Neural Approximate Sufficient Statistics

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References

Paper:

Yanzhi Chen*, Dinghuai Zhang*, Michael U. Gutmann, Aaron Courville, Zhanxing Zhu Neural approximate sufficient statistics for implicit models *ICLR 2021* https://openreview.net/pdf?id=SRDuJssQud

Code:

https://github.com/cyz-ai/neural-approx-ss-lfi

*did the hard work, equal contribution

- 1. Sufficient statistics are information maximising representations.
- 2. We can learn approximate sufficient statistics using estimators of mutual information or their proxies.
- 3. The learned statistics boost the performance of Bayesian inference methods for implicit models.

Background on sufficient statistics

Proposed method to learn approximate sufficient statistics

Application to Bayesian inference with implicit models

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Sufficient statistics

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Fisher–Neyman factorisation: A statistic T is sufficient for θ if and only if p(x|θ) factorises as

$$p(\mathbf{x}|\boldsymbol{\theta}) = u(\mathbf{x})v(T(\mathbf{x}),\boldsymbol{\theta})$$
(2)

for all **x** and θ , where *u* and *v* are two non-negative functions.

• Classic example: *n* iid observations of a Gaussian random variable with mean θ and known variance σ^2 .

$$p(\mathbf{x}|\boldsymbol{\theta}) = \prod_{i=1}^{n} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2\sigma^2}(x_i - \theta)^2\right)$$
(3)
$$= \underbrace{\frac{1}{(2\pi\sigma^2)^{\frac{n}{2}}} \exp\left(-\frac{\sum_{i=1}^{n} x_i^2}{2\sigma^2}\right)}_{u(\mathbf{x})} \underbrace{\exp\left(\frac{2n\theta\bar{\mathbf{x}} - n\theta^2}{2\sigma^2}\right)}_{v(T(\mathbf{x}),\theta)}$$

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 Sufficient statistics are important both for MLE and Bayesian inference

$$p(\boldsymbol{\theta}|\mathbf{x}) = p(\boldsymbol{\theta}|T(\mathbf{x})) \propto v(T(\mathbf{x}), \boldsymbol{\theta})\pi(\boldsymbol{\theta}), \quad (6)$$

where $\pi(\theta)$ is the prior.

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Computational benefits of sufficient statistics

Dimensionality reduction: Both the posterior and the (log)-likelihood only depend on x via T(x) ⇒ we don't need to store or work with the raw data but can work with T(x), which is often much easier.

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- Gaussian example: 1 number vs n numbers
- Many algorithms work by comparing data sets to each other. But comparing x with x' is very hard due to high dimensionality. Comparing T(x) with T(x') is often simpler.

Characterisation in terms of mutual information

Denote the mutual information between by two random variables y₁ and y₂ by *l*(y₁; y₂),

$$I(\mathbf{y}_1; \mathbf{y}_2) = \mathbb{E}_{\mathbf{y}_1, \mathbf{y}_2} \left[\log \frac{\rho(\mathbf{y}_1, \mathbf{y}_2)}{\rho(\mathbf{y}_1) \rho(\mathbf{y}_2)} \right]$$
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▶ (Data-processing inequality) For a Markov chain $\theta \rightarrow x \rightarrow z$,

$$l(\theta; \mathbf{z}) \le l(\theta; \mathbf{x})$$
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We can't gain MI but only lose it by transforming data. Inequality also holds for deterministic functions $\mathbf{z} = g(\mathbf{x})$.

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No information loss for sufficient statistics:

T is a sufficient statistic $\iff I(\theta; T(\mathbf{x})) = I(\theta; \mathbf{x})$ (9)

Background on sufficient statistics

Proposed method to learn approximate sufficient statistics

Application to Bayesian inference with implicit models

Sufficient statistics are infomax representations

MI-based characterisation of sufficient statistics T

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 is a sufficient statistic $\Longleftrightarrow {\mathcal I}({m heta};{\mathcal T}({f x})) = {\mathcal I}({m heta};{f x})$ (10)

Since for deterministic transformations g

$$l(\boldsymbol{\theta}; g(\mathbf{x})) \le l(\boldsymbol{\theta}; \mathbf{x}) \tag{11}$$

we have a variational characterisation of sufficient statistics

$$T \text{ is a sufficient statistic} \iff I(\theta; T(\mathbf{x})) = \max_{g \in \mathcal{G}} I(\theta; g(\mathbf{x}))$$
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Choosing a function family G can introduce an approximation.
 We work with neural networks with a fixed number of outputs (2 dim(θ)).

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Székely and Rizzo, Brownian distance covariance, The Annals of Applied Statistics, 2009

Székely and Rizzo, Partial distance correlation with methods for dissimilarities, The Annals of Statistics, 2014

Learning sufficient statistics with the JSD

A density-free variational formulation of the JSD between p(θ, x) and p(θ)p(x) is

$$\sup_{F} \mathbb{E}_{p(\theta, \mathbf{x})} \left[- \operatorname{sp}(-F(\theta, \mathbf{x})) \right] - \mathbb{E}_{p(\theta)p(\mathbf{x})} \left[\operatorname{sp}(F(\theta, \mathbf{x})) \right] \quad (13)$$

where sp(t) = log(1 + exp(t)) is the softplus function.

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Objective for learning sufficient statistics:

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Same as learning the ratio p(θ, x)/p(θ)p(x) = p(θ|x) by logistic regression (classification) with a particular constraint on the processing of x.

(see"LFI by ratio estimation" by Thomas et al, 2016; Hermans et al, 2020)

(Székely and Rizzo, 2014)

The distance correlation between two random variables is a multivariate dependence coefficient defined as

$$R^{2}(\boldsymbol{\theta}, \mathbf{x}) = \frac{\mathbb{E}[A_{\boldsymbol{\theta}}A_{\mathbf{x}}]}{\sqrt{\mathbb{E}[A_{\boldsymbol{\theta}}^{2}]\mathbb{E}[A_{\mathbf{x}}^{2}]]}}$$
(15)

where A_x is a double-centred (random) distance function

$$A_{\mathbf{x}} = \|\mathbf{x} - \mathbf{x}'\| - \mathbb{E}_{\mathbf{x}}[\|\mathbf{x} - \mathbf{x}'\|] - \mathbb{E}_{\mathbf{x}'}[\|\mathbf{x}' - \mathbf{x}\|] + \mathbb{E}_{\mathbf{x}'}\mathbb{E}_{\mathbf{x}}[\|\mathbf{x} - \mathbf{x}'\|]$$

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Expectation in the numerator is taken with respect to (x, θ) and the independent and identically distributed tuple (x', θ'). (The expectations in the denominator are taken with respect to the corresponding marginals.)

There are equivalent definitions in terms of characteristic functions and the so-called Brownian distance covariance

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Links to maximum mean discrepancy (MMD, Sejdinovic et al, 2013)

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 - ► $R(\theta, \mathbf{x}) = 1$ means θ and \mathbf{x} are a linear transformation of each other.
- Objective for learning sufficient statistics:

$$\max_{g} R^{2}(\boldsymbol{\theta}, g(\mathbf{x}))$$
(16)

Note: we only need to train one network and not two as in the JSD (and other variational MI estimators), which makes this approach faster.

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Goal: approximate Bayesian parameter inference for implicit models

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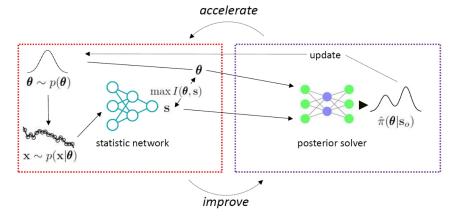
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- Focus on sequential inference methods:
 - (variant of) sequential approximate Bayesian computation (SMC-ABC, Beaumont, 2009)
 - sequential neural likelihood (SNL, Papamakarios et al., 2019)

Overview of the approach

We jointly learn the statistics and the posterior in multiple rounds.



Variant of SMC-ABC with neural suff stats (SMC-ABC+)

Input: prior $\pi(\theta)$, observed data \mathbf{x}_{α} **Output:** estimated posterior $\hat{\pi}(\boldsymbol{\theta}|\mathbf{x}_{o})$ Initialisation: $\mathcal{D} = \emptyset, p_1(\theta) = \pi(\theta)$ **for** *j* in 1 to *r* **do** repeat sample $\theta_i \sim p_i(\theta)$; sample from proposal distr simulate $\mathbf{x}_i \sim p(\mathbf{x}|\boldsymbol{\theta}_i)$; sample data from the model until *n* samples $\mathcal{D} \leftarrow \mathcal{D} \cup \{\boldsymbol{\theta}_i, \mathbf{x}_i\}_{i=1}^n$ learn approx suff stats $S(\cdot)$ using \mathcal{D} ; \leftarrow the main modification compute $\mathbf{s}_{o} = S(\mathbf{x}_{o})$ and $\mathbf{s}_{i} = S(\mathbf{x}_{i})$ for $(\boldsymbol{\theta}_{i}, \mathbf{x}_{i}) \in \mathcal{D}$; sort \mathcal{D} according to $\|\mathbf{s}_i - \mathbf{s}_o\|$; fit $p(\theta | \mathbf{s}_{o})$ with the top $m \theta$ s in \mathcal{D} ; e.g. MoG or copula model $q_i(\theta|\mathbf{s}_o) \propto p(\theta|\mathbf{s}_o)\pi(\theta) / \sum_{l}^{J} p_l(\theta); \qquad \pi / \sum_{l}^{j} p_l: importance weights$ $p_{i+1}(\theta) \leftarrow q_i(\theta|\mathbf{s}_o);$ update proposal distribution end for return $\hat{\pi}(\boldsymbol{\theta}|\mathbf{x}_{o}) = q_{r}(\boldsymbol{\theta}|\mathbf{s}_{o})$

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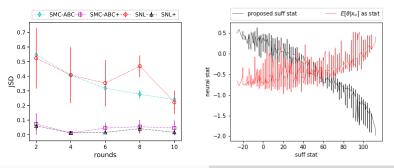
alternatively: return the weighted samples
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SNL with neural suff stats (SNL+)

Input: prior $\pi(\theta)$, observed data \mathbf{x}_o **Output:** estimated posterior $\hat{\pi}(\boldsymbol{\theta}|\mathbf{x}_{o})$ Initialisation: $\mathcal{D} = \emptyset, p_1(\theta) = \pi(\theta)$ **for** *j* in 1 to *r* **do** repeat sample $\theta_i \sim p_i(\theta)$; sample from proposal distr simulate $\mathbf{x}_i \sim p(\mathbf{x}|\boldsymbol{\theta}_i)$; sample data from the model **until** *n* samples $\mathcal{D} \leftarrow \mathcal{D} \cup \{\boldsymbol{\theta}_i, \mathbf{x}_i\}_{i=1}^n$ learn approx suff stats $S(\cdot)$ using \mathcal{D} ; ← the modification compute $\mathbf{s}_o = S(\mathbf{x}_o)$ and $\mathbf{s}_i = S(\mathbf{x}_i)$ for $(\boldsymbol{\theta}_i, \mathbf{x}_i) \in \mathcal{D}$; fit $q(\mathbf{s}|\boldsymbol{\theta})$ as in original SNL; neural density estimator, e.g. MAF $q_i(\theta|\mathbf{s}_o) \propto \pi(\theta) \cdot q(\mathbf{s}_o|\theta)$: prior times estimated likelihood $p_{i+1}(\boldsymbol{\theta}) \leftarrow q_i(\boldsymbol{\theta}|\mathbf{s}_o);$ update proposal distribution end for return $\hat{\pi}(\boldsymbol{\theta}|\mathbf{x}_{o}) = q_{r}(\boldsymbol{\theta}|\mathbf{s}_{o})$

Example results: Ising model (using JSD)

- 64-dimensional Ising model, θ: coupling strength (prior: U(0, 1.5))
- Sufficient statistics are known. Reference posterior obtained by (expensive) rejection sampling.
- The learned statistics (algorithms with a +) improve the inference.
- Posterior mean as statistics is sub-optimal.



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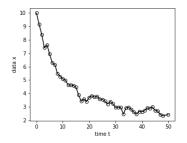
Example results: Ornstein-Uhlenbeck process (using JSD)

 Stochastic differential equation simulated with the Euler-Maruyama method

$$x_{t+1} = x_t + \Delta x_t$$
(18)
$$\Delta x_t = \theta_1(\exp(\theta_2) - x_t)\Delta t + 0.5\epsilon, \quad \epsilon \sim \mathcal{N}(\epsilon; 0, \Delta t)$$
(19)

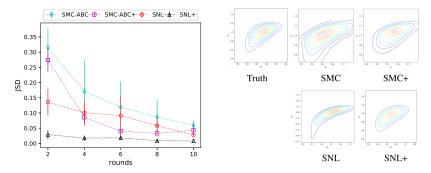
where $\Delta t = 0.2$ and $x_0 = 10$.

- Data: x_1, \ldots, x_{50} .
- Unknowns: θ_1 and θ_2 with priors $\mathcal{U}(0,1)$ and $\mathcal{U}(-2.0,2.0)$, respectively.



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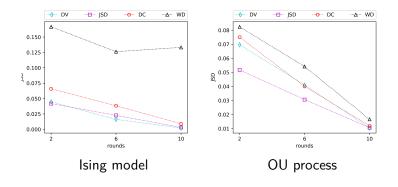
- Learning approximate sufficient statistics improves the inference.
- Learned statistics give better calibrated posteriors.



Other MI proxies

(Results for SNL+)

- We can use other MI proxies than JSD and DC. Results for Donsker-Varadhan (DV) and Wasserstein distance (WD).
- JSD performs here best but DC is about 15 times faster than the other methods.



Conclusions

- Two characterisations of sufficient statistics:
 - Fisher-Neyman factorisation
 - Characterisation in terms of mutual information (MI)
- Variational characterisation: sufficient statistics are information maximising representations.
- Learn (approximate) sufficient statistics using (proxy) MI estimators.
- We used the learned statistics to boost the performance of Bayesian inference with implicit models.
- "Approach plays well with others": can be used to enhance existing algorithms
- More results and comparisons in the paper Neural approximate sufficient statistics for implicit models https://openreview.net/pdf?id=SRDuJssQud