

# Fast Likelihood-Free Inference via Bayesian Optimization

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Joint work with Jukka Corander

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For all the details:

M.U. Gutmann and J. Corander

Bayesian optimization for likelihood-free inference of  
simulator-based statistical models

*Journal of Machine Learning Research*, in press.

<http://arxiv.org/abs/1501.03291>

Early results:

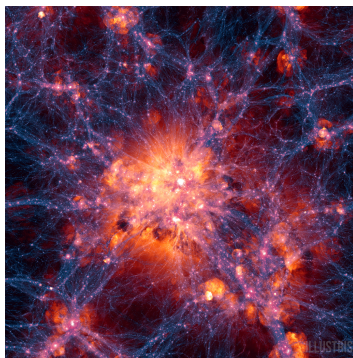
Bayesian Optimization for Likelihood-Free Estimation  
Poster at ABC in Rome, 2013.

Statistical inference for models where

1. the likelihood function is too costly to compute
2. sampling – simulating data – from the model is possible

# Why does it matter?

- ▶ Such models occur widely:
  - ▶ Astrophysics:  
Simulating the formation of galaxies, stars, or planets
  - ▶ Evolutionary biology:  
Simulating the evolution of life
  - ▶ Health science:  
Simulating the spread of an infectious disease
  - ▶ ...
- ▶ Enables inference for models with complex data generating mechanisms (e.g. scientific models)



Dark matter density simulated by the Illustris collaboration  
(Figure from <http://www.illustris-project.org>)

# Likelihood-free inference is an umbrella term

- ▶ There are several flavors of likelihood-free inference. In Bayesian setting e.g.
  - ▶ Approximate Bayesian computation (ABC)  
(for review, see e.g. Marin et al, Statistics and Computing, 2012)
  - ▶ Synthetic likelihood (Wood, Nature, 2010)
- ▶ General idea: Identify the values of the parameters of interest  $\theta$  for which simulated data resemble the observed data
- ▶ Simulated data resemble the observed data if some discrepancy measure  $\Delta \geq 0$  is small.

*Here: Focus on ABC, see reference paper for more*

# Meta ABC algorithm

- ▶ Let  $\mathbf{y}^o$  be the observed data.
- ▶ Iterate many many times:
  1. Sample  $\theta$  from a proposal distribution  $q(\theta)$
  2. Sample  $\mathbf{y}|\theta$  according to the model
  3. Compute discrepancy  $\Delta$  between  $\mathbf{y}^o$  and  $\mathbf{y}$
  4. Retain  $\theta$  if  $\Delta \leq \epsilon$

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- ▶ Different choices for  $q(\theta)$  give different algorithms
  - ▶ rejection ABC (Tavaré et al, 1997; Pritchard et al, 1999)
  - ▶ MCMC ABC (Marjoram et al, 2003)
  - ▶ Population Monte Carlo ABC (Sisson et al, 2007)
- ▶  $\epsilon$ : trade-off between statistical and computational performance
- ▶ Produces samples from an approximate posterior

# Two major difficulties

1. How to measure the discrepancy
2. How to handle the computational cost



# Two major difficulties

## 1. How to measure the discrepancy

### → Use classification

M.U. Gutmann, R. Dutta, S. Kaski, and J. Corander  
Statistical Inference of Intractable Generative Models via  
Classification

<http://arxiv.org/abs/1407.4981>

## 2. How to handle the computational cost

### → Use Bayesian optimization

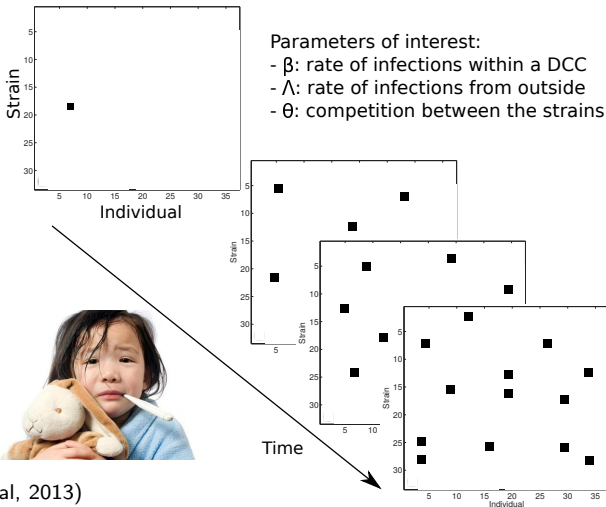
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# Example: Bacterial infections in child care centers

- ▶ Likelihood intractable for cross-sectional data
- ▶ But generating data from the model is possible



(Numminen et al, 2013)

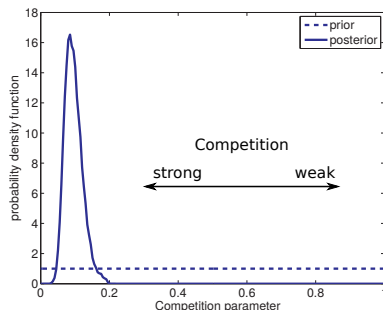
# Example: Bacterial infections in child care centers

(Numminen et al, 2013)

- ▶ Data: *Streptococcus pneumoniae* colonization for 29 centers
- ▶ Inference with Population Monte Carlo ABC
- ▶ Reveals strong competition between different bacterial strains

## Expensive:

- ▶ 4.5 days on a cluster with 200 cores
- ▶ More than one million simulated data sets



# Why is ABC so expensive?

- ▶ Let  $\mathbf{y}^o$  be the observed data.
- ▶ Building block of several ABC algorithms:
  1. Sample  $\theta$  from a proposal distribution  $q(\theta)$
  2. Sample  $\mathbf{y}|\theta$  according to the model
  3. Compute discrepancy  $\Delta$  between  $\mathbf{y}^o$  and  $\mathbf{y}$
  4. Retain  $\theta$  if  $\Delta \leq \epsilon$
- ▶ Previous work: focus on choice of proposal distribution
- ▶ Key bottleneck: presence of the rejection step  
small  $\epsilon \Rightarrow$  small acceptance probability  $\Pr(\Delta \leq \epsilon \mid \theta)$

# How to make the rejection step disappear ?

- ▶ Conditional acceptance probability corresponds to a likelihood approximation,

$$\tilde{L}(\boldsymbol{\theta}) \propto \Pr(\Delta \leq \epsilon \mid \boldsymbol{\theta})$$

- ▶ The conditional distribution of  $\Delta$  determines  $\tilde{L}(\boldsymbol{\theta})$ .
- ▶ If we knew the distribution of  $\Delta$  we could compute  $\tilde{L}(\boldsymbol{\theta})$ .
- ▶ Suggests an approach based on statistical modeling of  $\Delta$ .

# Proposed approach

## 1. Model and estimate the distribution of $\Delta$

- ▶ Estimated model yields computable approximation  $\hat{L}(\boldsymbol{\theta})$

$$\hat{L}(\boldsymbol{\theta}) \propto \hat{\text{Pr}}(\Delta \leq \epsilon \mid \boldsymbol{\theta})$$

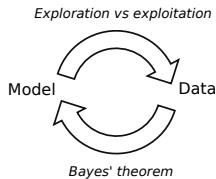
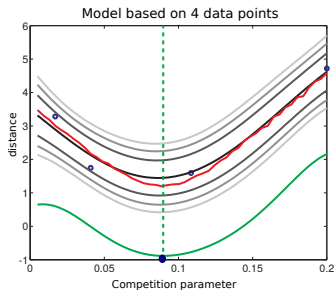
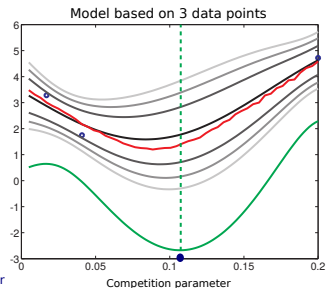
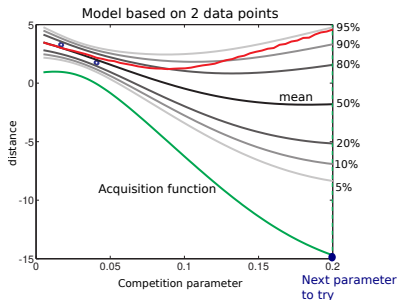
$\hat{\text{Pr}}$  is probability under the estimated model.

- ▶ Data for estimation by sampling  $\boldsymbol{\theta}$  from the prior or from some other proposal distribution
- ## 2. Give priority to regions in the parameter space where discrepancy $\Delta$ tends to be small.
- ▶ Prioritize modal regions of the likelihood/posterior
  - ▶ Use Bayesian optimization to find the regions where  $\Delta$  tends to be small.

# Bayesian optimization

- ▶ Set of methods to minimize black-box functions
- ▶ Basic idea:
  - ▶ A probabilistic model of  $\Delta$  guides the selection of points  $\theta$  where  $\Delta$  is next evaluated.
  - ▶ Observed values of  $\Delta$  are used to update the model by Bayes' theorem.
- ▶ When deciding where to evaluate  $\Delta$ , balance
  - ▶ points where  $\Delta$  is believed to be small (“exploitation”)
  - ▶ points where we are uncertain about  $\Delta$  (“exploration”)

# Bayesian optimization





# Vanilla implementation

- ▶ Assume (log) discrepancy follows a Gaussian process model.
- ▶ Assume a squared exponential covariance function  
 $\text{cov}(\Delta_{\boldsymbol{\theta}}, \Delta_{\boldsymbol{\theta}'}) = k(\boldsymbol{\theta}, \boldsymbol{\theta}')$ ,

$$k(\boldsymbol{\theta}, \boldsymbol{\theta}') = \sigma_f^2 \exp \left( \sum_j \frac{1}{\lambda_j^2} (\theta_j - \theta'_j)^2 \right). \quad (1)$$

- ▶ Use lower confidence bound acquisition function (e.g. Cox and John, 1992; Srinivas et al, 2012)

$$\mathcal{A}_t(\boldsymbol{\theta}) = \underbrace{\mu_t(\boldsymbol{\theta})}_{\text{post mean}} - \sqrt{\underbrace{\eta_t^2}_{\text{weight}} \underbrace{v_t(\boldsymbol{\theta})}_{\text{post var}}} \quad (2)$$

- ▶ Possibly use stochastic acquisition rule: sample from Gaussian centered at  $\text{argmin}_{\boldsymbol{\theta}} \mathcal{A}_t(\boldsymbol{\theta})$  while respecting boundaries.

# Recipe for fast likelihood-free inference

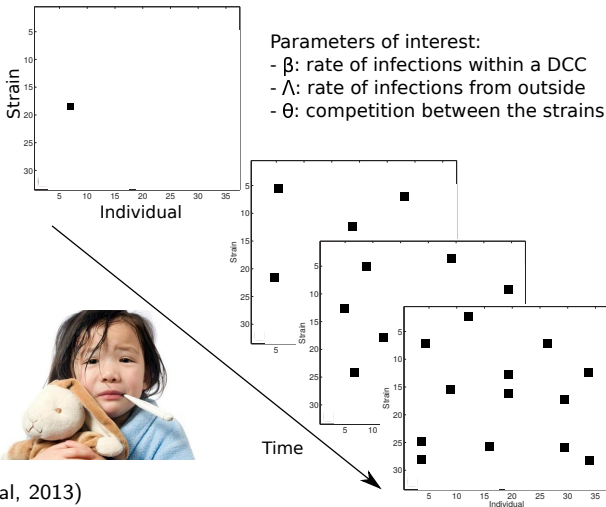
1. Estimate a model of the discrepancy using Bayesian optimization
2. Choose threshold  $\epsilon$  to obtain the likelihood approximation

$$\hat{L}(\boldsymbol{\theta}) \propto \hat{\Pr}(\Delta \leq \epsilon \mid \boldsymbol{\theta})$$

3. MLE or posterior inference with any standard method, using  $\hat{L}$  in place of true likelihood function.

# Example: Bacterial infections in child care centers

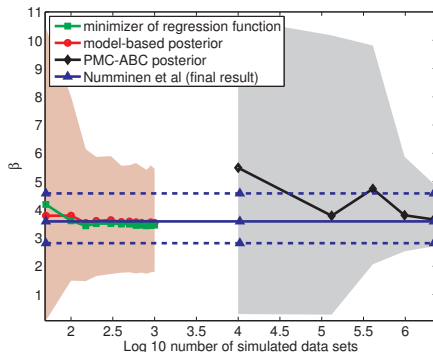
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# Inference results

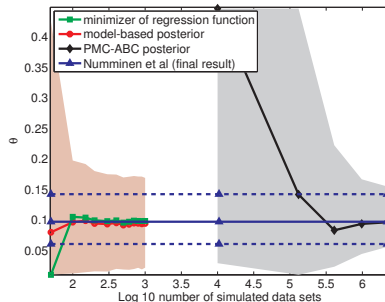
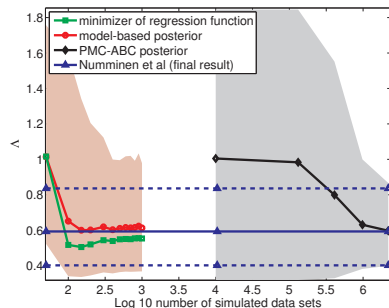
- ▶ Comparison of the proposed approach with a population Monte Carlo (PMC) ABC approach.
- ▶ Roughly equal results using 1000 times fewer simulations.
- ▶ The minimizer of the regression function under the model does not involve choosing a threshold  $\epsilon$ .

Posterior means: solid lines with markers,  
credibility intervals: shaded areas or dashed lines.



# Inference results

- ▶ Comparison of the model-based approach with a population Monte Carlo (PMC) ABC approach.



Posterior means are shown as solid lines with markers, credibility intervals as shaded areas or dashed lines.

## Further benefits

- ▶ Enables inference for models which were out of reach till now
  - ▶ model of evolution where simulating a single data set took us 12-24 hours (Marttinen et al, 2015)
- ▶ Allowed us to perform far more comprehensive data analysis than with standard approach (Numminen et al, 2016)
- ▶ Estimated  $\hat{L}(\theta)$  can be used to assess parameter identifiability for complex models
  - ▶ model about transmission dynamics of tuberculosis (Lintusaari et al, 2016)
- ▶ For point estimation, minimize  $\hat{E}(\Delta|\theta)$ 
  - ▶ no thresholds required

## Some open questions

- ▶ Modeling of the discrepancy:  
Vanilla GP-model worked surprisingly well but there are likely more suitable models.
- ▶ Exploration/exploitation trade-off:  
Can we find strategies which are optimal for parameter inference?

# Summary

- ▶ **Problem considered:** Computational cost of likelihood-free inference
- ▶ **Proposed approach:** Combine optimization with modeling of the discrepancy between simulated and observed data
- ▶ **Outcome:** Approach increases the efficiency of the inference by several orders of magnitude
- ▶ Talk was on approximate Bayesian computation with uniform kernels. For other kernels and synthetic likelihood see

M.U. Gutmann and J. Corander

Bayesian Optimization for Likelihood-Free Inference of Simulator-Based Statistical Models, *Journal of Machine Learning Research*, in press.

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Ricker model

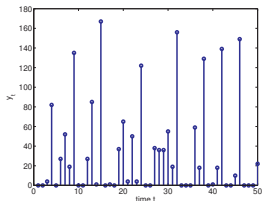
Details of the bacterial transmission model

# Application to parameter inference in chaotic systems

- ▶ Data: Time series with counts  $y_t$  (animal population size)
- ▶ Simulator-based model: Stochastic version of the Ricker map followed by an observation model

$$\log N_t = \log(r) + \log N_{t-1} - N_{t-1} + \sigma e_t, \quad e_t \sim \mathcal{N}(0, 1)$$
$$y_t | N_t, \varphi \sim \text{Poisson}(\varphi N_t)$$

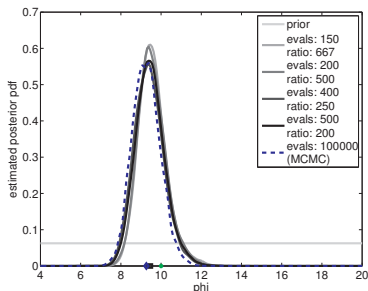
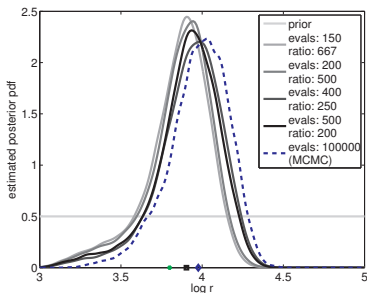
- ▶ Parameters  $\theta$ :
  - ▶  $\log r$  (growth rate)
  - ▶  $\sigma$  (noise var),
  - ▶  $\varphi$  (scale parameter)



Example data,  $\theta^o = (3.8, 0.3, 10)$ .

# Application to parameter inference in chaotic systems

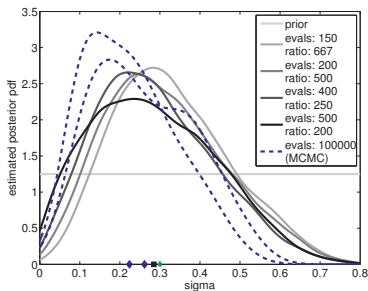
- ▶ Speed up:  $\approx 600$  times fewer evaluations of the distance function.
- ▶ Slight shift in posterior mean towards the data generating parameter  $\theta^o$  (green circle)



Comparison with results using MCMC (Wood, Nature, 2010)

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Comparison with results using MCMC (Wood, Nature, 2010)

# Bacterial transmission model (Numminen et al, 2013)

- ▶ Latent continuous time Markov chain for the transmissions inside a center

$$\Pr(I_{is}^{t+h} = 0 | I_{is}^t = 1) = h + o(h) \quad (3)$$

$$\Pr(I_{is}^{t+h} = 1 | I_{is'}^t = 0 \forall s') = R_s(t)h + o(h) \quad (4)$$

$$\Pr(I_{is}^{t+h} = 1 | I_{is}^t = 0, \exists s' : I_{is'}^t = 1) = \theta R_s(t)h + o(h) \quad (5)$$

$$R_s(t) = \beta E_s(t) + \Lambda P_s \quad (6)$$

- ▶  $P_s$  : infections from outside the group (static)
- ▶  $E_s(t) = \sum_i \frac{1}{N-1} I_{is}^t \frac{1}{n_i(t)}$ : infections from within the group  
 $n_i(t) = \sum_{s'} I_{is'}^t$ : number of strains that individual  $i$  carries
- ▶ Observation model: Cross-sectional sampling at random time.

# Distance measure used

- ▶ Summary statistics for each center:
  - ▶ the diversity of the strains present
  - ▶ the number of different strains present
  - ▶ the proportion of infected individuals
  - ▶ the proportion of individuals with more than one strain.
- ▶ Distance  $\equiv$  Distance between the empirical cumulative distribution functions (cdfs) of the four summary statistics.