

Completeness Thresholds for Memory Safety of Array Traversing Programs

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Workshop on the State Of the Art in Program Analysis
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What This Work Is About

- Connection between bounded & unbounded proofs
- Ideas to increase trust in bounded model checking

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- Connection between bounded & unbounded proofs
- Ideas to increase trust in bounded model checking
- When is a bounded “proof” a proof?

Model Checking: Easy Off-by-1 Error

- WHILE language with pointer arithmetic
- Targeted property: Memory safety
- Memory assumption `array(a, s)`:
`a[0] ... a[s-1]` allocated

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for i in [0 : s-1] do  
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for i in [0 : s-1] do  
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Which bounds should we choose for s ?

- $s = 0$: No error
- $s = 1$: Error

Model Checking: “Harder” Off-by-N Error

Memory assumption:
`array(a, s)`

```
for i in [0 : s-2] do  
  !a[i+2]
```

Which bounds should we choose for *s*?

Model Checking: “Harder” Off-by-N Error

Memory assumption:
`array(a, s)`

```
for i in [0 : s-2] do  
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```

Which bounds should we choose for s ?

- $s = 0$: No error
- $s = 1$: No error
- $s = 2$: Error

Model Checking: No Off-by-N Error

Memory assumption:
`array(a, s)`

```
for i in [0 : s-1] do  
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```

Which *s* can convince us?

Model Checking: No Off-by-N Error

Memory assumption:
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for i in [0 : s-1] do  
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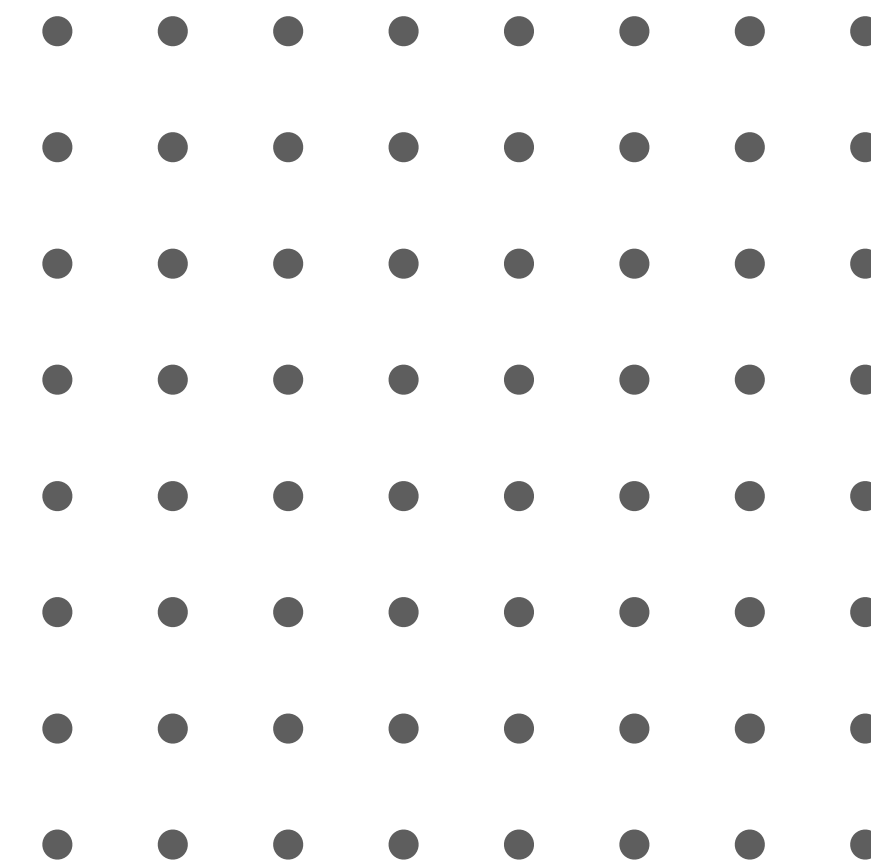
Which s can convince us?

- $s = 0$: No error
- $s = 1$: No error
- $s = 2$: No error
- $s = 3$: No error
- \vdots

\Rightarrow Which size bound is large enough?

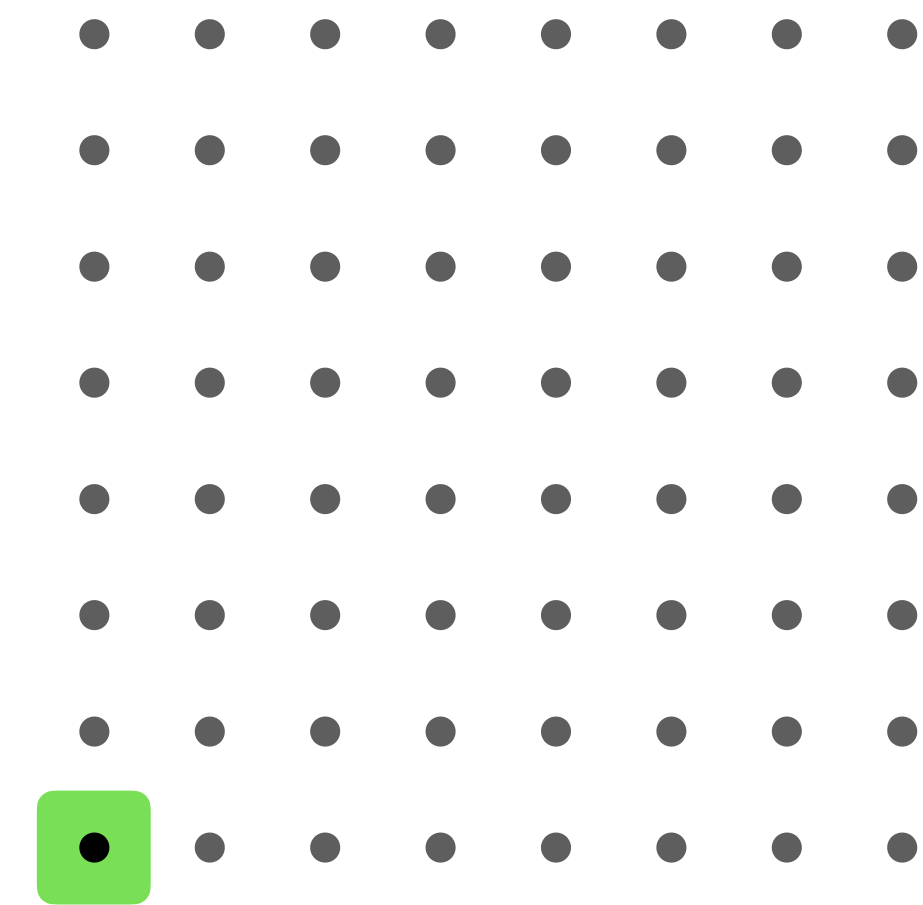
Model Checking Finite Systems

- Finite state transition system T
- Prove property Gp
 $G \approx$ globally $\approx p$ holds in every state
- Approach:
Prove Gp for all paths up to length k
 $T \vDash_k Gp$



Model Checking Finite Systems

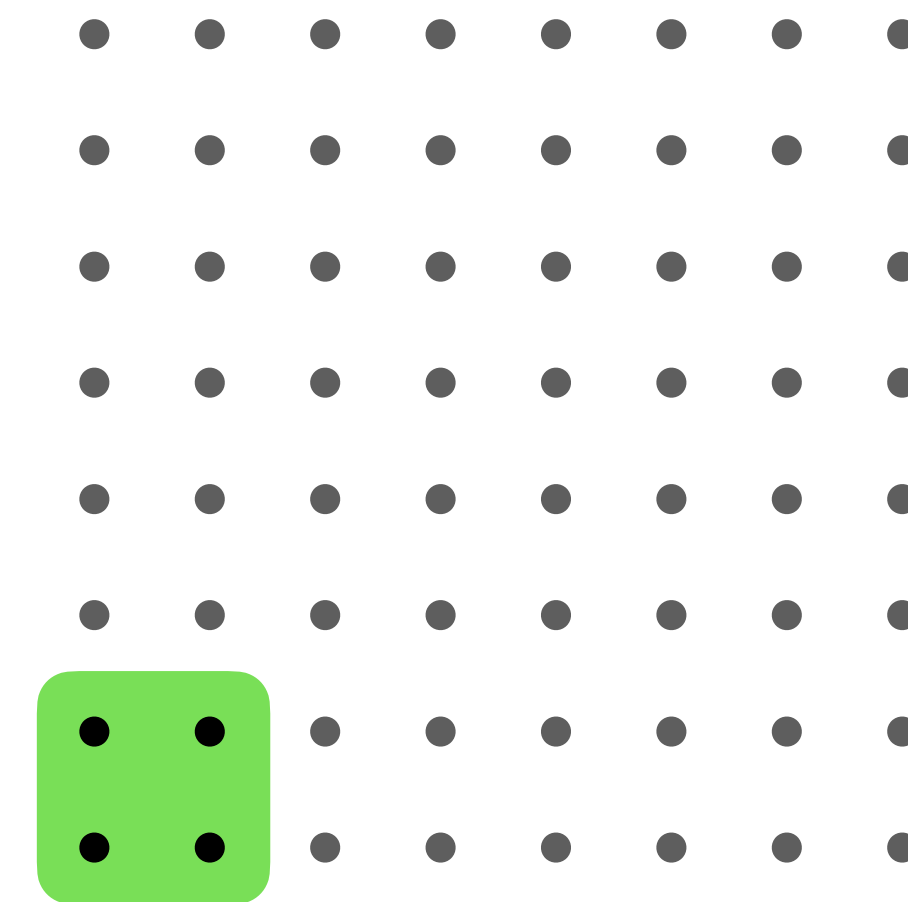
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$T \models_0 Gp$

Model Checking Finite Systems

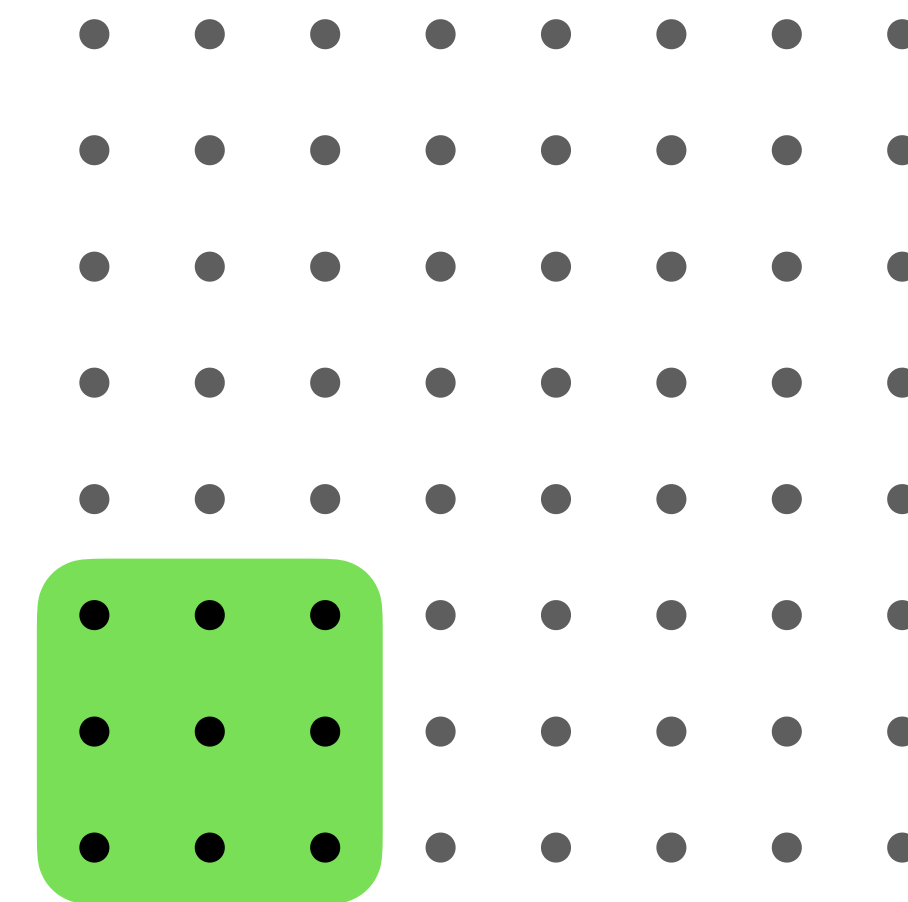
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$$T \models_1 Gp$$

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$$T \models_2 Gp$$

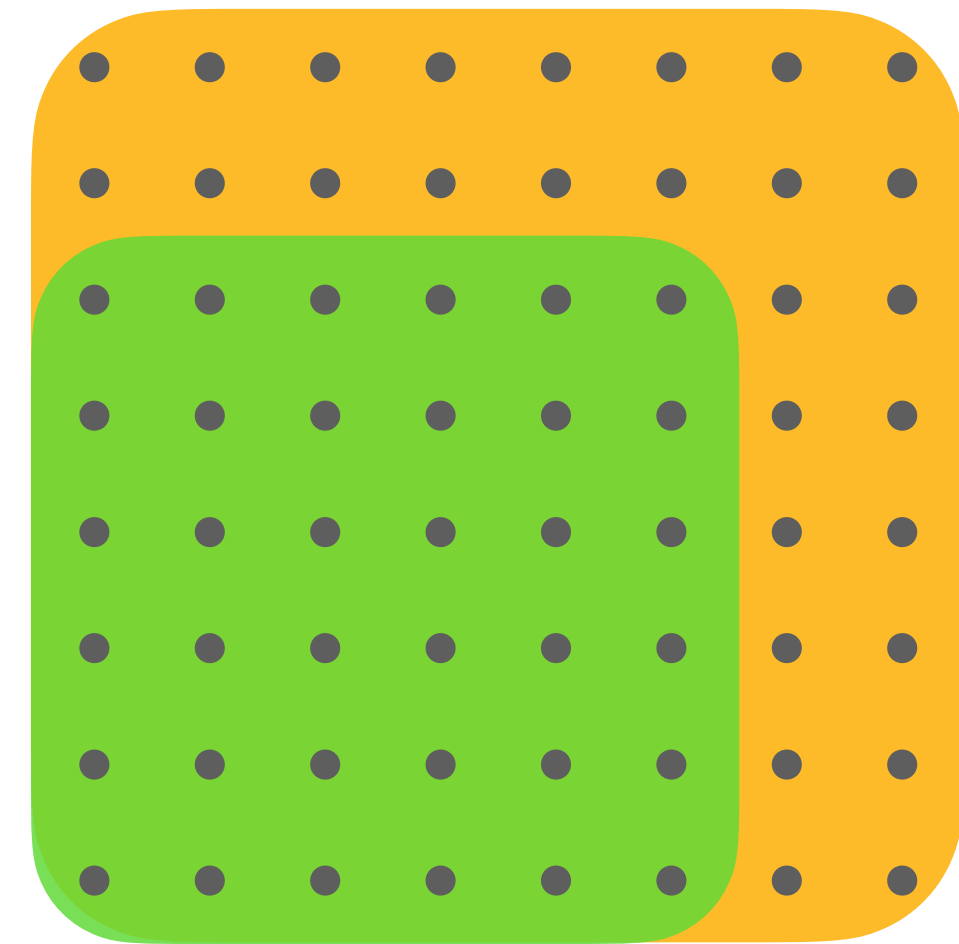
When should we stop?

Completeness Thresholds for Finite Systems

- k is completeness thresholds (CT) iff

$$T \vDash_k \phi \Rightarrow T \vDash \phi$$

- For specific ϕ :
Can over-approximate CT via of key props of T



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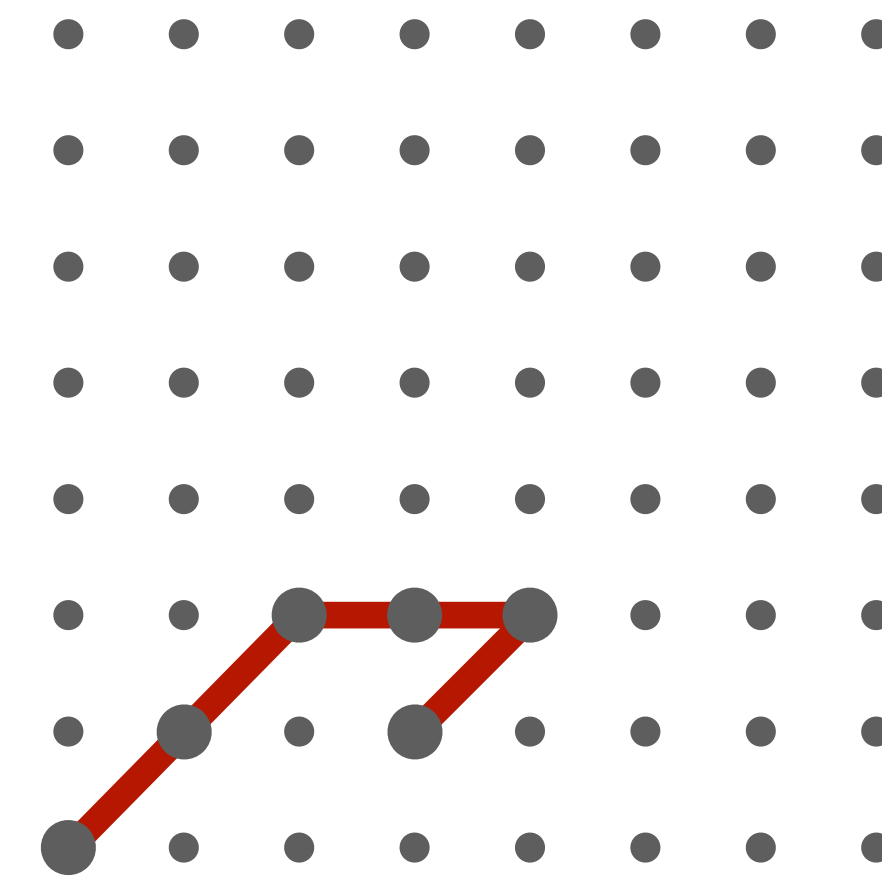
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- For $\phi = Gp$ we know

$$CT(T, Gp) = \text{diameter}(T)$$

(longest distance between any states)



$$\text{diameter}(T) = 5$$

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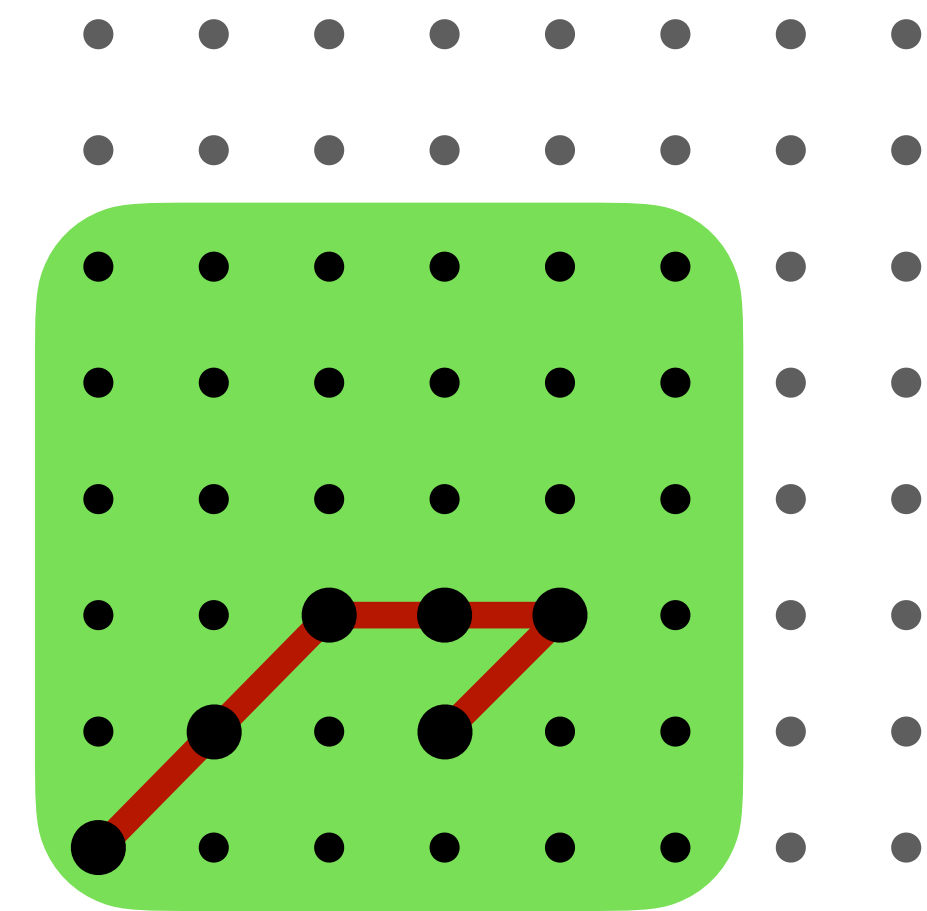
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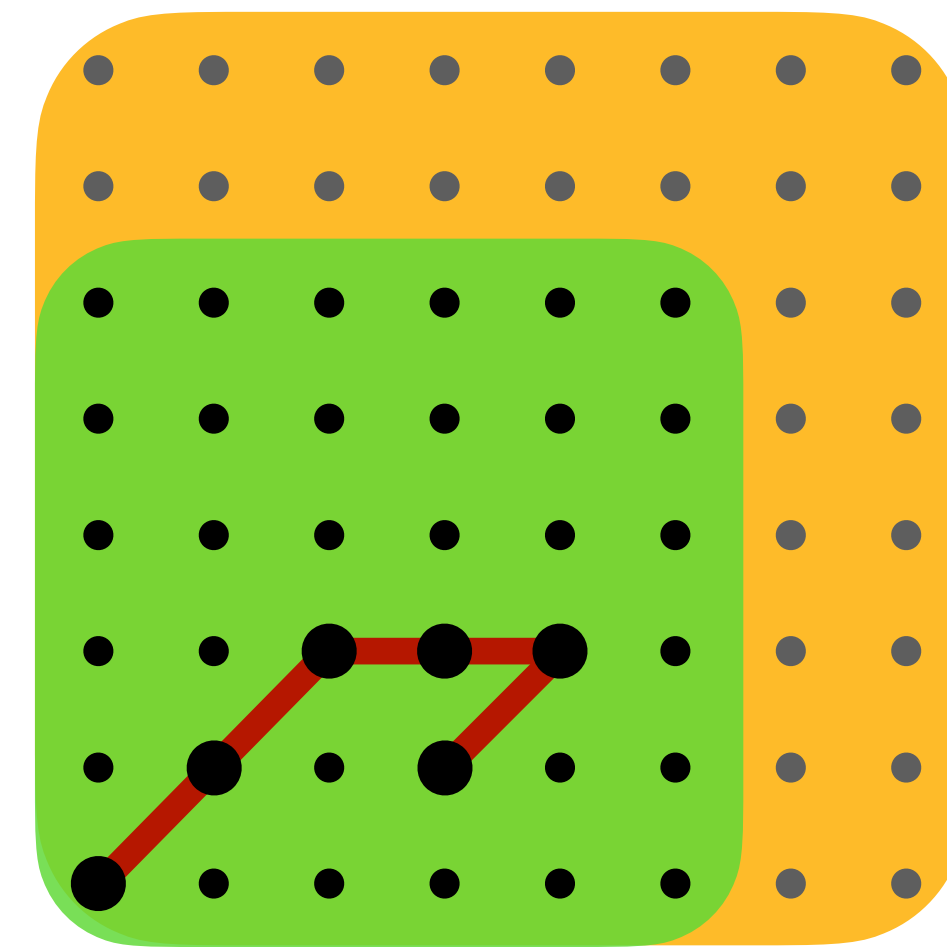
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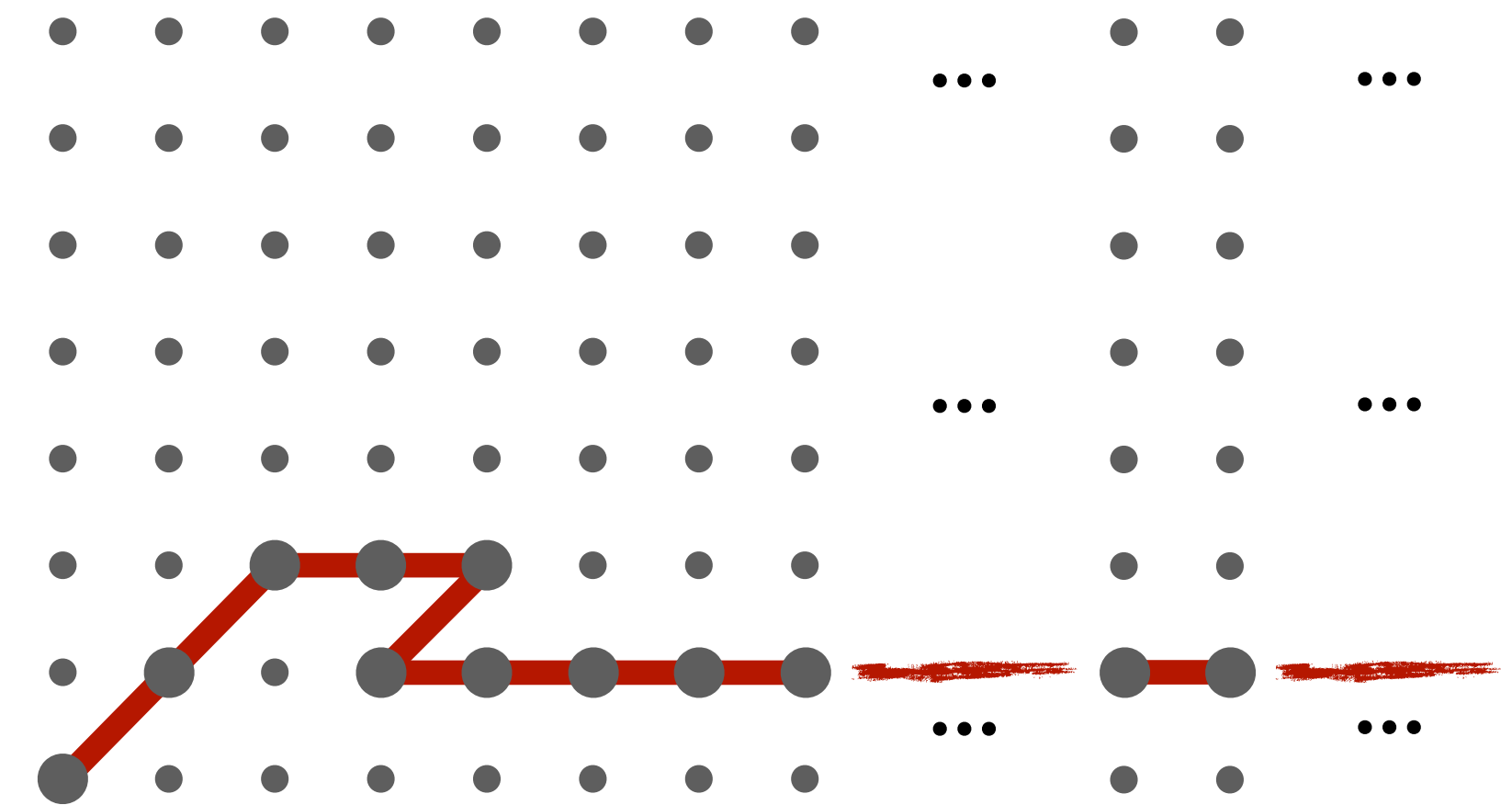


$$T \vDash Gp$$

CTs for Infinite Systems?

Problem

Key properties used to describe CTs may be ∞



$$\text{diameter}(T) = \infty$$

CTs for Infinite Systems?

Problem

Key properties used to describe CTs may be ∞

Our Approach

Analyse program's *verification conditions*
instead of transition system

Verification Conditions

- Logical formula vc is VC for any spec $Spec(c)$ iff

$$\models vc \Rightarrow \models Spec(c)$$

- Can verify VC instead of program
- In general: VCs are over-approximations, i.e., possible that $\not\models vc$ but $\models Spec(c)$

Completeness Thresholds

- Program variable x with domain X
- Specification $\forall x \in X. Spec(c)$

Completeness Thresholds

- Program variable x with domain X
- Specification $\forall x \in X. Spec(c)$
- Subdomain $Q \subseteq X$ is a CT for x in $\forall x \in X. Spec(c)$ iff
$$\vDash \forall x \in Q. Spec(c) \quad \Rightarrow \quad \vDash \forall x \in X. Spec(c)$$
- For us: CT are subdomains, not depths

How to Prove CTs

- Generate VC: $Spec(c) \rightsquigarrow \forall x \in X. vc(x)$

How to Prove CTs

- Generate VC: $Spec(c) \rightsquigarrow \forall x \in X. vc(x)$
- Identify subdomain $Y \subseteq X$ where choice $x \in Y$ does not influence validity of $vc(x)$

$$\left(\models vc(x) \iff \models vc' \text{ with } x \notin \text{free}(vc') \right)$$

\implies Found CT: $(X \setminus Y) \cup \{y\}$ (for any choice of $y \in Y$)

How Does the Array Size Affect Memory Safety?

Memory assumption:
`array(a, s)`

for *i* in [*L* : *s*-*R*] do
 !`a[i+Z]`

How Does the Array Size Affect Memory Safety?

Memory assumption:

$\text{array}(a, s)$

for i in $[L : s-R]$ do

$!a[i+Z]$

Generate VC

(fully automated)

VC $vc_0 := \forall s. \text{array}(a, s) \rightarrow \forall i \in \{L, \dots, s-R\}. a[i+Z] \text{ alloc}$

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Range $L, \dots, s-R$ empty?

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Range $L, \dots, s-R$ empty?

Yes

$$s^- < L + R$$

Simplify VC!

$$\begin{aligned} vc_0 &\equiv \forall s^-. \dots \rightarrow \forall i \in \emptyset. \dots \\ &\equiv \text{True} \end{aligned}$$

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No need to check

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Simplify VC!

No

$$s^+ \geq L + R$$

$$vc_0 \equiv \forall i. (L \leq i < s^+ - R) \rightarrow (0 \leq i+Z < s^+)$$

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$$\begin{aligned} vc_0 &\equiv \forall i. (L \leq i < \cancel{s^+} - R) \rightarrow (0 \leq i+Z < \cancel{s^+}) \\ &\equiv \forall i. (L \leq i \rightarrow 0 \leq i+Z) \\ &\quad \wedge (i \leq -R) \rightarrow i+Z < 0) \end{aligned}$$

\Rightarrow Validity does not depend on size

How Does the Array Size Affect Memory Safety?

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No need to check

No

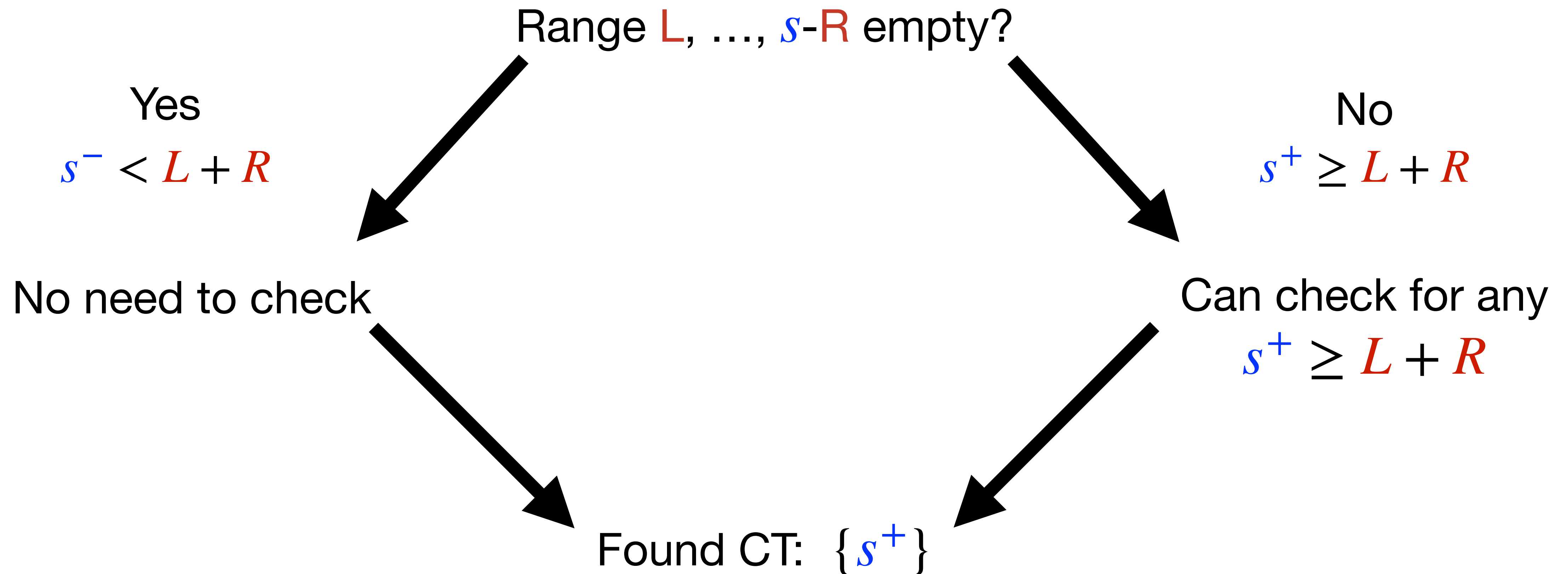
$$s^+ \geq L + R$$

Can check for any

$$s^+ \geq L + R$$

How Does the Array Size Affect Memory Safety?

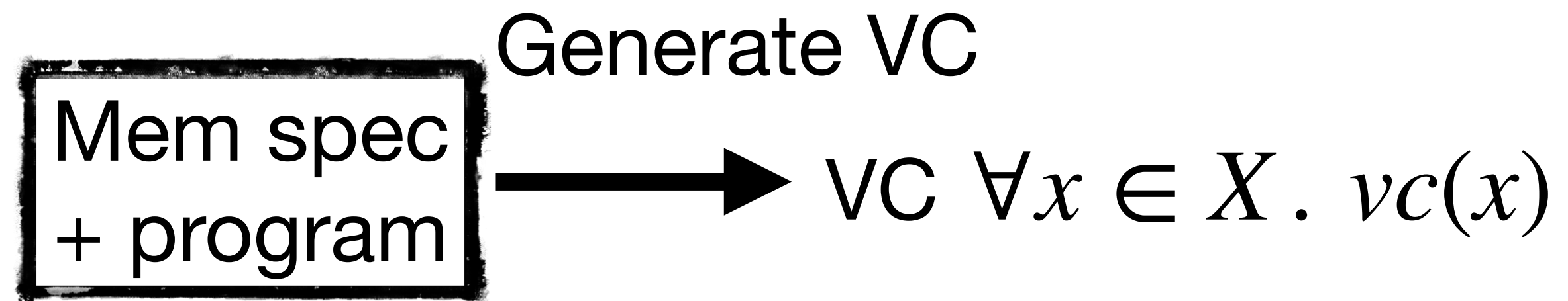
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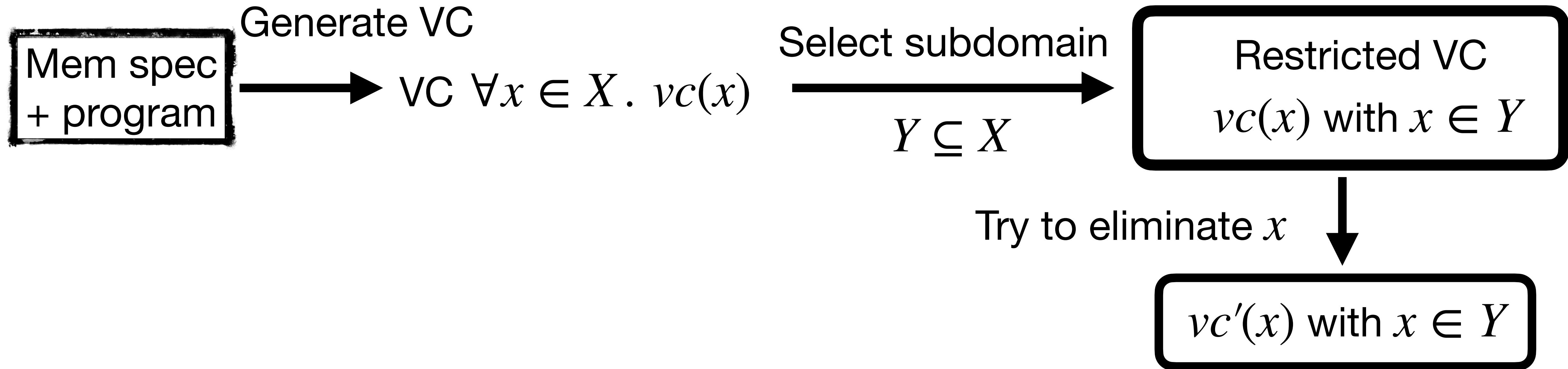
Workflow: How to Find CTs

Mem spec
+ program

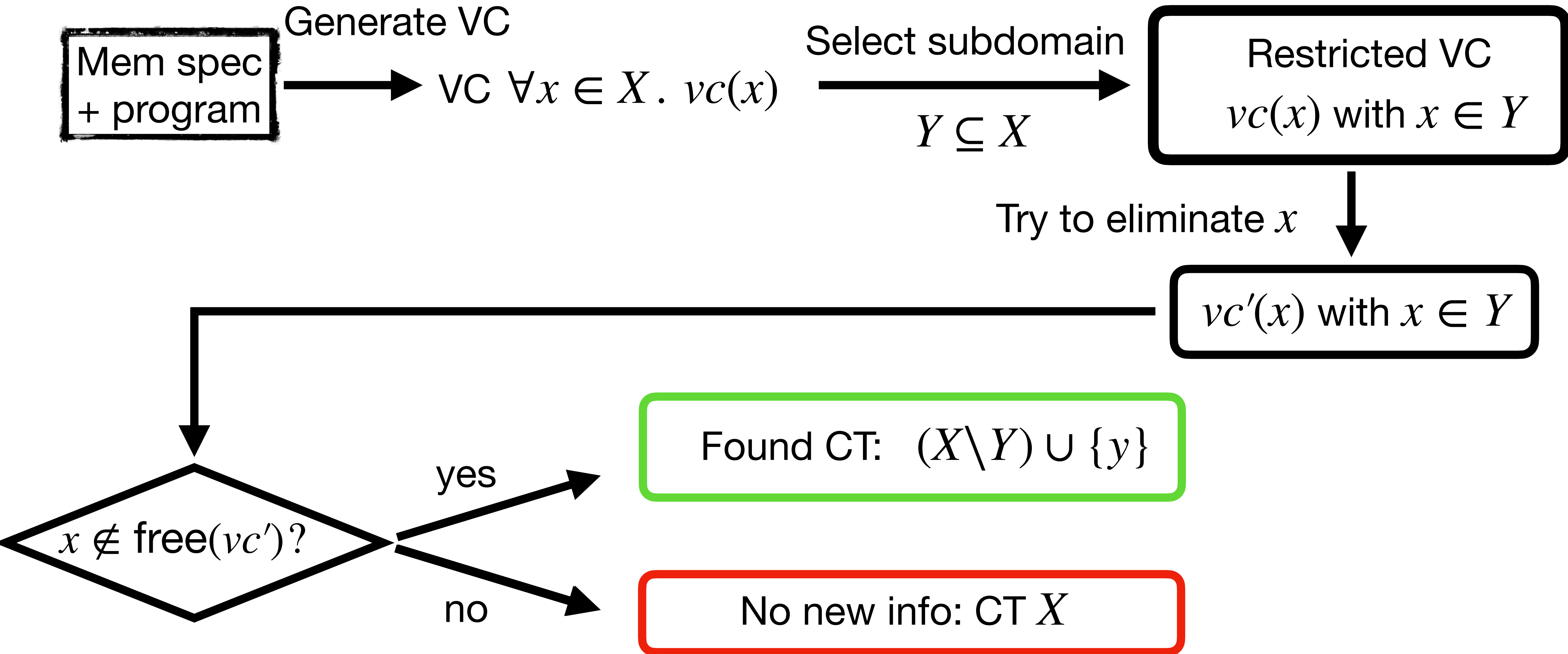
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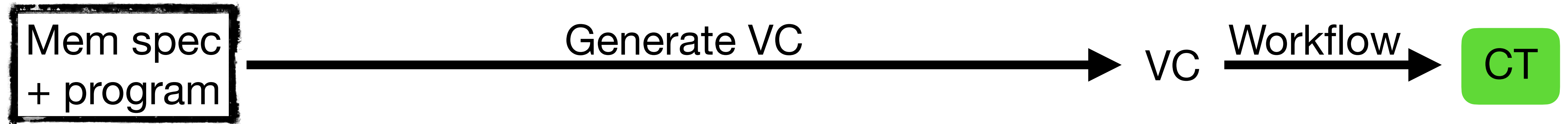


Workflow: How to Find CTs



Scalability

Program Slicing



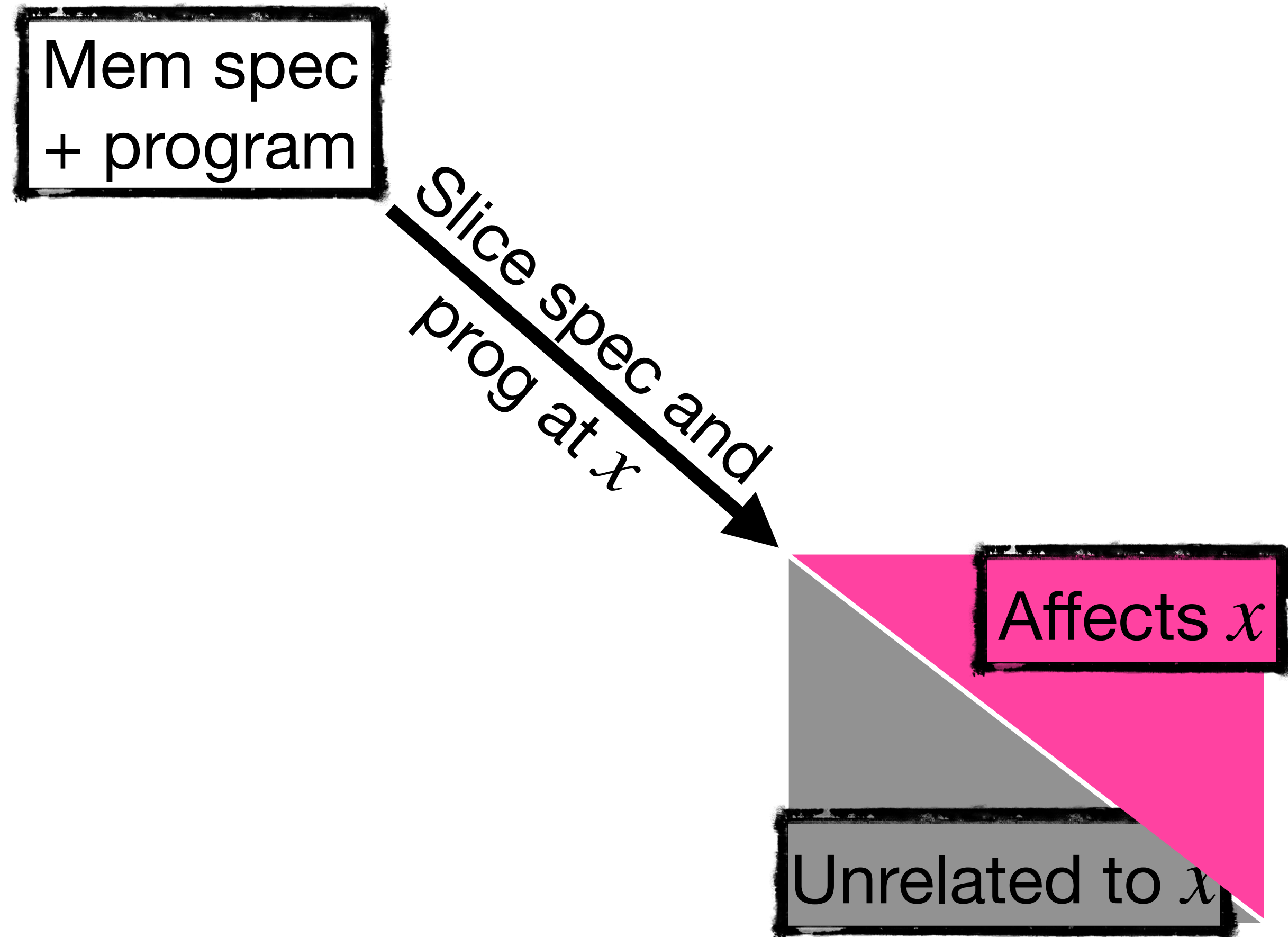
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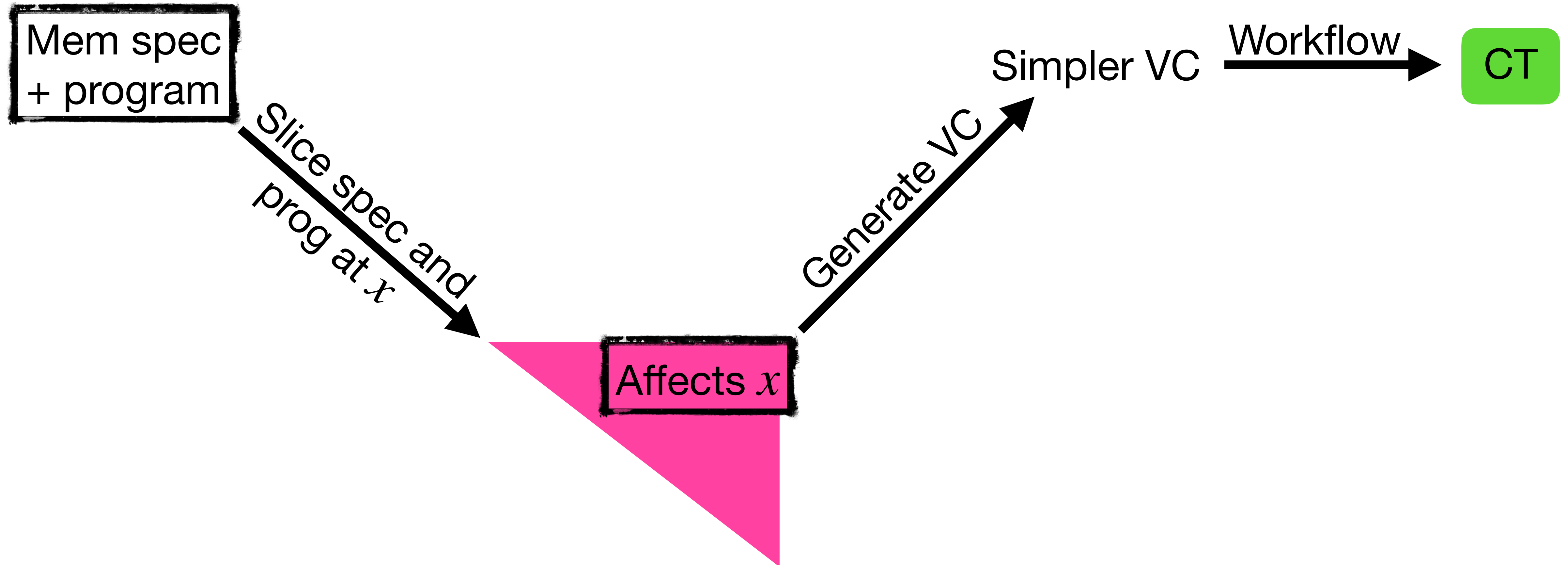
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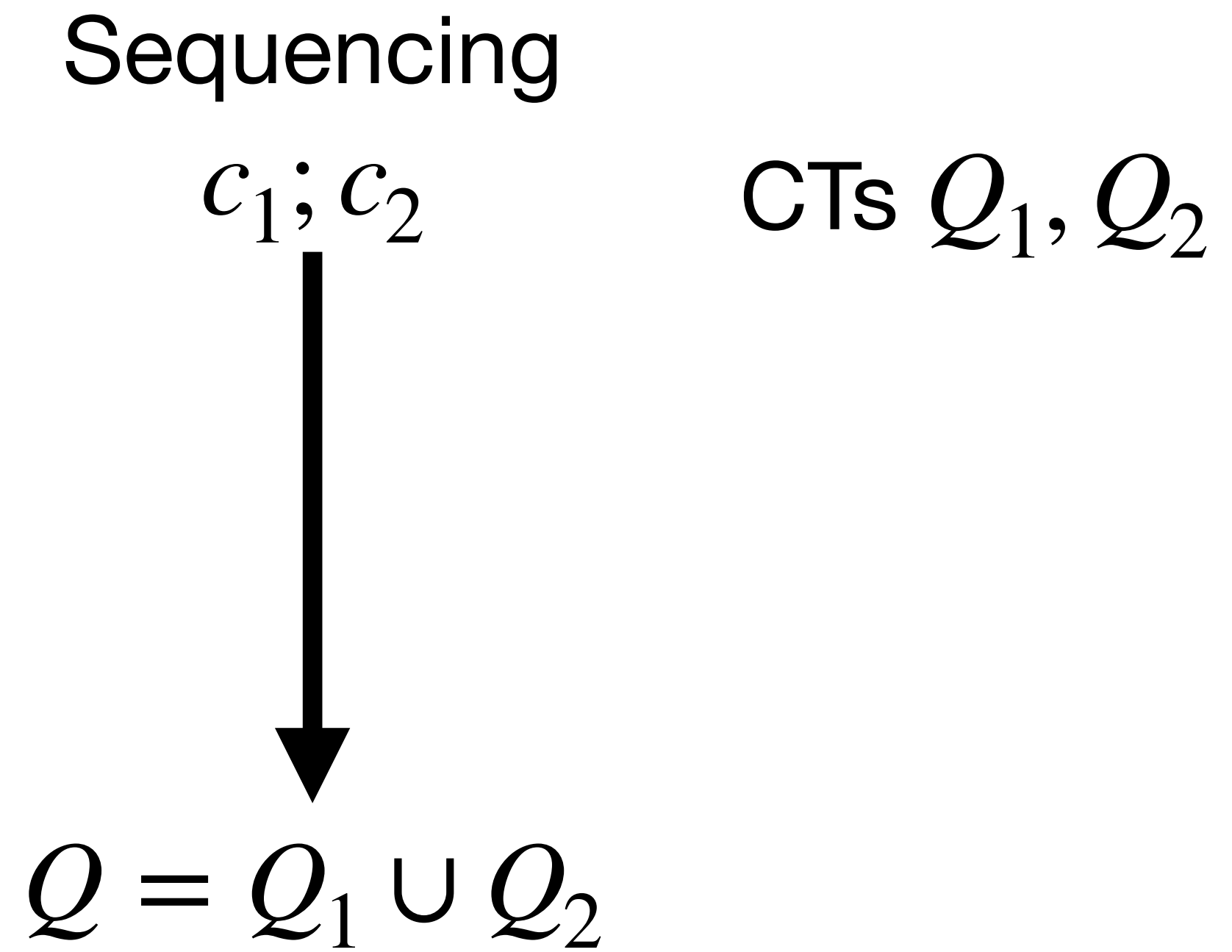
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Scalability

CT Combinators

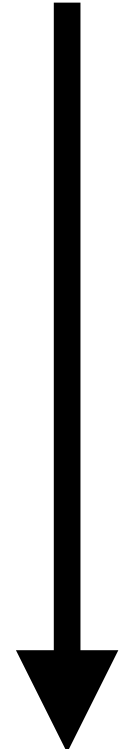


Scalability

CT Combinators

Sequencing

$c_1; c_2$



$$Q = Q_1 \cup Q_2$$

CTs Q_1, Q_2

Branching

if e then c_1 else c_2



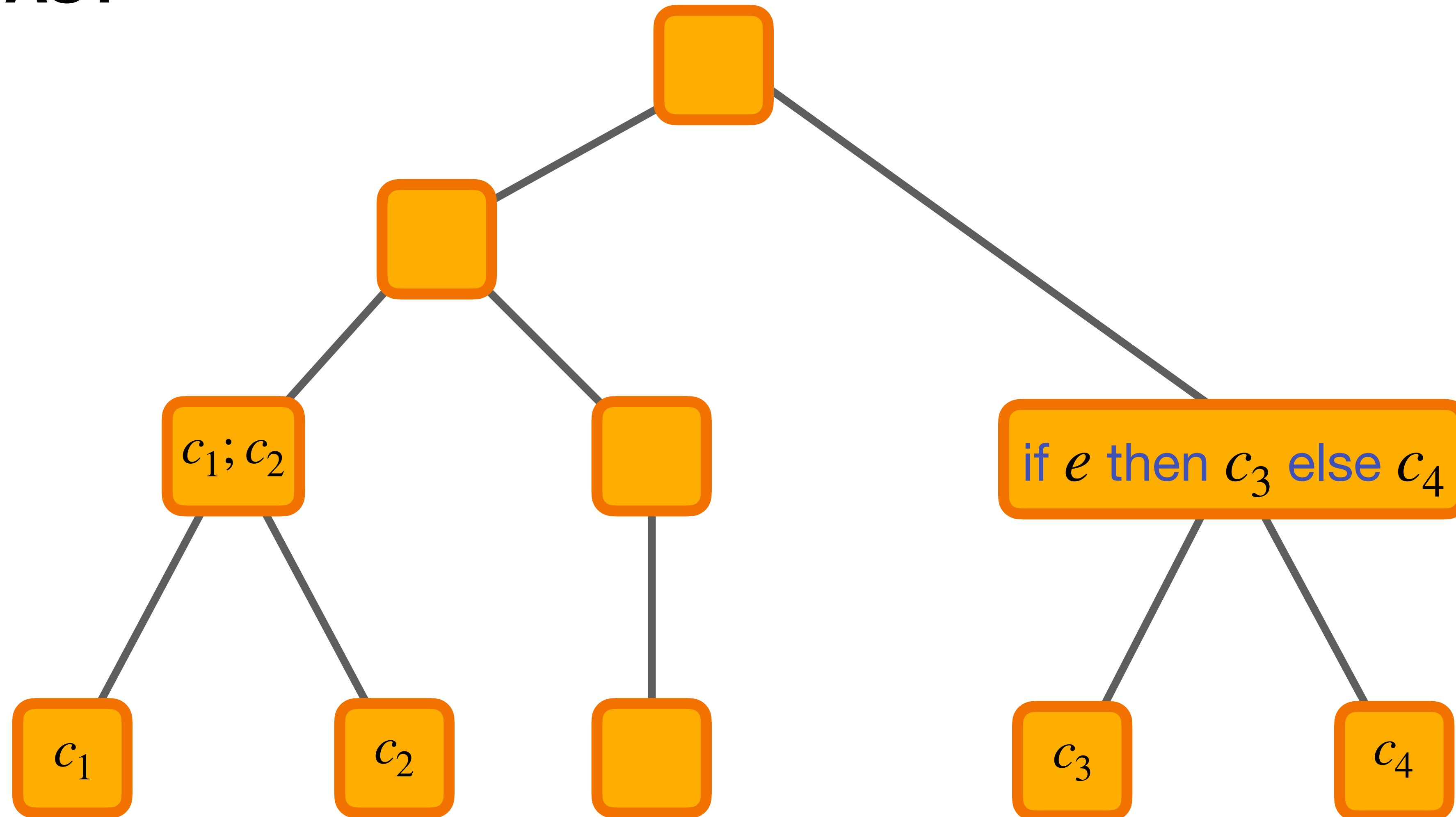
$$Q \sim (e \wedge K_1) \vee (\neg e \wedge K_2)$$

CTs as constraints

$$Q_i \sim K_i$$

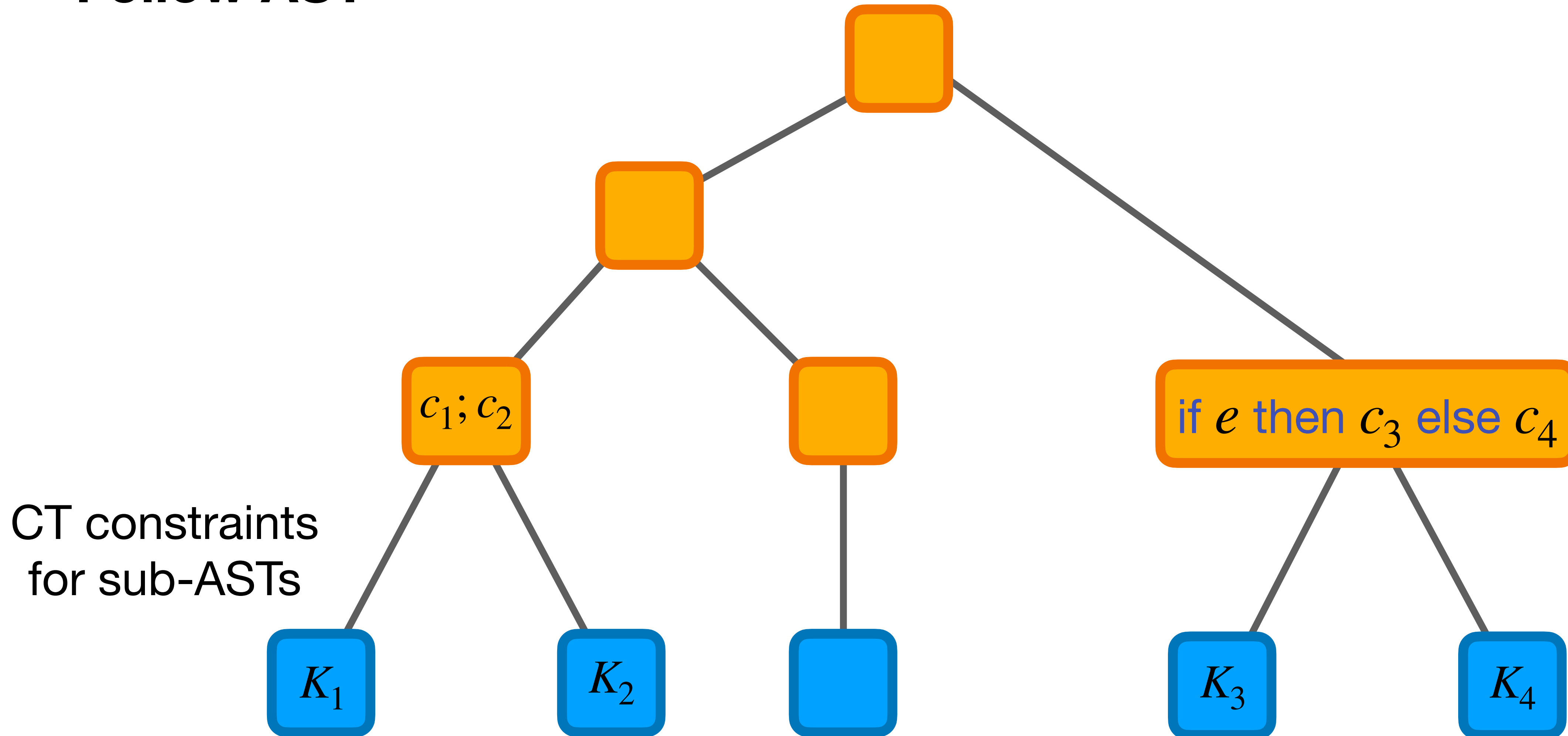
Scalability

Follow AST



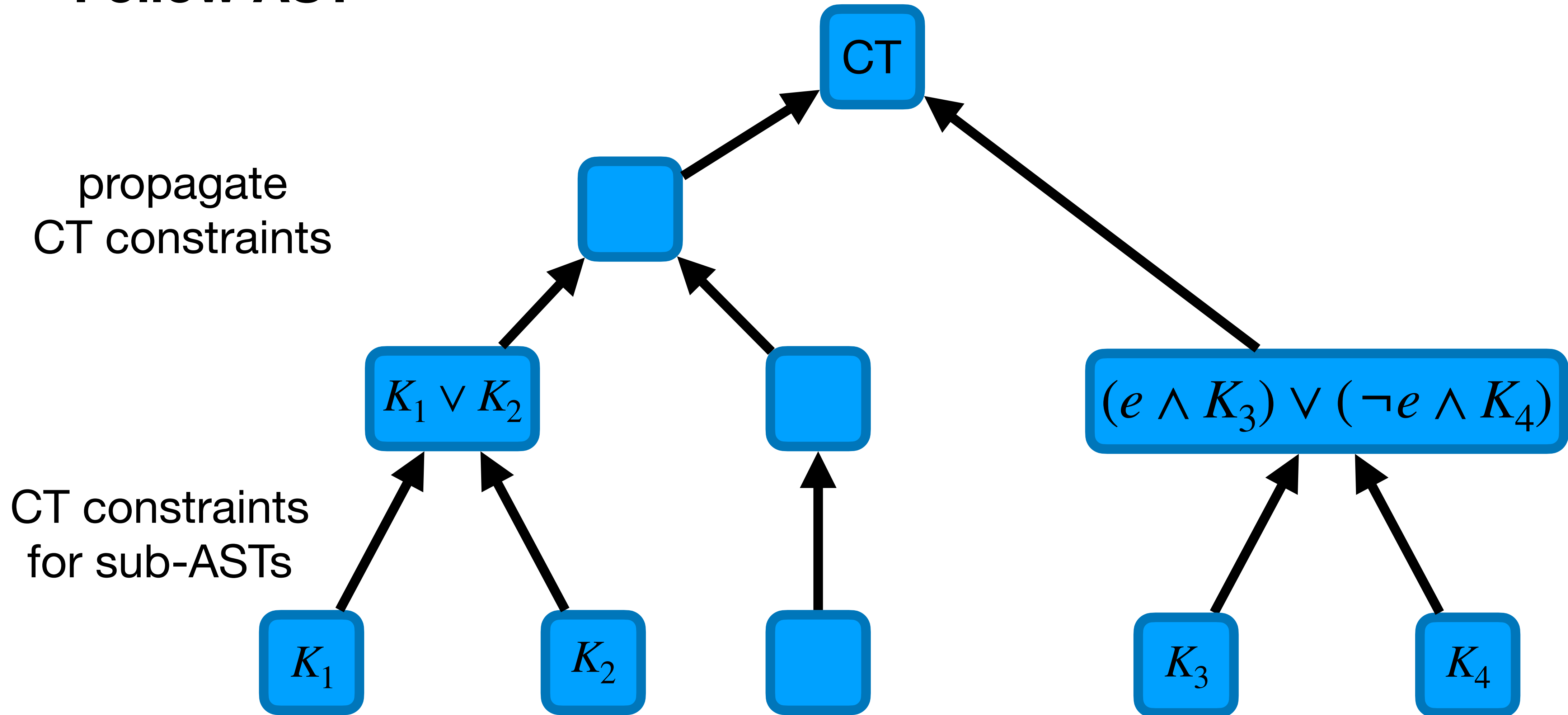
Scalability

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Outlook: Challenges

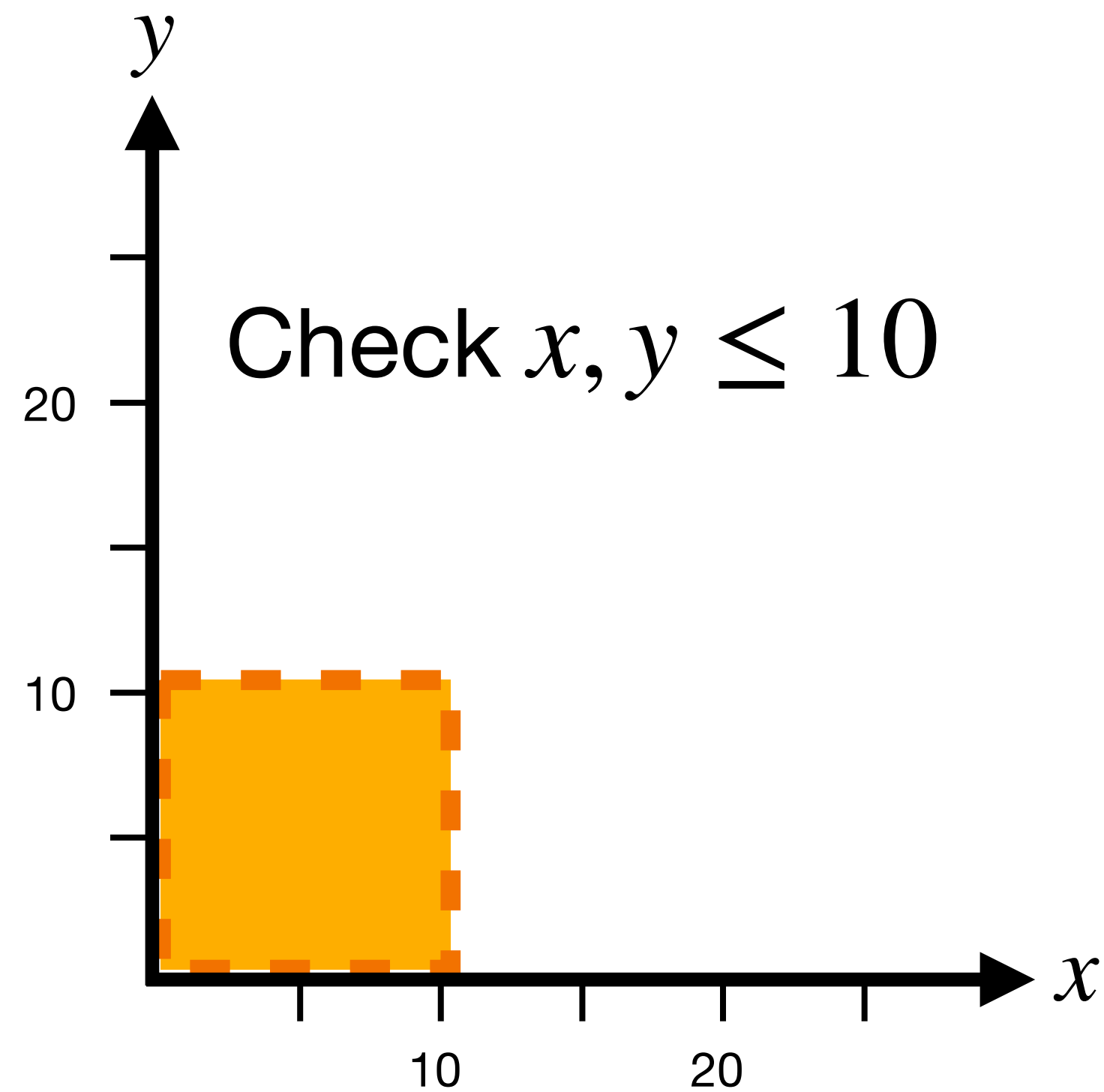
- Automation, e.g., automatic VC rewriting
- Demo scalability: Complex programs & data (e.g. lists, trees)

Outlook: Increase Trust in BMC

- Turn bounded into unbounded proof

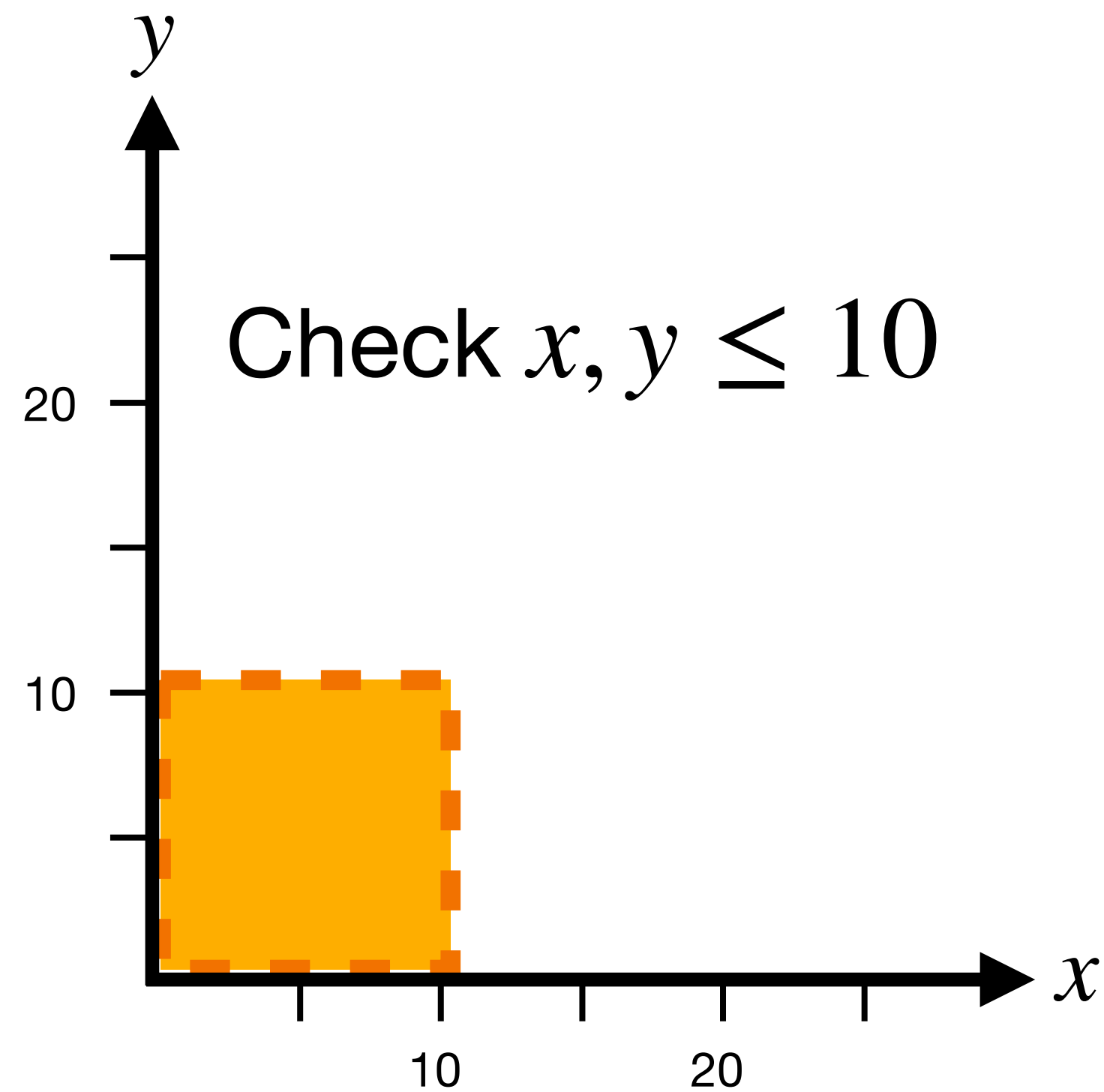
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- Shift resources to critical bounds

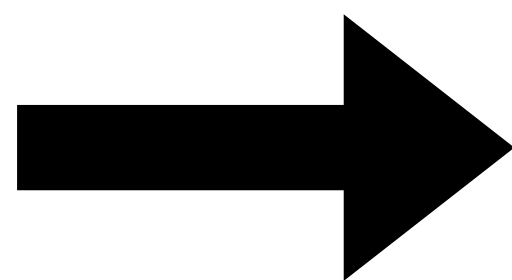


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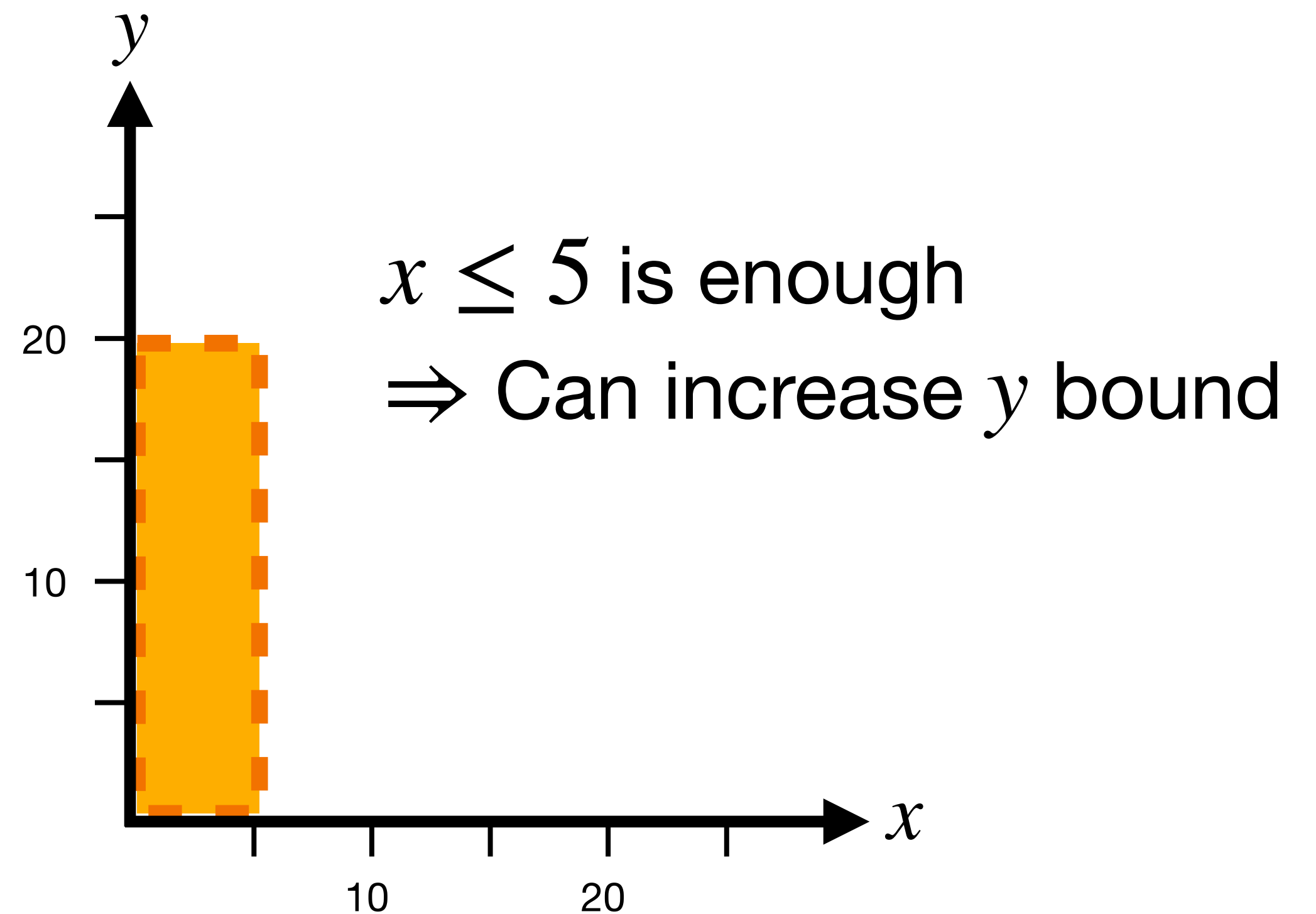
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CT for x :
 $\{0, \dots, 5\}$



50



Conclusion

- First generalisation of CTs to infinite state systems
- Connection between bounded & unbounded proofs in program verification
- Foundational research but potential for integration into BMC

Backup Slides

Precise VCs

- VC vc is *precise* for x in $Spec$ iff

$$\forall v. \left(\models Spec[x \mapsto v] \Rightarrow \models vc[x \mapsto v] \right)$$

Intuition: vc does not over-approximate wrt. x

- Q is CT $vc \wedge vc$ is precise $\Rightarrow Q$ is CT $Spec$

Precise VCs

