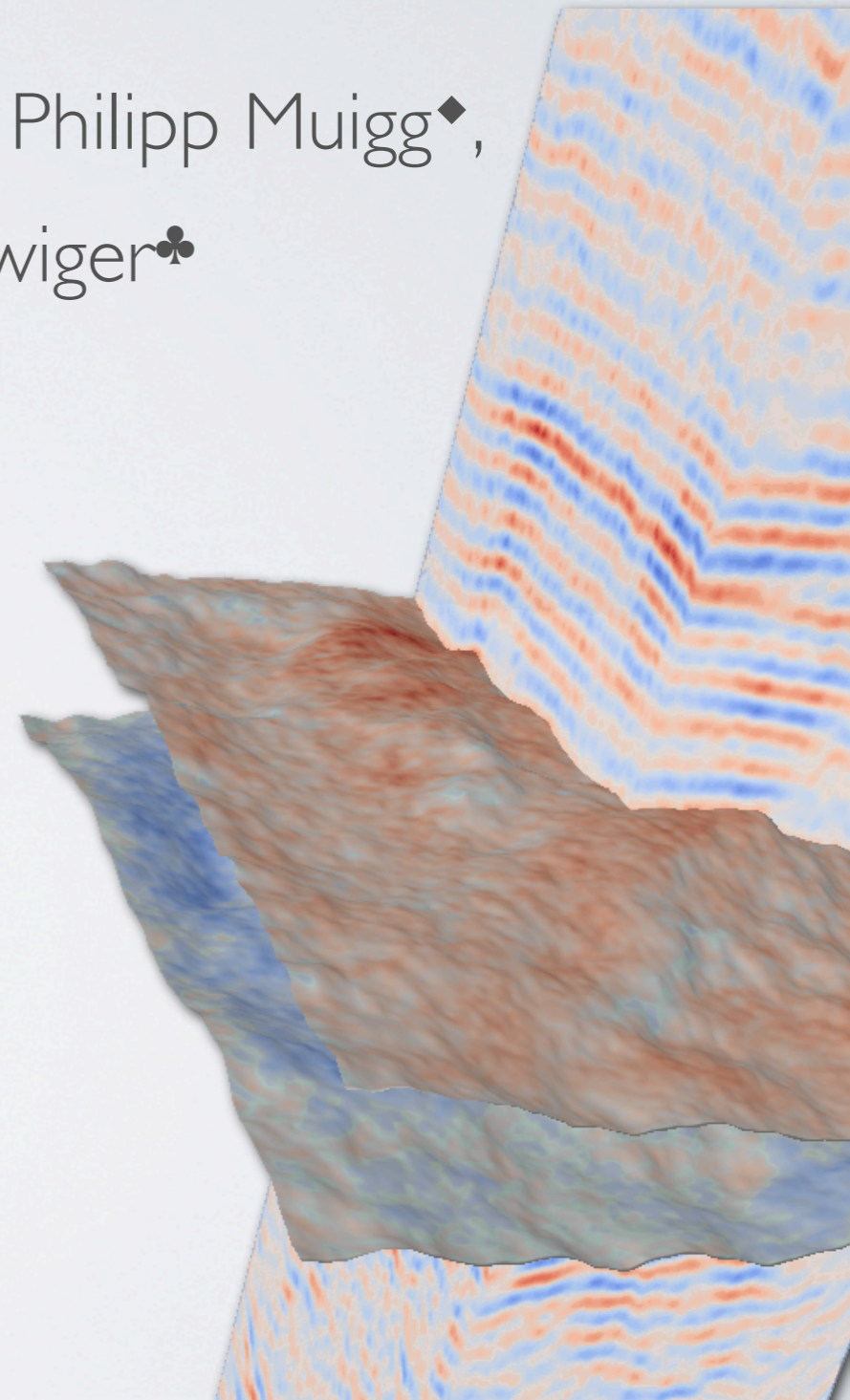


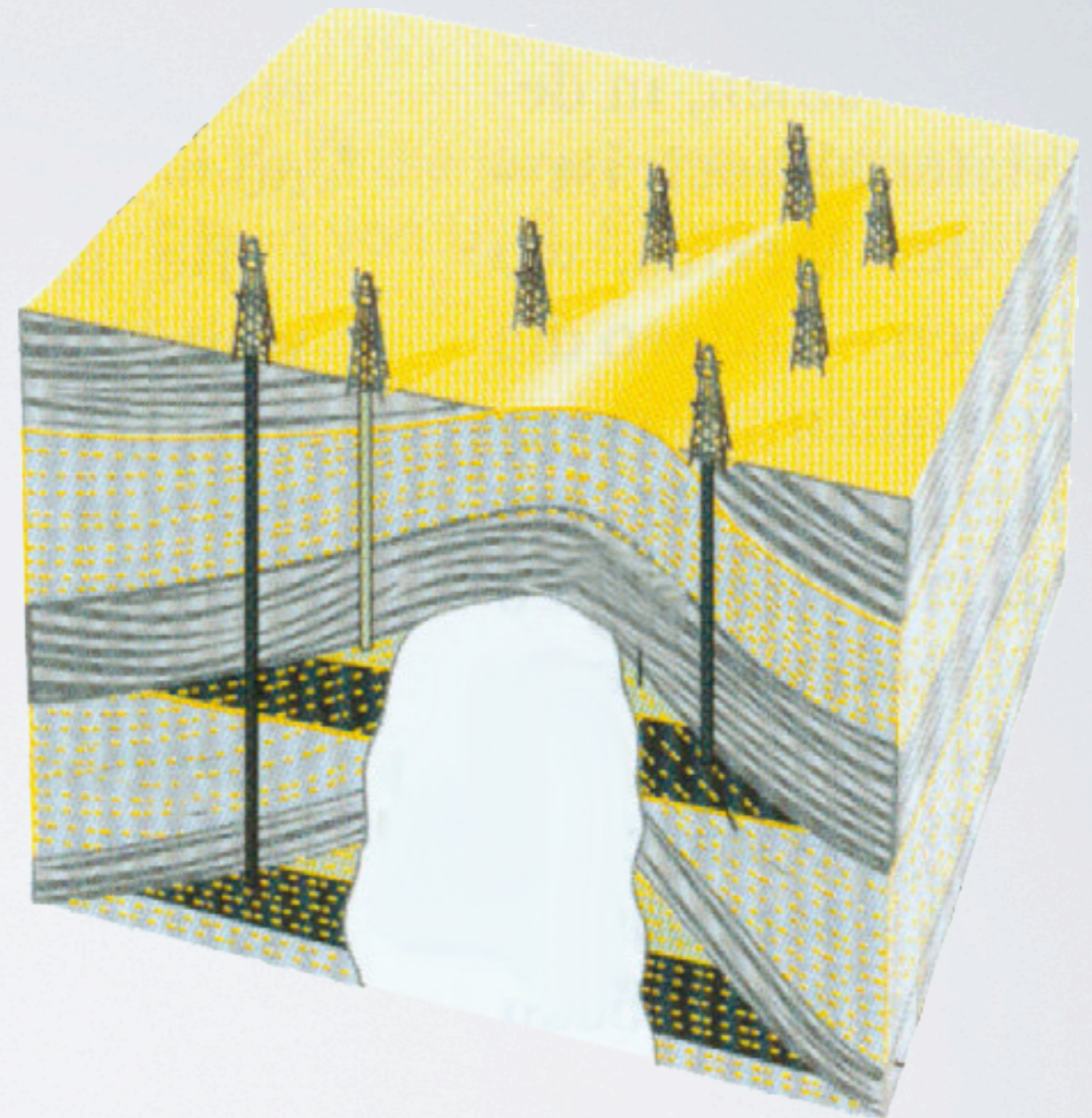
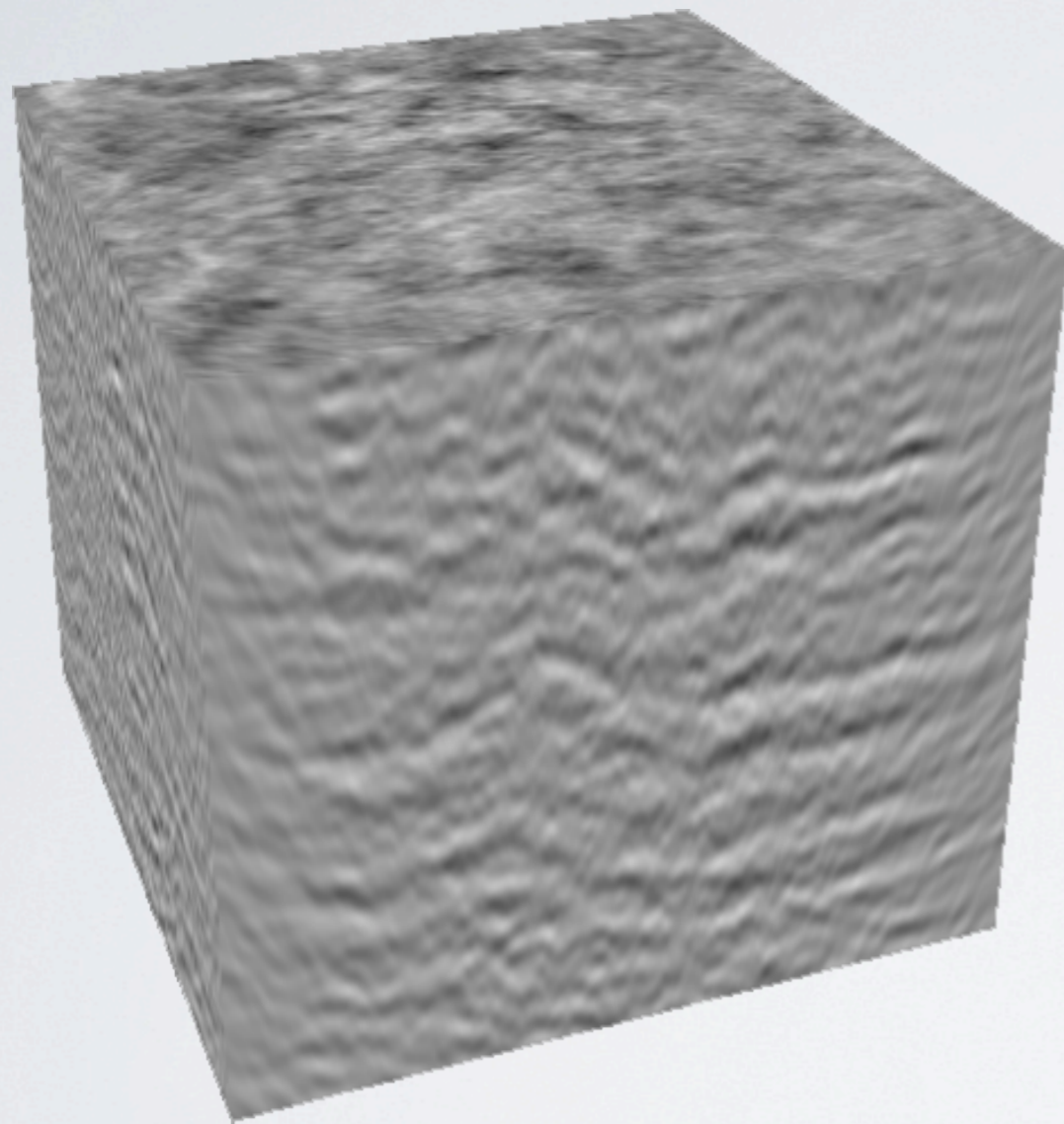
Interactive Seismic Interpretation with Piecewise Global Energy Minimization

Thomas Höllt♣, Johanna Beyer♣, Fritz Gschwantner•, Philipp Muigg♦,
Helmut Doleisch♦, Gabor Heinemann▪, Markus Hadwiger♣

- ♣ King Abdullah University of Science and Technology
- VRVis Research Center
- ♦ SimVis GmbH
- Heinemann Oil GmbH



Seismic Interpretation



Grotzinger et al.
Understanding Earth



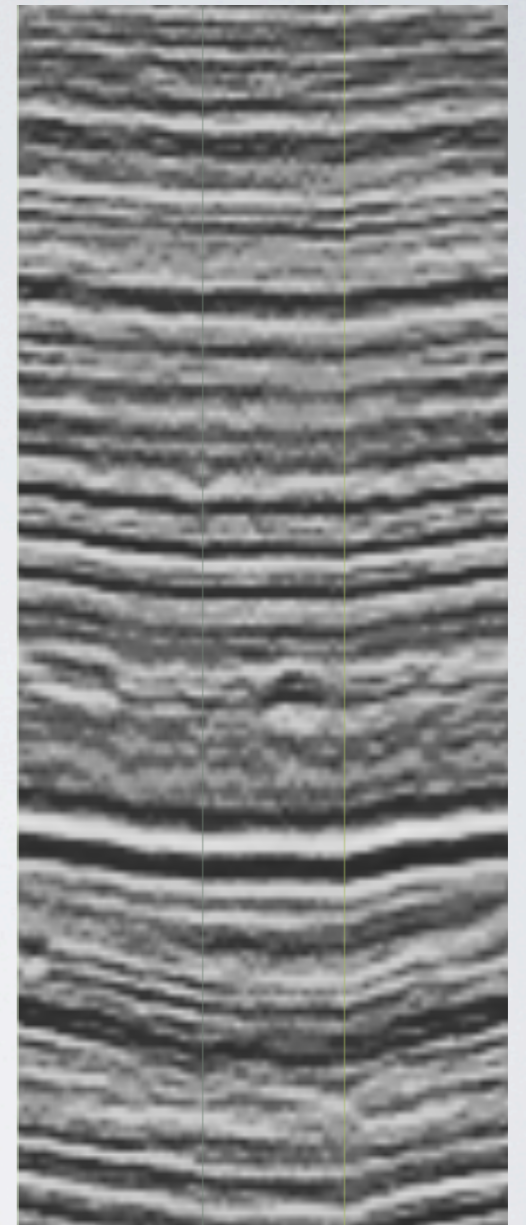
KAUST

Interactive Seismic Interpretation with Piecewise Global Energy Minimization

Thomas Höllt

What is a Horizon?

- Boundary between two different subsurface layers
- These boundaries reflect seismic waves
- Amplitude of reflected waves is measured
- Strong amplitude depicts a boundary
- Horizons indicated by ridge-, valley-lines/surfaces



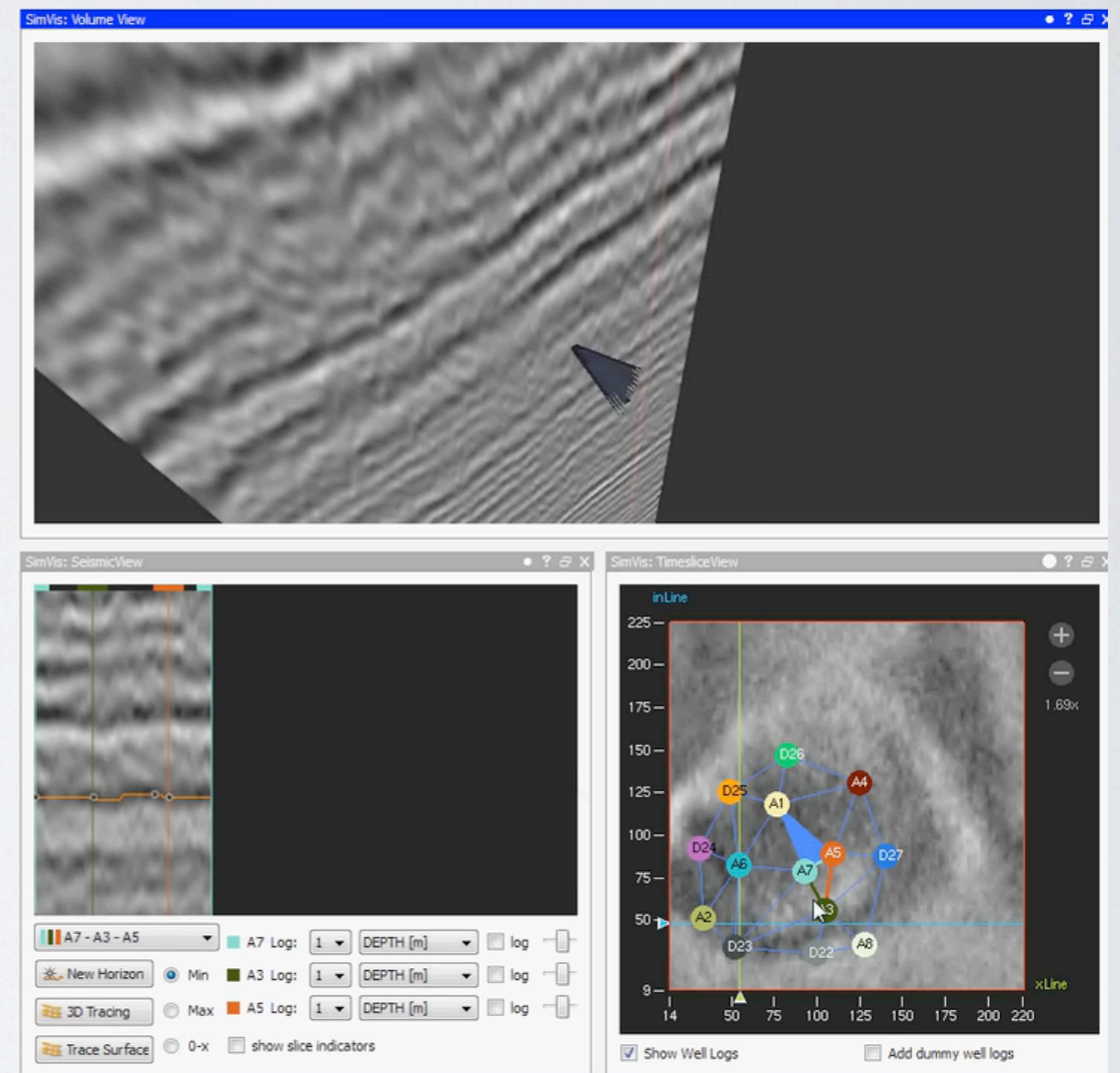
Workflow

- Interpretation based on well logs/positions
 - Triangulate well logs
 - Work on triangles/prisms instead on slices

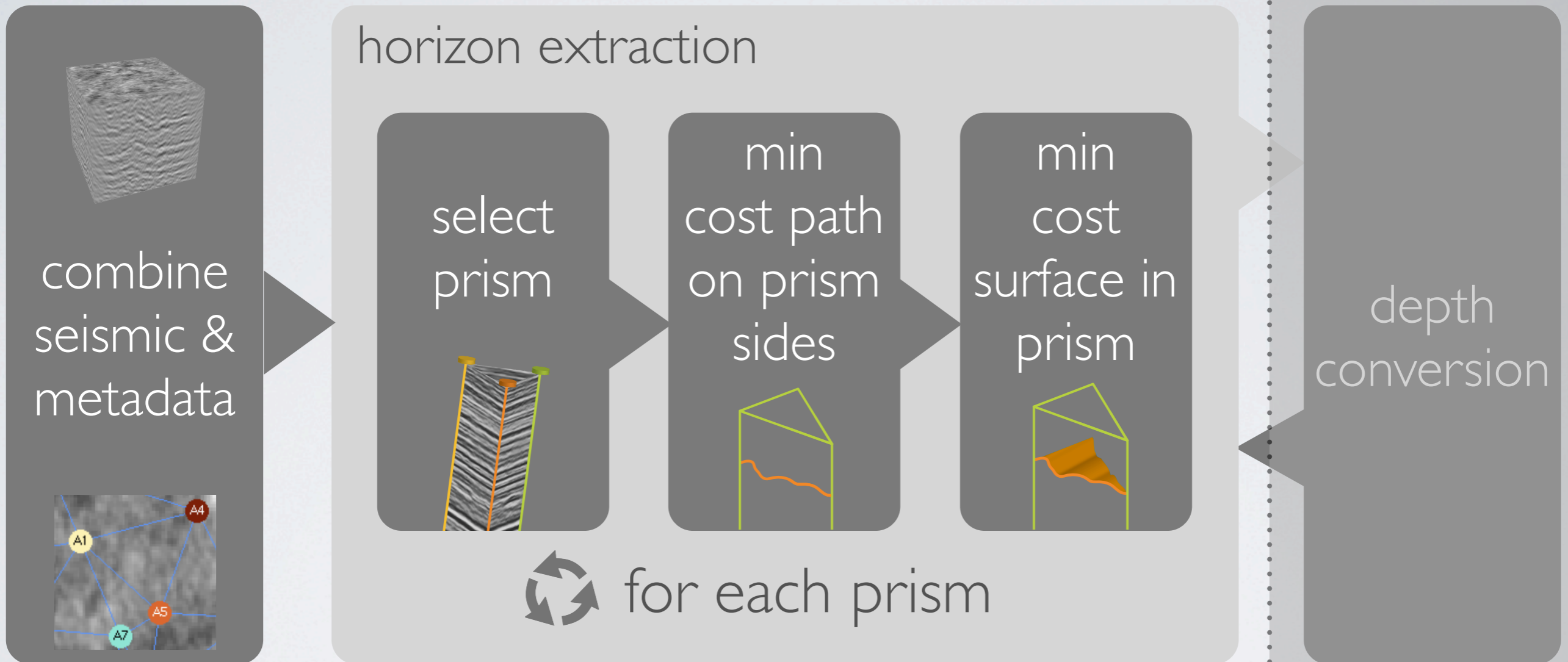


Workflow

- Interpretation based on well logs/positions
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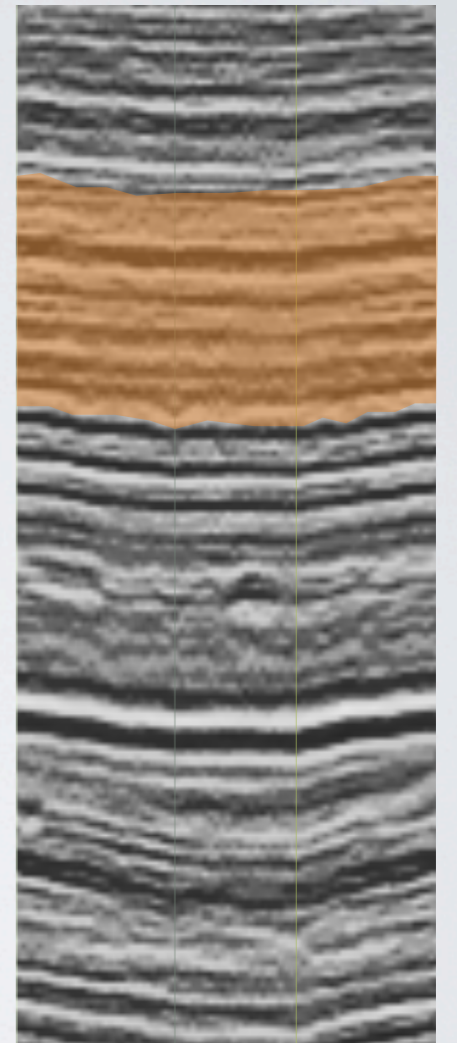


Workflow



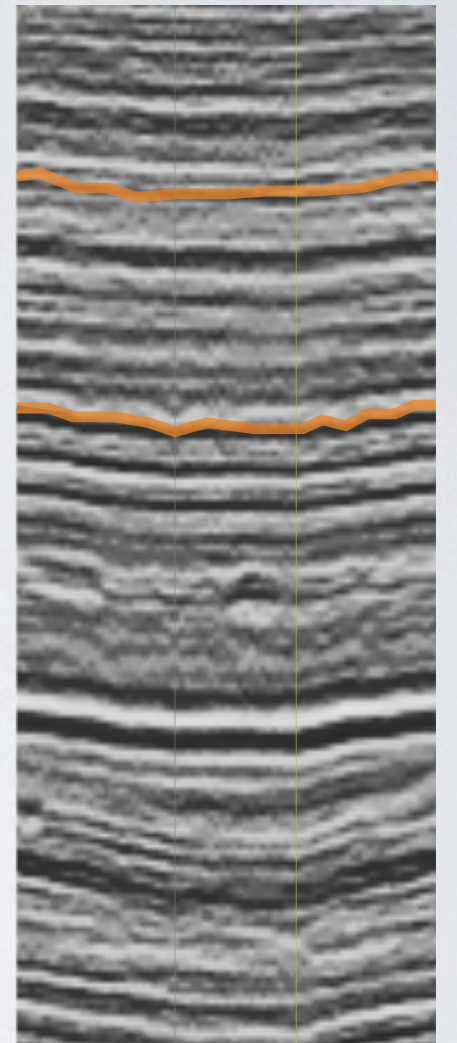
Horizons as Features

- In image segmentation:
 - segments are features
 - boundaries implicit
- Explicit boundary segmentation
 - Explicit boundary labeling
 - Boundary constraints
 - Works on primal instead of dual graph

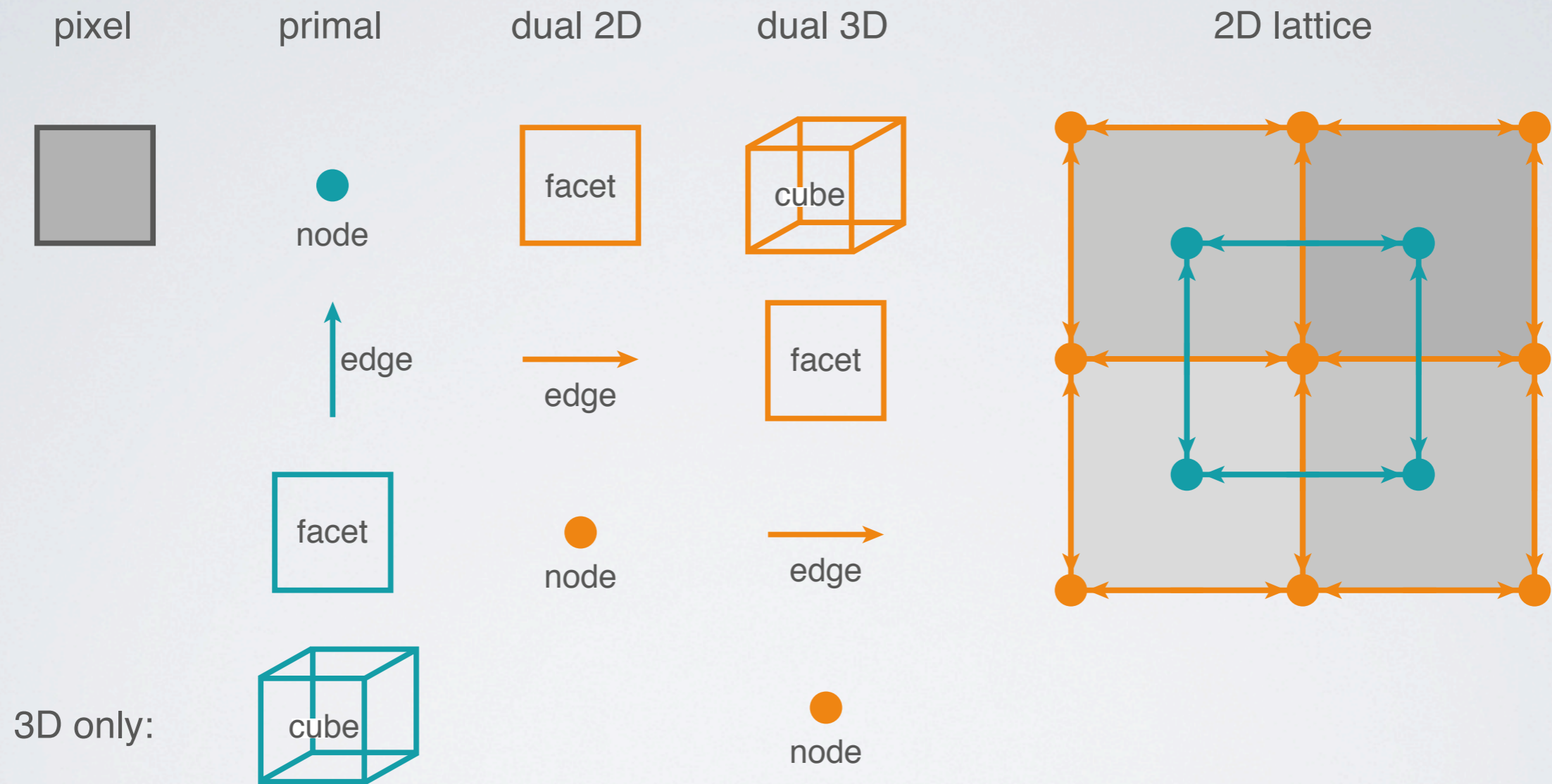


Horizons as Features

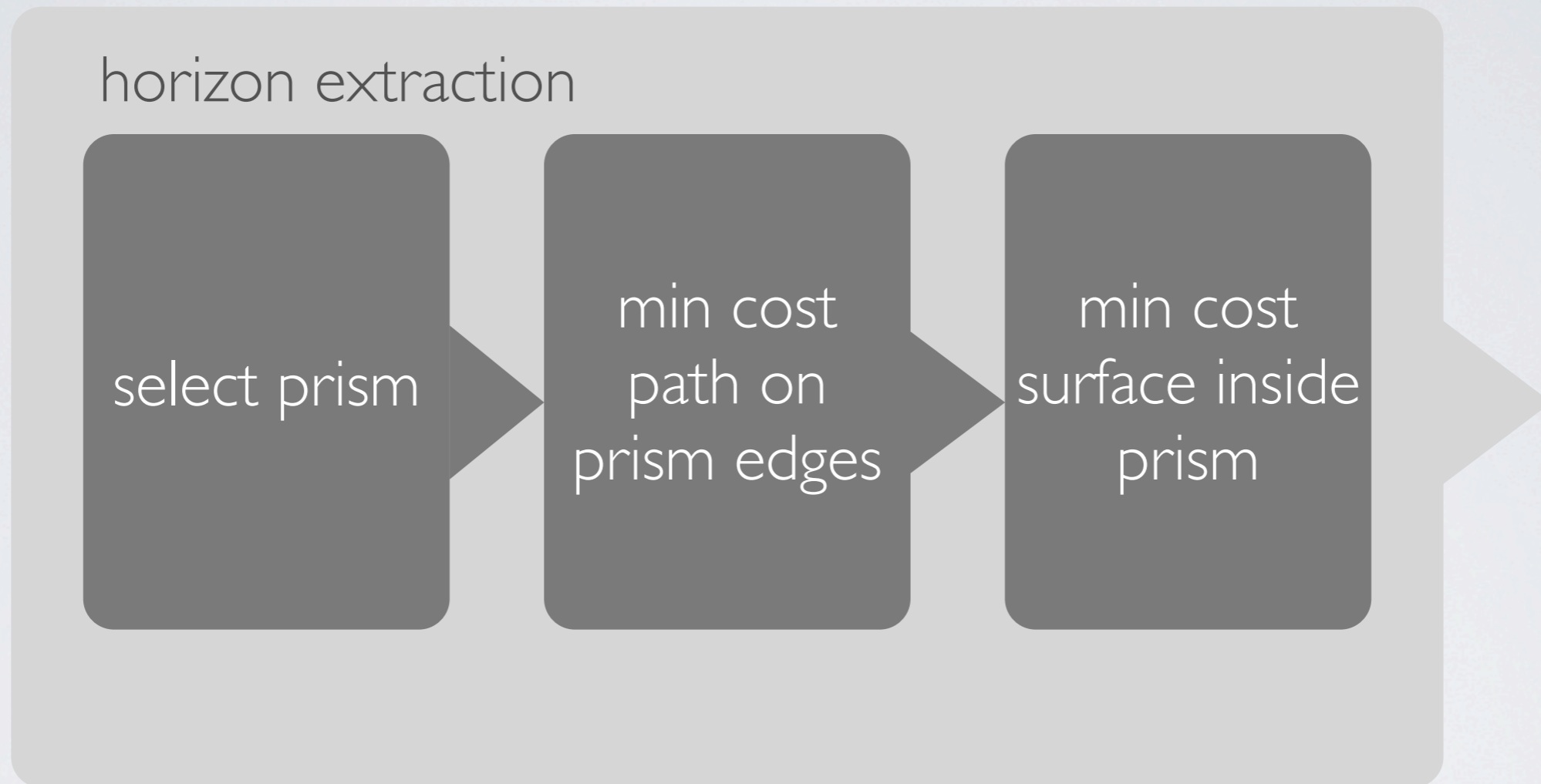
- In image segmentation:
 - segments are features
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- Explicit boundary segmentation
 - Explicit boundary labeling
 - Boundary constraints
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Image/Seismic to Graph



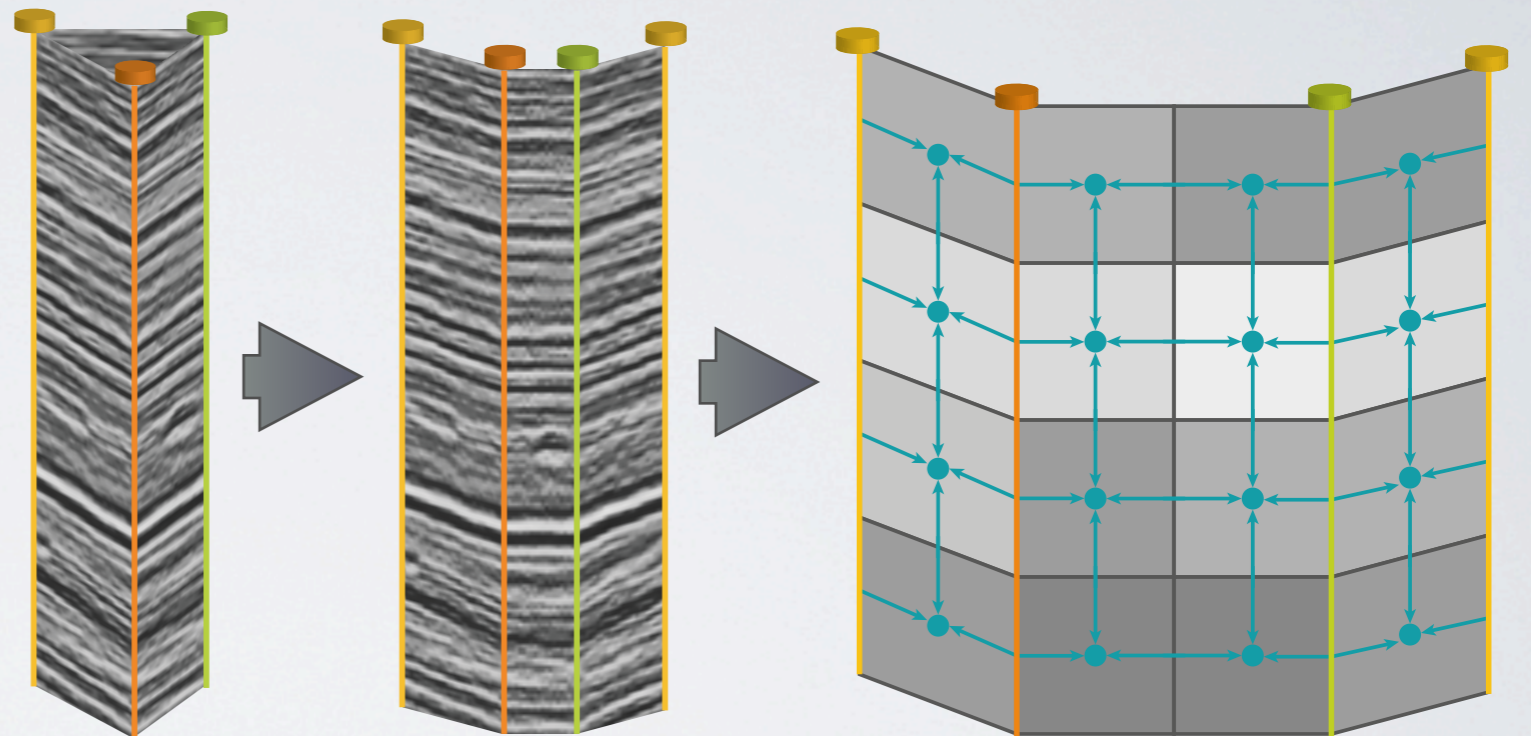
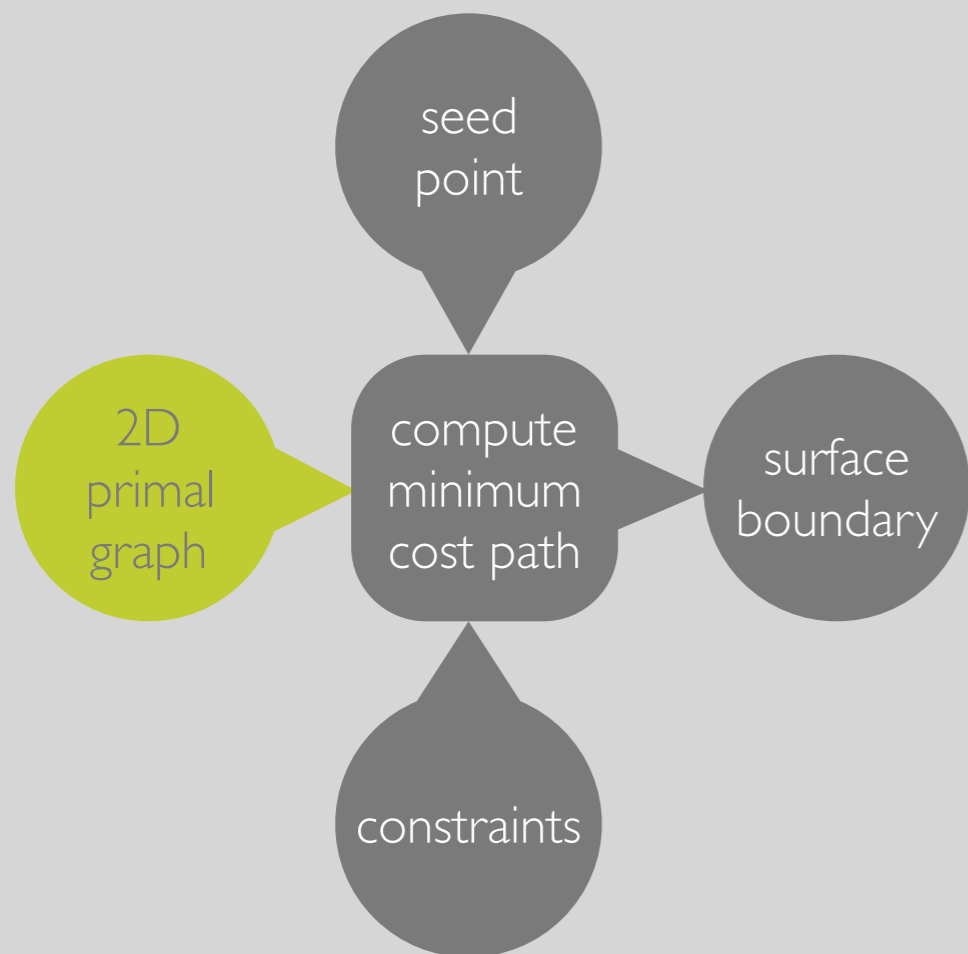
Horizon Extraction



2D Min Cost Paths

min cost path on
prism edges

(1st prism)



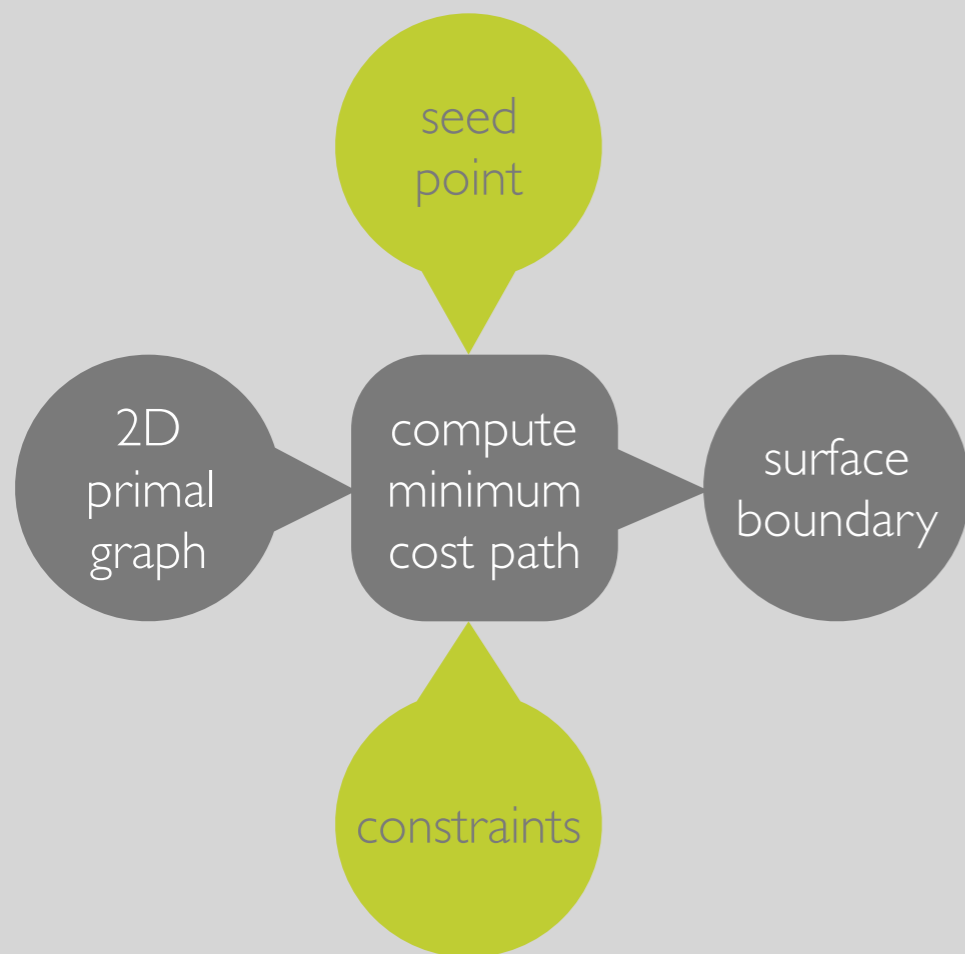
- Input: prism sides, rep. as primal graph



2D Min Cost Paths

min cost path on
prism edges

(1st prism)



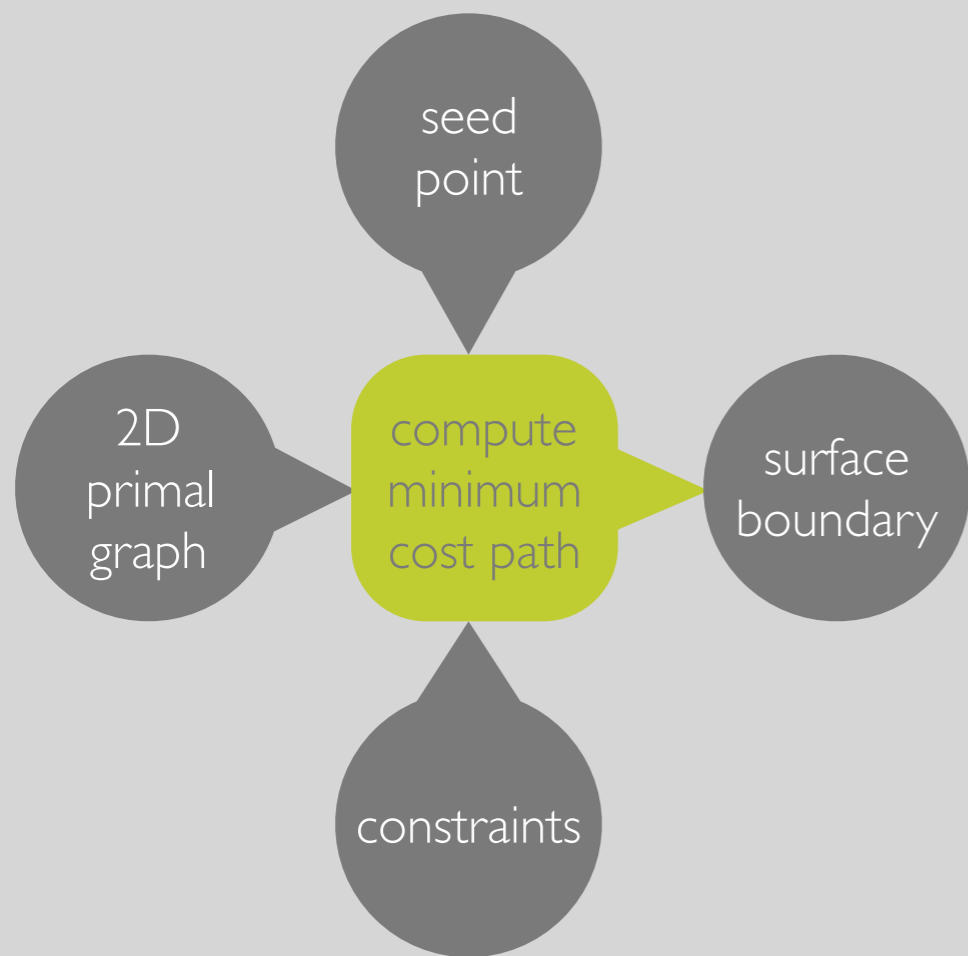
- Seed is start- and target-node
- Nodes can be added as constraints
- Path split up in segments connecting constraints



2D Min Cost Paths

min cost path on
prism edges

(1st prism)



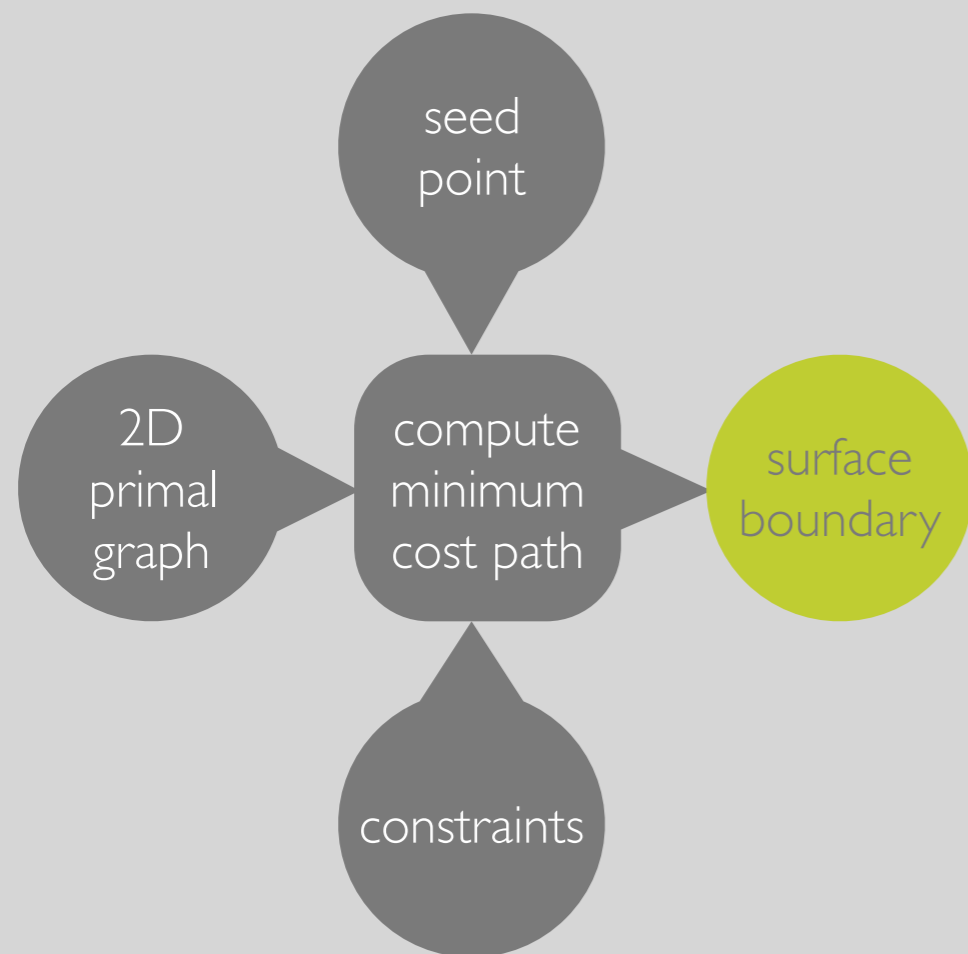
- Variant of Dijkstra's algorithm
- Cost of edges defined by adjacent nodes
(dev. from target amplitude
+ dev. from average amplitude)



2D Min Cost Paths

min cost path on
prism edges

(1st prism)

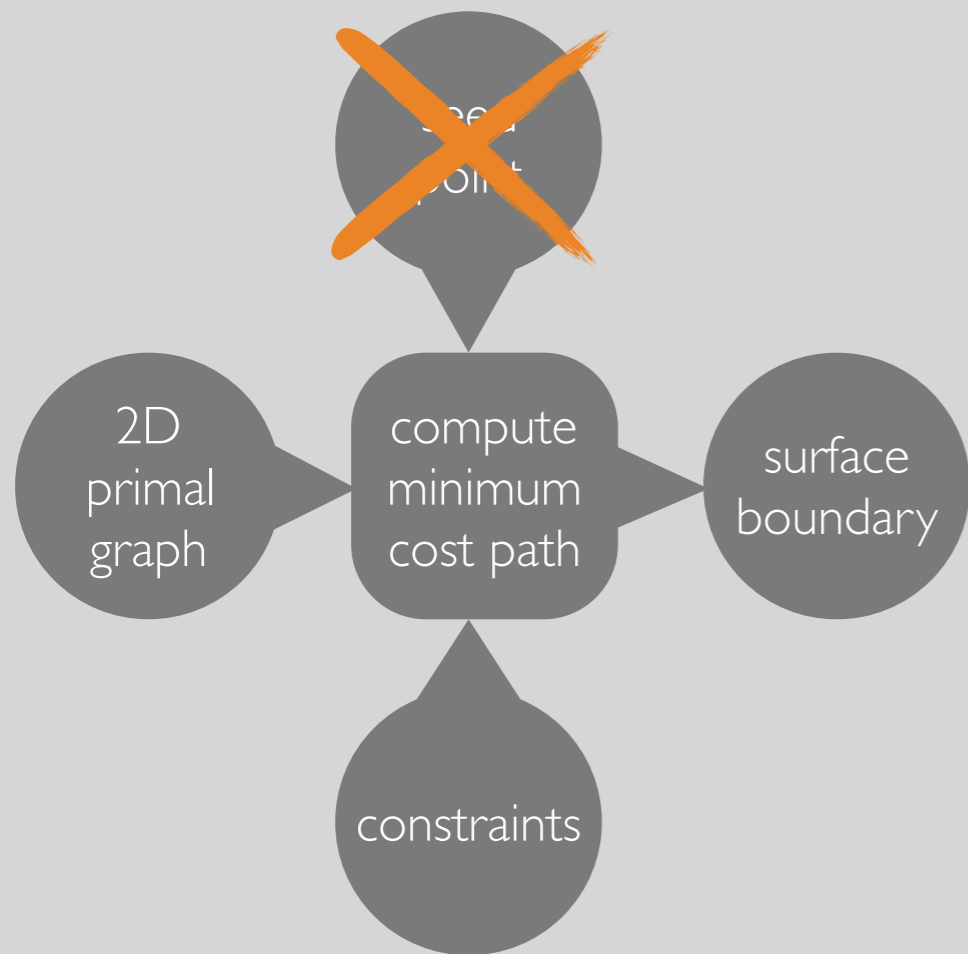


- Set of pixels forming closed contour on the prisms sides



2D Min Cost Paths

min cost path on
prism edges

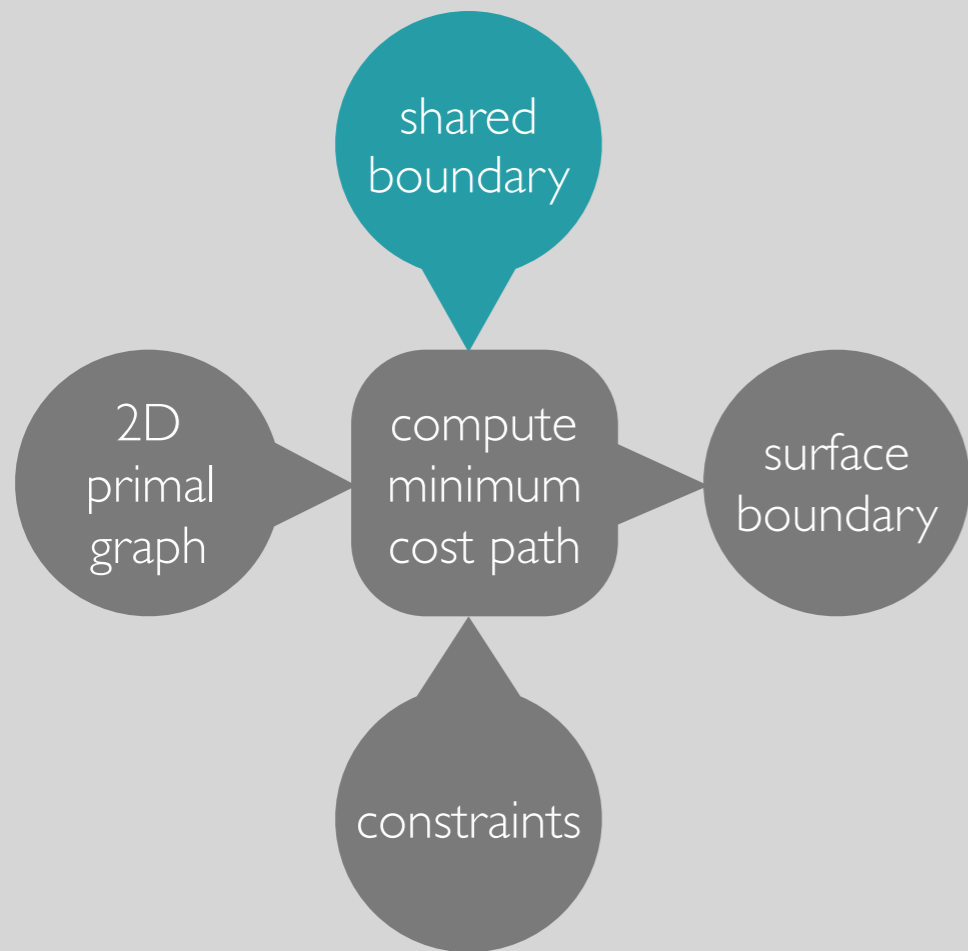


- For adjacent prisms no new seed needed
- Traced paths are shared between prisms
 - Positions at well logs fixed for traced paths
 - Fixed positions function as seeds/constraints



2D Min Cost Paths

min cost path on
prism edges



- For adjacent prisms no new seed needed
- Traced paths are shared between prisms
 - Positions at well logs fixed for traced paths
 - Fixed positions function as seeds/constraints



Horizon Extraction II

horizon extraction

select prism

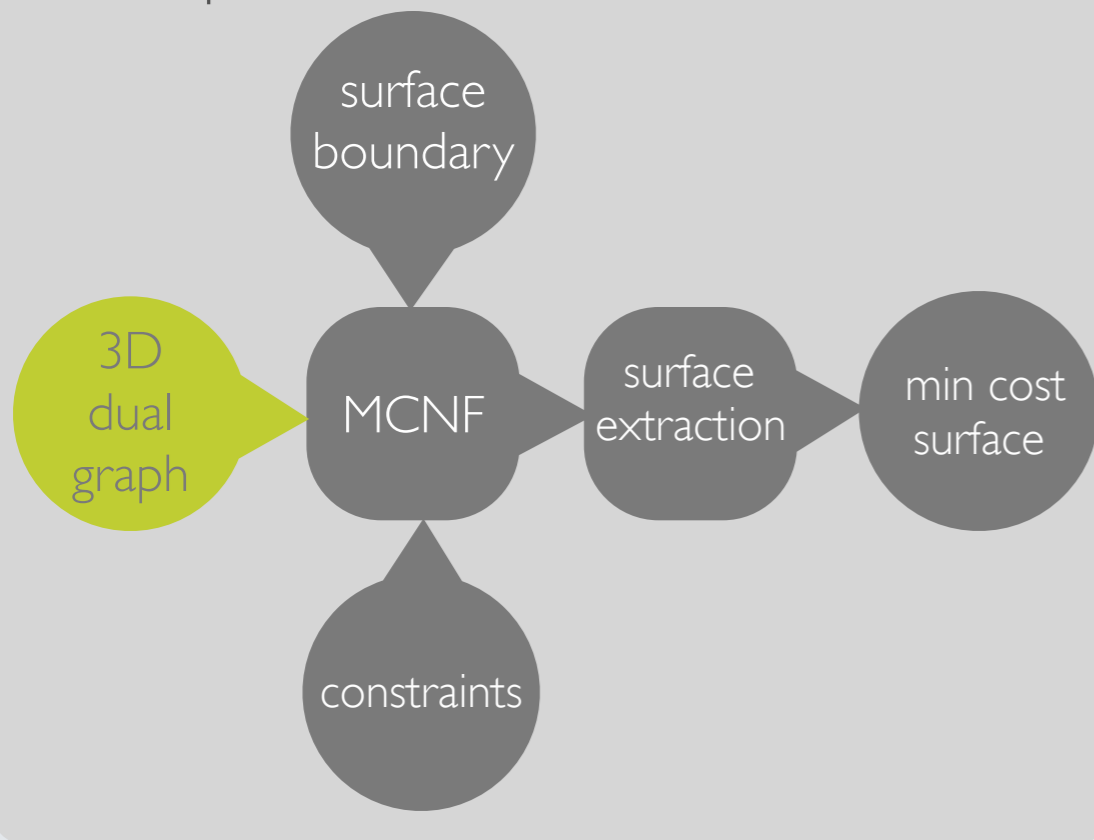
min cost
path on
prism edges

min cost
surface inside
prism



3D Min Cost Surfaces

min cost surface
inside prism

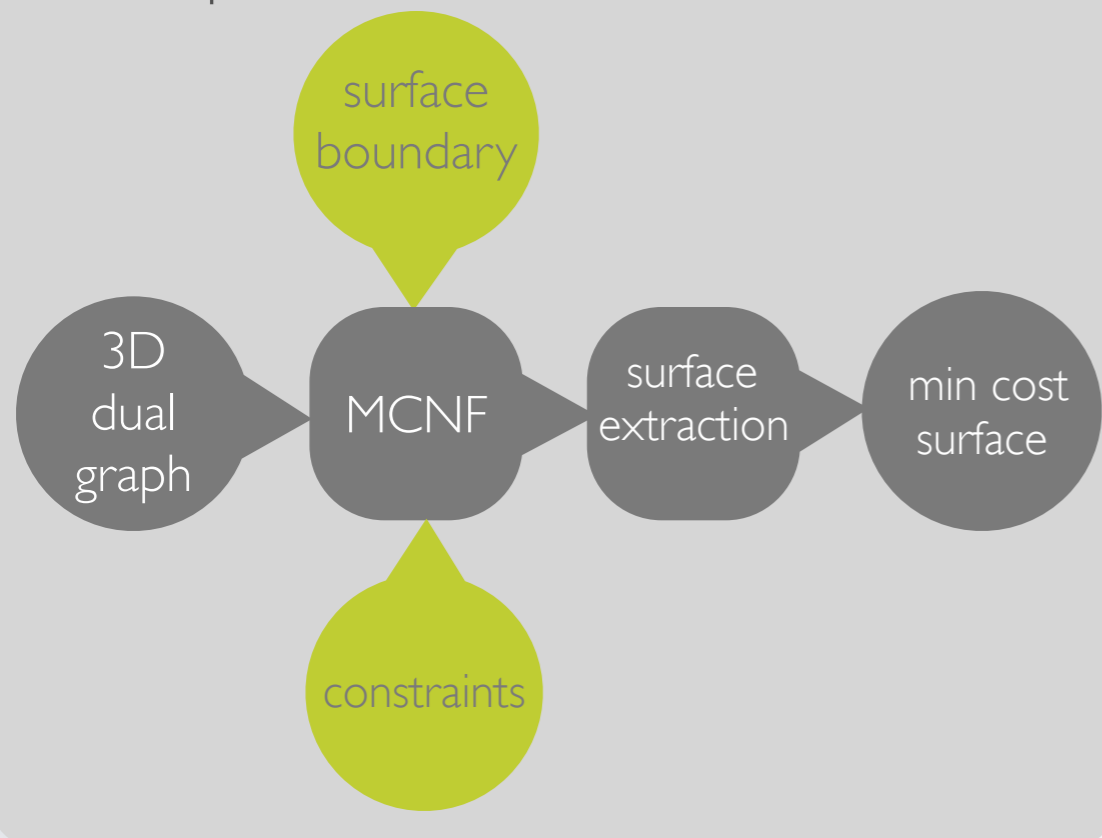


- Dijkstra's algorithm not for surfaces
- Instead solve dual problem
 - ➔ Minimum cost Circulation Network Flow (MCNF)
- Input is the dual graph



3D Min Cost Surfaces

min cost surface
inside prism

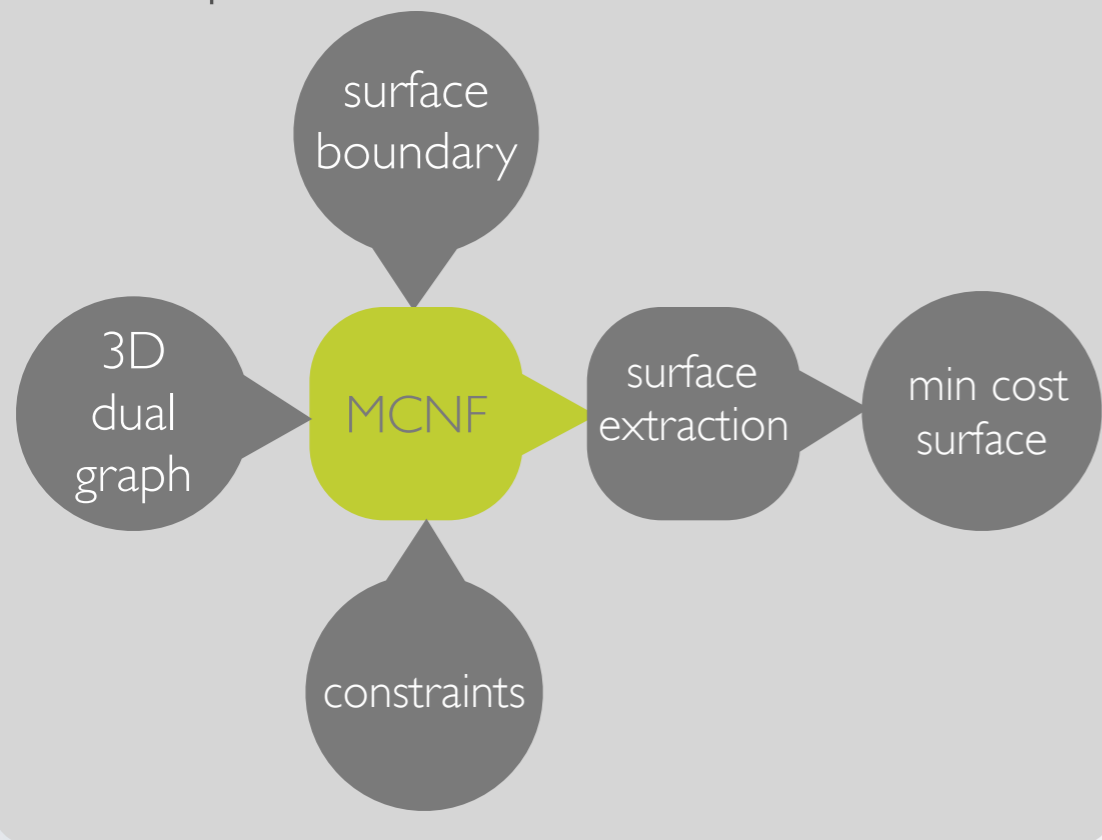


- Min cost path functions as outer surface boundary
- Facets can be added as constraints
 - Facet boundary is inner surface boundary



3D Min Cost Surfaces

min cost surface
inside prism

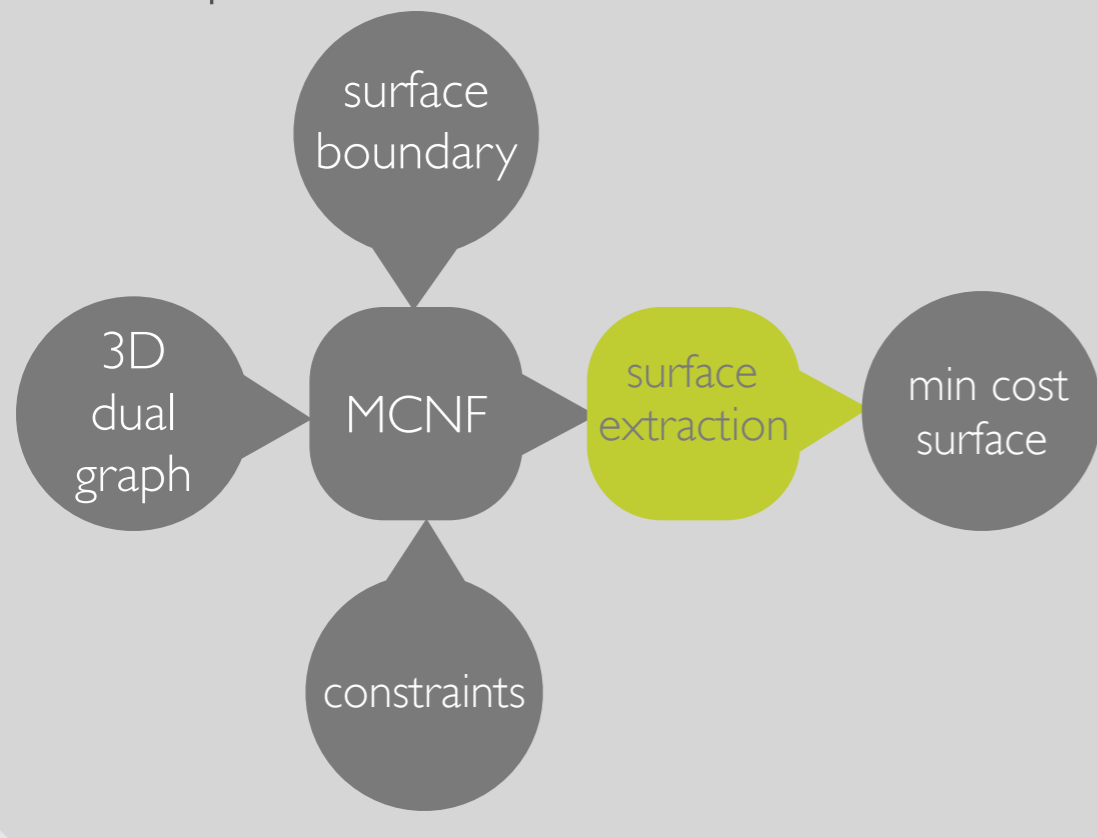


- MCNF using lemon graph library
- Same cost function as min cost path
 - used for edge capacity in dual graph



3D Min Cost Surfaces

min cost surface
inside prism

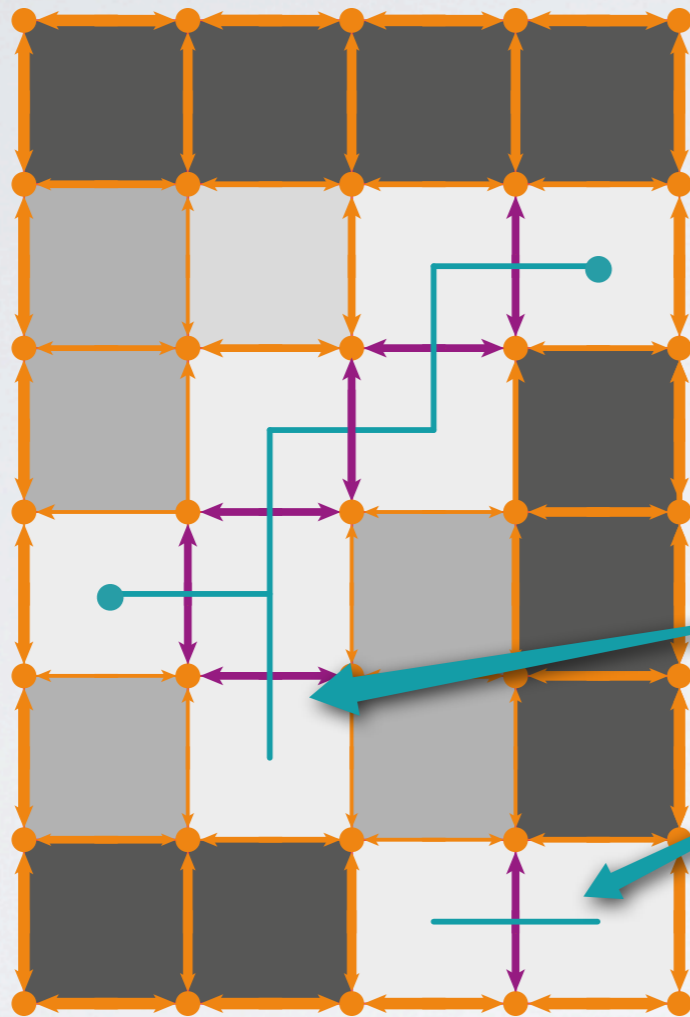


- MCNF returns set of facet candidates
 - Min cost surface is closed surface bounded by initial boundary
 - False candidates might be:
 - dead ends
 - disconnected from the surface
- Removed by iteratively deleting candidates without neighbors on all sides



3D Min Cost Surfaces

- ↑ dual edge
- ↑ saturated dual edge
- path in primal
- boundary nodes

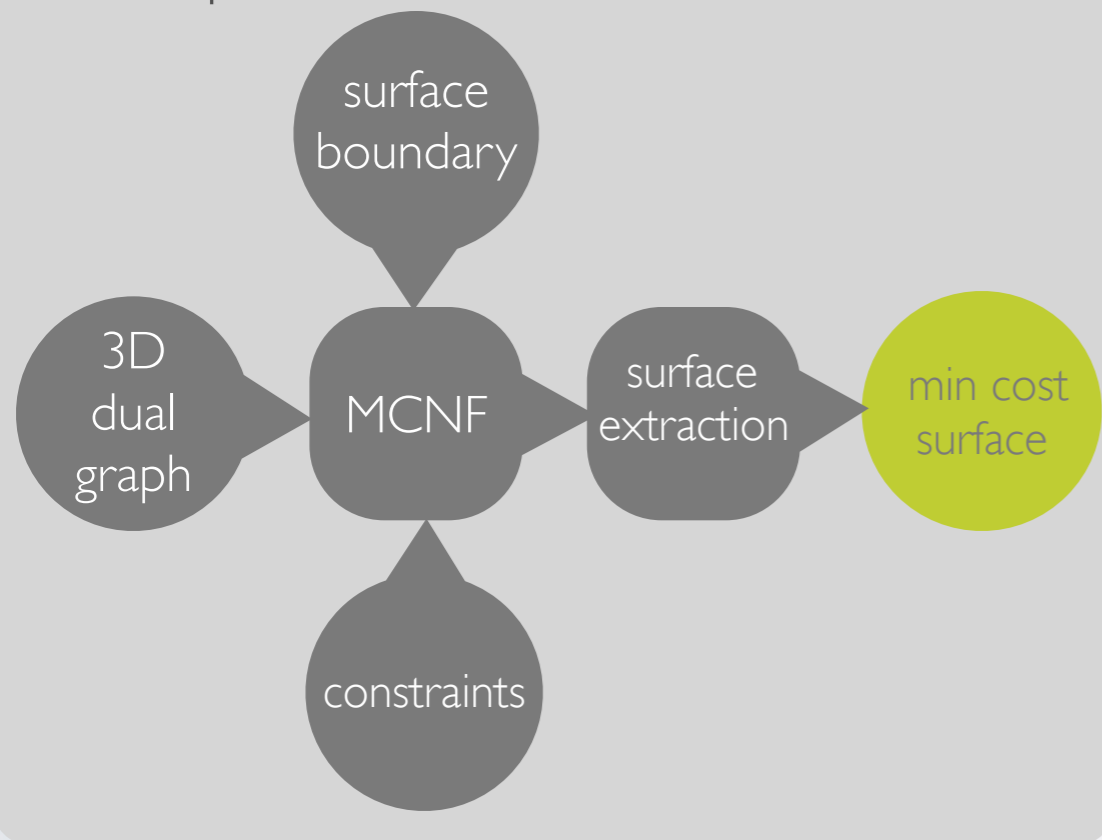


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3D Min Cost Surfaces

min cost surface
inside prism

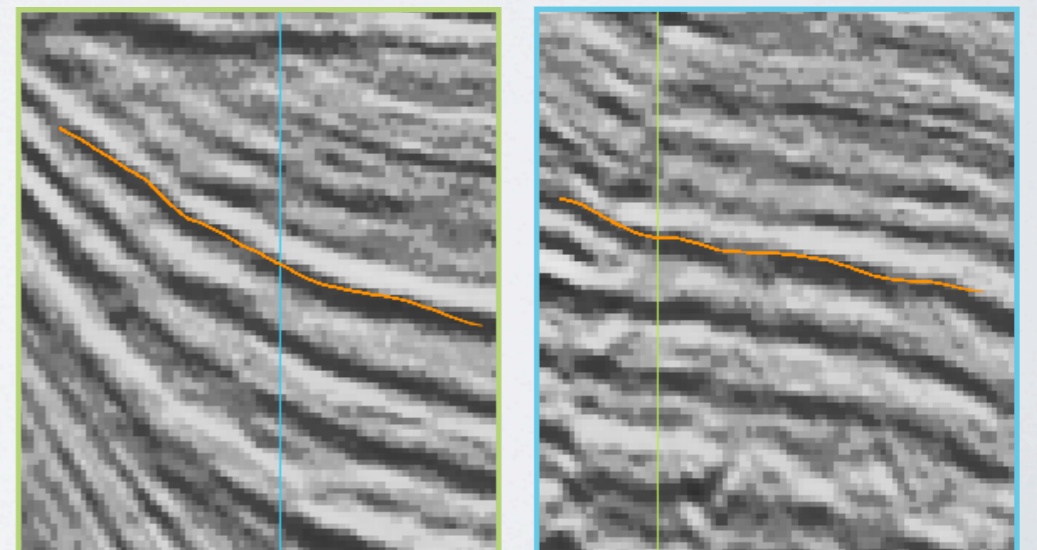
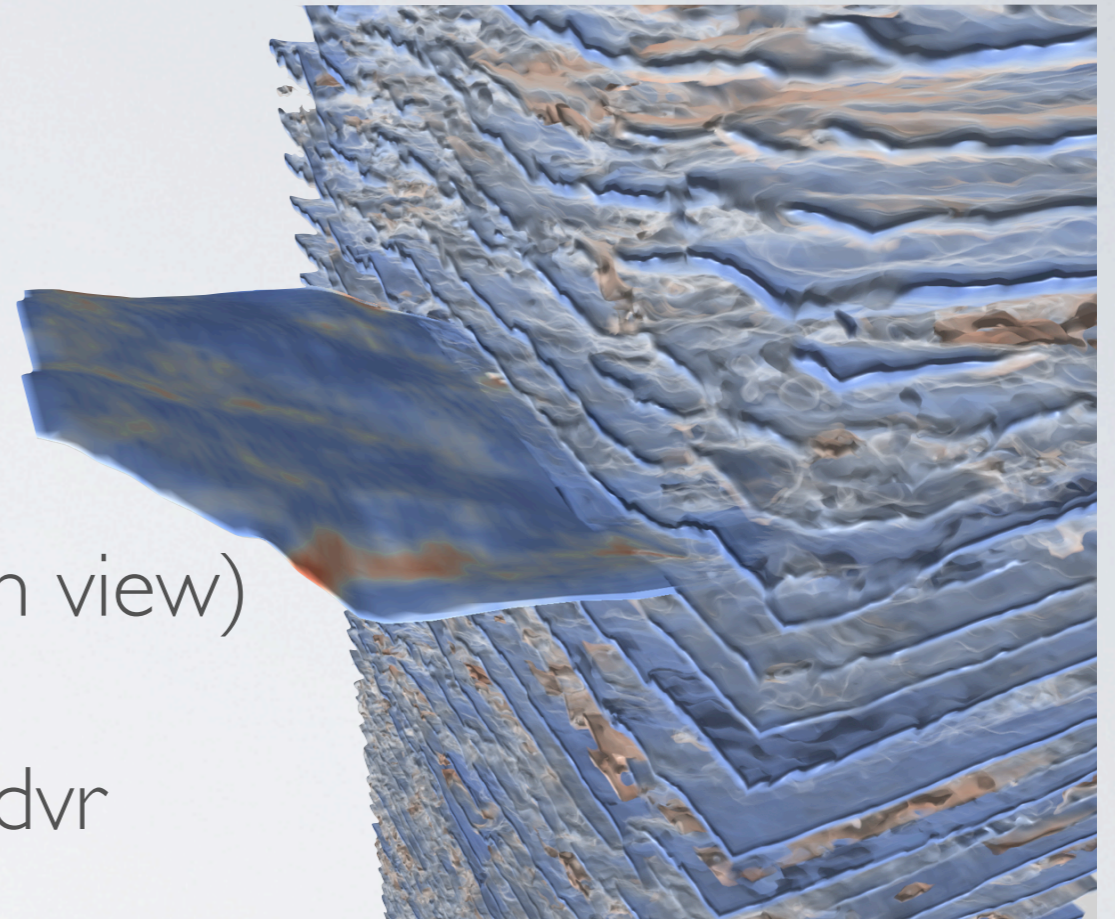


- Set of facets forming closed surface inside prism

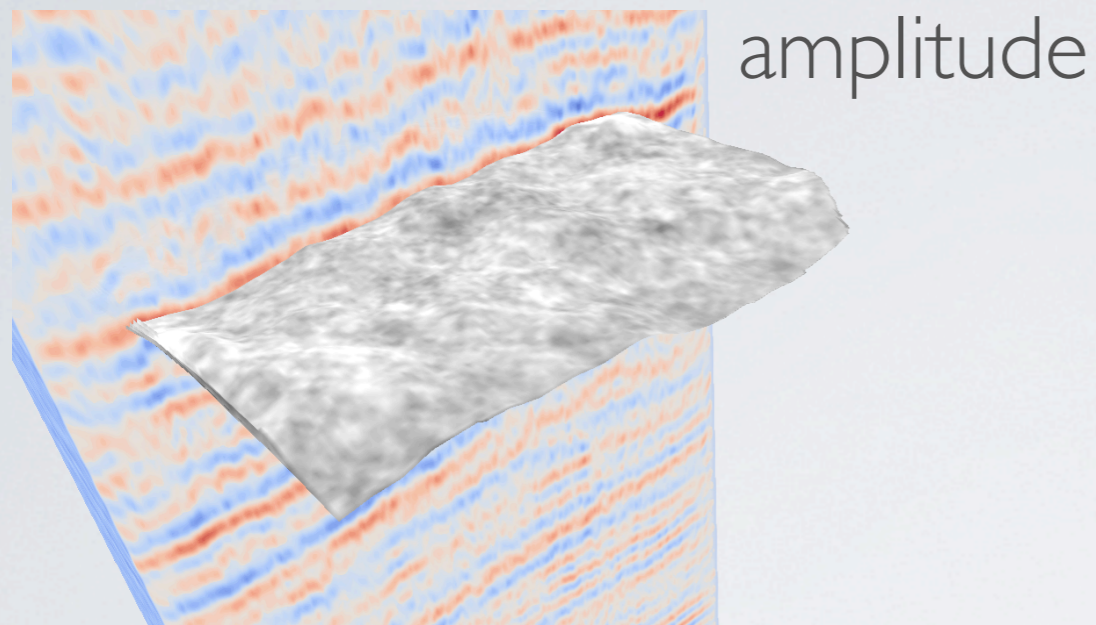


Horizon Visualization

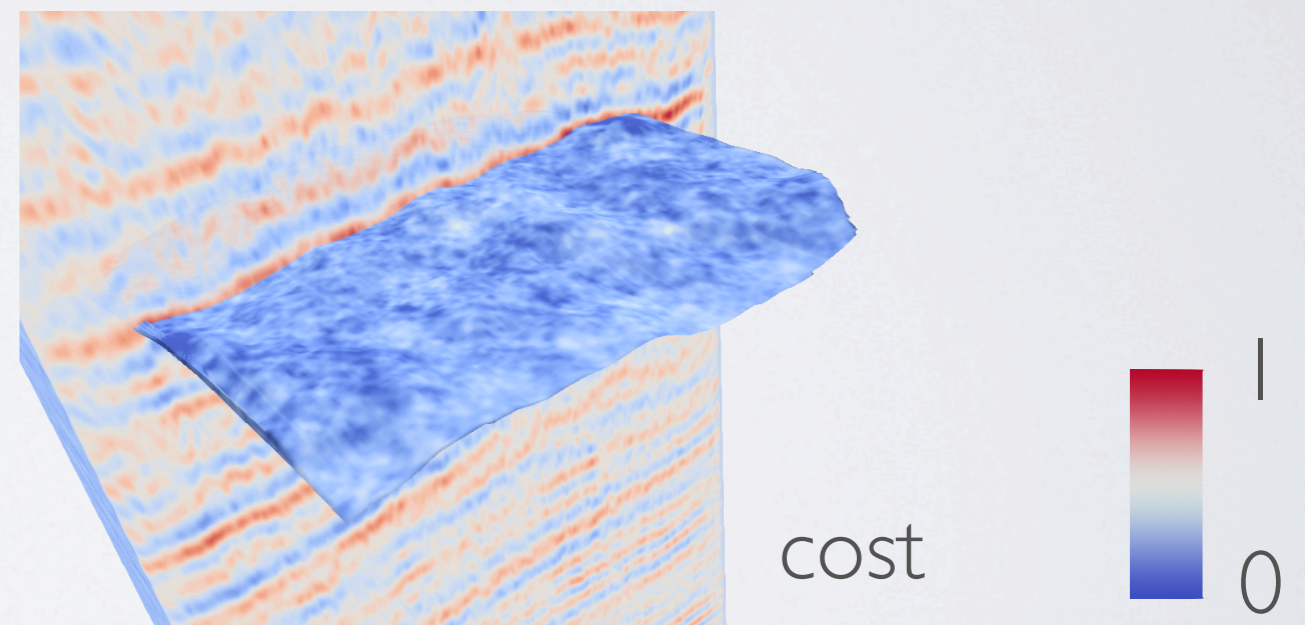
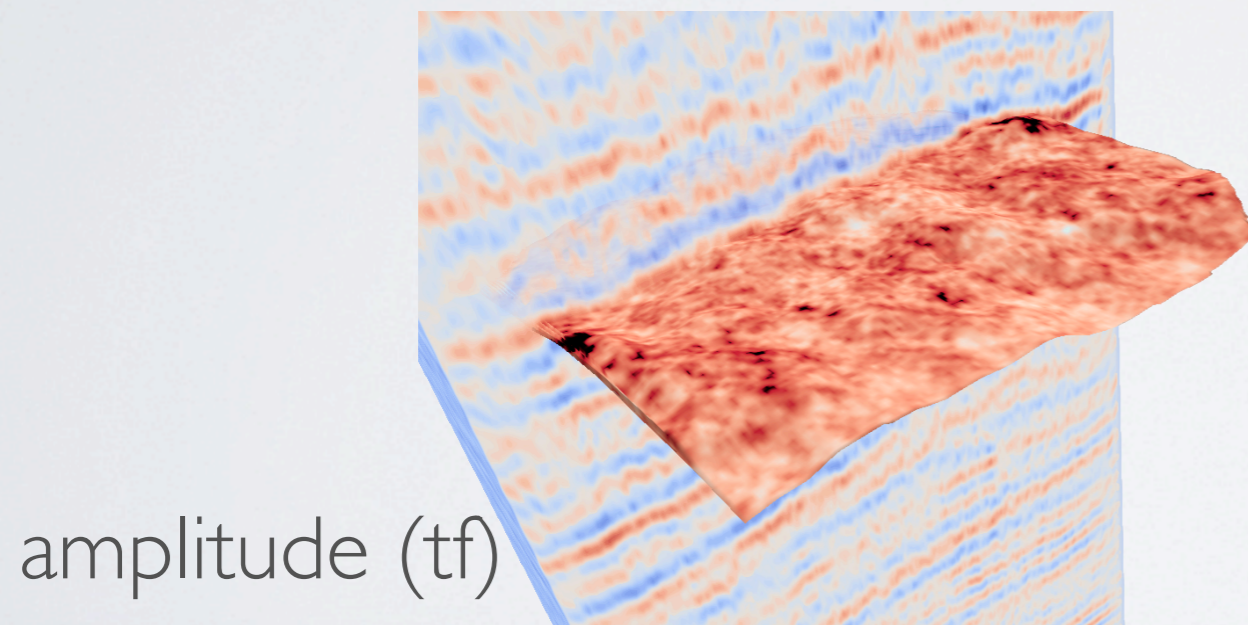
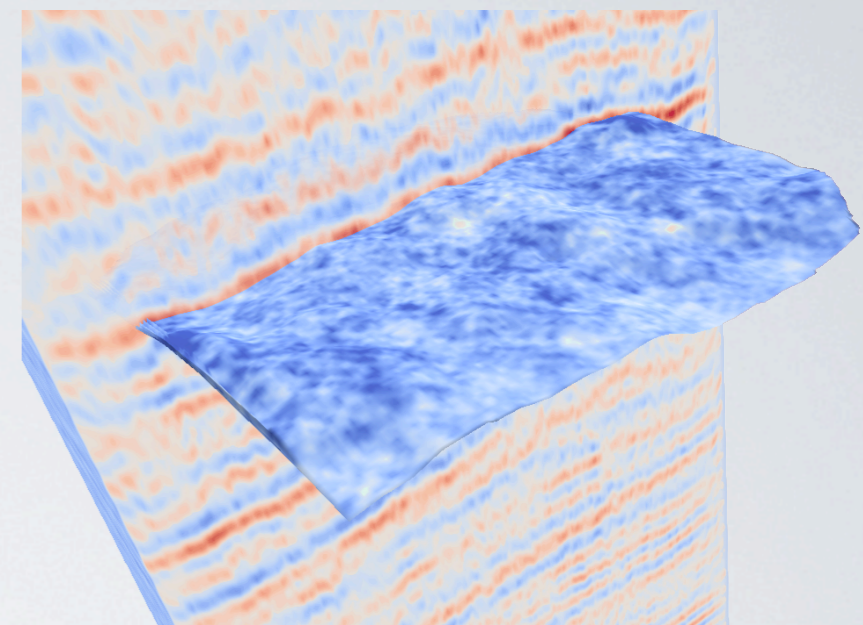
- Horizons shown in all applicable views (volume view, slice views, interpretation view)
- In volume view as geometry alongside dvr
- Several properties plotted directly onto horizons (amplitude, deviation, cost...)



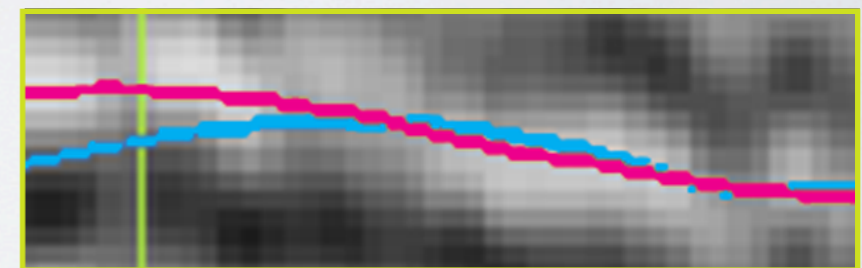
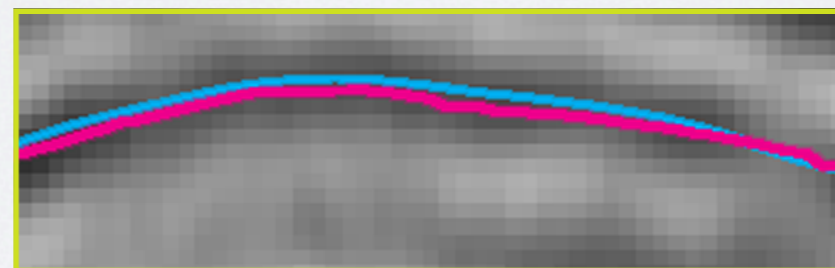
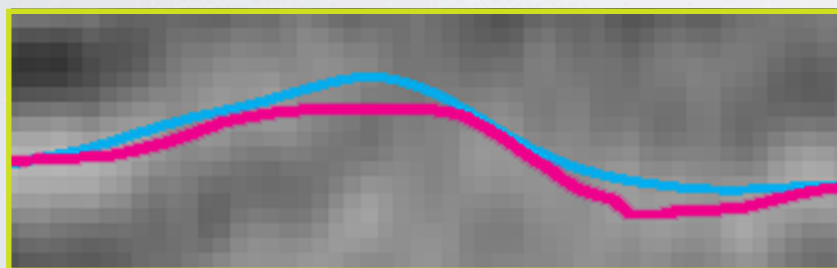
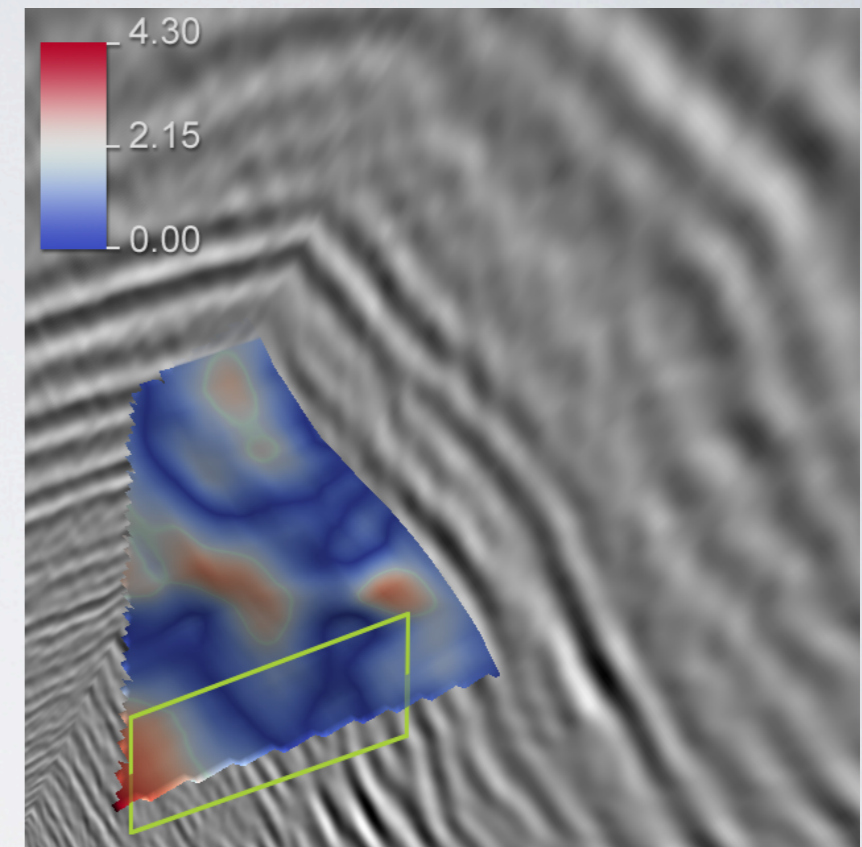
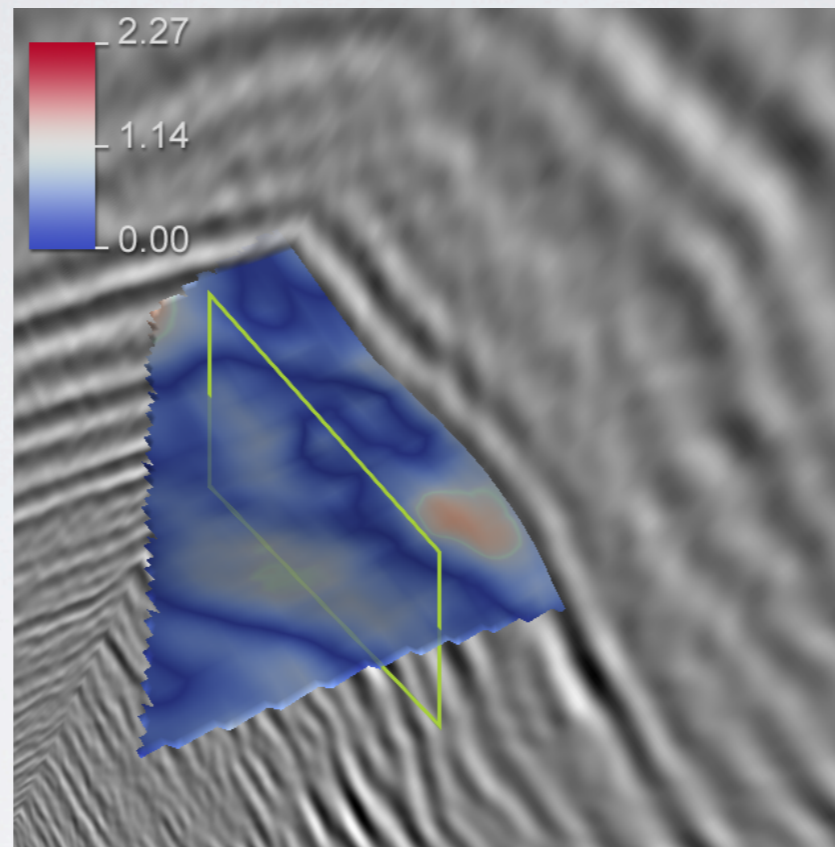
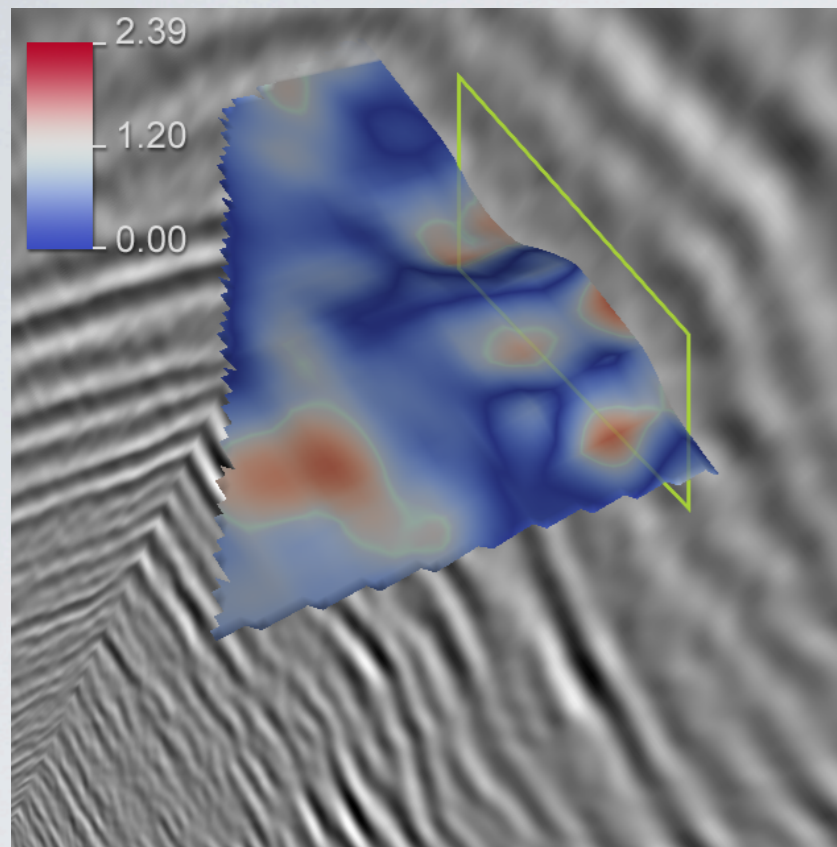
Horizon Visualization



difference
to target
amplitude



Surface Quality

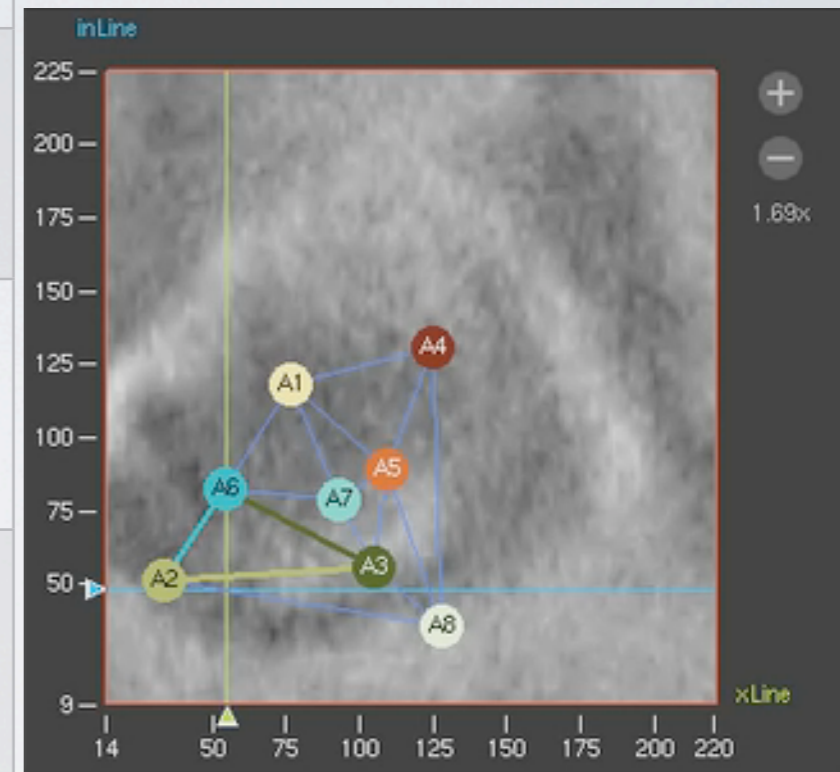


— our method — manual interpretation



Results

horizon	constraints	edit time	tracing time	max distance
a	1+8	< 5min	61 sec	2,39px
b	1+5	< 2min	53sec	2,27px
c	1+5	< 5min	74sec	4,3px



- 240x240x1509 volume
- $\sim 1/5$ area covered

- 8 logs
- 9 prisms

- $\sim 20k$ triangles for surface



Conclusions & Future Work

- Prism based approach & decoupling of 2D interaction and 3D computation received well by collaborators
- Horizons in context of volume + superimposed properties
➔ instantaneous feedback on quality
- Performance, performance, performance!
 - Cuda implementation of surface computation
- Integrate live depth conversion



QUESTIONS?

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