### Efficient Approximations for Cache-Conscious Data Placement

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- $\blacktriangleright$  Given a sequence  $\Sigma$  of accesses, our goal is to minimize cache misses over  $\Sigma$

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▶ We have n objects (data items)  $O = \{o_1, o_2, \ldots, o_n\}$  and a sequence  $\Sigma \in O^N$  of accesses to these items

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- We analyze the runtime based on n and N and assume that t and k are small constants

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For a cache with more than two lines, CDP is not only NP-hard, but also hard to approximate within any non-trivial factor  $O(N^{1-\epsilon})$  unless P=NP

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This is a very strong hardness result and it holds for the simple cache structure in CDP

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All following works are heuristics with no guarantees

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- Stronger hardness results
  - Both approximation and parameterization (sparsity) are needed at the same time

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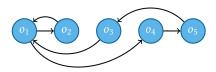
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- Experimental Results
  - Not practical
    - Only applicable to small caches with a handful of lines
    - Due to exponential dependence on k
  - On these small caches, our approach beats the heuristics in 84-88% of the cases

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# Access Graphs



$$\Sigma = \langle o_1, o_2, o_1, o_4, o_5, o_3, o_3, o_1, o_2 \rangle$$

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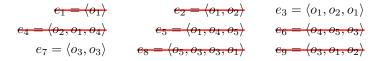
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$$e_{1} = \langle o_{1} \rangle \qquad e_{2} = \langle o_{1}, o_{2} \rangle \qquad e_{3} = \langle o_{1}, o_{2}, o_{1} \rangle$$
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# Approximation Theorem

#### Theorem

For any  $\epsilon > 0$ , by applying the approach above using the sparsified access hypergraph  $\tilde{G}_{d_{\epsilon}}$  of order  $d_{\epsilon} := \lceil t \cdot k + \frac{t \cdot k}{\epsilon} \rceil$ , we obtain a  $(1 + \epsilon)$ -approximation of the optimal number of cache misses in a direct-mapped cache, i.e.  $\operatorname{Misses}_{k}(\hat{f}, \Sigma) \leq (1 + \epsilon) \cdot \operatorname{Misses}_{k}(f^{*}, \Sigma)$ .

• Every edge in our hypergraph starts and ends with the same vertex

$$\begin{array}{ccc} e_1 = \langle o_1 \rangle & e_2 = \langle o_1, o_2 \rangle & e_3 = \langle o_1, o_2, o_1 \rangle \\ e_4 = \langle o_2, o_1, o_4 \rangle & e_5 = \langle o_1, o_4, o_5 \rangle & e_6 = \langle o_4, o_5, o_3 \rangle \\ e_7 = \langle o_3, o_3 \rangle & e_8 = \langle o_5, o_3, o_3, o_1 \rangle & e_9 = \langle o_3, o_1, o_2 \rangle \end{array}$$

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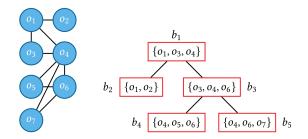
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- ▶ NP-hard Problem: Find a coloring that minimizes missed edges.

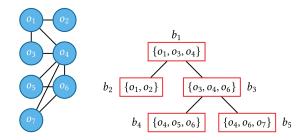
# Treewidth-based Dynamic Programming



We assume our sparsified access graphs have small treewidth
In reality, they do [Chatterjee et al, POPL 2019]

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Do a linear-time bottom-up dynamic programming as if you are coloring a tree

 $dp[b_i, partial coloring c] =$ 

minimum number of missed edges in the subtree of  $b_i$ 

if we color the vertices in  $b_i$  according to c

# Conclusion

- CDP is really hard, even when the sequence of accesses is given apriori
- It is not as hard as previously thought since real-world instances are sparse
- ▶ The sparsity (tree-likeness) can be exploited to obtain  $(1 + \epsilon)$ -approximations for any  $\epsilon > 0$
- CDP requires both approximation and parameterization (by the treewidth of access graphs) to become tractable
- We provided the first positive theoretical result for CDP but there is still a long way until it becomes practical
- The current algorithm can be used for limit studies and comparison of heuristics