



# Hybrid Variational/Ensemble Data Assimilation

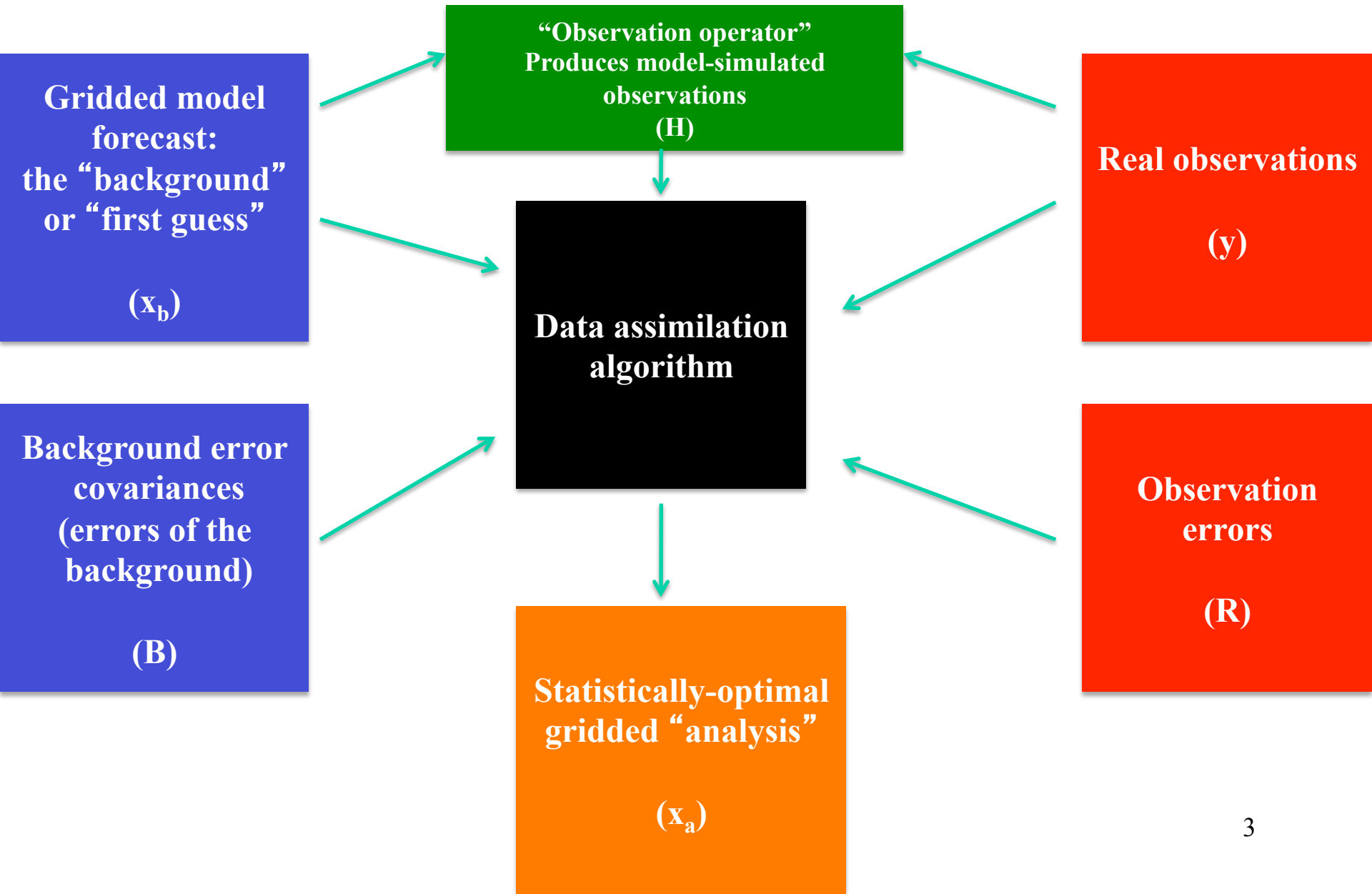
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**NCAR/MMM**

# Outline

- Background
- Some results
- Introduction to hybrid practice

# What is data assimilation?

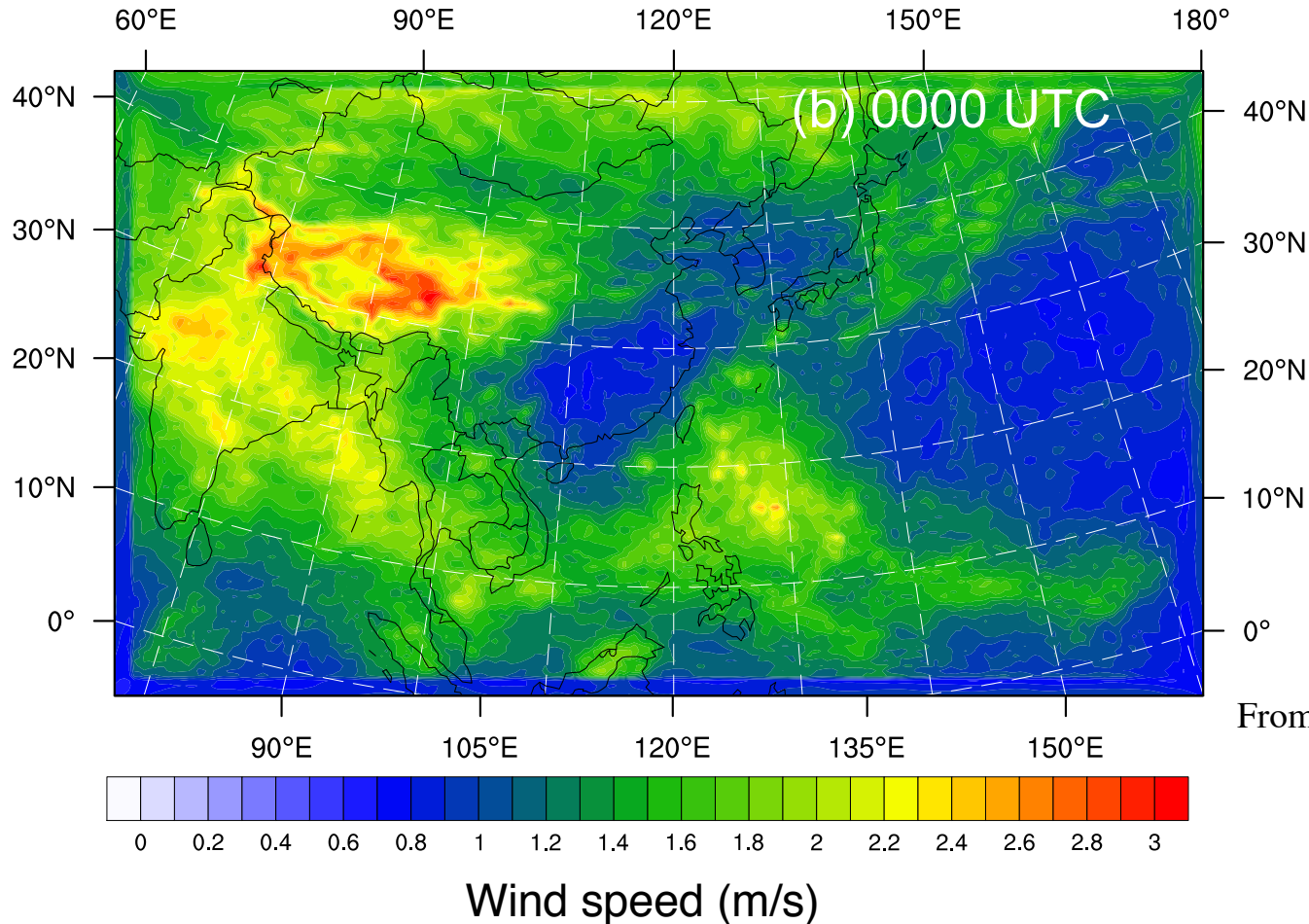


# Some data assimilation methods

- Three-dimensional variational (3DVAR)
  - Background error covariances (BECs) typically fixed/ time-invariant
  - May yield poor results when actual flow differs from that encapsulated within the fixed “climatology”
- Ensemble Kalman filter (EnKF)
  - Time-evolving, “**flow-dependent**” BECs estimated from a short-term ensemble forecast
  - Many different flavors (e.g., ETKF, EAKF)

# Ensemble BECs (i.e., spread)

- Average ensemble spread of wind speed over ~3 weeks at 0000 UTC



# Ensemble BECs (i.e., spread)

- General definition of covariance:

$$\frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})$$

- In vector matrix form (here,  $n$  is ensemble size):

$$\begin{aligned} &= \frac{1}{n-1} \sum_{i=1}^n (\mathbf{x}_i - \bar{\mathbf{x}})(\mathbf{x}_i - \bar{\mathbf{x}})^T \\ &= \frac{1}{n-1} \sum_{i=1}^n (\delta \mathbf{x}_i)(\delta \mathbf{x}_i)^T \end{aligned}$$

# “Hybrid” variational/ensemble DA

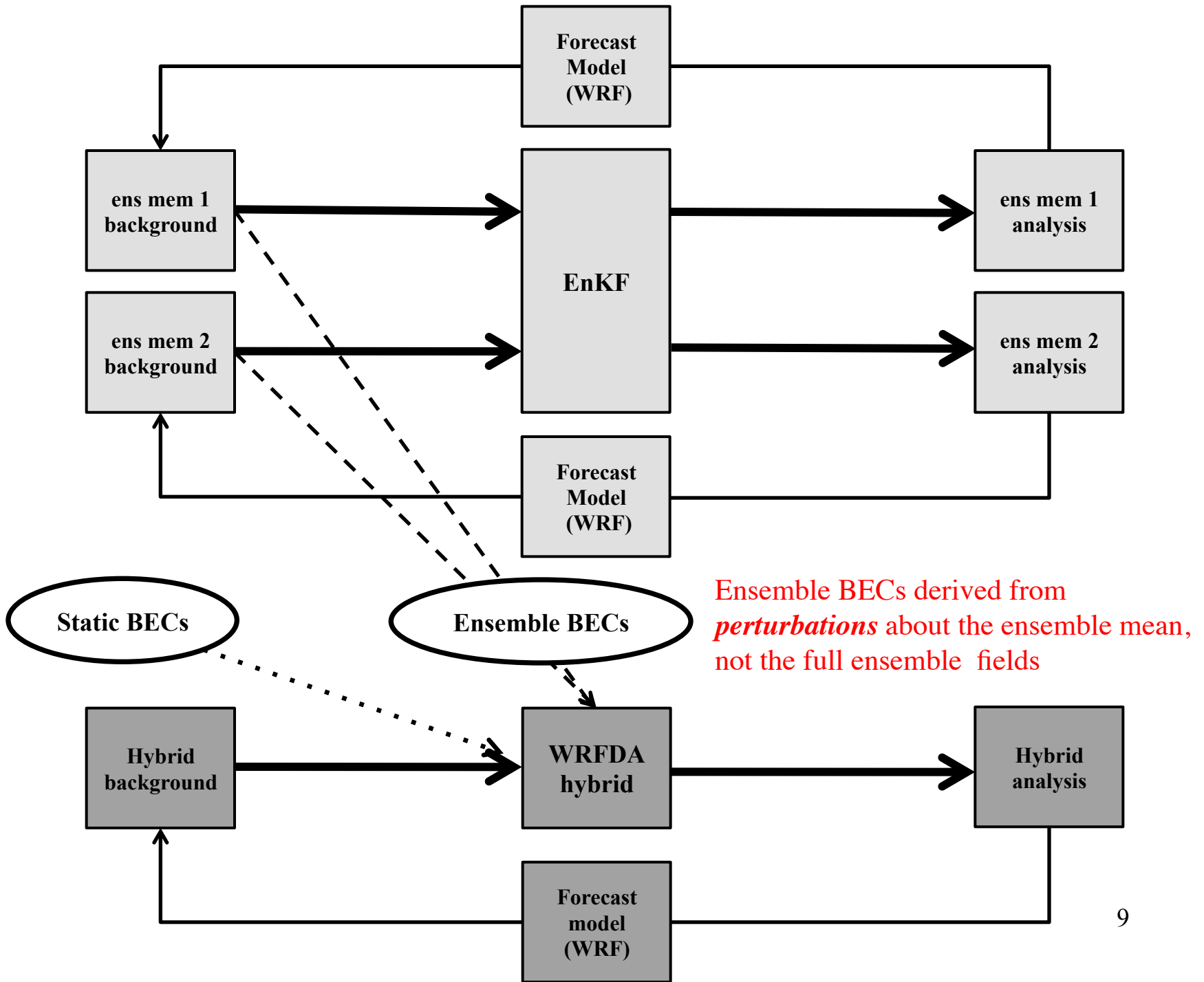
- “Hybrid” variational/ensemble
  - Incorporates ensemble background errors within a variational (e.g., 3DVAR) framework
  - Combination of fixed and time-evolving background errors
  - Main additional expense compared to 3DVAR is running an ensemble of forecasts

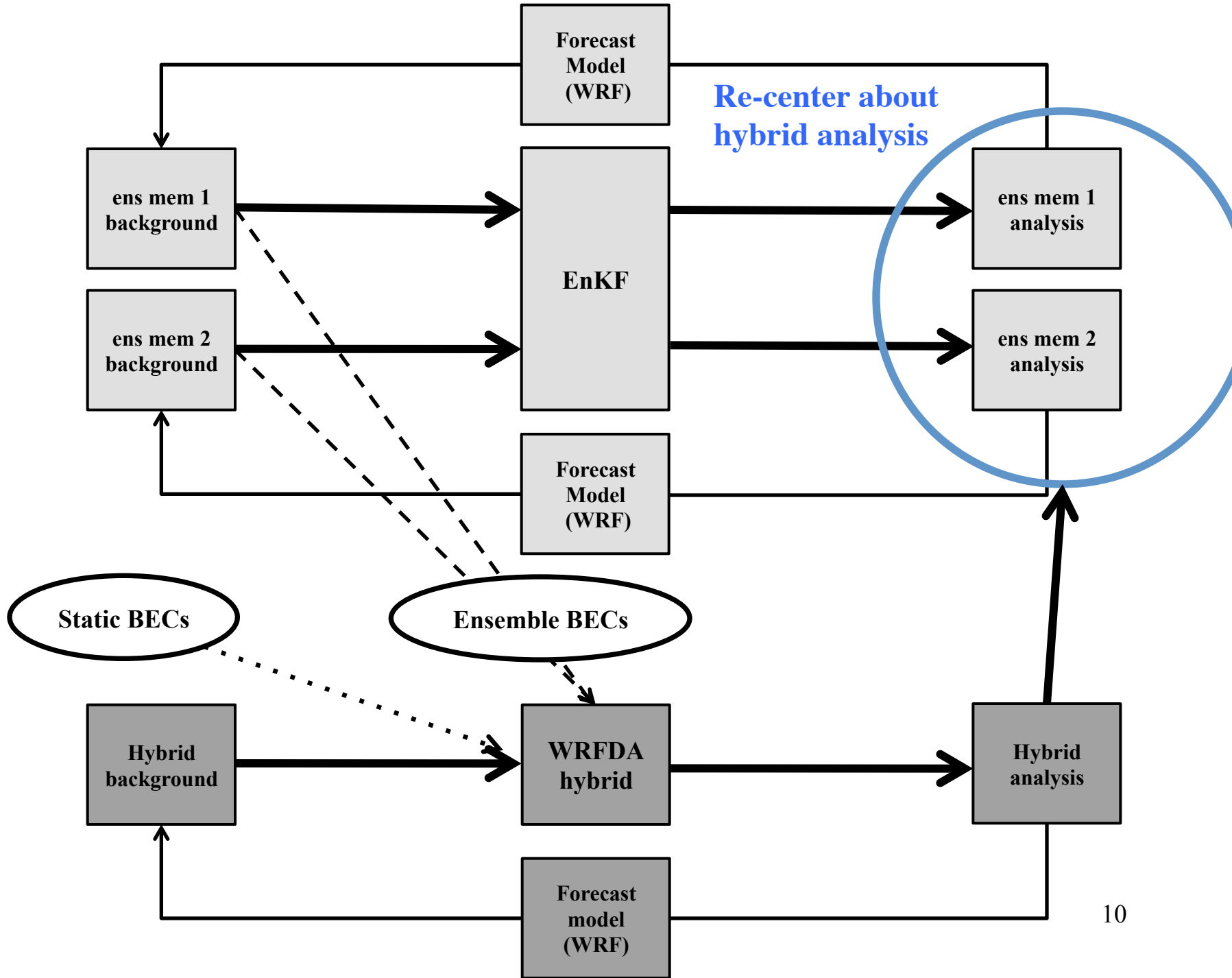


# What is Hybrid DA?

- **Deterministic background** is analyzed by a variational algorithm (i.e., minimize a cost function)
  - It combines the 3DVAR “climatological” BECs and “errors of the day” from ensemble perturbations
- Traditionally generates a deterministic analysis (like 3DVAR)
- Need a separate system to update ensemble
  - Could be ensemble forecasts already available from operational centers
  - Could be an EnKF-based DA system
  - Could be a multiple model/physics ensemble
- Ensemble needs to be good to well-represent “errors of the day”







# Hybrid formulation

(Hamill and Snyder, 2000)

- 3DVAR cost function

$$J(\mathbf{x}) = \frac{1}{2}(\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}^{-1}(\mathbf{x} - \mathbf{x}_b) + \frac{1}{2}[H(\mathbf{x}) - \mathbf{y}]^T \mathbf{R}^{-1}[H(\mathbf{x}) - \mathbf{y}]$$

- Idea: replace  $\mathbf{B}$  by a weighted sum of static  $\mathbf{B}_s$  and the ensemble  $\mathbf{B}_e$

$$\mathbf{B} = a_s \mathbf{B}_s + a_e \mathbf{B}_e \circ \mathbf{C}, \quad a_s = 1 - a_e$$

- Term  $\mathbf{C}$  is localization for the ensemble
  - Terms  $a_s$  and  $a_e$  can be tuned to determine how much  $\mathbf{B}_s$  and  $\mathbf{B}_e$  are weighted
- This form is difficult to implement for a large NWP model
    - Most systems use “extended control variables”

# Hybrid formulation used in WRFDA

(Lorenc, 2003)

- Ensemble covariance is included in the 3DVAR cost function through augmentation of control variables

$$J(\mathbf{x}, \alpha) = \beta_s \frac{1}{2} (\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}_b) + \overbrace{\beta_e \frac{1}{2} \sum_{i=1}^N \alpha_i^T \mathbf{C}^{-1} \alpha_i}^{\text{ensemble control variable } \alpha_i \text{ (} M \times 1 \text{)}} + \frac{1}{2} [\mathbf{y} - H(\mathbf{x} + \mathbf{x}'_e)]^T \mathbf{R}^{-1} [\mathbf{y} - H(\mathbf{x} + \mathbf{x}'_e)]$$

$$\mathbf{x}'_e = \sum_{i=1}^N \alpha_i \circ \mathbf{x}'_i, \text{ where } \mathbf{x}'_i \text{ is the ensemble perturbation for the ensemble member } i.$$

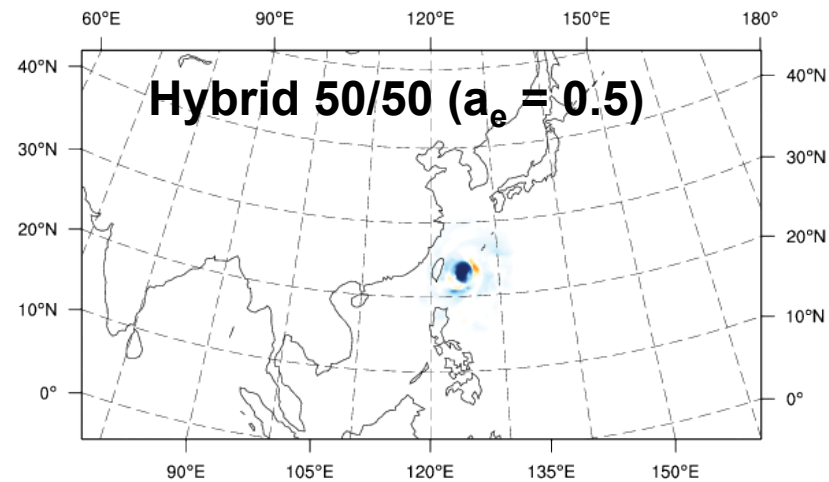
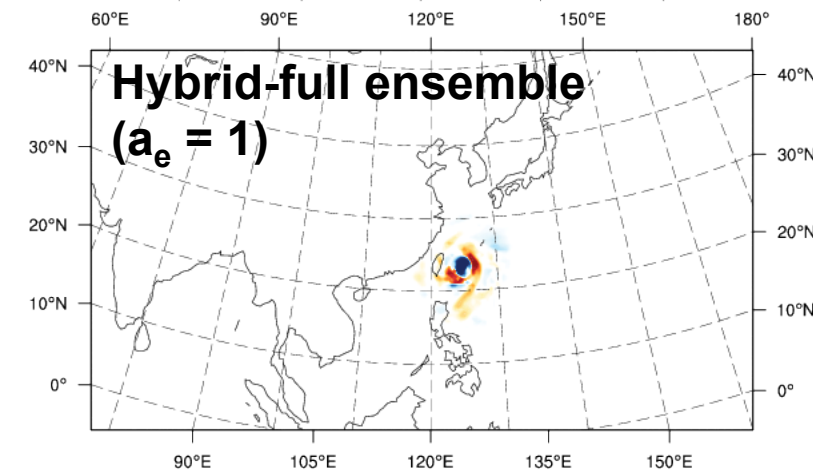
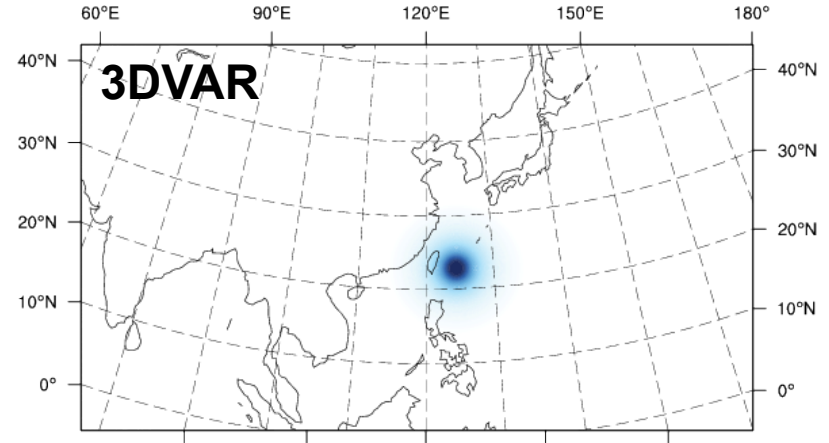
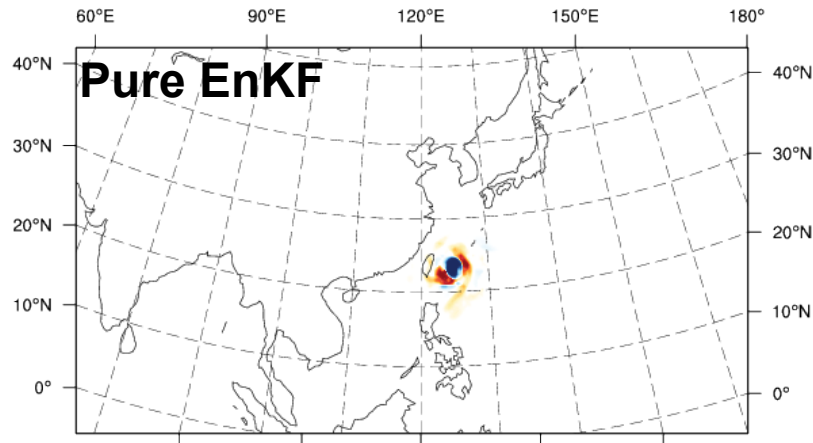
◦ denotes element-wise product.  $\alpha_i$  is in effect the ensemble weight.

**C**: correlation matrix (effectively localization of ensemble perturbations)

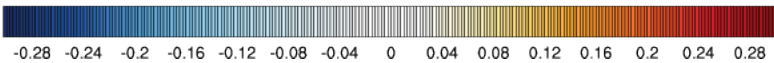
- More simply:  $J(\mathbf{x}, \alpha) = J_b + J_e + J_o$
- $\beta_s$  and  $\beta_e$  ( $1/\beta_s + 1/\beta_e = 1$ ) can be tuned to have different weight between static and ensemble part

# Single observation tests

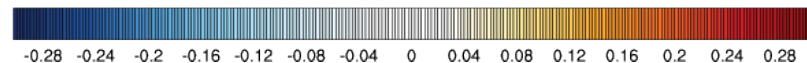
- Potential temperature increment, 21<sup>st</sup> model level



Average increment of T (K)

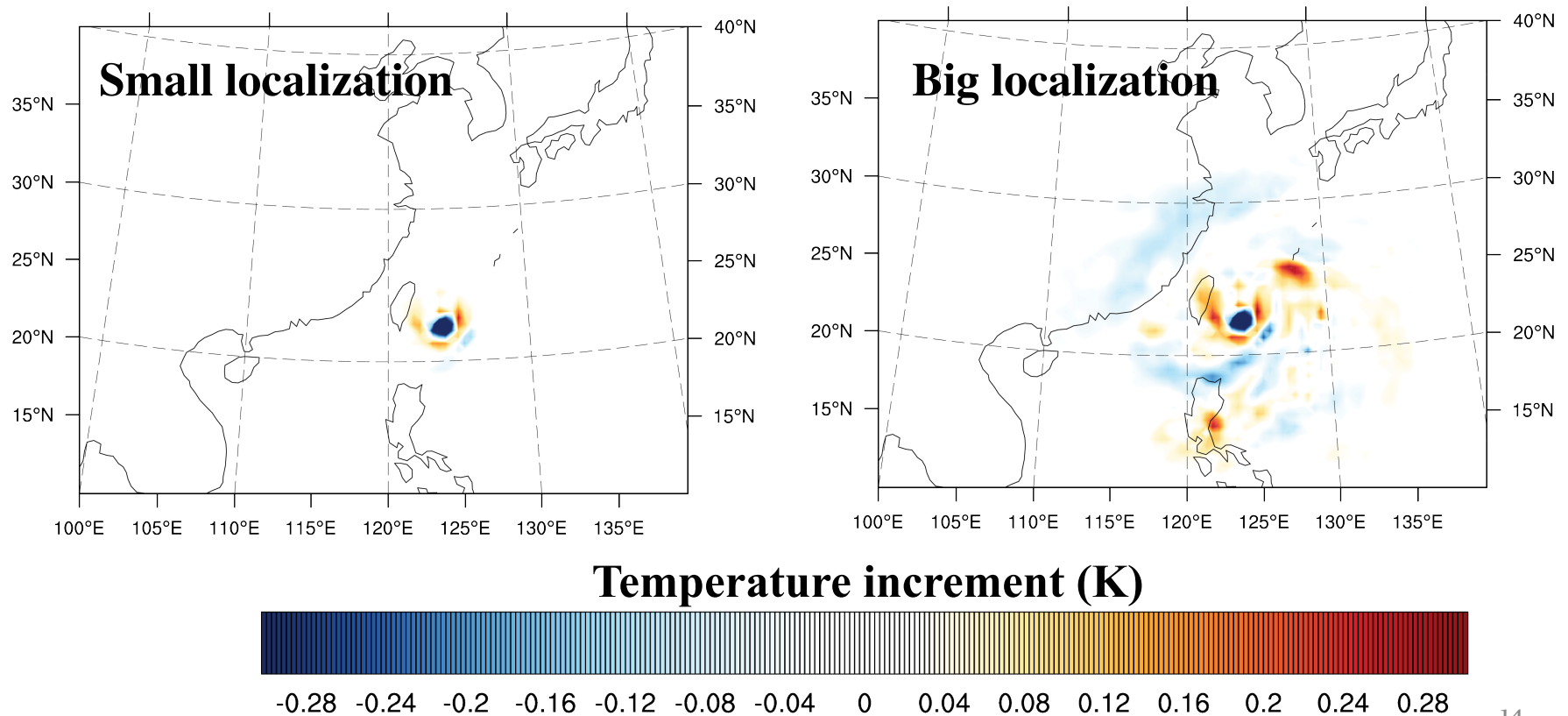


Average increment of T (K)



# Meaning of localization

- Localization defines the extent to which an observation can produce an analysis increment
- In this example, 100% of the BECs are from ensemble

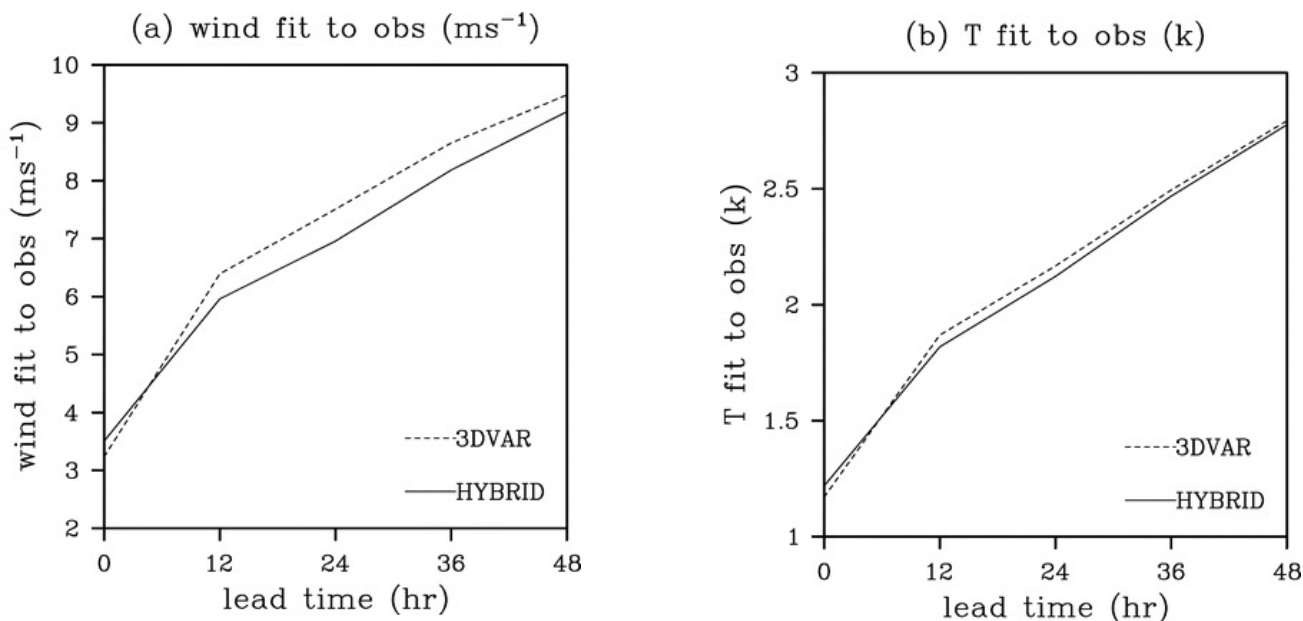


# Advantages of Hybrid DA

- Hybrid localization is in model space while EnKF localization is usually in observation space
- For some observation types (e.g., radiances), localization is not well defined in observation space
- Easier to make use of existing radiance VarBC in hybrid
- For small ensembles, use of static **B** could be beneficial to have a higher-rank covariance.

# Sample results

- Example over North America at coarse grid spacing
- Similar results have been obtained by many studies

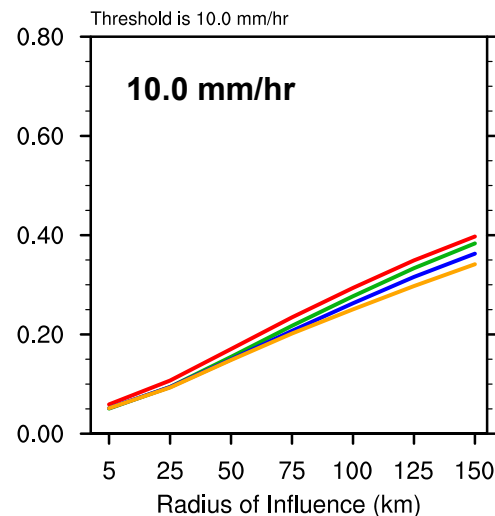
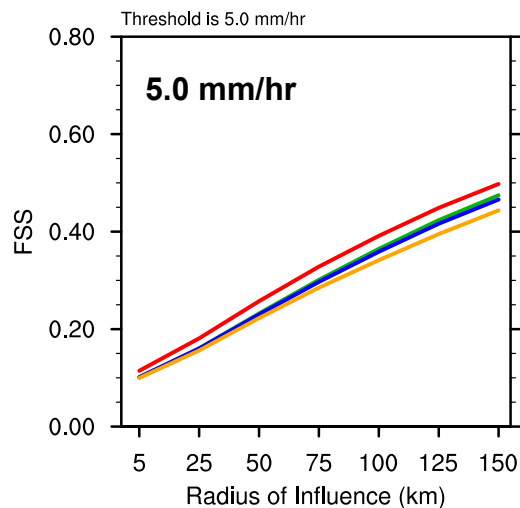
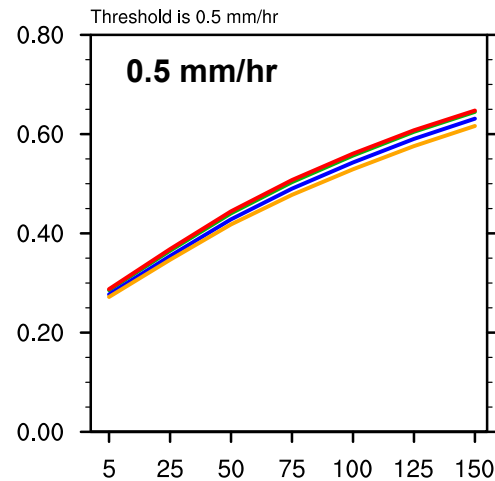
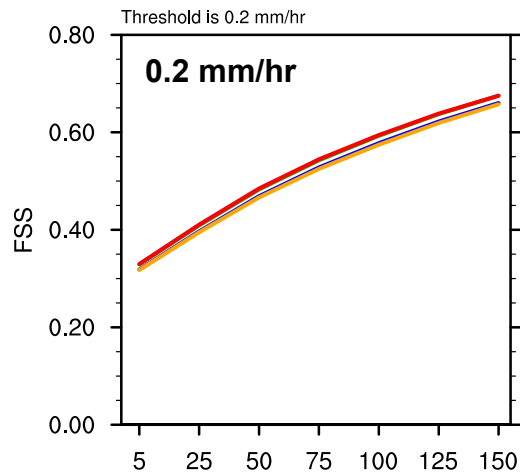


From Wang et al. (2008)

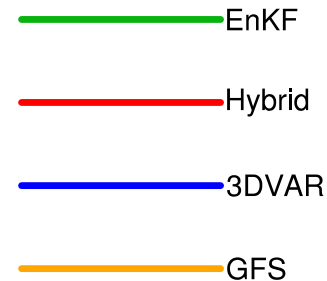


# Hybrid vs. 3DVAR and EnKF

- Fractions skill scores for rainfall (higher is better)



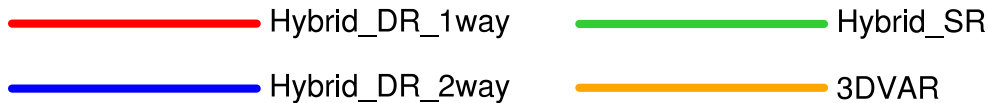
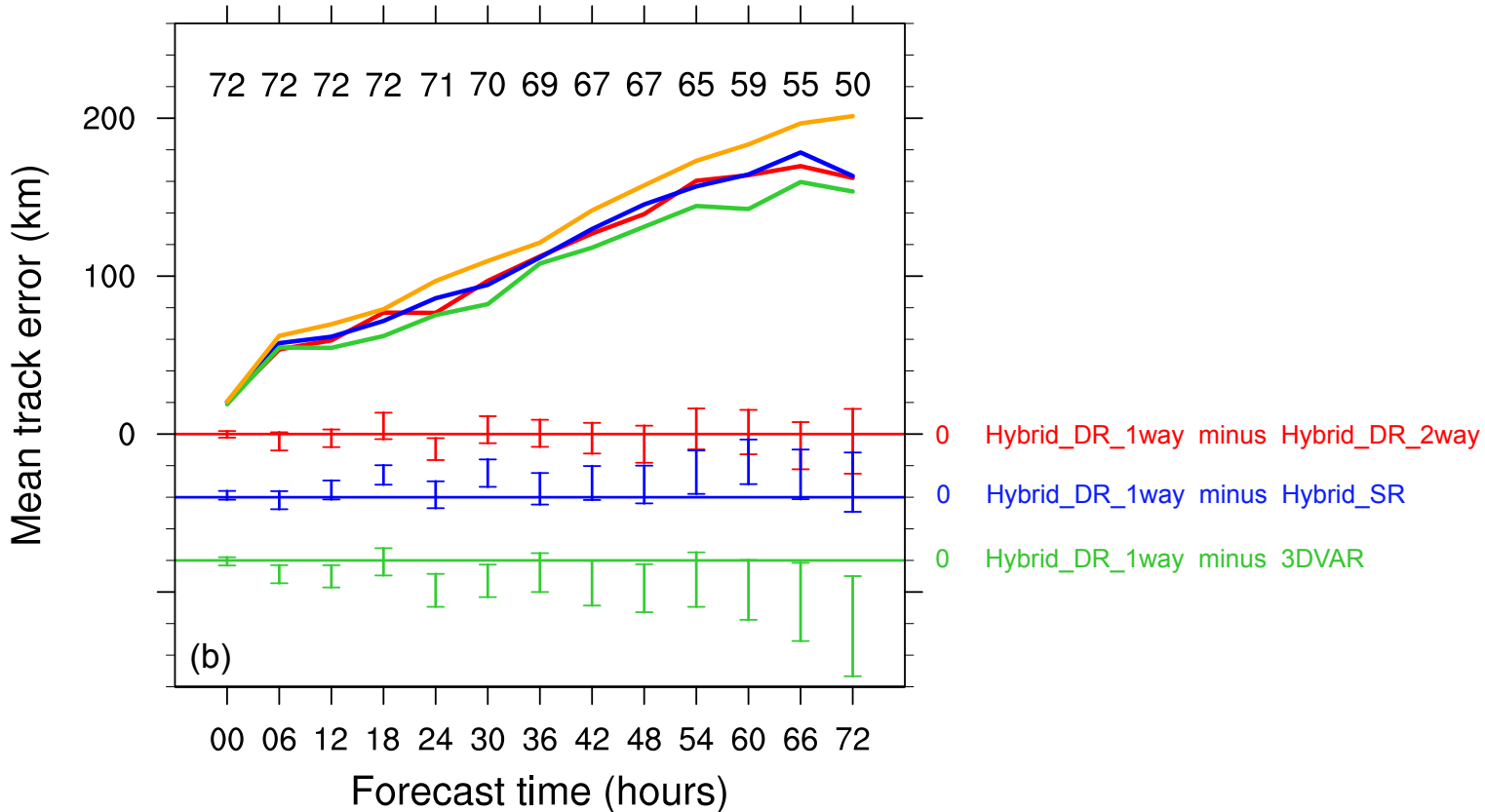
**Aggregated over hourly 18-36-hr forecasts of precipitation**



Modified from Schwartz and Liu (2014)

# Typhoon example

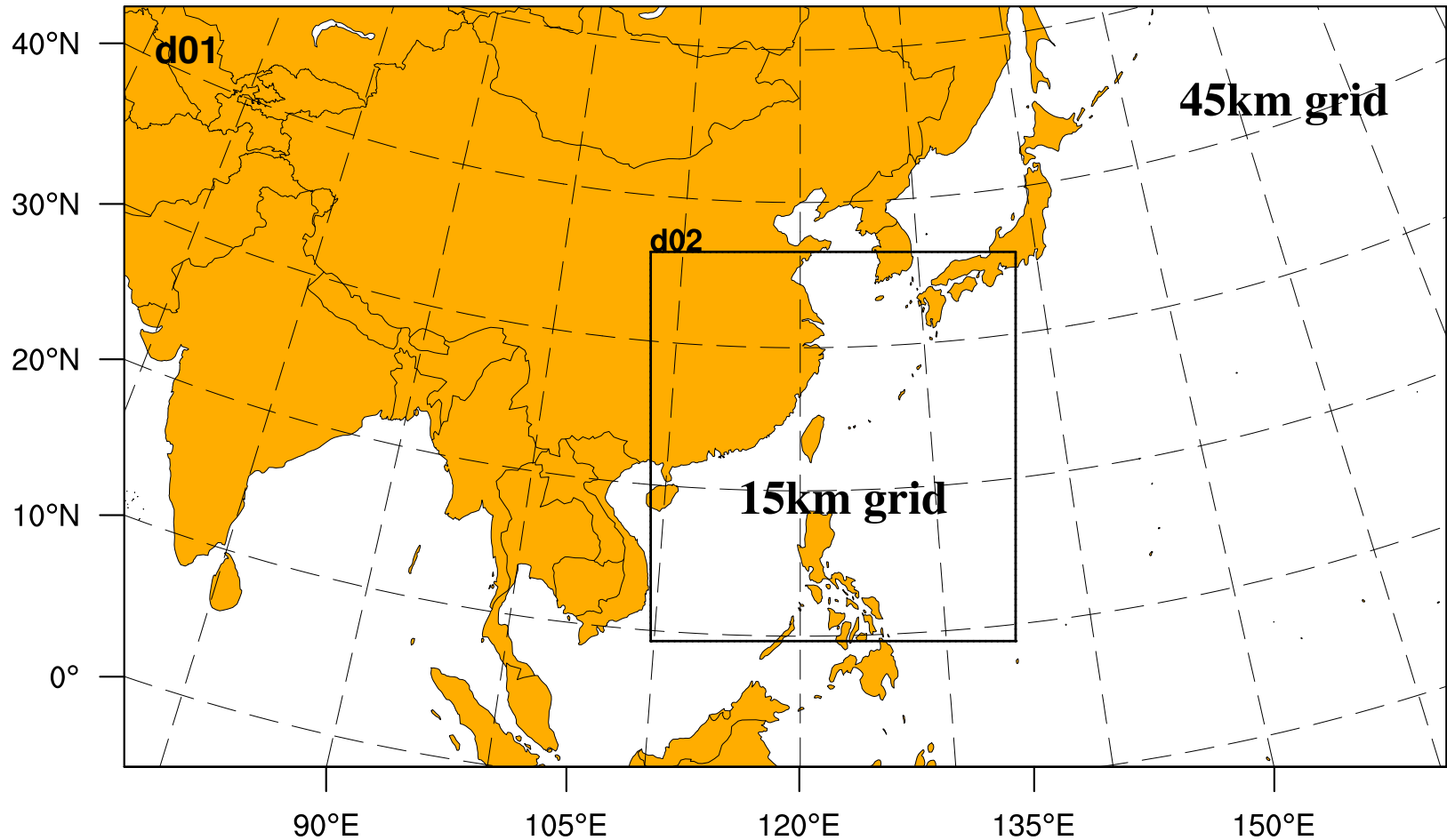
- Mean tropical cyclone track errors



From Schwartz et al. (2015)

# Dual-Resolution hybrid (V3.6)

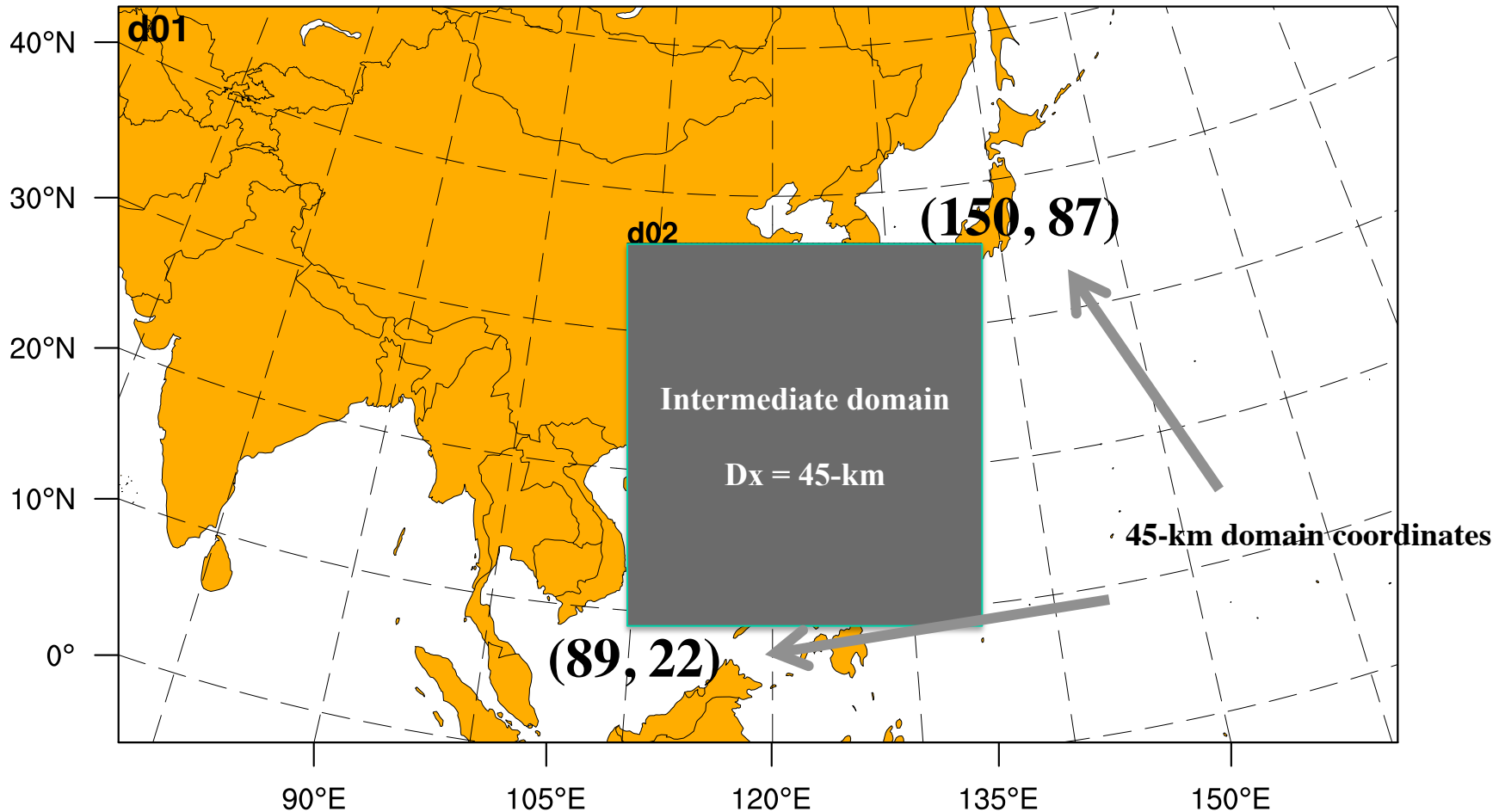
Schwartz et al. (2015; MWR)



**Hybrid analysis on 15-km grid but with ensemble perturbation input from 45-km grid**

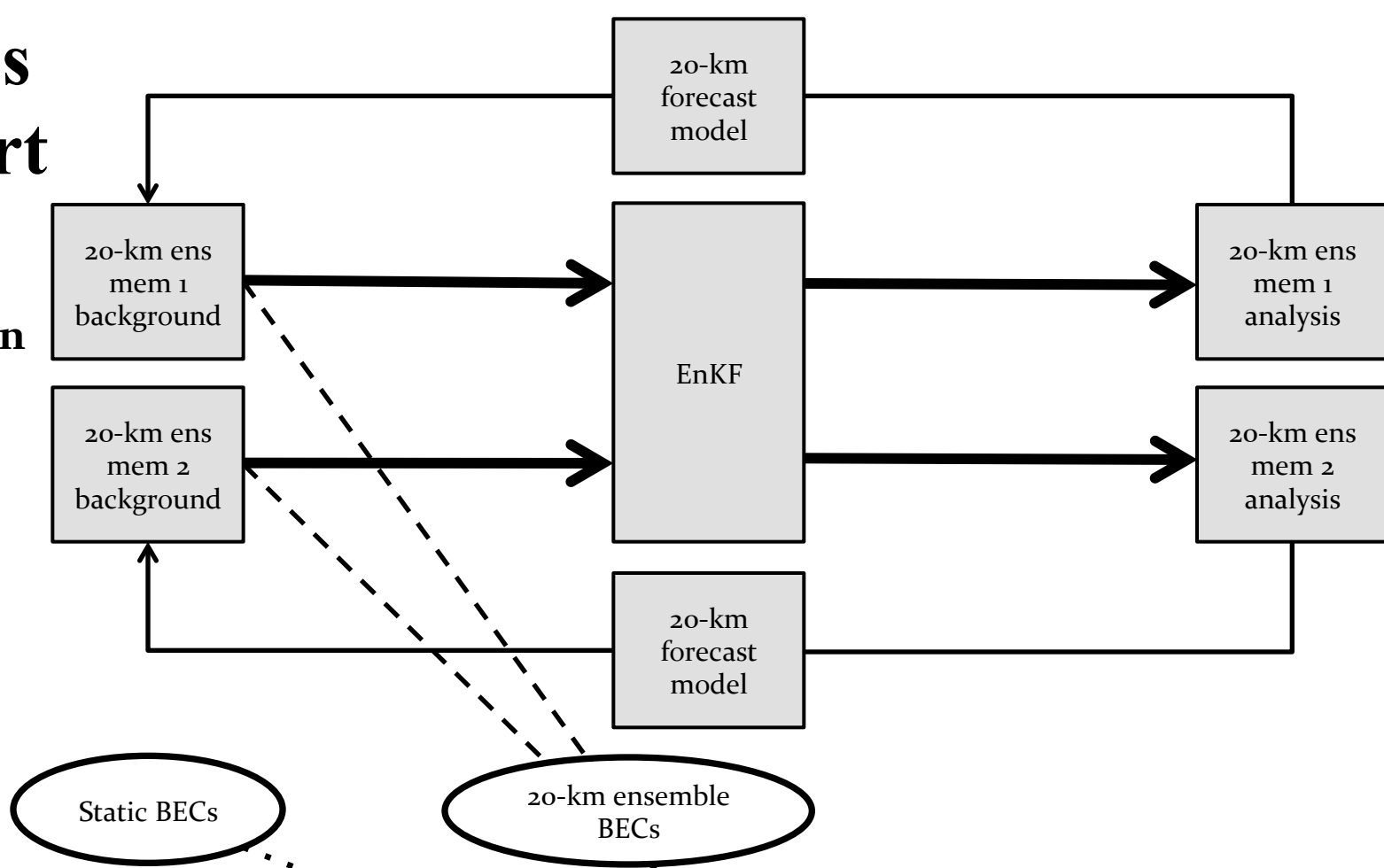
# Intermediate domain

- WRFDA directly reads in d01 ensembles, then cuts to d02 size (making use of WRF model nest namelist setting)

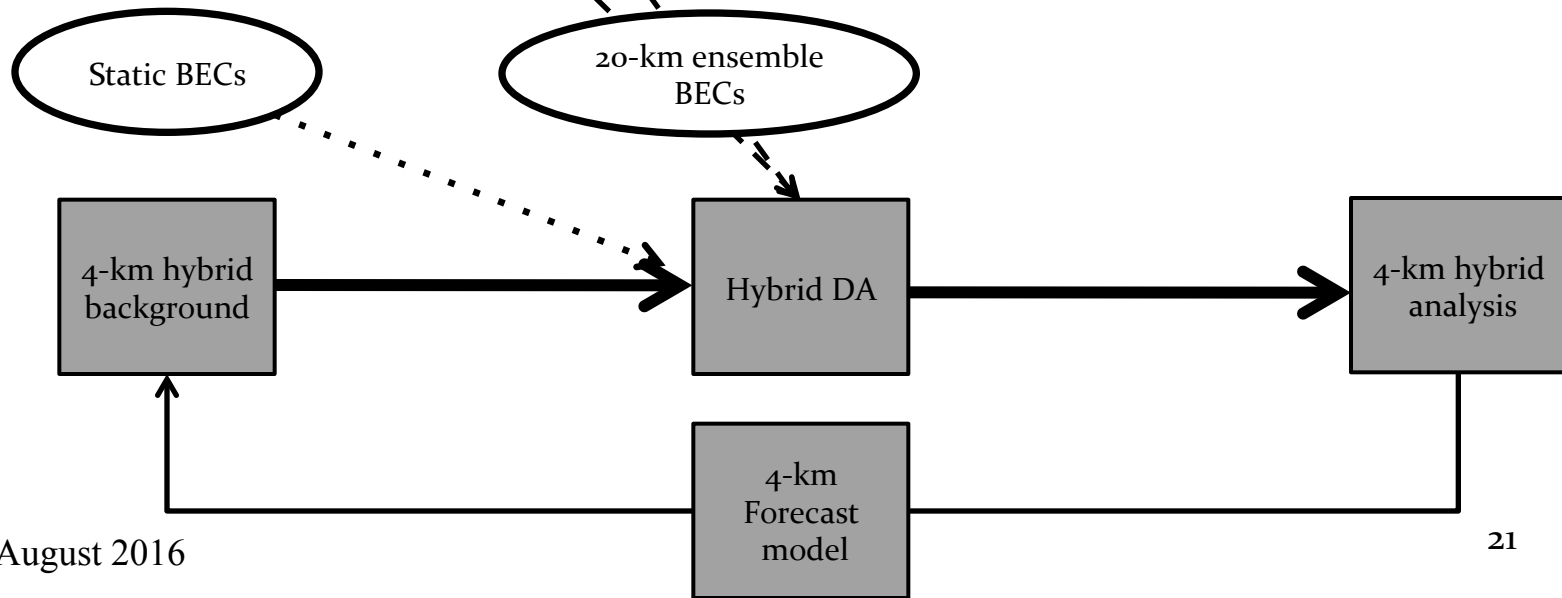


# Dual-res flowchart

Low-resolution  
(20-km)

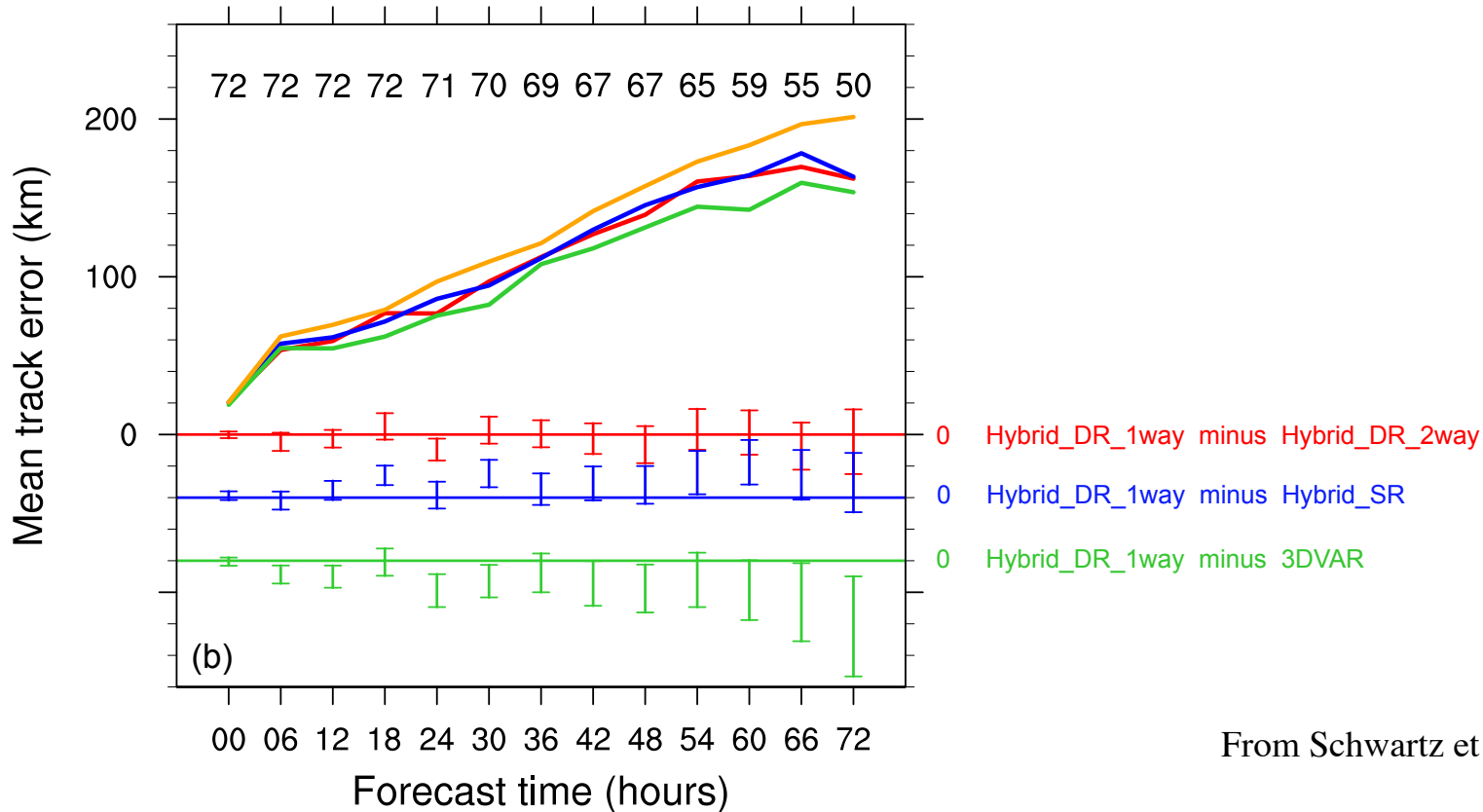


High-res  
(4-km)

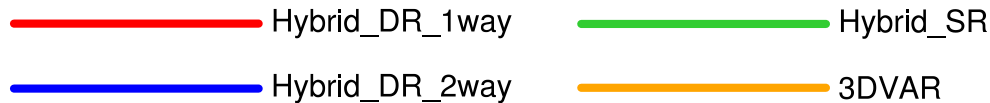


# Impact of dual-resolution

- Mean tropical cyclone track errors

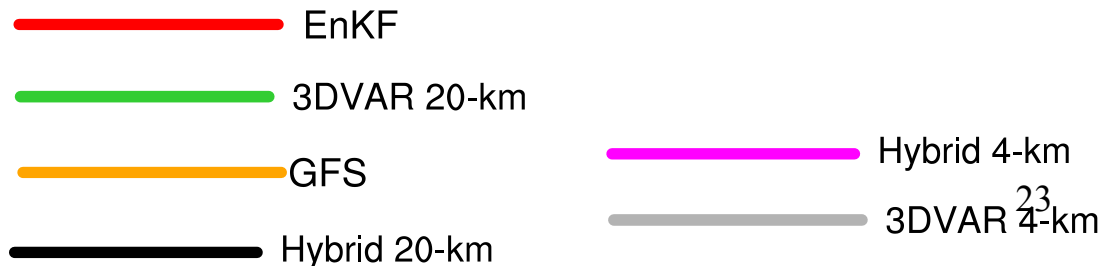
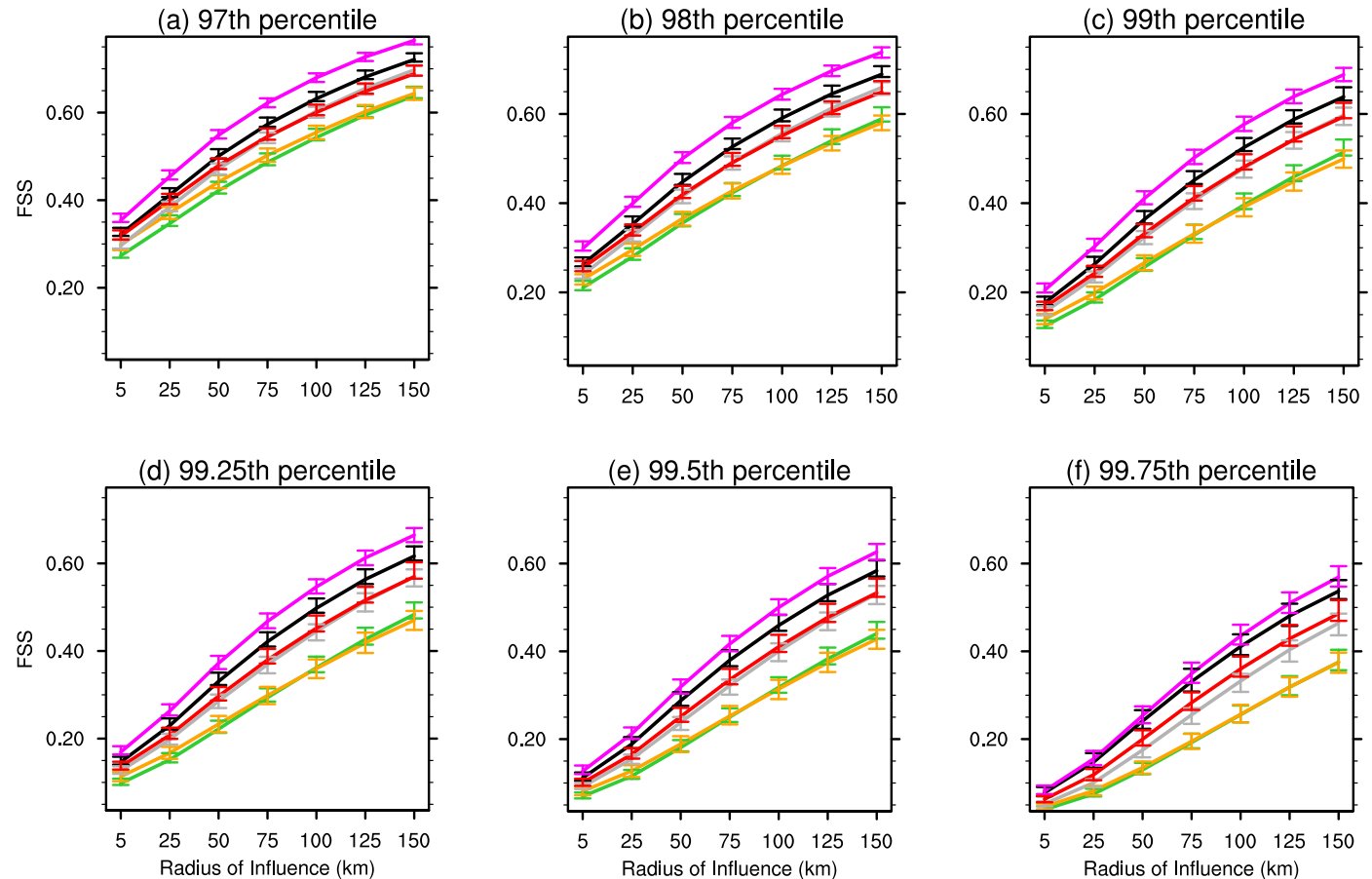


From Schwartz et al. (2015)



# Impact of dual-resolution

- Fractions skill score (FSS) aggregated over the first 12 forecast hours and 55 4-km forecasts



# Hybrid practice

- **Computation steps:**
  - Compute ensemble mean (**gen\_be\_ensmean.exe**)
  - Extract ensemble perturbations (**gen\_be\_ep2.exe**)
  - Run WRFDA in “hybrid” mode (**da\_wrfvar.exe**)
  - Display results for: ens\_mean, std\_dev, ensemble perturbations, hybrid increments, cost function
  - If time permits, play with different namelist settings: “je\_factor” and “alpha\_corr\_scale”
- **Scripts to use:**
  - Some NCL scripts to display results
- **Ensemble generation part not included in current practice**



# Namelist for WRFDA in hybrid mode

&wrfvar7

je\_factor=2, # half/half for ensemble and static B weightings (**tunable parameter**)

&wrfvar16

alphacv\_method=2, # ensemble part is in model space (u,v,t,q,ps)

ensdim\_alpha=10, # ensemble size

alpha\_corr\_type=3, # 1=Exponential; 2=SOAR; 3=Gaussian

alpha\_corr\_scale=750., # correlation scale in km (**tunable parameter**)

alpha\_std\_dev=1.,

alpha\_vertloc=true, (use program “**gen\_be\_vertloc.exe 42**” to generate file)

hybrid\_dual\_res = .false. # If true, hybrid is in “dual-resolution” mode

# Namelist for **dual-resolution** hybrid

- Dual-resolution hybrid uses WRF nesting to define grids, so also need to specify **nested domain** geometry in the namelist
- Analysis on the nested domain (i.e., “d02”), but using the ensemble from the parent domain (i.e., “d01”)
- When running in dual-resolution mode, also need to link “d01” file to run directory as “./fg\_ens”:

`ln -sf ${dir}/wrfinput_d01 ./fg_ens (ensemble grid)`

`ln -sf ${dir}/wrfinput_d02 ./fg (high-res background)`

```
&wrfvar16  
hybrid_dual_res = .true.
```

```
&domains  
e_we = 222, 316  
e_sn = 128, 274  
s_vert = 1,1  
e_vert = 45, 45  
dx = 45000, 15000,  
dy = 45000, 15000,  
hypsometric_opt = 2  
max_dom = 2  
grid_id = 1, 2,  
parent_id = 0, 1  
i_parent_start = 0, 74,  
j_parent_start = 0, 17,  
parent_grid_ratio = 1, 3
```

# References

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