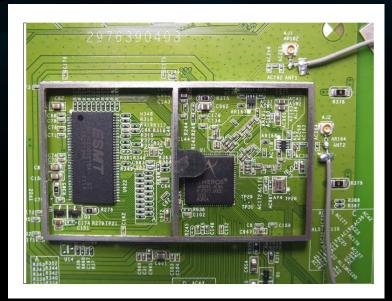
# FCCID Lookup => Internal Photos

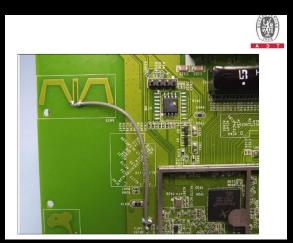
#### https://fccid.io/PY312300212/Internal-Photos/Internal-Photos-1855783

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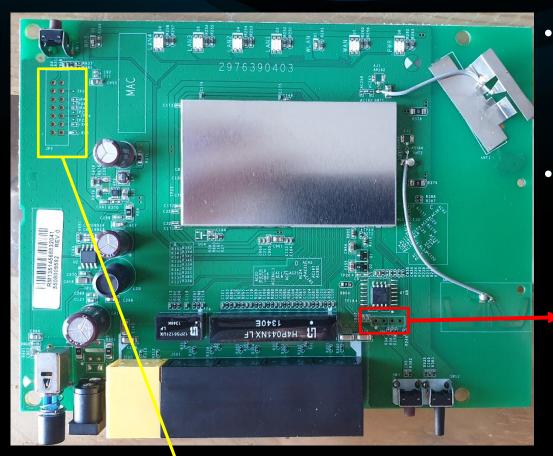






# **2> INTERNAL INSPECTION**

#### **Open the Device**



- No need to remove metallic EMC shield for now (we have full internal photos)
- Here, no trivial indicator of debug interface is written on PCB (eg. TX, RX, TDO, TDI, TCK...)

Row of 4 pads => Looks like UART

Double row 14 pads => Maybe JTAG debug interface ?

# **Components Identification (1/2)**

- Search references/codes on chips/components on:
  - <u>https://www.alldatasheet.com/</u>
  - <u>https://www.datasheets360.com/</u>
  - Google (filetype:pdf)



MXIC MX 25L3208E 32 M-Bit (4MB) CMOS Serial Flash <u>https://www.alldatasheet.com/datasheet-</u> pdf/pdf/575458/MCNIX/MX25L3208EM2I12G.html => NOR Flash – Non-volatile memory



#### MP1482DS

2A, 18V Synchronous Rectified Step-Down Converter
 <u>https://www.alldatasheet.com/datasheet-pdf/pdf/551573/MPS/MP1482DS.html</u>
 => Related to Power Supply, not interesting for us

## **Components Identification (2/2)**

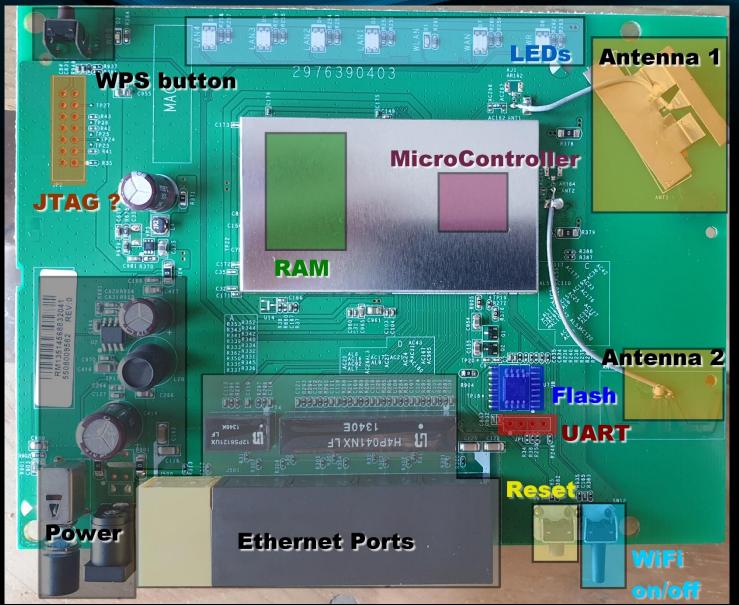


ESMT M13S2561616A – 5T 4M x 16 Bit x 4 Banks Double Data Rate SDRAM (32MB) https://www.alldatasheet.com/datasheetpdf/pdf/204934/ESMT/M13S2561616A.html



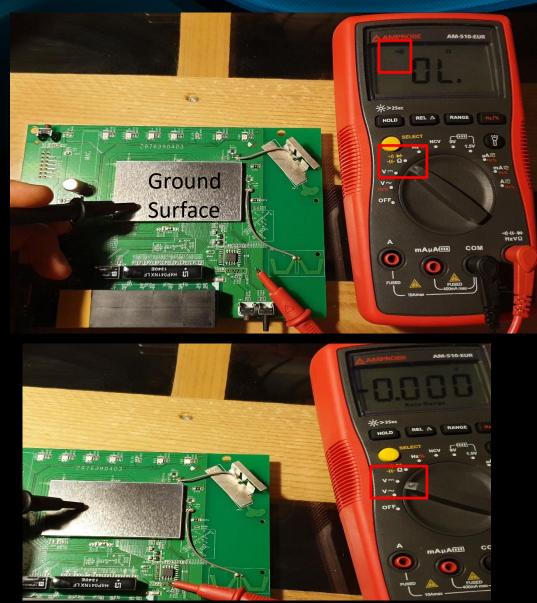
ATHEROS AR9341-AL3A Highly-Integrated and Feature-Rich IEEE 802.11n 2x2 2.4 GHz Premium SoC for Advanced WLAN Platforms <u>https://www.alldatasheet.com/datasheet-pdf/pdf/1168533/ETC1/AR9341.html</u> => Micro-Controller (MCU)

### **PCB Overview**





### **UART Pins Identification - Methodology**

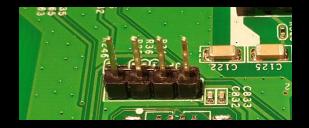


- 1. Multimeter in "continuity test" mode & Device powered OFF
  - Black probe on known Ground (metallic surface)
  - Red probe on each pin/pad
  - $\Rightarrow$  Beep indicates GND
- Multimeter in Voltmeter (DC) mode
   & Device powered ON
  - Black probe on known Ground
  - Red probe on each pin/pad
  - V=3.3V or 5V (constant) => Vcc
  - V=High voltage with fluctuation at boot => Probably Tx
  - V=Low voltage => Probably Rx
  - V=0V => GND (already found)

### **UART Pins Identification - Results**

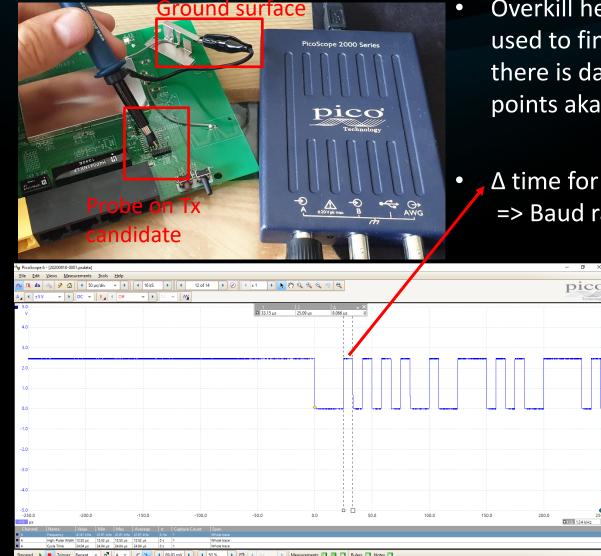
	PIN	R_GND (dev OFF)	V (device ON)	Notes
	1	∞	3,3V	Vcc
	2	~80kΩ	1,7-2,5V (fluctuations)	Tx
22 1 2 3 4 6	3	~12kΩ	0-0,004V	Rx
	4	0Ω (beep)	0V	GND

- UART is used for asynchronous communication (i.e. without a clock) => Baud rate (nb of bits / second) is required
- Common Baud rates: 9600, 38400, 19200, 57600, 115200
- We need to solder Pin headers to be able to connect using jump wires
  - Warning: bad soldering may result in bad contact or no contact at all !!



### **Baud rate identification with PicoScope**

#### Connected to

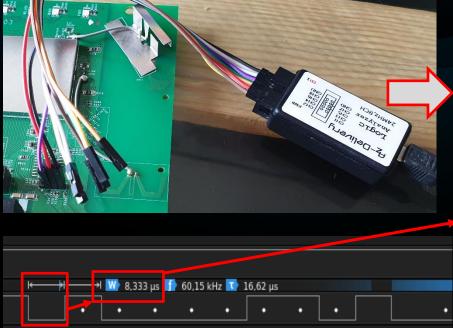


Overkill here, but PicoScope can be used to find tricky points on PCB where there is data emission (eg. Isolated test points aka "TP")

Δ time for 1-bit ≈ 8,066 μs => Baud rate ≈ 1/(8,066 \* 10^-6) ≈ 123 977

> => Closest common rate is: 115 200

# **Baud rate identification with Logic Analyzer**



*	-0			Saleae Logic 1.2.18 -
			 	 3 s : 38 ms
		▼ ns		
00 :::::		✿ +f		
01 :::::		¢+f —		
02 :::::		¢+f —		
03 ::::		¢+5 —		ididate
04 ::::		*+F		
05 :::::		Q +J —		,

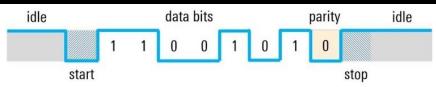
 $\Delta$  time for 1-bit ≈ 8,333 µs => Baud rate ≈ 1/(8,333 \* 10^-6) ≈ 120 048

=> Closest common rate is: 115 200

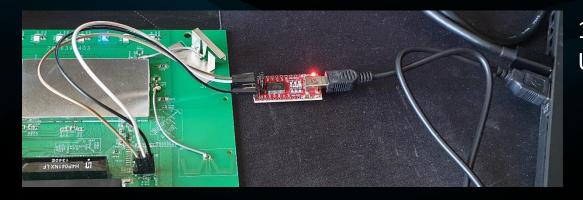
#### Logic Analyzer can then decode data:

0.4	obarrad d	(HE)	a	t	h	r	S	2	7		p
	Channel 4 🏼 🎝	+f									
*****										11 1111	
05	Channel 5 🔅	+-									

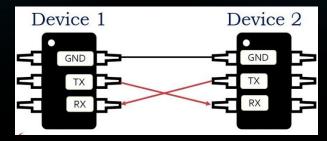
#### UART frame format:



### **Baud rate identification with Bruteforce**



1. Connect Serial adapter to UART



#### 2. Run script <u>https://github.com/devttys0/baudrate/blob/master/baudrate.py</u> Will loop around common baud rates until it receives readable data

root@hackbox:/home/jbr/pentest-tools/ha	rdware/baudrate	# python2 baudrate.py -a
Starting baudrate detection on /dev/tty Press Ctl+C to quit.	USB0, turn on y	our serial device now.
ລລລລລລລລລລລລລລລລລລລລລລລລລລສ Baudrate: 115200	იიიიიიიიიიიიიიიიიი	බබබබබබ
U-Boot 1.1.4 (Nov 26		
Detected baudrate: 115200		
Save minicom configuration as: ^C		

### **Connection to UART**

#### screen /dev/ttyUSB0 115200 $\bullet$

	BusyBox v1.4.2 (2013-11-12 17:41:20 CST) B	üilt-in⊺shell (ash)
Setting DUV	Enter 'help' for a list of built-in comman	
Setting PHY	Enter netp for a tist of built-in comman	GND
ADDRCONF(NETDEV_UP): eth0: link is not ready		
athr_gmac_ring_alloc Allocated 640 at 0×81e3dc00		
athr_gmac_ring_alloc Allocated 2048 at 0×81ea6000	Power OFF	
WASP $\longrightarrow$ S27 PHY MDIO		T:/ I
Setting Drop CRC Errors, Pause Frames and Length Error frames		
ATHRS27: resetting s27		
ATHRS27: s27 reset done		
Setting PHY	_   WIRELESS FREED	0 M
ADDRCONF(NETDEV_UP): eth1: link is not ready	KAMIKAZE (bleeding edge, r18571) ———	
athr_gmac_ring_free Freeing at 0×81e3d800	* 10 oz Vodka Shake well with ice	and strain
athr_gmac_ring_free Freeing at 0×81e55800		
athr_gmac_ring_free Freeing at 0×81e3dc00	* 10 oz Triple sec mixture into 10 shot	glasses.
athr_gmac_ring_free Freeing at 0×81ea6000	* 10 oz lime juice Salute!	
Write Reg: 0×0000002c: Oldval = 0×fe7f007f Newval = 0×fe7f7f		
Write Reg: 0×0000003c: Oldval = 0×cf00004e Newval = 0×ce48004e		
Write Reg: 0×00000104: Oldval = 0×00004804 Newval = 0×00304804	root@WNR2000v4:/# Sending discover	
Write Reg: 0×00000204: Oldval = 0×00004004 Newval = 0×00304004 Write Reg: 0×00000304: Oldval = 0×00004004 Newval = 0×00304004	Sending discover	
Write Reg: 0×00000304. Oldval = 0×00004004 Newval = 0×00304004 Write Reg: 0×00000404: Oldval = 0×00004004 Newval = 0×00304004		
Write Reg: 0×00000504: Oldval = 0×00004004 Newval = 0×00304004 Write Reg: 0×00000504: Oldval = 0×00004004 Newval = 0×00304004	Sending discover	
Write Reg: 0×0000003c: Oldval = 0×00004044 Newval = 0×00504004 Write Reg: 0×0000003c: Oldval = 0×ce48004e Newval = 0×ce68004e		
Write Reg: 0×00058804: Oldval = 0×00000017 Newval = 0×00000000	root@WNR2000v4:/# Sending discover	
Write Reg: 0×00058808: Oldval = 0×00000010 Newval = 0×00000000		
Write Reg: 0×00058800: Oldval = 0×00000003 Newval = 0×00000000	Sending discover	
Write Reg: 0×00058810: Oldval = 0×0000001c Newval = 0×00000000		
Write Reg: 0×00058800: Oldval = 0×00000000 Newval = 0×00000001	root@WNR2000v4:/#	
Write Reg: 0×00058818: Oldval = 0×00000002 Newval = 0×00000006		
Write Reg: $0.00058400$ : Oldval = $0.750000521$ Newval = $0.567fffa$	root@WNR2000v4:/# Sending discover	
Write Reg: 0×00058404: Oldval = 0×10f21502 Newval = 0×00000100	ls	
Write Reg: 0×00058408: Oldval = 0×88061000 Newval = 0×00000000	bin jffs	
Write Reg: 0×0005840c: Oldval = 0×2804eb95 Newval = 0×00000001		sbin
Write Reg: 0×00058410: Oldval = 0×00000081 Newval = 0×00000001	default_language_version lib	sys
Write Reg: 0×00058c00: Oldval = 0×6657757e Newval = 0×6fffffff	dev mnt	tmp
Write Reg: 0×00058c04: Oldval = 0×80c493f2 Newval = 0×0000ffff		
Write Reg: 0×00058c08: Oldval = 0×f8f517e0 Newval = 0×00000000		
Write Reg: 0×00058c0c: Oldval = 0×bff7dbd6 Newval = 0×00000fff	firmware_region proc	
Write Reg: 0×00058814: Oldval = 0×0000004f Newval = 0×0000001f	firmware version rom	
Write Reg: 0×0005881c: Oldval = athr_gmac_ring_alloc Allocated 640 at 0×81eae000	-	
0×00000000 Newvaathr_gmac_ring_alloc Allocated 2048 at 0×81eea000	hardware_version root	
l = 0×00000001	root@WNR2000v4:/# cat firmware_version	
Write Reg: $0 \times 000$ WASP $\longrightarrow$ S27 PHY MDIO	V1.0.0.50	
58000: Oldval = Setting Drop CRC Errors, Pause Frames and Length Error frames		
0×00000000 NewvaSetting PHY	root@WNR2000v4:/# Sending discover	
L = 0×00000000	Sending discover	
Write Reg: 0×00058004: Oldval = 0×08049100 Newval = 0×11f00000		
Write Reg: 0×00058008: Oldval = 0×00000000 Newval = 0×00000000	Sending discover	
init.enet: Default WAN MAC is : C4:04:15:99:6A:CB		

- Well-known open-source OS for embedded devices (based on Linux) OpenWrt  $\bullet$ is used
- UART connection gives a root shell => full access to filesystem ullet

Copyright 2005 by Johnny Egeland <johnny@rlo.org> Modified by Tos Xu for IGMP snooping in April, 2009. Distributed under the GNU GENERAL PUBLIC LICENSE, Version 2 - check GPL.txt

MTD partition not found. Boot up procedure is Finished!!!

Please press Enter to activate this console. Sending discover ... Sending discover ... Sending discover ...

4> BOOTLOADER (via UART)

# Info Gathering using Bootloader (1/2)

- Bootloader in use: U-Boot (very popular for embedded devices)
- Boot logs analysis (record all data sent by Tx & look for interesting stuff)
- Enter in Bootloader menu (press key at boot) and look for available commands

U-Boot 1.1.4 (Nov 26-2012 - 15:58:42) II - 1000009 Corolly	bootm - boot application image from memory
DNT HW TD: 29763904 flash 4MB RAM 32MB U-boot dni29 V0.5	bootm - boot apprication image from memory
DRAM:	
sri ino parti di toto tono.	cmp 1 3 memory comparen 0.1 beta2, Build 090422
Wasp 1.3 wasp_ddr_initial_config(281): Wasp (16bit) ddr1 init	coninfo - print console devices and information
Tap value selected = $0 \times f [0 \times 0 - 0 \times 1f]$	cp - memory copy
32 MB Sending discover.	crc32 <sup>1-S</sup> checksum calculation <sup>10</sup> GENERAL PUBLIC LICENSE. VELSION 2 SCHECK GPLIC
Top of RAM usable for U-Boot at: 82000000 Reserving 218k for U-Boot at: 81fc8000	dhcp – invoke DHCP client to obtain IP/boot params
Reserving 192k for malloc() at: 81f98000	echo – echo args to console
Reserving 44 Bytes for Board Info at: 81f97fd4 Built in shell issue	erase - erase FLASH memory
Reserving 36 Bytes for Global Data at: 81f97fb0 middle Reserving 128k for boot params() at: 81f77fb0	ethreg - S26 PHY Reg rd/wr utility
Stack Pointer at: 81f77f98	exit - exit script
Now running in RAM - U-Boot at: 81fc8000	flinfo - print FLASH memory information
Flash Manuf Id 0×c2, DeviceId0 0×20, DeviceId1 0×16	fw_recovery - start tftp server to recovery dni firmware image.
flash size 4MB, sector count = 64	
*** Warning - bad CRC, using default environment	go start application at address 'addr'
In: serial of line duice state to shot glasses.	help - print online help
Out: serial	iminfo 🛛 – print header information for application image shall have
Err: serialRR2000v4:/# Sending discover	imls E-tlist all images found in flashin commands.
Net: ag934x_enet_initialize	itest – return true/false on integer compare
Fetching MAC Address from 0×81fecd38 Fetching MAC Address from 0×81fecd38	loop – infinite loop on address range
wasp reset mask:c03300 Sending discover	macset - Set ethernet MAC address
WASP $\longrightarrow$ S27 PHY OVER	macshow - Show ethernet MAC addresses
: cfg1 0×80000000 cfg2 0×7114 eth0: c4:04:15:99:6a:cb	md - memory display
s27 reg init <sup>W1R2000V4:7#</sup> Sending discover	mii - MII utility commands
athrs27_phy_setup ATHR_PHY_CONTROL 4 :1000	mm - memory modify (auto-incrementing)
athrs27_phy_setup ATHR_PHY_SPEC_STAUS 4 :10 eth0 up	mtest – simple RAM test
WASP $\rightarrow$ S27 PHY	DUL – TUUZ HIDLE, SEL WIXLULE INLU IU SHUL QLASSES.
: cfg1 0×f cfg2 0×7214 eth1: c4:04:15:99:6a:ca	
s27 reg init lan	nm – memory modify (constant address)
ATHRS27: resetting s27	nmrp - start nmrp mechanism to upgrade firmware-image or string-table.
ATHRS27: s27 reset done athrs27_phy_setup ATHR_PHY_CONTROL 0 :1000	nor_fw_integrity_check - verify firmware checksum in NOR
athrs27_phy_setup ATHR_PHY_SPEC_STAUS 0 :10	nor_two_part_fw_integrity_check - verify firmware checksum in NOR
athrs27_phy_setup_ATHR_PHY_CONTROL 1 :1000	pci – list and access PCI Configuration Space
athrs27_phy_setup_ATHR_PHY_SPEC_STAUS_1 :10	ping - send ICMP ECHO_REQUEST to network host
athrs27_phy_setup ATHR_PHY_CONTROL 2 :1000 athrs27_phy_setup ATHR_PHY_SPEC_STAUS 2 :10	pll cpu-pll dither ddr-pll dither - Set to change CPU & DDR speed
athrs27_phy_setup ATHR_PHY_CONTROL 3 :1000	pll erase
athrs27_phy_setup ATHR_PHY_SPEC_STAUS 3 :10	pll getroot@WNR2000v4:/#
eth0, eth1	printenv- print environment variables
Hit any key to stop autoboot:	
ar7240>	

### Info Gathering using Bootloader (2/2)

#### ar72405

ar7240> bdinfo boot\_params = 0×81F77FB0 memstart = 0×80000000 memsize = 0×02000000 flashstart = 0×9F000000 flashsize = 0×00400000 flashoffset = 0×0002E310 ethaddr = 00:AA:BB:CC:D):EE ip\_addr = 192.168.1.1 baudrate = 115200 bps ar7240> ar7240> board\_ssid\_show board\_ssid : NETGEAR32 ar7240> ar7240> coninfo List of available devices: serial 80000003 SIO stdin stdout stderr a1/240/ ar7240> imls Image at 9F040000: Image Name: MIPS OpenWrt Linux-2.6.31 Created: 2013-11-12 9:49:12 UTC MIPS Linux Kernel Image (lzma compressed) Image Type: Data Size: 804410 Bytes = 785.6 kB Load Address: 80002000 Entry Point: 801e68d0 VETTLYING CHECKSUM ... UK

ar7240> ar7240> version

U-Boot 1.1.4 (Nov 26 2012 - 15:58:42) ar7240>

```
ar7240> printenv
```

bootargs=console=ttyS0,115200 root=31:02 rootfstype=jffs2 init=/sbin/init mtdpart bootcmd=sleep 1; nmrp; nor\_two\_part\_fw\_integrity\_check 0×9f040000; bootm 0×9f0400 bootdelay=1 baudrate=115200

ethaddr=0×00:0×aa:0×bb:0×cc:0×dd:0×ee

ipaddr=192.168.1.1

```
serverip=192.168.1.10
```

```
dir=
```

lu=tftp 0×80060000 \${dir}u-boot.bin&Gerase 0×9f000000 +\$filesize;cp.b \$fileaddr 0>
lf=tftp 0×80060000 \${dir}db12x\${bc}-jffs2&Gerase 0×9f050000 +0×630000;cp.b \$filead
lk=tftp 0×80060000 \${dir}vmlinux\${bc}.lzma.uImage&Gerase 0×9f680000 +\$filesize;cp.
stdin=serial

stdout=serial stderr=serial ethact=eth0 • Analysis Results Notes:

	Bootloader:	U-Boot 1.1.4 (Nov 26 2012 - 15	58:42)
9	OS: Arch: GCC version:	MIPS OpenWrt Linux-2.6.31 MIPS gcc version 4.3.3 (GCC)	
	U-Boot addr: Firmware addr:	81fc8000 9F040000	
	RAM device: RAM start addr: RAM size:	80000000 02000000 (32MB)	
	Flash device: Flash start addr: Flash size:	29763904 flash 4MB 9F000000 00400000 (4MB)	
	Image Size: Load Address: Entry Point:	804410 Bytes = 785.6 kB 80002000 (in RAM) 801e68d0 (in RAM)	
	Root filesystem: MTD partitions:	squashfs version 4.0 (2009/01/3	31)
:: )(	0x000000000000-0x00 0x000000030000-0x00 0x000000040000-0x00 0x000000110000-0x00 0x0000003a0000-0x00	0000040000 : "u-boot-env" 0000110000 : "kernel" 00003a0000 : "rootfs"	192kB 64kB 832kB 2624kB
)» 10 ).	0x0000003a0000-0x00 0x0000003c0000-0x00 0x0000003d0000-0x00 0x0000003e0000-0x00 0x0000003f0000-0x00	00003c0000 : "language" 00003d00000 : "pot" 00003e00000 : "traffic_meter" 00003f00000 : "config" 00004000000 : "art"	128kB 64kB 64kB 64kB 64kB 64kB
	0x000000040000-0x00 BusyBox version:	00003a0000 : "firmware" BusyBox v1.4.2 (2013-11-12 17:4	3456kB 11:20 CST

21

### **Dump Firmware via U-Boot**

**Command** md (memory display) can be used to display memory areas ullet(including Flash where firmware is stored)

etnø, etni				
Hit any key to sto				
ar7240> md 9F11000				
9f110000: 68737173	5d040000 96f98152	00000200	hsqs]R	
9f110010: 29000000	02001100 c0000100	04000000	)	
9f110020: c60f2c1e			User Handal . (	
9f110030: add52800	00000000 fffffff	fffffff	(	
9f110040: b67b2800	00000000 b89d2800	00000000	.{((	
9f110050: 3bcd2800			;.((	
9f110060: 6d000000	01003f91 45846008	463f70a4	<pre>IGm.SOULO?TECTOF?p.</pre>	
9f110070: f09e899e	91daf065 02758f95	d7fa5ac6	Z.	
9f110080: 5ce06db2	e3b714b6 686a0b98	18f10208	\.mhj	
9f110090: f66471d4	1c0b9602 70540128	78895ef6	.dqpT.(x.^.	
9f1100a0: 656557e0	79c96e7d fd3241d4	c3031f70	eeW.y.n}.2Ap	
9f1100b0: 1c8bb84d	8f06b7eb f9de6d11	86ae3b71	Mm;q	
9f1100c0: ff6222cf	6c156374 1f892999	2a09f502	.b".l.ct).*	
9f1100d0: 8037cda9	d87c6bfe 5f8b80f1	8d55a9ca	Op.7 alio [kl.]asoriUlion	
9f1100e0: e901a687	f04d476f 80c3be0a	6dc65fbd	MGom	

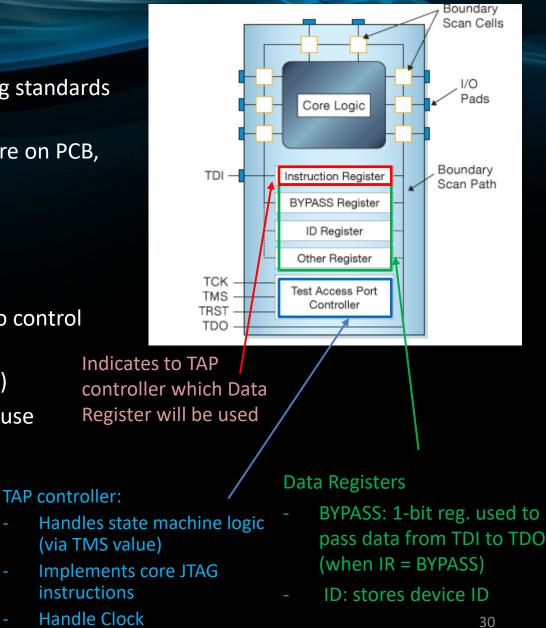
- Dump Firmware:
  - Full Flash dump (4MB) can be done with command: 1. md.b 9F000000 0x400000
  - Record all outputs to file. Wait... 2.
  - Convert full hexdump to binary (https://github.com/gmbnomis/uboot-3. mdb-dump



# JTAG (IEEE 1149.1)

- One of most widely deployed debug standards for embedded devices
- Provides direct interface to hardware on PCB, such as Flash or RAM
- JTAG Pins:
  - TDI: Data In
  - TDO: Data Out
  - TMS: Test Mode Select (used to control state of TAP controller)
  - TCK: Clock (for synchronization)
  - TRST: Test Reset (optional because possible to reset using TMS)

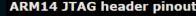
https://www.optiv.com/explore-optivinsights/downloads/jtag-interfaceattackers-perspective

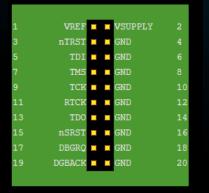


### **JTAG Pins Identification – Standards Pinouts**

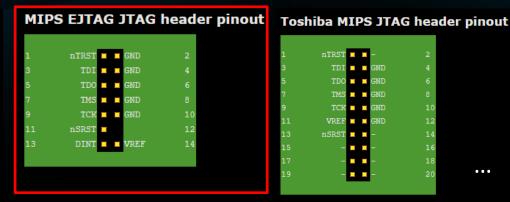
Some standard pinouts are known: http://www.jtagtest.com/pinouts/  $\bullet$ 

#### ARM JTAG header pinout ARM14 JTAG header pinout



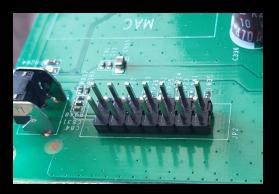


	114 31	-	Incauc	, hui
	VREF		GND	2
	nTRST		GND	4
	TDI		GND	6
	TMS		GND	8
	TCK		GND	10
11	TDO		nSRST	12
13	VREF		GND	14



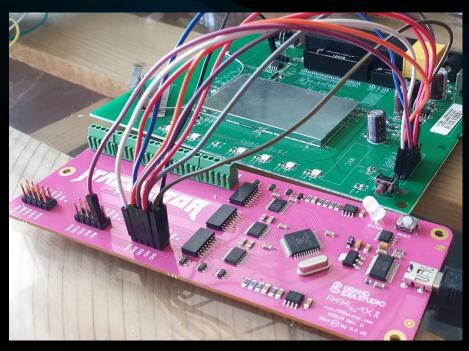
#### Good candidate for following reasons:

- Same number of pins
- Same position of GND (continuity test with multimeter)
- **Device architecture is MIPS**



For further tests on this interface, we solder Pin  $\bullet$ headers to be able to connect with jump wires

### JTAG Pins Identification – JTAGulator



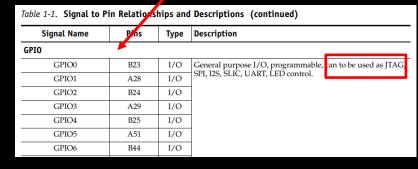
Author's demo: https://www.youtube.com/watch?v=GgMOBhmEJXA

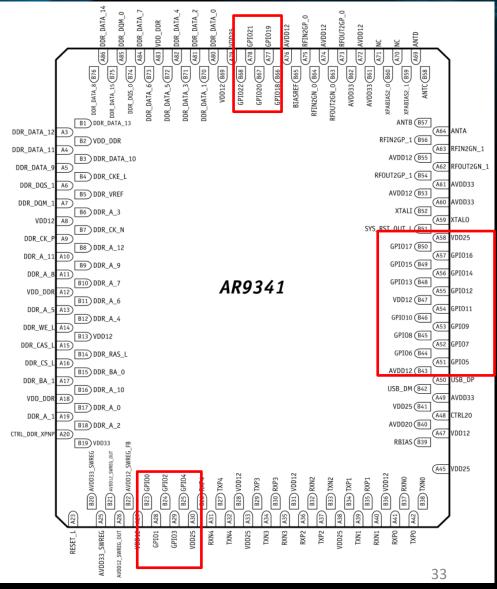
- 1. Connect GND -> GND
- 2. Connect CH0..CHX -> Pins to test on PCB
- 3. Connect to JTAGulator (baud rate 115200)
- 4. Set target voltage (here 3.3V)
- 5. Run IDCODE scan (fast) to detect:
  - TDO
  - ТСК
  - TMS
- 6. Run BYPASS scan (slow) to detect remaining TDI pin

# But here: FAIL 🛞 No JTAG pins found on this interface !

# Advanced JTAG Research (1/2)

- Finding JTAG may require analyzing PCB traces:
  - 1. Check Micro-Controller pinouts from datasheet
  - 2. Identify pins that can be used for JTAG
  - Follow traces from those pins (visual inspection + continuity test with multimeter)
- Here we see that GPIO tagged pins can be used for JTAG (but also many other stuff)





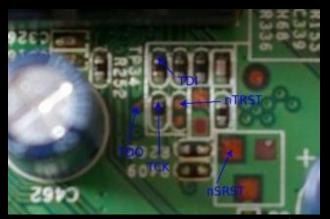
# Advanced JTAG Research (2/2)

- Micro-Controller is under EMC shield
- Analysis of PCB traces from GPIO pins:





- Here I could not find JTAG on this
   PCB
- Maybe it has been disabled (often the case in production)
- JTAG can be very tricky to find => Example on previous version of router (WNR2000v1):



https://openwrt.org/toh/netgear/wn<sup>34</sup>2000

### **Testing on Device with known JTAG**

- For experimentation purpose: Proxmark3's PCB has a known JTAG interface
- Let's find out JTAG pinout as if it was not available

				UU	LLL					
- 333 -	TTTTT	TT AAAAA	GGGGGGGGGGG	G UUUU	r <b>LLL</b> bin	AAAAA T	TTTTT	T 00000	00 RRRRRRRR	
ננננ	TTTTT	ΤΤ ΑΑΑΑΑΑ	GGGGGGG	UUUU	LLL A	ΑΑΑΑΑ Τ	TTTTT	T 00000	00 RRRRRRRR	
3333	TTTT	AAAAAAA	GGG (	UUUU UUUU	LLL	AAA AAA	TTT	0000 0	00 RRR RRR	
7777	TTTT	AAA AAA	GGG GGG (	UUUU UUUU	LLL AA	AAA AAA	TTT	000 0	00 RRRRRRR	
3333	TTTT	AAA AA	GGGGGGGGG	υυυυυυυ	LLLLL	LLL AAAA	n d <b>itit</b> iti	0000000	00 RRR RRR	
333	TTTT	AAA AA	GGGGGGGGG	υυυυυυυυ	LLLLL	LLLL AAA	nc.TTT <sup>o</sup>	0000000	00 - RRR - RRR	
777	TT		GGG		https <b>AA</b> A	<b>∖</b> rvices.fra			RR RRR	
333			GG		https <b>AA</b> s				RRR	
כננ									Control Sitte mark	

Welcome to JTAGulator. Press 'H' for available commands.

#### JTAG Commands:

- I Identify JTAG pinout (IDCODE Scan)
- B Identify JTAG pinout (BYPASS Scan)
- D Get Device ID(s)
- T Test BYPASS (TDI to TDO)

UART Commands:

- U Identify UART pinout
- P UART passthrough

General Commands:

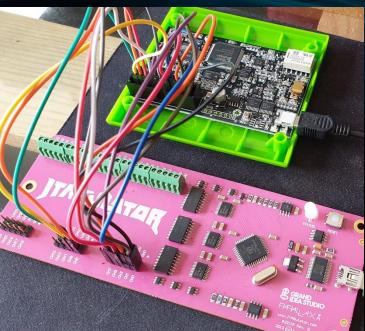
- V Set target I/O voltage (1.2V to 3.3V)
  <u>R Read all channels (input)</u>
- W Write all channels (output)
- J Display version information
- H Display available commands

Current target I/O voltage: Undefined Enter new target I/O voltage (1.2 - 3.3, 0 for off): 3.3 New target I/O voltage set: 3.3 Ensure VADJ is NOT connected to target!

#### I Enton number of channels to use (2 - 24); ff

Ensure connections are on CHOB.CHO. Possible permutations: 990 Press spacebar to begin (any other key to abort)... JTAGulating! Press any key to abort..... TOI: N/A TOD: 3 TCK: 5 TMS: 6 ...... IDCODE scan complete! :B Enter number of channels to use (4 - 24): 11 Ensure connections are on CH10..CH0. Possible permutations: 7920 Press spacebar to begin (any other key to abort)... JTAGulating! Press any key to abort..... TDI: 7 TDO: 3 TCK: 5 TMS: 6 Number of devices detected: 1

BYPASS scan complete!



#### :T Enter new TDI pin [0]: 7 Enter new TDO pin [0]: 3 Enter new TCK pin [0]: 5 Enter new TMS pin [0]: 6 Enter number of devices

#### Testing

Enter new IMS pin [0]: 6 Enter number of devices in JTAG chain [0]: 1 All other channels set to output HIGH.

Pattern in to TDI: 0110011100010101111010010011000 Pattern out from TDO: 01100111000101011110110010011000 Match!

TDI not needed to retrieve Device ID. Enter new TDO pin [3]: Enter new TCK pin [5]: Enter new TMS pin [6]: Enter number of devices in JTAG chain [1]: All other channels set to output HIGH.

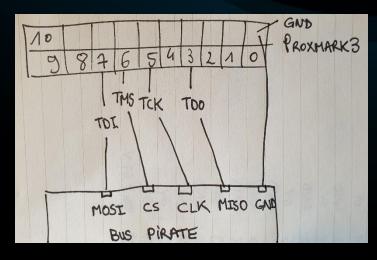
Device ID: 0011 1111000011110000 11110000111 1 (0×3F0F0F0F) → Manufacturer ID: 0×787 → Part Number: 0×F0F0 → Version: 0×3

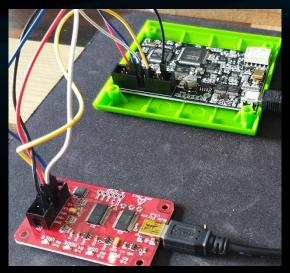
IDCODE listing complete!

#### 35

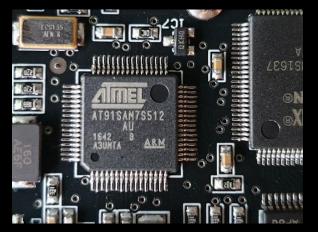
## Dumping Firmware via JTAG (1/3)

1. Based on discovered JTAG pinout, connect Bus Pirate as follows:





2. Identify Micro-Controller on PCB. On Proxmark3 => AT91SAM7S512 (ARM)



3. Search for OpenOCD's configuration for this Micro-Controller

jbr@hackbox:/usr/s				
at91sam7a2.cfg	at91sam7se512.cfg	at91sam7sx.cfg	at91sam7×256.cfg	at91sam7×512.cfg

# **Dumping Firmware via JTAG (2/3)**

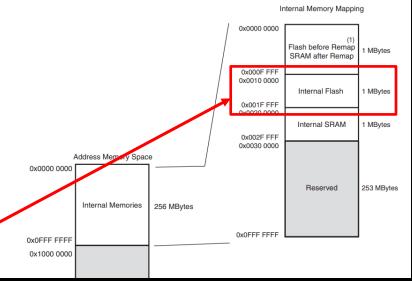
#### 4. Run OpenOCD with config for Bus Pirate + config for Micro-Controller:

rootwhackbox./home/jbr/Projet-weigear# root@hackbox:/home/jbr/Projet-Netgear# openocd -f ./buspirate.cfg -f /usr/share/openocd/scripts/target/at91sam7×512.cfg Open On-Chip Debugger 0.10.0+dev-snapshot (2020-08-19-07:12) Licensed under GNU GPL v2 For bug reports, read http://openocd.org/doc/doxygen/bugs.html srst only separate srst gates jtag srst open drain connect deassert srst Info : auto-selecting first available session transport "jtag". To override use 'transport select <transport>'. Info : Listening on port 6666 for tcl connections Info : Listening on port 4444 for telnet connections Info : Buspirate JTAG Interface ready! Info : This adapter doesn't support configurable speed Info : JTAG tap: sam7×512.cpu tap/device found: 0×3f0f0f0f (mfg: 0×787 (<unknown>), part: 0×f0f0, ver: 0×3) Info : Embedded ICE version 1 Info : sam7×512.cpu: hardware has 2 breakpoint/watchpoint units Info : starting gdb server for sam7×512.cpu on 3333 Info : Listening on port 3333 for gdb connections

 We need to know which memory region we want to dump ?
 Proxmark3 has no external Flash, and the firmware is directly stored on MCU (no OS, no filesystem like on our router)

=> Check MCU datasheet for Memory Mapping

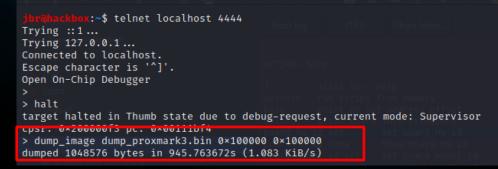
Internal Flash mapped at: 0x100000-0x1FFFFF (size=0x100000 bytes)



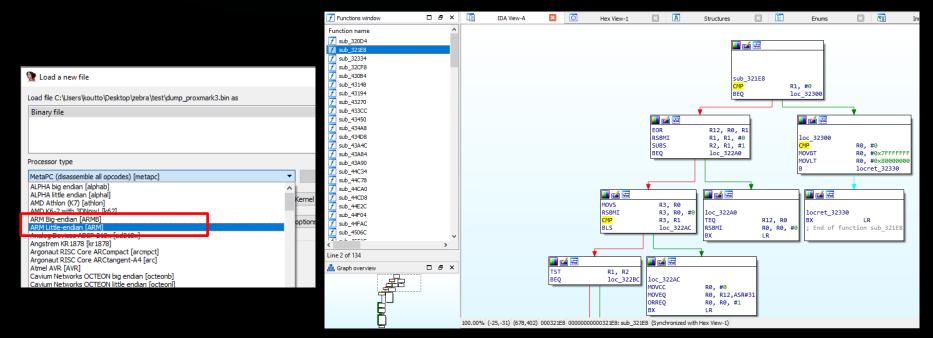
#### Figure 8-1. SAM SAM7S512/256/128/64/321/32/161/16 Memory Mapping

# Dumping Firmware via JTAG (3/3)

#### 6. Connect to localhost:4444 and run dump image with correct offset & size:

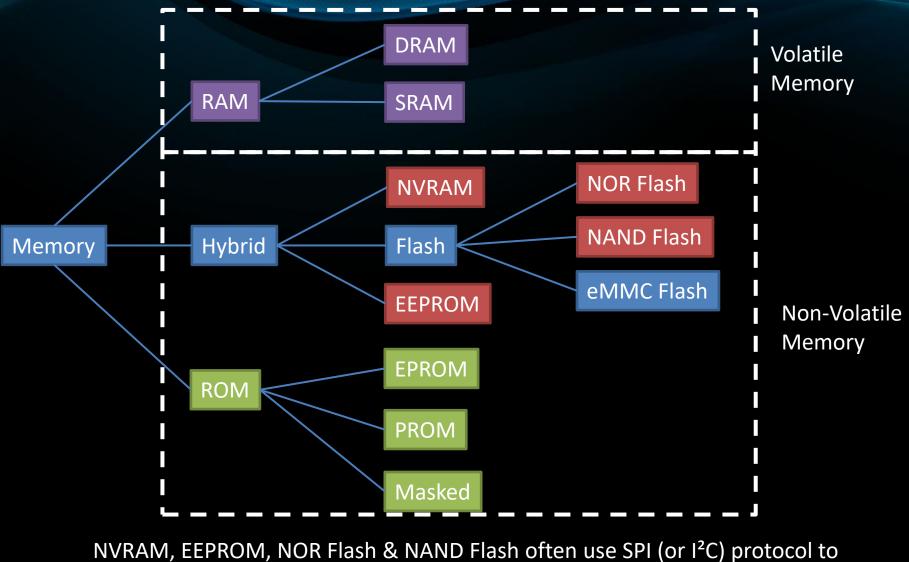


#### 7. Dump contains firmware's ARM code. It is possible to open it with IDA:



6> SPI FLASH

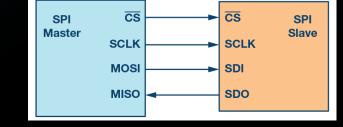
### **Memory Types**



NVRAM, EEPROM, NOR Flash & NAND Flash often use SPI (or I<sup>2</sup>C) protocol t communicate with Micro-Controller

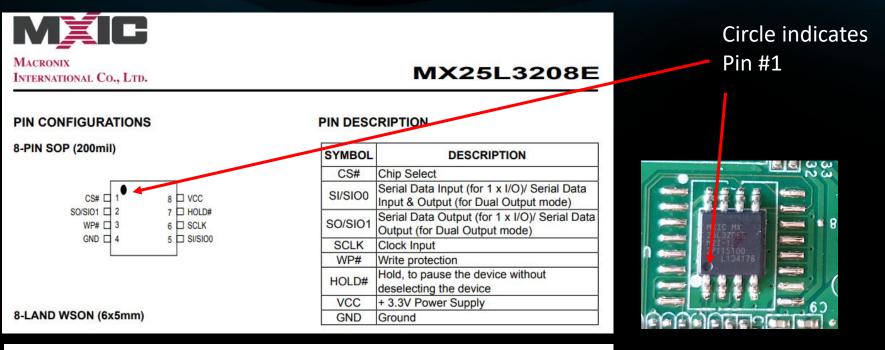
# **SPI (Serial Peripheral Interface) Protocol**

- Synchronous (requires clock) serial communication
- Designed for inter-components communication (hi speed)
- 1 Master (Micro-Controller) / Multiple Slaves (eg. Flash)
- SPI Pins:
  - MISO: Master In Slave Out (Master <- Slave)</li>
  - MOSI: Master Out Slave In (Master -> Slave)
  - SCLK: Clock
  - CS: Chip Select . Required to select 1 Slave among others for any action.
     CS put to 0 when chip selected
- Non-standard Pin names are also used. From Slave point-of-view:
  - SDI / DI / DIN / SI: Data In. Connect to MOSI on Master
  - SDO / DO / DOUT / SO: Data Out. Connect to MISO on Master



# **Identify SPI Flash**

• Refer to Flash datasheet to find SPI compatibility & pinout:



#### GENERAL DESCRIPTION

The device feature a serial peripheral interface and software protocol allowing operation on a simple 3-wire bus. The three bus signals are a clock input (SCLK), a serial data input (SI), and a serial data output (SO). Serial access to the device is enabled by CS# input.

When it is in Dual Output read mode, the SI and SO pins become SIO0 and SIO1 pins for data output.

#### https://pdf1.alldatasheet.com/datasheet-pdf/view/575458/MCNIX/MX25L3208EM2I12G.html

Serial NOR Flash

# **Check SPI Pins with Logic Analyzer**

• Connect to the Flash using a SOIC/SOP 8-Pin chip clip with Logic Analyzer

<image>

Red cable corresponds to Pin #1

#### Data emitted/received

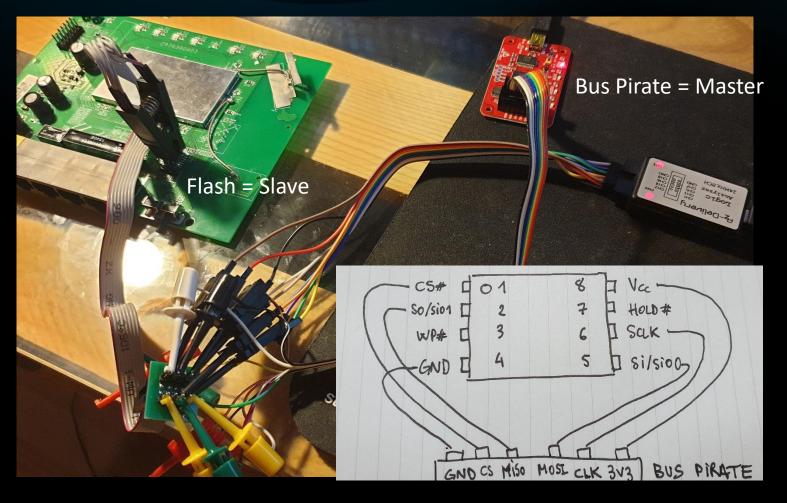
CS (Chip Select) drops to 0 when communication begins

Saleae Logic 1 2.18 - [Connected] - [24,00 MHz Digit									Hz Digital, 5,0	00 s]						
	Otor				0 s : 414 ms : 500 μs								0 s : 414			
	Star	τ		•					+40				+70 μs	+80 µs		
	CS		<b>\$</b> +	-Ŧ					1							
	MISO		<b>Þ</b> 1	-F								239'	ת ביתר		'255'	'141'
	SCLK SPI - CLOCK		<b>¢</b> [+	- <del>-</del> -					┨┨┨┎	AAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAAA			᠋᠇᠇᠇᠇	AAAAAAA	$\{1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,1,$	$\left  \left\{ \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} = \left\{ \left\{ \left\{ \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} = \left\{ \left\{ \left\{ \left\{ \left\{ \left\{ \left\{ \left\{ \right\} \right\} \right\} \right\} \right\} = \left\{ $
	MOSI		¢ +	- <b>F</b>	10'	'0'	0				1'			92'	'0'	'0'
				-												
	Channel 4		<b>\$</b> ]+	-F]												
	Channel 5		<b>\$</b> ]+	-F)												

# Dump SPI Flash – First try... (1/2)

Now we are sure of Flash pinout, let's try to dump it using Bus Pirate:

1. Connect Bus Pirate as follows:



# Dump SPI Flash – First try... (2/2)

2. Check for Flash support in flashrom: https://flashrom.org/Supported hardware

Macronix MX25L3206E/MX25L3208E

4096 SPI OK OK OK 0K 2.700 3.600

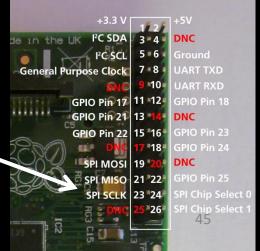
#### 3. Run flashrom, it should auto-detect the Flash (Warning: device powered OFF):

root@hackbox:/home/jbr/Projet-Netgear# flashrom -p buspirate\_spi:dev=/dev/ttyUSB0 flashrom v1.2 on Linux 5.4.0-kali4-amd64 (x86\_64) flashrom is free software, get the source code at https://flashrom.org

Using clock\_gettime for delay loops (clk\_id: 1, resolution: 1ns). Bus Pirate firmware 6.1 and older does not support SPI speeds above 2 MHz. Limiting speed to 2 MHz. It is recommended to upgrade to firmware 6.2 or newer. No EEPROM/flash device found. Note: flashrom can never write if the flash chip isn't found automatically.

- 4. Try to find cause of fail:
  - "Sniff" communication with Logic Analyzer
  - Also, test with Raspberry Pi as SPI Interface

=> Unfortunately, seems like there are interferences with other components on the board

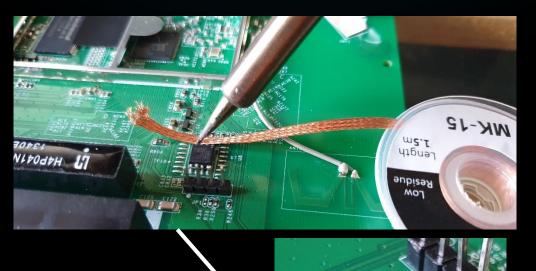




# Let's get serious

# **Removing Flash from PCB**

- When everything else has failed => Desolder chip from PCB
- Very invasive, can be very hard to solder it back !! => Possible PCB destruction !
- Recommended tool: Hot air gun
- I don't have one, let's do it the dirty way <sup>(2)</sup>



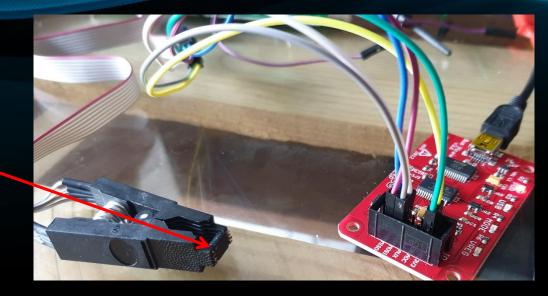




# **Dump SPI Flash – Second try**

1. Connect to Bus Pirate again:

Flash is in the clip



#### 2. Run flashrom again:

root@hackbox:/home/jbr/Projet-Netgear# flashrom -p buspirate\_spi:dev=/dev/ttyUSB0
flashrom v1.2 on Linux 5.4.0-kali4-amd64 (x86\_64)
flashrom is free software, get the source code at https://flashrom.org

Using clock\_gettime for delay loops (clk\_id: 1, resolution: 1ns). Bus Pirate firmware 6.1 and older does not support SPI speeds above 2 MHz. Limiting speed to 2 MHz. It is recommended to upgrade to firmware 6.2 or newer. Found Macronix flash chip "MX25L3206E/MX25L3208E" (4096 kB, SPI) on buspirate\_spi. Matching correct Flash

#### 3. Dump Flash memory content:

root@hackbox:/home/jbr/Projet-Netgear# flashrom -p buspirate\_spi:dev=/dev/ttyUSB0,spispeed=1M -c "MX25L3206E/MX25L3208E" -r dump.bin flashrom v1.2 on Linux 5.4.0-kali4-amd54 (x26\_64) flashrom is free software, get the source code at https://flashrom.org

Using clock gettime for delay loops (clk id: 1, resolution: 1ns). Found Macronix flash chip "MX25L3206E/MX25L3208E" (4096 kB, SPI) on buspirate\_spi. Reading flash... done. root@hackbox:/home/jbr/Projet-Netgear#

# **7> FIRMWARE ANALYSIS**

### **Root Filesystem Extraction**

#### • Automatic Filesystem extraction with binwalk:

jbr@hackbox:		<pre>\$ binwalk -e flashdump.bin ashfs version 4.0 (2009/01/31) http://doi.org/10.0000</pre>
DECIMAL	HEXADECIMAL	DESCRIPTION 00000000-0x000000000000000000000000000
134816 150864 151232 160905 262208 1114112	0×20EA0 0×24D50 0×24EC0 0×27489 0×40040 0×110000	Certificate in DER format (x509 v3), header length: 4, sequence length: 64 U-Boot version string, "U-Boot 1.1.4 (Nov 26 2012 - 15:58:42)" CRC32 polynomial table, big endian Copyright string: "copyright." LZMA compressed data, properties: 0×6D, dictionary size: 8388608 bytes, uncompressed size: 2465316 bytes Squashfs filesystem, little endian, version 4.0, compression:lzma, size: 2676149 bytes, 1117 inodes, blocksize: 131072 bytes,
3801092	0×3A0004	POSIX tar archive (GNU), owner user name: "_table.tar.gz"

jbr@hackbox:

/\_flashdump.bin.extracted\$ cd squashfs-root/ /\_flashdump.bin.extracted/squashfs-root\$ ll

total 96K								
drwxr-xr-x	16	jbr	jbr	4,0K	nov.	12	2013	
drwxr-xr-x	3	jbr	jbr	4,0K	sept.	20	16:58	
drwxr-xr-x	2	jbr	jbr	4,0K	nov.	12	2013	bin
-rw-rr	1	jbr	jbr	11	nov.	12	2013	default_language_version
drwxr-xr-x	2	jbr	jbr	4,0K	nov.	12	2013	dev
drwxr-xr-x	15	jbr	jbr	4,0K	nov.	12	2013	etc
-rw-rr	1	jbr	jbr	1	nov.	12	2013	firmware_region
-rw-rr	1	jbr	jbr	10	nov.	12	2013	firmware_version
-rw-rr	1	jbr	jbr	10	nov.	12	2013	hardware_version
drwxr-xr-x	2	jbr	jbr	4,0K	nov.	12	2013	jffs
drwxr-xr-x	8	jbr	jbr	4,0K	nov.	12	2013	lib
drwxr-xr-x	2	jbr	jbr	4,0K	nov.	12	2013	mnt
-rw-rr	1	jbr	jbr	10	nov.	12	2013	module_name
drwxr-xr-x	2	jbr	jbr	4,0K	nov.	12	2013	proc
drwxr-xr-x	2	jbr	jbr	4,0K	nov.	12	2013	rom
drwxr-xr-x								
drwxr-xr-x	2	jbr	jbr	4,0K	nov.	12	2013	sbin
drwxr-xr-x	2	jbr	jbr	4,0K	nov.	12	2013	sys
drwxrwxrwx	2	jbr	jbr	4,0K	nov.	12	2013	tmp
drwxr-xr-x	7	jbr	jbr	4,0K	nov.	12	2013	usr
lrwxrwxrwx	1	jbr	jbr	4	sept.	20	16:58	$var \rightarrow /tmp$
drwxr-xr-x	8	jbr	jbr	16K	nov.	12	2013	www



Config

**Flash Content** 

#### **Firmware Analysis**

- Static Analysis:
  - Explore filesystem: Search for interesting files, configurations... (firmwalker)
  - Check various scripts
  - Binary analysis (IDA)
- Dynamic Analysis:
  - Emulate firmware with firmadyne tool (<u>https://github.com/firmadyne/firmadyne</u>)
     + QEMU (support for MIPS & ARM)
  - Binary exploitation often easier because usually less defense mechanisms (ASLR, NX...) on embedded devices



At this step, we deal with stuff we are more familiar with !