







# 1 ParticleTracking: A GUI and library for particle 2 tracking on stereo camera images

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## Software

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## 6 Summary

7 The ParticleTracking software is intended to facilitate semi-automatic detection, 3D position  
8 and orientation reconstruction and tracking of arbitrarily shaped particles from 2-view stereo  
9 camera footage. The software consists of two packages, RodTracker and ParticleDetection.  
10 The ParticleDetection package provides functionality for training and application of neural  
11 networks (e.g. Mask R-CNN) for particle detection in camera images, as well as automatic  
12 3D matching and multi-object tracking of these particles. The RodTracker package is a  
13 graphical user interface (GUI) for the particle tracking task, encapsulating the functionality  
14 of ParticleDetection and providing means to manually correct the automatically generated  
15 particle coordinates and tracking data.

16 The main features of this software are given below with a more extensive feature description  
available in the documentation under <https://particletracking.readthedocs.io/en/latest/>:

- training and application of (Detectron2) Mask R-CNN models for detecting particles on images
- automated particle endpoint localization from segmentation masks
- automated assignment of particle correspondences (3D matching) between two camera views
- reconstruction of 3D coordinates and orientations of particles identified on camera images
- automated tracking of particles over multiple stereo camera frames, i.e. the course of an experiment
- providing a GUI for applying manual corrections to the automatically generated data with a typical workflow shown in [Figure 1](#)

28 The main focus of this software is currently on elongated (rod-shaped) particles, but it is  
29 extensible with new particle geometries. The software can also be modified for inclusion of  
30 additional camera views for more accurate 3D tracking, or for 1-view 2D particle tracking.  
31 The RodTracker software is currently employed for data extraction in the German Aerospace  
32 Center (DLR) projects EVA (50WM2048), VICKI (50WM2252), and CORDYGA (50WM2242).  
33 Several publications that use this library for data extraction are currently in preparation. The  
34 prototype software for particle detection and tracking was described in ([Puzyrev et al., 2020](#)).

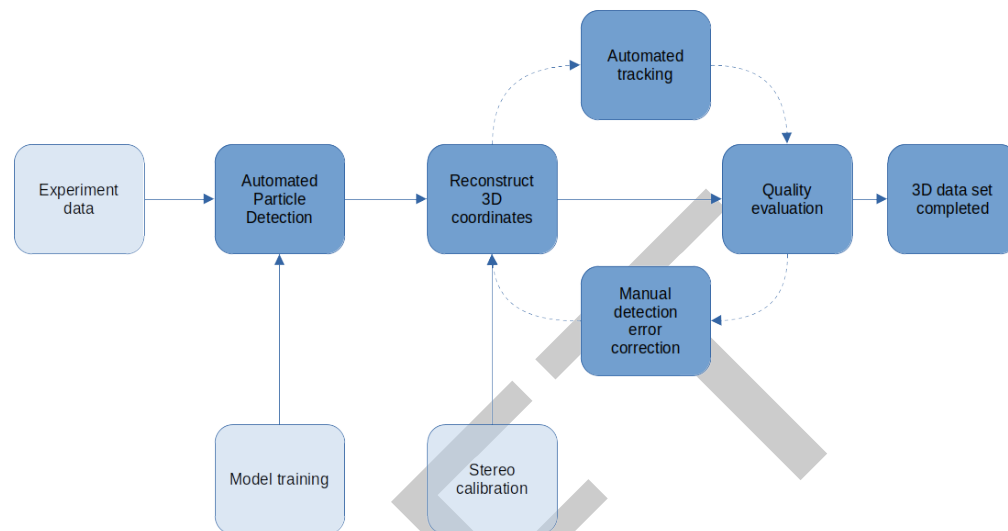


Figure 1: Typical workflow with the RodTracker for data extraction.

## Statement of need

Many natural and industrial processes deal with granular gases, i.e. dilute ensembles of macroscopic particles floating and colliding in space. One of the defining features of such systems is inelasticity of the collision, i.e. dissipation of particle kinetic energy. This leads to fascinating phenomena such as spontaneous clustering, absence of energy equipartition and non-Gaussian velocity distributions. While most of 2D experiments can be performed in normal gravity, 3D experiments with granular gases require microgravity conditions. Starting from the pioneering results on cluster formation (É. Falcon et al., 1999), 3D experiments have been reported for spherical grains (E. Falcon et al., 2006; Yu et al., 2020), ellipsoids (Pitikaris et al., 2022) and rods (K. Harth et al., 2013; Kirsten Harth et al., 2018).

In typical microgravity experiments, ensembles of particles are placed in the container, excited mechanically or magnetically and observed with a stereo-camera setup. Many experiments were performed in the VIP-Gran instrument by the Space Grains ESA Topical team (spacegrains.org) during parabolic flight campaigns. In the majority of VIP-Gran experiments, particle density does not allow for tracking individual grains.

Another possibility is to perform the experiment with dilute ensembles, where most particles can be directly observed on video footage (Kirsten Harth et al., 2018; Puzyrev et al., 2020). In this case, the focus has been on experiments with elongated particles, due to the fact that collision rates for such particles are much higher than for spheres for the same packing fraction. Thus, even if particles overlap on the camera views, usually their endpoints still can be observed and their 3D positions and orientations can be reconstructed. In addition, study of elongated particles allows to observe the evolution of their orientations and to find the kinetic energy associated with the rotational degrees of freedom. Experiments with other particle types are planned as well.

For the study of such systems, it is beneficial to know the 3D positions and orientations over time for as many particles as possible. To achieve statistically meaningful results, the tracking

61 of many tens to hundreds of particles is usually required. With that information, a reliable  
62 statistical analysis of the ensemble properties and their evolution over time can be achieved.  
63 Due to the large number of simultaneously tracked objects and their relatively high velocity,  
64 accurate experimental data analysis requires high frame rates. In one drop tower experimental  
65 run, around 9 seconds of 100 to 240 fps video footage must be analyzed. This makes manual  
66 data analysis exceptionally time-consuming. Due to the large number of overlapping particles,  
67 conventional particle detection methods based on color separation, morphological operations,  
68 and Hough transform have proven to be unstable. For this reason, an AI-assisted approach  
69 based on Matterport Mask R-CNN implementation (Abdulla, 2017; He et al., 2017) has been  
70 successfully employed (Puzyrev et al., 2020) in extraction and processing of data from the raw  
71 stereo camera images. This approach still suffered from long manual data processing times,  
72 due to the necessity to correct remaining errors after automatic particle detection, matching  
73 and tracking, as well as a suboptimal user interface to perform the correction tasks.

74 The ParticleTracking software is an evolution of the AI-assisted framework for the analysis  
75 of dilute granular ensembles, improved by the transition to the Detectron2 platform, inclusion  
76 of a GUI, and a documented and extensible codebase.

## 77 Dependencies

78 Among others, the software depends on the following open source libraries: For the particle  
79 detection the Detectron2 (Wu et al., 2019) framework is used. For tracking the software relies  
80 heavily on functions provided by numpy (Harris et al., 2020), scipy (Virtanen et al., 2020) and  
81 PuLP. The GUI was constructed with PyQt5 and is using pandas (team, 2022) for its data  
82 management.

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86 the work of Meera Subramanian and Adithya Viswanathan that provided a first prototype of  
87 the RodTracker GUI.

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