

<Linear Algebra 2023 Fall HW3>

Cosine Transform and its Application

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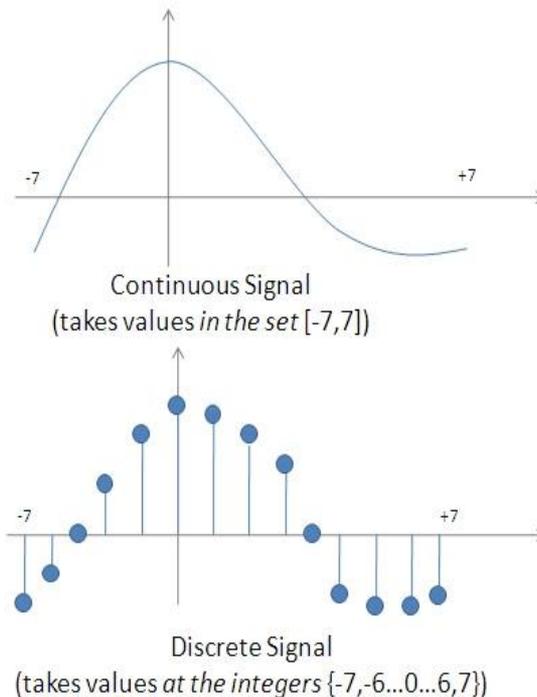
`linear-algebra-lee-2023@googlegroups.com`

Outline

- What is signal
- Fourier Transform
- Cosine Transform
- Homework:
 - Problem 1 - Filtering
 - Problem 2 - JPEG compression
- Rules

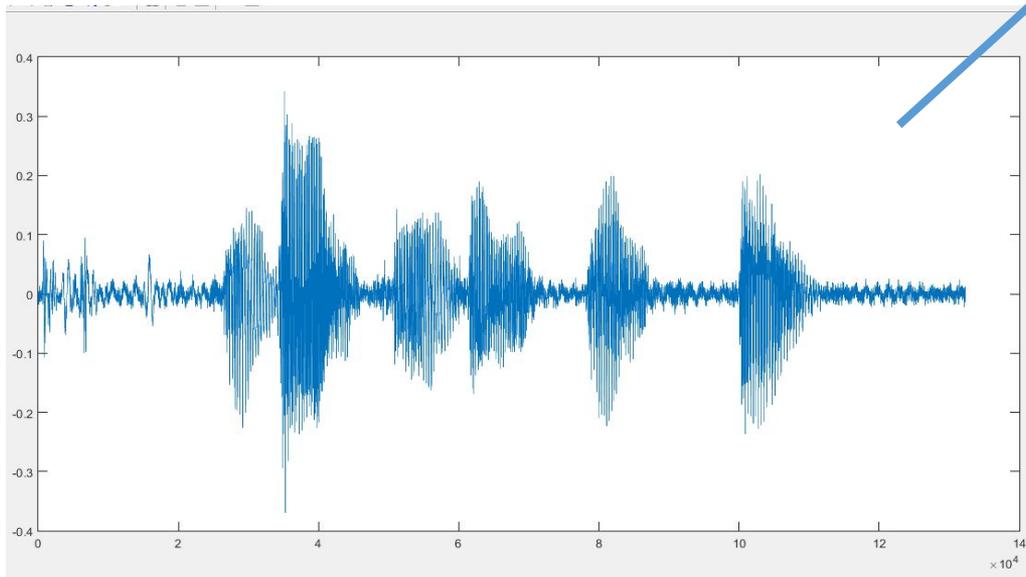
What is signal

- 傳遞有關一些現象的行為或屬性的資訊的函數
- Example
 - $f(t)$: 音訊
 - $f(x, y)$: 圖片
- Type
 - Continuous
 - Discrete
- In this homework, we use
 - discrete signal



Basis

- How to use basis in signal analysis
- Given a speech signal
 - Can we find basis to describe this signal ?



$$\mathbf{x} = [x_0, x_1, \dots, x_{N-1}]$$

$$\mathbf{B} = \{\mathbf{b}_0, \mathbf{b}_1, \dots, \mathbf{b}_{N-1}\}$$
$$[\mathbf{x}]_{\mathbf{B}} = [a_0, a_1, \dots, a_{N-1}] = \mathbf{a}$$
$$\mathbf{x} = \sum_{k=0}^{N-1} a_k \mathbf{b}_k$$

Joseph Fourier

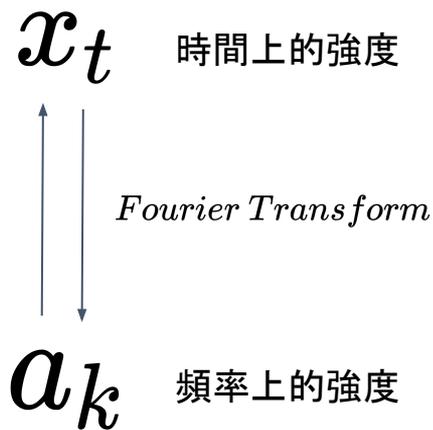
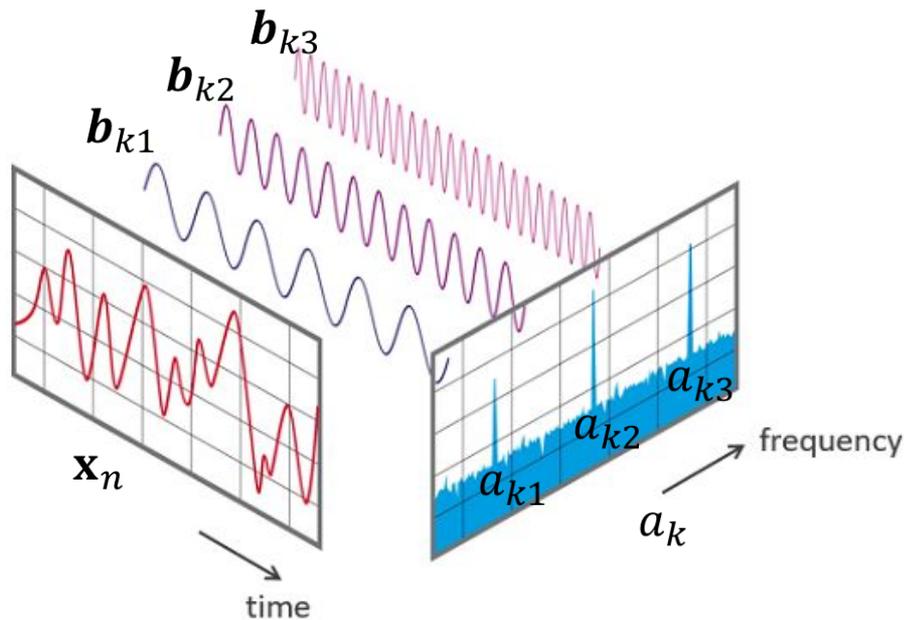


Any **periodic** signal
can be represented
as a sum of
sinusoids.

Fourier Transform

假設 x 主要由三個basis vector組成
→三個頻率的cosine signal組成

$$\mathbf{x} = a_{k1} \mathbf{b}_{k1} + a_{k2} \mathbf{b}_{k2} + a_{k3} \mathbf{b}_{k3}$$



Cosine Transform

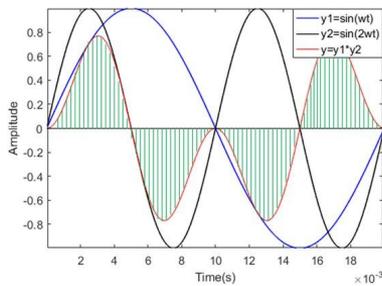
- Fourier Transform includes complex number computation
 - We use cosine transform instead
- Cosine Transform Formula
 - Given a discrete signal $x = [x_0, x_1, \dots, x_n, \dots, x_{N-1}]$ with N length
 - Basis Matrix:

• $\mathbf{B} = \{\mathbf{b}_0, \mathbf{b}_1, \dots, \mathbf{b}_{N-1}\}$ 用N種basis來分解x, 也就是有N種頻率, 頻率用下標k表示

$$b_{n,k} = \begin{cases} \frac{1}{\sqrt{N}}, & \text{if } k = 0 \\ \frac{\sqrt{2}}{\sqrt{N}} \cos \frac{(n+0.5)k\pi}{N}, & \text{else} \end{cases}$$

n: 時間上的index
k: 頻率上的index

How to get a
→



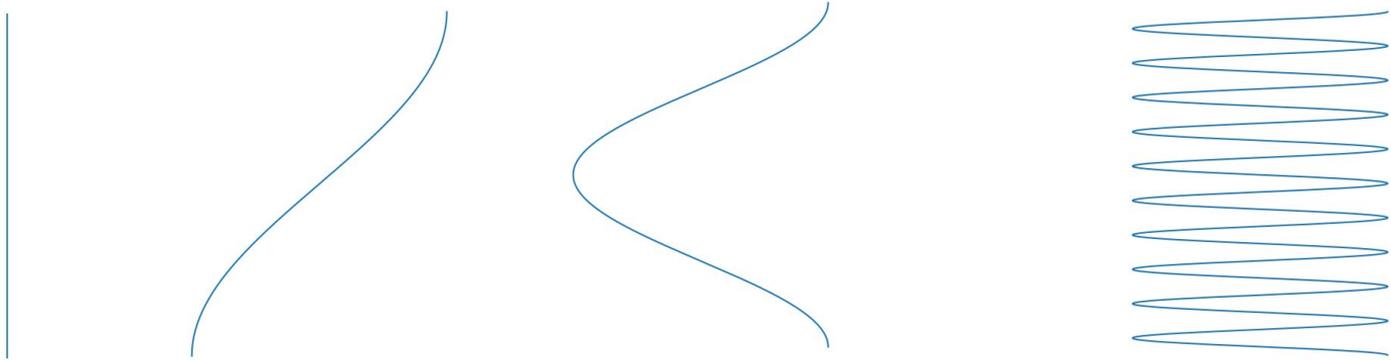
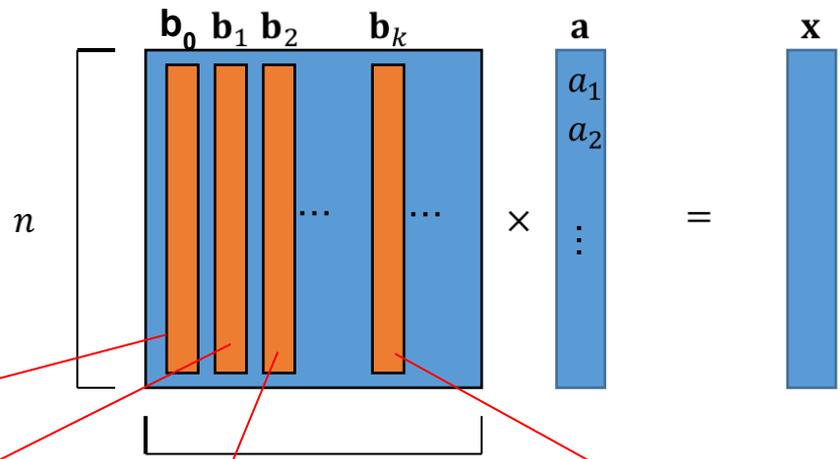
$$\mathbf{x} = \mathbf{B}\mathbf{a} \quad \text{Inverse Cosine transform}$$

$$\mathbf{a} = \mathbf{B}^{-1}\mathbf{x} \quad \text{Cosine transform}$$

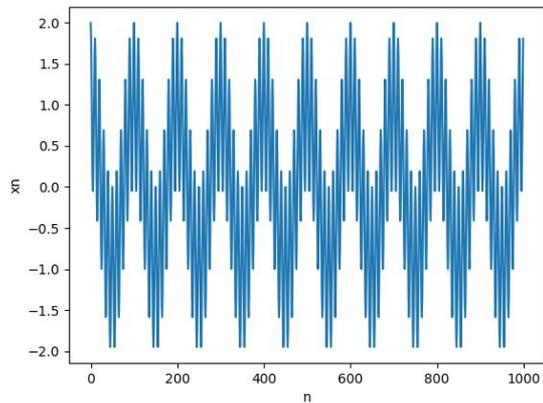
Why sine/cosine waves are basis?

$$\langle \varphi_j, \varphi_k \rangle = \int_{-\pi}^{\pi} \cos jx \cos kx \, dx$$

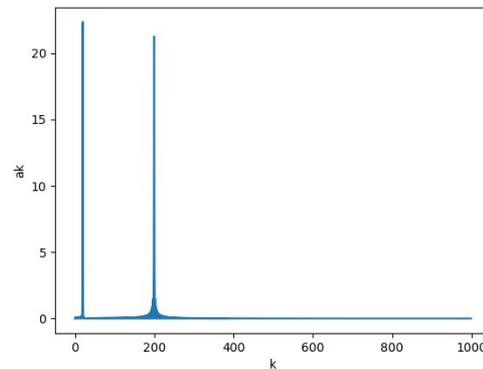
$$b_{n,k} = \begin{cases} \frac{1}{\sqrt{N}}, & \text{if } k = 0 \\ \frac{\sqrt{2}}{\sqrt{N}} \cos \frac{(n+0.5)k\pi}{N}, & \text{else} \end{cases}$$



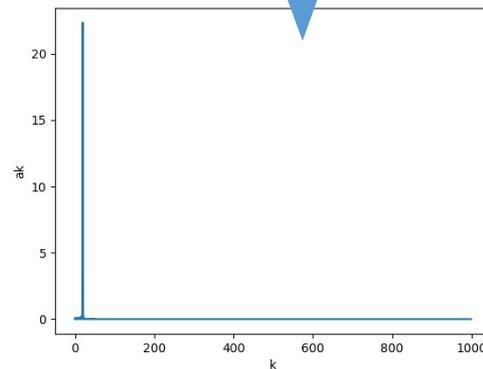
If we want to get the low frequency signal of a mixed signal...



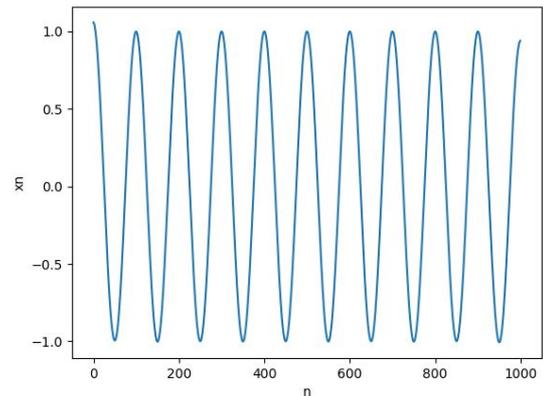
Cosine transform
 $\mathbf{a} = \mathbf{B}^{-1}\mathbf{x}$



mask [1 0 0 0 0 0 0 0 0 0 ... 0 0 0 0 0]



Inverse cosine transform
 $\mathbf{x}' = \mathbf{B}\mathbf{a}$



Application

- **Filtering**

- Human voice
 - Man: 85-180Hz
 - Woman: 165-255Hz
- Remove high frequency noise from speech signal

- **Compression**

- Mel-frequency cepstral coefficients (MFCCs)
- JPEG

strong "energy compaction" property. In typical applications, most of the signal information tends to be concentrated in a few low-frequency components of the DCT

Homework

- **Filtering (problem 1) 3%**
 - p1.py
- **JPEG Compression (problem 2) 3%**
 - p2.py

Code & Data link [Colab link](#)

Github repository contains below files:

- [p1.py](#)
- [p2.py](#)
- example_data
 - [test.txt](#)
 - [test.png](#)
- example_output
 - [freq.png](#)
 - [f1.png](#)
 - [f3.png](#)
 - [reconstructed.png](#)

Problem 1 - Filtering

Input data

- example_data/test.txt
- Total 1000 lines, one value per line

$$x = \sum_{i=1}^5 \text{Cosine}(2\pi f_i)$$

- $f_1 < f_2 < f_3 < f_4 < f_5$

```
1 2.0000000000000000e+00
2 1.807043722803219010e+00
3 1.301131695689425438e+00
4 6.732702563537411589e-01
5 1.595661667536837358e-01
6 -4.894348370484646882e-02
7 1.207594915133041180e-01
8 5.958100580910720145e-01
9 1.185323674418810924e+00
10 1.653344919876962527e+00
11 1.809016994374947451e+00
12 1.579530237150736927e+00
13 1.037985621796358338e+00
14 3.755301115537416079e-01
15 -1.715930046262574837e-01
16 -4.122147477075268629e-01
17 -2.731901993959511277e-01
18 1.727366797267690379e-01
19 7.347962859400198887e-01
20 1.177141547059625148e+00
21 1.309016994374947451e+00
22 1.057706881539801413e+00
23 4.963983089606727184e-01
24 -1.836837608106426378e-01
25 -7.462264748456348684e-01
26 -9.999999999999998890e-01
27 -8.718075139042609223e-01
28 -4.343502279392522092e-01
29 1.216356797892221842e-01
30 5.603271072100921568e-01
31 6.909830056250526598e-01
32 4.408924416902699206e-01
33 -1.167622971901245421e-01
34 -7.907706684766655503e-01
```

TODO

- Goal:

Original waveform contain $f_1 < f_2 < f_3 < f_4 < f_5$

Filtering to extract only f_1 and f_3 component in time-domain

- You should finish all the **#TODO block** in p1.py

```
if __name__ == '__main__':
    # Do not modify these 2 lines
    signal_path = sys.argv[1]
    out_directory_path = sys.argv[2]

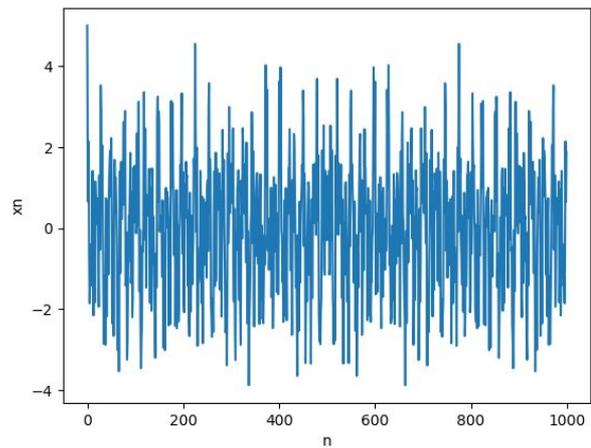
    # TODO
    # filter original waveform to f1-only and f3-only time-domain waveform
    # f1 = ...
    # f3 = ...
```

```
def CosineTrans(x, B):
    # TODO
    # implement cosine transform
    return

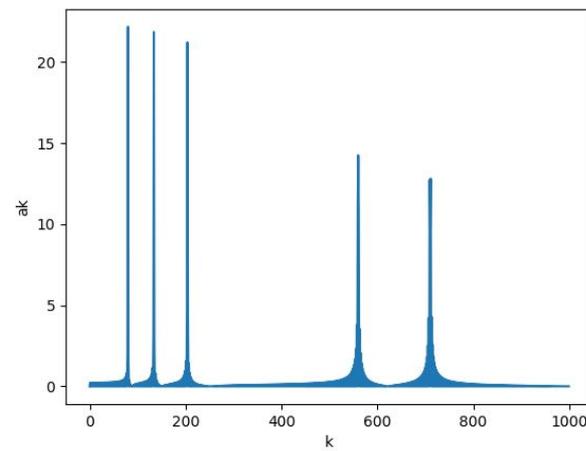
def InvCosineTrans(a, B):
    # TODO
    # implement inverse cosine transform
    return
```

```
def gen_basis(N):
    # TODO
    return
```

Example

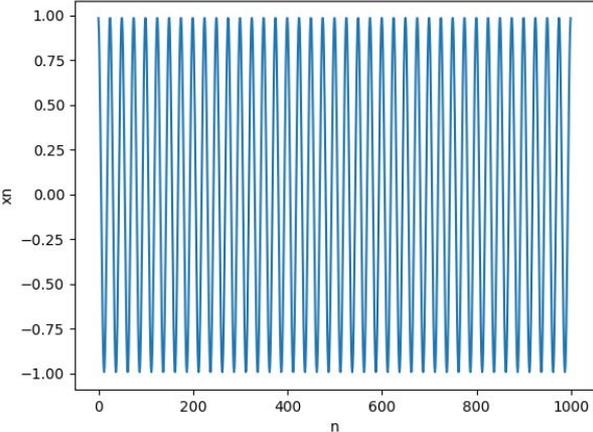


wave

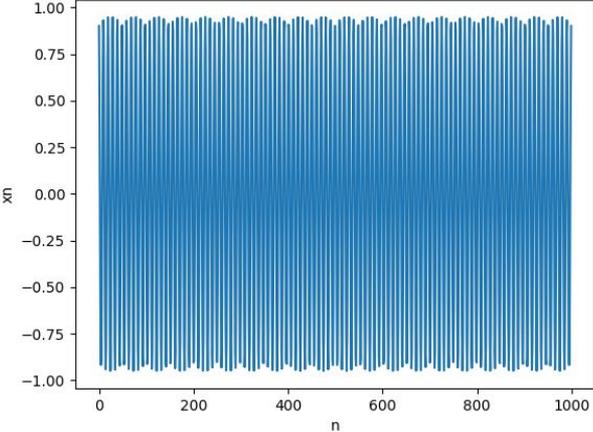


a_k

f1 and f3 in time domain



f1



f3

Run the code

- *python p1.py <input_signal_txt> <output_dir_path>*
- e.g.
python p1.py example_data/test.txt ./
- Your code should generate 3 .png files in <output_dir_path> (e.g. ./).
 - freq.png
 - f1.png
 - f3.png

Scoring

1. (1%) Plot the figure of a (freq.png)
2. (1%) Plot the figure of f_1 (f1.png)
3. (1%) Plot the figure of f_3 (f3.png)

Problem 2 - JPEG

Extend 1D DCT to 2D DCT

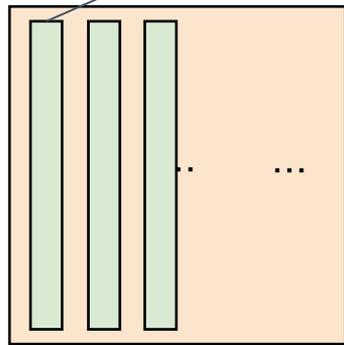
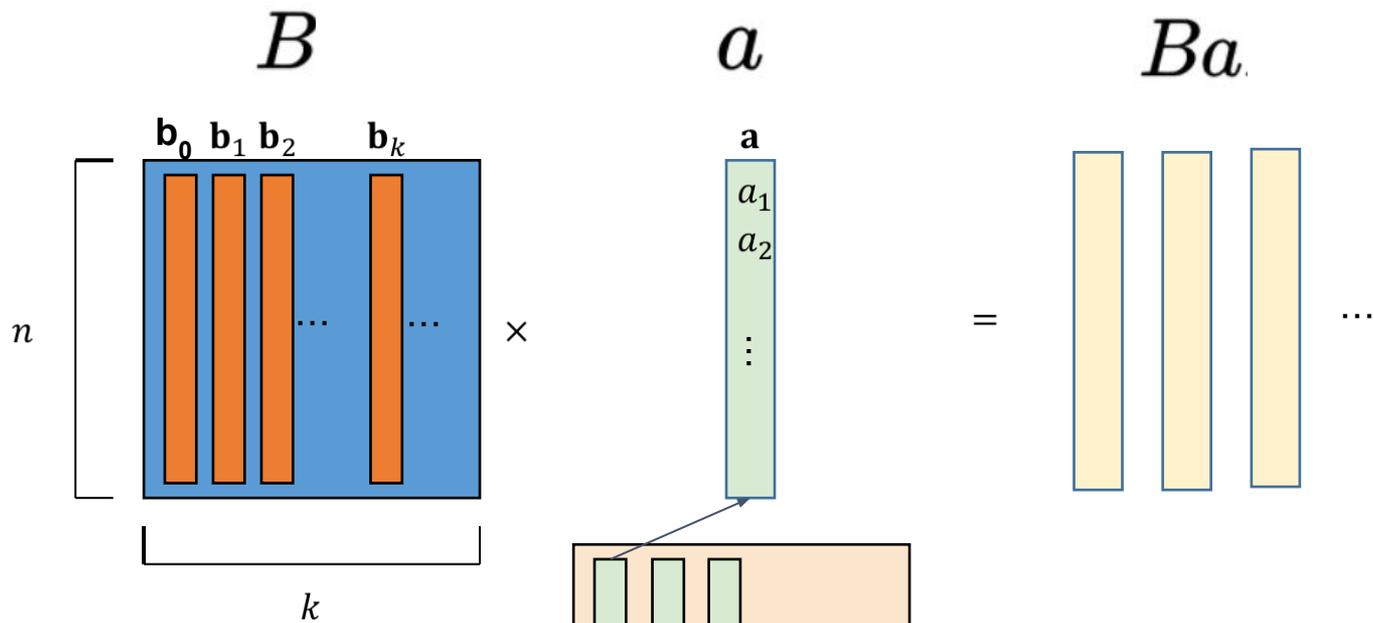
The trick is to **apply the 1D DCT to every column, *and* then also apply it to every row**, i.e.

$$F(m, n) = \frac{2}{\sqrt{MN}} C(m)C(n) \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) \cos \frac{(2x+1)m\pi}{2M} \cos \frac{(2y+1)n\pi}{2N}$$

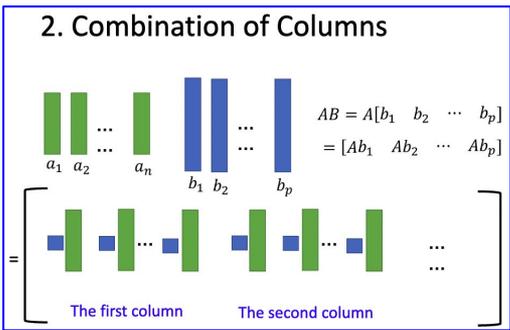
where $C(m) = C(n) = 1/\sqrt{2}$ for $m, n = 0$ and $C(m), C(n) = 1$ otherwise.

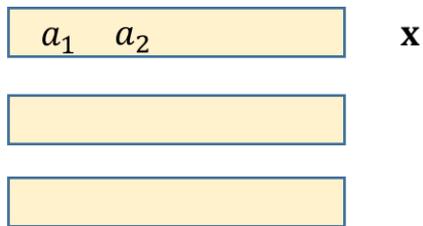
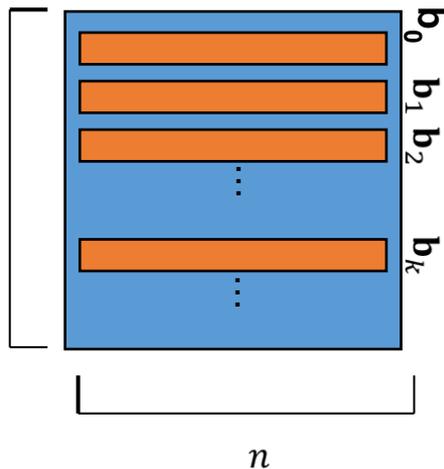
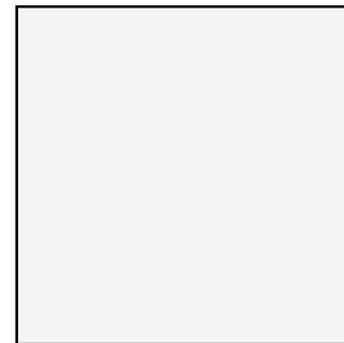
We focus on the square image here, that is **M = N**,

$$X = BaB^T \quad a = ?$$



1D iDCT for every columns
 each column vector in Ba is the weighted sum of column vector in B



Ba  \mathbf{x} \times B^T  $=$ X **1D iDCT for every rows**

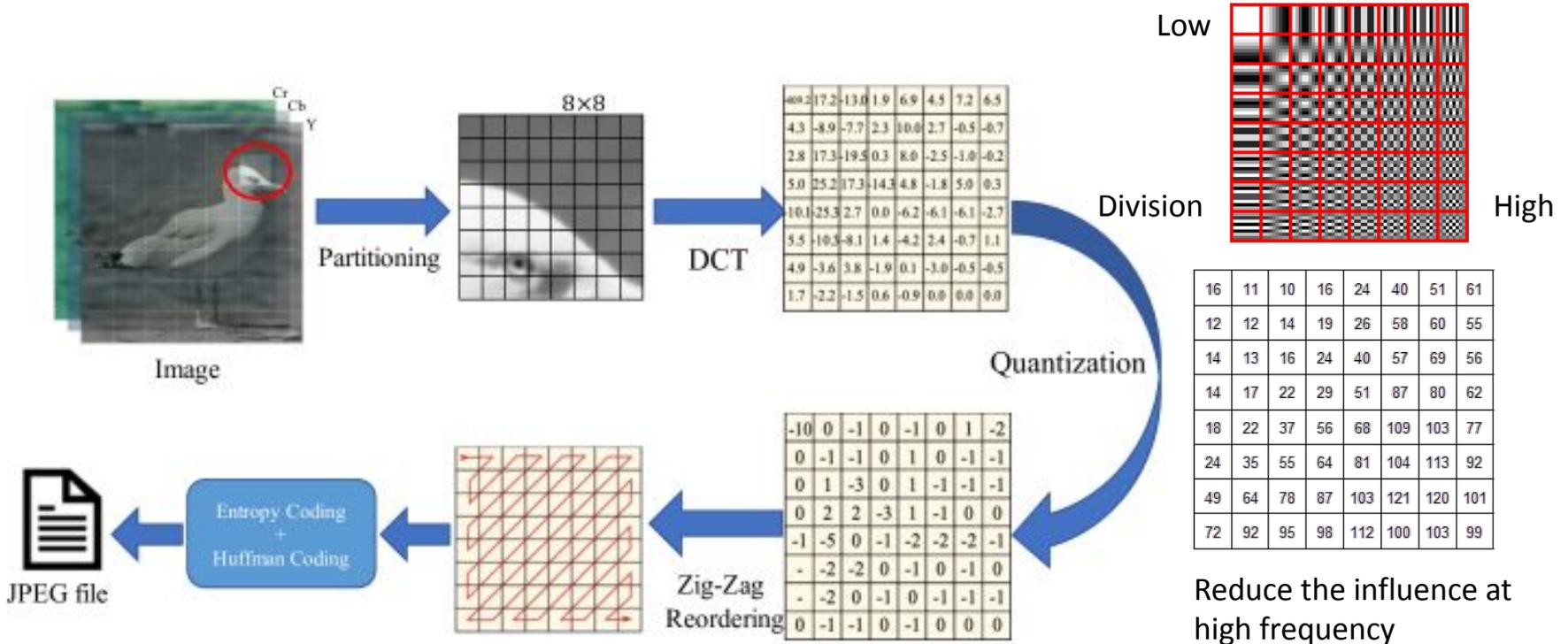
each row vector of X is the weighted sum of row vector in the transpose of B

3. Combination of Rows

$$\begin{matrix}
 a_1^T & \text{---} & b_1^T \\
 a_2^T & \text{---} & b_2^T \\
 \vdots & \vdots & \vdots \\
 a_m^T & \text{---} & b_n^T
 \end{matrix}
 =
 \begin{bmatrix}
 a_{11}b_1^T + a_{12}b_2^T \cdots + a_{1n}b_n^T \\
 a_{21}b_1^T + a_{22}b_2^T \cdots + a_{2n}b_n^T \\
 \vdots \\
 a_{m1}b_1^T + a_{m2}b_2^T \cdots + a_{mn}b_n^T
 \end{bmatrix}$$

JPEG compression

Strongly recommend you to see this tutorial for detail
https://www.youtube.com/watch?v=Q2aEzeMDHMA&ab_channel=Computerphile



TODO

記得先寫好p1.py再寫p2, 因為p2.py
會call p1.py的*gen_basis* function

- Goal:

Implement 2D DCT in *CosineTrans2d* and 2D iDCT in *InvCosineTrans2d*

- You should finish all the **#TODO block** in p2.py

```
# input: Basis (B), 2D image array (X)
# output: coefficient in 2D (a)
def CosineTrans2d(B, X):
    # TODO
    # implement 2D DCT
    return
```

```
# input: Basis (B), coefficient in 2D (a)
# output: reconstructed image (X')
def InvCosineTrans2d(B, a):
    # TODO
    # implement 2D DCT
    return
```

Important

- If you want to know more about the implementation of JPEG compression, we encourage you to trace other code in `p2.py` and play with it.
- **but when submission your final code, DON'T modify other code in `p2.py`, or your reconstructed image might look significantly different.**

JPEG result

only use 0.15 original size of
information to reconstruct



original



JPEG reconstructed

Run the code

- *python p2.py <input_image_file> <output_dir_path>*
- e.g.
python p2.py example_data/test.png ./
- Your code should generate 1 .png files in <output_dir_path> (e.g. ./), which is your JPEG reconstructed image.
 - reconstructed.png

Scoring

1. 2D DCT (1%)
2. 2D iDCT (1%)
3. reconstructed.png (1%)

只要2D DCT, iDCT實作正確, 重建後的圖片後圖片沒有明顯artifact就給過 (除非你改了#TODO以外的code上傳時又沒有改回去), 不需要每個pixel都跟測資一樣, 因為矩陣運算些微誤差會導致某些pixel改變

Code Rules

- 不可以import除了numpy以外的library來實作 (i.e. 上傳的版本中不能import任何其他的library, 最多用numpy)

Submission Rule

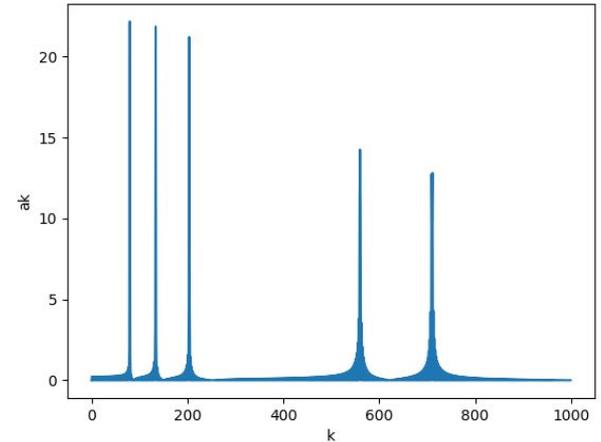
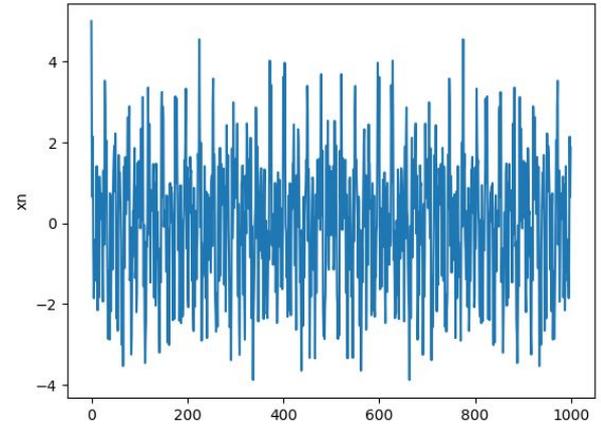
- 不要抄作業，不要交別人的答案，第一次抓到作弊該作業0分計算，第二次抓到作弊直接當掉。本作業會用moss抓抄襲。
- 上傳p1.py與p2.py檔案到 NTU COOL
- Deadline: **2023/11/17(五) 23:59** (GMT+8:00)
- 遲交每過一天:分數 $\times 0.8$ (per day) 超過三天拒收
- 格式、檔案、各種奇怪的錯誤讓助教無法改作業:分數 $\times 0.7$
- **請務必注不要更改input & output path成自己的電腦路徑！保持使用sys.argv的方式彈性讀取檔案**

```
if __name__ == '__main__':  
    # Do not modify these 2 lines  
    signal_path = sys.argv[1]  
    out_directory_path = sys.argv[2]
```

```
if __name__ == '__main__':  
    im_path = sys.argv[1]  
    output_path = sys.argv[2]
```

Some utility functions

```
9
10 def plot_wave(x, path = './wave.png'):
11     # util function
12     plt.gcf().clear()
13     plt.plot(x)
14     plt.xlabel('n')
15     plt.ylabel('xn')
16     plt.savefig(path)
17
18 def plot_ak(a, path =  './freq.png' ):
19     # util function
20     plt.gcf().clear()
21
22     # Only plot the mag of a
23     a = np.abs(a)
24     plt.plot(a)
25     plt.xlabel('k')
26     plt.ylabel('ak')
27     plt.savefig(path)
28
```



FAQ

Q1. 找 $f_1 \sim f_5$ 是找 a 中最大的5個還是要對 a 取絕對值之後再找？

A. 對 a 取絕對值之後再找最大的5個。

Q & A

若有**作業相關問題**請到**NTU COOL作業討論版**發問
你的問題很可能也是其他同學的問題：)