

18.337 Final Project: Solving the Grad-Shafranov Equation w/ NeuralPDE.jl

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May 15, 2023

1 Background

Tokamaks are magnetic confinement fusion (MCF) devices that use large magnets to confine the plasma in a toroidal, donut-like, shape and have been the primary focus of fusion energy research for the past several decades. Plasmas are inherently highly unstable, thus fast real-time control algorithms are necessary to make adjustments to the magnets to maintain plasma stability. One necessary condition is to keep the plasma in an *Ideal Magnetohydrodynamic (MHD) Equilibrium*, that is, the plasma must satisfy the following system of partial differential equations in 3D space (PDEs):

$$\mathbf{J} \times \mathbf{B} = \nabla p \tag{1}$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} \tag{2}$$

$$\nabla \cdot \mathbf{B} = 0 \tag{3}$$

where \mathbf{J} is the current density, \mathbf{B} is the magnetic field, and p is the pressure. Tokamaks are symmetric in the sense that every “slice of the donut” is the same. By leveraging this symmetry, Ideal MHD equilibria for tokamaks are described by the 2D Grad-Shafranov equation [3, 4]:

$$\frac{\partial^2 \psi(r, z)}{\partial r^2} - \frac{1}{r} \frac{\partial \psi(r, z)}{\partial r} + \frac{\partial^2 \psi(r, z)}{\partial z^2} = -\mu_0 r^2 \frac{dp(\psi)}{d\psi} - \frac{1}{2} \frac{d}{d\psi}(F^2(\psi)) \tag{4}$$

where ψ is a quantity known as the *poloidal magnetic flux* and is related to the magnetic field in the poloidal plane (see Figure 1 for a description), p is the pressure, and $F = rB_\theta$ where B_θ is a component of the magnetic field. Plasma control systems often need access to the full ψ contours for control tasks, e.g. controlling the shape of the ψ contours [1], however only ψ values at the edge can be directly measured and thus ψ everywhere else must be inferred, a problem known as *equilibrium reconstruction*. This is done with external measurements, or a priori information on, p , F , and boundary conditions on ψ and then solving the Grad-Shafranov equation. The challenging real-time constraints generally force compromises on real-time algorithms solving the Grad-Shafranov equation, and prior works have explored training neural networks on offline, higher fidelity, solutions to obtain better real-time results [5]. Instead of training on offline solutions to another solver, the goal of this work is to instead obtain a general real-time capable neural network solver for the Grad-Shafranov equation using the tools available in NeuralPDE.jl [6].

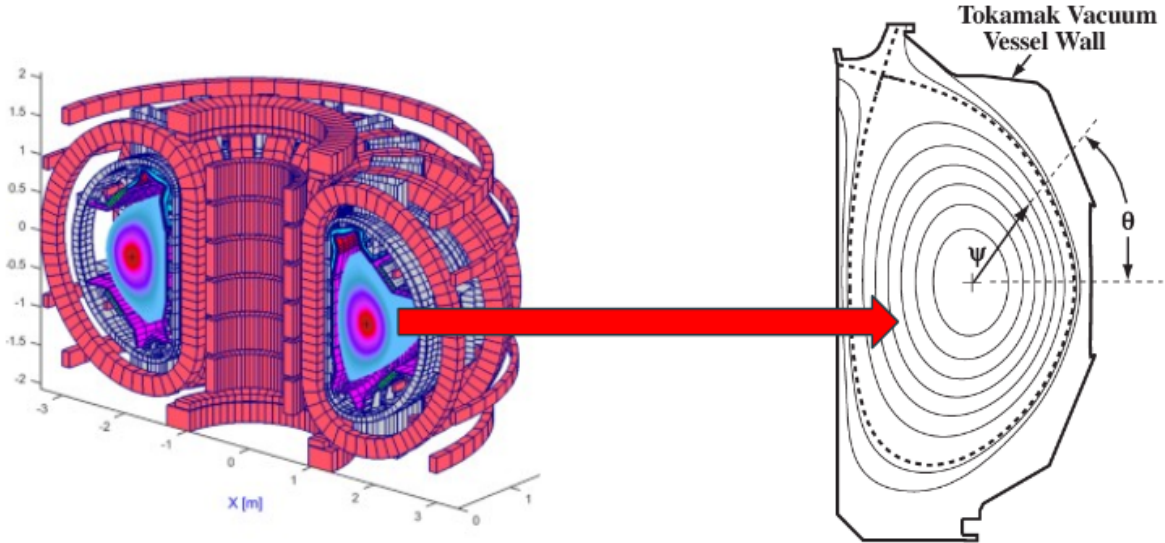


Figure 1: (Left) Cross-section of a tokamak showing magnets and plasma and (right) a “poloidal plane” showing contours of constant ψ .

2 Problem Setup

For an initial test problem, I tried to replicate example 5 in FreeGS, an open source Grad-Shafranov solver [2]. I obtained the p and F profiles for that example (Figure 2). The primary challenge of this problem relative to existing examples is that p and F must be constant with respect to normalized flux:

$$\psi_n(r, z) \equiv \frac{\psi(r, z)}{\max_{r,z} \psi(r, z)} \quad (5)$$

That is, the following quantities are fixed:

$$p(\psi_n) \quad F(\psi_n) \quad (6)$$

However, the Grad-Shafranov equation has the following:

$$\frac{dp(\psi)}{d\psi} \quad \frac{d}{d\psi}(F^2(\psi)) \quad (7)$$

To address this problem, I introduce a scale factor c and added the following additional loss term:

$$\left\| \frac{1}{\max_{r,z} \psi(r, z)} - c \right\| \quad (8)$$

in doing so, I identified a documentation inconsistency with the code that will now be fixed <https://github.com/SciML/NeuralPDE.jl/issues/679>. With this c parameter, we can

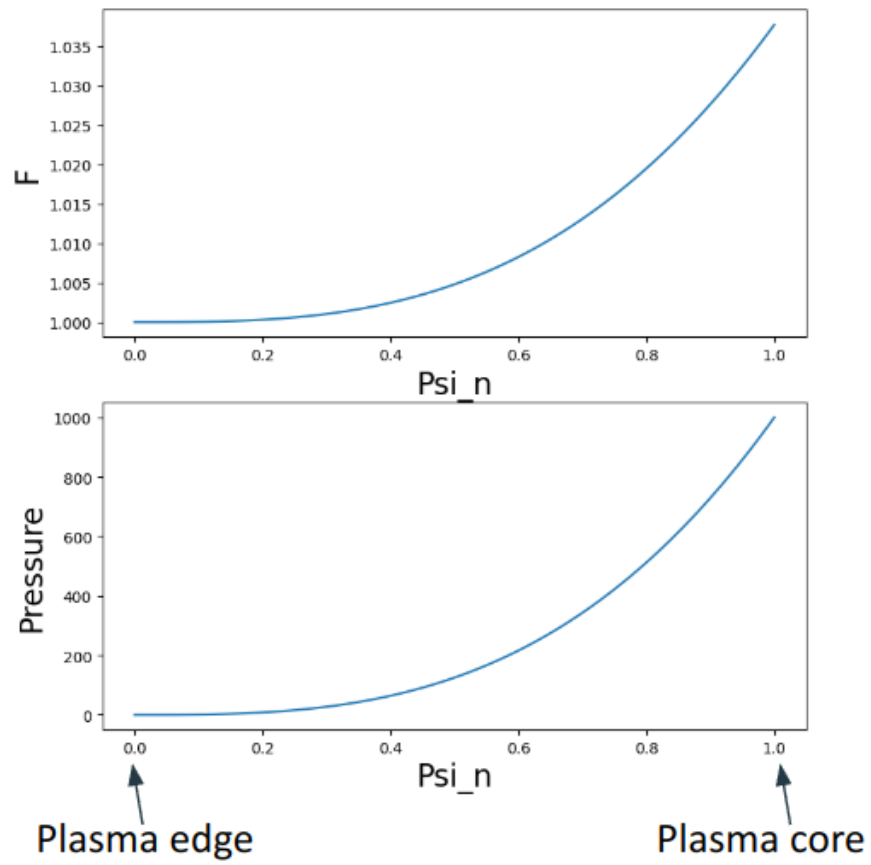


Figure 2: p and F profiles as functions of ψ_n for Example 5 of FreeGS

approximate the quantities in the Grad-Shafranov equation with the following functions of ψ_n :

$$\frac{dp(\psi)}{d\psi} \approx c \frac{dp(\psi_n)}{d\psi_n} \quad (9)$$

$$\frac{d}{d\psi}(F^2(\psi)) \approx 2c \frac{d}{d\psi_n}(F^2(\psi_n)) \quad (10)$$

3 Solving the Problem

The standard functionality of NeuralPDE.jl was used to solve the problem (source code attached). Typically, the loss would decrease to about 10^{-1} but then it would stop decreasing. In almost all solution attempts of the ψ function made, a banded structure such as the one shown in Figure 4 would occur. I tried quite a number of techniques to fix the problem to no avail; they include but are not limited to:

1. Using different learning rate schedules (e.g. 0.05 for 5000 iterations followed by 0.025 for 5000 then 0.01 for 5000, etc.)
2. Using BFGS in addition to Adam
3. Manually checked the underlying model with `build_symbolic_loss_function`, it looks correct
4. Introducing a convexity metric into the loss function by taking finite differences on ψ to include $\frac{d^2\psi}{dr^2}$ in the loss function
5. Both grid and quadrature training
6. Introducing $\frac{\partial\psi(r,z)}{\partial r}$ and $\frac{\partial\psi(r,z)}{\partial z}$ as additional dependent variables to solve for with boundary conditions relating them to $\psi(r, z)$
7. Using ψ_n as the dependent variable instead thus making the formulation look like $\frac{1}{c} \frac{\partial^2\psi_n}{\partial r^2} - \frac{1}{rc} \frac{\partial\psi_n}{\partial r} + \frac{1}{c} \frac{\partial^2\psi_n}{\partial z^2} = -\mu_0 r^2 c \frac{dp}{d\psi_n}(\psi_n) - 2c \frac{d}{d\psi_n}(F^2)$
8. Using different RNG seeds

4 Summary and Outlook

Solving the Grad-Shafranov equation faster would help enhance the abilities of plasma control systems as current real-time Grad-Shafranov solvers have to make compromises due to the extremely challenging real-time constraints. In this work, I tried exploring using NeuralPDE.jl to solve an example problem, but the solution always converges to a banded-structure that doesn't properly solve the problem. A number of different techniques were tried to no avail. Given that a decision has been made to rewrite NeuralPDE.jl (<https://github.com/SciML/NeuralPDE.jl/issues/687>), it is likely a good idea to wait for the new version before attempting further investigation.

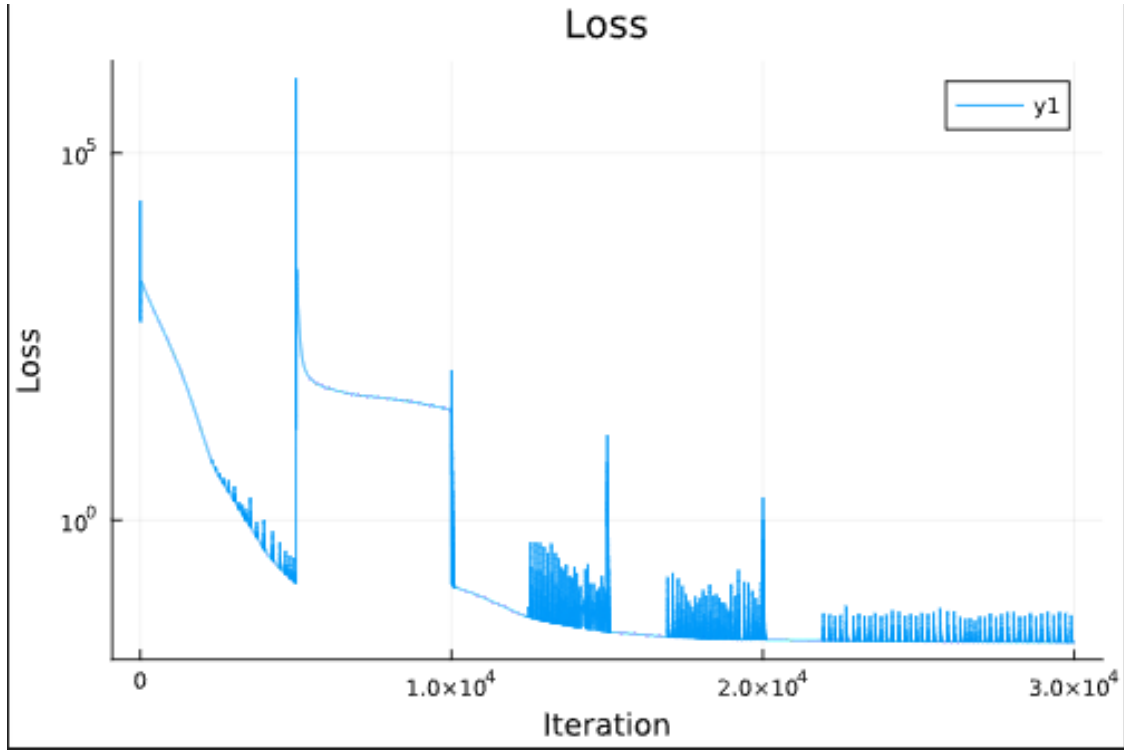


Figure 3: Typical loss curve. The large jump occurred upon restarting the optimization with a new learning rate.

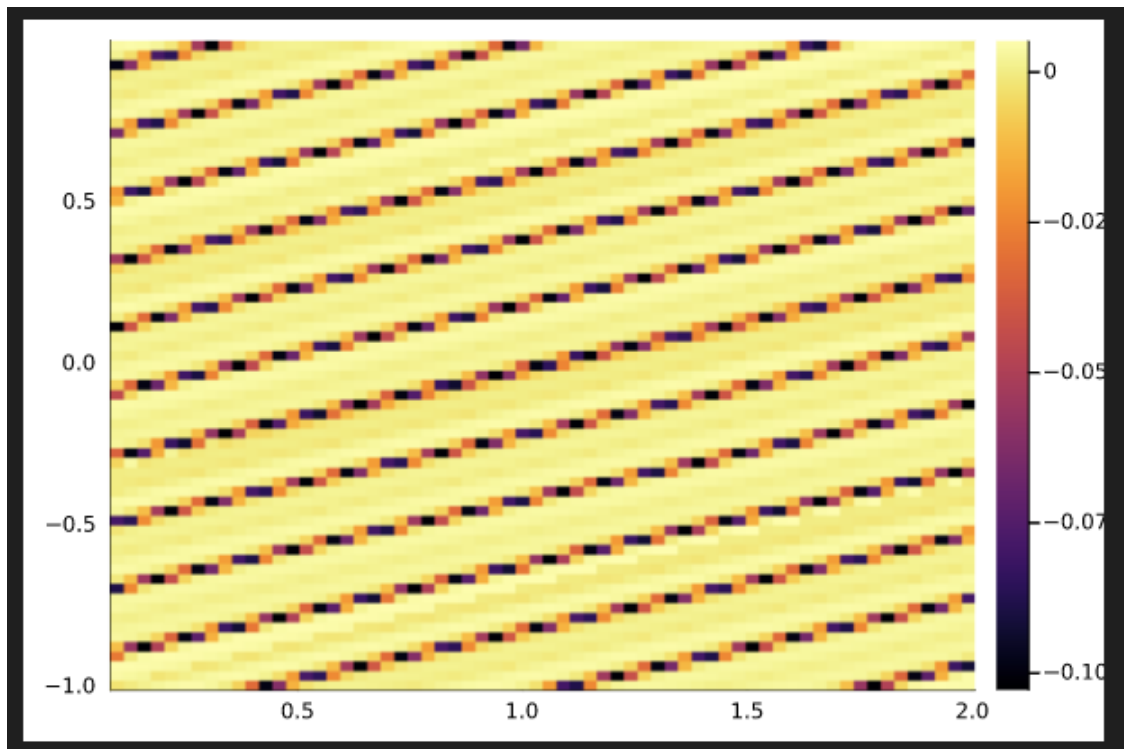


Figure 4: Typical plot of the ψ solution

References

- [1] Jonas Degraeve, Federico Felici, Jonas Buchli, Michael Neunert, Brendan Tracey, Francesco Carpanese, Timo Ewalds, Roland Hafner, Abbas Abdolmaleki, Diego de Las Casas, et al. Magnetic control of tokamak plasmas through deep reinforcement learning. *Nature*, 602(7897):414–419, 2022.
- [2] Ben Dudson. freegs. <https://github.com/freegs-plasma/freegs>, 2023.
- [3] Harold Grad and Hanan Rubin. Hydromagnetic equilibria and force-free fields. *Journal of Nuclear Energy (1954)*, 7(3-4):284–285, 1958.
- [4] Vitaly Dmitrijevitch Shafranov. Equilibrium of a toroidal plasma in a magnetic field. *Journal of Nuclear Energy. Part C, Plasma Physics, Accelerators, Thermonuclear Research*, 5(4):251, 1963.
- [5] JT Wai, MD Boyer, and E Kolemen. Neural net modeling of equilibria in nstx-u. *Nuclear Fusion*, 62(8):086042, 2022.
- [6] Kirill Zubov, Zoe McCarthy, Yingbo Ma, Francesco Calisto, Valerio Pagliarino, Simone Azeglio, Luca Bottero, Emmanuel Luján, Valentin Sulzer, Ashutosh Bharambe, et al. Neuralpde: Automating physics-informed neural networks (pinns) with error approximations. *arXiv preprint arXiv:2107.09443*, 2021.

```
In [ ]: using NeuralPDE, Lux, ModelingToolkit, Optimization, OptimizationOptimisers,
import ModelingToolkit: IntervalDomain, infimum, supremum
```

```
In [ ]: vars = npzread("profiles.npz")
psis = vars["psis"]
psin = psis/(maximum(psis) - minimum(psis))

pprime_interp = LinearInterpolation(psin, vars["pprime"], extrapolation_bc=L
ffprime_interp = LinearInterpolation(psin, vars["ffprime"], extrapolation_bc

function pprime_interp_f(psi)
    return pprime_interp(psi)
end

function ffprime_interp_f(psi)
    return ffprime_interp(psi)
end

# Without these two lines, a function overload that accepts floats just does
pprime_interp_f(0.0)
ffprime_interp_f(0.5)

# Register the functions.
@register pprime_interp_f(psi)
@register ffprime_interp_f(psi)
```

```
In [ ]: @parameters r, z, scale
@variables psi(..), Drpsi(..), Dzpsi(..)

Dr = Differential(r)
Drr = Differential(r)^2
Dz = Differential(z)
Dzz = Differential(z)^2
mu0 = 4.0 * pi * 1e-7

eq = Dr(Drpsi(r, z)) - 1.0/r * Drpsi(r, z) + Dz(Dzpsi(r, z)) ~
    -mu0 * r^2 * scale * pprime_interp_f(scale*psi(r, z)) - 2 * scale * ffpr

# Space and time domains
domains = [
    r ∈ IntervalDomain(0.1, 2.0),
    z ∈ IntervalDomain(-1.0, 1.0)
]

dx = 0.03
rs, zs = [infimum(d.domain):(dx):supremum(d.domain) for d in domains]

rs = Vector(rs)
zs = Vector(zs)

function additional_loss(phi, θ, p)
    c = p[1] # Scale factor.
    psi_eval = (r, z) -> phi[1]([r, z], θ[:psi])[1]
```

```

# Evaluate the maximum and minimum at the z=0 plane.
psis = psi_eval.(rs, 0.0)
psi_max = maximum(psis)
psi_min = minimum(psis)
psi_diff = psis[2:end] - psis[1:end-1]
psi_diff2 = psi_diff[2:end] - psi_diff[1:end-1]
return 100.0 * abs2((1.0/psi_max - c))
end

# Boundary conditions
bcs = [
  psi(0.1, z) ~ 0.0, psi(2.0, z) ~ 0.0,
  psi(r, -1.0) ~ 0.0, psi(r, 1.0) ~ 0.0,
  Dr(psi(r, z)) ~ Drpsi(r, z),
  Dz(psi(z, z)) ~ Dzpsi(r, z),
]

```

$$\psi(0.1, z) = 0.0 \quad (1)$$

$$\psi(2.0, z) = 0.0 \quad (2)$$

$$\psi(r, -1.0) = 0.0 \quad (3)$$

$$\psi(r, 1.0) = 0.0 \quad (4)$$

$$\frac{d}{dr} \psi(r, z) = \text{Drpsi}(r, z) \quad (5)$$

$$\frac{d}{dz} \psi(z, z) = \text{Dzpsi}(r, z) \quad (6)$$

```

In [ ]: # Neural network
dim = 2 # number of dimensions

vars = [psi(r, z), Drpsi(r, z), Dzpsi(r, z)]
chains = [Lux.Chain(Dense(dim, 16, Lux.σ), Dense(16, 16, Lux.σ), Dense(16, 16, Lux.σ))]

# Seeding
rng = Random.default_rng()
Random.seed!(rng, 420)
for chain in chains
  Lux.setup(rng, chain).|> gpu
end

discretization = PhysicsInformedNN(chains, QuadratureTraining(), additional_

@named pde_system = PDESystem(eq, bcs, domains, [r, z], vars, [scale], default_
prob = discretize(pde_system, discretization)

```


OptimizationProblem. In-place: true

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u0: ComponentVector{Float64}(depvar = (psi = (layer_1 = (weight = [-0.5222790
837287903 0.2450590282678604; 0.24435700476169586 0.1965530663728714; ... ; -0.
5399954915046692 0.31157130002975464; -0.020784961059689522 0.545043766498565
7], bias = [0.0; 0.0; ... ; 0.0; 0.0;]), layer_2 = (weight = [-0.2224248945713
0432 0.0797654464840889 ... 0.3757952153682709 0.15557150542736053; -0.18783475
45862198 -0.31503376364707947 ... -0.10993435978889465 -0.13735470175743103; ...
; 0.3551483750343323 0.15315645933151245 ... -0.28155404329299927 -0.0844416245
8181381; -0.2335842251777649 0.12314730882644653 ... 0.06038163974881172 -0.131
67117536067963], bias = [0.0; 0.0; ... ; 0.0; 0.0;]), layer_3 = (weight = [0.3
340683579444885 -0.07777102291584015 ... 0.45195043087005615 0.3676756918430328
4], bias = [0.0;]), Drpsi = (layer_1 = (weight = [-0.054033536463975906 0.4
119073450565338; -0.441193163394928 -0.56633061170578; ... ; 0.0294930413365364
07 -0.22794397175312042; 0.028729284182190895 -0.2146928608417511], bias =
[0.0; 0.0; ... ; 0.0; 0.0;]), layer_2 = (weight = [-0.13559329509735107 -0.111
10404878854752 ... 0.07901331037282944 0.28638899326324463; -0.3807540535926819
-0.29612699151039124 ... 0.40122872591018677 0.23254482448101044; ... ; -0.269849
35998916626 -0.27580526471138 ... -0.0014545239973813295 0.34738361835479736; -
0.40942221879959106 0.2895776629447937 ... 0.403973788022995 -0.033536486327648
16], bias = [0.0; 0.0; ... ; 0.0; 0.0;]), layer_3 = (weight = [0.0520434975624
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; 0.0; 0.0;]), layer_2 = (weight = [0.10484801232814789 0.382907509803772 ...
0.0547507144510746 -0.2697623670101166; 0.20850497484207153 -0.32748779654502
87 ... -0.11751493811607361 0.19711211323738098; ... ; 0.40632104873657227 0.1997
4587857723236 ... 0.37682831287384033 0.024786941707134247; -0.2799744904041290
3 -0.4199541509151459 ... -0.3284936547279358 0.2347298115491867], bias = [0.0;
0.0; ... ; 0.0; 0.0;]), layer_3 = (weight = [0.4409675896167755 0.010308898985
385895 ... 0.25882217288017273 0.5142514109611511], bias = [0.0;])), p = [20.
0])
```

```
In [ ]: losses = []

callback = function (p, l)
    append!(losses, l)
    if length(losses) % 100 == 0
        println("Current loss is: $l")
    end
    return false
end

res = Optimization.solve(prob, ADAM(0.05); callback = callback, maxiters = 5
prob = remake(prob, u0 = res.minimizer)
res = Optimization.solve(prob, ADAM(0.01); callback = callback, maxiters = 5
prob = remake(prob, u0 = res.minimizer)
res = Optimization.solve(prob, ADAM(0.005); callback = callback, maxiters =
prob = remake(prob, u0 = res.minimizer)
res = Optimization.solve(prob, ADAM(0.0025); callback = callback, maxiters =
prob = remake(prob, u0 = res.minimizer)
res = Optimization.solve(prob, ADAM(0.001); callback = callback, maxiters =
```

Current loss is: 1567.2871062299068
Current loss is: 1217.7537544693432
Current loss is: 971.8251341341283
Current loss is: 786.3138271898505
Current loss is: 635.9554596827132
Current loss is: 513.4599873308053
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Current loss is: 336.8634841365945
Current loss is: 272.2206355922599
Current loss is: 218.50839356196158
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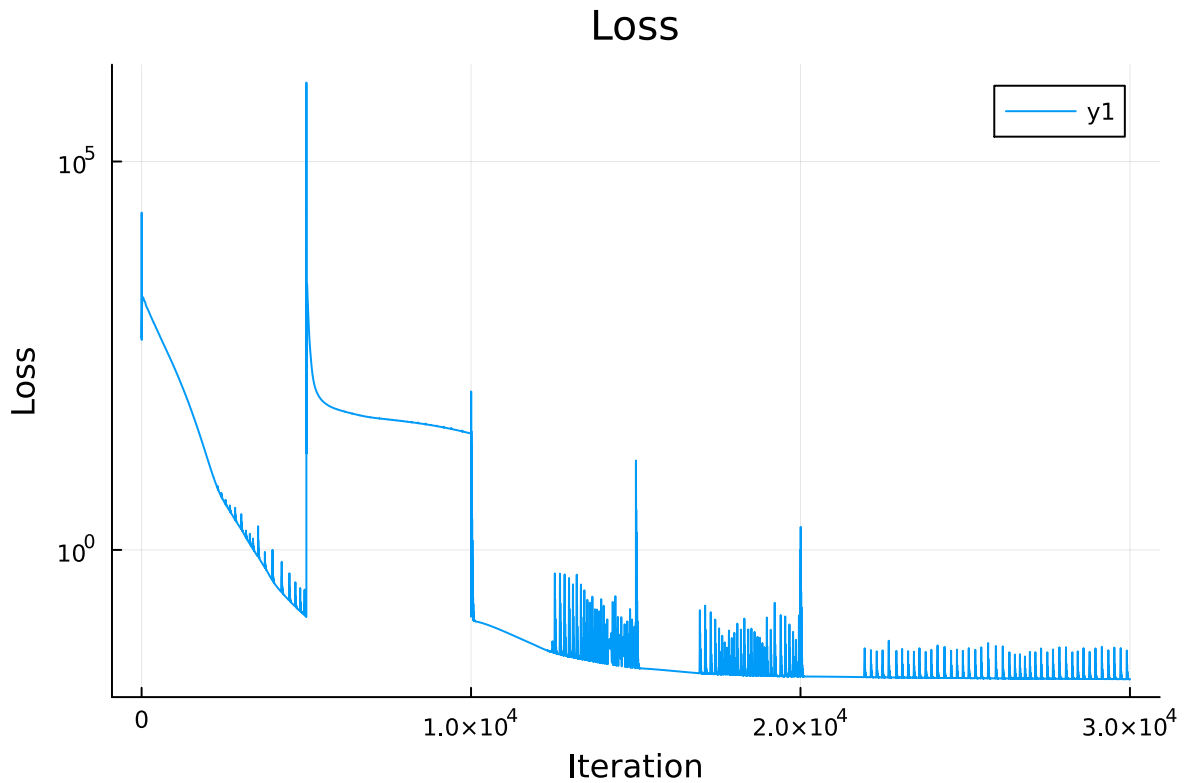
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Current loss is: 0.02427508117438649
Current loss is: 0.023536980346281593
Current loss is: 0.023445934646816418
Current loss is: 0.023431718470437013
Current loss is: 0.02341690222594708
Current loss is: 0.02340037041137554
Current loss is: 0.023382129385148907
Current loss is: 0.023362588234505148
Current loss is: 0.02334214649586923
Current loss is: 0.02332002648144195
Current loss is: 0.023297297882105623
Current loss is: 0.023273359846577107
Current loss is: 0.023248429657171794
Current loss is: 0.023222282762422
Current loss is: 0.023194722984578767
Current loss is: 0.023166911953231926
Current loss is: 0.023138010546541948
Current loss is: 0.02310828400543892
Current loss is: 0.023077090897505093
Current loss is: 0.023045667482288066
Current loss is: 0.023206886003762462
Current loss is: 0.022987673638717336
Current loss is: 0.02299085365200115
Current loss is: 0.023107252833889813
Current loss is: 0.02290813652815811

Current loss is: 0.032672311435033685
Current loss is: 0.02285556130673597
Current loss is: 0.02305499828964112
Current loss is: 0.022809942905112554
Current loss is: 0.023683671406962235
Current loss is: 0.022760357324779806
Current loss is: 0.02798607060043494
Current loss is: 0.022714510981985778
Current loss is: 0.022723862957439316
Current loss is: 0.02267252158531061
Current loss is: 0.022655819299035363
Current loss is: 0.023180515986667833
Current loss is: 0.022615738915579595
Current loss is: 0.045024627093115256
Current loss is: 0.022564582621796947
Current loss is: 0.023809693827513245
Current loss is: 0.022526513798241384
Current loss is: 0.022865058859969943
Current loss is: 0.022487136774049756
Current loss is: 0.023405540269622663
Current loss is: 0.02245033809849987
Current loss is: 0.023424966913418808
Current loss is: 0.022411996433323166
Current loss is: 0.022497340519671456
Current loss is: 0.0223750832706941
Current loss is: 0.022384630547681066
Current loss is: 0.024395846693324178
Current loss is: 0.022331828330905763
Current loss is: 0.02782205938891775
Current loss is: 0.022295131567034655
Current loss is: 0.025413879170308292
Current loss is: 0.02225759304916228
Current loss is: 0.02523179080236041
Current loss is: 0.022229579531831717
Current loss is: 0.022210153758341514
Current loss is: 0.02219917582790636
Current loss is: 0.022178288766957398
Current loss is: 0.022212072281368095
Current loss is: 0.02214808605474029
Current loss is: 0.022132398726998882
Current loss is: 0.024483994045063
Current loss is: 0.02211244196143023
Current loss is: 0.022433424429411805
Current loss is: 0.022498087272275112
Current loss is: 0.022057130616408134
Current loss is: 0.022386666809776766
Current loss is: 0.02202918539426679
Current loss is: 0.022054885775950987
Current loss is: 0.035668123388169416
Current loss is: 0.021995146444960527
Current loss is: 0.03180832247900964
Current loss is: 0.021960539056283125
Current loss is: 0.022651617282126762
Current loss is: 0.021936464626198107
Current loss is: 0.022345134969981577
Current loss is: 0.02191046486999173

```
Current loss is: 0.0222789161188733
Current loss is: 0.021883969278565042
Current loss is: 0.021885103249248083
Current loss is: 0.021998532641358804
Current loss is: 0.021851261130678624
Current loss is: 0.032413200113537
Current loss is: 0.02182023575360416
Current loss is: 0.02394182307176615
Current loss is: 0.021795620552546274
Current loss is: 0.021799011928735172
Current loss is: 0.021770625257576427
Current loss is: 0.021863645637438197
Current loss is: 0.021746483966655822
Current loss is: 0.021750212677520846
Current loss is: 0.02172902856879842
Current loss is: 0.02173596182654484
Current loss is: 0.02172951799389933
Current loss is: 0.021688038827991887
Current loss is: 0.026741131057687745
Current loss is: 0.02166380540130919
u: ComponentVector{Float64}(depvar = (psi = (layer_1 = (weight = [-0.66923063
71595532 18.425410519170093; -0.1505369418382242 10.636163368045624; ... ; -0.5
86136977955502 -23.59086974144638; -0.3662618904943838 -1.7641232836621157],
bias = [-0.09419355523421064; -0.15479595791973194; ... ; -0.5807254249726345;
-0.8709768432798962;;]), layer_2 = (weight = [-0.5267117362365629 -0.14200824
502927392 ... 0.4688551513618925 0.0009987090118028221; -1.3039552249468083 -0.
5299225558254037 ... -0.6654225027223537 -0.4531270276039166; ... ; 0.26884585130
121913 -0.04215633633587162 ... -0.49848065931072516 -0.2686186907861078; -0.48
19546466307932 -0.05307944383447722 ... 0.2153093393831614 -0.259214861063533
2], bias = [-0.15508410573880693; -0.7452803805176187; ... ; -0.176674999963461
28; -0.11935418993473192;;]), layer_3 = (weight = [0.25234917616251584 -0.131
72307123914112 ... 0.31210403676559034 0.2888075830376271], bias = [0.120955609
96395993;;])), Drpsi = (layer_1 = (weight = [-3.6168901635020156 8.4159801629
64662; 2.715488442973611 -9.267227788931022; ... ; 2.9294238002406097 -2.753659
290095273; -0.16062441728819207 -6.250794692687454], bias = [0.86653820072721
91; 0.048129350946179296; ... ; -1.0170044042922903; -0.22446265647946276;;]),
layer_2 = (weight = [-0.8061322582371894 -0.5849637646164765 ... -0.54156242940
65029 -0.2721648024609249; -1.0355358607698848 -0.7070570573888194 ... 0.094262
66567017963 0.8193864820421471; ... ; -0.9819066901329443 -1.1419297846733103 ...
-0.6359790201531179 0.9789629465632668; -0.9807419889600515 -0.19458286274863
64 ... -0.06875234588772616 0.1615392066296994], bias = [-0.5825989704498492; -
0.19388345753405944; ... ; -0.09150233396270939; -0.33963849164202264;;]), laye
r_3 = (weight = [0.08858100352038073 0.857961174371266 ... 0.7715847272616732
0.235416235356368], bias = [0.08037131936706753;;])), Dzpsi = (layer_1 = (wei
ght = [-1.5147455944389892 -0.9721012504428336; -7.675801695482528 1.18219953
57165604; ... ; 0.426627740068026 -1.7465701766752733; 1.346243295705222 -0.031
31400832701576], bias = [-0.843892418042364; -3.6060851209522338; ... ; -0.7334
325045083282; 0.4588722659278727;;]), layer_2 = (weight = [-0.497510228940908
8 0.23837005287463442 ... -0.7454879618445904 -1.1810210540753716; 1.8347052396
07666 -5.654690688226655 ... 0.7371658155796983 0.7892749109900493; ... ; -0.6406
427442465615 -1.8747289079264533 ... 0.939462034107082 0.8368721176422634; -1.5
524493055412232 -1.0954504785697987 ... -1.4708869212493991 0.01068866485382321
6], bias = [-0.7532080240770771; -1.4633917615384286; ... ; 0.0177451719662897
8; 0.31534271328774127;;]), layer_3 = (weight = [0.7555879712439234 -1.510675
6183913719 ... 0.9511512454855499 0.760118670228731], bias = [0.027574014937335
88;;]))), p = [-9.691406701475902])
```

```
In [ ]: plot(losses, title="Loss", xlabel="Iteration", ylabel="Loss",yscale=:log10)
```



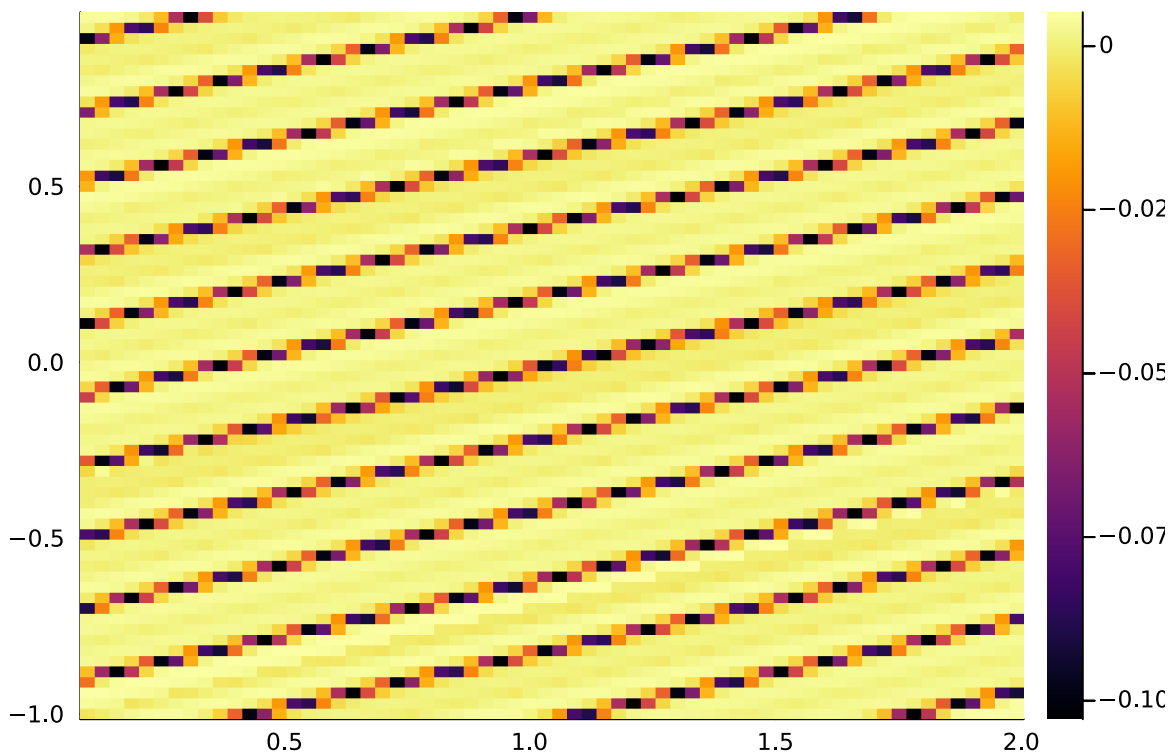
```
In [ ]: phi = discretization.phi
scale_res = res.u[end]

psi_predict = reshape([phi[1]([r, z], res.u.depvar[:psi])[1] for r in rs for
psi_min = minimum(psi_predict)
psi_max = maximum(psi_predict)
println("Scale factor is: $scale_res")
println("Psi min is: $psi_min")
println("Psi max is: $psi_max")
heatmap(rs, zs, psi_predict)
```

Scale factor is: -9.691406701475902

Psi min is: -0.1028266564892037

Psi max is: 0.005196024798997223



```
In [ ]: # Calculate the RHS.
p_term = reshape([-mu0 * r^2 * scale_res * pprime_interp_f(scale_res*phi[1])(
ff_term = reshape([-0.58814188 * ffprime_interp_f(scale_res*phi[1])([r, z], r
rhs = p_term + ff_term

# Calculate the LHS
dz = (1.0/dx).*(psi_predict[2:end, :] .- psi_predict[1:end-1, :])
dr = (1.0/dx).*(psi_predict[:, 2:end] .- psi_predict[:, 1:end-1])

dz = vcat(zeros(1, size(dz, 2)), dz)
dr = hcat(zeros(size(dr, 1), 1), dr)

dzz = (1.0/dx).*(dz[2:end, :] .- dz[1:end-1, :])
drr = (1.0/dx).*(dr[:, 2:end] .- dr[:, 1:end-1])

dzz = vcat(zeros(1, size(dzz, 2)), dzz)
drr = hcat(zeros(size(drr, 1), 1), drr)

lhs = dzz .+ drr .- 1.0./rs .* dr
```

64×67 Matrix{Float64}:

```

 0.0      1.5041   -0.902782  ... -0.0332397  0.0394222  0.108373
 0.281751  0.402389 -0.418053  ...  0.13112    0.24915    0.355347
-0.00776092 0.331438  1.07975   ... -0.153555  -0.0932404 -0.0380712
-0.00921045 -0.955254  2.59983   ... -0.189654  -0.127641  -0.0775582
-0.0107754  0.565665  1.87555   ... -0.228537  -0.1552    -0.10828
-0.0124629 -0.616758  1.10674   ... -0.28133   -0.179713  -0.133191
-0.0142812 -0.591377 -0.421881  ... -0.366663  -0.205089  -0.154196
-0.0162405 -0.558567  1.20661   ... -0.519368  -0.236941  -0.172912
-0.0183533 -0.518467 -0.0905553 ... -0.807374  -0.284929  -0.191246
-0.0206364 -0.470994 -0.118425  ... -1.36527   -0.367057  -0.212103
  ⋮
-0.0639672  0.6268   -0.94748   ... -0.270207  1.77498    -0.0241417
-0.0549472  0.834342 -0.834496  ... -0.863718  2.34919    -0.0350548
-0.0469668  1.0144   -0.734414  ... -1.4526    2.91705    -0.0453139
-0.039926   1.17007   -0.645403  ...  1.85237   -0.411223   1.90613
-0.0337316  1.30414   -0.566191  ... -1.50399   -1.001      2.47392
-0.0282968  1.41913   -0.495776  ... -0.13697   -1.58569    3.03534
-0.0235396  1.5173    -0.433294  ... -0.148214  1.97883    -0.554342
-0.0193832  1.60066   -0.377962  ... -0.159025  -1.63827   -1.14036
-0.0157553  1.67102   -0.329047  ... -0.169302  -0.138298  -1.72083

```

```
In [ ]: display(heatmap(rs, zs, lhs))
display(heatmap(rs, zs, rhs))
```

