



Hybrid Variational/Ensemble Data Assimilation

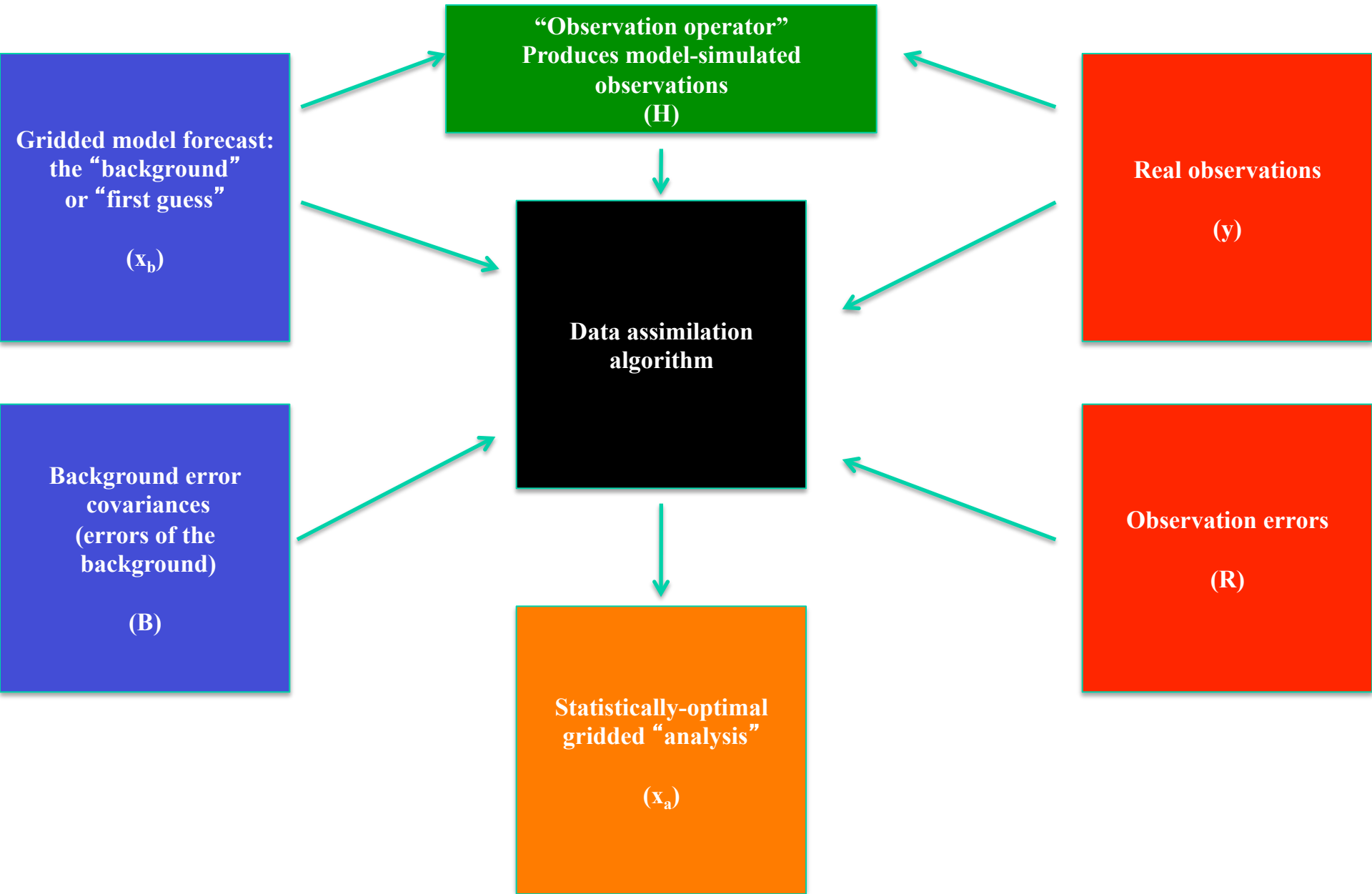
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NCAR/MMM

Outline

- Background
- Some results
- Introduction to hybrid practice

What is data assimilation?

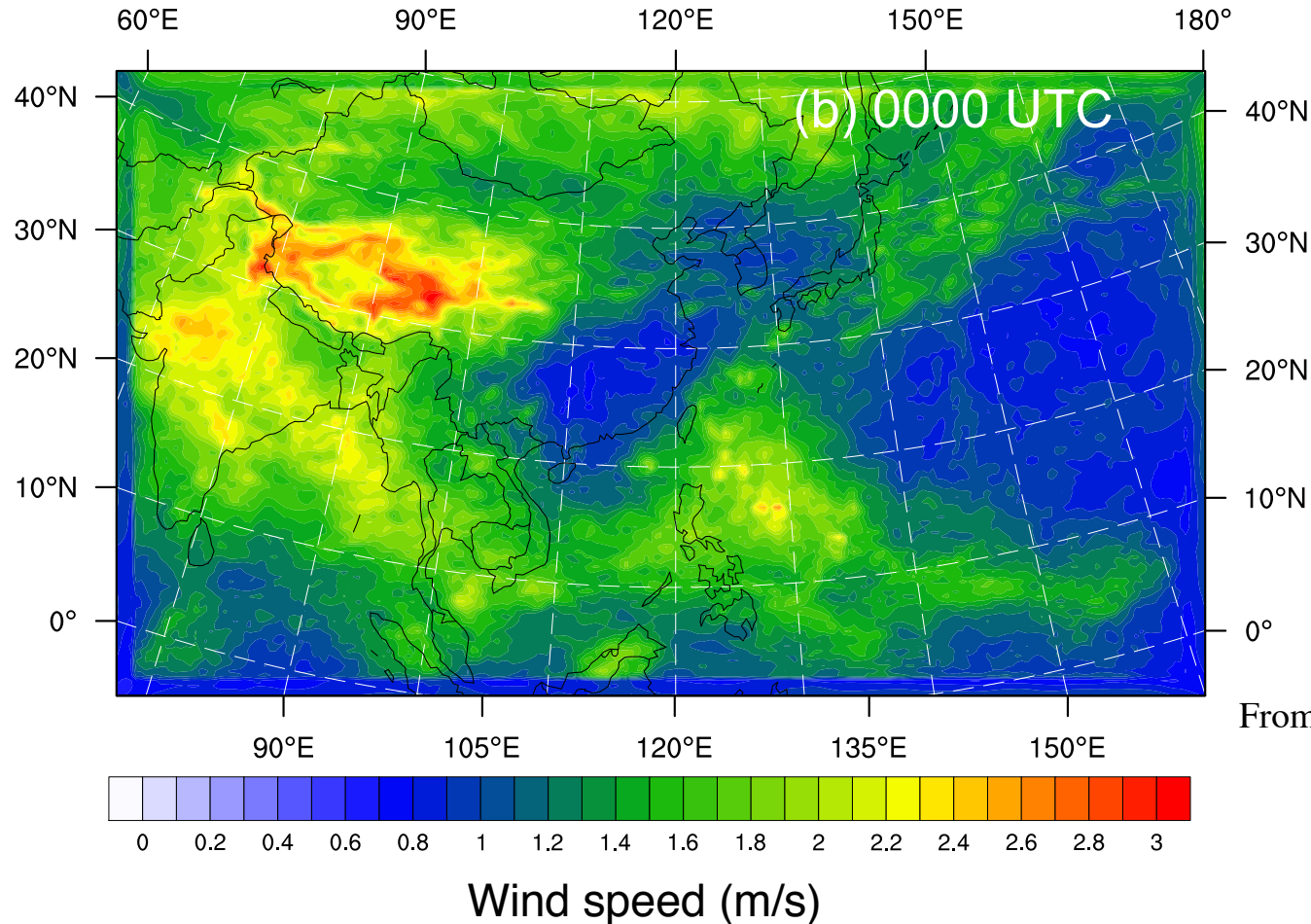


Some data assimilation methods

- Three-dimensional variational (3DVAR)
 - Background error covariances (BECs) typically fixed/ time-invariant
 - May yield poor results when actual flow differs from that encapsulated within the fixed “climatology”
- Ensemble Kalman filter (EnKF)
 - Time-evolving, “**flow-dependent**” BECs estimated from a short-term ensemble forecast
 - Many different flavors (e.g., ETKF, EAKF)

Ensemble BECs (i.e., spread)

- Average ensemble spread of wind speed over ~3 weeks at 0000 UTC



Ensemble BECs (i.e., spread)

- General definition of covariance:

$$\frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})$$

- In vector matrix form (here, assume n is ensemble size):

$$\begin{aligned} &= \frac{1}{n-1} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})(\mathbf{x}_i - \bar{\mathbf{x}})^T \\ &= \frac{1}{n-1} \sum_{i=1}^n (\delta \mathbf{x}_i)(\delta \mathbf{x}_i)^T \end{aligned}$$

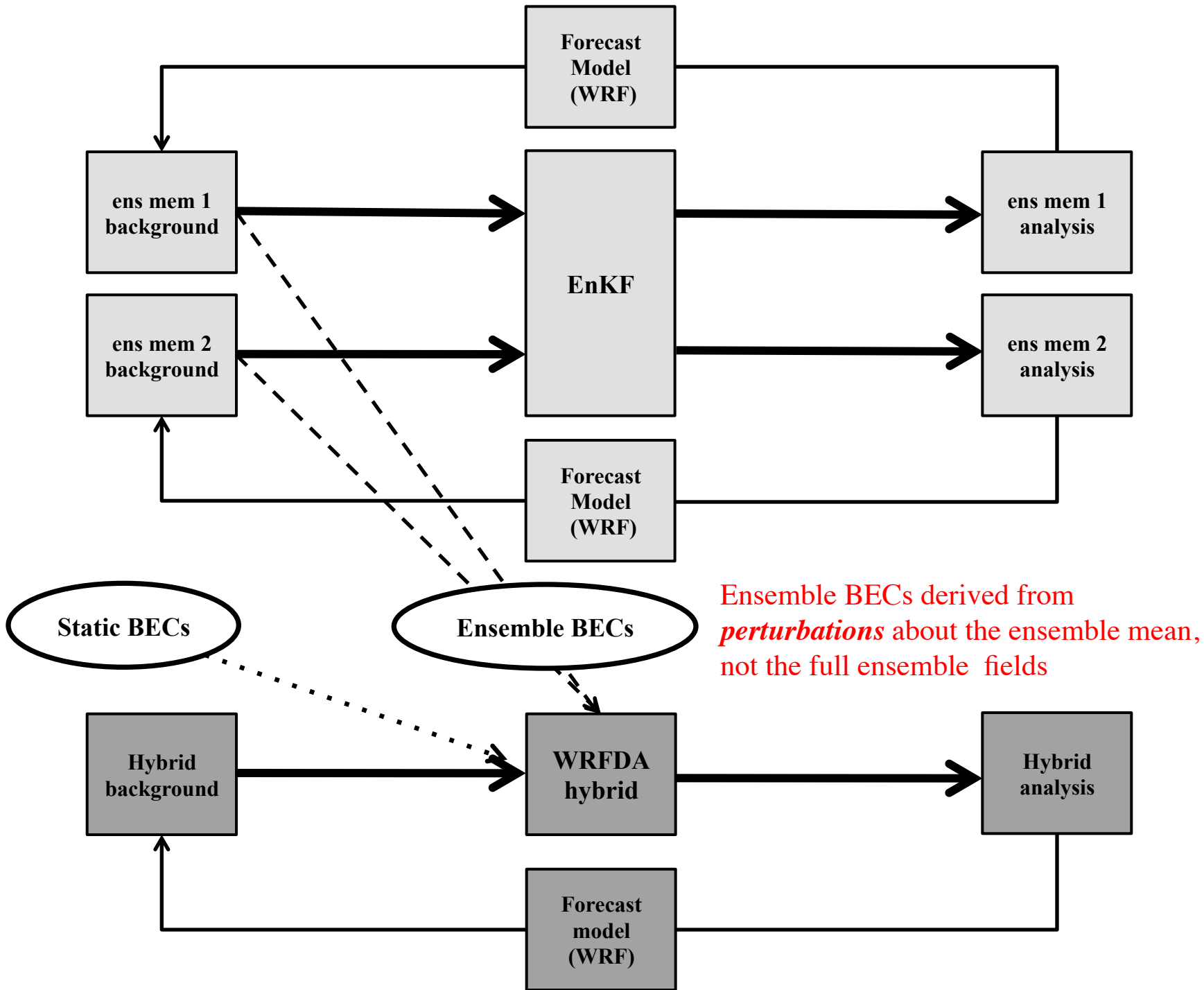
“Hybrid” variational/ensemble DA

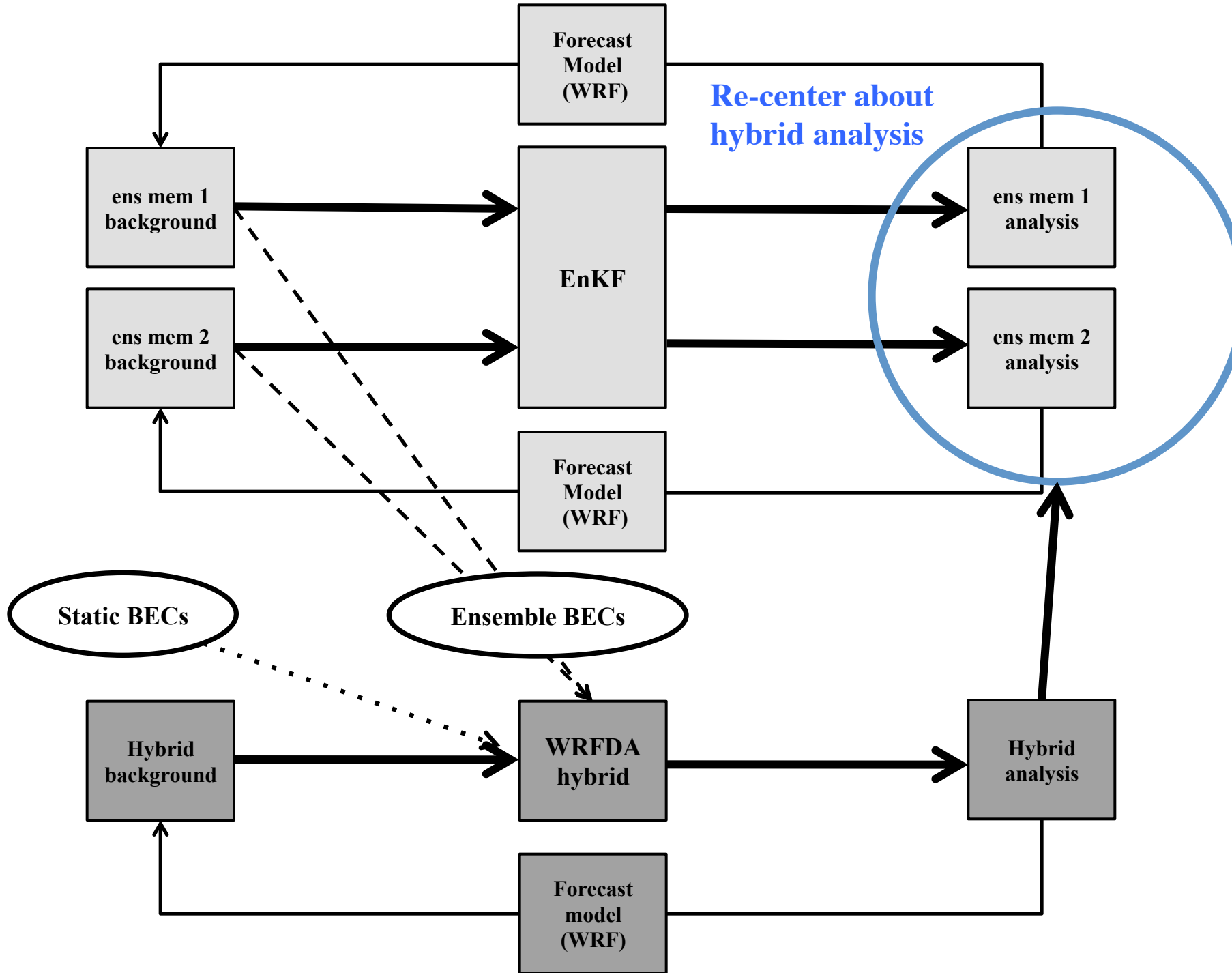
- “Hybrid” variational/ensemble
 - Incorporates ensemble background errors within a variational (e.g., 3DVAR) framework
 - Combination of fixed and time-evolving background errors
 - Main additional expense compared to 3DVAR is running an ensemble of forecasts



What is Hybrid DA?

- **Deterministic background** is analyzed by a variational algorithm (i.e., minimize a cost function)
 - It combines the 3DVAR “climatological” BECs and “errors of the day” from ensemble perturbations
- Traditionally generates a deterministic analysis (like 3DVAR)
- Need a separate system to update ensemble
 - Could be ensemble forecasts already available from operational centers
 - Could be an EnKF-based DA system
 - Could be a multiple model/physics ensemble
- Ensemble needs to be good to well-represent “errors of the day”





Hybrid formulation

(Hamill and Snyder, 2000)

- 3DVAR cost function

$$J(\mathbf{x}) = \frac{1}{2}(\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}_b) + \frac{1}{2}[H(\mathbf{x}) - \mathbf{y}]^T \mathbf{R}^{-1}[H(\mathbf{x}) - \mathbf{y}]$$

- Idea: replace \mathbf{B} by a weighted sum of static \mathbf{B}_s and the ensemble \mathbf{B}_e

$$\mathbf{B} = a_s \mathbf{B}_s + a_e \mathbf{B}_e \circ \mathbf{C}, \quad a_s = 1 - a_e$$

- Term \mathbf{C} is localization for the ensemble
 - Terms a_s and a_e can be tuned to determine how much \mathbf{B}_s and \mathbf{B}_e are weighted
- This form is difficult to implement for a large NWP model
 - Most systems use “extended control variables”

Hybrid formulation used in WRFDA

(Lorenc, 2003)

- Ensemble covariance is included in the 3DVAR cost function through augmentation of control variables

$$J(\mathbf{x}, \alpha) = \beta_s \frac{1}{2} (\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}_b) + \overbrace{\beta_e \frac{1}{2} \sum_{i=1}^N \alpha_i^T \mathbf{C}^{-1} \alpha_i}^{\text{ensemble control variable } \alpha_i \text{ (} M \times 1 \text{)}} + \frac{1}{2} [\mathbf{y} - H(\mathbf{x} + \mathbf{x}'_e)]^T \mathbf{R}^{-1} [\mathbf{y} - H(\mathbf{x} + \mathbf{x}'_e)]$$

$$\mathbf{x}'_e = \sum_{i=1}^N \alpha_i \circ \mathbf{x}'_i, \text{ where } \mathbf{x}'_i \text{ is the ensemble perturbation for the ensemble member } i.$$

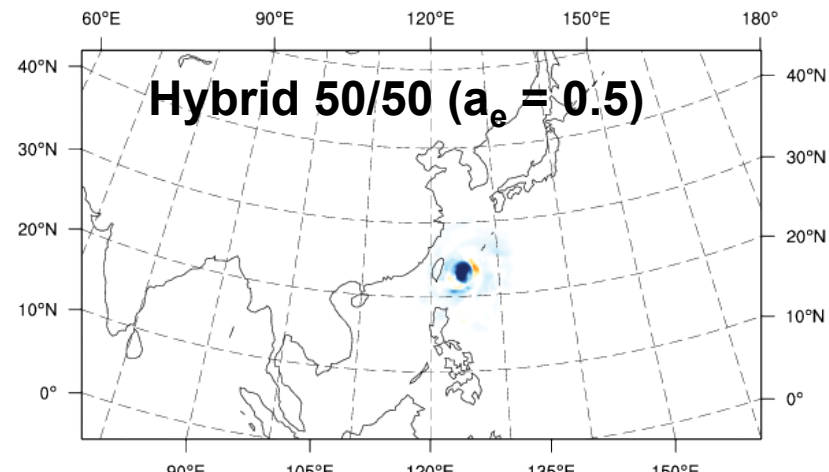
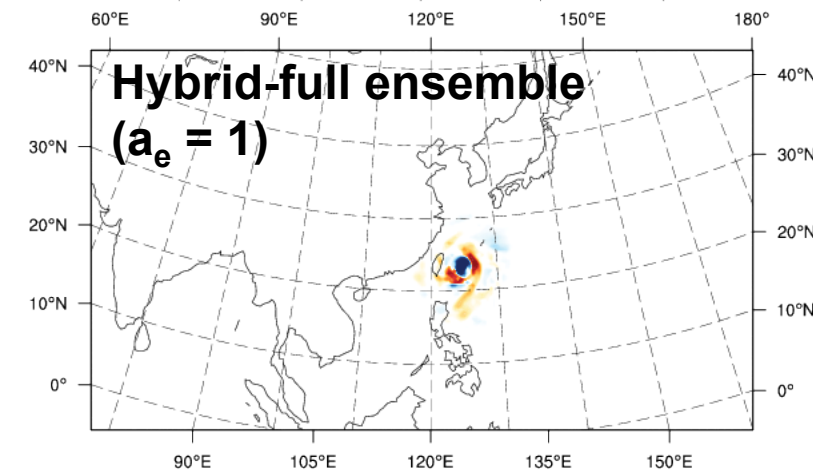
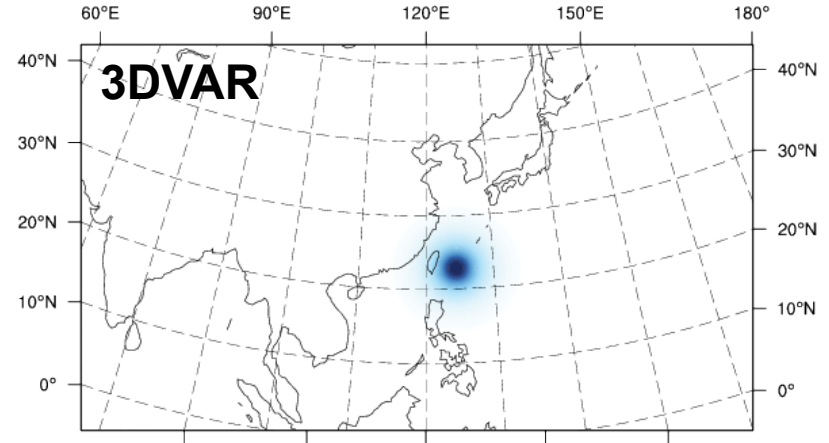
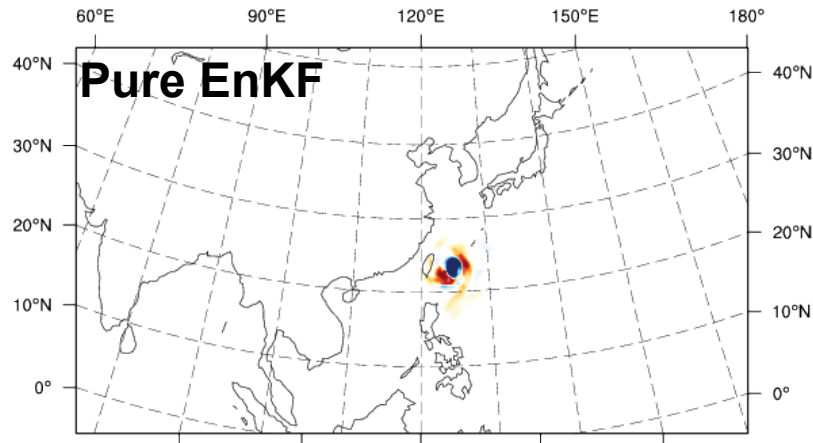
◦ denote element - wise product. α_i is in effect the ensemble weight.

\mathbf{C} : correlation matrix (effectively localization of ensemble perturbations)

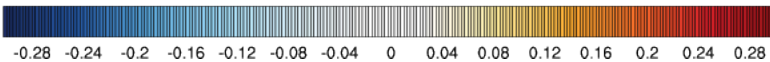
- More simply: $J(\mathbf{x}, \alpha) = J_b + J_e + J_o$
- β_s and β_e ($1/\beta_s + 1/\beta_e = 1$) can be tuned to have different weight between static and ensemble part

Single observation tests

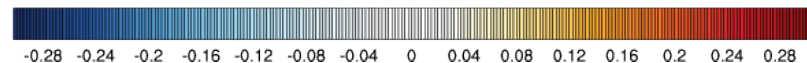
- Potential temperature increment, 21st model level



Average increment of T (K)

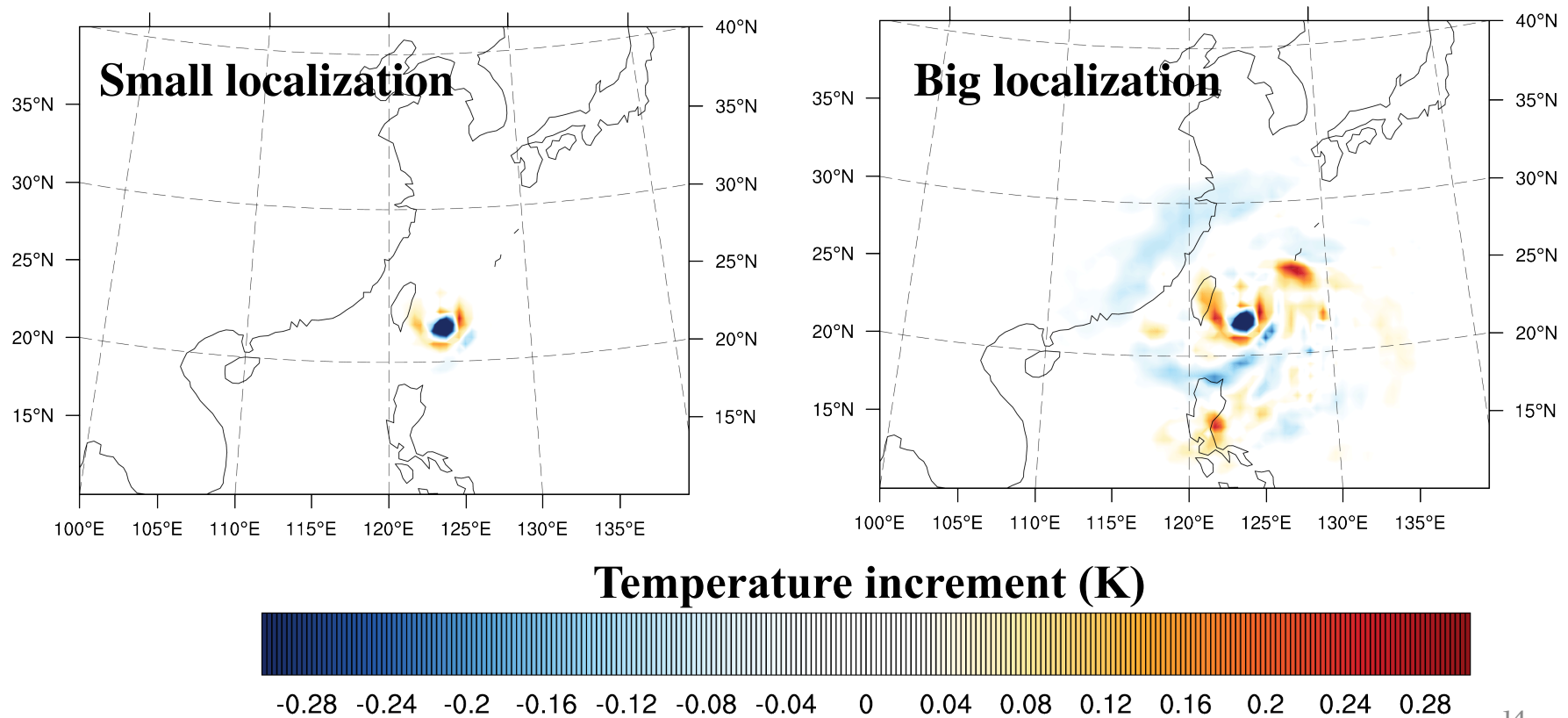


Average increment of T (K)



Meaning of localization

- Localization defines the extent to which an observation can produce an analysis increment
- In this example, 100% of the BECs are from ensemble

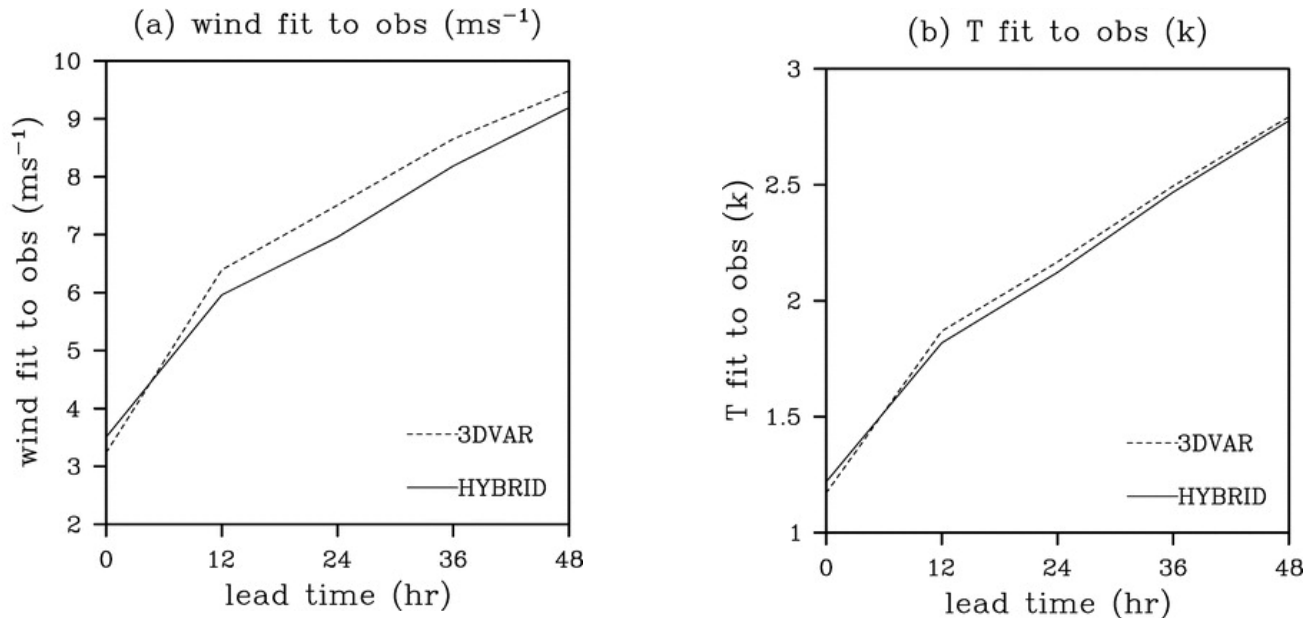


Advantages of Hybrid DA

- Hybrid localization is in model space while EnKF localization is usually in observation space
- For some observation types (e.g., radiances), localization is not well defined in observation space
- Easier to make use of existing radiance VarBC in hybrid
- For small ensembles, use of static **B** could be beneficial to have a higher-rank covariance.

Sample results

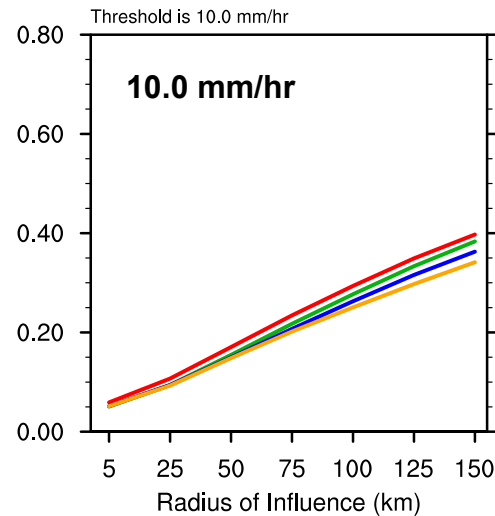
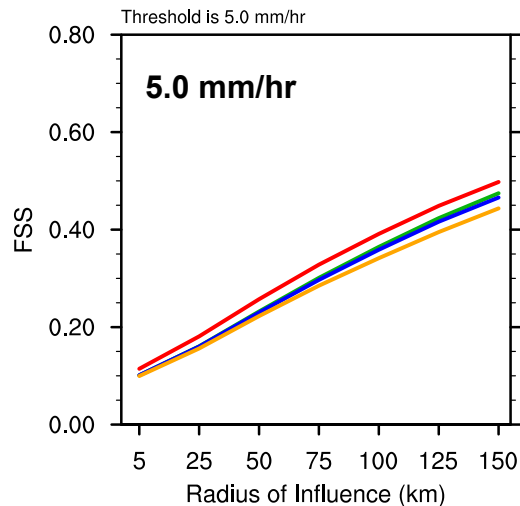
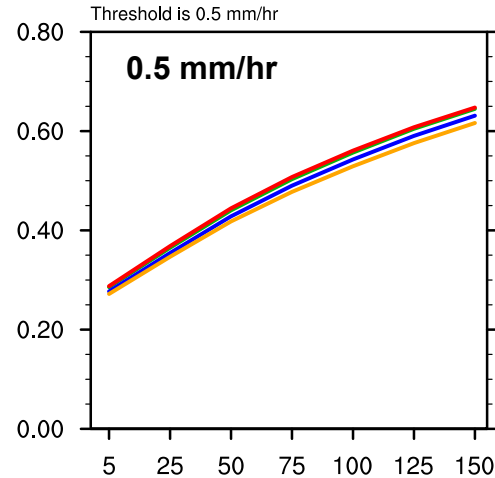
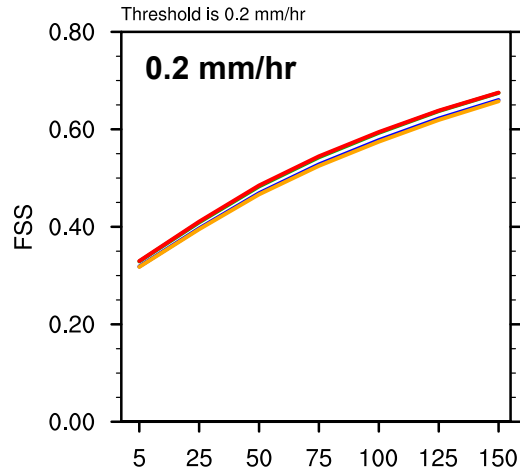
- Example over North America at coarse grid spacing
- Similar results have been obtained by many studies



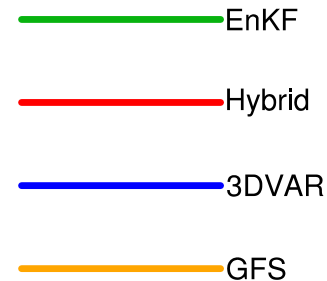
From Wang et al. (2008)

Hybrid vs. 3DVAR and EnKF

- Fractions skill scores for rainfall (higher is better)



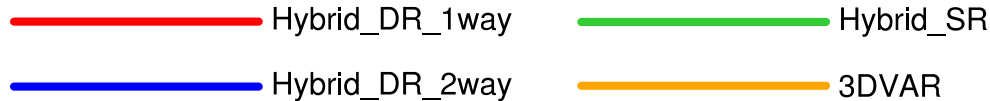
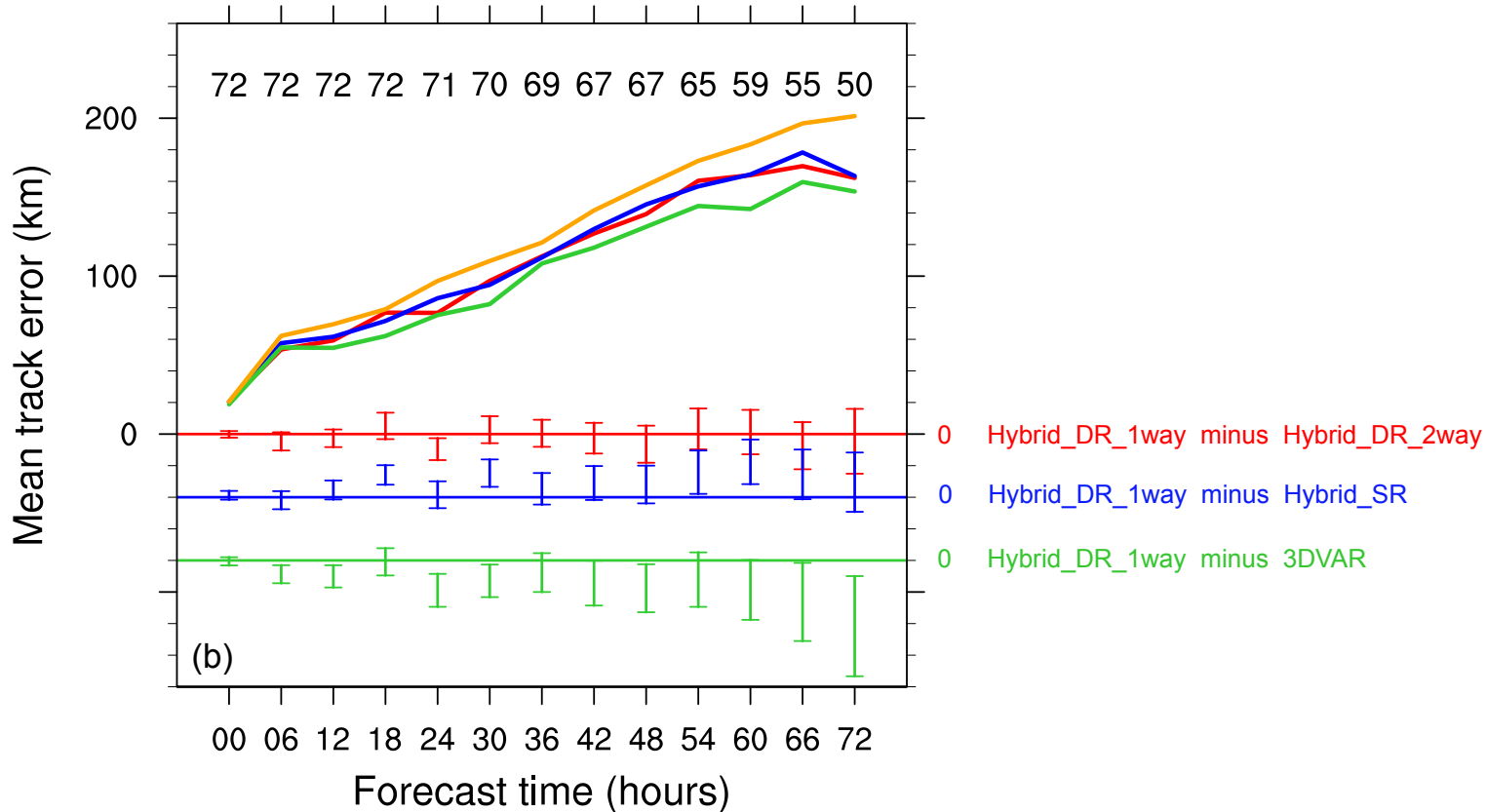
Aggregated over hourly 18-36-hr forecasts of precipitation



Modified from Schwartz and Liu (2014)

Typhoon example

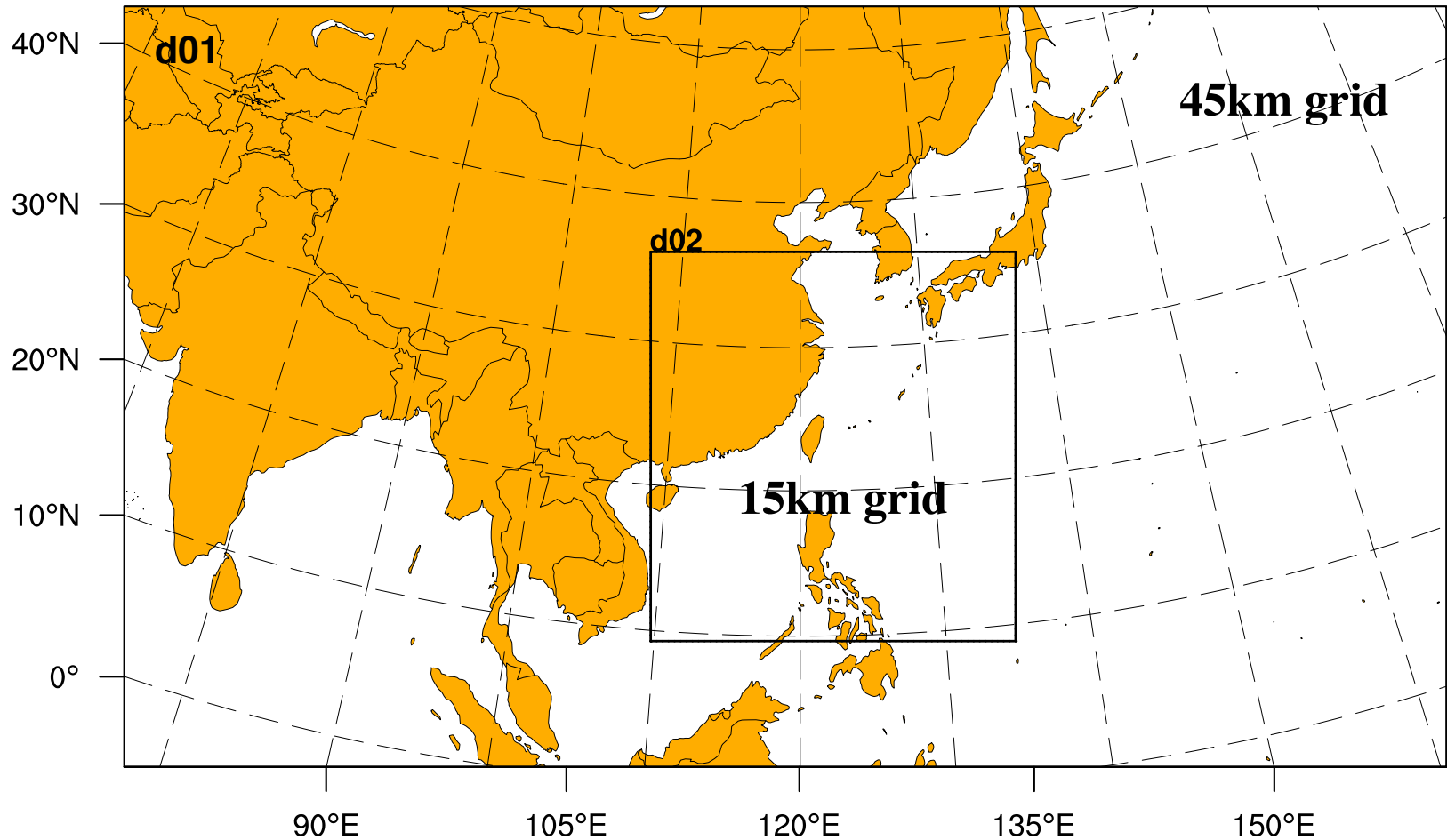
- Mean tropical cyclone track errors



From Schwartz et al. (2015)

Dual-Resolution hybrid (V3.6)

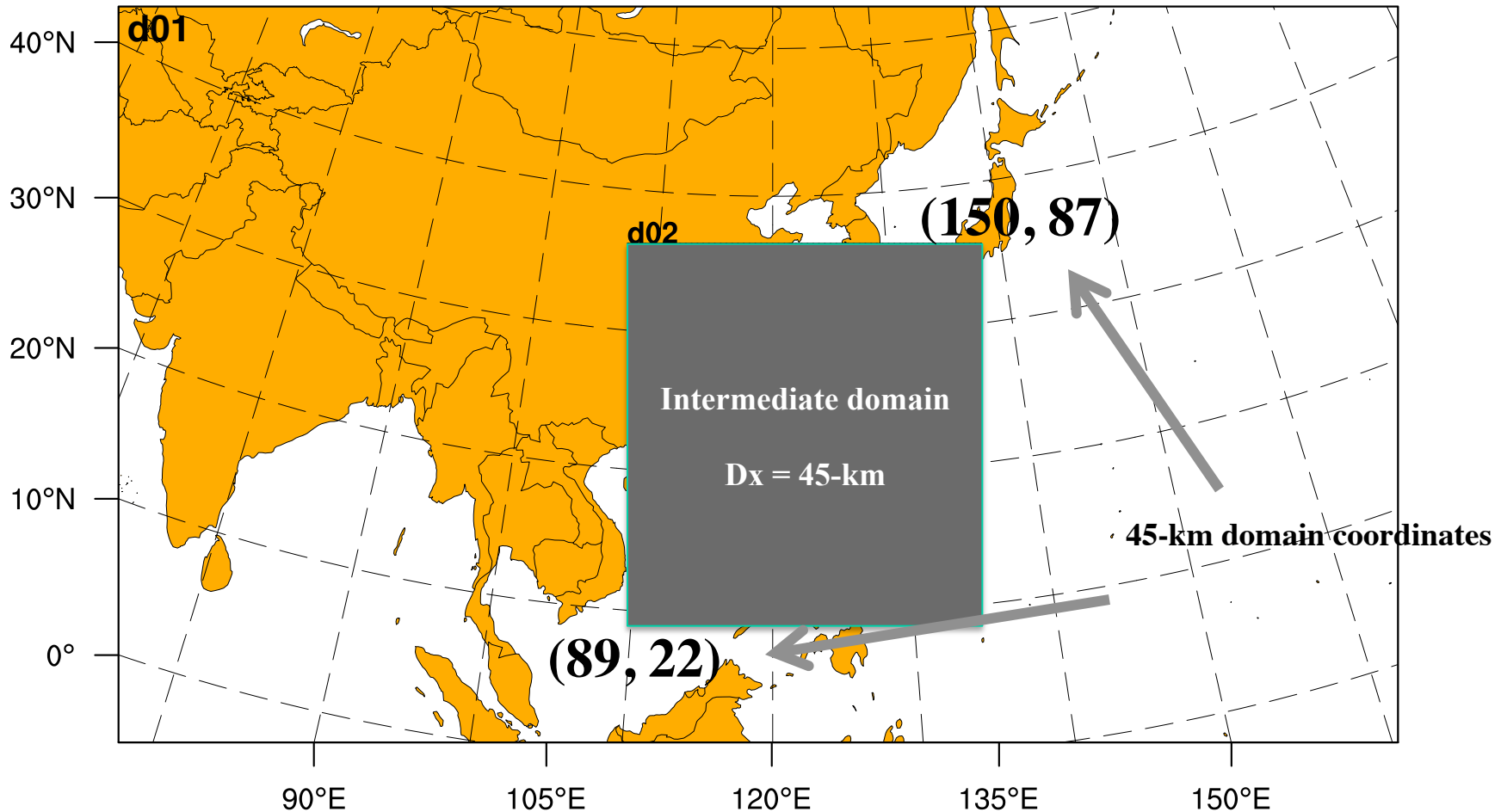
Schwartz et al. (2015; MWR)



Hybrid analysis on 15-km grid but with ensemble perturbation input from 45-km grid

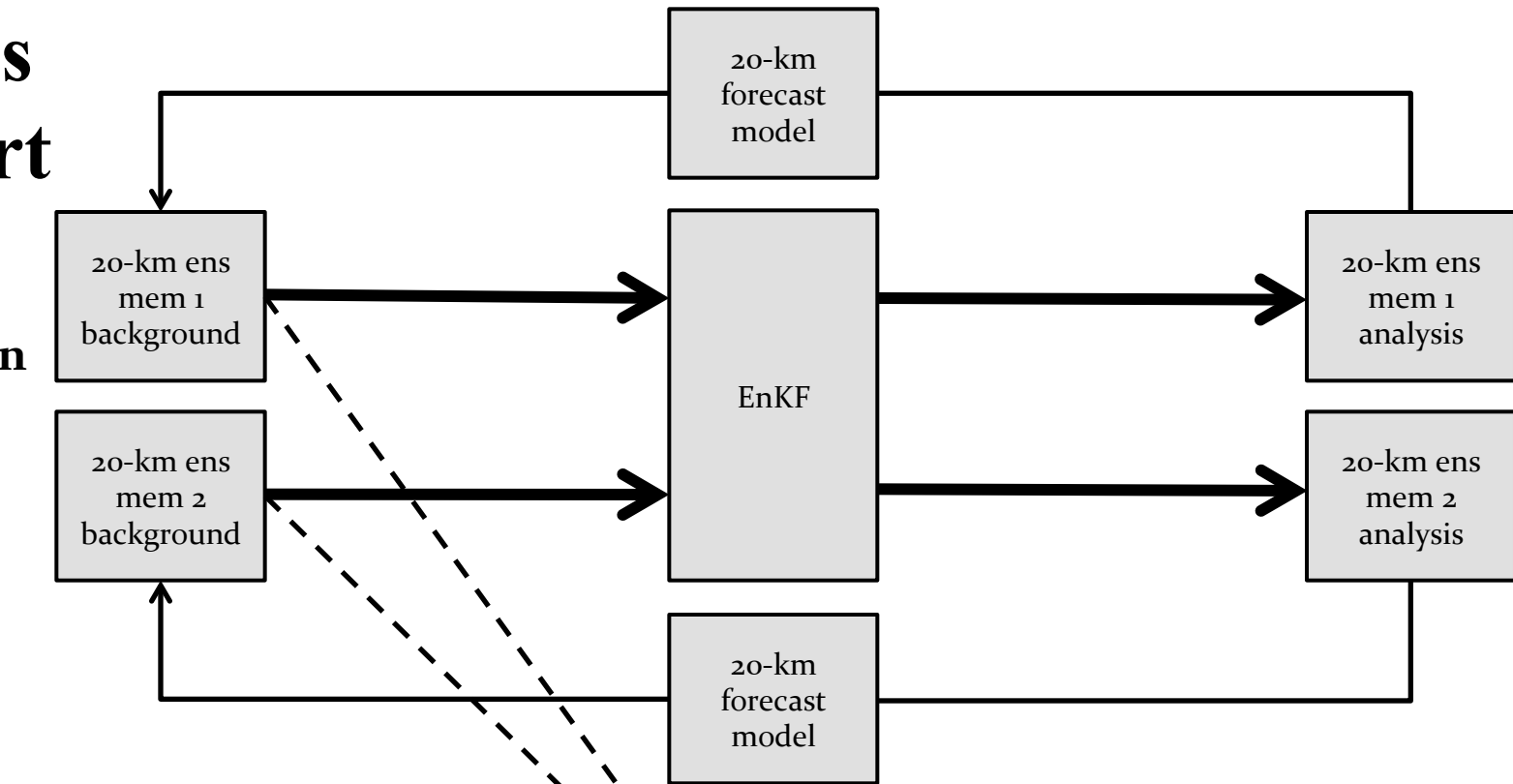
Intermediate domain

- WRFDA directly reads in d01 ensembles, then cuts to d02 size (making use of WRF model nest namelist setting)

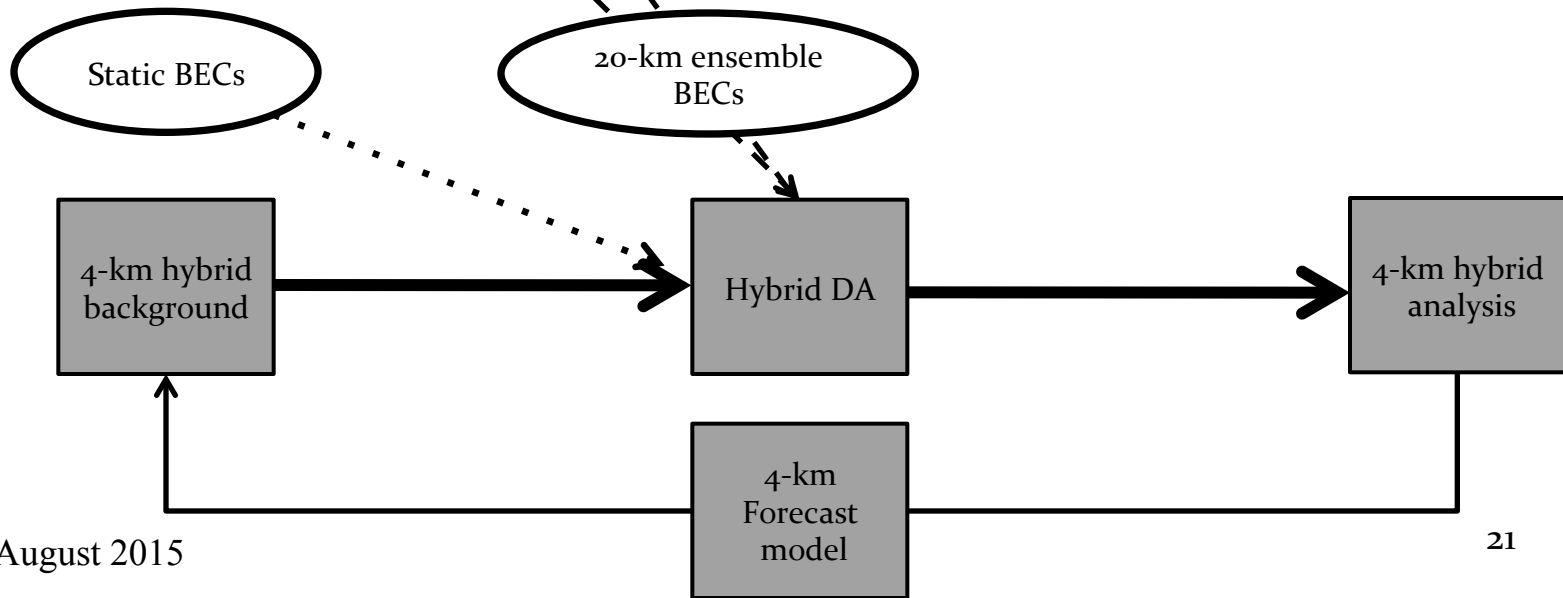


Dual-res flowchart

Low-resolution
(20-km)

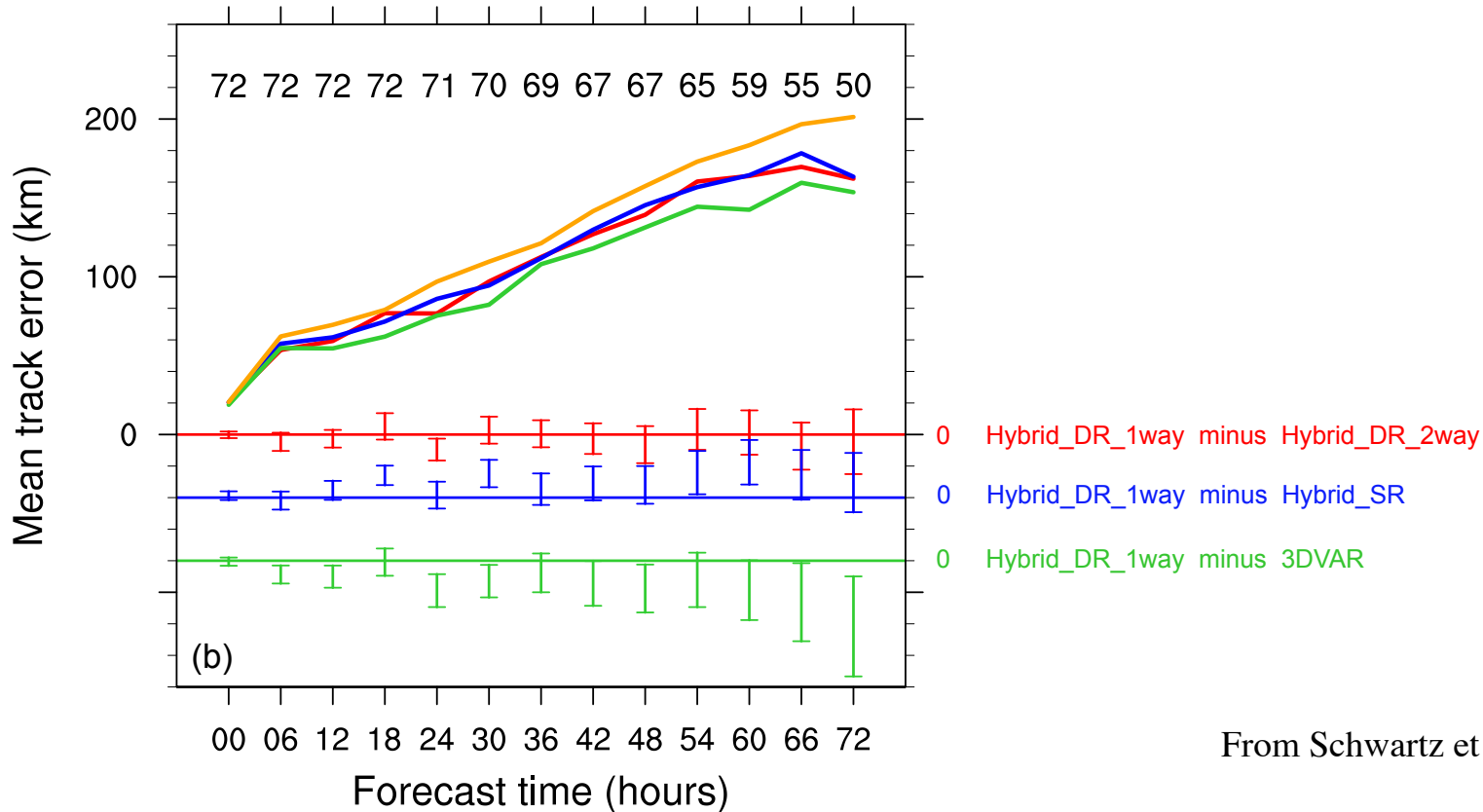


High-res
(4-km)

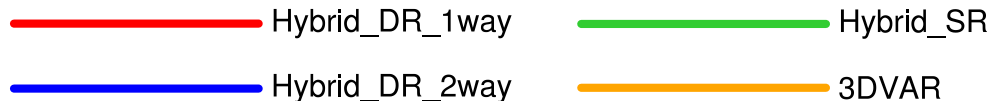


Impact of dual-resolution

- Mean tropical cyclone track errors

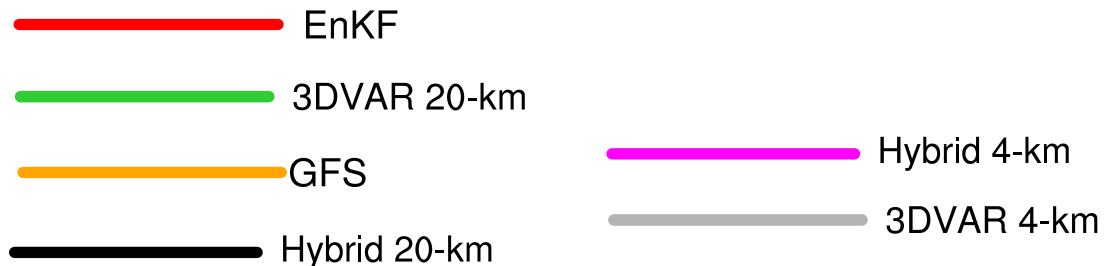
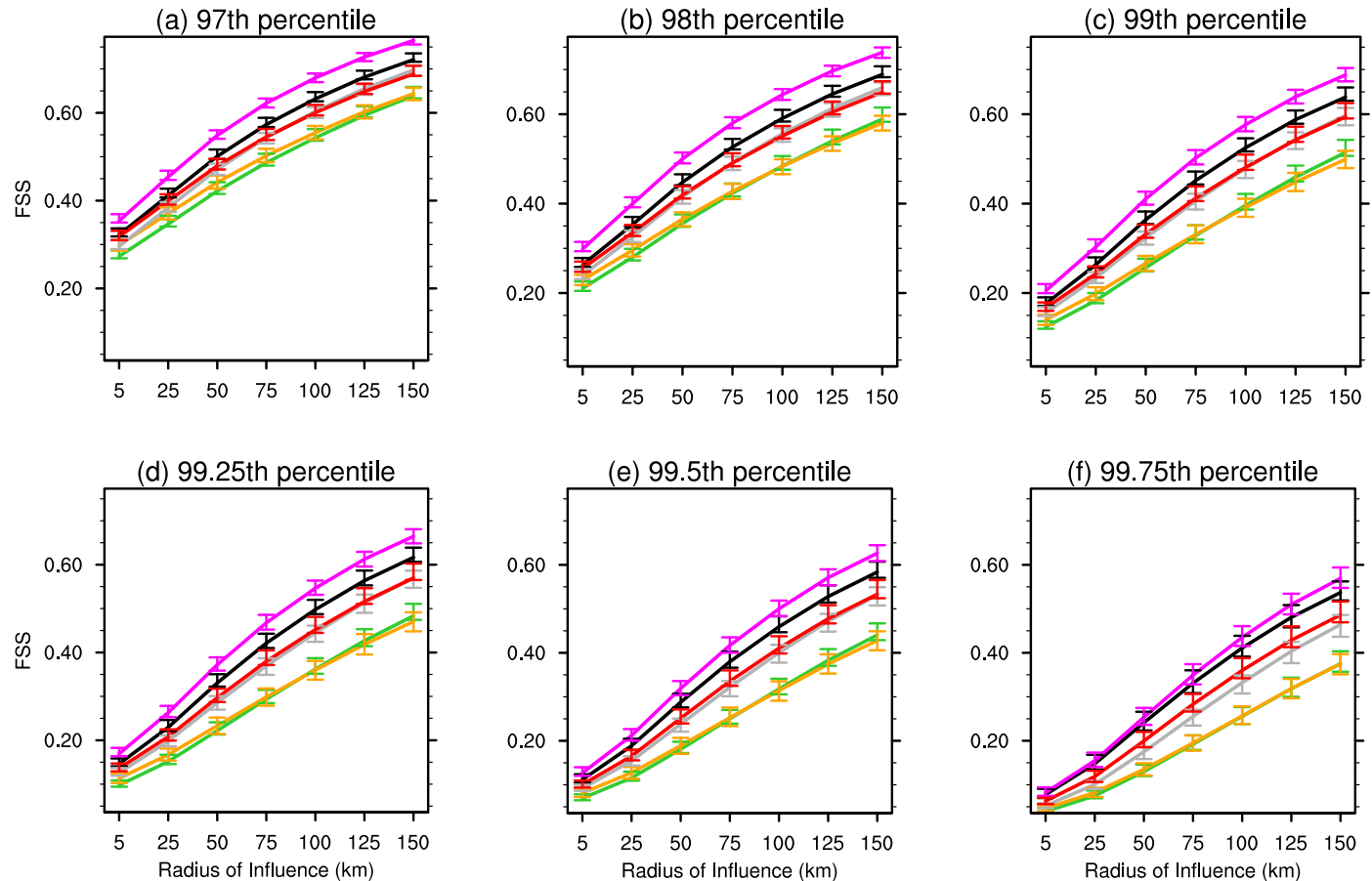


From Schwartz et al. (2015)



Impact of dual-resolution

- Fractions skill score (FSS) aggregated over the first 12 forecast hours and 55 4-km forecasts



Hybrid practice

- **Computation steps:**
 - Compute ensemble mean (**gen_be_ensmean.exe**)
 - Extract ensemble perturbations (**gen_be_ep2.exe**)
 - Run WRFDA in “hybrid” mode (**da_wrfvar.exe**)
 - Display results for: ens_mean, std_dev, ensemble perturbations, hybrid increments, cost function
 - If time permits, play with different namelist settings: “je_factor” and “alpha_corr_scale”
- **Scripts to use:**
 - Some NCL scripts to display results
- **Ensemble generation part not included in current practice**

Namelist for WRFDA in hybrid mode

&wrfvar7

je_factor=2, # half/half for ensemble and static B weightings (**tunable parameter**)

&wrfvar16

alphacv_method=2, # ensemble part is in model space (u,v,t,q,ps)

ensdim_alpha=10, # ensemble size

alpha_corr_type=3, # 1=Exponential; 2=SOAR; 3=Gaussian

alpha_corr_scale=750., # correlation scale in km (**tunable parameter**)

alpha_std_dev=1.,

alpha_vertloc=true, (use program “**gen_be_vertloc.exe 42**” to generate file)

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