Cyclic Reduction for Solving Tridiagonal Systems

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1 Banded and Tridiagonal Linear System

2 Cyclic Reduction and its Parallelization



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Bandwidth: the bandwidth of a n × n matrix A is the smallest b such that

$$A_{i,j} = 0 \,\,\forall |i-j| > b$$

- **2** A is banded if b << n.
- 3 A is tridiagonal if b = 1.

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Tridiagonal linear system has form

$$\begin{bmatrix} b_{1} & c_{1} & & & \\ a_{2} & b_{2} & c_{2} & & \\ & \ddots & \ddots & \ddots & \\ & & a_{n-1} & b_{n-1} & c_{n-1} \\ & & & & a_{n} & b_{n} \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{n-1} \\ x_{n} \end{bmatrix} = \begin{bmatrix} y_{1} \\ y_{2} \\ \vdots \\ y_{n-1} \\ y_{n} \end{bmatrix}$$

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2 Cyclic Reduction and its Parallelization

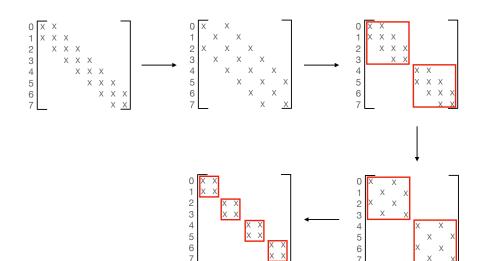


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Overview



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Cyclic Reduction: Transformation of Coefficients

1 The original *i*-th row:

$$a_i x_{i-1} + b_i x_i + c_i x_{i+1} = y_i$$

O The new *i*-th row:

$$\bar{a}_i x_{i-2} + \bar{b}_i x_i + \bar{c}_i x_{i+2} = \bar{y}_i$$

such that

$$\bar{\mathbf{a}}_i = \alpha_i \mathbf{a}_{i-1}, \quad \bar{\mathbf{b}}_i = \mathbf{b}_i + \alpha_i \mathbf{c}_{i-1} + \beta_i \mathbf{a}_{i+1} \\ \bar{\mathbf{c}}_i = \beta_i \mathbf{c}_{i+1}, \quad \bar{\mathbf{y}}_i = \mathbf{y}_i + \alpha_i \mathbf{y}_{i-1} + \beta_i \mathbf{y}_{i+1}$$

where

$$egin{array}{lll} lpha_i = -a_i/b_{i-1} & ext{for } i \in [2,N], \ eta_i = -c_i/b_{i+1} & ext{for } i \in [1,N-1], \ lpha_1 = eta_N = 0 \end{array}$$

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Cyclic Reduction: Transformation of Coefficients

4 After transformation:

$$\begin{bmatrix} \bar{b}_1 & 0 & \bar{c}_1 & & & \\ 0 & \bar{b}_2 & 0 & \bar{c}_2 & & \\ \bar{a}_3 & 0 & \bar{b}_3 & 0 & \bar{c}_3 & & \\ & \ddots & \ddots & \ddots & \ddots & \ddots & \\ & & \bar{a}_{n-2} & 0 & \bar{b}_{n-2} & 0 & \bar{c}_{n-2} \\ & & & \bar{a}_{n-1} & 0 & \bar{b}_{n-1} & 0 \\ & & & & \bar{a}_n & 0 & \bar{b}_n \end{bmatrix}$$

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Cyclic Reduction: Reordering Equations

After reordering:

$$\begin{bmatrix} \bar{b}_{1} & \bar{c}_{1} & & & \\ \bar{a}_{3} & \bar{b}_{3} & \ddots & & \\ & \ddots & \ddots & \bar{c}_{n-3} & & \\ & \bar{a}_{n-1} & \bar{b}_{n-1} & 0 & & \\ & & 0 & \bar{b}_{2} & \bar{c}_{2} & & \\ & & \bar{a}_{4} & \bar{b}_{4} & \ddots & \\ & & \ddots & \ddots & \bar{c}_{n-2} \\ & & & \bar{a}_{n} & \bar{b}_{n} \end{bmatrix}$$

Intermatrix becomes tridiagonal again!

- We can now break the $N \times N$ system into two $N/2 \times N/2$ independent systems that remain tridiagonal.
- We can solve the two systems simultaneously.
- We can apply the same transformation and reordering recursively!

Simultaneous Transformation of Equations: coefficients

$$\bar{\mathbf{a}}_i = \alpha_i \mathbf{a}_{i-1}, \quad \bar{\mathbf{b}}_i = \mathbf{b}_i + \alpha_i \mathbf{c}_{i-1} + \beta_i \mathbf{a}_{i+1} \\ \bar{\mathbf{c}}_i = \beta_i \mathbf{c}_{i+1}, \quad \bar{\mathbf{y}}_i = \mathbf{y}_i + \alpha_i \mathbf{y}_{i-1} + \beta_i \mathbf{y}_{i+1}$$

can be computed in parallel.

② Simultaneous Solution of Multiple Tridiagonal Subsystems: the reduced two $N/2 \times N/2$ system remains tridiagonal and can be solved independently.

- Breaking the tridiagonal system until the system is easily solvable (e.g., 2 × 2 system) takes log n recursive calls.
- (In sequential computation) Diving each system into subsystem requires Θ(n) operations
- Solving each of the $\Theta(n)$ trivial subsystems takes O(1) operations.
- The total work is $\Theta(n \log n)$.
- Solution $\Theta(\log n)$ time with *n*-fold parallelism.

Banded and Tridiagonal Linear System

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- Sequential version is completed.
- Multi-threading: Simultaneous solution provides more speed up than simultaneous transformation.
- We are designing a scheme to assign processes to execute the nested function calls.
- We are devising ways to reuse the arrays in the subsequent recursive calls to reduce the allocations.

- Solving block tridiagonal systems (block in the form of diagonal/tridiagonal matrices)
- Solving linear systems associated with PDEs such as the Poisson's equation
- S Combining with other iterative or direct methods