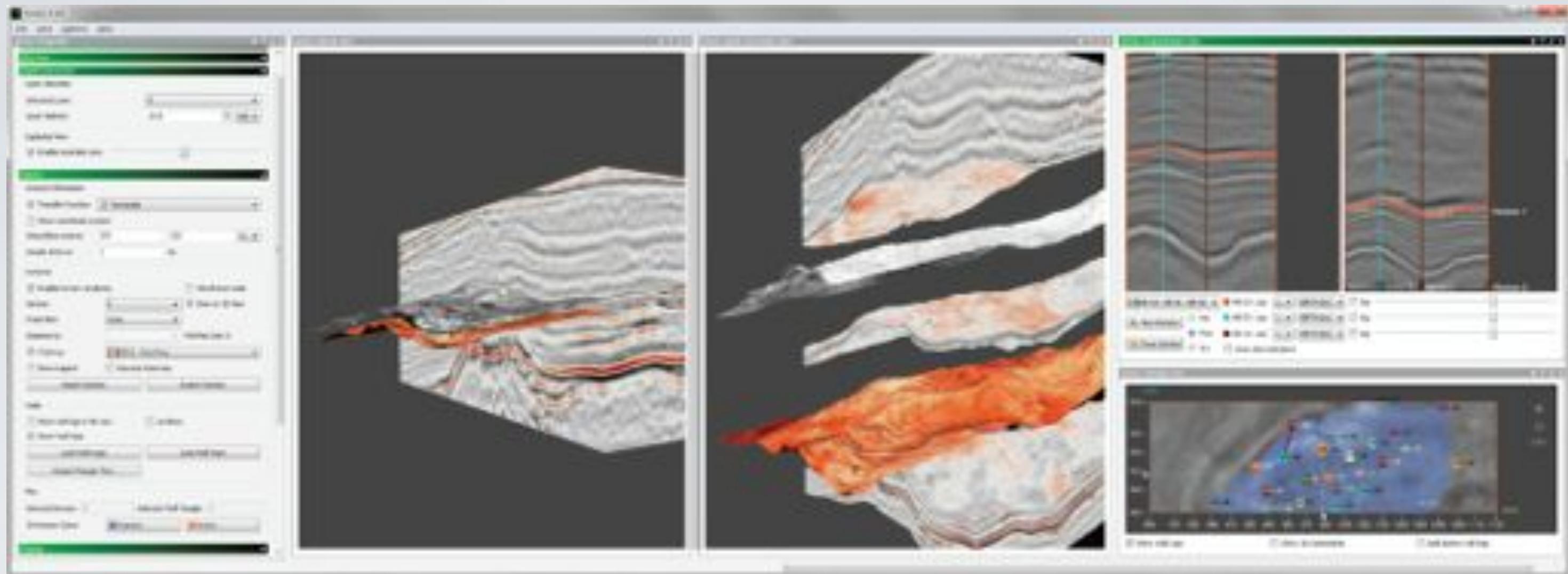


# Visual Workflows for Oil and Gas Exploration

Thomas Höllt // 14. April 2013







# Publications



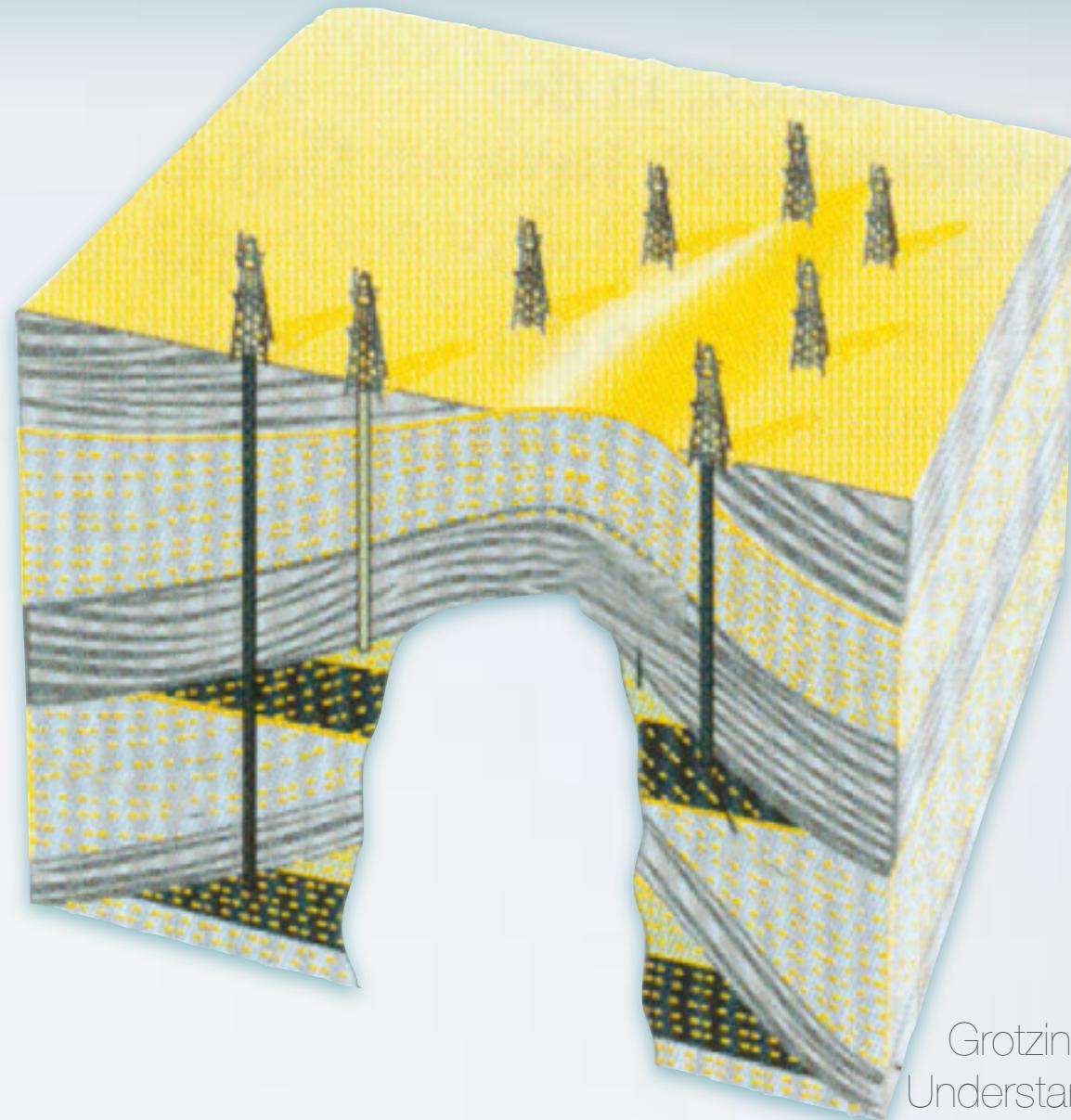
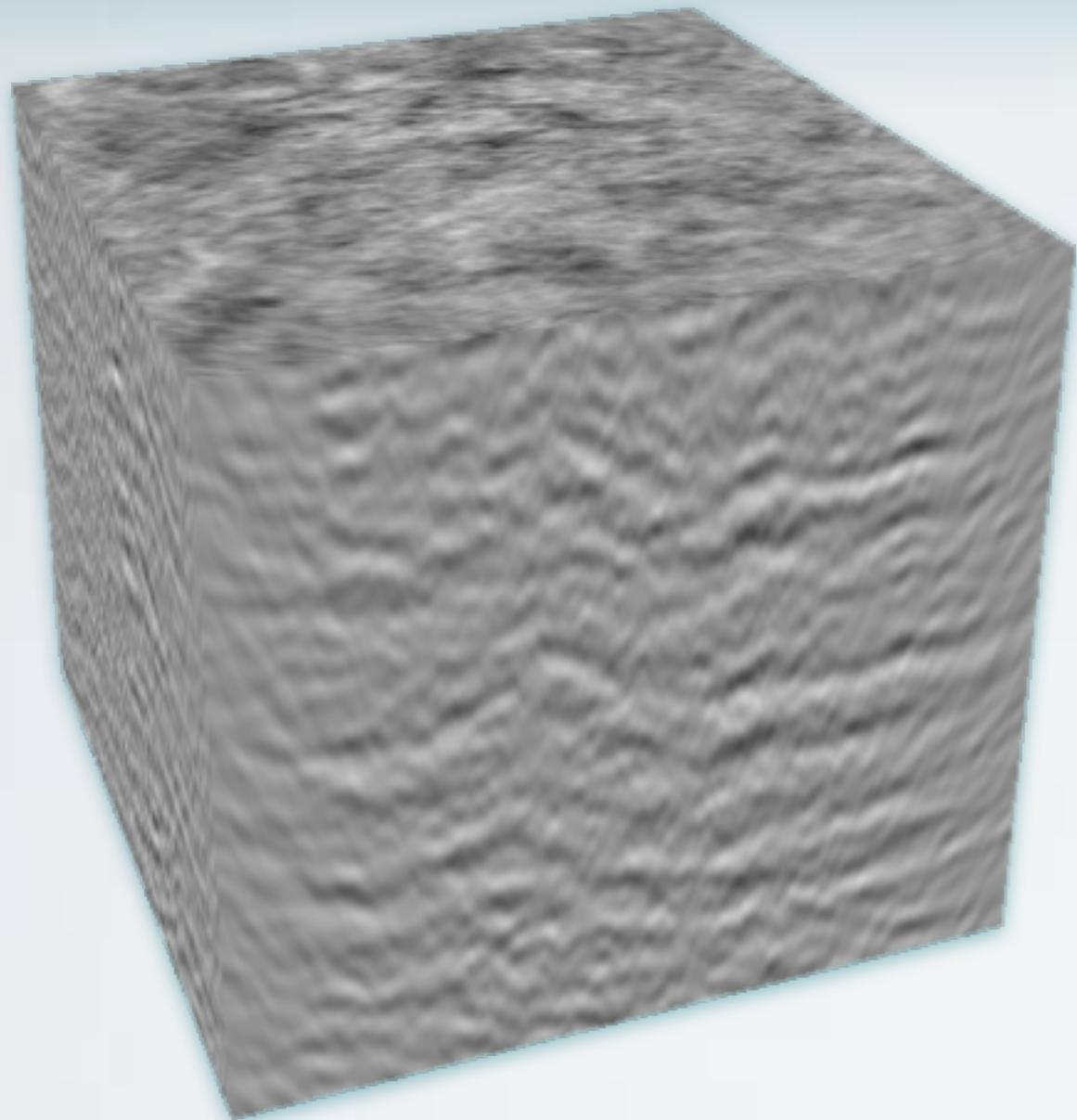
T. Höllt, J. Beyer, F. Gschwantner, P. Muigg, H. Doleisch, G. Heinemann, and M. Hadwiger.  
**Interactive Seismic Interpretation with Piecewise Global Energy Minimization.**  
In *Proceedings of IEEE Pacific Visualization Symposium 2011*, pages 59–66, 2011.



T. Höllt, W. Freiler, F.M. Gschwantner, H. Doleisch, G. Heinemann, and M. Hadwiger.  
**SeiVis: An Interactive Visual Subsurface Modeling Application.**  
*IEEE Transactions on Visualization and Computer Graphics*, 18(12): 2226–2235, 2012.



# Visual Subsurface Modeling

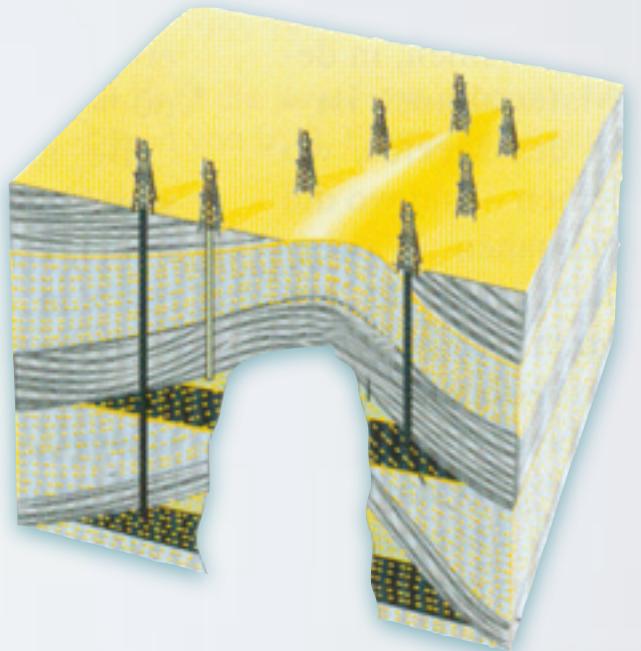
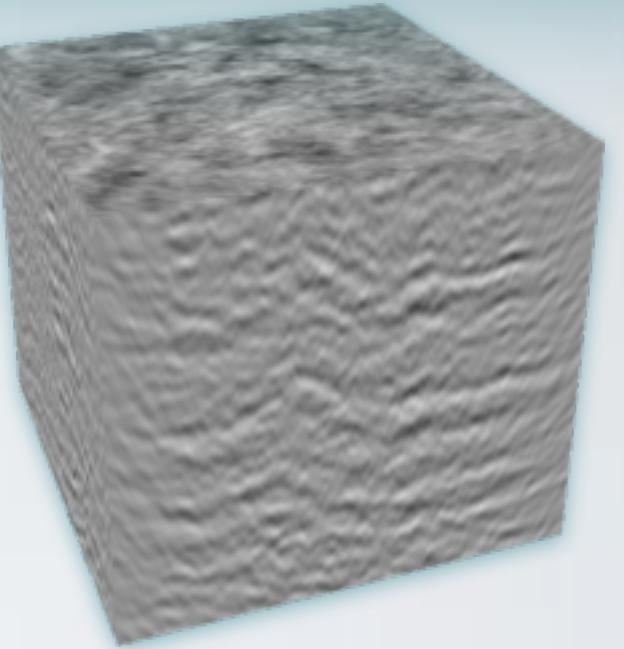


Grotzinger et al.  
Understanding Earth



# Seismic To Model

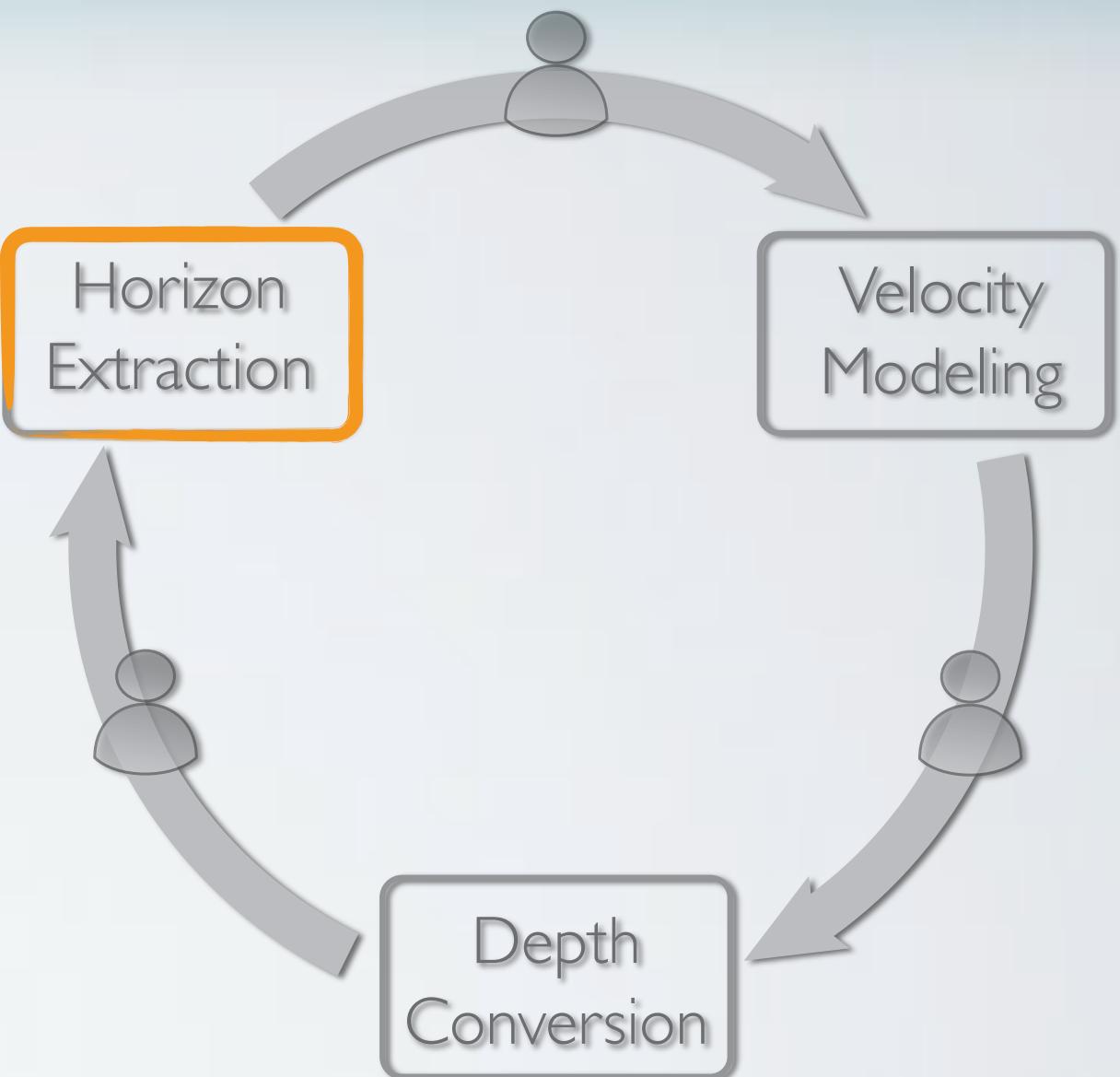
- Description of subsurface layers
  - horizons
  - faults
- Created from seismic survey
  - well data + seismic tomography
  - Seismic tomography
    - recorded depth dimension is time
    - target depth dimension is lateral depth



# Conventional Workflow



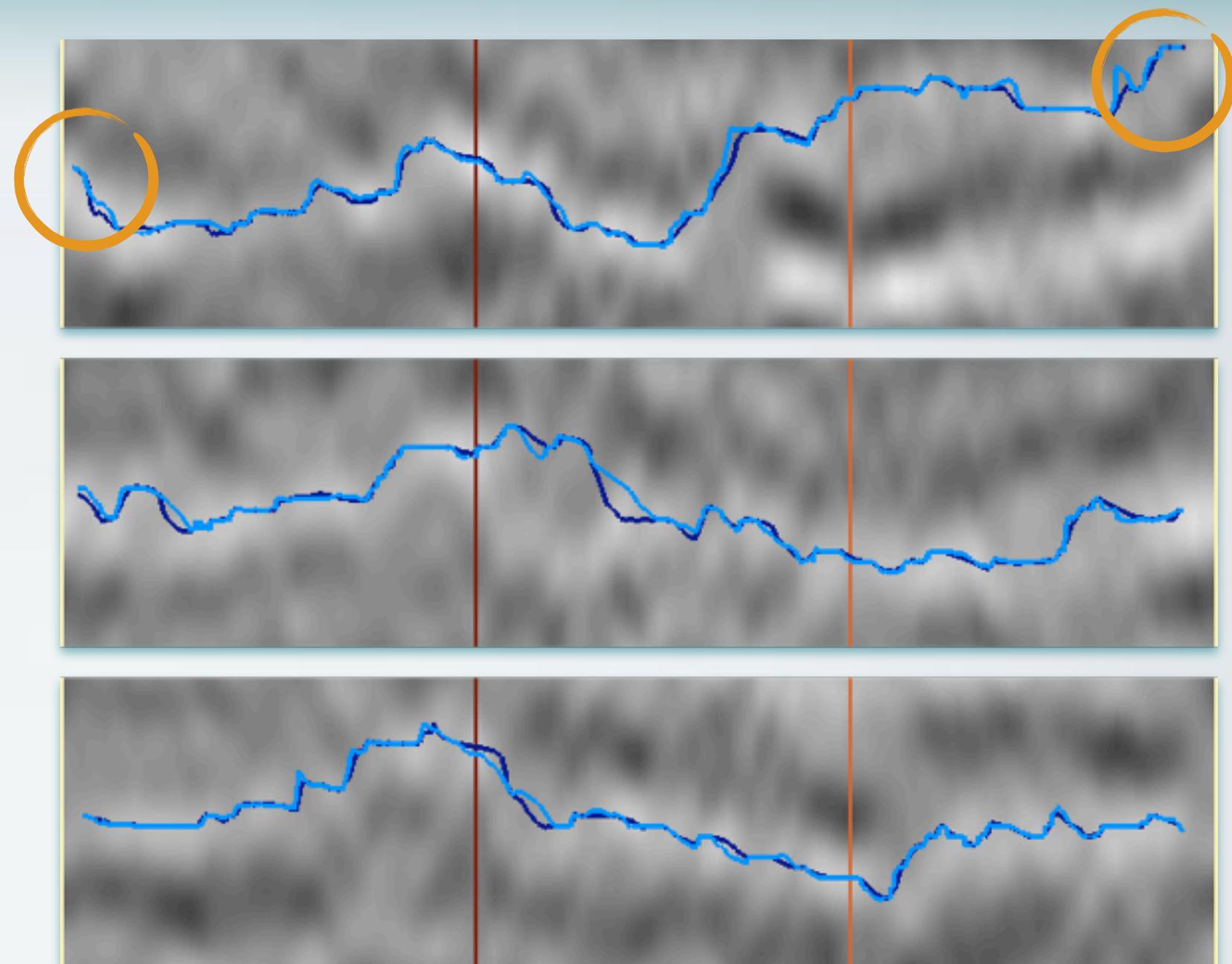
- Feature extraction
  - based on seismic tomography
  - results in model in time domain



# Conventional Workflow // Feature Extraction



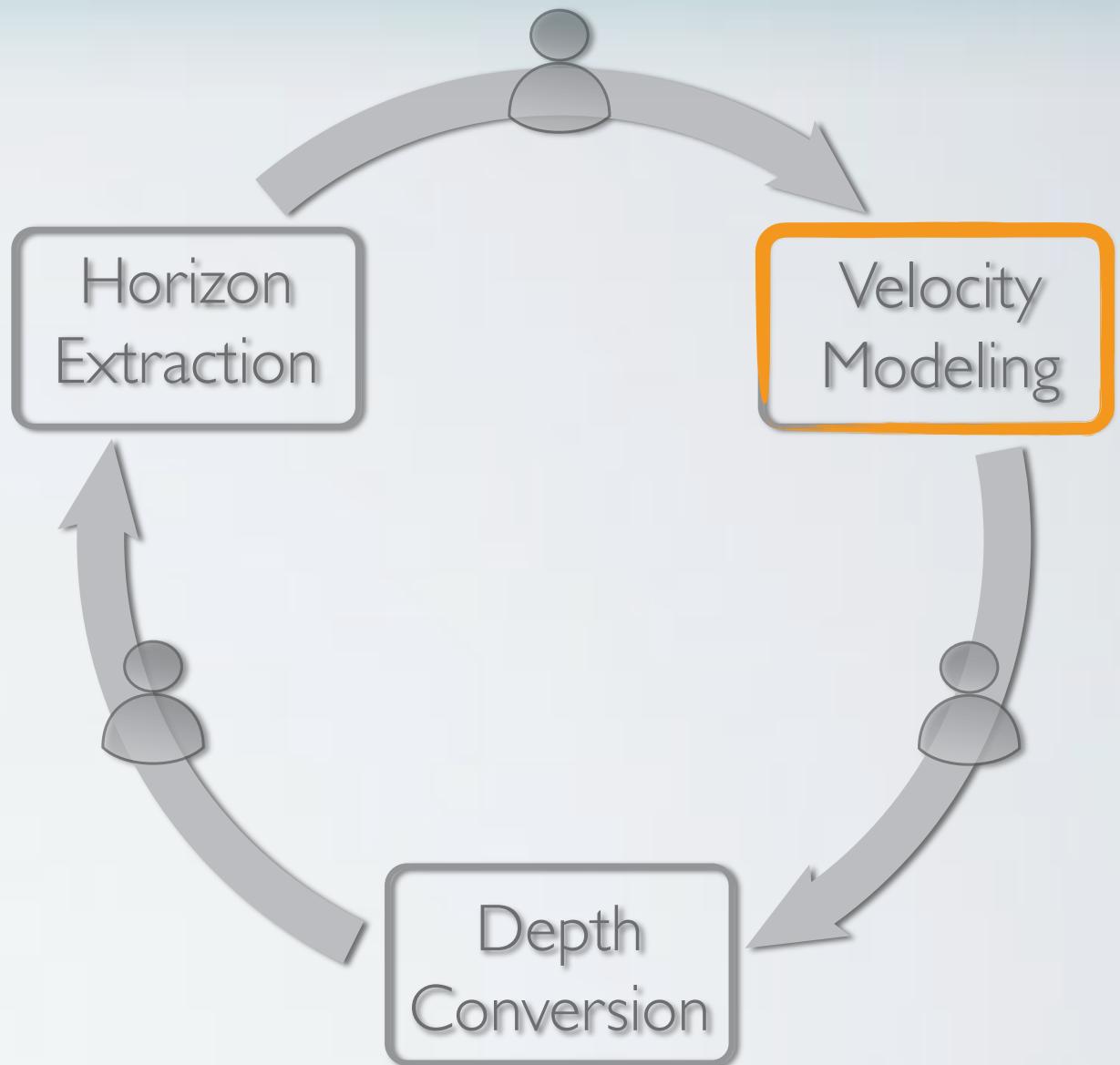
- Based on local solvers
  - no constraints, hard to interact with
  - no guarantee for a closed contour
  - no guarantee for a complete surface





# Conventional Workflow

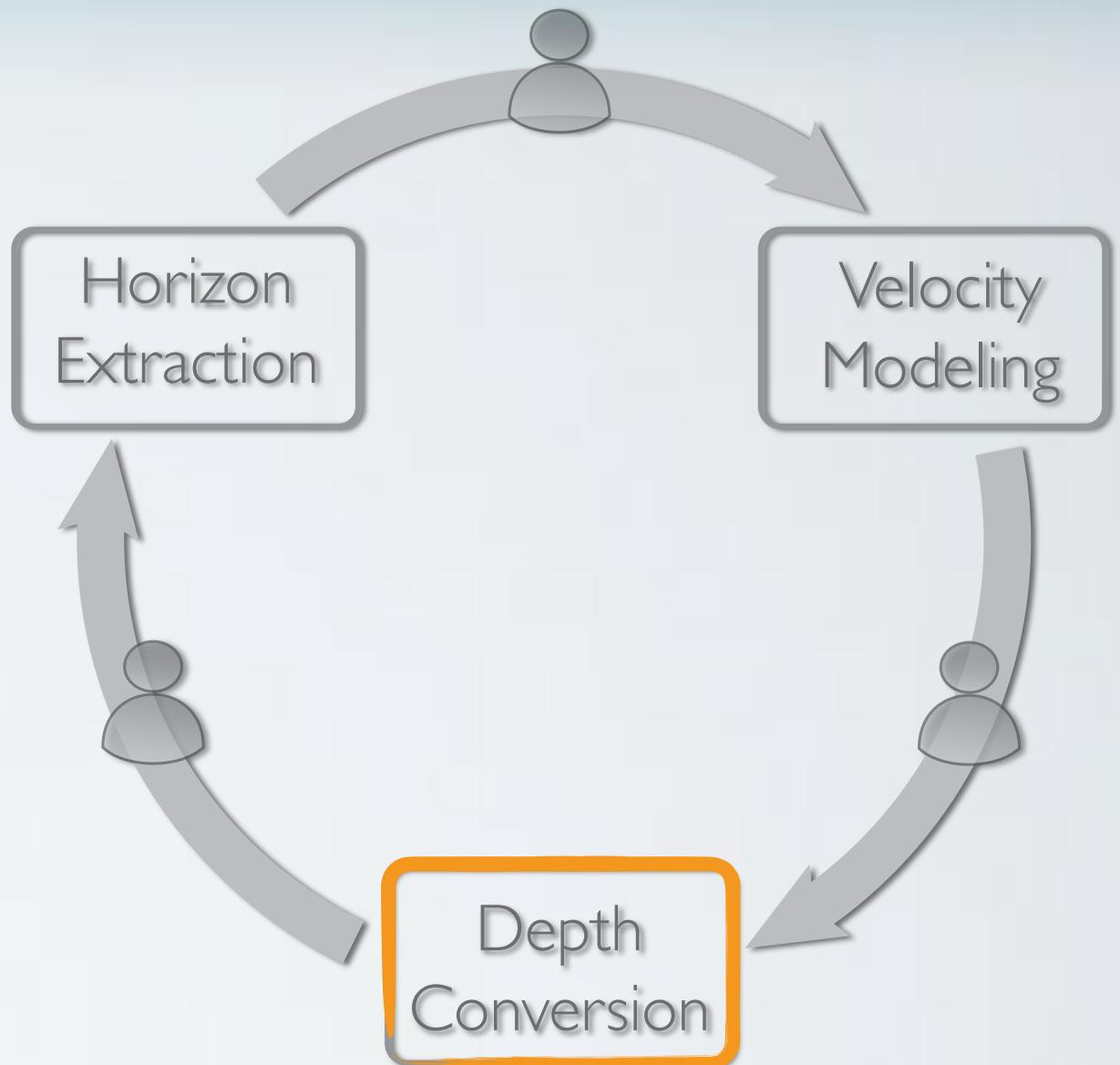
- Feature extraction
  - based on seismic tomography
  - results in model in time domain
- Velocity modeling
  - per layer velocity based on model in time
  - results in velocity model
- Depth Conversion
  - transforms model from time to depth





# Conventional Workflow

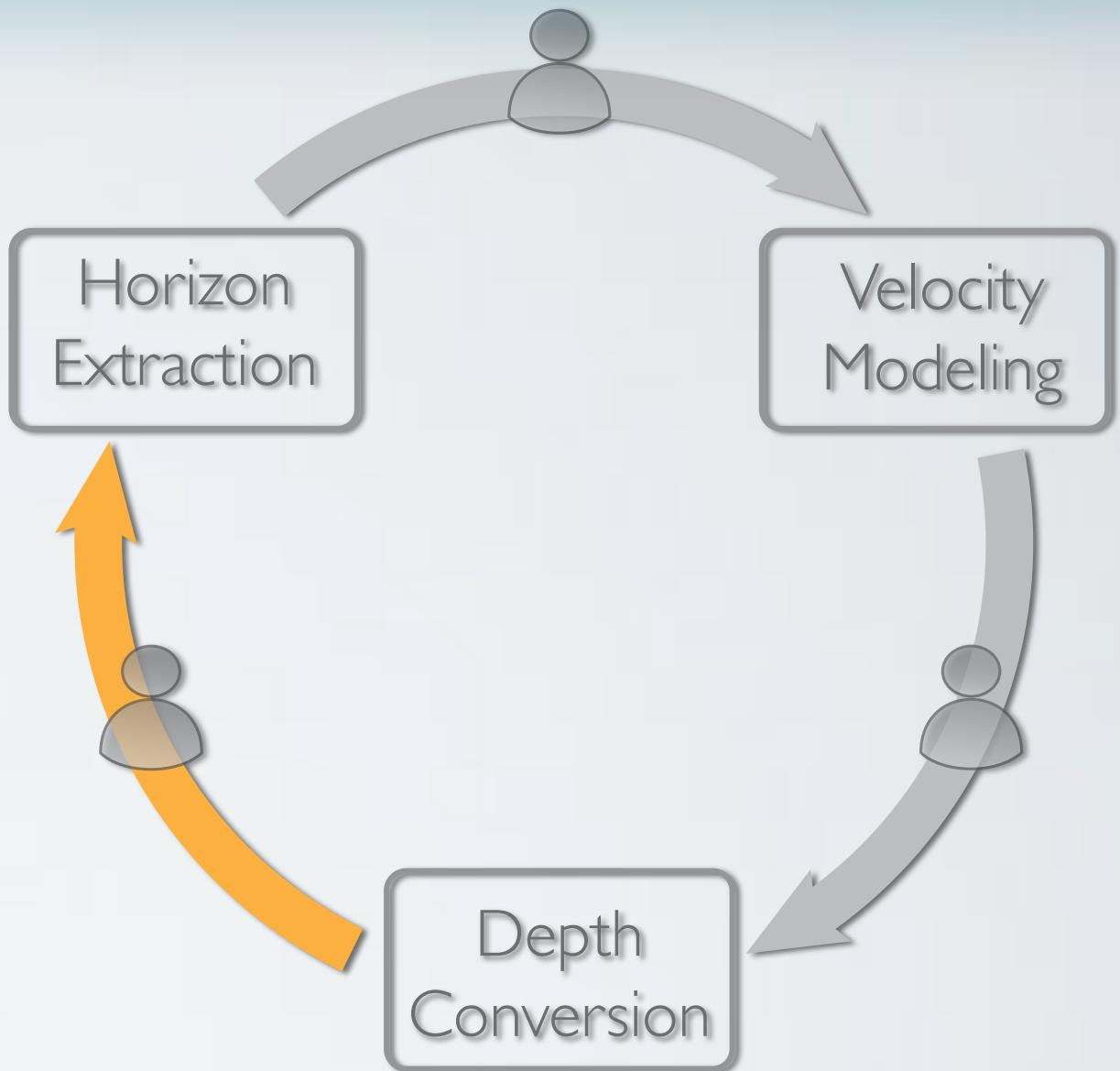
- Feature extraction
  - based on seismic tomography
  - results in model in time domain
- Velocity modeling
  - per layer velocity based on model in time
  - results in velocity model
- Depth Conversion
  - transforms model from time to depth





# Conventional Workflow // Problems

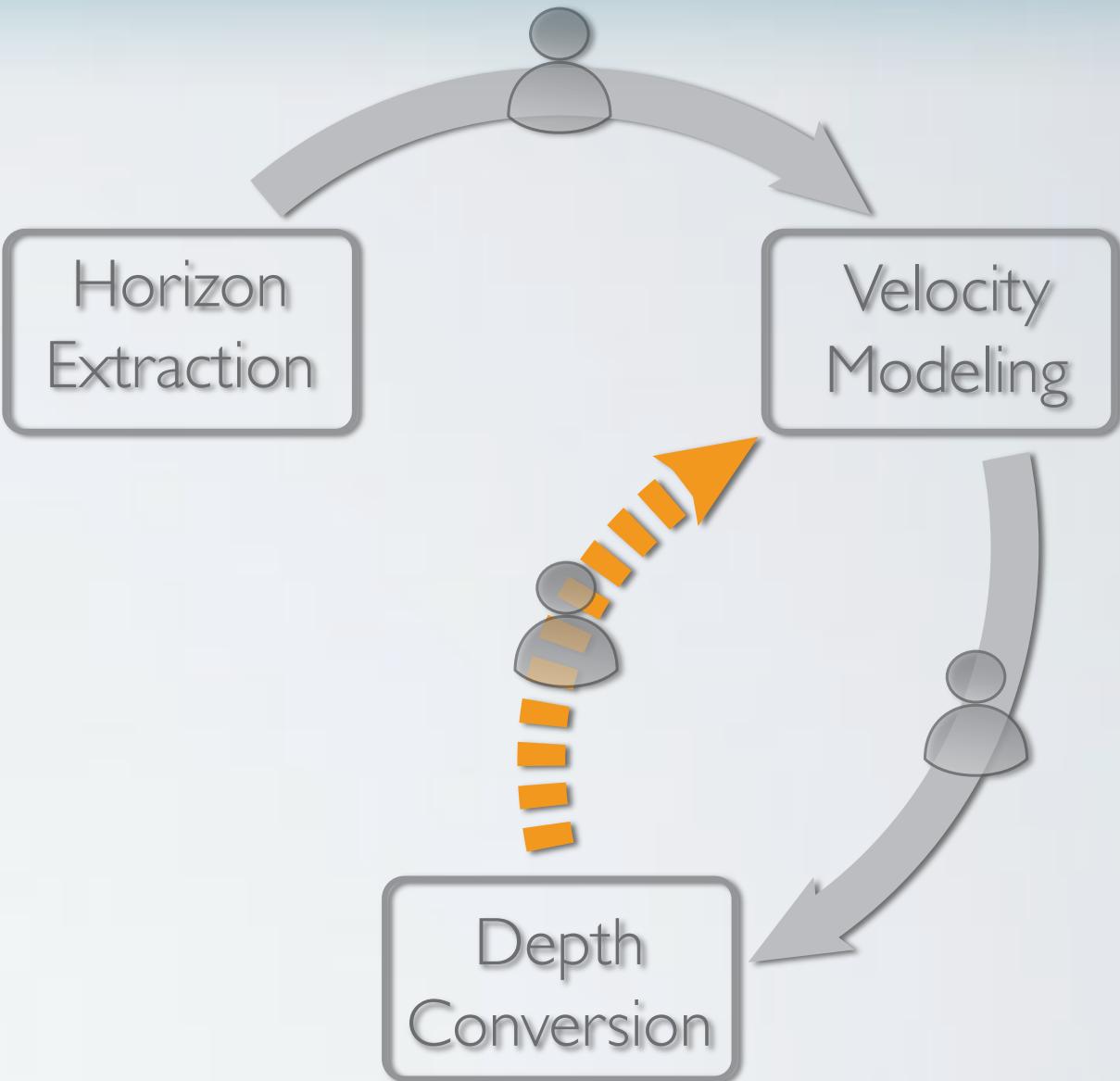
- Additional data only at the end of pipeline
- Errors become visible after depth conversion
  - propagating fixes back into interpretation is time-consuming and hard
  - instead locally hot-fixing velocity model
    - + might fix the layer model
    - might result in unphysical velocity model

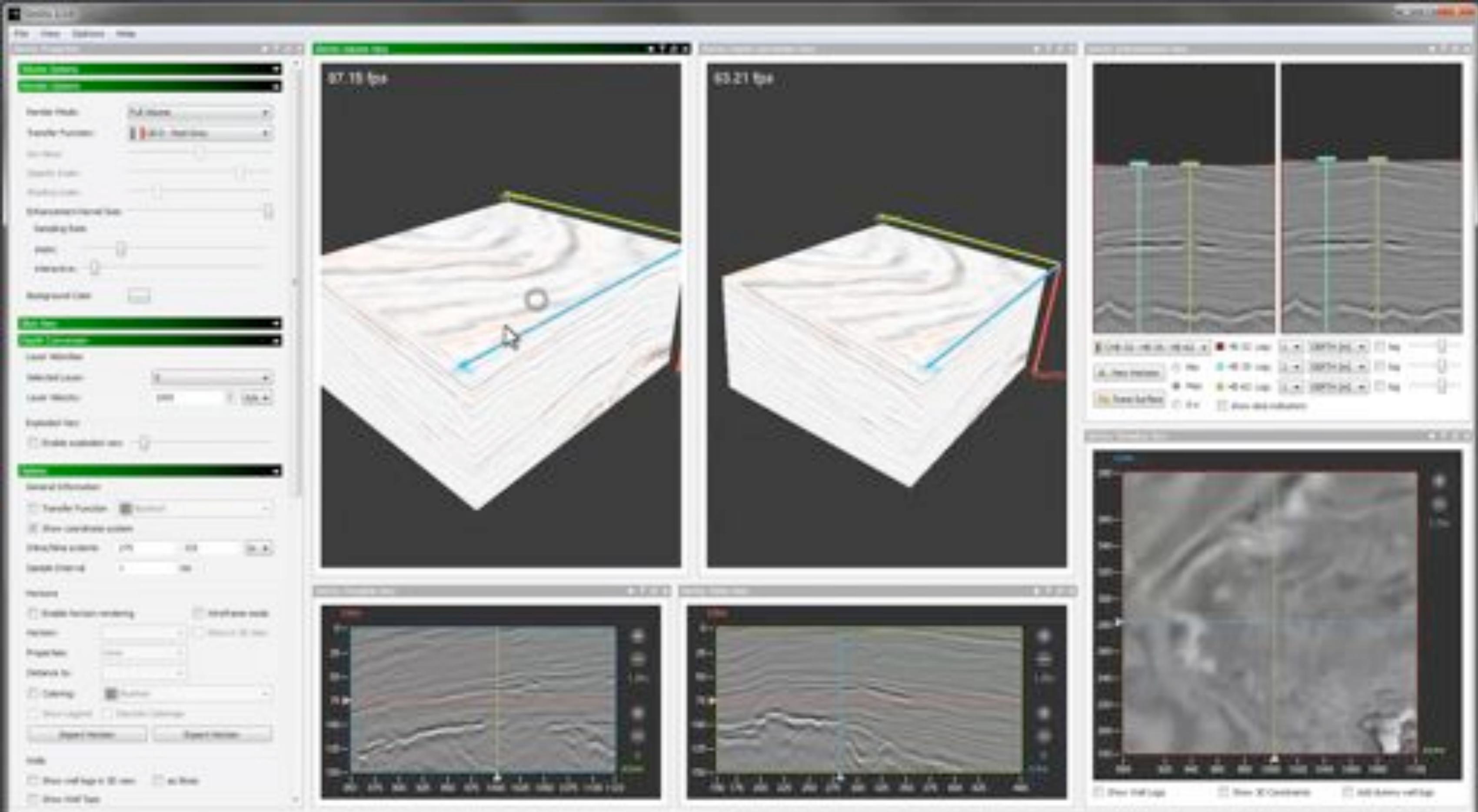




# Conventional Workflow // Problems

- Additional data only at the end of pipeline
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  - instead locally hot-fixing velocity model
    - + might fix the layer model
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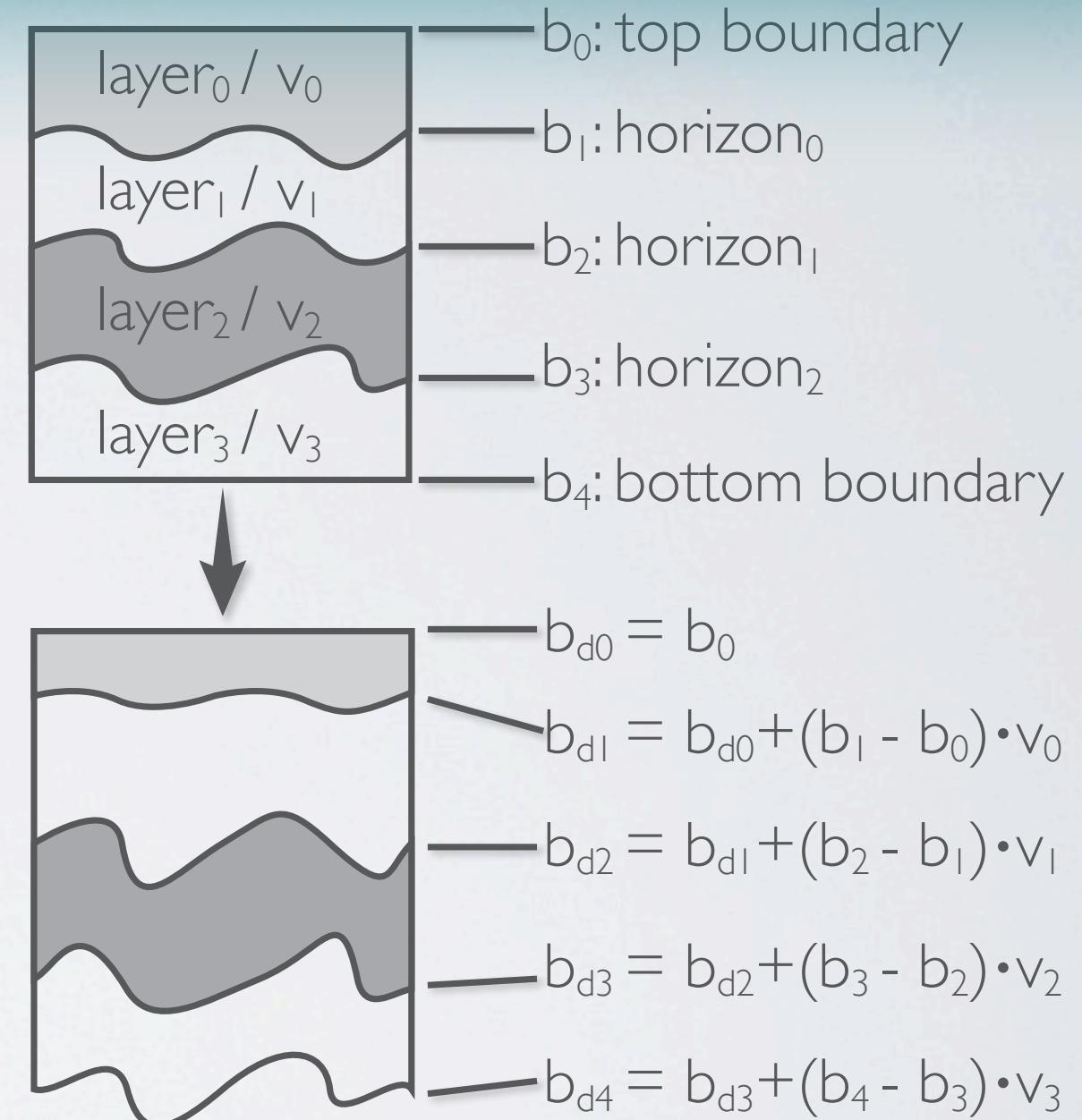




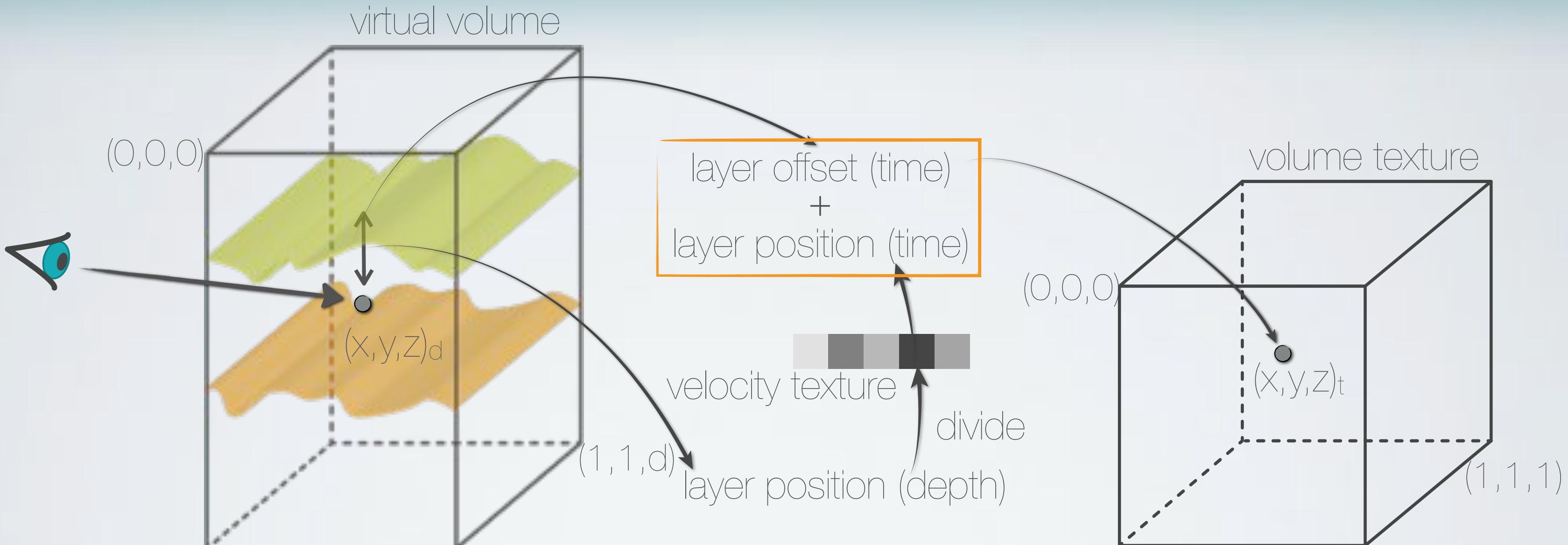
# Joint Time/Depth Domain // Deformation



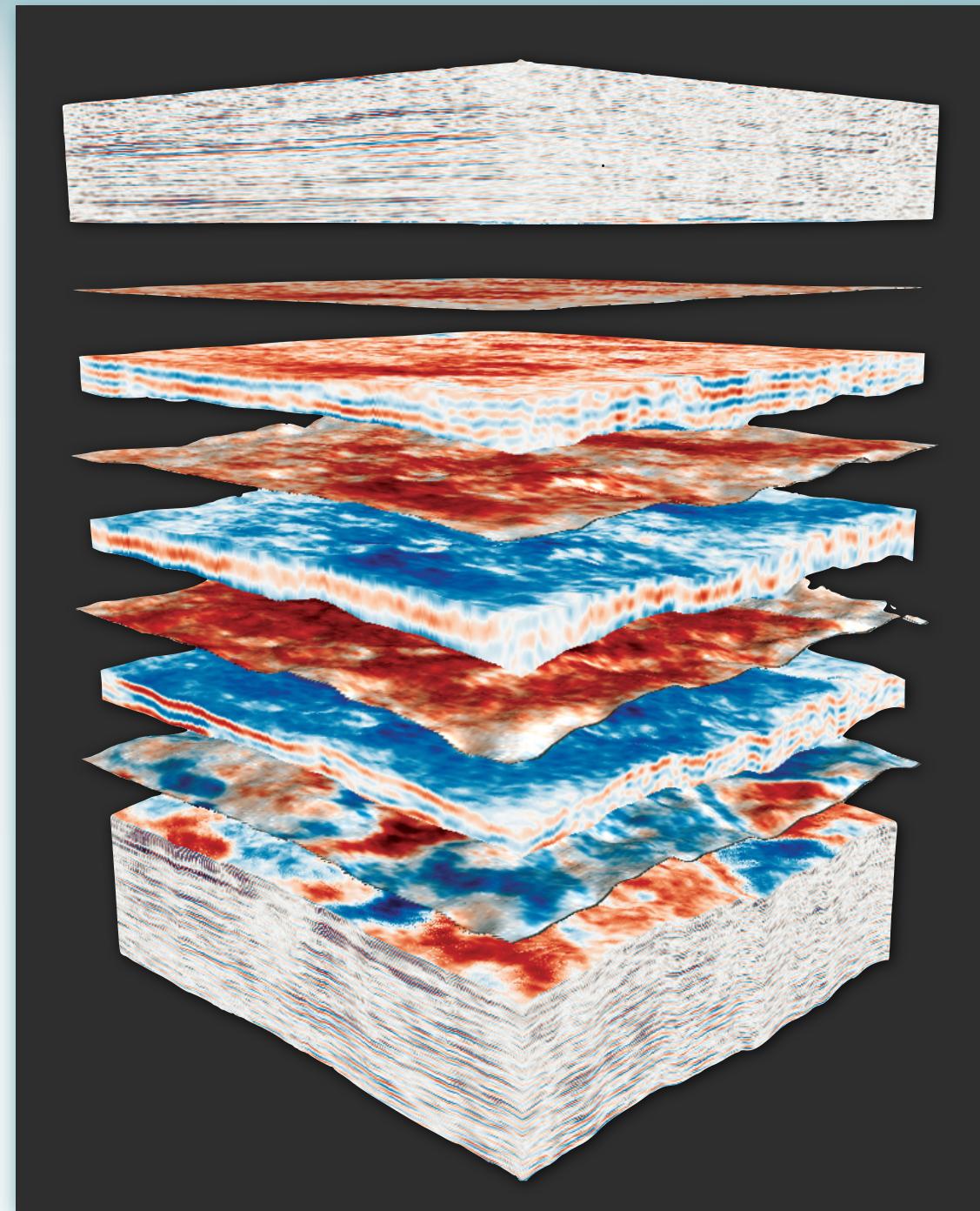
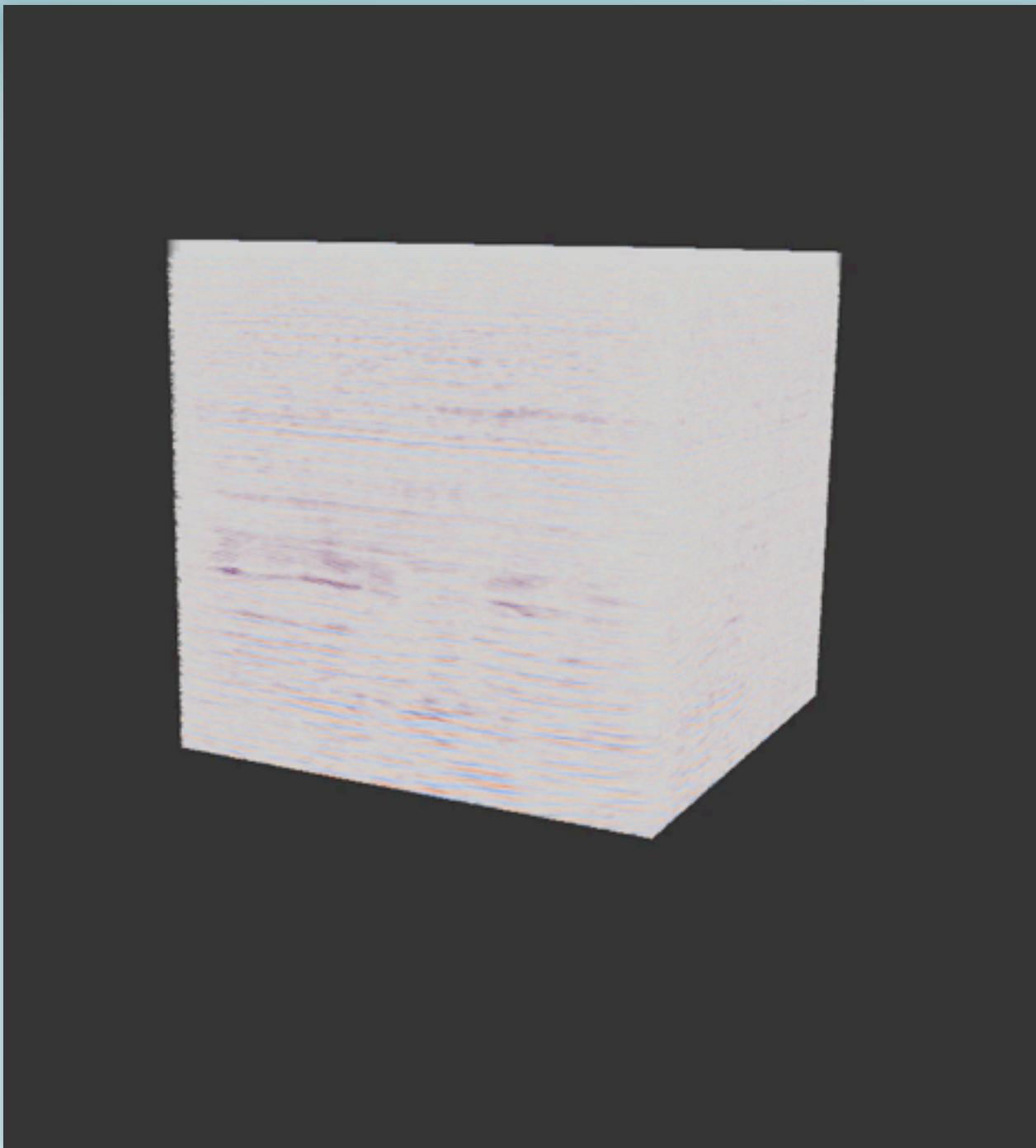
- Horizon deformation
  - iteratively deform boundaries from top to bottom
  - top boundary is equal in time & depth
  - following boundaries are sum of previous deformed boundary and deformed layer
  - all x,y-coordinates are independent



# Joint Time/Depth Domain // Deformation



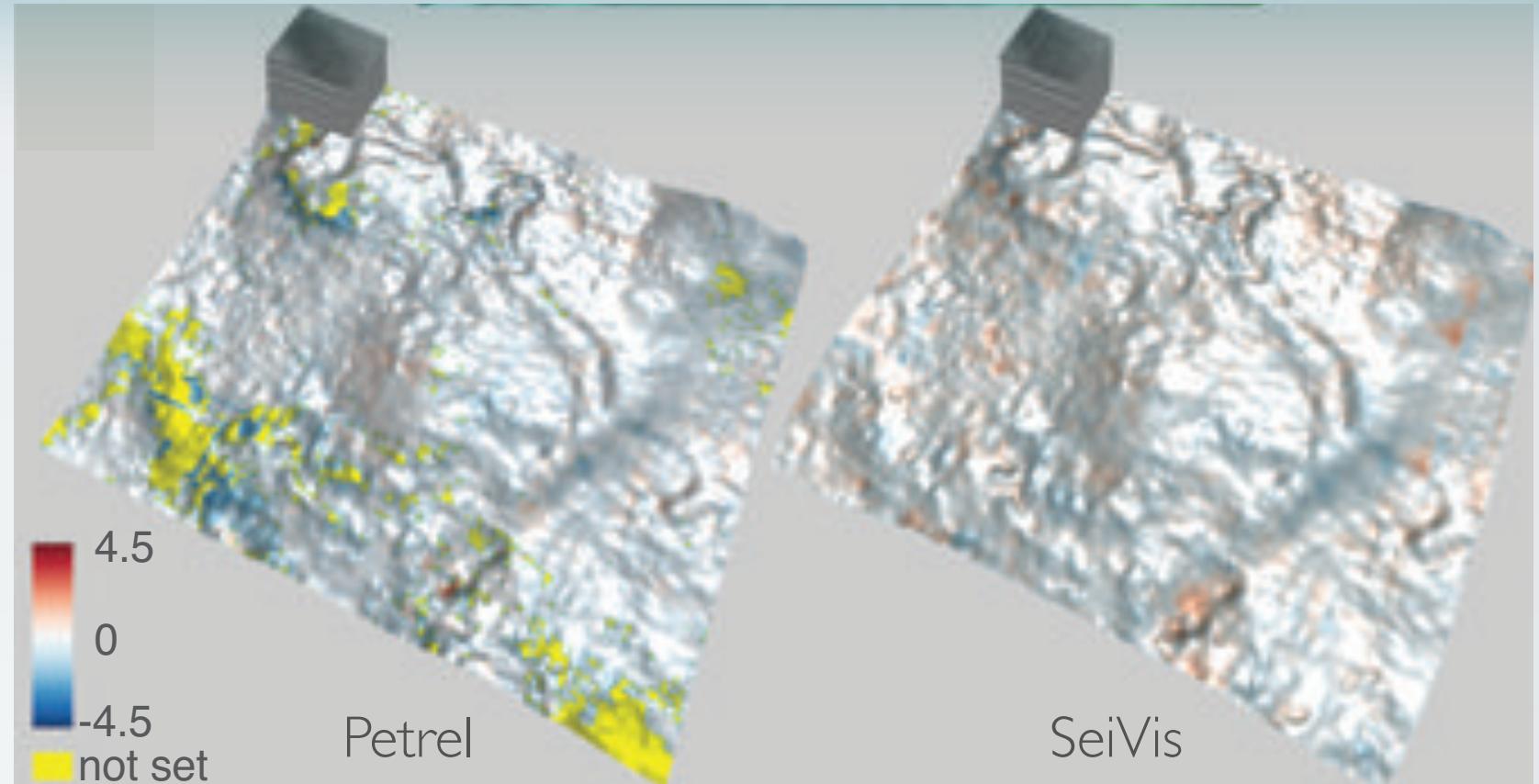
# Volume Deformation // Exploded Views



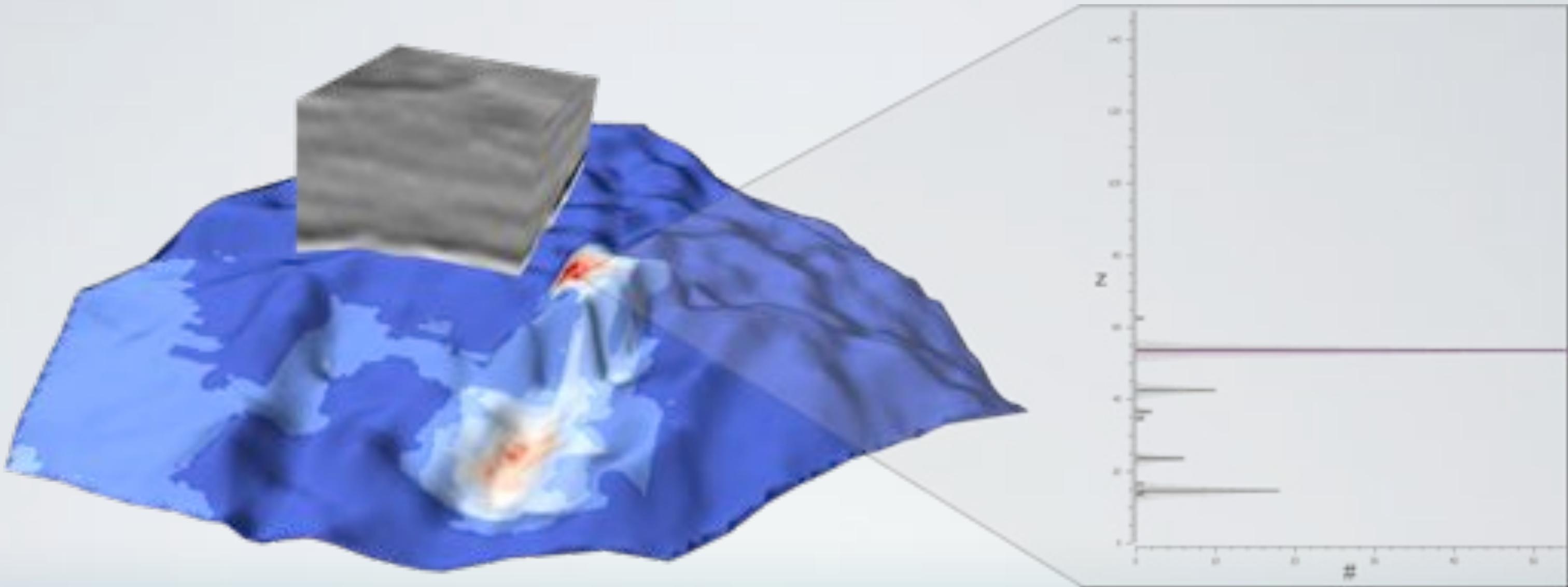


# Results // Expert Evaluation

- 60 minutes for both apps  
(after introduction to our tool)
- Expert likes prism based workflow
- Live depth conversion is very helpful



App	Initial Interpret.	Velocity computation	Depth conv. computation	Refine	# slices / prisms	Avg. time
Petrel	>60min	21s	29s	n/a	18	200s
SeiVis	~45min	on the fly	on the fly	<10 min	63	43s



Visual Parameter Exploration for Horizon Extraction





# Publications



T. Höllt, G. Chen, C.D. Hansen, and M. Hadwiger.  
**Extraction and Visual Analysis of Seismic Horizon Ensembles.**  
To appear in *Proceedings of Eurographics 2013 (short papers)*.



# Motivation // Cost Function

- Three components, linearly blended:

- gray value-based term,  $g_{\text{gray}}$

- waveform-based term,  $g_{\text{wave}}$

- similarity-based term,  $g_{\text{smooth}}$

- Penalty for larger surfaces

- Final cost with three user adjustable parameters:

$$\text{cost}(e) = p_2 \cdot \left( p_1 \cdot (p_0 \cdot g_{\text{gray}} + (1 - p_0) \cdot g_{\text{wave}}) + (1 - p_1) \cdot g_{\text{smooth}} \right)$$

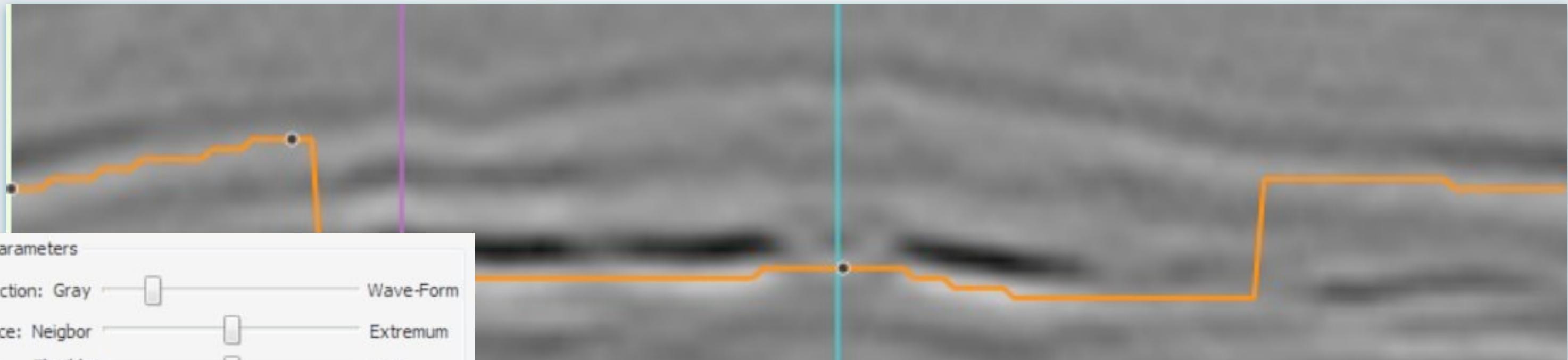
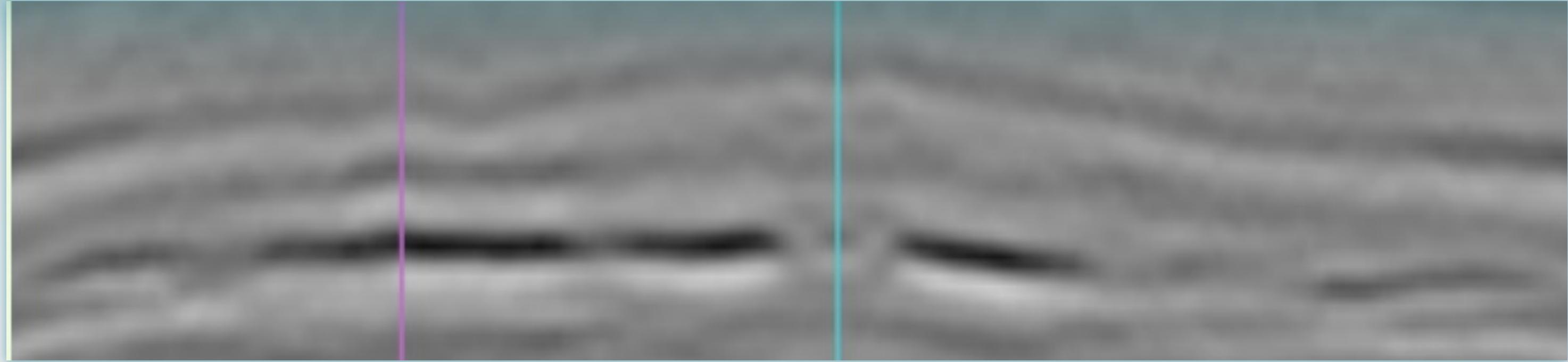
$$g_{\text{gray}}(e) = \sum_{(x,y,z) \in \mathcal{N}(e)} |t - f(x, y, z)|$$

$$g_{\text{wave}}(e) = \sum_{(x,y,z) \in \mathcal{N}(e)} \left( 1 - \sum_{k=1}^m \varphi_s(x, y, z, k) \right)$$

$$g_{\text{smooth}}(e) = \sum_{(x,y,z) \in \mathcal{N}(e)} |f(x, y, z) - \text{avg}(e)|$$

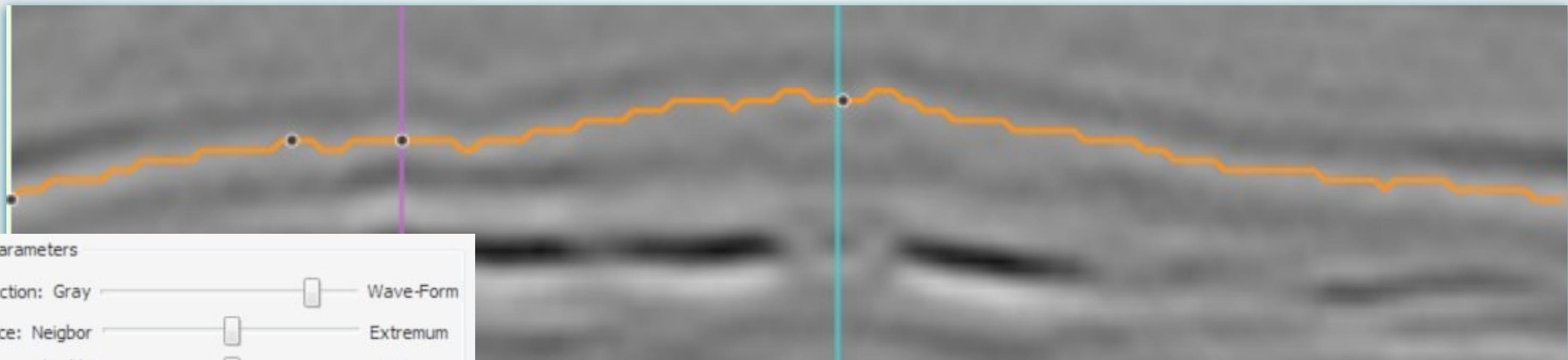
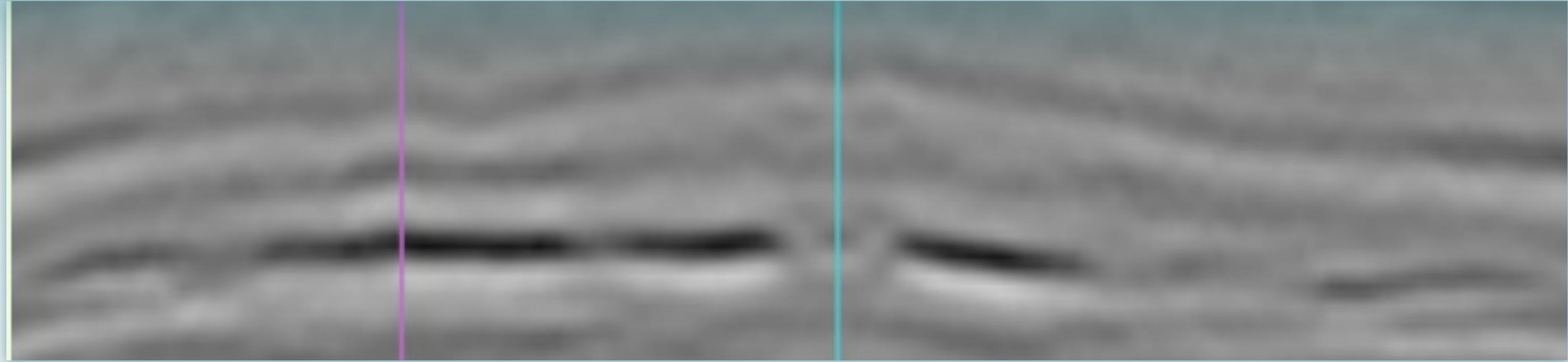


# Motivation





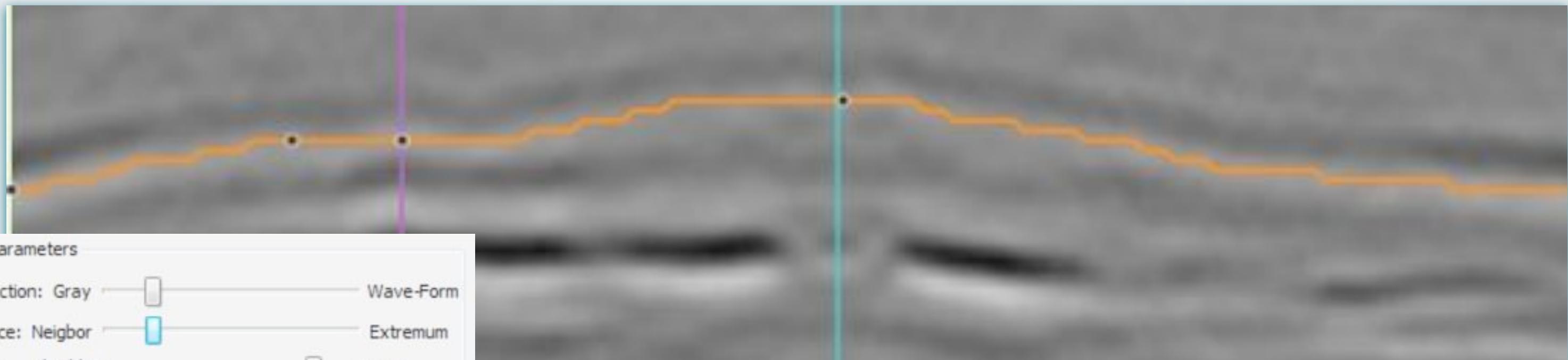
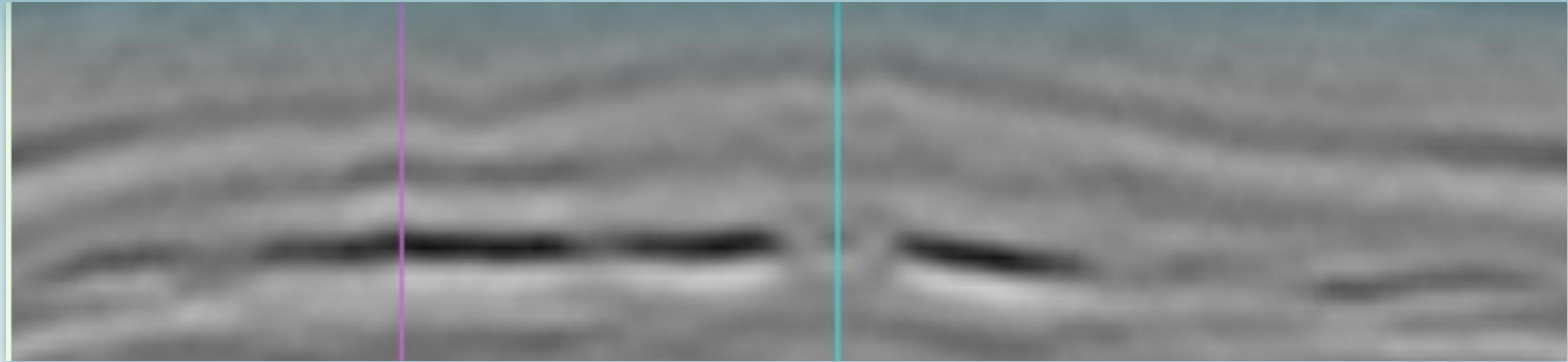
# Motivation



Tracing Parameters	
Cost Function:	Gray
Preference:	Neigbor
Flexibility:	Flexible
Wave-Form	<input type="checkbox"/>
Extremum	<input type="checkbox"/>
Stiff	<input type="checkbox"/>

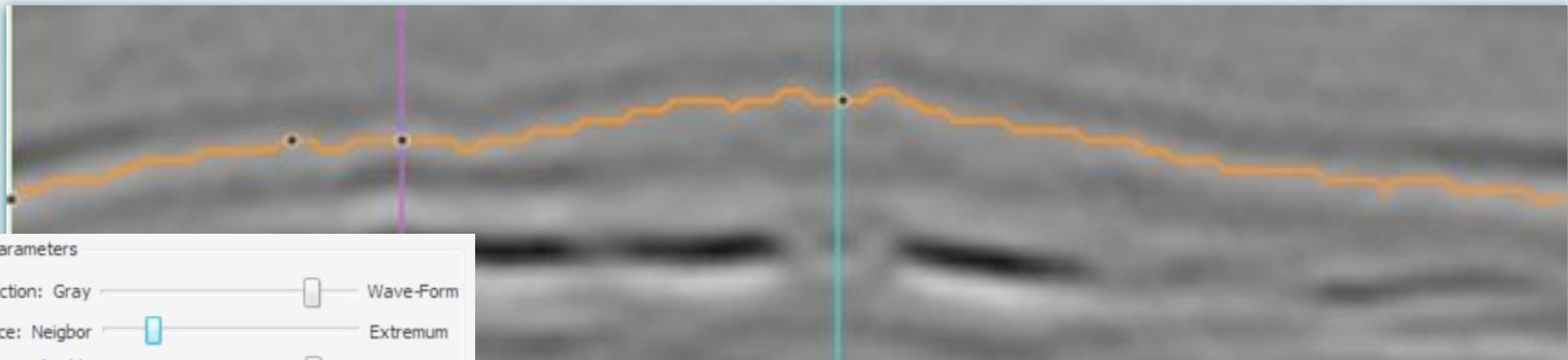
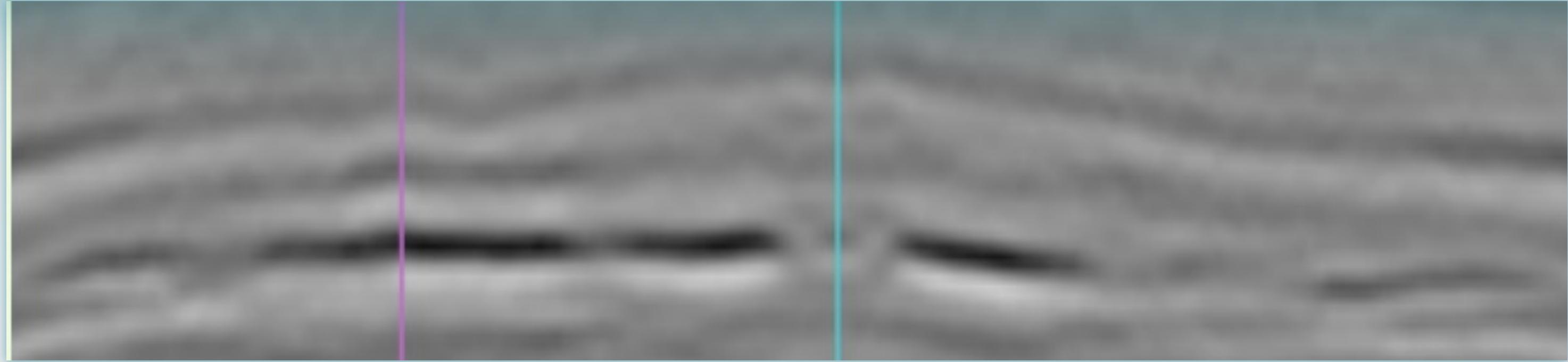


# Motivation





# Motivation

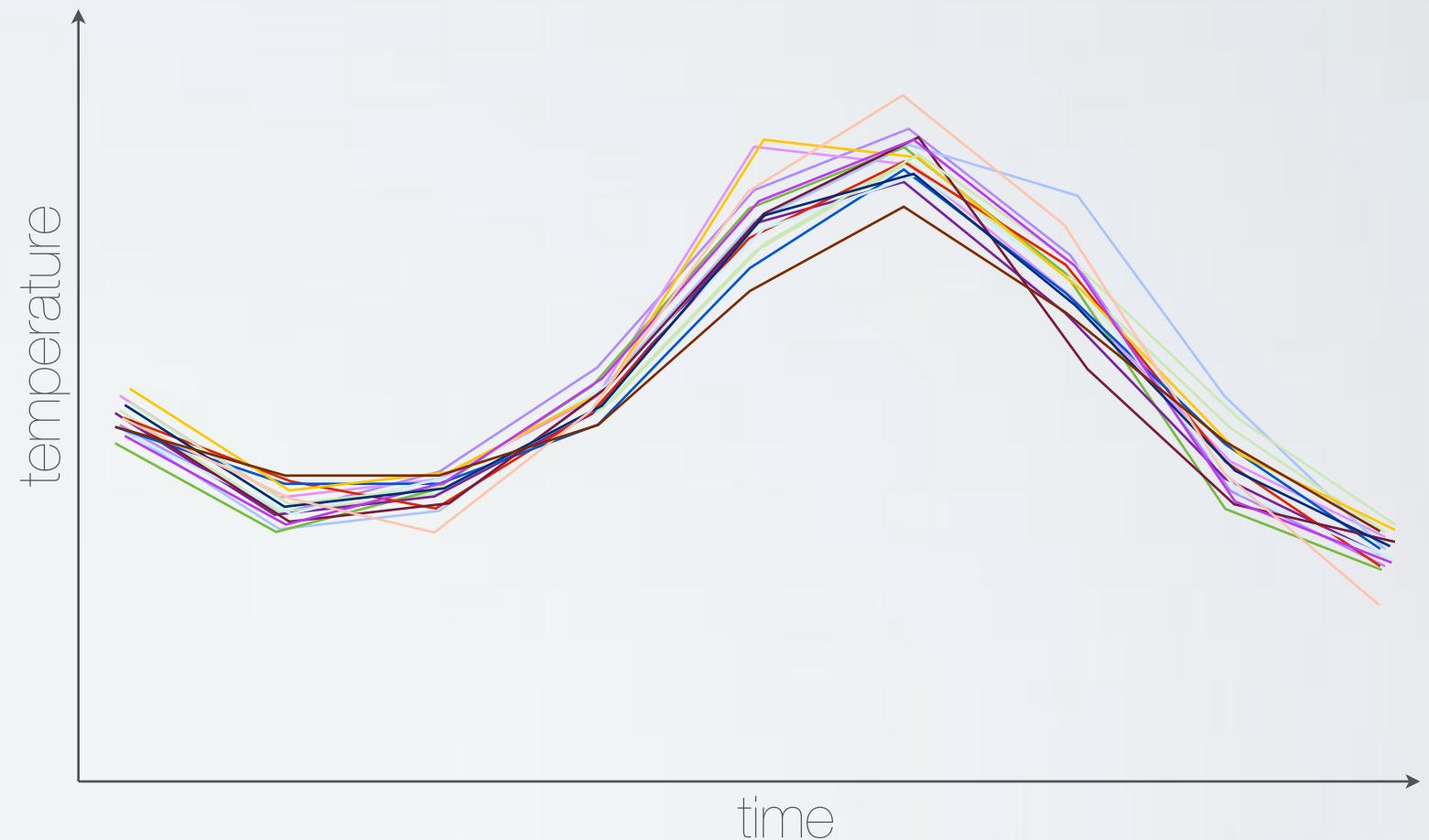


Tracing Parameters		
Cost Function:	Gray	<input type="checkbox"/> Wave-Form
Preference:	Neigbor	<input checked="" type="checkbox"/> Extremum
Flexibility:	Flexible	<input type="checkbox"/> Stiff



# Ensemble Data

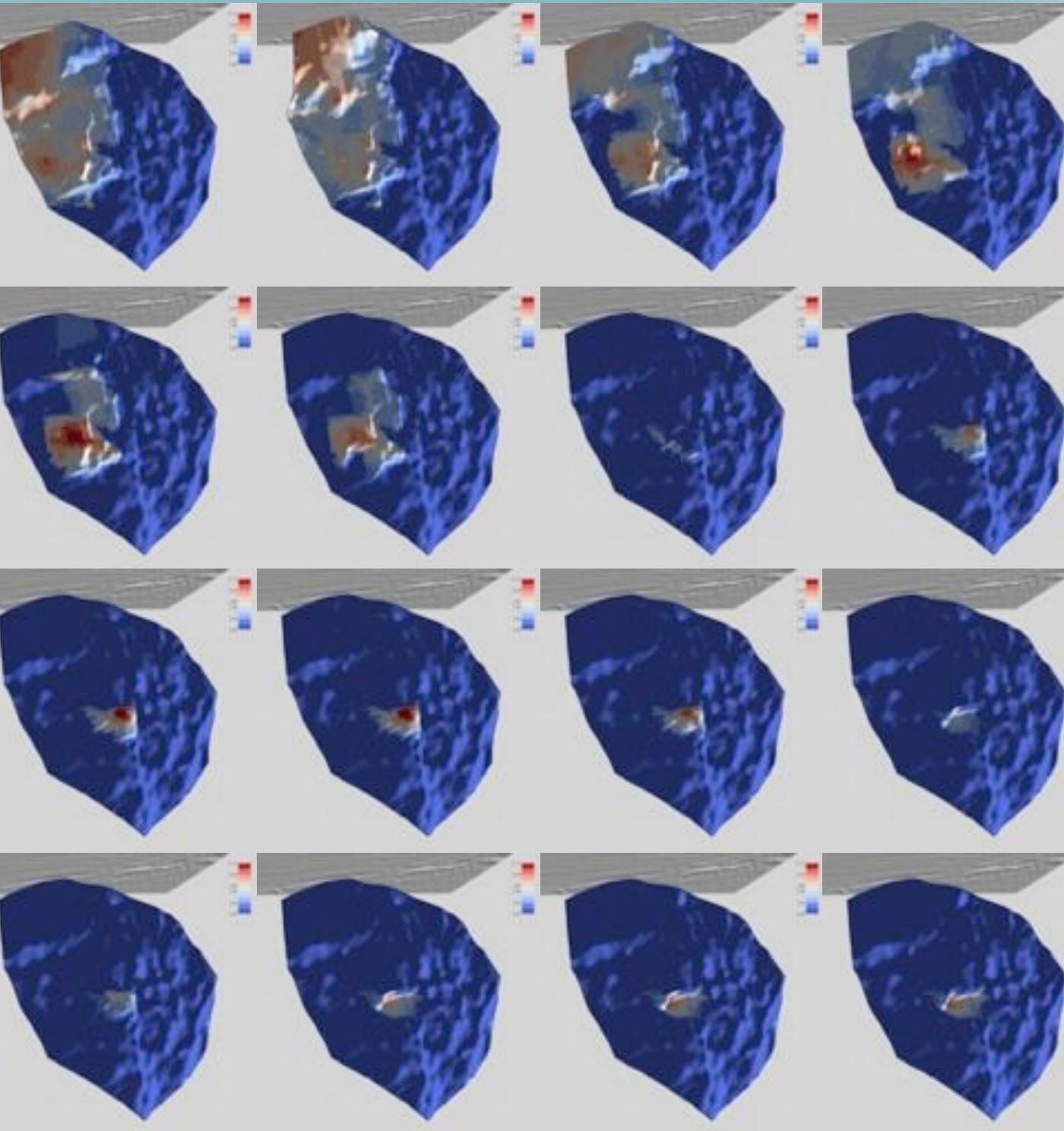
- Idea: compute multiple solutions for a single simulation/feature/event
- An ensemble usually is
  - multivalued
  - multivariate
  - multidimensional



# Ensemble Extraction



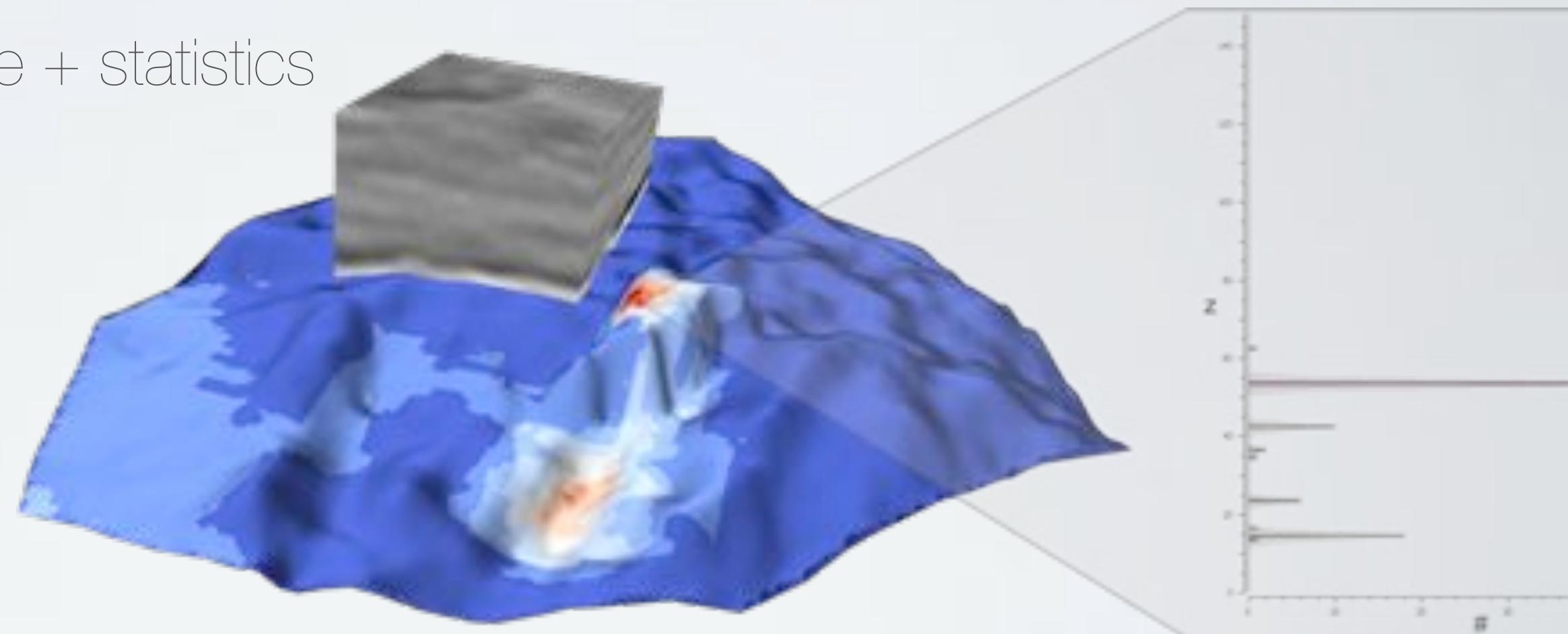
- We have global optimization surface extraction technique with a parameterized cost function
  - sample parameter space
  - extract surface for each sample without interaction
  - results in a set of possible surfaces for each horizon





# Multivalue Visualization

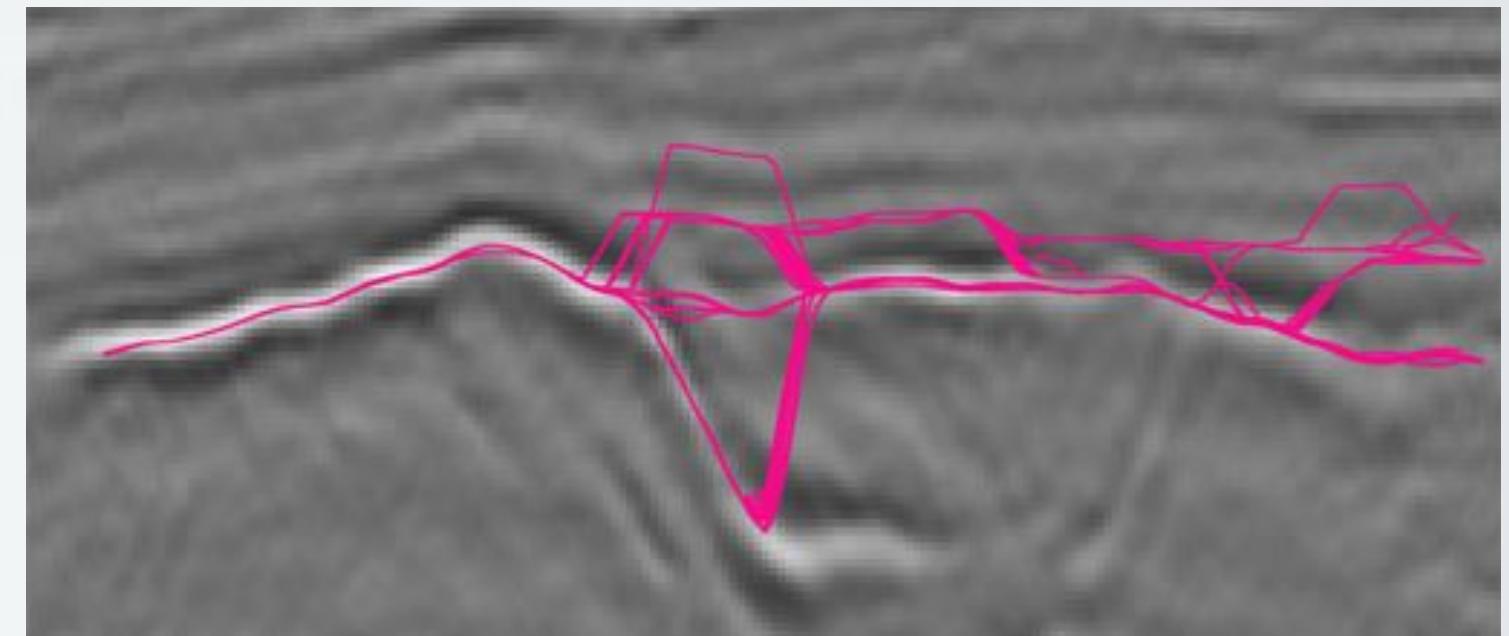
- Statistical analysis
- Overview first
  - representative surface + statistics
- Details on demand
  - interactive probing
  - live parameter-space exploration



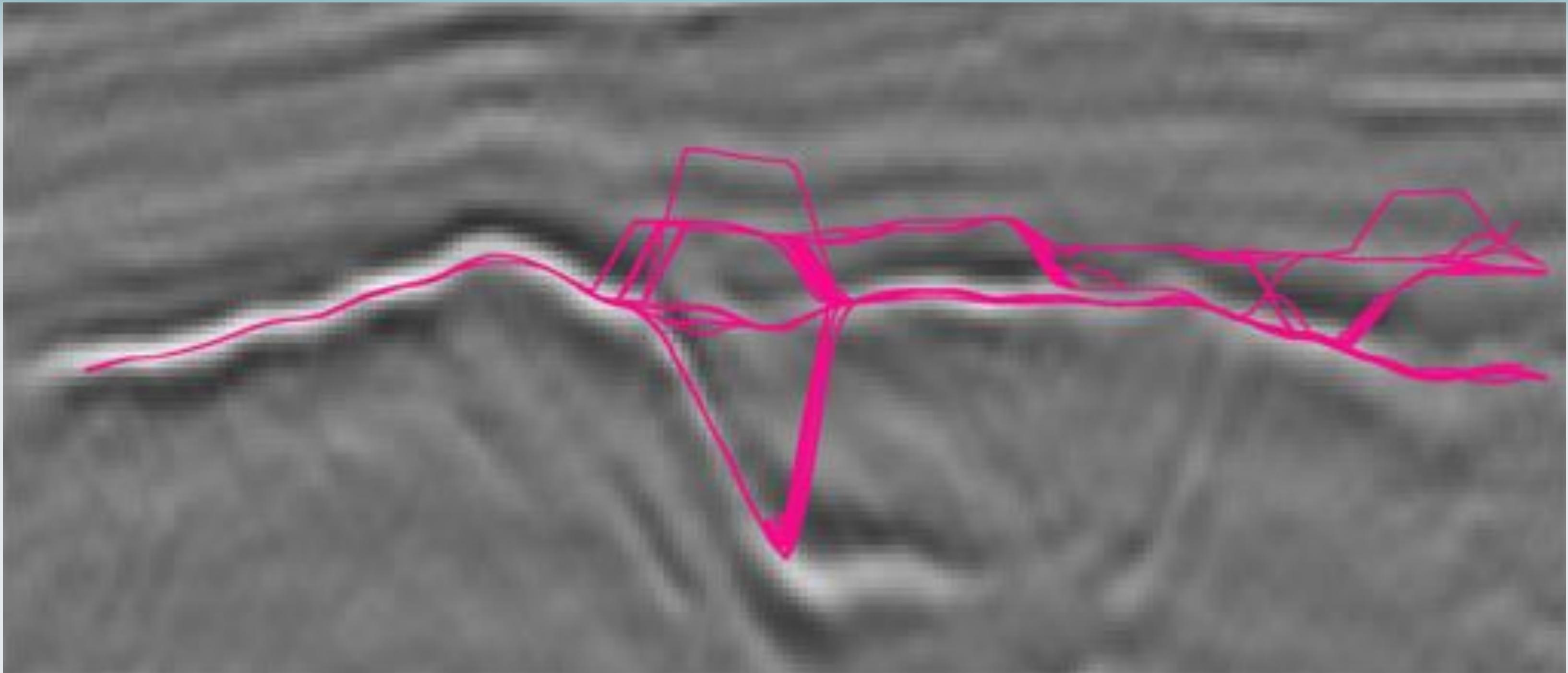
# Representative Surface



- Surface extraction leads to clustering
  - mean surface is not a good fit



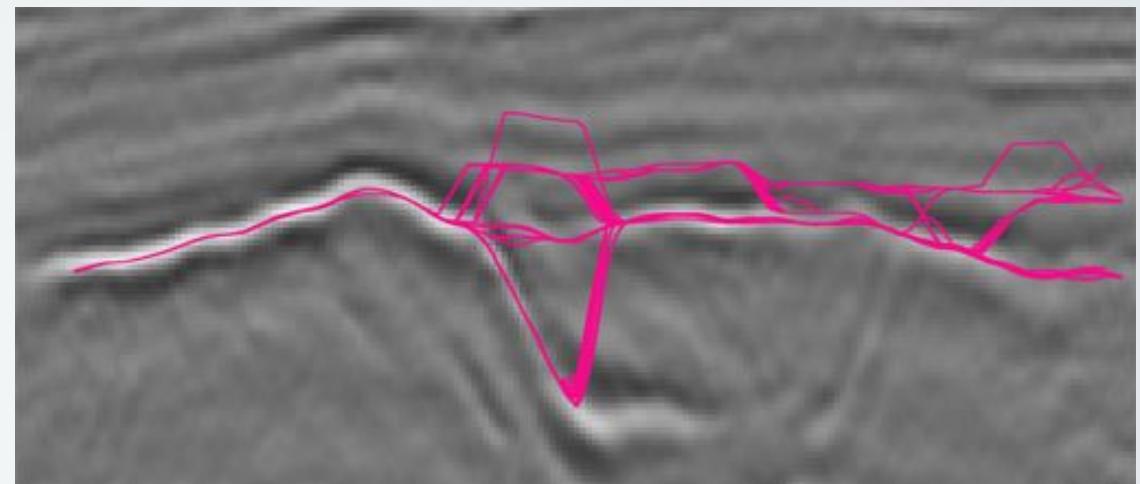
# Representative Surface



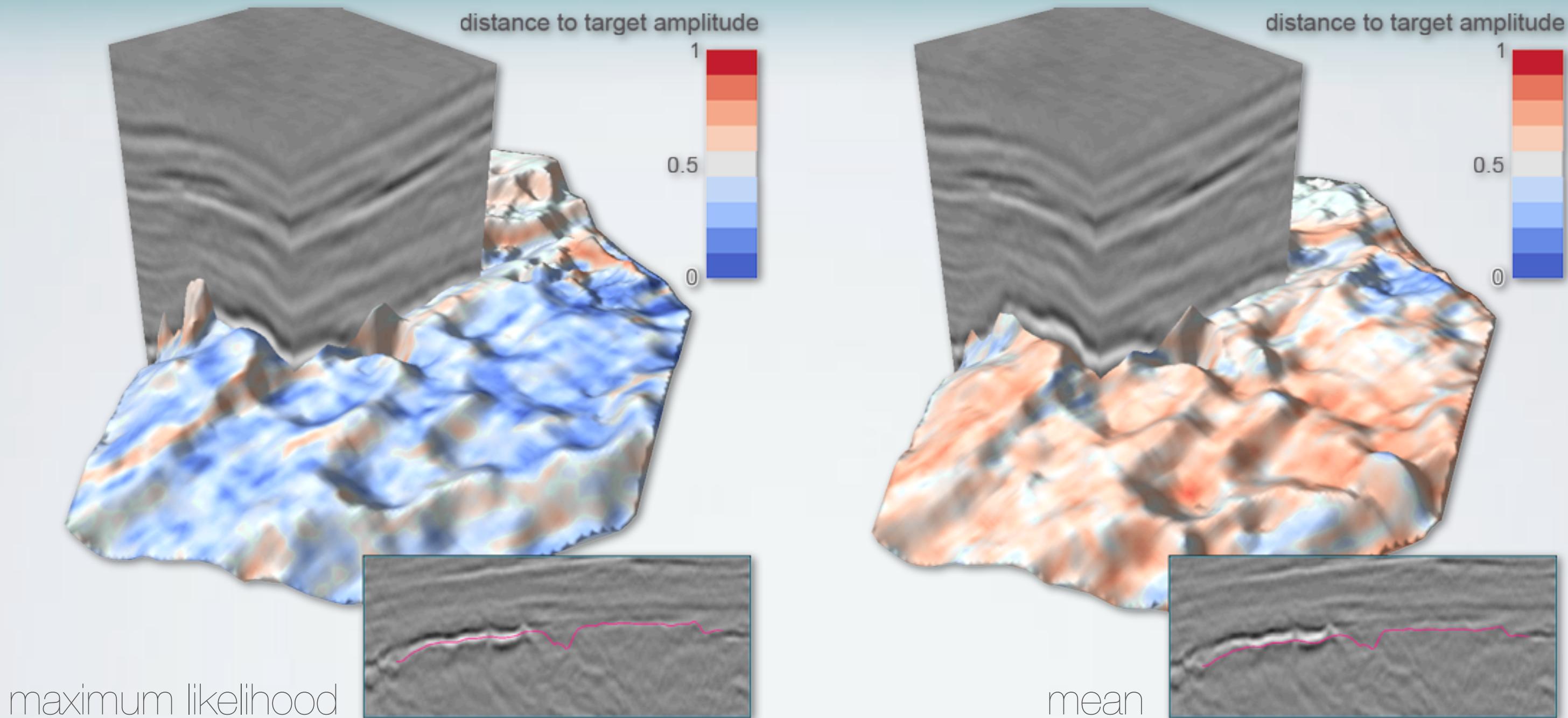
# Representative Surface



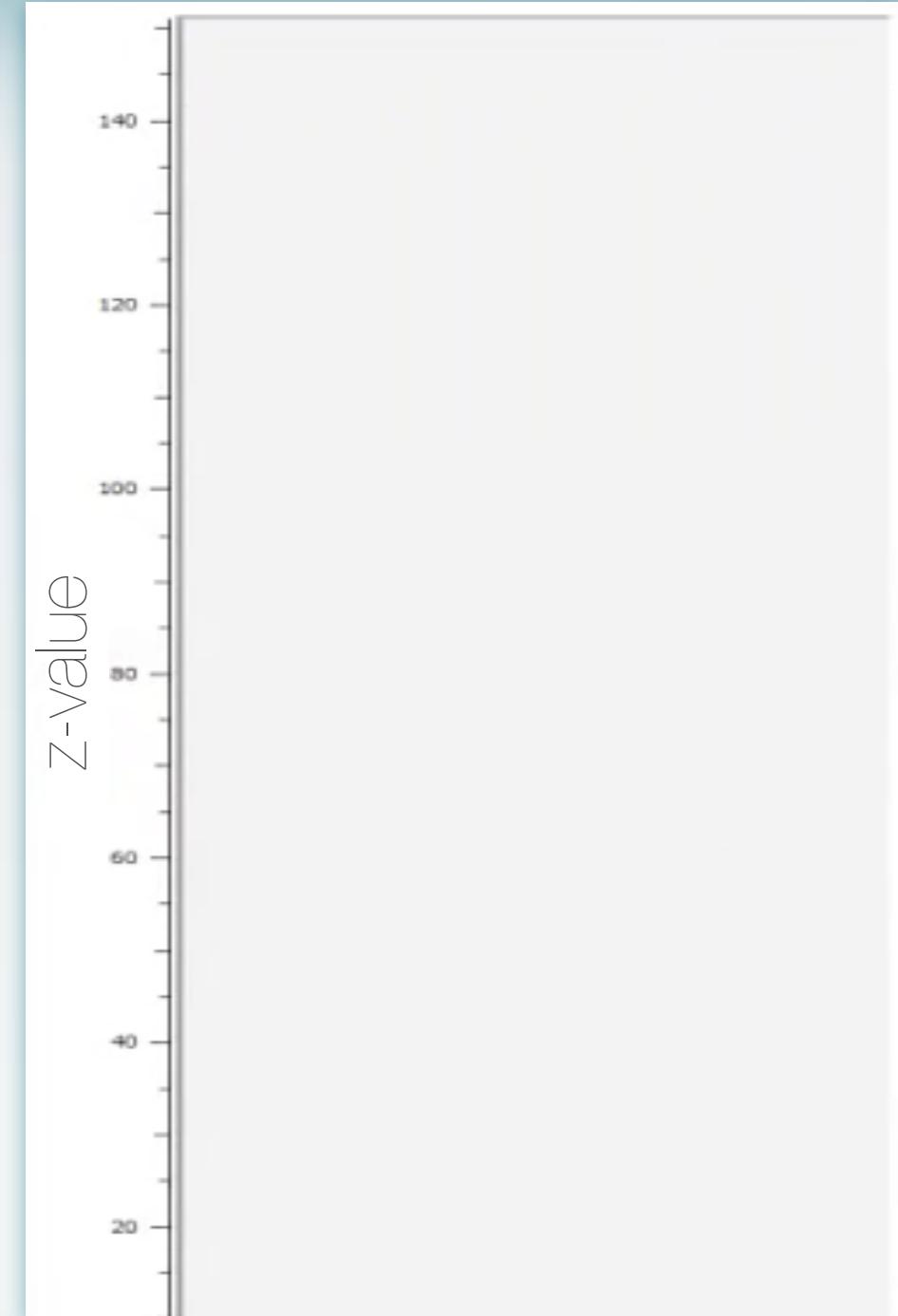
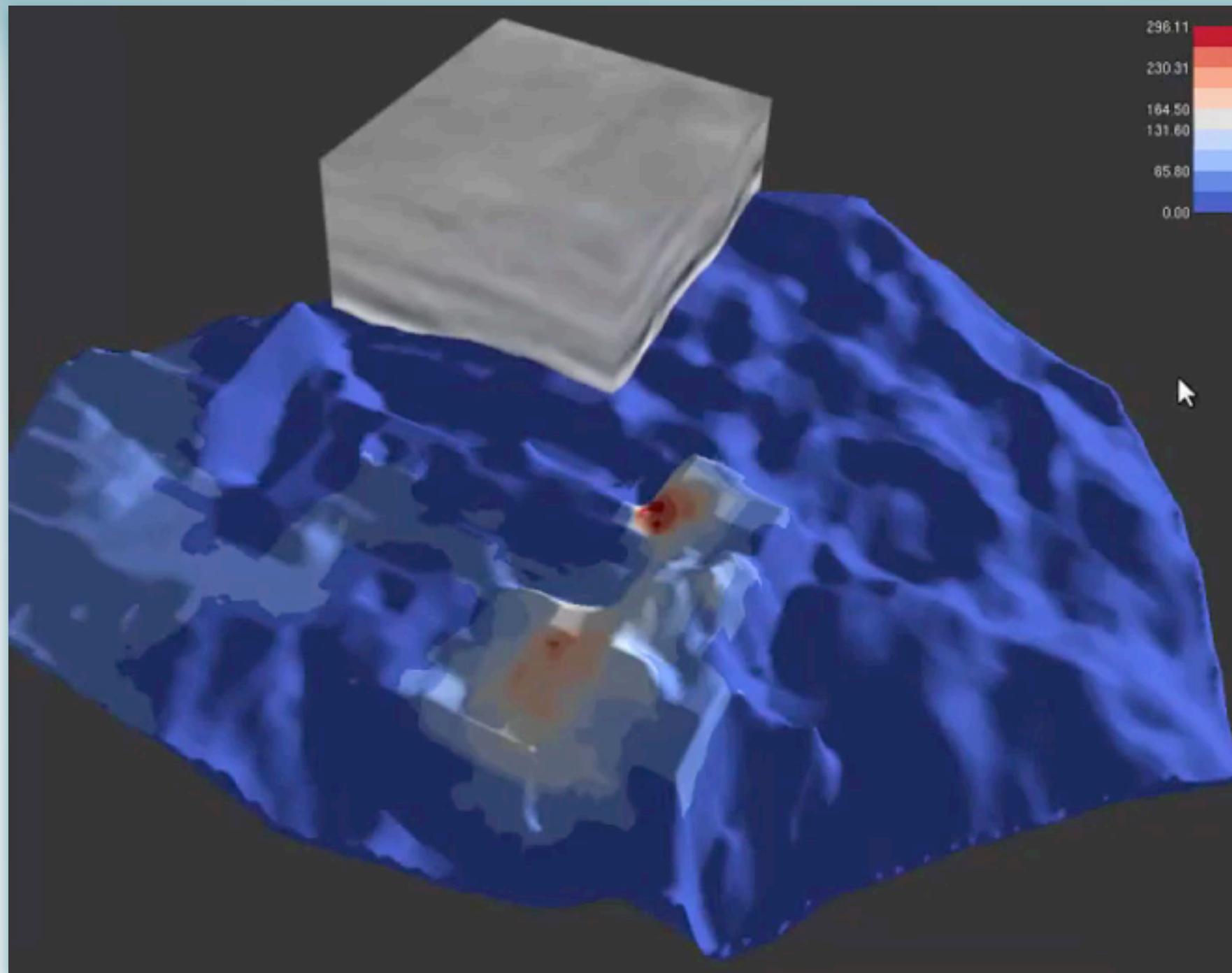
- Surface extraction leads to clustering
  - mean surface is not a good fit
- ⇒ use a 'maximum likelihood' surface instead
  - compute a probability for each surface patch
  - sum up probabilities for all patches
  - use surface with the highest sum



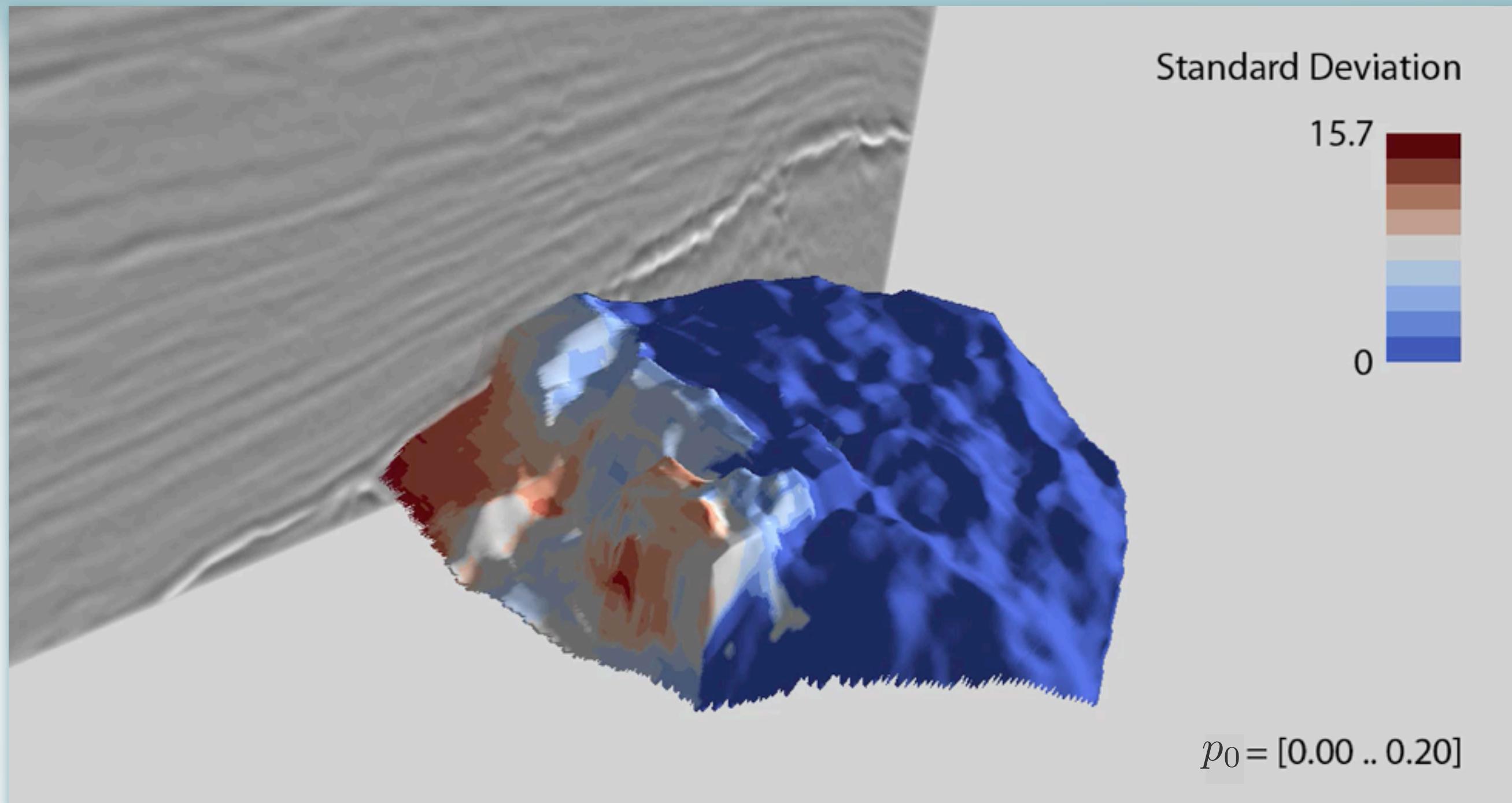
# Maximum Likelihood Surface II



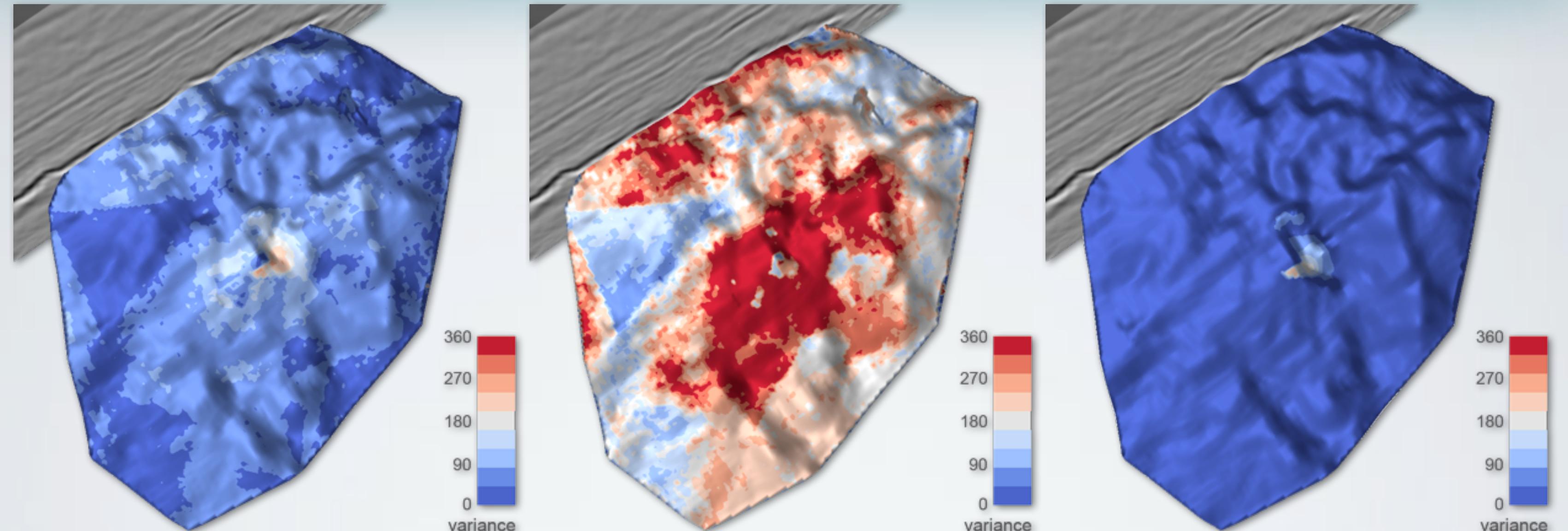
# Interactive Probing



# Parameter Space Exploration



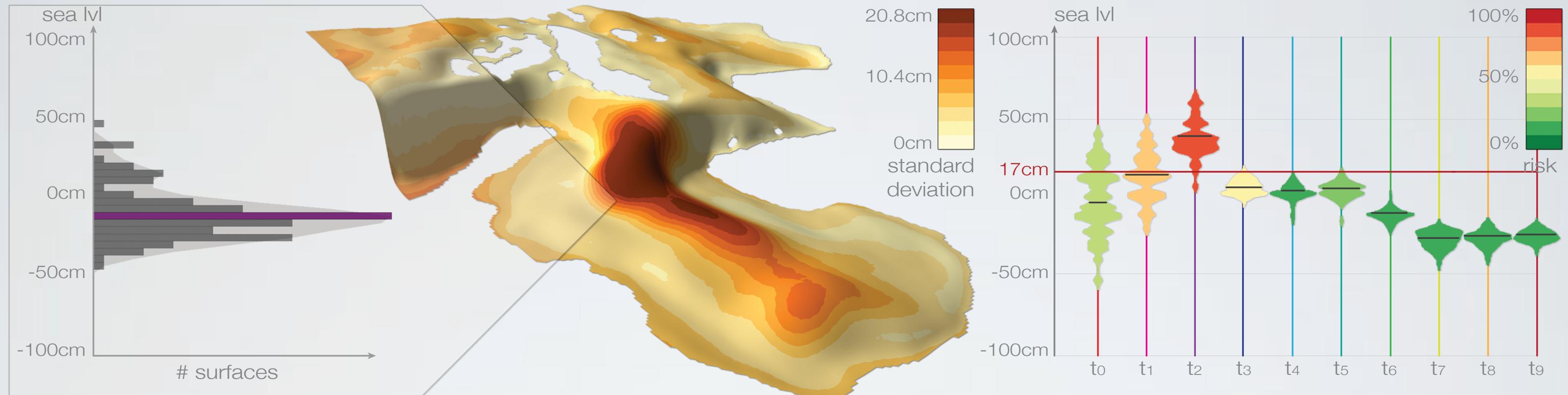
# Parameter Space Exploration II



$p_1 = [0..1]$

$p_1 = [0.9..1.0]$

$p_1 = [0.0..0.9]$



# Visual Analysis of Uncertainties in Ocean Forecasts





# Publications

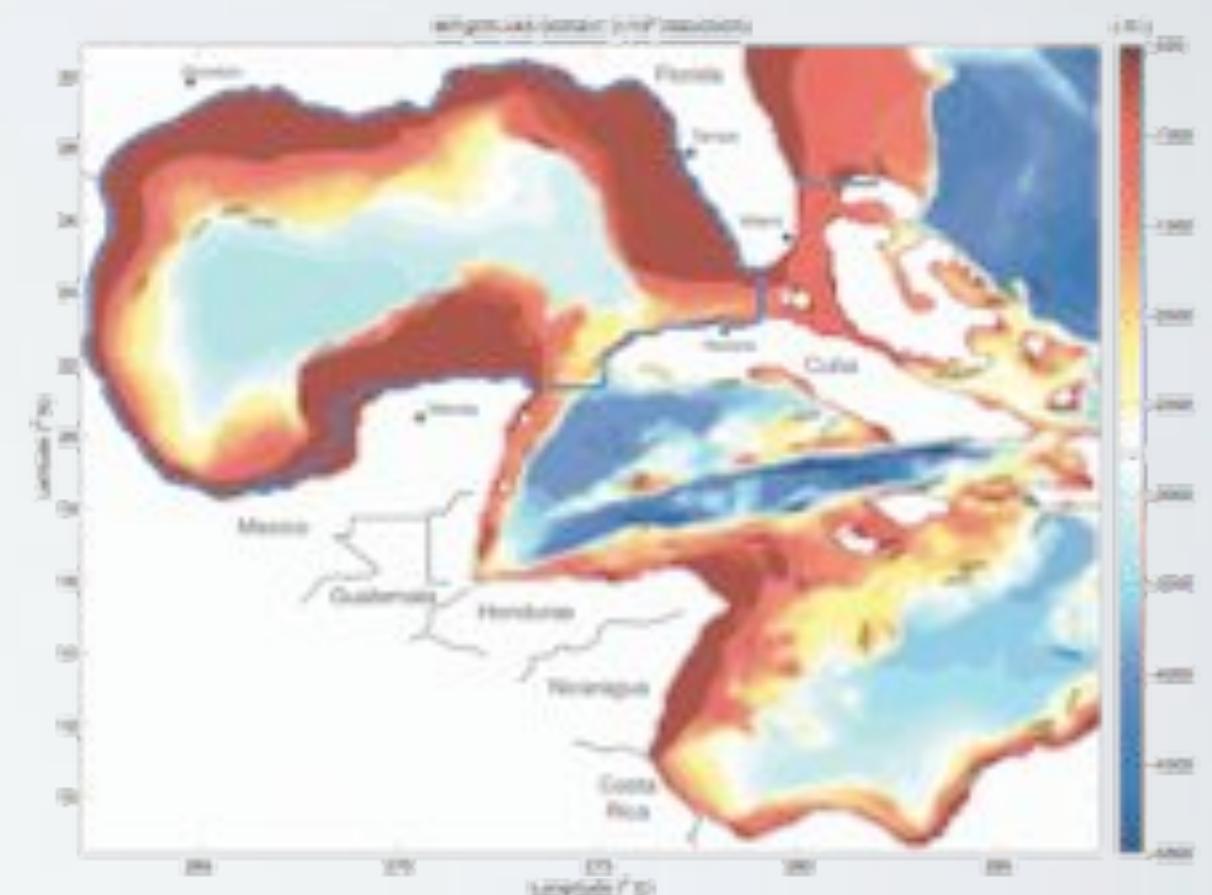


T. Höllt, A. Magdy, G. Chen, G. Gopalakrishnan, I. Hoteit, C.D. Hansen, and M. Hadwiger.  
**Visual Analysis of Uncertainties in Ocean Forecasts for Planning and Operation of Off-Shore Structures.**  
In *Proceedings of IEEE Pacific Visualization Symposium 2013*, pages 185–192, 2013.  
Honorable mention for best paper award.

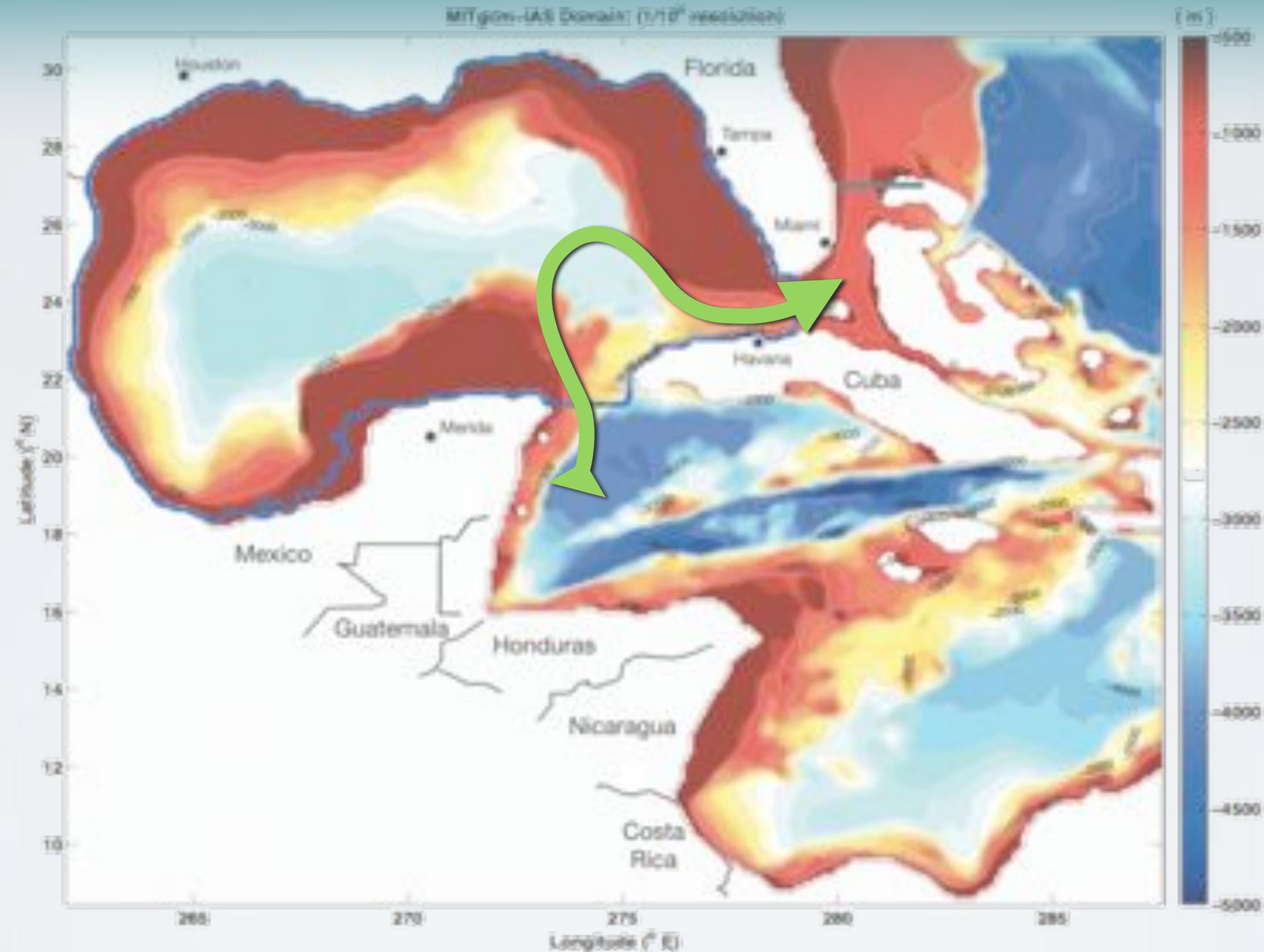


# Motivation

- Planning off-shore rig operation
  - off-shore oil exploration vulnerable to hazards



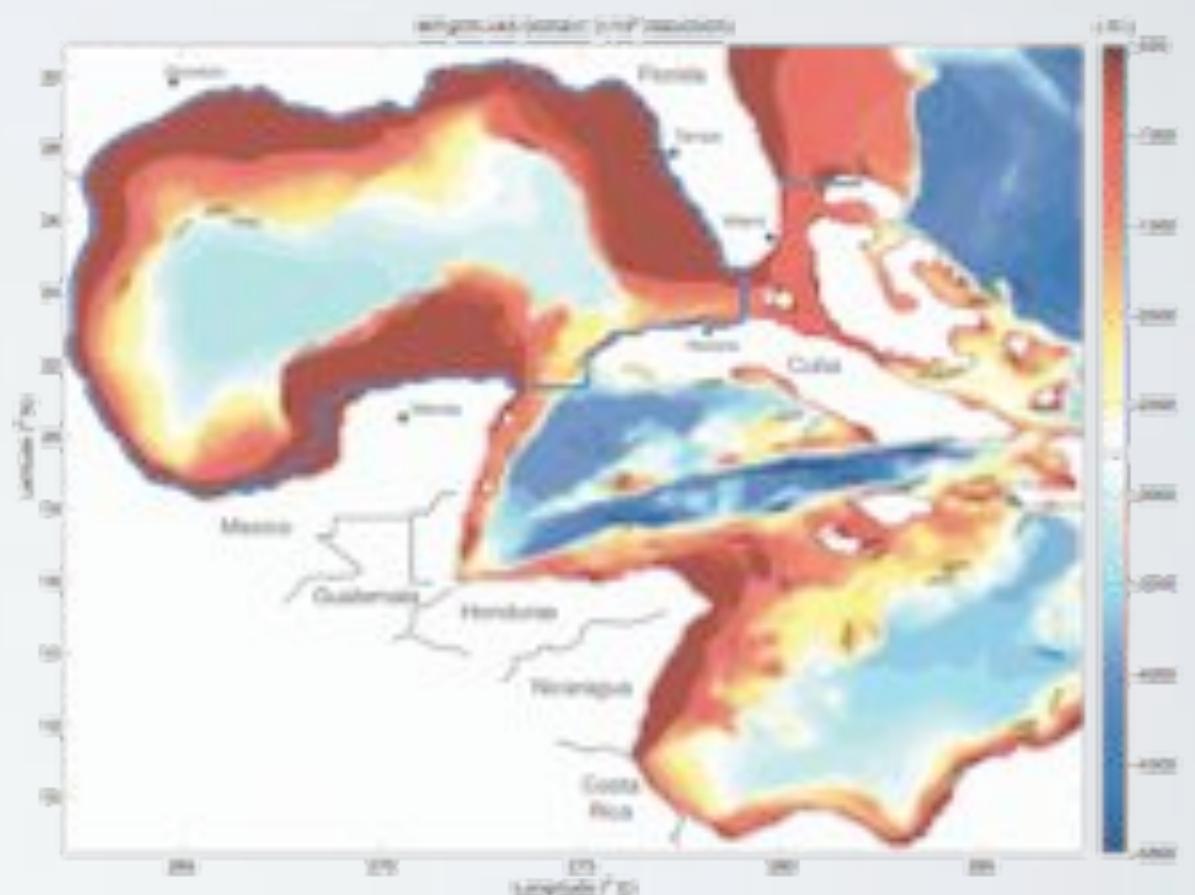
# Motivation // GoM Eddy Sheding





# Motivation

- Planning off-shore rig operation
  - off-shore oil exploration vulnerable to hazards
- ocean forecasts allow planning operation
- forecasts based on ensemble simulation





# Ensemble Forecasts

- Ensemble simulation
  - multiple simulation runs for the same event
  - maps model or starting condition uncertainty to variation in simulation results
- + allows more precise forecasts
  - results in large amount of data
  - hard to visualize

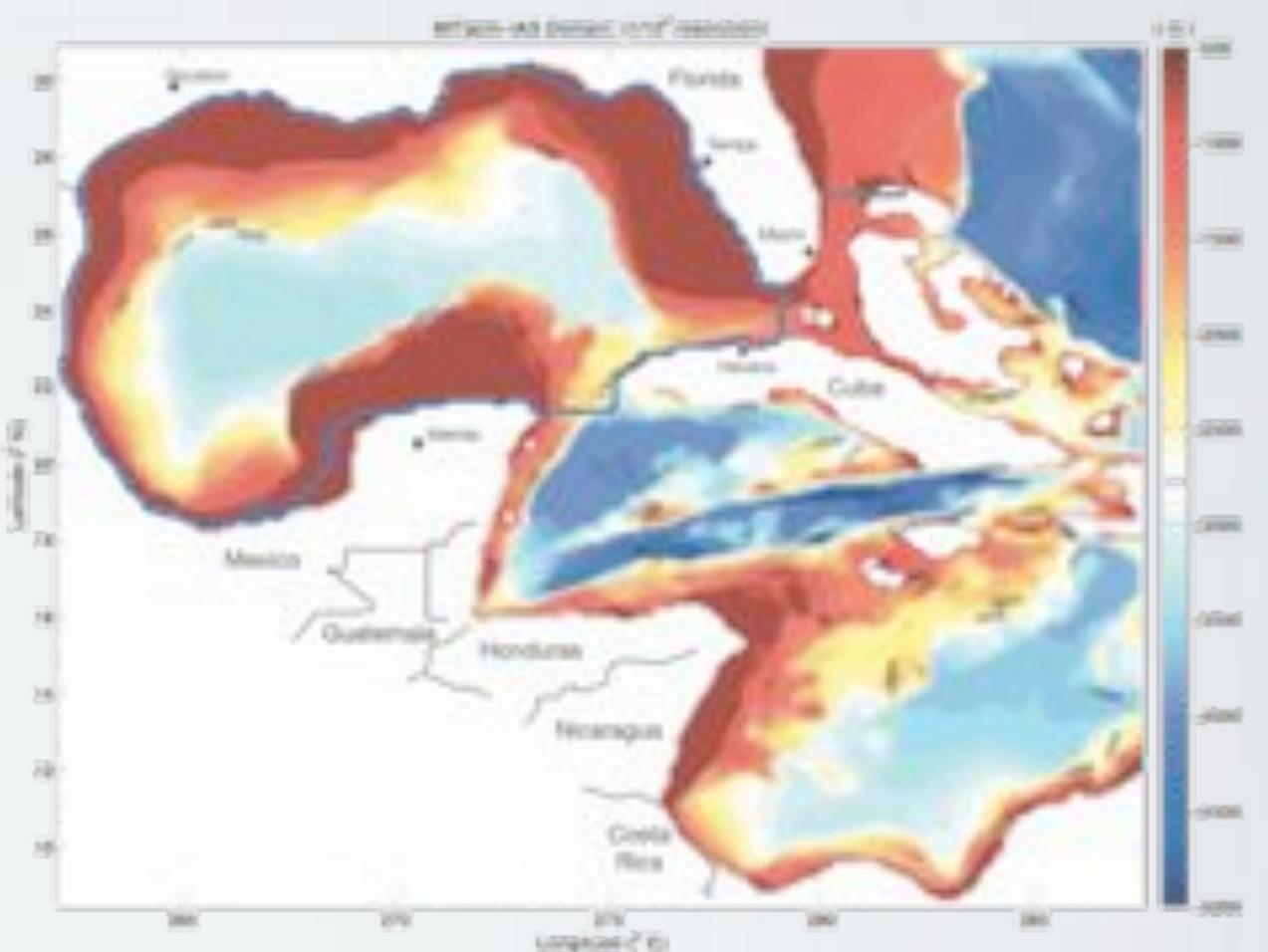


*"There is  
a 70% chance for  
rain tomorrow."*



# Input Data

- Sea surface simulation of the GoM
  - height fields / 2D functions
  - 1/10° grid of the GoM ↡ 275 x 325 samples
  - 10 time steps
  - 100 simulation runs each





# On the Fly Analysis

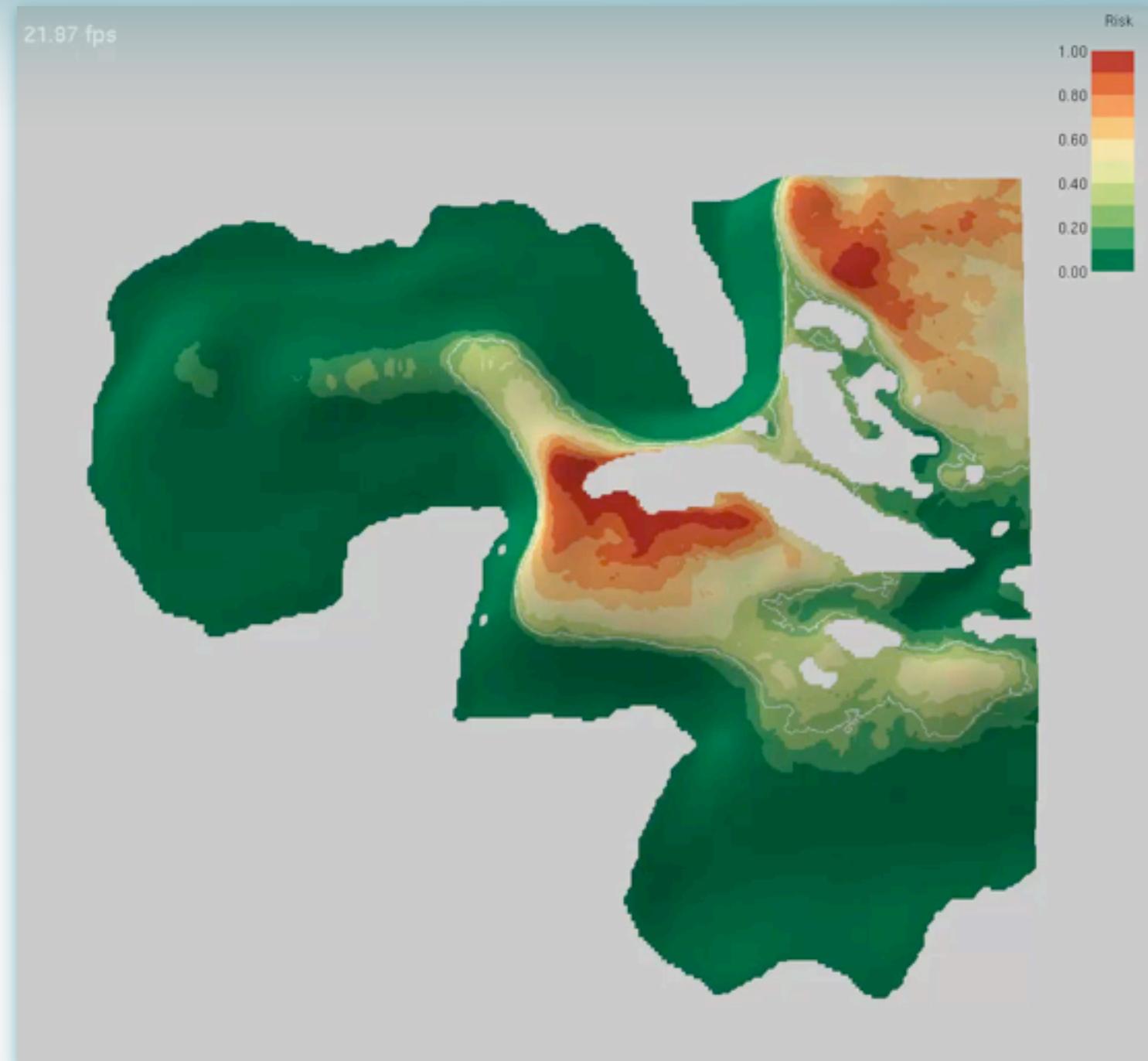
- Interactive parameter space exploration
  - statistics based on user defined ensemble subset
  - GPU-based computation
- Statistical analysis
  - histogram, pdf
  - mean, median, maximum mode ➔ surfaces
  - variance, kurtosis, risk estimate ... ➔ textures
- Iso Contouring





# Statistical Analysis // Risk

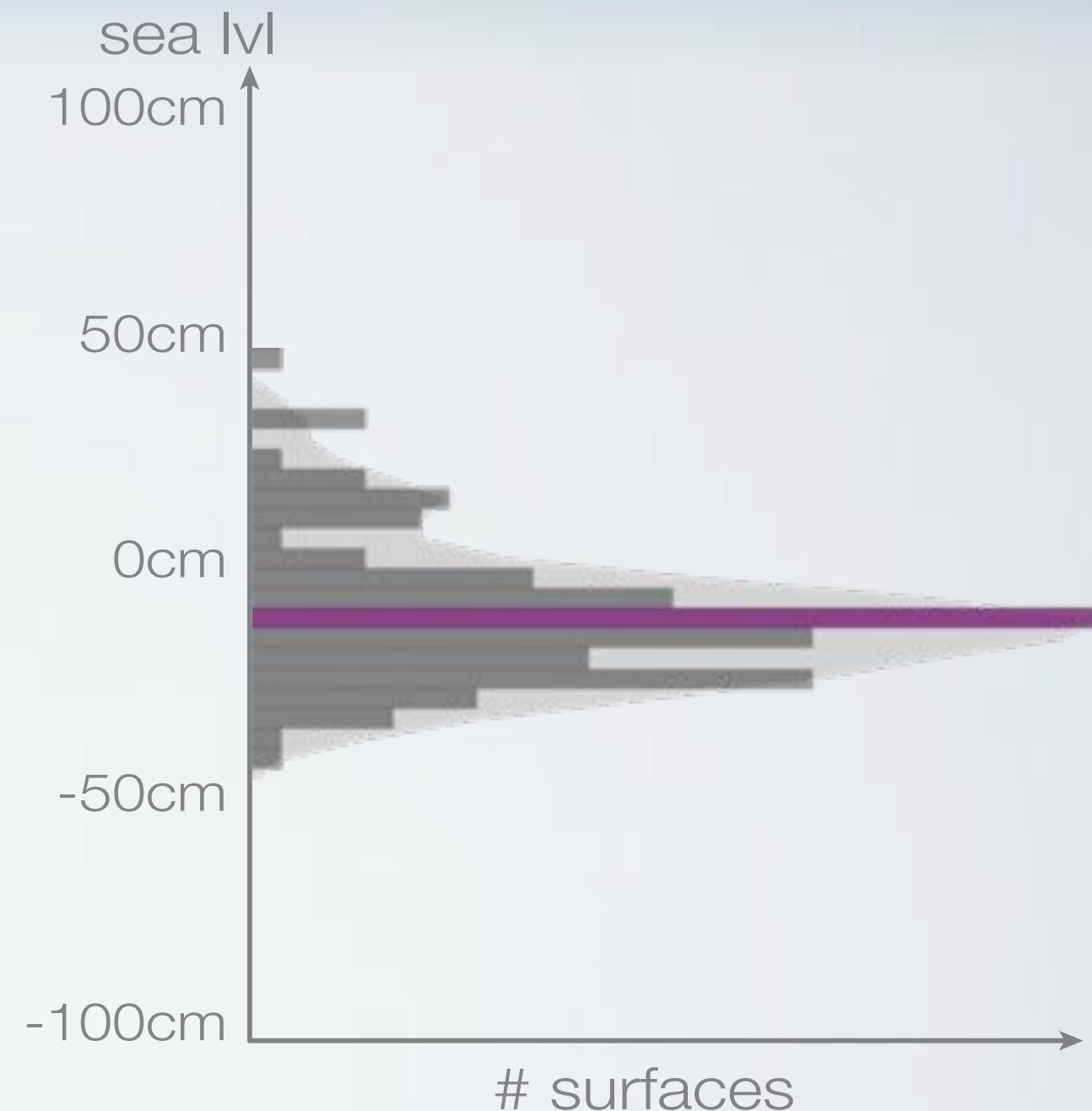
- Based on user defined critical sea-level
  - fraction of surfaces above critical value
- On the fly adjustment of sea-level
- Live parameter space exploration
- Iso contouring for precise area definition





# Statistical Analysis // 3D Histogram

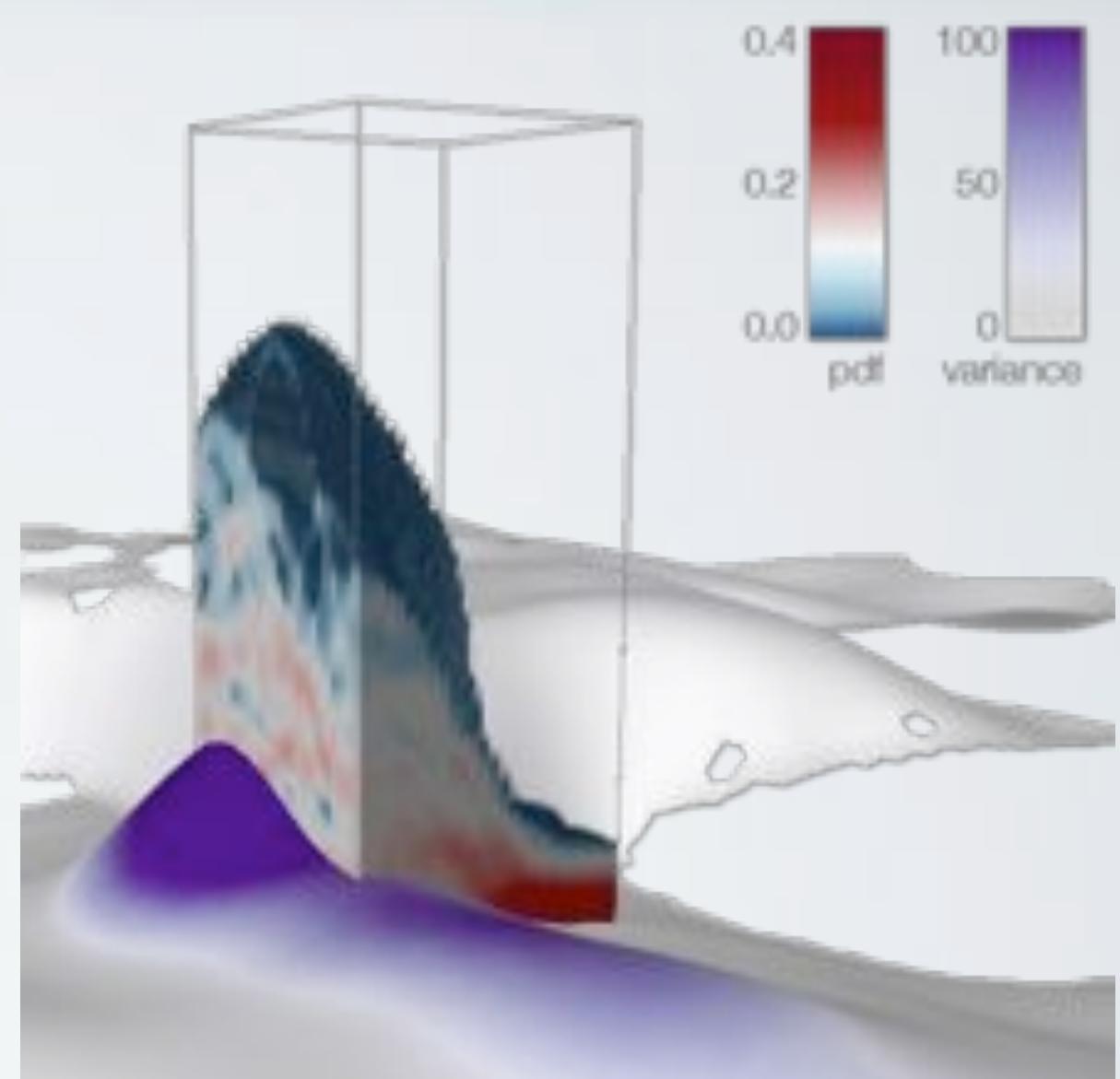
- Complete distribution for each x,y position
  - histogram + pdf
- 3D volumetric cursor
  - user adjustable size
  - avoids clutter of rendering complete volume





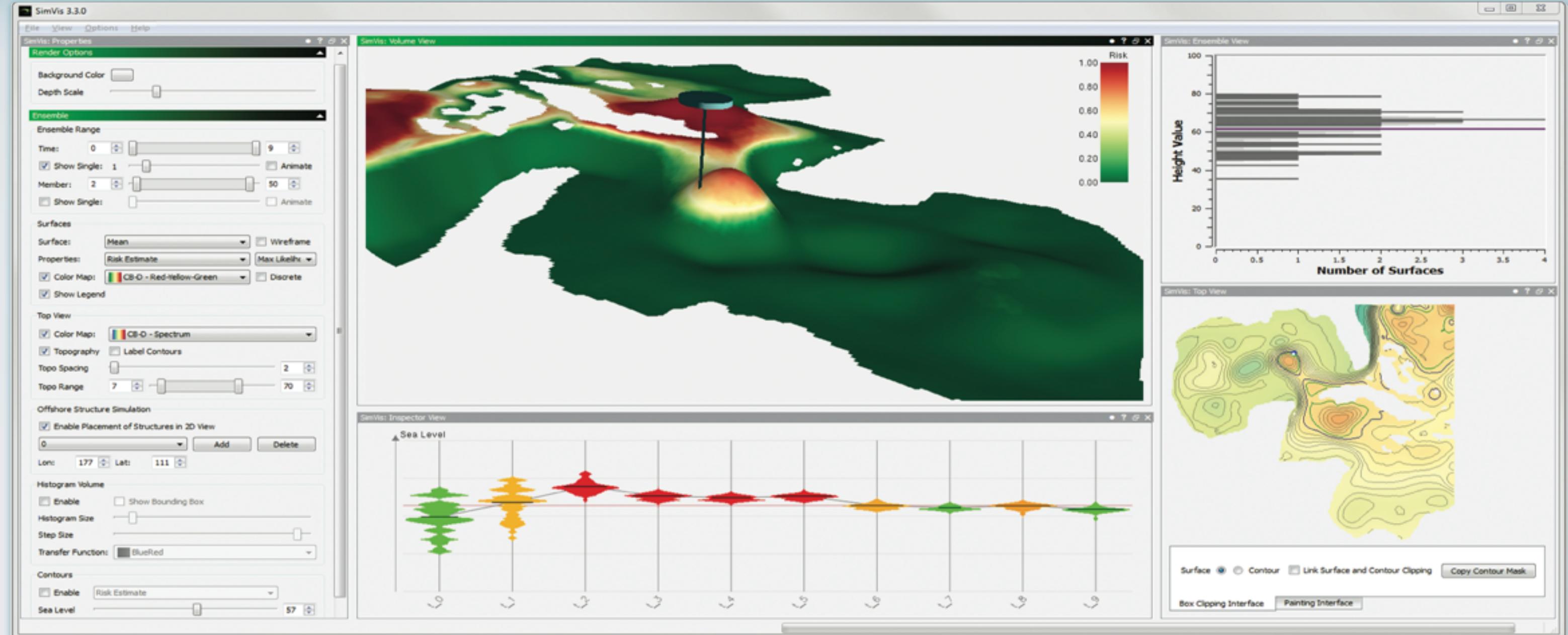
# Statistical Analysis // 3D Histogram

- Complete distribution for each x,y position
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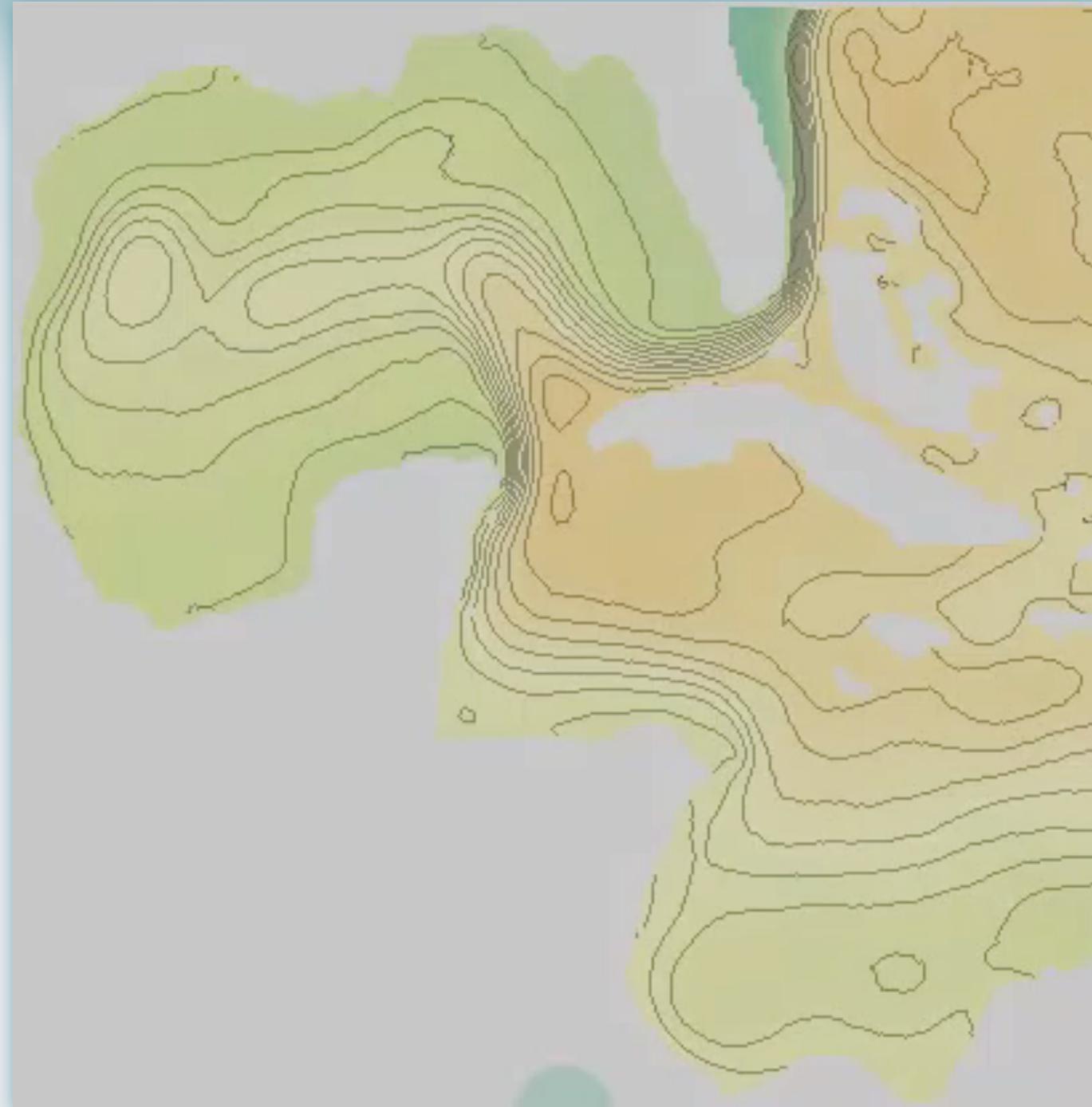




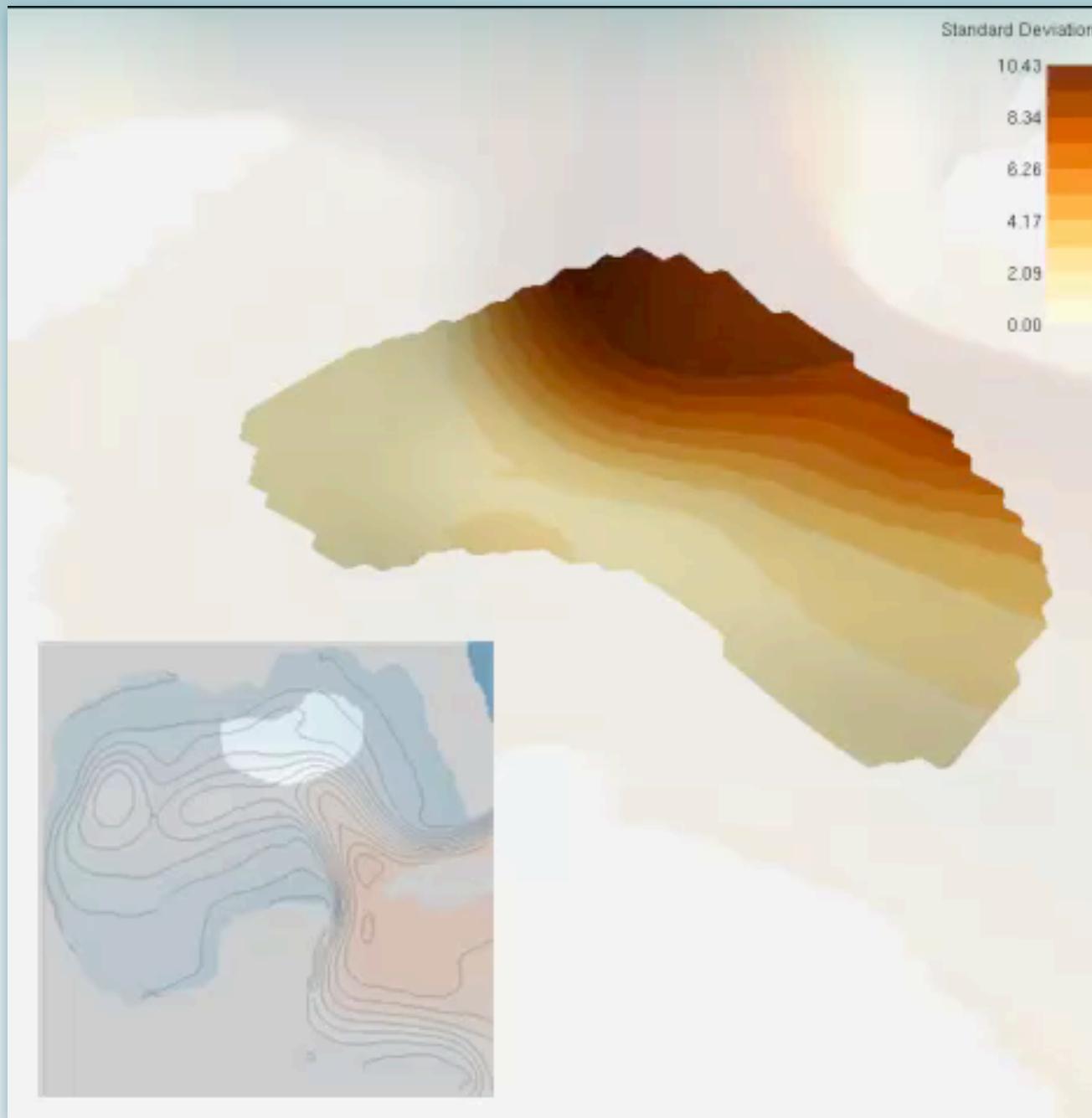
# Workflow I



# Workflow II

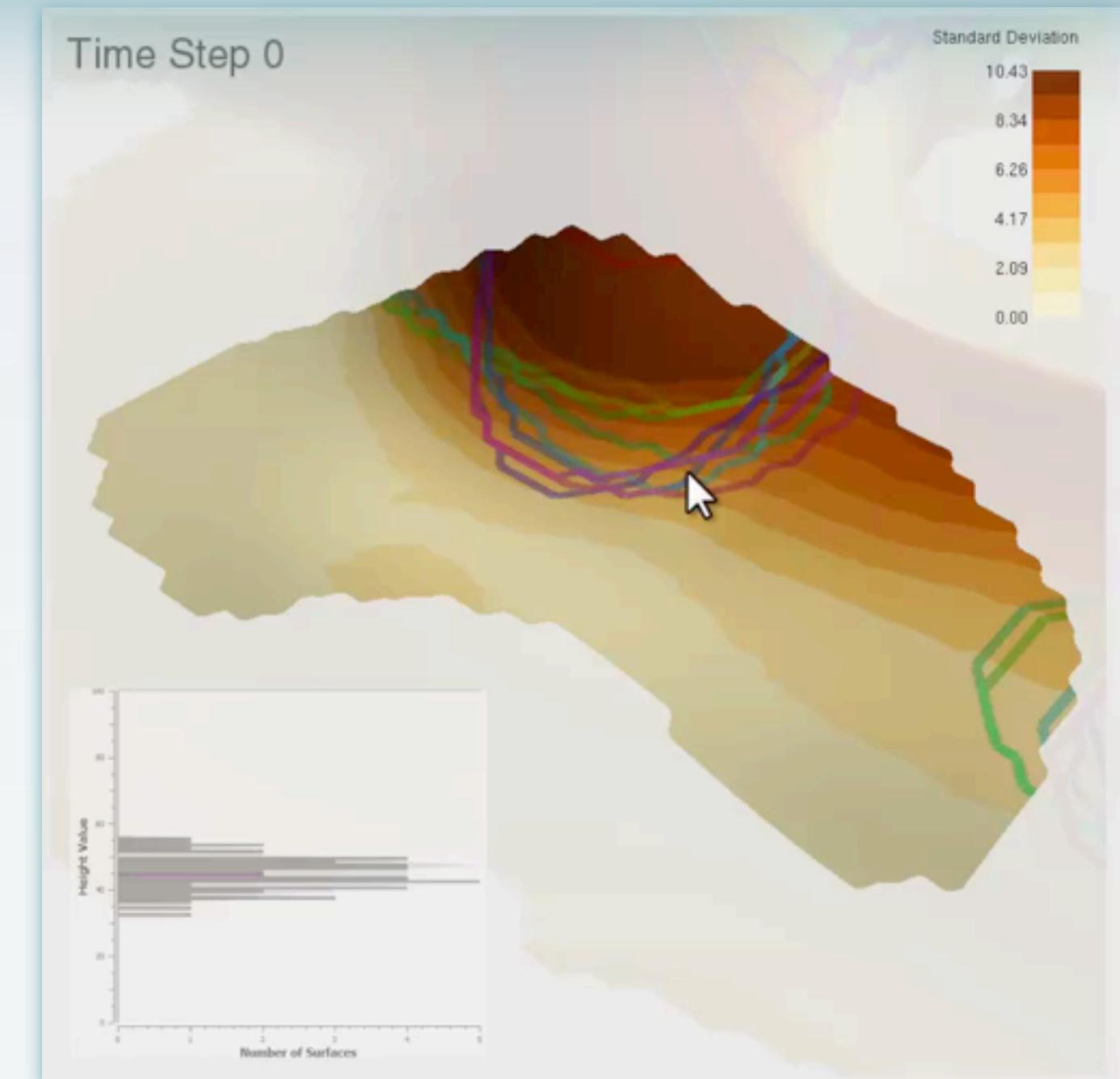


# Workflow III





# Workflow III





# Workflow IV

