Neural Approximate Sufficient Statistics

Michael U. Gutmann

<michael.gutmann@ed.ac.uk>

School of Informatics, University of Edinburgh

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References

Paper:

Yanzhi Chen[∗] , Dinghuai Zhang[∗] , Michael U. Gutmann, Aaron Courville, Zhanxing Zhu Neural approximate sufficient statistics for implicit models $ICIR$ 2021 <https://openreview.net/pdf?id=SRDuJssQud>

Code:

<https://github.com/cyz-ai/neural-approx-ss-lfi>

[∗]did the hard work, equal contribution

- 1. Sufficient statistics are information maximising representations.
- 2. We can learn approximate sufficient statistics using estimators of mutual information or their proxies.
- 3. The learned statistics boost the performance of Bayesian inference methods for implicit models.

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Sufficient statistics

- \triangleright Consider a parametric statistical model $p(\mathbf{X}|\theta)$ for data $X = (x_1, \ldots, x_n).$
- \triangleright A statistic T is a vector-valued function of the data. Basic example is the sample average:

$$
\bar{\mathbf{x}} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_i \tag{1}
$$

I Fisher–Neyman factorisation: A statistic T is sufficient for *θ* if and only if the joint $p(X|\theta)$ factorises as

$$
p(\mathbf{X}|\boldsymbol{\theta}) = u(\mathbf{X})v(\mathcal{T}(\mathbf{X}), \boldsymbol{\theta})
$$
 (2)

for all **X** and θ , where u and v are two non-negative functions.

Example

 \blacktriangleright Classic example: *n* iid observations of a Gaussian random variable with mean θ and known variance $\sigma^2.$

$$
p(\mathbf{X}|\boldsymbol{\theta}) = \prod_{i=1}^{n} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2\sigma^2}(x_i - \theta)^2\right)
$$
(3)

$$
= \underbrace{\frac{1}{(2\pi\sigma^2)^{\frac{n}{2}}}\exp\left(-\frac{\sum_{i=1}^{n}x_i^2}{2\sigma^2}\right)}_{u(\mathbf{X})} \underbrace{\exp\left(\frac{2n\theta\bar{x} - n\theta^2}{2\sigma^2}\right)}_{v(T(\mathbf{X}),\theta)}
$$

with $T(X) = \bar{x}$.

 \blacktriangleright Intuition:

(1) the model parameters θ only interact with **X** through $T(X)$ (2) $\theta \perp X$ | $T(X)$

Log likelihood function

$$
\blacktriangleright \text{ Assume } p(\mathbf{X}|\boldsymbol{\theta}) = u(\mathbf{X})v(\mathcal{T}(\mathbf{X}), \boldsymbol{\theta})
$$

 \triangleright Given some observed data **X**, the log likelihood function is

$$
\ell(\boldsymbol{\theta}) = \log v(T(\mathbf{X}), \boldsymbol{\theta}) + \text{const}
$$
 (4)

 \triangleright To infer *θ* from **X**, we do not need to know **X** = (**x**₁..., **x**_n) but only the value of $T(X)$.

 \blacktriangleright Gaussian example

$$
\ell(\theta) = \frac{n}{2\sigma^2} (2\theta \bar{x} - \theta^2)
$$
 (5)

so that $\hat{\theta}_{\text{MIE}} = \bar{x}$

 \triangleright Sufficient statistics are important both for MLE and Bayesian inference

$$
p(\theta|\mathbf{X}) = p(\theta|\mathcal{T}(\mathbf{X})) \propto \nu(\mathcal{T}(\mathbf{X}), \theta)\pi(\theta), \quad (6)
$$

where $\pi(\theta)$ is the prior.

Computational benefits of sufficient statistics

- \triangleright Dimensionality reduction: Both the posterior and the (log)-likelihood only depend on **X** via $T(X) \Rightarrow$ we don't need to store or work with the raw data but can work with $T(X)$, which is often much easier.
- Gaussian example: 1 number vs n numbers
- \blacktriangleright Many algorithms work by comparing data sets to each other. But comparing X with X' is very hard due to high dimensionality. Comparing $T(X)$ with $T(X')$ is often simpler.

Characterisation in terms of mutual information

 \triangleright Denote the mutual information between by two random **variables** y_1 **and** y_2 **by** $I(y_1; y_2)$ **,**

$$
I(\mathbf{y}_1; \mathbf{y}_2) = \mathbb{E}_{\mathbf{y}_1, \mathbf{y}_2} \log \frac{p(\mathbf{y}_1, \mathbf{y}_2)}{p(\mathbf{y}_1)p(\mathbf{y}_2)}
$$
(7)

 \triangleright (Data-processing inequality) For a Markov chain $\theta \to \mathsf{X} \to \mathsf{Z}$,

$$
I(\boldsymbol{\theta}; \mathbf{Z}) \leq I(\boldsymbol{\theta}; \mathbf{X}) \tag{8}
$$

We can't gain MI but only lose it by processing data. Inequality also holds for deterministic functions $Z = g(X)$.

 \triangleright No information loss if T is a sufficient statistic:

$$
\mathcal{T} \text{ is a sufficient statistic} \Longleftrightarrow I(\theta; \mathcal{T}(\mathbf{X})) = I(\theta; \mathbf{X}) \qquad (9)
$$

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Sufficient statistics are infomax representations

 \blacktriangleright MI-based characterisation of sufficient statistics T

 T is a sufficient statistic $\Longleftrightarrow I(\theta; T(\mathbf{X})) = I(\theta; \mathbf{X})$ (10)

 \triangleright Since for deterministic transformations g

$$
I(\boldsymbol{\theta}; g(\mathbf{X})) \le I(\boldsymbol{\theta}; \mathbf{X})
$$
\n(11)

we have a variational characterisation of sufficient statistics

$$
\mathcal{T} \text{ is a sufficient statistic} \Longleftrightarrow I(\theta; \mathcal{T}(\mathbf{X})) = \max_{g \in \mathcal{G}} I(\theta; g(\mathbf{X}))
$$
\n(12)

 \triangleright Choosing a function family G can introduce an approximation. We work with neural networks with a fixed number of outputs (2 dim(*θ*)).

Combining the idea with MI estimators

- \blacktriangleright Estimating MI is hard.
- \blacktriangleright We are interested in finding an argmax $_{g}$ I $(\theta;g(\mathsf{X}))$ rather than knowing the precise value of the MI.
- \triangleright Broadens the set of applicable MI estimators to include surrogate quantities.
	- \triangleright MI as KL divergence between joint and marginals \rightarrow Use the more robust Jensen-Shannon divergence (JSD) instead of the KL divergence
	- \blacktriangleright MI as a nonlinear dependency measure
		- \rightarrow Use the ratio-free distance correlation (Székely and Rizzo, 2009, 2014)

Székely and Rizzo, Brownian distance covariance, The Annals of Applied Statistics, 2009

Székely and Rizzo, Partial distance correlation with methods for dissimilarities, The Annals of Statistics, 2014

Learning sufficient statistics with the JSD

 \triangleright A density-free variational formulation of the JSD between $p(\theta, \mathbf{X})$ and $p(\theta)p(\mathbf{X})$ is

$$
\sup_{F} \mathbb{E}_{p(\theta, \mathbf{X})} \left[-\operatorname{sp}(-F(\theta, \mathbf{X})) \right] - \mathbb{E}_{p(\theta)p(\mathbf{X})} \left[\operatorname{sp}(F(\theta, \mathbf{X})) \right] (13)
$$

where $sp(t) = log(1 + exp(t))$ is the softplus function.

 \triangleright Objective for learning sufficient statistics:

$$
\sup_{S,F} \mathbb{E}_{p(\theta,\mathbf{X})} \left[-\operatorname{sp}(-F(\theta,S(\mathbf{X})) \right] - \mathbb{E}_{p(\theta)p(\mathbf{X})} \left[\operatorname{sp}(F(\theta,S(\mathbf{X})) \right]
$$
\n(14)

 \triangleright Same as learning the ratio $p(\theta, \mathbf{X})/p(\theta)p(\mathbf{X}) = p(\theta|\mathbf{X})$ by logistic regression (classification) with a particular constraint on the processing of **X**. (see"LFI by ratio estimation" by Thomas et al, 2016, 2021)

Learning sufficient statistics via distance correlation

(Székely and Rizzo, 2014)

 \blacktriangleright The distance correlation between two random variables is a multivariate dependence coefficient defined as

$$
R^2(\boldsymbol{\theta}, \mathbf{X}) = \frac{\mathbb{E}[A_{\boldsymbol{\theta}} A_{\mathbf{X}}]}{\sqrt{\mathbb{E}[A_{\boldsymbol{\theta}}^2] \mathbb{E}[A_{\mathbf{X}}^2]}}
$$
(15)

where A_X is a double-centred (random) distance function

$$
\textbf{A}_{\textbf{X}} = \|\textbf{X}-\textbf{X}'\|-\mathbb{E}_{\textbf{X}}[\|\textbf{X}-\textbf{X}'\|]-\mathbb{E}_{\textbf{X}'}[\|\textbf{X}'-\textbf{X}\|]+\mathbb{E}_{\textbf{X}'}\mathbb{E}_{\textbf{X}}[\|\textbf{X}-\textbf{X}'\|]
$$

(equivalent definition for A*θ*)

Expectation in the numerator is taken with respect to (\mathbf{X}, θ) and the independent and identically distributed tuple (X', θ') . (The expectations in the denominator are taken with respect to the corresponding marginals.)

Learning sufficient statistics via distance correlation

 \blacktriangleright There are equivalent definitions in terms of characteristic functions and the so-called Brownian distance covariance

(Székely and Rizzo, 2009, 2014)

- \blacktriangleright Key properties:
	- \blacktriangleright 0 < R(θ , **X**) < 1
	- $R(\theta, \mathbf{X}) = 0 \Longleftrightarrow \theta \perp \mathbf{X}$
	- $R(\theta, X) = 1$ means θ and X are a linear transformation of each other.
- \triangleright Objective for learning sufficient statistics:

$$
\max_{S} R^{2}(\theta, S(\mathbf{X}))
$$
 (16)

Note: we only need to train one network and not two as in the JSD (and other variational MI estimators), which makes this approach faster.

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- \triangleright Goal: approximate Bayesian parameter inference for implicit models
- \blacktriangleright Implicit models: models where sampling is possible but evaluating the likelihood function is computationally infeasible

$$
\mathbf{X} \sim p(\mathbf{X}|\boldsymbol{\theta}) \tag{17}
$$

- \triangleright Approach: learn approximate sufficient statistics and aim at $p(\theta|T(\mathbf{X}))$ instead of $p(\theta|\mathbf{X})$ to increase efficiency.
- \blacktriangleright Focus on sequential inference methods:
	- \triangleright (variant of) sequential approximate Bayesian computation (Beaumont, 2009)
	- \triangleright sequential neural likelihood (Papamakarios et al., 2019)

Overview of the sequential approach

We jointly learn the statistics and the posterior in multiple rounds. (see paper for details)

Example results: Ising model (using JSD)

- \triangleright 64-dimensional Ising model, θ : coupling strength (prior: $U(0, 1.5)$
- \triangleright Sufficient statistics are known. Reference posterior obtained by (expensive) rejection sampling.
- \blacktriangleright The learned statistics (algorithms with a $+)$ improve the inference.
- \triangleright Posterior mean as statistics is sub-optimal.

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Example results: Ornstein-Uhlenbeck process (using JSD)

 \triangleright Stochastic differential equation simulated with the Euler-Maruyama method

$$
x_{t+1} = x_t + \Delta x_t
$$
\n
$$
\Delta x_t = \theta_1(\exp(\theta_2) - x_t)\Delta t + 0.5\epsilon, \quad \epsilon \sim \mathcal{N}(\epsilon; 0, \Delta t)
$$
\n(19)

where $\Delta t = 0.2$ and $x_0 = 10$.

- Data: x_1, \ldots, x_{50} .
- **I** Unknowns: θ_1 and θ_2 with priors $U(0, 1)$ and U(−2*.*0*,* 2*.*0), respectively.

Example results: Ornstein-Uhlenbeck process (using JSD)

- \blacktriangleright Learning approximate sufficient statistics improves the inference.
- \blacktriangleright Learned statistics give better calibrated posteriors.

Other MI proxies

(Results for SNL+)

- ▶ We can use other MI proxies than JSD and DC. Results for Donsker-Varadhan (DV) and Wasserstein distance (WD).
- \triangleright JSD performs here best but DC is about 15 times faster than the other methods.

Conclusions

- \blacktriangleright Two characterisations of sufficient statistics:
	- \blacktriangleright Fisher-Neyman factorisation
	- \triangleright Characterisation in terms of mutual information (MI)
- \blacktriangleright Variational characterisation: sufficient statistics are information maximising representations.
- \blacktriangleright Learn (approximate) sufficient statistics using (proxy) MI estimators.
- \triangleright We used the learned statistics to boost the performance of Bayesian inference with implicit models.
- \triangleright More results in the paper Neural approximate sufficient statistics for implicit models <https://openreview.net/pdf?id=SRDuJssQud>