

# Simple Analysis of Priority Sampling

New York University, Majid Daliri

January 9, 2024

## Collaboration

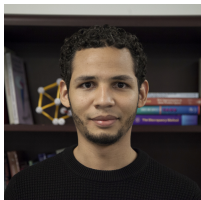
This project was a joint effort by the following individuals:



Prof. Juliana Freire  
New York University



Prof. Christopher Musco  
New York University



Aécio Santos  
New York University



Haoxiang Zhang  
New York University

# Motivation: Priority Sampling Problem

## Problem Overview

Consider a set of items, labeled from 1 to  $n$ , with each item  $i$  having an associated **positive** weight  $w_i$ .

## Specific Query

Given a subset  $\mathbf{Q}$  of  $\{1, 2, \dots, n\}$ , the query asks: *"What is the total sum of weights in  $\mathbf{w}$  corresponding to the elements in  $\mathbf{Q}$ ?"*

$$\sum_{i=1}^n w_i \cdot \mathbb{1}[i \in \mathbf{Q}]$$

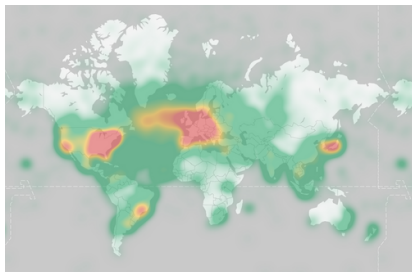
## Significance

This problem is fundamental in data analysis, where efficient and accurate estimations of such sums are crucial, especially in large datasets.

# Motivating Example: Website Traffic Analysis

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## Analysis Goals

- ▶ Users are labeled as items 1 to  $n$ .
- ▶ Let  $w_i$  represent the number of visits by user  $i$ .
- ▶ The goal is to compute the total number of visits to the website from users in Washington D.C.
- ▶ Define  $Q$  as the set of users  $i$  who are located in Washington D.C.
- ▶  $\sum_{i=1}^n w_i \cdot \mathbb{1}[i \in Q]$

# Sampling

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## Sampling Strategy

This approach assigns each item a sampling ratio of  $p_i$  and samples each item  $i$  with probability  $p_i$ .

$$\sum_{i=1}^n p_i \approx k$$

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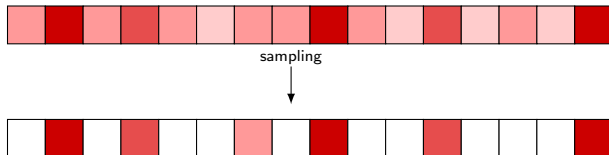
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$$\sum_{i=1}^n p_i \approx k$$

To achieve more accurate sampling, items with higher weight should be sampled with a higher probability.





## Formal Objectives for Effective Sampling

$$\hat{w}_i = \begin{cases} \frac{w_i}{p_i} & \text{sampled with probability } p_i, \\ 0 & \text{otherwise} \end{cases}.$$

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$$\mathbb{E} \left[ \sum_{i=1}^n \hat{w}_i \cdot \mathbb{1}[i \in Q] \right] = \sum_{i=1}^n w_i \cdot \mathbb{1}[i \in Q]$$

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In our ideal case, to minimize the variance of the estimator when sampling  $k$  items, if  $\sum p_i = k$ , we aim to minimize

$$\min_{p_1, \dots, p_n} \text{Var} \left[ \sum_{i=1}^n \hat{w}_i \cdot \mathbb{1}[i \in Q] \right]$$

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Given that  $Q$  is unknown at the time of building the data structure and we cannot speculate about the query, our goal is to minimize

$$\min_{p_1, \dots, p_n} \sum_{i=1}^n \text{Var}[\hat{w}_i]$$

# Threshold Sampling: Sampling WOR

## Sampling Criterion

Consider a hashing function  $h : \{1, 2, \dots, n\} \rightarrow (0, 1]$ .

An item  $i$  is sampled if:

$$\frac{h_i}{w_i} < \tau \Rightarrow i \in \mathcal{S}$$

where  $h_i$  is the hash value of item  $i$ ,  $w_i$  is its weight, and  $\tau$  is a predefined threshold.

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## Probability of Sampling an item

The probability of sampling an item in this context is determined by the condition:

$$p_i = \min(1, \tau w_i)$$



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## Setting the Threshold

Setting the threshold  $\tau$  as  $\frac{k}{\sum w_i}$ , where  $k$  is a constant, results of sampling  $k$  items in the **expectation**.

$$\sum_{i=1}^n p_i = k$$

# Threshold Sampling: Answer Queries

## Definition of Estimated Weight

We define

$$\hat{w}_i = \begin{cases} \frac{w_i}{\min(1, w_i \tau)} & i \in \mathcal{S} \\ 0 & i \notin \mathcal{S} \end{cases}.$$

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## Query Answer

$$\sum_{i=1}^n \hat{w}_i \cdot \mathbb{1}[i \in Q]$$

# Threshold Sampling: Variance Bound

## Theorem (Variance Bound)

$$\text{Var} [\hat{w}_i] \leq \frac{w_i}{\tau} = w_i \cdot \frac{W}{k}$$

Where  $W = \sum_{i=1}^n w_i$

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## Estimator Variance Objective

$$\sum_{i=1}^n \text{Var}[\hat{w}_i] \leq \frac{W^2}{k}$$

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$$\sum_{i=1}^n \text{Var}[\hat{w}_i] \leq \frac{W^2}{k}$$

**This bound is optimal among all choices of probabilities.**

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where  $h_i$  is the hash value of item  $i$ ,  $w_i$  is its weight, and  $\tau$  is a predefined threshold.

## Main Disadvantage

There is no **deterministic** upper limit on the number of items that are sampled.

# Priority Sampling: Fixed-Size Sampling WOR

## Challenge

The key challenge in sampling without replacement lies in consistently achieving a fixed number of samples



# Priority Sampling : Fixed-Size Sampling WOR

## Literature

Significant contributions in this area include:

- ▶ Introduction of Priority Sampling [Duffield, Lund, and Thorup, SIGMETRICS 2004]
- ▶ Upper Bound on Variance [Alon, Duffield, Lund, and Thorup, PODS 2005]
- ▶ Tight Upper Bound on Variance [Szegedy, STOC 2006]

## Tight Variance Bound

$$\text{Var} [\hat{w}_i] \leq w_i \cdot \frac{W}{k-1}$$

Where  $W = \sum_{i=1}^n w_i$

Our Contribution

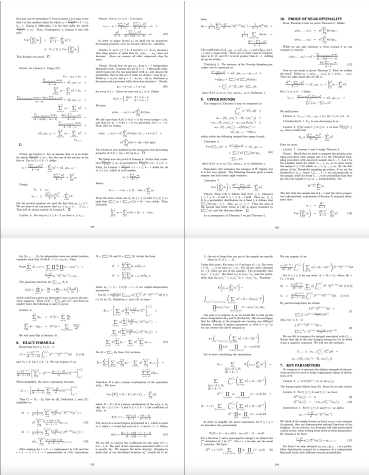


Figure: "The DLT priority sampling is essentially optimal", Szegedy, STOC 2006



Figure: Our Paper, SOSA 2024

# Priority Sampling

## Sampling Criterion

Consider a hashing function  $h : \{1, 2, \dots, n\} \rightarrow (0, 1]$ .

define  $\tau$  as  $(k + 1)^{\text{th}}$  smallest  $\frac{h_i}{w_i}$ .

An item  $i$  is sampled if:

$$\frac{h_i}{w_i} < \tau \Rightarrow i \in \mathcal{S}$$

where  $h_i$  is the hash value of item  $i$ ,  $w_i$  is its weight.

## Key Difference from Threshold Sampling

Priority Sampling is similar to Threshold Sampling, but with a crucial difference: the threshold  $\tau$  is adaptively chosen as the  $(k + 1)^{\text{st}}$  smallest  $\frac{h_i}{w_i}$ .

# Priority Sampling: Fixed-Size Sampling WOR

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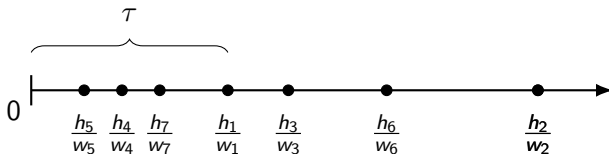


Figure: Illustration of Selecting  $\tau$  for  $k = 3$  in a Set of  $n = 7$  Elements

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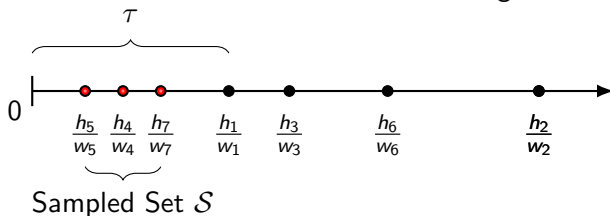


Figure: Illustration of the Sampling Process for Selected Elements

# Priority Sampling: Answer Queries

## Definition of Estimated Weight

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Fact (Expected Value)

$$\mathbb{E}[\hat{w}_i] = w_i$$

Fact (Pairwise Uncorrelated)

$$\mathbb{E}[\hat{w}_i \cdot \hat{w}_j] = w_i \cdot w_j$$

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# Priority Sampling: Variance Bound Proof Structure

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Define  $\tau_i$  for each  $i$  as  $k^{\text{st}}$  smallest  $\frac{h_j}{w_j}$  for  $j \in \{1, 2, \dots, n\} - \{i\}$ .

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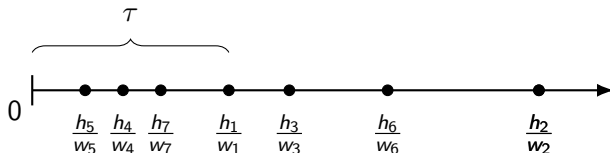


Figure: Illustration of Selecting  $\tau$  for  $k = 3$  in a Set of  $n = 7$  Elements

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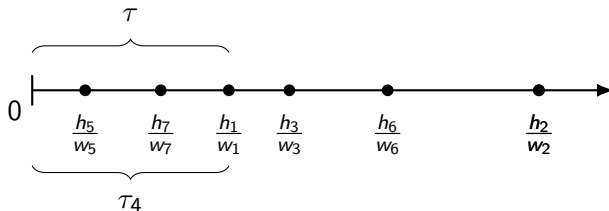


Figure: Illustration of Selecting  $\tau, \tau_4$  for  $k = 3$  in a Set of  $n = 7$  Elements

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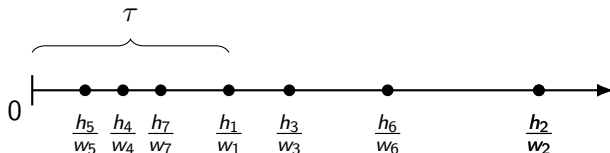


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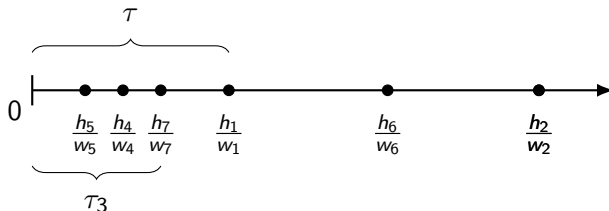


Figure: Illustration of Selecting  $\tau, \tau_3$  for  $k = 3$  in a Set of  $n = 7$  Elements

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## Lemma (Variance Bound of Estimated Weight)

$$\text{Var} [\hat{w}_i] \leq w_i \cdot \mathbb{E} \left[ \frac{1}{\tau_i} \right]$$



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## Lemma (Expected Inverse Threshold)

$$\mathbb{E}\left[\frac{1}{\tau_i}\right] \leq \frac{W}{k-1}$$

Where  $W = \sum_{i=1}^n w_i$

# Priority Sampling: Proof

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$$\Rightarrow \hat{W} \geq \sum_{i \in S} \frac{1}{\tau} = \frac{k}{\tau}$$

$$\Rightarrow \mathbb{E}[\hat{W}] \geq k \mathbb{E} \left[ \frac{1}{\tau} \right]$$

$$\Rightarrow W \geq k \mathbb{E} \left[ \frac{1}{\tau} \right] \Rightarrow \mathbb{E} \left[ \frac{1}{\tau} \right] \leq \frac{W}{k}$$



# Priority Sampling: Proof

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$$\Rightarrow \mathbb{E} \left[ \frac{1}{\tau_i} \right] \leq \frac{W - w_i}{k-1} \leq \frac{W}{k-1}$$

# Priority Sampling: Application

## Inner Product Sketch

Our study demonstrates that straightforward proof enables extending our method to inner product sketching. Our analysis shows priority sampling outperforms the Johnson-Lindenstrauss (JL) transform in reducing estimation error.

## Reference Paper :

**Title:** "Sampling Methods for Inner Product Sketching"

**Authors:** Majid Daliri, Juliana Freire, Christopher Musco, Aécio Santos, Haoxiang Zhang

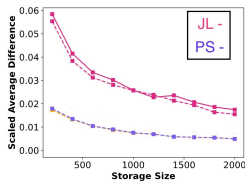


Figure: Experimental Results of JL vs Priority sampling

Questions?

Any Questions?