

# 1 spINAR: An R Package for Semiparametric and 2 Parametric Estimation and Bootstrapping of 3 Integer-Valued Autoregressive (INAR) Models

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## Software

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## 6 Summary

7 While the statistical literature on continuous-valued time series processes is vast and the  
8 toolbox for parametric, non-parametric and semiparametric approaches is methodologically  
9 sound, the literature on count data time series is considerably less developed. Such count data  
10 time series models are usually categorized in parameter-driven and observation-driven models.  
11 Among the observation-driven approaches, the integer-valued autoregressive (INAR) models  
12 that rely on the famous binomial thinning operation due to Steutel & Van Harn (1979) are  
13 arguably the most popular ones. They have a simple intuitive and easy interpretable structure  
14 and have been widely applied in practice (Weiß, 2009). In particular, the INAR( $p$ ) model can  
15 be seen as the discrete analogue of the well-known AR( $p$ ) model for continuous-valued time  
16 series. The INAR(1) model was first introduced by Al-Osh & Alzaid (1987) and McKenzie  
17 (1985), and its extension to the INAR( $p$ ) model by Du and Li (1991) is defined according to

$$X_t = \alpha_1 \circ X_{t-1} + \alpha_2 \circ X_{t-2} + \dots + \alpha_p \circ X_{t-p} + \varepsilon_t,$$

with  $\varepsilon_t \stackrel{\text{i.i.d.}}{\sim} G$ , where the innovation distribution  $G$  has range  $\mathbb{N}_0 = \{0, 1, 2, \dots\}$ . The vector  
of INAR coefficients  $\alpha = (\alpha_1, \dots, \alpha_p)' \in (0, 1)^p$  fulfills  $\sum_{i=1}^p \alpha_i < 1$  and

$$\alpha_i \circ X_{t-i} = \sum_{j=1}^{X_{t-i}} Z_j^{(t,i)}, \quad Z_j^{(t,i)} \sim \text{Bin}(1, \alpha_i),$$

20 where “ $\circ$ ” denotes the binomial thinning operator first introduced by Steutel & Van Harn  
21 (1979). Although many contributions have been made during the last decades, most of  
22 the literature focuses on parametric INAR models and estimation techniques. We want to  
23 emphasize the efficient semiparametric estimation of INAR models (Drost, Van den Akker, &  
24 Werker, 2009).

## 25 Statement of need

26 INAR models find applications in a wide variety of fields such as medical sciences, environ-  
27 mentology and economics. For example, Franke & Seligmann (1993) model epileptic seizure  
28 counts using an INAR(1) model, Thyregod, Carstensen, Madsen, & Arnbjerg-Nielsen (1999)  
29 use integer-valued autoregressive models to model the dynamics of rainfall and McCabe &  
30 Martin (2005) to analyze wage loss claims data. They all have in common assuming that the  
31 innovation distribution belongs to a parametric class of distributions. Non- or semiparametric  
32 estimation of the INAR model was not considered until Drost et al. (2009) came up with  
33 their semiparametric estimation approach. A possible explanation is the complexity of the  
34 semiparametric setup since despite in the AR case the estimation in the INAR case cannot

35 be based on the residuals: Even if the autoregressive coefficients were known, observing  
36 the data does not imply observing the innovations (Drost et al., 2009). Nonetheless, one  
37 big advantage of semiparametric estimation is that we do not need to make a parametric  
38 distribution assumption on the innovations. The Poisson assumption is, for example, the  
39 most frequently used assumption for innovations and is characterized by equidispersion. In  
40 most cases, however, the data shows a higher variance than the mean value. The question  
41 arises when the distance between these two moments is large enough to not rather assume  
42 overdispersion, which would probably lead to assume negative binomially or geometrically  
43 distributed innovations. Furthermore, when dealing with low counts, we often observe many  
44 zeros in the data. This could be a sign for a zero-inflated innovation distribution such as the  
45 zero-inflated Poisson distribution (Jazi, Jones, & Lai, 2012). However, it is unclear at what  
46 point the zero is represented frequently enough in the data set to justify such an assumption.  
47 The mentioned points indicate that the assumption of an appropriate innovation distribution  
48 is often critical, bearing in mind that an incorrect assumption can lead to poor estimation  
49 performance. With semiparametric estimation, we do not have to commit to an innovation  
50 distribution, which makes this approach appealing.

51 To deal with count data time series, R (R Core Team, 2023) provides the package `tscount`  
52 (Liboschik, Fokianos, & Fried, 2017) which, a.o., includes likelihood-based estimation of  
53 parameter-driven count data time series models which do not include INAR models and  
54 exclusively allows for conditional Poisson or negative binomially distributed data. The R  
55 package `ZINARp` (Medina Garay, de Lima Medina, & Rossiter Araújo Monteiro, 2022) allows to  
56 simulate and estimate INAR data by using MCMC algorithms for estimation but the package  
57 is limited to parametric estimation of INAR models, that is, of the INAR coefficients and of a  
58 parametrically specified innovation distribution  $\{G_\theta \mid \theta \in \mathbb{R}^q, q \in \mathbb{N}\}$  where they only cover  
59 the cases of Poisson or zero-inflated Poisson distributed innovations. The Julia (Bezanson,  
60 Edelman, Karpinski, & Shah, 2017) package `CountTimeSeries` (Stapper, 2022) deals with  
61 integer counterparts of ARMA and GARCH models and some generalizations including the  
62 INAR model. It covers the parametric estimation setup for INAR models but does also not allow  
63 for non-parametric estimation of the innovation distribution. Such a semiparametric estimation  
64 technique that still relies on the binomial thinning operation, but comes along without any  
65 parametric specification of the innovation distribution was proposed and proven to be efficient  
66 by Drost et al. (2009). Also neither of the three packages contains procedures for bootstrapping  
67 INAR models within these parametric and semiparametric setups. The R package `spINAR` fills  
68 this gap and combines simulation, estimation and bootstrapping of INAR models in a single  
69 package. Both, the estimation and the bootstrapping, are implemented semiparametrically and  
70 also parametrically. The package covers INAR models of order  $p \in \{1, 2\}$ , which are mainly  
71 used in applications.

## 72 Features

73 For the simulation of INAR data, our package allows for flexible innovation distributions that  
74 can be inserted in form of a parametric probability mass function (pmf) or by simply passing a  
75 user-defined vector as pmf argument. Regarding the estimation, it allows for moment- and  
76 maximum likelihood-based parametric estimation of INAR models with Poisson, geometrically  
77 or negative binomially distributed innovations (see for example Weiß (2018) for details), but  
78 the main contribution lies in the semiparametric maximum likelihood estimation of INAR  
79 models introduced by Drost et al. (2009) which they proved to be efficient. Additionally, a  
80 finite sample refinement for the semiparametric setup consisting of an estimation approach,  
81 that penalizes the roughness of the innovation distribution as well as a validation function  
82 for the penalization parameters is implemented (Faymonville, Jentsch, Weiß, & Aleksandrov,  
83 2022). Furthermore, the package includes the possibility to bootstrap INAR data. Again, the  
84 user is able to choose the parametric or the more flexible semiparametric model specification  
85 and to perform the (semi)parametric INAR bootstrap described in Jentsch & Weiß (2017).

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