

# 2D Scene Relighting

Alexandre Dherse,  
Martin Everaert,  
Jakub Gwizdala

Supervised by  
Majed El Helou

May 2020



# Introduction and motivation of the problem

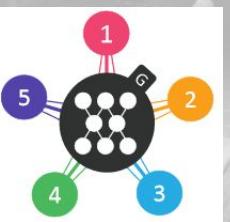
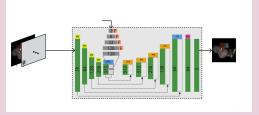
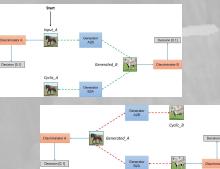
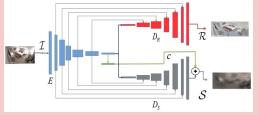
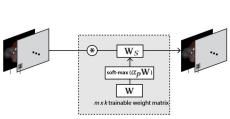
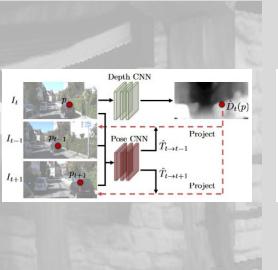
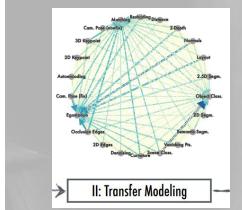
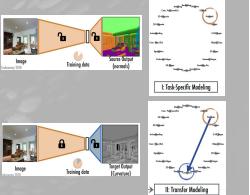
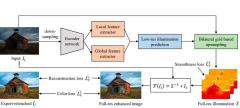
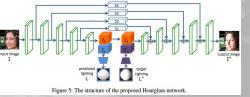
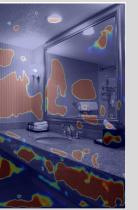
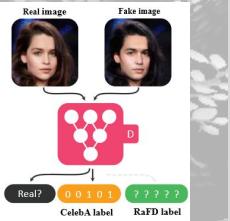
Transfer the illumination from one image to another.

Having a method for general relighting of images with varied content

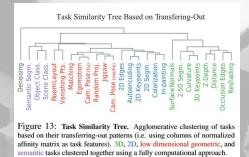
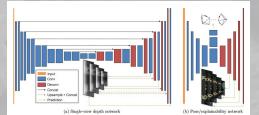
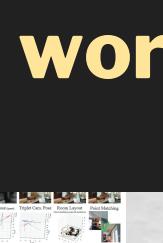


# Introduction and motivation of the problem

- **post-production tool** for images (videos) to change original lighting (aesthetic reasons or eliminating the need of light setup equipment)
- perform **data augmentation** before training a network, allowing a wider variety of images for training (e.g. eliminate illumination bias)



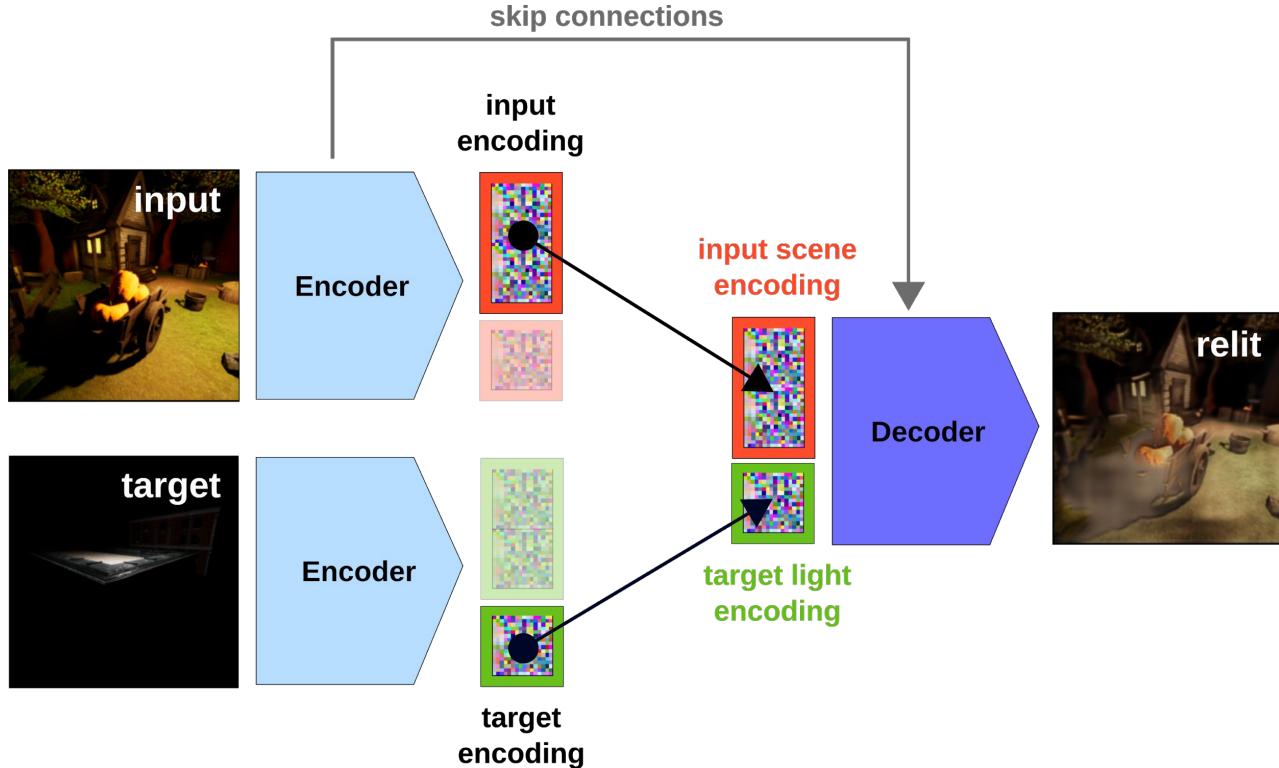
**Figure 2.** Skin through a multi-task learning approach



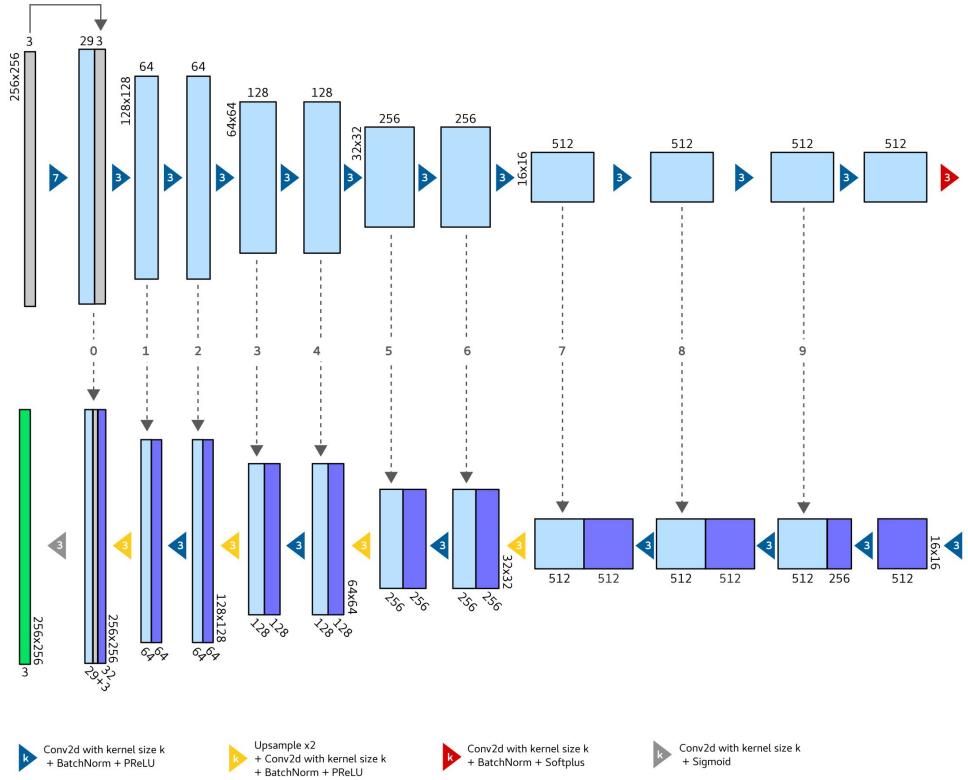
# Background and related works

(44, 228) (45, 305)

# Overall architecture scheme

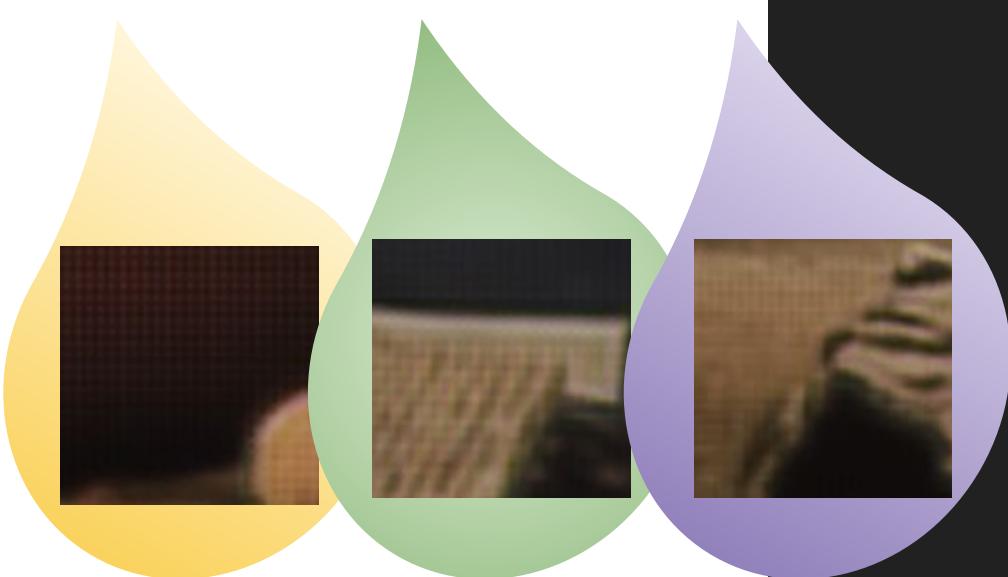


# Details of the solution @all



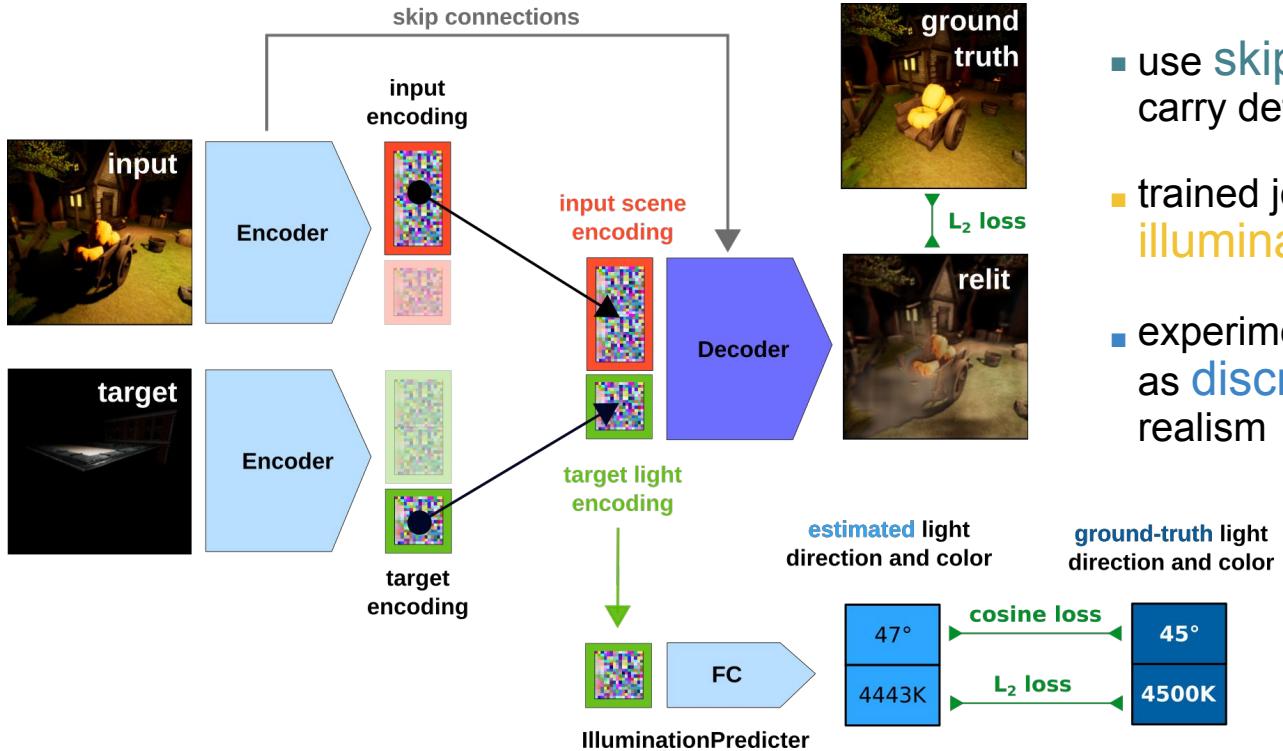
encoder

decoder



# Implementation detail: checkerboard artifacts

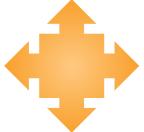
# Details of the solution @1



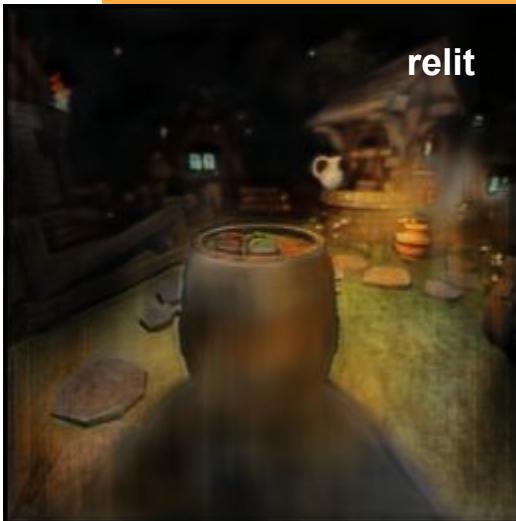
- split the latent variable into light and scene
- use **skip-links** from input to carry details
- trained jointly with an **illumination predictor**
- experiments with a PatchGAN as **discriminator** for more realism



input



target



relit



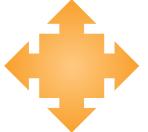
ground-truth

# Experimental results @1 (eval w/o discriminator)

 $L_2$  loss



input



target



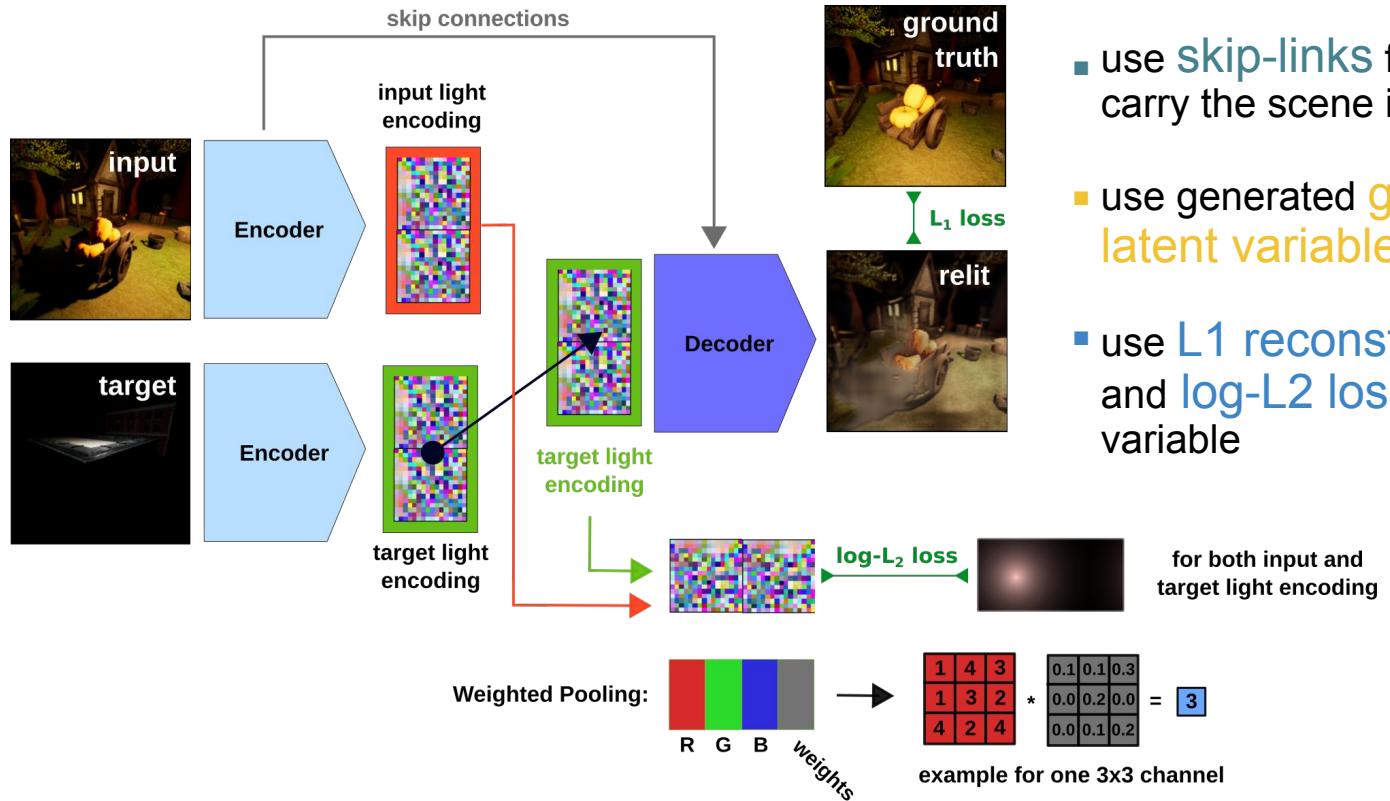
relit



ground-truth

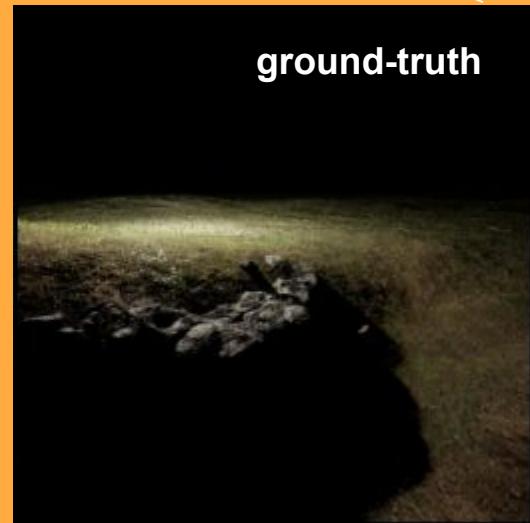
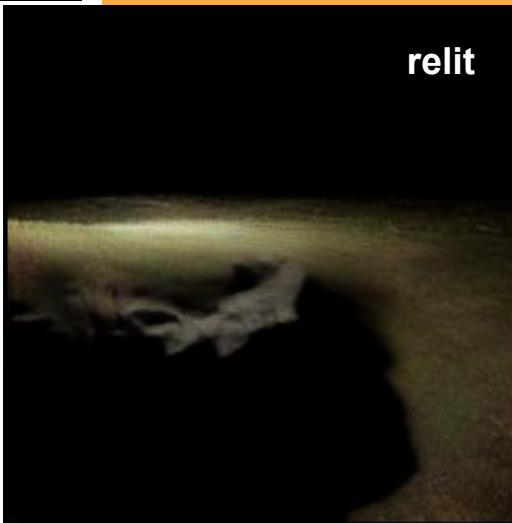
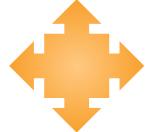
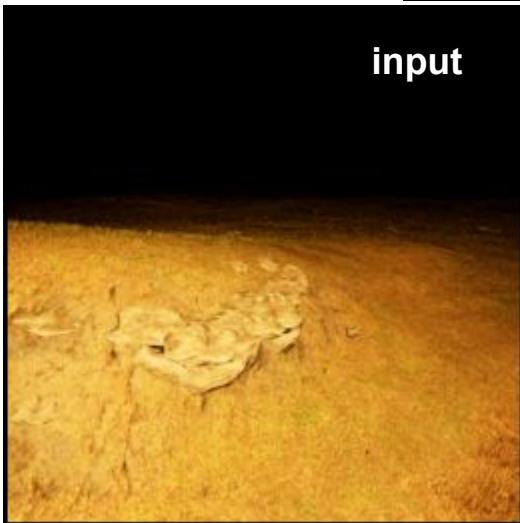
# Experimental results @1 (eval w/ discriminator)

# Details of the solution @2



- latent space represents only light conditions

- use skip-links from input to carry the scene information
- use generated ground-truth latent variables
- use L1 reconstruction loss and log-L2 loss for latent variable

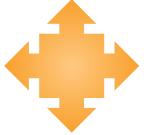


# Experimental results @2 (train)

 $L_1$  loss



input



relit

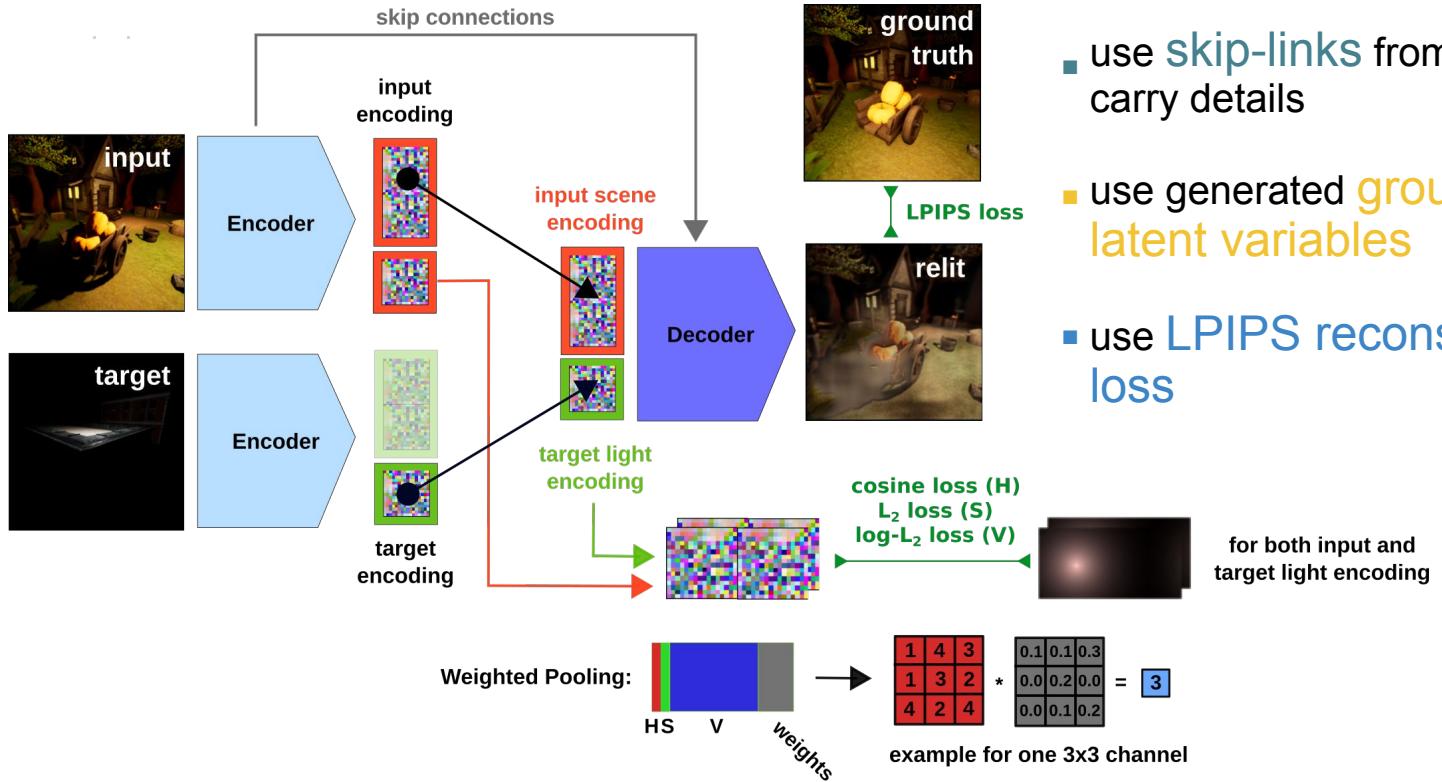


ground-truth



# Experimental results @2 (eval)

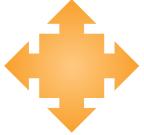
# Details of the solution @3



- split the latent variable into light and scene
- use skip-links from input to carry details
- use generated ground-truth latent variables
- use LPIPS reconstruction loss



input



target



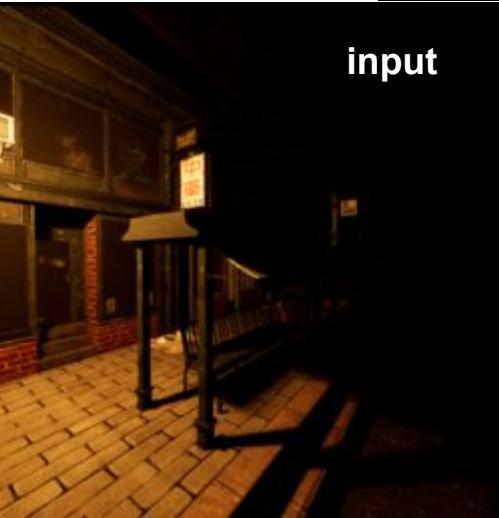
relit



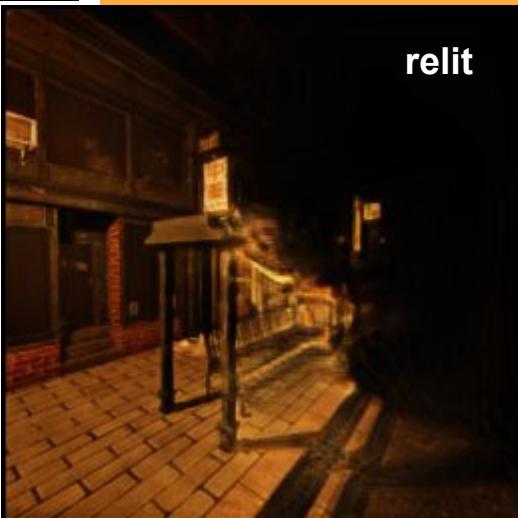
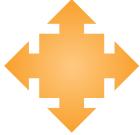
ground-truth

# Experimental results @3 (train)

LPIPS loss



input



relit



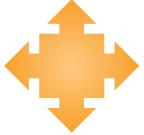
ground-truth



# Experimental results @3 (eval)



input



target



relit



ground-truth

LPIPS loss

# Experimental results @3 (eval)

# Experimental results

Metric name	IlluminationPredicter	@1 Envmap	@2 Envmap + scene
MSE	0.0238	<b>0.0219</b>	0.0254
SSIM	<b>0.3365</b>	0.1832	0.2988
PSNR	18.11 dB	<b>18.66</b> dB	18.10 dB
LPIPS	0.3268	0.2738	<b>0.2564</b>

# Pros and cons of the proposed method

- **good results** compared to identity mapping (relit = input) as well as for estimating light conditions (illumination predictor)
- color temperature much easier to estimate and transfer than **light direction**
- tendency to **remove shadows** instead of really change light direction ( $L_2$  loss)
- poor **realism**



# Conclusion

- **experimenting with more variations:** tune the network depth, latent variable size, regularization (as  $L_2$ -regularization), loss factors and functions ( $L_1, L_2$ , LPIPS, ...)
- for realism, **conduct GAN experiments** – e.g. use conditional GAN





Alexandre Dherse,  
Martin Everaert,  
Jakub Gwizdala

Supervised by  
Majed El Helou

# References

- [1] I. Anokhin et al. “High-Resolution Daytime Translation Without Domain Labels”. In: *arXiv preprint arXiv:2003.08791* (2020).
- [2] S. Bell, K. Bala, and N. Snavely. “Intrinsic images in the wild”. In: *ACM Transactions on Graphics (TOG)* 33.4 (2014), pp. 1–12.
- [3] J. Bromley et al. “Signature verification using a “siamese” time delay neural network”. In: *Advances in neural information processing systems*. 1994, pp. 737–744.
- [4] Y. Choi et al. “Stargan: Unified generative adversarial networks for multi-domain image-to-image translation”. In: *Proceedings of the IEEE conference on computer vision and pattern recognition*. 2018, pp. 8789–8797.
- [5] F. Fleuret. *Transposed convolutions. Deep learning lecture handout for EE-559 at EPFL*. Accessed: 2020-05-26. URL: <https://fleuret.org/ee559/materials/ee559-handout-7-1-transposed-convolutions.pdf>.
- [6] I. Goodfellow et al. “Generative adversarial nets”. In: *Advances in neural information processing systems*. 2014, pp. 2672–2680.
- [7] M. E. Helou et al. “VIDIT: Virtual Image Dataset for Illumination Transfer”. In: *arXiv preprint arXiv:2005.05460* (2020).
- [8] A. Hore and D. Ziou. “Image quality metrics: PSNR vs. SSIM”. In: *2010 20th International Conference on Pattern Recognition*. IEEE. 2010, pp. 2366–2369.

# References

- [9] Y. Hu, B. Wang, and S. Lin. “Fc4: Fully convolutional color constancy with confidence-weighted pooling”. In: *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*. 2017, pp. 4085–4094.
- [10] P. Isola et al. “Image-to-Image Translation with Conditional Adversarial Networks”. In: *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*. Code: <https://github.com/junyanz/pytorch-CycleGAN-and-pix2pix>. 2017, pp. 5967–5976.
- [11] P. Isola et al. “Image-to-image translation with conditional adversarial networks”. In: *Proceedings of the IEEE conference on computer vision and pattern recognition*. 2017, pp. 1125–1134.
- [12] A. Jolicoeur-Martineau. “The relativistic discriminator: a key element missing from standard GAN”. In: *arXiv preprint arXiv:1807.00734* (2018).
- [13] B. Kovacs et al. “Shading annotations in the wild”. In: *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*. 2017, pp. 6998–7007.
- [14] Z. Li and N. Snavely. “Learning intrinsic image decomposition from watching the world”. In: *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*. 2018, pp. 9039–9048.
- [15] T. Mansencal et al. *Colour 0.3.15*. Version 0.3.15. Jan. 2020. DOI: [10.5281/zenodo.3627408](https://doi.org/10.5281/zenodo.3627408). URL: <https://doi.org/10.5281/zenodo.3627408>.

# References

- [16] Martín Abadi et al. *TensorFlow: Large-Scale Machine Learning on Heterogeneous Systems*. Software available from tensorflow.org. 2015. URL: <http://tensorflow.org/>.
- [17] M. Mirza and S. Osindero. “Conditional generative adversarial nets”. In: *arXiv:1411.1784* (2014).
- [18] L. Murmann et al. “A Dataset of Multi-Illumination Images in the Wild”. In: *Proceedings of the IEEE International Conference on Computer Vision*. 2019, pp. 4080–4089.
- [19] A. Paszke et al. “PyTorch: An Imperative Style, High-Performance Deep Learning Library”. In: *Advances in Neural Information Processing Systems 32*. Ed. by H. Wallach et al. Curran Associates, Inc., 2019, pp. 8024–8035. URL: <http://papers.neurips.cc/paper/9015-pytorch-an-imperative-style-high-performance-deep-learning-library.pdf>.

# References

- [20] E. Riba et al. *Kornia: an Open Source Differentiable Computer Vision Library for PyTorch*. 2020. URL: <https://arxiv.org/pdf/1910.02190.pdf>.
- [21] W. Shi et al. “Real-time single image and video super-resolution using an efficient sub-pixel convolutional neural network”. In: *Proceedings of the IEEE conference on computer vision and pattern recognition*. 2016, pp. 1874–1883.
- [22] T. Sun et al. “Single image portrait relighting”. In: *ACM Transactions on Graphics (Proceedings SIGGRAPH)* (2019).
- [23] S. Uchida. *LPIPS implementation*. Accessed: 2020-05-28. URL: <https://github.com/S-aueo32/lpipspytorch>.
- [24] R. Wang et al. “Underexposed photo enhancement using deep illumination estimation”. In: *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*. 2019, pp. 6849–6857.
- [25] Z. Wang et al. “Image quality assessment: from error visibility to structural similarity”. In: *IEEE transactions on image processing* 13.4 (2004), pp. 600–612.

# References

- [26] Z. Xu et al. “Deep image-based relighting from optimal sparse samples”. In: *ACM Transactions on Graphics (TOG)* 37.4 (2018), pp. 1–13.
- [27] C. Yang, Y. Shen, and B. Zhou. “Semantic hierarchy emerges in deep generative representations for scene synthesis”. In: *arXiv preprint arXiv:1911.09267* (2019).
- [28] A. R. Zamir et al. “Taskonomy: Disentangling task transfer learning”. In: *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*. 2018, pp. 3712–3722.
- [29] L. Zhang et al. “Generating Digital Painting Lighting Effects via RGB-space Geometry”. In: *Transactions on Graphics (Presented at SIGGRAPH)* 39.2 (2020).
- [30] R. Zhang et al. “The unreasonable effectiveness of deep features as a perceptual metric”. In: *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*. 2018, pp. 586–595.
- [31] H. Zhou et al. “Deep Single-Image Portrait Relighting”. In: *Proceedings of the IEEE International Conference on Computer Vision*. 2019, pp. 7194–7202.
- [32] T. Zhou et al. “Unsupervised learning of depth and ego-motion from video”. In: *Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition*. 2017, pp. 1851–1858.
- [33] J.-Y. Zhu et al. “Unpaired image-to-image translation using cycle-consistent adversarial networks”. In: *Proceedings of the IEEE international conference on computer vision*. 2017, pp. 2223–2232.